#### Multilevel models

Mark Andrews Psychology Department, Nottingham Trent University

#### Introduction

- Multilevel models are a broad class of models that are applied to data that consist of sub-groups or clusters, including when these clusters are hierarchically arranged.
- ▶ A number of related terms are used to describe multilevel models: hierarchical models, mixed effects models, random effects models, and more.
- ► The defining feature of multilevel models is that they are *models of models*.
- ▶ In other words, for each cluster or sub-group in our data we create a statistical model, and then model how these statistical models vary across the clusters or sub-groups.

### Plan

- ▶ We will begin our coverage of multilevel models by exploring *random effects* models. These are some of the simplest types of multilevel models, but yet they can make clear the key defining characteristics of the multilevel models generally.
- ▶ We then proceed to cover multilevel linear models, which are often referred to a *linear mixed effects* models.
- After that, we will cover multilevel generalized linear models, which are the generalized linear model counterpart of linear mixed effects models.
- Finally, we will cover how to perform Bayesian multilevel models.

## Random effects models

Let us consider the following data set, which is on rat tumours.

Let us begin by focusing in on a single batch.

```
rats_df_42 <- filter(rats_df, batch == '42')
```

- ► In this batch, out of 13 rats, the recorded number of tumours was 2.
- ▶ With these numbers alone, we can provide a simple statistical model of the tumour rate in batch 42.

# Random effects models

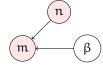
- In this model, we can say that there is a fixed but unknown probability of a tumour in this batch, which we will denote by  $\theta$ .
- ▶ In other words, our model is a binomial model:

$$\mathfrak{m} \sim \text{Binom}(\mathfrak{g}, \mathfrak{n}).$$

This is identical to the following binomial logistic regression model.

$$\mathfrak{m} \sim \operatorname{Binom}(\theta, \mathfrak{n}), \quad \log\left(\frac{\theta}{1-\theta}\right) = \beta.$$

This binomial model can be represented by the following diagram.



► We can implement this binomial logistic model in R using glm.

From this model M, we can see that our estimate of  $\theta$  is as follows:

```
ilogit <- function(x) 1/(1 + exp(-x))
coef(M) %>% ilogit() %>% unname()
#> [1] 0.1538462
```

► This is expected given that out of 13 rats in this batch, the recorded number of tumours was 2, which is a proportion of 0.154.

▶ We can now easily extend this model to apply to all batches in our data set.

et. 
$$\theta_i$$

```
m_j \sim Binom(\theta_j, n_j), \quad log\left(\frac{\theta_j}{1-\theta_i}\right) = \beta_j.
► This is implemented using glm as follows.
```

family = binomial(link = 'logit')

 $M \leftarrow glm(cbind(m, n-m) \sim 0 + batch,$ data = rats df,

► Although we have implemented a single glm model, this has effectively lead to J separate binomial models.

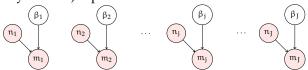


Figure 1: Inferring the log odds of a tumour  $\beta_j$  in each of the J batches is identical to J independent binomial models.

- From this, we have a model of the tumour rate for batch 1, another for batch 2, and so on. We do not have a model of the distribution of tumour rates across all batches.
- ▶ We do not, for example, have a model that gives us the mean or standard deviation, or any other information, about the tumour
- rate across all possible batches in this experiment, of which our set of 71 batches are a sample.

▶ In order to obtain this model, we must perform a *multilevel model*.

► A multilevel model extension of the binomial logistic regression model above is as follows.

$$\begin{split} \text{for } j \in 1 \dots J, \quad m_j \sim \text{Binom}(\theta_j, n_j), \\ \log \left( \frac{\theta_j}{1 - \theta_j} \right) &= \beta_j, \\ \beta_j \sim N(b, \tau^2). \end{split}$$

The crucial added feature here is that the log odds of the tumour probabilities is being modelled as normally distributed with a mean of b and a standard deviation of τ. ► The random effects dependencies are shown in the following Bayesian network diagram.

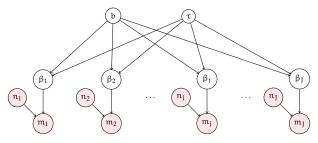


Figure 2: Inferring the log odds of a tumour  $\beta_j$  in each of the J batches is identical to J independent binomial models.

