#### Day 3: Calculus 2

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# Today

- Today
  - Partial derivative
  - Integral
    - \* Definition
    - \* Calculation rules
    - \* Calculation techniques

#### Partial Derivative

- What to do when there are more than one input variables?
- Partial derivative of a function with more than one input variable is defined as the derivative with respect to one of those variables with others held constant.
- Formally, the partial derivative of  $f(x_1, x_2, \dots, x_n)$  with respect to  $x_i$  is defined as

$$\frac{\partial f}{\partial x_i}(x_1,x_2,\cdots,x_n) = \lim_{h \to 0} \frac{f(x_1,x_2,\cdots,x_i+h,\cdots,x_n) - f(x_1,x_2,\cdots,x_i,\cdots,x_n)}{h}$$

 As in the case of derivative of univariate functions, we can take higher-order derivatives.

#### Partial Derivative: Example

• Let  $f(x,y) = 3x^2y + 2y^3$ . Then,

$$\frac{\partial f}{\partial x}(x,y) = (3x^2y)' + (2y^3)'$$
$$= 3y \cdot (x^2)' = 6xy$$

and

$$\frac{\partial f}{\partial y}(x,y) = (3x^2y)' + (2y^3)'$$
$$= 3x^2 \cdot (y)' + 2 \cdot (y^3)' = 3x^2 + 6y^2$$

#### Partial Derivative: Example (cont.)

We can take second-order derivative as

$$\frac{\partial^2 f}{\partial x^2}(x,y) = \frac{\partial}{\partial x} \left( \frac{\partial}{\partial x} f(x,y) \right)$$
$$= (6xy)' = 6y \cdot (x)' = 6y$$

and

$$\frac{\partial^2 f}{\partial y^2}(x,y) = \frac{\partial}{\partial y} \left( \frac{\partial}{\partial y} f(x,y) \right)$$
$$= (3x^2)' + (6y^2)' = 6 \cdot (y^2)' = 12y$$

#### Partial Derivative: Example (cont.)

We can also take second-order mixed derivative as

$$\frac{\partial^2 f}{\partial x \partial y}(x, y) = \frac{\partial}{\partial x} \left( \frac{\partial}{\partial y} f(x, y) \right)$$
$$= (3x^2)' + (6y^2)' = 3 \cdot (x^2) = 6x$$

The order of differentiation does not matter:

$$\frac{\partial^2 f}{\partial x \partial y}(x, y) = \frac{\partial}{\partial y} \left( \frac{\partial}{\partial x} f(x, y) \right)$$
$$= (6xy)' = 6x \cdot (y)' = 6x$$

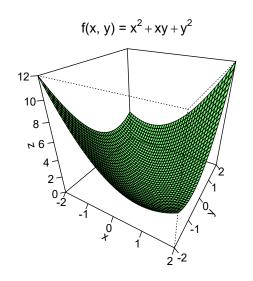
#### Partial Derivative: Exercises

- Let  $f(x,y) = 3x^3y^2 3xy^2 \sqrt{y} + x$ . Calculate the following partial derivatives.
  - 1.  $\frac{\partial f}{\partial x}(x,y)$
  - $2. \ \frac{\partial f}{\partial y}(x,y)$
  - 3.  $\frac{\partial^2 f}{\partial x^2}(x,y)$
  - 4.  $\frac{\partial^2 f}{\partial y^2}(x,y)$
  - $5. \ \frac{\partial^2 f}{\partial x \partial y}(x,y)$

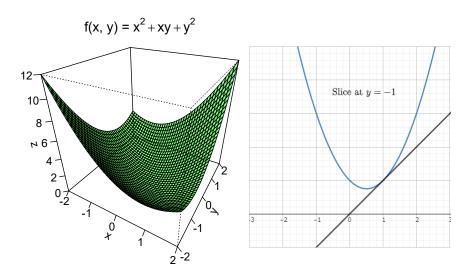
#### Partial Derivative: Application

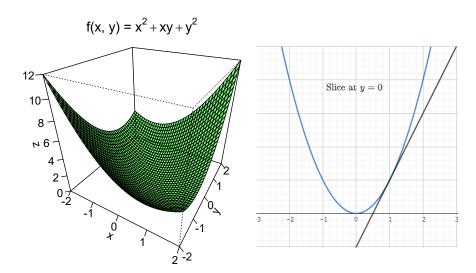
- Same as the univariate case, partial derivative stand for the rate of change of a function.
- Application examples
  - Marginal effects
    - $\star$  How much does the value of y change due to one-unit change in x?
    - $\star$  e.g.,  $y = \alpha + \beta_1 x + \beta_2 z + \beta_3 xz$
  - Multivariate optimization

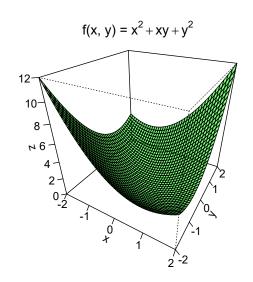
- For a point on a graph of a function with more than one input, there are an infinite number of tangent lines.
- Then how do we determine the rate of change of the function?
- Partial derivative of  $y = f(x_1, x_2, \cdots, x_n)$  with regard to  $x_i$  computes the rate of change by finding the slope of a tangent line parallel to the  $x_iy$ -plane.
- Let's take a look at an example of a function with two independent variables.

