# Chapter 2

# DJM

30 January 2018

# What is this chapter about?

Problems with regression, and in particular, linear regression

A quick overview:

- 1. The truth is almost never linear.
- 2. Collinearity can cause difficulties for numerics and interpretation.
- 3. The estimator depends strongly on the marginal distribution of X.
- 4. Leaving out important variables is bad.
- 5. Noisy measurements of variables can be bad, but it may not matter.

# Asymptotic notation

• The Taylor series expansion of the mean function  $\mu(x)$  at some point u

$$\mu(x) = \mu(u) + (x - u)^{\top} \frac{\partial \mu(x)}{\partial x}|_{x=u} + O(\|x - u\|^2)$$

- The notation f(x) = O(g(x)) means that for any x there exists a constant C such that f(x)/g(x) < C.
- More intuitively, this notation means that the remainder (all the higher order terms) are about the size of the distance between x and u or smaller.
- So as long as we are looking at points u near by x, a linear approximation to  $\mu(x) = \mathbb{E}[Y \mid X = x]$  is reasonably accurate.

### What is bias?

- We need to be more specific about what we mean when we say bias.
- Bias is neither good nor bad in and of itself.
- A very simple example: let  $Z_1, \ldots, Z_n \sim N(\mu, 1)$ .
- We don't know  $\mu$ , so we try to use the data (the  $Z_i$ 's) to estimate it.
- I propose 3 estimators:
  - 1.  $\widehat{\mu}_1 = 12$ , 2.  $\widehat{\mu}_2 = Z_6$ , 3.  $\widehat{\mu}_3 = \overline{Z}$ .
- The bias (by definition) of my estimator is  $\mathbb{E}[\widehat{\mu}] \mu$ .
- Calculate the bias and variance of each estimator.

## Regression in general

• If I want to predict Y from X, it is almost always the case that

$$\mu(x) = \mathbb{E}\left[Y \mid X = x\right] \neq x^{\top}\beta$$

- There are always those errors  $O(||x-u||)^2$ , so the **bias** is not zero.
- We can include as many predictors as we like, but this doesn't change the fact that the world is non-linear.

# Covariance between the prediction error and the predictors

• In theory, we have (if we know things about the state of nature)

$$\beta^* = \arg\min_{\beta} \mathbb{E}\left[ \|Y - X\beta\|^2 \right] = \operatorname{Cov}\left[X, \ X\right]^{-1} \operatorname{Cov}\left[X, \ Y\right]$$

- Define  $v^{-1} = \text{Cov}[X, X]^{-1}$ .
- Using this optimal value  $\beta^*$ , what is  $Cov[Y X\beta^*, X]$ ?

$$\begin{aligned} \operatorname{Cov}\left[Y-X\beta^{*},\ X\right]&=\operatorname{Cov}\left[Y,\ X\right]-\operatorname{Cov}\left[X\beta^{*},\ X\right] & \text{(Cov is linear)} \\ &=\operatorname{Cov}\left[Y,\ X\right]-\operatorname{Cov}\left[X(v^{-1}\operatorname{Cov}\left[X,\ Y\right]),\ X\right] & \text{(substitute the def. of }\beta^{*}) \\ &=\operatorname{Cov}\left[Y,\ X\right]-\operatorname{Cov}\left[X,\ X\right]v^{-1}\operatorname{Cov}\left[X,\ Y\right] & \text{(Cov is linear in the first arg)} \\ &=\operatorname{Cov}\left[Y,\ X\right]-\operatorname{Cov}\left[X,\ Y\right]=0. \end{aligned}$$

## Bias and Collinearity

- Adding or dropping variables may impact the bias of a model
- Suppose  $\mu(x) = \beta_0 + \beta_1 x_1$ . It is linear. What is our estimator of  $\beta_0$ ?
- If we instead estimate the model  $y_i = \beta_0$ , our estimator of  $\beta_0$  will be biased. How biased?
- But now suppose that  $x_1 = 12$  always. Then we don't need to include  $x_1$  in the model. Why not?
- Form the matrix [1  $x_1$ ]. Are the columns collinear? What does this actually mean?

#### When two variables are collinear, a few things happen.

- 1. We cannot **numerically** calculate  $(\mathbf{X}^{\top}\mathbf{X})^{-1}$ . It is rank deficient.
- 2. We cannot **intellectually** separate the contributions of the two variables.
- 3. We can (and should) drop one of them. This will not change the bias of our estimator, but it will alter our interpretations.
- 4. Collinearity appears most frequently with many categorical variables.
- 5. In these cases, software **automatically** drops one of the levels resulting in the baseline case being in the intercept. Alternately, we could drop the intercept!
- 6. High-dimensional problems (where we have more predictors than data points) also lead to rank deficiencies.
- 7. There are methods (regularizing) which attempt to handle this issue (both the numerics and the interpretability). We may have time to cover them slightly.

