Stochastic Optimization

Prof. Lutz Hendricks

Econ720

November 15, 2019

Stochastic Optimization

- ▶ We add shocks to the growth model.
- Recursive methods are needed.
- ► The resulting model is used to study
 - business cycles
 - asset pricing

Model

Demographics:

▶ 1 representative household lives forever

Preferences: expected utility

$$\mathbb{E}_0 \sum_{t=0}^{\infty} \beta^t u(c_t) \tag{1}$$

- $ightharpoonup \mathbb{E}_0$ denotes the expectation given information at date 0.
- The household needs to know the probability distribution of c_t implied by his choices

Endowments: k_0 at t = 0

Technology

$$k_{t+1} = f(k_t, \theta_t) - c_t \tag{2}$$

 θ_t : productivity shock

a Markov process with N (finite) discrete values

$$\theta_t \in \{\theta^1, ..., \theta^N\} \tag{3}$$

and transition matrix

$$\Pr(\theta_{t+1} = \theta^j | \theta_t = \theta^i) = \Omega_{ij}$$

Planner's Problem

$$\max \mathbb{E}_0 \sum_{t=0}^{\infty} \beta^t u(c_t) \tag{4}$$

subject to

$$k_{t+1} = f(k_t, \theta_t) - c_t \tag{5}$$

Key problem: what does the planner choose?

- ► He cannot choose sequences $\{c_t, k_t\}$ because we don't know the realizations of θ_t .
- ▶ He must choose a sequence $\{c_t, k_t\}$ for every possible history of shocks $(\theta_0, \theta_1, ...)$.
- state contingent plans.

Notation

Define a history up to date t as

$$s^t = (\theta_0, ..., \theta_t) \tag{6}$$

A state contingent plan is a mapping from histories to choices:

$$c_t = c(s^t) \tag{7}$$

and

$$k_{t+1} = \kappa(s^t) \tag{8}$$

Two period example

Two period example

The problem is

$$\max E_0 \sum_{t=1}^2 \beta^{t-1} u(c_t)$$

subject to

$$k_2 = f(k_1, \theta_1) - c_1$$

 $c_2 = f(k_2, \theta_2)$
 θ_1 known

Two period example

Write out the expectation explicitly:

$$\begin{aligned} & \max u(c_1) + \sum_{j=1}^{N} \Pr(\theta_2 = \theta_j) \beta \ u(c_2(\theta_j)) \\ & + \lambda_1 \left[f(k_1, \theta_1) - c_1 - k_2 \right] \\ & + \sum_{j=1}^{N} \lambda_2(\theta_j) \left[f(k_2, \theta_j) - c_2(\theta_j) \right] \end{aligned}$$

The household chooses c_1, k_2 and $c_2(\theta_j)$.

The budget constraint must hold in every history.

First-order conditions

$$c_1 : u'(c_1) = \lambda_1$$

$$k_2 : \lambda_1 = \sum \lambda_2(\theta_j) f_k(k_2, \theta_j)$$

$$c_2(\theta_j) : \Pr(\theta_2 = \theta_j) \beta u'(c_2(\theta_j)) = \lambda_2(\theta_j)$$

Euler equation:

$$u'(c_1) = \beta \sum \Pr(\theta_2 = \theta_j) \ u'(c_2(\theta_j)) \ f_k(k_2, \theta_j)$$
$$= \beta \ E\{u'(c_2) \ f_k(k_2, \theta_2) | \theta_1\}$$

Interpretation ...

Notes

- 1. $\mathbb{E}\{u'(c_2(\theta_2))f_k(k_2,\theta_2)\} \neq \mathbb{E}u'(c_2(\theta_2)) \times \mathbb{E}f_k(k_2,\theta_2)$
- 2. Naively maximizing $u(c_1) + \mathbb{E}\beta u(f(k_1; \theta_1) c_1)$, treating \mathbb{E} as a number (!) would have produced the right answer.

Many periods

Many periods

A history of length t is s^t .

