Multilevel models

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Introduction

- Multilevel models are a broad class of models that are applied to data that consist of sub-groups or clusters, including when these clusters are hierarchically arranged.
- ▶ A number of related terms are used to describe multilevel models: hierarchical models, mixed effects models, random effects models, and more.
- ► The defining feature of multilevel models is that they are *models of models*.
- ▶ In other words, for each cluster or sub-group in our data we create a statistical model, and then model how these statistical models vary across the clusters or sub-groups.

Plan

- ▶ We will begin our coverage of multilevel models by exploring *random effects* models. These are some of the simplest types of multilevel models, but yet they can make clear the key defining characteristics of the multilevel models generally.
- ▶ We then proceed to cover multilevel linear models, which are often referred to a *linear mixed effects* models.
- After that, we will cover multilevel generalized linear models, which are the generalized linear model counterpart of linear mixed effects models.
- Finally, we will cover how to perform Bayesian multilevel models.

Random effects models

Let us consider the following data set, which is on rat tumours.

Let us begin by focusing in on a single batch.

```
rats_df_42 <- filter(rats_df, batch == '42')</pre>
```

- ► In this batch, out of 13 rats, the recorded number of tumours was 2.
- ▶ With these numbers alone, we can provide a simple statistical model of the tumour rate in batch 42.

Random effects models

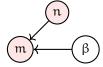
- In this model, we can say that there is a fixed but unknown probability of a tumour in this batch, which we will denote by θ .
- ▶ In other words, our model is a binomial model:

$$\mathfrak{m} \sim \operatorname{Binom}(\mathfrak{g}, \mathfrak{n}).$$

► This is identical to the following binomial logistic regression model.

$$\mathfrak{m} \sim \operatorname{Binom}(\theta, \mathfrak{n}), \quad \log\left(\frac{\theta}{1-\theta}\right) = \beta.$$

This binomial model can be represented by the following diagram.



▶ We can implement this binomial logistic model in R using glm.

From this model M, we can see that our estimate of θ is as follows:

```
ilogit <- function(x) 1/(1 + exp(-x))
coef(M) %>% ilogit() %>% unname()
#> [1] 0.1538462
```

► This is expected given that out of 13 rats in this batch, the recorded number of tumours was 2, which is a proportion of 0.154.

We can now easily extend this model to apply to all batches in our data set.

$$m_j \sim Binom(\theta_j, n_j), \quad log\left(\frac{\theta_j}{1 - \theta_i}\right) = \beta_j.$$

► This is implemented using glm as follows.

► Although we have implemented a single glm model, this has effectively lead to J separate binomial models.

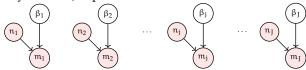


Figure 1: Inferring the log odds of a tumour β_j in each of the J batches is identical to J independent binomial models.

- ► From this, we have a model of the tumour rate for batch 1, another for batch 2, and so on. We do not have a model of the distribution of tumour rates across all batches.
- ▶ We do not, for example, have a model that gives us the mean or standard deviation, or any other information, about the tumour rate across all possible batches in this experiment, of which our set of 71 batches are a sample.
- ▶ In order to obtain this model, we must perform a *multilevel model*.

► A multilevel model extension of the binomial logistic regression model above is as follows.

$$\begin{split} \text{for } j \in 1 \dots J, \quad m_j \sim Binom(\theta_j, n_j), \\ \log\left(\frac{\theta_j}{1-\theta_j}\right) &= \beta_j, \\ \beta_j \sim N(b, \tau^2). \end{split}$$

The crucial added feature here is that the log odds of the tumour probabilities is being modelled as normally distributed with a mean of b and a standard deviation of τ .

► The random effects dependencies are shown in the following Bayesian network diagram.

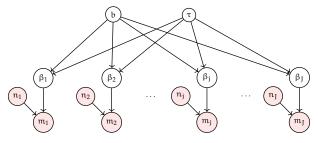


Figure 2: Inferring the log odds of a tumour β_j in each of the J batches is identical to J independent binomial models.

- ▶ In this multilevel model, just as in the previous non-multilevel model, $\beta_1, \beta_2, \dots \beta_{\bar{1}} \dots \beta_{\bar{1}}$ have fixed but unknown values.
- ► However, in addition, these values are modelled as all drawn from the same normal distribution.
- ► The two important consequences of this are as follows.
- First, it provides a model of the *population* from which $\beta_1, \beta_2, \dots \beta_j \dots \beta_J$ are a sample.
- ▶ Given that each β_j effectively defines a model for a batch of rats, then the normal distribution from which $\beta_1, \beta_2 \dots \beta_j \dots \beta_J$ are drawn is a *model of models*.
- Amongst other things, this population model of the β's allows to predict the log odds, or probability, of a tumour for any future batch of rats, i.e. batch J + 1.

- ▶ Second, because we are assuming that $\beta_1, \beta_2, \dots \beta_j \dots \beta_J$ are all drawn from the same normal distribution, this introduces constraints on the inference of the values of each β_i .
- ▶ In other words, to infer the value of β_j , the observed values of m_j and n_j are not the only relevant pieces of information.
- Now, the values of b and τ are also relevant, and because b and τ are also unknown, they themselves must be inferred from $\beta_1, \beta_2, \dots \beta_1 \dots \beta_1$.
- ► This effectively means that the inferences concerning $\beta_1, \beta_2, \dots \beta_j \dots \beta_J$ are inter-dependent and mutually constrain one another.

 $\begin{tabular}{l} \blacksquare & Given that we can rewrite $\beta_j \sim N(b,\tau^2)$ as $\beta_j = b + \xi_j$ where $\xi_j \sim N(0,\tau^2)$, we can rewrite the multilevel model as $\xi_j \sim N(0,\tau^2)$.} \label{eq:continuous_problem}$

$$\begin{split} \text{for } j \in 1 \dots J, \quad m_j \sim \text{Binom}(\theta_j, n_j), \\ \log\left(\frac{\theta_j}{1-\theta_j}\right) &= b + \xi_j, \\ \xi_i \sim N(0, \tau^2). \end{split}$$

► We can then implement this model using the glmer model that is part of the lme4 package.