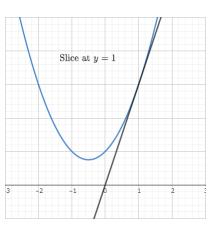


- Let  $z = f(x, y) = x^2 + xy + y^2$
- $\frac{\partial f}{\partial x}(x,y)=2x+y$  describes how slope of the tangent lines paralell to the xz-plane changes with values of x and y
- It is same as
  - first slicing the graph at a specific value of  $y = y_0$
  - ▶ then finding the slope of a tangent line on the sliced plane









#### Multivariate Optimization

- How do we find local minima/maxima for functions with several inputs?
- Let's again use an example of a function f(x,y) with two independent variables.
- At a local minimum/maximum, slope of the tangent lines on the xz-plane and the yz-place must be 0!
- Therefore, we need to solve the system of equations

$$\begin{cases} \frac{\partial f}{\partial x}(x,y) = 0\\ \frac{\partial f}{\partial y}(x,y) = 0 \end{cases}$$

#### Multivariate Optimization (cont.)

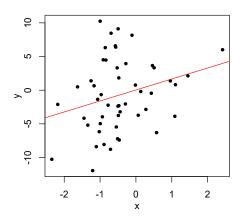
• By extending the logic, to find local minima/maxima of a function  $f(x_1, x_2, \dots, x_n)$ , we need to solve the system of equations

$$\begin{cases} \frac{\partial f}{\partial x_1}(x_1, x_2, \cdots, x_n) = 0\\ \frac{\partial f}{\partial x_2}(x_1, x_2, \cdots, x_n) = 0\\ \vdots\\ \frac{\partial f}{\partial x_i}(x_1, x_2, \cdots, x_n) = 0\\ \vdots\\ \frac{\partial f}{\partial x_n}(x_1, x_2, \cdots, x_n) = 0 \end{cases}$$

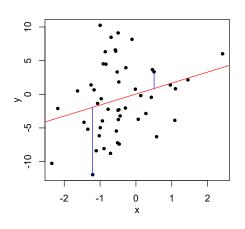
#### Multivariate Optimization (cont.)

- Second order condition?
  - Distinguishing local maxima/minima is much harder in a multivariate case.
  - We'll briefly touch on this issue tomorrow.

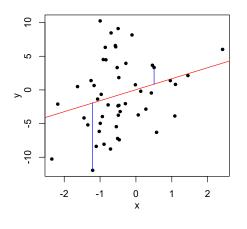
#### Multivariate Optimization: Example



- We often want to know the relationship between one variable (x) and another (y).
  - e.g., GRE score and grades in graduate school
  - Notation
    - $\star$  Total number of observations/points: n
    - \* Denote each observation/point as  $(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)$
- Let's consider drawing a line that best fits the data.
  - y = a + bx



- Ordinary Least Square
   (OLS): find a line which
   minimizes the sum of squared
   residuals
- What is residual?
  - Distance between the line and each point.
- Residual for point  $(x_i, y_i)$ :
  - A point on a line at  $x = x_i$ :  $(x_i, a + bx_i)$
  - ► Therefore, residual for point  $(x_i, y_i)$  is  $y_i (a + bx_i)$



Residual for observation i

$$y_i - (a + bx_i)$$

Squared residual for observation i

$$\left\{y_i - (a + bx_i)\right\}^2$$

Sum of squared residuals

$$\sum_{i=1}^{n} \{y_i - (a + bx_i)\}^2$$

 Let's find the values of a and b which minimize the sum of squared residuals.

$$\underset{a,b}{\operatorname{argmin}} \sum_{i=1}^{n} \left\{ y_i - (a + bx_i) \right\}^2$$

 Following the discussion so far, we need to solve the system of equations

$$\begin{cases} \frac{\partial}{\partial a} \sum_{i=1}^{n} \left\{ y_i - (a + bx_i) \right\}^2 = 0\\ \frac{\partial}{\partial b} \sum_{i=1}^{n} \left\{ y_i - (a + bx_i) \right\}^2 = 0 \end{cases}$$

• NB: Here we treat a and b as variables and  $x_i$ s and  $y_i$ s and as constants!