The household chooses $c(s^t)$ and $k(s^t)$ to maximize

$$\sum_{s^t} p(s^t) \beta^t u(c(s^t))$$

subject to

$$x(s^t) + c(s^t) = f(k(s^t), \theta(s^t)), \forall s^t$$

$$k(s_{t+1}, s^t) = x(s^t), \forall s^t, s_{t+1}$$

The last constraint ensures that $k(s^{t+1})$ is the same for all s_{t+1} .

Important point

You need the constraint

$$k(s_{t+1}, s^t) = x(s^t), \ \forall s^t, s_{t+1}$$
 (9)

that ensures $k(s^{t+1})$ is the same for all s^t !

► The following would be wrong:

$$k(s^{t+1}) + c(s^t) = f(k(s^t), \theta(s^t))$$
(10)

Try to write down a Lagrangian and take FOCs - it does not work.

Lagrangian

$$\sum_{t} \sum_{s^{t}} p(s^{t}) \beta^{t} u(f(k(s^{t}), \theta(s^{t})) - x(s^{t})) + \sum_{t} \sum_{s^{t}} \sum_{s_{t+1}} \varphi(s_{t+1}, s^{t}) [k(s_{t+1}, s^{t}) - x(s^{t})]$$

FOC:

$$x(s^{t}) : \beta^{t} p(s^{t}) u'(s^{t}) = \sum_{s_{t+1}} \varphi(s_{t+1}, s^{t})$$

$$k(s^{t}) : \beta^{t} p(s^{t}) u'(s^{t}) f_{k}(s^{t}) = \varphi(s^{t})$$

What do these say in words?

Euler equation

$$\beta^{t} p(s^{t}) u'(s^{t}) = \sum_{s_{t+1}} f_{k}(s_{t+1}, s^{t}) \beta^{t+1} p(s_{t+1}, s^{t}) u'(s_{t+1}, s^{t})$$
(11)

Divide by $\beta^t p(s^t)$ and note that

$$p(s_{t+1},s^t)/p(s^t) = \Pr(s_{t+1}|s^t)$$
 (12)

This yields the usual Euler equation:

$$u'(s^t) = \beta \sum_{s^{t+1}} \Pr(s_{t+1}|s^t) f_k(s_{t+1}, s^t) u'(s_{t+1}, s^t)$$
 (13)

$$= \beta \mathbb{E} \left\{ f_k(t+1)u'(c(t+1)) \mid s^t \right\}$$
 (14)

Euler equation

- Be careful with notation.
- lt would be wrong to write

$$\beta^{t} p(s^{t}) u'(s^{t}) = \sum_{s^{t+1}} f_{k}(s^{t+1}) \beta^{t+1} p(s^{t+1}) u'(s^{t+1})$$
 (15)

► Why is this wrong?

The point

- ▶ With uncertainty, the sequence approach is a mess.
- Two solutions:
 - 1. Recursive methods.
 - 2. A shortcut: Maximize as if one could choose sequences.

A shortcut

Let's proceed mechanically as if we were choosing sequences $\{c_t, k_t\}$:

$$\Gamma = E_0 \sum_{t=0}^{\infty} \beta^t u(c_t)$$

$$+ E_0 \sum_{t=0}^{\infty} \lambda_t [f(k_t, \theta_t) - c_t - k_{t+1}]$$

This is not quite right: the budget constraint should bind state by state, not just in expectation.

► See the 2 period example.

A shortcut

First-order conditions

$$E_0 \beta^t u'(c_t) = E_0 \lambda_t$$

$$E_0 \lambda_{t-1} = E_0 \lambda_t f_k(k_t, \theta_t)$$

Euler equation:

$$E_0 u'(c_t) = \beta E_0 u'(c_{t+1}) f_k(k_{t+1}, \theta_{t+1})$$

► When date *t* arrives:

$$u'(c_t) = \beta E_t u'(c_{t+1}) f_k(k_{t+1}, \theta_{t+1})$$

► The point: Treating the E as a constant in the optimization problem actually yields the right result!

A shortcut

This approach is advocated by Chow (1997)

Why does the shortcut work, even though it is entirely wrong?

- ▶ One reason: \mathbb{E} is linear: $\mathbb{E}(x) = \sum p(x_i)x_i$.
- ▶ The recursive approach makes this clearer...