Let us look at the summary of this model.

```
summary(M_ml)
#> Generalized linear mixed model fit by maximum likelihood (Laplace
#> Approximation) [glmerMod]
#> Family: binomial ( logit )
\# Formula: cbind(m, n - m) \sim 1 + (1 \mid batch)
#> Data: rats df
#>
#> AIC BIC logLik deviance df.resid
#> 319.9 324.4 -157.9 315.9
#>
#> Scaled residuals:
#> Min 1Q Median 3Q Max
#> -1.2392 -0.6230 -0.1055 0.4795 1.0253
#>
#> Random effects:
#> Groups Name Variance Std.Dev.
#> batch (Intercept) 0.4417 0.6646
#> Number of obs: 71, groups: batch, 71
#>
#> Fixed effects:
#>
        Estimate Std. Error z value Pr(>|z|)
#> (Intercept) -1.9369 0.1211 -16 <2e-16 ***
#> ---
#> Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
```

► From the summary, our model of the distribution of the log odds of the tumours is a normal distribution whose mean and standard deviation are estimated to be -1.937 and 0.665, respectively.

From this model, we can also obtain the estimates of $\xi_1, \xi_2 \dots \xi_j \dots \xi_J$ from the model by using the ranef command.

```
ranef(M_ml)$batch %>%
head()

#> (Intercept)

#> 1  -0.6298720

#> 10  -0.6096908

#> 11  -0.6096908

#> 12  -0.5888596

#> 13  -0.5888596

#> 14  -0.5673326
```

▶ We may obtain the estimates of b using the fixef command.

```
b <- fixef(M_ml)
```

▶ We may then add on the estimates of b to get the estimates of $\beta_1, \beta_2 \dots \beta_j \dots \beta_J$.

```
b + ranef(M_ml)$batch %>%
head()

#> (Intercept)

#> 1  -2.566785

#> 10  -2.546604

#> 11  -2.546604

#> 12  -2.525773

#> 13  -2.525773

#> 14  -2.504246
```

▶ We may obtain the estimates of $\beta_1, \beta_2 \dots \beta_j \dots \beta_J$ more directly by using the coef command.

```
M_ml_estimates <- coef(M_ml)$batch</pre>
M ml estimates %>%
 head()
#> (Intercept)
#> 1 -2.566785
#> 10 -2.546604
#> 11 -2.546604
#> 12 -2.525773
#> 13 -2.525773
#> 14 -2.504246
```

- ► Comparing these values to the corresponding values in the non-multilevel model, we can see how the estimates of $\beta_1, \beta_2 ... \beta_1 ... \beta_1$ mutually constrain one another.
- ► This phenomenon is an example of *shrinkage*. In this model, it is easier to visualize this effect if we look at $\theta_1, \theta_2 \dots \theta_j \dots \theta_J$, which are simply the inverse logit transforms of $\beta_1, \beta_2 \dots \beta_j \dots \beta_J$.

In Figure 3, we compare the estimates of $\theta_1, \theta_2 \dots \theta_j \dots \theta_J$ from the flat or non-multilevel model M against those of the multilevel model M_ml.

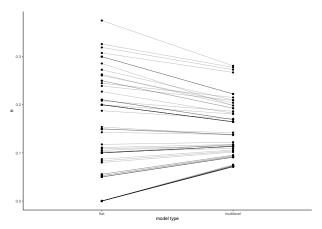


Figure 3: Estimates for $\theta_1, \theta_2 \dots \theta_j \dots \theta_J$ from the flat or non-multilevel model (left) and the multilevel model (right).

Normal random effects models

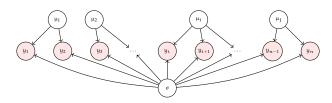
Let us now consider a new data set.

```
alcohol_df <- read_csv(here('data/alcohol.csv'))</pre>
```

- ▶ In this, we have the per capita average alcohol consumption in J=189 countries in K=22 different years, though we do not necessarily have data from each country in each year. Let us denote the per capita alcohol values by $y_1, y_2 \dots y_i \dots y_n$. For each y_i , we have an indicator variable $x_i \in 1 \dots J$, which indicates the country that y_i corresponds to.
- An initial model for $y_1, y_2 ... y_i ... y_n$ could then be

$$y_i \sim N(\mu_{[x_i]}, \sigma^2), \quad \text{for } i \in 1 \dots n,$$

where $\mu_1, \mu_2 \dots \mu_J \dots \mu_J$ are the country alcohol per capita consumption averages for the J countries.



This is a non-multilevel model because the alcohol consumption averages in each country are being modelled independently of those of other countries.

A multilevel counterpart to the above model would be as follows.

$$\begin{split} y_i \sim N(\mu_{[x_i]}, \sigma^2), & \text{ for } i \in 1 \dots n, \\ \mu_j \sim N(\varphi, \tau^2), & \text{ for } j \in 1 \dots J. \end{split}$$

* This model extends the previous one by assuming that the $\mu_1, \mu_2 \dots \mu_j \dots \mu_J$ are drawn from a normal distribution with mean φ and standard deviation of τ .

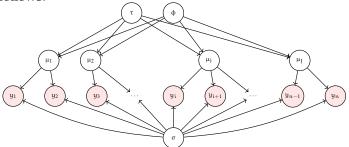
▶ Given that y_i can be rewritten as $y_i = \mu_{[x_i]} + \varepsilon_i$, where $\varepsilon_i \sim N(0, \sigma^2)$, and that μ_j can be rewritten as $\mu_j = \varphi + \xi_j$ where $\xi_j \sim N(0, \tau^2)$, we can rewrite the above model as

$$y_i = \phi + \xi_{[x_i]} + \varepsilon_i$$
, for $i \in 1...n$,

where each $\xi_j \sim N(0, \tau^2)$ and each $\varepsilon_i \sim N(0, \sigma^2)$.

- Here, φ signifies the global average per capita alcohol consumption rate.
- **Each** ξ_j is the *random offset* of country j from φ, and each ε_i is the residual error for each observation.
- In this model, the residual error ε_i gives the random year by year deviation from the country x_i 's average consumption rate.

► The Bayesian model of this random effects normal linear model is as follows:



We can implement this model using lme4::lmer as follows.

- ▶ The (Intercept) estimate in the Fixed effects and the Std.Dev. for country in the Random effects, the normal distribution of the μ values has a mean of $\phi=6.661$ and standard deviation of $\tau=4.713$.
- The residual standard deviation σ is given by the Std.Dev. for Residual in the Random effects, and has the value of $\sigma = 1.053$.