### White noise

White noise is a stronger assumption than Gaussian.

Consider a random vector  $\epsilon$ .

- 1.  $\epsilon \sim N(0, \Sigma)$ .
- 2.  $\epsilon_i \sim N(0, \sigma^2(x_i))$ . 3.  $\epsilon \sim N(0, \sigma^2 I)$ .

The third is white noise. The  $\epsilon$  are normal, their variance is constant for all i and independent of  $x_i$ , and they are independent.

# Asymptotic efficiency

This and MLE are covered in 420.

There are many properties one can ask of estimators  $\hat{\theta}$  of parameters  $\theta$ 

- 1. Unbiased:  $\mathbb{E}\left[\widehat{\theta}\right] \theta = 0$ 2. Consistent:  $\widehat{\theta} \xrightarrow{n \to \infty} \theta$ 3. Efficient:  $\mathbb{V}\left[\widehat{\theta}\right]$  is the smallest of all unbiased estimators
- 4. Asymptotically efficient: Maybe not efficient for every n, but in the limit, the variance is the smallest of all unbiased estimators.
- 5. Minimax: over all possible estimators in some class, this one has the smallest MSE for the worst problem.
- 6. ...

## Problems with R-squared

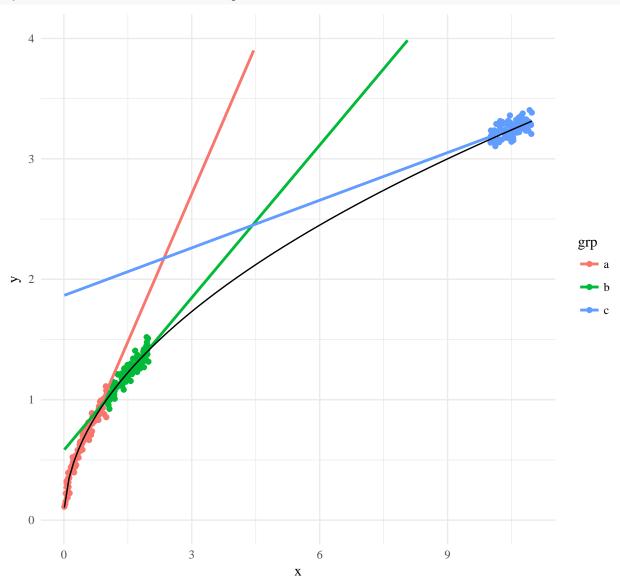
$$R^{2} = 1 - \frac{SSE}{\sum_{i=1}^{n} (Y_{i} - \overline{Y})^{2}} = 1 - \frac{MSE}{\frac{1}{n} \sum_{i=1}^{n} (Y_{i} - \overline{Y})^{2}} = 1 - \frac{SSE}{SST}$$

- This gets spit out by software
- X and Y are both normal with (empirical) correlation r, then  $R^2 = r^2$
- In this nice case, it measures how tightly grouped the data is about the regression line
- Data that is tightly grouped about the regression line can be predicted accurately by the regression line.
- Unfortunately, the implication does not go both ways.
- High  $R^2$  can be achieved in many ways, same with low  $R^2$
- You should just ignore it completely (and the adjusted version), and encourage your friends to do the same

#### High R-squared with non-linear relationship

```
genY <- function(X, sig) Y = sqrt(X)+sig*rnorm(length(X))</pre>
sig=0.05; n=100
X1 = runif(n,0,1)
X2 = runif(n,1,2)
X3 = runif(n,10,11)
df = data.frame(x=c(X1,X2,X3), grp = rep(letters[1:3],each=n))
df$y = genY(df$x,sig)
ggplot(df, aes(x,y,color=grp)) + geom_point() +
```

```
geom_smooth(method = 'lm', fullrange=TRUE, se = FALSE) +
ylim(0,4) + stat_function(fun=sqrt,color='black')
```



df %>% group\_by(grp) %>% summarise(rsq = summary(lm(y~x))\$r.sq)

```
## # A tibble: 3 x 2
##   grp   rsq
##   <fctr> <dbl>
## 1 a   0.930
## 2 b   0.868
## 3 c   0.369
```