- In this multilevel model, just as in the previous non-multilevel model,  $\beta_1, \beta_2, \dots \beta_1 \dots \beta_I$  have fixed but unknown values.
- ▶ However, in addition, these values are modelled as all drawn from the same normal distribution.
- ► The two important consequences of this are as follows.
- First, it provides a model of the *population* from which  $\beta_1, \beta_2, \dots \beta_1 \dots \beta_I$  are a sample.
- $\triangleright$  Given that each  $\beta_i$  effectively defines a model for a batch of rats, then the normal distribution from which  $\beta_1, \beta_2 \dots \beta_{\bar{1}} \dots \beta_{\bar{1}}$  are
- drawn is a model of models. ightharpoonup Amongst other things, this population model of the  $\beta$ 's allows to predict the log odds, or probability, of a tumour for any future batch of rats, i.e. batch I + 1.

- $\triangleright$  Second, because we are assuming that  $\beta_1, \beta_2, \dots \beta_1 \dots \beta_I$  are all drawn from the same normal distribution, this introduces
- constraints on the inference of the values of each  $\beta_i$ . In other words, to infer the value of  $\beta_i$ , the observed values of  $m_i$ and  $n_i$  are not the only relevant pieces of information.
- Now, the values of b and  $\tau$  are also relevant, and because b and  $\tau$ are also unknown, they themselves must be inferred from
- $\beta_1, \beta_2, \dots \beta_1 \dots \beta_1$ . ► This effectively means that the inferences concerning  $\beta_1, \beta_2, \dots \beta_1 \dots \beta_1$  are inter-dependent and mutually constrain one another.

▶ Given that we can rewrite  $\beta_j \sim N(b, \tau^2)$  as  $\beta_j = b + \xi_j$  where  $\xi_j \sim N(0, \tau^2)$ , we can rewrite the multilevel model as

for 
$$j \in 1...J$$
,  $m_j \sim Binom(\theta_j, n_j)$ , 
$$\log\left(\frac{\theta_j}{1-\theta_j}\right) = b + \xi_j,$$

▶ We can then implement this model using the glmer model that is part of the lme4 package.

 $\xi_i \sim N(0, \tau^2).$ 

### Let us look at the summary of this model.

```
summary(M_ml)
#> Generalized linear mixed model fit by maximum likelihood (Laplace
#> Approximation) [qlmerMod]
#> Family: binomial ( logit )
\# Formula: cbind(m, n - m) \sim 1 + (1 \mid batch)
#> Data: rats df
#>
#> AIC BIC logLik deviance df.resid
#> 319.9 324.4 -157.9 315.9 69
#>
#> Scaled residuals:
#> Min 1Q Median 3Q Max
#> -1.2392 -0.6230 -0.1055 0.4795 1.0253
#>
#> Random effects:
#> Groups Name Variance Std.Dev.
#> batch (Intercept) 0.4417 0.6646
#> Number of obs: 71, groups: batch, 71
#>
#> Fixed effects:
#> Estimate Std. Error z value Pr(>|z|)
#> (Intercept) -1.9369 0.1211 -16 <2e-16 ***
#> ---
#> Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
```

► From the summary, our model of the distribution of the log odds of the tumours is a normal distribution whose mean and standard deviation are estimated to be -1.937 and 0.665, respectively.

From this model, we can also obtain the estimates of  $\xi_1, \xi_2 \dots \xi_j \dots \xi_J$ from the model by using the ranef command.

```
ranef(M ml)$batch %>%
 head()
#> (Intercept)
#> 1 -0.6298720
```

#> 10 -0.6096908 *#> 11 -0.6096908 #> 12 -0.5888596* #> 13 -0.5888596 #> 14 -0.5673326 ▶ We may obtain the estimates of b using the fixef command.

b <- fixef(M ml)

 $\beta_1, \beta_2 \dots \beta_1 \dots \beta_I$ .

b + ranef(M\_ml)\$batch %>%

head() #> (Intercept)

#> 1 -2.566785

#> 12 -2.525773

#> 13 -2.525773

#> 10 -2.546604 #> 11 -2.546604

#> 14 -2.504246

▶ We may then add on the estimates of b to get the estimates of

▶ We may obtain the estimates of  $\beta_1, \beta_2 \dots \beta_1 \dots \beta_I$  more directly by using the coef command.