Intraclass correlation

- Figure 3. Given the nature of the random effects model, i.e. each y_i is modelled as $y_i = \phi + \xi_{[x_i]} + \varepsilon_i$, the variance of y is equal to $\tau^2 + \sigma^2$.
- ► The value

$$\frac{\tau^2}{\tau^2+\sigma^2}$$

is known as the *intraclass correlation* (ICC), which takes on values between 0 and 1.

- ▶ Obviously, ICC tells us how much of the total variance in the data is due to variation between the countries.
- ▶ If the ICC is relatively high, and so τ^2/σ^2 is relatively high, the observed values *within* countries will be close together relative to the *between* country averages, and thus there will be relatively high clustering of the data.
- ► In this data, the ICC is 0.95.

Linear mixed effects models

- ▶ We will now consider multilevel linear regression models.
- ► These are often referred to as linear mixed effects models, for reasons that will be clear after we describe them in more detail.
- As with random effects models, these models are best introduced by way of example.
- ► For this, we will use he sleepstudy data set from lme4, which provides the average reaction time for each person on each day of a sleep deprivation experiment that lasted 10 days.

```
sleepstudy <- lme4::sleepstudy %>%
  as_tibble()
```

Sleep deprivation study

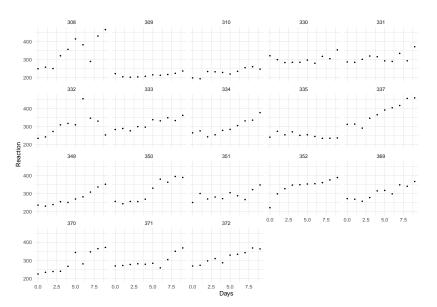


Figure 4: Each figure shows the average reaction time data from a subject in

- ► To begin our analysis, let us first focus on one arbitrarily chosen experimental subject, namely subject 350.
- ► The trend over time in this subject's average reaction time can be modelled using the following normal linear model:

$$y_d \sim N(\mu_d, \sigma^2)$$
, $\mu_d = \beta_0 + \beta_1 x_d$, for $d \in 1...n$,

where y_d represents the subject's reaction time on their dth observation, and $x_d \in \{0,2,\dots n=9\}$ indicates the day when this observation happened.

Using $\vec{\beta} = [\beta_0, \beta_1]^\mathsf{T}$, we can represent this model using a Bayesian network diagram as we do in Figure 5. In that figure, we provide two equivalent diagrams, with Figure 5b using a plate notation that denotes a repetition of nodes within a bounding plate according to an index, which in this case is $d \in 1 \dots n$.

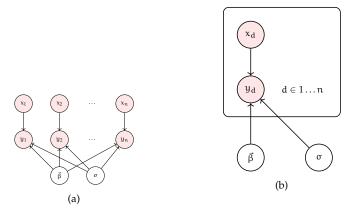


Figure 5: Two equivalent Bayesian network diagrams representing a normal linear model with one predictor variable. Diagram b) uses a compact plate notation whereby all variables within the plate are repeated for all values of the index i, which takes values from 1 to n.

▶ This model is implemented in R as follows.

```
M_350 <- lm(Reaction ~ Days, data = sleepstudy_350)
```

▶ The estimated values of the coefficients are as follows.

```
#> (Intercept) Days
#> 225.83460 19.50402
```

- ► Thus, we estimate that the average reaction time of subject 350 increases by 19.5 on each day of study.
- In addition, because the first day of the study was indicated by $x_i = 0$, this subject's average reaction prior to any sleep deprivation was 225.83.

- ▶ Were we to provide a similar model for each subject in the experiment, whom we will index by $j \in 1...J$, this would lead to J independent normal linear models.
- ▶ If we denote the average reaction time on observation d for subject j by y_{jd} , this set of models is as follows.

$$\begin{split} &y_{j\,d} \sim N(\mu_{j\,d},\sigma_j^2),\\ &\mu_{j\,d} = \beta_{j0} + \beta_{j1}x_{j\,d}, \quad \text{for } j \in 1\dots J, \text{for } d \in 1\dots n_j. \end{split}$$

► This model is represented in a Bayesian network diagram in Figure 6a.

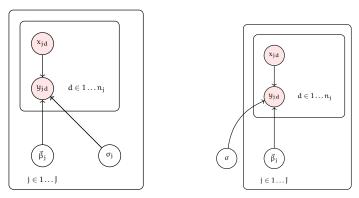


Figure 6: Bayesian network diagrams for a) a set of J independent normal linear models, and b) a varying slope and varying intercept linear model whereby the slope and intercept vary by a categorical variable with J levels.

- ▶ If we assume that there is a common residual standard deviation term σ , rather than one per each of the J subjects, this model is identical to a varying intercept and varying slope linear model.
- ▶ Using R, we can implement this model as follows.

Formally, this model is equivalent to

$$\begin{split} &y_{j,d} \sim N(\mu_{j,d}, \sigma^2), \\ &\mu_{j,d} = \beta_{j0} + \beta_{j1} x_{j,d}, \quad \text{for } j \in 1 \dots J, \text{for } d \in 1 \dots n_j, \end{split}$$

and we have provided a Bayesian network diagram of it in Figure 6b.

- Let us now consider a multilevel variant of this non-multilevel varying intercept and slope model.
- In this, we assume that the vector of coefficients $\vec{\beta}_j = [\beta_{j0}, \beta_{j1}]^T$ is drawn from a multivariate Normal distribution with mean vector \vec{b} and covariance matrix Σ.
- ► This model can be written as follows.

$$\begin{split} &y_{jd} \sim N(\mu_{jd},\sigma), \\ &\mu_{jd} = \beta_{j0} + \beta_{j1} x_{jd}, \quad \text{for } j \in 1 \dots J, \text{for } d \in 1 \dots n_{j,\prime\prime} \\ &\vec{\beta}_j \sim N(\vec{b},\Sigma) \quad \text{for } j \in 1 \dots J, \end{split}$$

- ► The Bayesian network diagram for this model is shown in Figure 7.
- As we can see, this is an extension of the Bayesian network diagram in Figure 6b, with the extension being that each $\vec{\beta}_j$ are modelled as functions of \vec{b} and Σ.