Recursive Approach

Recursive Approach

- We generalize the DP approach introduced for deterministic problems.
- Nothing of substance changes, except there is an *E* in front of each equation.
- Why does nothing change?
 - ▶ Because E is a linear operator just the sum of $Pr(s'|s) \times outcome(s')$.
- We start by assuming that stochastic DP works as expected.
- ▶ Then we state the conditions under which it works.

Recursive Approach to the Growth Model

State vector: $s_t = (k_t, \theta_t)$.

Bellman equation:

$$\begin{array}{lcl} V(k,\theta) & = & \max u(c) + \beta \, E \, V \left(f(k,\theta) - c, \theta' \right) \\ & = & \max u(c) + \beta \, \sum_{\theta'} \Pr(\theta' \, | \, \theta) \, V \left(f(k,\theta) - c, \theta' \right) \end{array}$$

First-order conditions:

$$u'(c) = \beta E V_k(k', \theta')$$

Envelope condition:

$$V_k(k,\theta) = \beta E V_k(k',\theta') f_k(k,\theta)$$

Now we can see why the shortcut works.

Euler Equation

$$u'(c) = \beta \sum_{k} \Pr(\theta'|\theta) V_k(k', \theta')$$

$$= \beta \sum_{k} \Pr(\theta'|\theta) f_k(k', \theta') \underbrace{\left[\beta \sum_{k} \Pr(\theta''|\theta') V_k(k'', \theta'')\right]}_{u'(c')}$$
(16)

Or

$$u'(c) = \beta E\left\{u'(c')f_k(k', \theta')\right\}$$
(18)

Recursive Solution

Solution: $V(k, \theta), c(k, \theta)$ that satisfy:

- 1. Given V, $c(k, \theta)$ maximizes the right-hand-side of the Bellman equation.
- 2. *V* is a fixed point of the Bellman operator:

$$V(k,\theta) = u(c[k,\theta]) + \beta EV(f[k,\theta] - c[k,\theta], \theta')$$
 (19)

Continuous state Markov chains

- What if the random vector takes on a continuum of values?
- Simply replace sums with integrals when calculating expectations.

Continuous state Markov chains

- Assume that $\theta \in \Theta = [\underline{\theta}, \overline{\theta}]$.
- ▶ The evolution of θ is governed by a **transition function**:

$$\Pr\left(\theta' \le x | \theta\right) = \Pi\left(x, \theta\right) \tag{20}$$

- ightharpoonup This is really a cdf conditional on θ .
- ▶ The transition density for this CDF is π with

$$\int_{\underline{\theta}}^{x} \pi(\theta', \theta) d\theta' = \Pi(x, \theta)$$
 (21)

► This is the analogue to the transition matrix $Pr(\theta'|\theta)$ in the discrete case.

Continuous state Markov chains

 \triangleright The conditional expectation of f is then

$$E[f(\theta')|\theta] = \int_{\underline{\theta}}^{\theta} f(\theta') \pi(\theta',\theta) d\theta'$$
$$= \int_{\underline{\theta}}^{\overline{\theta}} f(\theta') \Pi(d\theta',\theta)$$

The point: In the continuous case, simply replace all the $\sum_{\theta'} \Pr(\theta'|\theta)$ with $\int \pi(\theta',\theta) d\theta'$.

Reading

- Acemoglu (2009), ch. 16.1-16.2.
- ► Krusell (2014), ch. 6.
- Stokey et al. (1989) discuss the technical details of stochastic Dynamic Programming.
- ► Ljungqvist and Sargent (2004), ch. 2 talk about Markov chains.

References I

- Acemoglu, D. (2009): *Introduction to modern economic growth*, MIT Press.
- Chow, G. C. (1997): Dynamic Economics: Optimization by the Lagrange Method, Oxford University Press, USA.
- Krusell, P. (2014): "Real Macroeconomic Theory," Unpublished.
- Ljungqvist, L. and T. J. Sargent (2004): *Recursive macroeconomic theory*, 2nd ed.
- Stokey, N., R. Lucas, and E. C. Prescott (1989): "Recursive Methods in Economic Dynamics," .