- #> (Intercept)

- #> 1 -2.566785
- #> 10 -2.546604
- #> 11 -2.546604
- #> 12 -2.525773

#> 13 -2.525773 *#> 14 -2.504246* 

- Comparing these values to the corresponding values in the non-multilevel model, we can see how the estimates of  $\beta_1, \beta_2 \dots \beta_j \dots \beta_J$  mutually constrain one another.
- ▶ This phenomenon is an example of *shrinkage*. In this model, it is easier to visualize this effect if we look at  $\theta_1, \theta_2 \dots \theta_j \dots \theta_J$ , which

are simply the inverse logit transforms of  $\beta_1, \beta_2 \dots \beta_j \dots \beta_J$ .

In Figure 3, we compare the estimates of  $\theta_1, \theta_2 \dots \theta_j \dots \theta_J$  from the flat or non-multilevel model M against those of the multilevel model M\_ml.

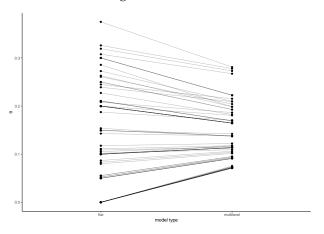


Figure 3: Estimates for  $\theta_1, \theta_2 \dots \theta_j \dots \theta_J$  from the flat or non-multilevel model (left) and the multilevel model (right).

# Normal random effects models

Let us now consider a new data set.

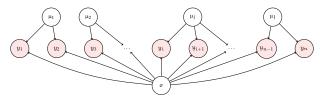
```
alcohol_df <- read_csv(here('data/alcohol.csv'))</pre>
```

- ▶ In this, we have the per capita average alcohol consumption in J=189 countries in K=22 different years, though we do not necessarily have data from each country in each year. Let us denote the per capita alcohol values by  $y_1, y_2 \dots y_i \dots y_n$ . For each  $y_i$ , we have an indicator variable  $x_i \in 1 \dots J$ , which indicates the country that  $y_i$  corresponds to.
- An initial model for  $y_1, y_2 ... y_i ... y_n$  could then be

$$y_i \sim N(\mu_{[x_i]}, \sigma^2), \text{ for } i \in 1...n,$$

where  $\mu_1, \mu_2 \dots \mu_j \dots \mu_J$  are the country alcohol per capita consumption averages for the J countries.

This model be represented by the Bayesian network diagram shown in Figure ??.



This is a non-multilevel model because the alcohol consumption averages in each country are being modelled independently of those of other countries. A multilevel counterpart to the above model would be as follows.

$$y_i \sim N(\mu_{[x_i]}, \sigma^2), \text{ for } i \in 1 \dots n,$$
  
 $\mu_i \sim N(\phi, \tau^2), \text{ for } j \in 1 \dots J.$ 

\*This model, which is depicted by a Bayesian network diagram in Figure ??, extends the previous one by assuming that the  $\mu_1, \mu_2 \dots \mu_j \dots \mu_J$  are drawn from a normal distribution with mean  $\varphi$  and standard deviation of  $\tau$ .

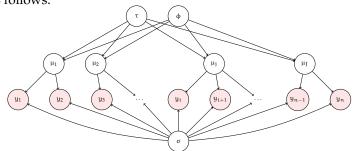
▶ Given that  $y_i$  can be rewritten as  $y_i = \mu_{[x_i]} + \varepsilon_i$ , where  $\varepsilon_i \sim N(0, \sigma^2)$ , and that  $\mu_j$  can be rewritten as  $\mu_j = \varphi + \xi_j$  where  $\xi_j \sim N(0, \tau^2)$ , we can rewrite the above model as

$$y_i = \phi + \xi_{[x_i]} + \epsilon_i$$
, for  $i \in 1...n$ ,

where each  $\xi_i \sim N(0, \tau^2)$  and each  $\varepsilon_i \sim N(0, \sigma^2)$ .

- Here, φ signifies the global average per capita alcohol consumption rate.
- Each  $\xi_j$  is the *random offset* of country j from φ, and each  $\varepsilon_i$  is the residual error for each observation.
- In this model, the residual error  $\epsilon_i$  gives the random year by year deviation from the country  $x_i$ 's average consumption rate.