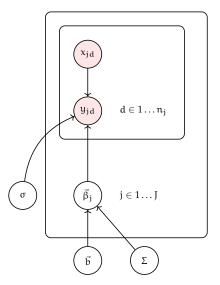


Figure 7: Bayesian network diagrams for a multilevel varying slopes and intercepts linear model.

▶ We can rewrite this multilevel model in the following manner.

$$\begin{split} \text{for } i \in 1 \dots n, \quad y_i \sim N(\mu_i, \sigma^2), \\ \mu_i &= \beta_{[s_i]0} + \beta_{[s_i]1} x_i, \\ \text{for } j \in 1 \dots J, \quad \vec{\beta}_j \sim N(\vec{b}, \Sigma). \end{split}$$

- Note that here the i index ranges over all values in the entire data-set, i.e. $i \in 1, 2...n$, and each $s_i \in 1, 2...J$ is an indicator variable that indicates the identity of the subject on observation i.
- ► This notation with a single subscript per observation and indicator variables is more extensible, especially for complex models.
- Using this new notation, given that $\vec{\beta}_j \sim N(\vec{b}, \Sigma)$, we can rewrite $\vec{\beta}_j$ as $\vec{\beta}_j = \vec{b} + \vec{\zeta}_j$ where $\vec{\zeta}_j \sim N(0, \Sigma)$.

Substituting $\vec{b} + \zeta_j$ for $\vec{\beta}$, and thus substituting $b_0 + \zeta_{j0}$ and $b_1 + \zeta_{j1}$ for β_{j0} and β_{j1} , respectively, we have the following model.

$$\begin{split} \text{for } i \in 1 \dots n, \quad y_i \sim N(\mu_i, \sigma^2), \\ \mu_i &= \underbrace{b_0 + b_1 x_i}_{\text{fixed effects}} + \underbrace{\zeta_{[s_i]0} + \zeta_{[s_i]1} x_i,}_{\text{random effects}} \end{split}$$

$$\text{for } j \in 1 \dots J, \quad \vec{\zeta}_j \sim N(0, \Sigma). \end{split}$$

As we can see from this, a multilevel normal linear model is equivalent to a non-multilevel model (the *fixed effects* models) plus a normally distributed random variation to the intercept and slope for each subject (the *random effects*).

- ► The fixed effects are sometimes known as *population level* effects: they apply to all observations.
- ► The random effects, on the other hand, vary across each different value of the grouping variable, which in this example is an individual participant in the experiment.
- Put another way, the fixed effects give the average effects in the population.
- ► The extent to which each individual varies around this average is given by the random effects.
- ▶ That the multilevel linear model can be described in terms of fixed and random effects is why these models are known as a *linear mixed effects model*.

▶ We can implement this model in R using lme4::lmer.

- ► The syntax here matches the fixed and random effects description of the model.
- ▶ The Reaction ~ Days tells us that the fixed effects model is a simple linear regression model with one predictor, and so with one intercept and one slope term.
- ► The (Days|Subjects) tells us that there is random variation to the slope for Days and implicitly there's also random variation to the intercept term.
- ► We could make the variation to the intercept term explicit by writing (1 + Days|Subject), which is identical to (Days|Subject) because the 1 + is included always by default just as it is included by default in fixed effects part, as it is in any R regression formula syntax.

▶ The results of this model is obtained as follows.

```
summary(M_ml)
```

► The value of \vec{b} is available under Estimate in the Fixed effects, and we can get these directly as follows.

```
b <- fixef(M_ml)
b

#> (Intercept) Days
#> 251.40510 10.46729
```

- ► Thus, the average effect of sleep deprivation on reaction time across all individuals is that their reaction time increases by 10.47 each day.
- ▶ Also, the average individual has an average reaction time of 251.41 on day 0 of the experiment, which means that this is the average reaction time of the average person generally.

- The values in the covariance matrix Σ and of the residual standard deviation σ can be obtained from the values provided under Random effects.
- ► These are available more directly as follows.

▶ Note that the covariance matrix is defined as follows.

$$\Sigma = \begin{bmatrix} \tau_0^2 & \tau_0 \rho \tau_1 \\ \tau_0 \rho \tau_1 & \tau_1^2 \end{bmatrix}.$$

► The estimates of each $\vec{\beta}_j$ for $j \in 1...$ J can be obtained using the coef function.

```
coef(M_ml)$Subject %>%
   head()

#> (Intercept) Days

#> 308   253.6637 19.666262

#> 309   211.0064  1.847605

#> 310   212.4447  5.018429

#> 330   275.0957  5.652936

#> 331   273.6654  7.397374

#> 332   260.4447 10.195109
```

Shrikage

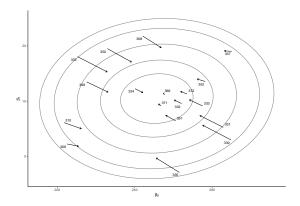


Figure 8: The contour plot shows the contours of the 2d normal distribution centered at \vec{b} and whose covariance matrix is Σ .

Varying intercepts or varying slopes only models

- ► The above model allowed for random variation in both the intercepts and slopes but we can choose to have random variation in only one or the other.
- ► A varying intercept only multilevel model is defined as follows.

$$\begin{split} \text{for } i \in 1 \dots n, \quad y_i \sim N(\mu_i, \sigma^2), \\ \mu_i &= \beta_{[s_i]0} + b_1 x_i, \\ \text{for } j \in 1 \dots J, \quad \beta_{j0} \sim N(b_0, \tau_0^2), \end{split}$$

which can be rewritten, using the same reasoning as above,

$$\begin{split} \text{for } i \in 1 \dots n, \quad y_i \sim N(\mu_i, \sigma^2), \\ \mu_i &= b_0 + b_1 x_i + \zeta_{[s_i]0}, \\ \text{for } j \in 1 \dots J, \quad \zeta_{j0} \sim N(0, \tau_0^2). \end{split}$$

Using lmer, we would implement this as follows.

► The fixed effects give us an estimate of the slope and intercept as before.

```
fixef(M_ml_vi)
#> (Intercept) Days
#> 251.40510 10.46729
```

The random effects just provide a measure of standard deviation τ_0 for the random intercepts as well as residual standard deviation σ .

```
VarCorr(M_ml_vi)
#> Groups Name Std.Dev.
#> Subject (Intercept) 37.124
#> Residual 30.991
```

Absent here, compared to the varying intercepts and varying slopes model is the estimate for τ_1 and ρ .

Varying slope only

- ► The varying slope only multilevel model allows only the slopes to vary across subjects and it leaves the intercepts fixed.
- ▶ It is defined as follows.

$$\begin{split} \text{for } i \in 1 \dots n, \quad y_i \sim N(\mu_i, \sigma^2), \\ \mu_i &= b_0 + \beta_{\lceil s_i \rceil 1} + x_i, \\ \text{for } j \in 1 \dots J, \quad \beta_{j1} \sim N(b_0, \tau_1^2), \end{split}$$

which can be rewritten

$$\begin{split} \text{for } i \in 1 \dots n, \quad y_i \sim N(\mu_i, \sigma^2), \\ \mu_i &= b_0 + b_1 x_i + \zeta_{[s_i]1} x_i, \\ \text{for } j \in 1 \dots J, \quad \zeta_{j1} \sim N(0, \tau_1^2). \end{split}$$

▶ Using lmer, we would implement this as follows.

► The fixed effects give us an estimate of both the slope and intercept as with the previous models.

```
fixef(M_ml_vs)
#> (Intercept) Days
#> 251.40510 10.46729
```

The random effect provide a measure of standard deviation τ_1 and σ .

```
VarCorr(M_ml_vs)
#> Groups Name Std.Dev.
#> Subject Days 7.260
#> Residual 29.018
```

Absent here compared to the full model is the estimate for τ_0 and ρ .

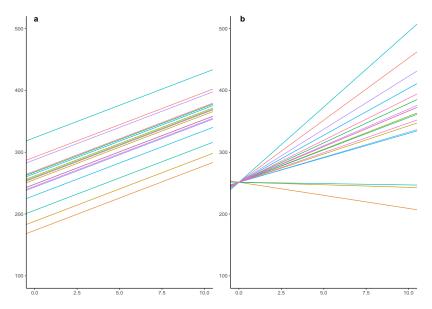


Figure 9: Lines of best fit for each data group in a varying intercepts only a) or varying slopes only b) multilevel linear model.

- ▶ One final variant of the full model is where we allow for both varying slopes and intercepts but assume no correlation between each β_{j0} and β_{j1} .
- In other words, we assume that these are drawn from independent normal distributions.

$$\begin{split} \text{for } i \in 1 \dots n, \quad y_i \sim N(\mu_i, \sigma^2), \\ \mu_i &= \beta_{[s_i]0} + \beta_{[s_i]1} x_i, \\ \text{for } j \in 1 \dots J, \quad \beta_{j0} \sim N(b_0, \tau_0^2), \\ \beta_{j1} \sim N(b_1, \tau_1^2), \end{split}$$

which is identical to each β_j vector being drawn from a diagonal covariance matrix, i.e. where $\rho=0$.

▶ Using lmer, we would implement this as follows.

► We can obtain the same model using the following formula syntax.

► The fixed effects give us an estimate of both the slope and intercept as with each of the previous models.

```
fixef(M_ml_diag2)
#> (Intercept) Days
#> 251.40510 10.46729
```

The random effect provide a measure of the τ_0 , τ_1 and σ standard deviations.

```
VarCorr(M_ml_diag2)
#> Groups Name Std.Dev.
#> Subject (Intercept) 25.0513
#> Subject.1 Days 5.9882
#> Residual 25.5653
```

The only quantity that is absent here compared to the full model is the estimate for ρ .

Multilevel models for nested data

- ▶ In all the examples considered thus far, our multilevel models had only two levels, which we can denote level 0 and level 1.
- ▶ For example, we had rats (level 0) within batches (level 1), observations of per capita alcohol consumption in different years (level 0) within different countries (level 1), individual observations of reaction times on different days (level 0) grouped by different experimental subjects (level 1).
- ▶ We can easily have groups within groups, and we usually refer to these models as *nested* multilevel models.

► Let us consider the following data which is based on a subset of the classroom data made available in R package WWGbook.

```
classroom_df <- read_csv(here('data/classroom.csv'))</pre>
```

- ► Each observation is of a child (level 0), and for each one we have their mathematics test score in their first grade (mathscore) and their home socioeconomic status (ses).
- ▶ There are n children in total, indexed by $i \in 1...n$.
- ► Each child is in one of J classes (level 1, denoted by classid), and each class is within one of K schools (level 2, denoted by schoolid).

▶ This hierarchical arrangement of the data is shown in Figure 10.

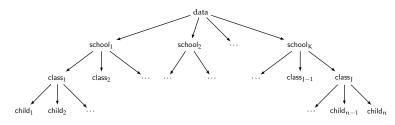


Figure 10: The hierarchical arrangement of the data in the classroom_df data set. Each one of the N children is in one of J classes and each one of the J classes is in one of K schools.

- ► The relationship between ses and mathscore can vary across different schools, see Figure 11a.
- ► Furthermore, *within* each school, there may be variation in the effect of ses on mathscore across different classes, see Figure 11b.
- Formally, a three-level multilevel varying intercepts and slopes linear model corresponding to the above problem may be presented as follows.

$$\begin{split} \text{for } i \in 1 \dots n, \quad y_i \sim N(\mu_i, \sigma^2), \\ \mu_i &= \gamma_{[c_i]0} + \gamma_{[c_i]1} x_i, \\ \text{for } j \in 1 \dots J, \quad \vec{\gamma}_j \sim N(\vec{\beta}_{[s_j]}, \Sigma_c), \\ \text{for } k \in 1 \dots K, \quad \vec{\beta}_k \sim N(\vec{b}, \Sigma_s), \end{split}$$

- For each one of the n children, we have their mathscore variable y_i , their ses variable x_i , and an indicator variable $c_i \in 1...J$.
- ► The indicator variable indicates which of the J different classes the child is a member of.
- ► For each of one of these J classes, we have another indicator variable $s_i \in 1...K$.
- ▶ This indicates the school that class j is a member of.
- For example, if $s_i = k$, this means that class j is within school k.
- ▶ From this description, we see that there are J vectors of coefficients, i.e. $\vec{\gamma}_1, \vec{\gamma}_2 \dots \vec{\gamma}_J$, and each one corresponds to one of the J different classes in the data set.
- Each vector $\vec{\gamma}_j$ is a sample from a multivariate normal distribution centered at $\vec{\beta}_{[s_i]}$, where s_j is the school that class j is a member of.
- The covariance matrix of this multivariate normal distribution is Σ_c .
- ► The are K different vectors $\vec{\beta}_1, \vec{\beta}_2 \dots \vec{\beta}_K$ are themselves drawn from another multivariate normal distribution whose center is \vec{b} and whose covariance matrix is Σ_s .