► The Bayesian model of this random effects normal linear model is as follows:



We can implement this model using lme4::lmer as follows.

- The (Intercept) estimate in the Fixed effects and the Std.Dev. for country in the Random effects, the normal distribution of the  $\mu$  values has a mean of  $\phi = 6.661$  and standard deviation of  $\tau = 4.713$ .
- The residual standard deviation  $\sigma$  is given by the Std.Dev. for Residual in the Random effects, and has the value of  $\sigma = 1.053$ .

### Intraclass correlation

- ▶ Given the nature of the random effects model, i.e. each  $y_i$  is modelled as  $y_i = \phi + \xi_{[x_i]} + \varepsilon_i$ , the variance of y is equal to  $\tau^2 + \sigma^2$ .
- ► The value

$$\frac{\tau^2}{\tau^2 + \sigma^2}$$

is known as the *intraclass correlation* (ICC), which takes on values between 0 and 1.

- ▶ Obviously, ICC tells us how much of the total variance in the data is due to variation between the countries.
- ▶ If the ICC is relatively high, and so  $\tau^2/\sigma^2$  is relatively high, the observed values *within* countries will be close together relative to the *between* country averages, and thus there will be relatively high clustering of the data.
- ▶ In this data, the ICC is 0.95.

# Linear mixed effects models

- ▶ We will now consider multilevel linear regression models.
- ▶ These are often referred to as linear mixed effects models, for reasons that will be clear after we describe them in more detail.
- As with random effects models, these models are best introduced by way of example.
- ▶ For this, we will use he sleepstudy data set from lme4, which provides the average reaction time for each person on each day of a sleep deprivation experiment that lasted 10 days.

```
sleepstudy <- lme4::sleepstudy %>%
  as_tibble()
```

# Sleep deprivation study

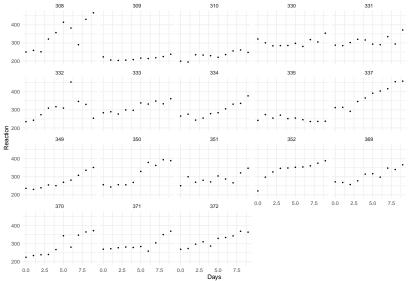


Figure 4: Each figure shows the average reaction time data from a subject in sleep deprivation on each day of the 10 day experiment.

- ► To begin our analysis, let us first focus on one arbitrarily chosen experimental subject, namely subject 350.
- ► The trend over time in this subject's average reaction time can be modelled using the following normal linear model:

$$y_d \sim N(\mu_d, \sigma^2), \quad \mu_d = \beta_0 + \beta_1 x_d, \quad \text{for } d \in 1 \dots n,$$

where  $y_d$  represents the subject's reaction time on their dth observation, and  $x_d \in \{0,2,\dots n=9\}$  indicates the day when this observation happened.

Using  $\vec{\beta} = [\beta_0, \beta_1]^\mathsf{T}$ , we can represent this model using a Bayesian network diagram as we do in Figure 5. In that figure, we provide two equivalent diagrams, with Figure 5b using a plate notation that denotes a repetition of nodes within a bounding plate according to an index, which in this case is  $d \in 1 \dots n$ .

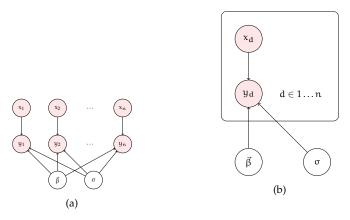


Figure 5: Two equivalent Bayesian network diagrams representing a normal linear model with one predictor variable. Diagram b) uses a compact plate notation whereby all variables within the plate are repeated for all values of the index i, which takes values from 1 to n.

► This model is implemented in R as follows.

```
M_350 <- lm(Reaction ~ Days, data = sleepstudy_350)
```

► The estimated values of the coefficients are as follows.

```
#> (Intercept) Days
#> 225.83460 19.50402
```

- ► Thus, we estimate that the average reaction time of subject 350 increases by 19.5 on each day of study.
- In addition, because the first day of the study was indicated by x<sub>i</sub> = 0, this subject's average reaction prior to any sleep deprivation was 225.83.