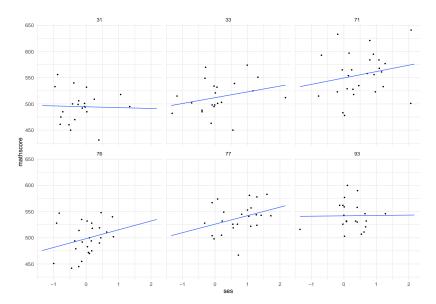


Figure 11: The line of best fit for the children in the school is shown.

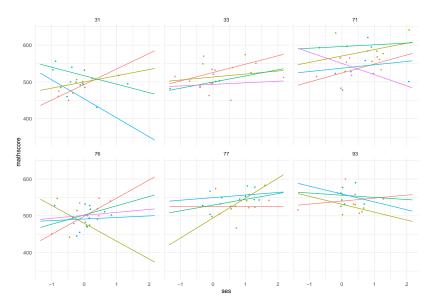


Figure 12: A separate line of best fit for each class within each school is shown.

- ▶ Using the same reasoning as above, we may rewrite $\vec{\gamma}_j \sim N(\vec{\beta}_{[s_i]}, \Sigma_c)$ as $\vec{\gamma}_j = \vec{\beta}_{[s_i]} + \vec{\xi}_j$ where $\vec{\xi}_j \sim N(0, \Sigma_c)$.
- Likewise, we may rewrite $\vec{\beta}_k \sim N(\vec{b}, \Sigma_s)$ as $\vec{\beta}_k = \vec{b} + \vec{\zeta}_k$ where $\vec{\zeta}_k \sim N(0, \Sigma_s)$. Thus, we have

$$\begin{split} \vec{\gamma}_j &= \vec{\beta}_{\lceil s_j \rceil} + \xi_j, \\ &= \vec{b} + \zeta_{\lceil s_j \rceil} + \xi_j. \end{split}$$

This allows us to rewrite the original model as follows.

$$\begin{split} \text{for } i \in 1 \dots n, \quad y_i \sim N(\mu_i, \sigma^2), \\ \mu_i &= \underbrace{b_0 + b_1 x_i}_{\text{fixed effects}} + \underbrace{\zeta_{[z_i]0} + \zeta_{[z_i]1} x_i}_{\text{school random effects}} + \underbrace{\xi_{[c_i]0} + \xi_{[c_i]1} x_i,}_{\text{class random effects}} \\ \text{for } j \in 1 \dots J, \quad \vec{\xi}_j \sim N(0, \Sigma_c), \\ \text{for } k \in 1 \dots K, \quad \vec{\zeta}_k \sim N(0, \Sigma_s). \end{split}$$

Here, for notational simplicity, we have used a new indicator variable $z_i = s_{[c_i]} \in 1...$ K that indicates the school that child i is a member of.

▶ Using lmer, we can implement this model as follows.

```
M_classroom <- lmer(
  mathscore ~ ses + (ses classid) + (ses schoolid),
  data = classroom_df)</pre>
```

As we can see, we simply use random effects terms, one for random variation by school and the other for random variation by class.

Before, we proceed, by examining the results of VarCorr, we see that there is a perfect correlation between the random slopes and random intercepts due to class.

► This indicates overparameterization in the model, and can be avoided by removing the possibility of a correlation between the slopes and intercepts for class.

```
M_classroom <- lmer(
  mathscore ~ ses + (ses | classid) + (ses | schoolid),
  data = classroom_df)</pre>
```

Now, just like previous linear mixed effects models, our fixed effects will consist of a single slope and intercept term.

- ► From this, we see that at a population level, every unit increase in ses leads to a 11.2 increase in mathscore.
- ► Information concerning the random effects are available from VarCorr.

```
VarCorr(M_classroom)
#> Groups Name Std.Dev. Corr
#> classid (Intercept) 8.3964
#> classid.1 ses 0.0000
#> schoolid (Intercept) 15.4398
#> ses 7.3039 0.470
#> Residual 32.8950
```

From this, amongst other things, we see there is a minimal random variation in the ses slopes across the different classes.

- ► The variable classid unambiguously identified the class of children by giving each class in each school a unique identifier.
- ► In some cases, we do not have unique identifiers for nested groups.
- As an example, consider the classid2 variable in the classroom_df data sets.

Let us draw a sample of observations from classroom_df.

- ▶ Unlike classid, classid2 provides an identifier for each class that is *relative* to its school.
- ▶ Thus, we have class 1 in school 41, and class 1 in school 97.
- ► These are completely unrelated classes.
- ► In order to deal with variables like this, we must use an alternative formula syntax.

▶ For example, in order to have a varying intercepts only model, where the intercept varies by class and school, and assuming we are using the classid2 variable, we use the following syntax in the formula to indicate that the values of classid2 are relative to that of schoolid.

```
M_classroom_vi <- lmer(
  mathscore ~ ses + (1|schoolid/classid2),
  data = classroom_df)</pre>
```

► This is identical to the following model.

```
M_classroom_vi2 <- lmer(
  mathscore ~ ses + (1|schoolid) + (1|schoolid:classid2),
  data = classroom_df)</pre>
```

► The syntax in this second version makes it clear that we are effectively creating a unique identifier for the class by combining the values of schoolid and classid2.

Crossed structures

- ► An alternative multilevel arrangement of data is known as a *crossed* structure.
- ► Again, this is easiest to illustrate by way of an example.
- Consider a type of cognitive psychology experiment known as a lexical decision task, which is used to understand the basic cognitive processes involved in reading words.
- ▶ In this experiment, multiple subjects are each shown multiple different letter strings, e.g. *dinosaur*, *morhet*, *children*, etc., and they have to respond as to whether the string is a word or not, and their reaction times to do so are also recorded.
- ▶ Thus, we would have subjects $s_1, s_2 ... s_j$ being shown letter strings $w_1, w_2 ... w_k ... w_K$, and from each subject for each string, we have a response, e.g. a yes/no binary response, or reaction, or both.

- Note the entire experiment, our total set of responses could be denoted $r_1, r_2 \dots r_n$.
- ► These are our level 0 observations.
- Crucially, each response is cross classified as belonging to a particular subject and a particular letter string.

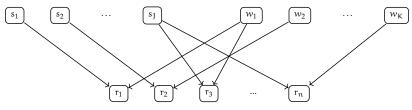


Figure 13: A *crossed* multilevel data arrangement, such as would arise in a lexical decision experiment. Each r_i is grouped under one of the $s_1, s_2 \dots s_J$ and also one of the $w_1, w_2 \dots w_K$.

- ▶ In general, when dealing with crossed multilevel structures, we simply consider the random variation of slopes or intercepts according to more than one grouping variable.
- ► As an example, consider the British Lexicon Project data that we also considered in Chapter 3.
- ► This provides us with data from a large lexical decision experiment, and a small fraction of this data is provided in the file data/blp-short2.csv.

```
blp_df <- read_csv(here('data/blp-short2.csv'))</pre>
```

- Here, each rt observation corresponds to a particular participant and a particular word (spelling).
- ▶ There are 58 distinct words and 78 distinct participants.

- ► For simplicity, let us consider the multilevel linear model whereby average rt varies by both participant and spelling.
- ► This model is as follows.

$$\begin{split} \text{for } i \in 1 \dots n, \quad y_i \sim N(\mu_i, \sigma^2), \\ \mu_i &= \beta_{\lceil s_i \rceil} + \gamma_{\lceil w_i \rceil}, \\ \text{for } j \in 1 \dots J, \quad \beta_j \sim N(b_s, \tau_s^2), \\ \text{for } k \in 1 \dots K, \quad \gamma_k \sim N(b_w, \tau_w^2). \end{split}$$

We can rewrite β_j as $\beta_j = b_s + \zeta_j$, where $\zeta_j \sim N(0, \tau_s^2)$, and rewrite γ_j as $\gamma_j = b_w + \xi_k$, where $\xi_k \sim N(0, \tau_w^2)$. This leads to

$$\begin{split} \text{for } i \in 1 \dots n, \quad y_i \sim N(\mu_i, \sigma^2), \\ \mu_i &= \nu + \zeta_{[s_i]} + \xi_{[w_i]}, \\ \text{for } j \in 1 \dots J, \quad \zeta_j \sim N(0, \tau_s^2), \\ \text{for } k \in 1 \dots K, \quad \xi_k \sim N(0, \tau_w^2), \end{split}$$

where $v = b_s + b_w$.

This is implemented in 1mer as follows.

From this, we see the estimate of ν is as follows.

```
fixef(M_blp)
#> (Intercept)
#> 586.2724
```

The estimates of τ_s , τ_w , and σ are as follows.

```
VarCorr(M_blp)
#> Groups Name Std.Dev.
#> participant (Intercept) 77.738
#> spelling (Intercept) 64.128
#> Residual 137.229
```

Group level predictors

- ► In the examples thus far, the predictor variables were at the bottom level, level 0.
- ► For example, at level 0, we had children, and the values of the predictor variable ses were specific to each child.
- ► Consider the following two related data sets, which are based on the MathAchieve and MathAchSchool data sets, respectively, available in the nlme package:

```
mathachschool_df <- read_csv(here('data/mathachieveschool.csv'))
mathach_df <- read_csv(here('data/mathachieve.csv'))</pre>
```

socioeconomic background, and their mathematical achieve score (mathach).Thus, in this data set, we have level 1 grouping variable, school,

► In the mathach_df data, for each pupil in a school, we have variable related to their ethnic minority status, sex, home

- but all predictors are at level 0.
 The mathachschool_df data set, on the other hand, provides us with predictors related to the schools.
- For example, we have the school's size, whether it is public or

- Group level predictors present do not special difficulty for linear mixed effects models but can not be treated identically to individual observation level predictors.
- ► For example, just like in similar examples above, we use a multilevel varying slope and varying intercept model to look at how ses affects mathach scores and how this effect varies by school.
- ► The ses variable is a pupil level variable, and we would be able to treat other pupil level variable s in a similar way.
- ► We would not, however, be able to use group level predictors, e.g. pracad, disclim, etc., in a similar way.
- For example, we could not perform the following model.
- ► This is simply because the effect of pracad on mathach can not vary by school: each school has exactly one value of pracad.

We still can easily use pracad in a linear mixed effect model, for example as follows.

```
# does work
# glp: group level predictor
M_glp <- lmer(mathach ~ pracad + (1|school), data = mathach_df2)</pre>
```

▶ In this case, our model is that a pupil's mathach varies by the school's pracad, and there is variation across schools in the terms of the average mathac, with the latter effect being due to the random intercepts term.

▶ In this model, the fixed effects coefficients are as follows.

- We therefore see that a unit increase in pracad leads to a 8.23 increase in mathach.
- ► The random effects are as follows.

```
VarCorr(M_glp)
#> Groups Name Std.Dev.
#> school (Intercept) 2.0614
#> Residual 6.2565
```

► From this, we see that the standard deviation in the intercept terms across schools is 2.06.

- ► A more interesting situation involving group level predictors arises in the following situation.
- Assuming that our outcome variable is still mathach, we could model how this varies by the pupil's ses, and how this effect varies across schools, using a multilevel varying slopes and intercepts model.
- ▶ We could also use a school level predictor, for example, himinty, and model how the school-level slopes and intercepts for the ses effect vary by it.

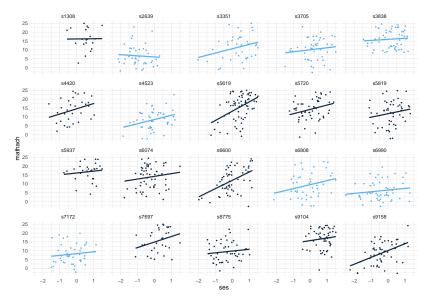


Figure 14: How mathematical achievement varies by a child's socioeconomic background across a sample of different school. Schools are colour coded to indicate whether they have high ethnic minority proportions (lighter colour)

Formally, this model would be as follows.

$$\begin{split} \text{for } i \in 1 \dots n \quad y_i \sim N(\mu_i, \sigma^2), \\ \mu_i &= \beta_{\lceil s_i \rceil 0} + \beta_{\lceil s_i \rceil 1} x_i, \\ \text{for } j \in 1 \dots J \quad \vec{\beta}_j \sim N(\vec{b}_0 + \vec{b}_1 z_j, \Sigma), \end{split}$$

where y_i is the mathach score and x_i is the ses score of pupil i, and z_i is the himinty score of school j.