- Were we to provide a similar model for each subject in the experiment, whom we will index by  $j \in 1...J$ , this would lead to J independent normal linear models.
- ► If we denote the average reaction time on observation d for subject j by y<sub>id</sub>, this set of models is as follows.

$$y_{jd} \sim N(\mu_{jd}, \sigma_j^2),$$
  
 $\mu_{jd} = \beta_{j0} + \beta_{j1}x_{jd}, \text{ for } j \in 1...J, \text{ for } d \in 1...n_j.$ 

► This model is represented in a Bayesian network diagram in Figure 6a.

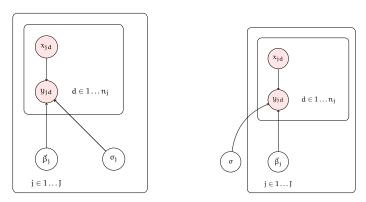


Figure 6: Bayesian network diagrams for a) a set of J independent normal linear models, and b) a varying slope and varying intercept linear model whereby the slope and intercept vary by a categorical variable with J levels.

▶ If we assume that there is a common residual standard deviation term  $\sigma$ , rather than one per each of the J subjects, this model is identical to a varying intercept and varying slope linear model.

▶ Using R, we can implement this model as follows.

M\_flat <- lm(Reaction ~ 0 + Subject + Subject:Days, data = sleep

Formally, this model is equivalent to

 $y_{id} \sim N(\mu_{id}, \sigma^2)$ ,

and we have provided a Bayesian network diagram of it in Figure 6b.

 $\mu_{id} = \beta_{i0} + \beta_{i1}x_{id}$ , for  $j \in 1...J$ , for  $d \in 1...n_i$ ,

- Let us now consider a multilevel variant of this non-multilevel varying intercept and slope model.
- ▶ In this, we assume that the vector of coefficients  $\vec{\beta}_j = [\beta_{j0}, \beta_{j1}]^T$  is drawn from a multivariate Normal distribution with mean vector  $\vec{b}$  and covariance matrix Σ.
- ▶ This model can be written as follows.

$$\begin{split} &y_{jd} \sim N(\mu_{jd},\sigma), \\ &\mu_{jd} = \beta_{j0} + \beta_{j1}x_{jd}, \quad \text{for } j \in 1 \dots J, \text{for } d \in 1 \dots n_{j,\prime\prime} \\ &\vec{\beta}_{j} \sim N(\vec{b},\Sigma) \quad \text{for } j \in 1 \dots J, \end{split}$$

- ► The Bayesian network diagram for this model is shown in Figure 7.
- As we can see, this is an extension of the Bayesian network diagram in Figure 6b, with the extension being that each  $\vec{\beta}_j$  are modelled as functions of  $\vec{b}$  and Σ.

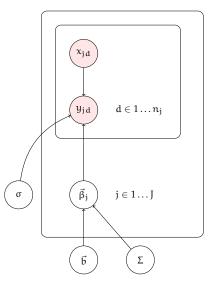


Figure 7: Bayesian network diagrams for a multilevel varying slopes and intercepts linear model.

▶ We can rewrite this multilevel model in the following manner.

for 
$$i \in 1...n$$
,  $y_i \sim N(\mu_i, \sigma^2)$ , 
$$\mu_i = \beta_{[s_i]0} + \beta_{[s_i]1}x_i$$
, for  $j \in 1...J$ ,  $\vec{\beta}_i \sim N(\vec{b}, \Sigma)$ .

- Note that here the i index ranges over all values in the entire data-set, i.e.  $i \in 1, 2...n$ , and each  $s_i \in 1, 2...J$  is an indicator variable that indicates the identity of the subject on observation i.
- ► This notation with a single subscript per observation and indicator variables is more extensible, especially for complex models.
- Using this new notation, given that  $\vec{\beta}_j \sim N(\vec{b}, \Sigma)$ , we can rewrite  $\vec{\beta}_j$  as  $\vec{\beta}_j = \vec{b} + \vec{\zeta}_j$  where  $\vec{\zeta}_j \sim N(0, \Sigma)$ .