► As before, we can rewrite $\vec{\beta}_i$ as follows,

$$\begin{split} \vec{\beta}_j &= \vec{b}_0 + \vec{b}_1 z_j + \vec{\zeta}_j, \\ \begin{bmatrix} \beta_{j0} \\ \beta_{j1} \end{bmatrix} &= \begin{bmatrix} b_{00} \\ b_{01} \end{bmatrix} + \begin{bmatrix} b_{10} \\ b_{11} \end{bmatrix} z_j + \begin{bmatrix} \zeta_{j0} \\ \zeta_{j1} \end{bmatrix}, \end{split}$$

where

$$\vec{\zeta}_{j} = \begin{bmatrix} \zeta_{j0} \\ \zeta_{j1} \end{bmatrix} \sim N(0, \Sigma).$$

From this, we have

$$\begin{split} \text{for } i \in 1 \dots n \quad y_i \sim N(\mu_i, \sigma^2), \\ \mu_i &= (b_{00} + b_{10} z_{[s_i]} + \zeta_{[s_i]0}) + (b_{01} + b_{11} z_{[s_i]} + \zeta_{[s_i]1}) x_i, \\ &= \underbrace{b_{00} + b_{01} x_i + b_{10} z_{[s_i]} + b_{11} z_{[s_i]} x_i}_{\text{fixed effects}} + \underbrace{\zeta_{[s_i]0} + \zeta_{[s_i]1} x_i,}_{\text{random effects}} \end{split}$$
 for $j \in 1 \dots J$ $\vec{\zeta}_j \sim N(0, \Sigma)$,

From this we see that the role of the group level predictor $z_{[s_i]}$ interacts with the pupil level predictor x_i .

- To implement this model in R, we first join the school level data with that of the pupil level data.
- ▶ Note that himinty is coded as binary variable where a value of 1 means that there is a high proportion of ethic minorities in the school.

► The standard deviations of variation in random intercepts and slopes, and their correlation is as follows.

► The fixed effects coefficients are as follows:

```
fixef(M_glp)
#> (Intercept) ses himinty ses:himinty
#> 13.1542443 2.5436697 -1.8593332 -0.5760956
```

▶ From this, we see that the role of himinty changing its value from 0 to 1 decreases the intercept by 1.86 and decreases the slope of the effect of ses by 0.58.

Multilevel generalized linear models

Multilevel generalized linear models can be approached just like multilevel linear models.

Bayesian multilevel models

- ▶ In practical terms, Bayesian approaches to multilevel modelling differ from their classical counterparts primarily in their method of inference.
- ▶ In both cases, we begin by specifying a probabilistic model of the observed data.
- ▶ For example, if our data was the sleep deprivation and reaction time data from above, regardless of whether a Bayesian or a classical approach is being taken, a reasonable model of this data would a multilevel varying slopes and intercepts linear model that can be stated as follows:

$$\begin{split} \text{for } i \in 1 \dots n, \quad y_i \sim N(\mu_i, \sigma^2), \\ \mu_i &= b_0 + b_1 x_i + \zeta_{[s_i]0} + \zeta_{[s_i]1} x_i, \\ \text{for } j \in 1 \dots J, \quad \vec{\zeta}_j \sim N(0, \Sigma). \end{split}$$

where y_i , s_i , x_i are, respectively, the reaction time, subject index, and days of sleep deprivation corresponding to observation i.

TT : 'C' 1.4 1.1.1 4 D : 1.1 : 1

▶ In general, how we specify this probabilistic model and the choices available to us are identical in both the Bayesian and classical approaches.

- ► Classical approaches infer estimators of these unknowns, for example, by maximum likelihood estimation, and then consider the sampling distribution of these estimators for hypothetical true values of the parameters.
- From this, we obtain p-values for hypothesis tests, null or otherwise, and confidence intervals, and related concepts.
- ▶ Bayesian approaches, on the other hand, first posit a *prior* probability distribution over the unknown parameters. In the above model, for example, we can parameterize it in terms of 6 unknowns:

$$b_0, b_1, \sigma, \tau_0, \tau_1, \rho,$$

where τ_0^2 , τ_1^2 are the diagonal elements of Σ , and ρ is its off-diagonal element.

- ▶ Bayesian methods will therefore posit a probability distribution $P(b_0, b_1, \sigma, \tau_0, \tau_1, \rho)$ over this six dimensional space.
- ► This prior is then combined, via Bayes's rule, with the *likelihood* function over the parameters to result in the posterior distribution.
- ▶ The posterior distribution tells us the probability that the true values of the parameters are a particular values, conditional on all the assumptions of the model.

- ▶ If we accept default settings for priors and other quantities, performing a Bayesian multilevel linear model using brms::brm is identical to using lme4::lmer.
- ► For example, the following implements the Bayesian counterpart of the lmer based model that we used above, which clearly differs only by using the command brm instead of lmer:

The main results of this model may be obtained by summary(M_bayes), or equivalently by just typing the name of the model M_bayes.

In this output, amongst other information, for each one of the six variables b_0 , b_1 , σ , τ_0 , τ_1 , ρ , we have the mean of the posterior distribution (Estimate), the standard deviation of the posterior distribution (Est.Error), and the upper and lower limits of the 95% high posterior density interval (1–95% CI, u–95% CI).

The prior on M_bayes can be seen as follows:

M_bay	es <mark>\$</mark> prior				
#>	prior	class	coef	group	res
<i>#> 1</i>		b			
#> 2		b	Days		
<i>#> 3</i>	student_t(3, 288.7, 59.3)	Intercept			
#> 4	$lkj_corr_cholesky(1)$	L			
<i>#> 5</i>		L		Subject	
<i>#> 6</i>	$student_t(3, 0, 59.3)$	sd			
#> 7		sd		Subject	
<i>#> 8</i>		sd	Days	Subject	
<i>#> 9</i>		sd	Intercept	Subject	
<i>#> 10</i>	$student_t(3, 0, 59.3)$	sigma			