Substituting  $\vec{b} + \zeta_i$  for  $\vec{\beta}$ , and thus substituting  $b_0 + \zeta_{i0}$  and  $b_1 + \zeta_{i1}$  for  $\beta_{i0}$  and  $\beta_{i1}$ , respectively, we have the following model.

$$\begin{aligned} \text{for } i \in 1 \dots n, \quad y_i \sim N(\mu_i, \sigma^2), \\ \mu_i &= \underbrace{b_0 + b_1 x_i}_{\text{fixed effects}} + \underbrace{\zeta_{[s_i]0} + \zeta_{[s_i]1} x_i}_{\text{random effects}}, \\ \text{for } j \in 1 \dots J, \quad \vec{\zeta}_i \sim N(0, \Sigma). \end{aligned}$$

► As we can see from this, a multilevel normal linear model is

equivalent to a non-multilevel model (the fixed effects models) plus a normally distributed random variation to the intercept and slope for each subject (the *random effects*).

- ► The fixed effects are sometimes known as *population level* effects: they apply to all observations.
- The random effects, on the other hand, vary across each different value of the grouping variable, which in this example is an individual participant in the experiment.
- Put another way, the fixed effects give the average effects in the population.
- The extent to which each individual varies around this average is given by the random effects.
   That the multilevel linear model can be described in terms of fixed.
- ▶ That the multilevel linear model can be described in terms of fixed and random effects is why these models are known as a *linear mixed effects model*.

▶ We can implement this model in R using lme4::lmer.

- ► The syntax here matches the fixed and random effects description of the model.
- ► The Reaction ~ Days tells us that the fixed effects model is a simple linear regression model with one predictor, and so with one intercept and one slope term.
- ► The (Days|Subjects) tells us that there is random variation to the slope for Days and implicitly there's also random variation to the intercept term.
- ▶ We could make the variation to the intercept term explicit by writing (1 + Days|Subject), which is identical to (Days|Subject) because the 1 + is included always by default just as it is included by default in fixed effects part, as it is in any R regression formula syntax.

▶ The results of this model is obtained as follows.

```
summary(M_ml)
```

▶ The value of  $\vec{b}$  is available under Estimate in the Fixed effects, and we can get these directly as follows.

```
b <- fixef(M_ml)
b
#> (Intercept) Days
#> 251.40510 10.46729
```

- ▶ Thus, the average effect of sleep deprivation on reaction time across all individuals is that their reaction time increases by 10.47 each day.
- ▶ Also, the average individual has an average reaction time of 251.41 on day 0 of the experiment, which means that this is the average reaction time of the average person generally.

- The values in the covariance matrix Σ and of the residual standard deviation σ can be obtained from the values provided under Random effects.
- ► These are available more directly as follows.

▶ Note that the covariance matrix is defined as follows.

$$\Sigma = \begin{bmatrix} \tau_0^2 & \tau_0 \rho \tau_1 \\ \tau_0 \rho \tau_1 & \tau_1^2 \end{bmatrix}.$$

► The estimates of each  $\vec{\beta}_j$  for  $j \in 1...J$  can be obtained using the coef function.

*#> 309 211.0064 1.847605* #> 331 273.6654 7.397374 

## Shrikage

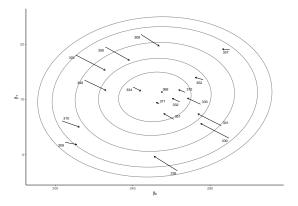


Figure 8: The contour plot shows the contours of the 2d normal distribution centered at  $\vec{b}$  and whose covariance matrix is  $\Sigma$ .

## Varying intercepts or varying slopes only models

- The above model allowed for random variation in both the intercepts and slopes but we can choose to have random variation in only one or the other.
- ► A varying intercept only multilevel model is defined as follows.

$$\begin{split} \text{for } i \in 1 \dots n, \quad y_i \sim N(\mu_i, \sigma^2), \\ \mu_i &= \beta_{\lceil s_i \rceil 0} + b_1 x_i, \\ \text{for } j \in 1 \dots J, \quad \beta_{j0} \sim N(b_0, \tau_0^2), \end{split}$$

which can be rewritten, using the same reasoning as above,

$$\begin{split} \text{for } i \in 1 \dots n, \quad y_i \sim N(\mu_i, \sigma^2), \\ \mu_i &= b_0 + b_1 x_i + \zeta_{[s_i]0}, \\ \text{for } j \in 1 \dots J, \quad \zeta_{j0} \sim N(0, \tau_0^2). \end{split}$$

▶ Using lmer, we would implement this as follows.

► The fixed effects give us an estimate of the slope and intercept as before.

```
fixef(M_ml_vi)
#> (Intercept) Days
#> 251.40510 10.46729
```

The random effects just provide a measure of standard deviation  $\tau_0$  for the random intercepts as well as residual standard deviation  $\sigma$ .

```
VarCorr(M_ml_vi)
#> Groups Name Std.Dev.
#> Subject (Intercept) 37.124
#> Residual 30.991
```

Absent here, compared to the varying intercepts and varying slopes model is the estimate for  $\tau_1$  and  $\rho$ .

## Varying slope only

- ► The varying slope only multilevel model allows only the slopes to vary across subjects and it leaves the intercepts fixed.
- ► It is defined as follows.

$$\begin{split} \text{for } i \in 1 \dots n, \quad y_i \sim N(\mu_i, \sigma^2), \\ \mu_i &= b_0 + \beta_{\lceil s_i \rceil 1} + x_i, \\ \text{for } j \in 1 \dots J, \quad \beta_{j1} \sim N(b_0, \tau_1^2), \end{split}$$

which can be rewritten

$$\begin{split} \text{for } i \in 1 \dots n, \quad y_i \sim N(\mu_i, \sigma^2), \\ \mu_i &= b_0 + b_1 x_i + \zeta_{[s_i]1} x_i, \\ \text{for } j \in 1 \dots J, \quad \zeta_{j1} \sim N(0, \tau_1^2). \end{split}$$

▶ Using lmer, we would implement this as follows.

► The fixed effects give us an estimate of both the slope and intercept as with the previous models.

```
fixef(M_ml_vs)
#> (Intercept) Days
#> 251.40510 10.46729
```

The random effect provide a measure of standard deviation  $\tau_1$  and  $\sigma$ .

```
VarCorr(M_ml_vs)
#> Groups Name Std.Dev.
#> Subject Days 7.260
#> Residual 29.018
```

Absent here compared to the full model is the estimate for  $\tau_0$  and  $\rho$ .

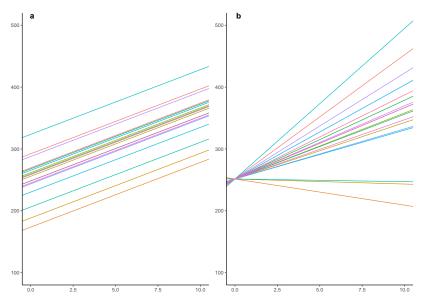


Figure 9: Lines of best fit for each data group in a varying intercepts only a) or varying slopes only b) multilevel linear model.

- ▶ One final variant of the full model is where we allow for both varying slopes and intercepts but assume no correlation between each  $\beta_{i0}$  and  $\beta_{i1}$ .
- ► In other words, we assume that these are drawn from independent normal distributions.

$$\begin{split} \text{for } i \in 1 \dots n, \quad y_i \sim N(\mu_i, \sigma^2), \\ \mu_i &= \beta_{\lceil s_i \rceil 0} + \beta_{\lceil s_i \rceil 1} x_i, \\ \text{for } j \in 1 \dots J, \quad \beta_{j0} \sim N(b_0, \tau_0^2), \\ \beta_{j1} \sim N(b_1, \tau_1^2), \end{split}$$

which is identical to each  $\beta_j$  vector being drawn from a diagonal covariance matrix, i.e. where  $\rho = 0$ .

▶ Using lmer, we would implement this as follows.

► We can obtain the same model using the following formula syntax.

► The fixed effects give us an estimate of both the slope and intercept as with each of the previous models.

```
fixef(M_ml_diag2)
#> (Intercept) Days
#> 251.40510 10.46729
```

► The random effect provide a measure of the  $\tau_0$ ,  $\tau_1$  and  $\sigma$  standard deviations.

```
VarCorr(M_ml_diag2)

#> Groups Name Std.Dev.

#> Subject (Intercept) 25.0513

#> Subject.1 Days 5.9882

#> Residual 25.5653
```

The only quantity that is absent here compared to the full model is the estimate for ρ.