• Let's compute the partial derivatives.

$$\frac{\partial}{\partial a} \sum_{i=1}^{n} \left\{ y_i - (a + bx_i) \right\}^2$$

$$= \frac{\partial}{\partial a} \left( \left\{ y_1 - (a + bx_1) \right\}^2 + \left\{ y_2 - (a + bx_2) \right\}^2 \dots + \left\{ y_n - (a + bx_n) \right\}^2 \right)$$

$$= \frac{\partial}{\partial a} \left\{ y_1 - (a + bx_1) \right\}^2 + \frac{\partial}{\partial a} \left\{ y_2 - (a + bx_2) \right\}^2 + \dots + \frac{\partial}{\partial a} \left\{ y_n - (a + bx_n) \right\}^2$$

$$= -2 \left\{ y_1 - (a + bx_1) \right\} - 2 \left\{ y_2 - (a + bx_2) \right\} - \dots - 2 \left\{ y_n - (a + bx_n) \right\}$$

$$= -2 \left\{ \left\{ y_1 - (a + bx_1) \right\} + \left\{ y_2 - (a + bx_2) \right\} + \dots + \left\{ y_n - (a + bx_n) \right\} \right)$$

$$= -2 \sum_{i=1}^{n} \left\{ y_i - (a + bx_i) \right\}$$

and

$$\frac{\partial}{\partial b} \sum_{i=1}^{n} \{y_i - (a + bx_i)\}^2 
= \frac{\partial}{\partial b} (\{y_1 - (a + bx_1)\}^2 + \{y_2 - (a + bx_2)\}^2 \cdots + \{y_n - (a + bx_n)\}^2) 
= \frac{\partial}{\partial b} \{y_1 - (a + bx_1)\}^2 + \frac{\partial}{\partial b} \{y_2 - (a + bx_2)\}^2 + \cdots + \frac{\partial}{\partial b} \{y_n - (a + bx_n)\}^2 
= -2x_1 \{y_1 - (a + bx_1)\} - 2x_2 \{y_2 - (a + bx_2)\} - \cdots - 2x_n \{y_n - (a + bx_n)\} 
= -2(x_1 \{y_1 - (a + bx_1)\} + x_2 \{y_2 - (a + bx_2)\} + \cdots + x_n \{y_n - (a + bx_n)\}) 
= -2\sum_{i=1}^{n} x_i \{y_i - (a + bx_i)\}$$

• The system of equations

$$\begin{cases}
-2\sum_{i=1}^{n} \{y_i - (a+bx_i)\} = 0 \\
-2\sum_{i=1}^{n} x_i \{y_i - (a+bx_i)\} = 0
\end{cases}$$

is called the normal equation.

- Rest is to solve the system of equations above!
  - which you are asked to do in GOVT 701...

#### Integral

- What is an integral?
  - 1. Antiderivative
    - \* inverse of a derivative
  - 2. Area under the curve
- Fundamental theorem of calculus connects these two explanations.

#### Indefinite Integral

• Antiderivative or indefinite integral of a function f(x), often denoted as F(x), is a function whose derivative is equal to the original function f(x). Formally,

$$F'(x) = f(x)$$

• Indefinite integral of f(x) is also written as

$$\int f(x)dx,$$

which is equal to F(x).

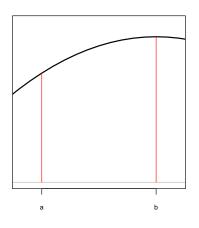
- Example: The function  $F(x) = x^3$  is an antiderivative of  $f(x) = 3x^2$ , since F'(x) = f(x).
- However, this is not the only antiderivative.
  - $F(x) = x^3 + 1$
  - $F(x) = x^3 + 100$
  - $F(x) = x^3 23$
  - $F(x) = x^3 1108564$
  - • •
- Since the derivative of a constant is 0, there are infinite number of antiderivatives!

- To represent this situation, we add an arbitrary constant, C, known as the *constant of integration*.
- Example: antiderivative of  $f(x) = 3x^2$  is

$$F(x) = x^3 + C$$

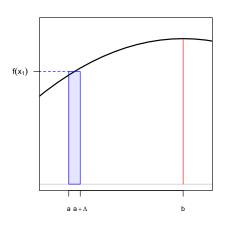
lacktriangle All values of F(x) can be obtained by changing the values of C.

#### Definite Integral



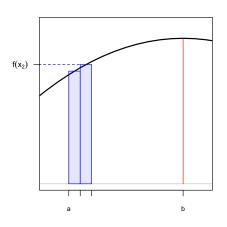
- Suppose we want to find the area under the curve defined by a function f(x) and some interval  $x \in [a, b]$ .
- Let's approximate the area using rectangles.
  - ► First partition the interval into *n* regions.
  - Let the length of each subinterval be  $\Delta x$
  - Denote the mid-points of subintervals as

$$x_1, x_2, \cdots, x_n$$



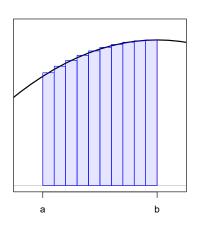
- Area of first rectangle:  $f(x_1)\Delta x$
- Area of second rectangle:  $f(x_2)\Delta x$
- . . .
- Add area of all the rectangles (Riemann sum):

$$\sum_{i=1}^{n} f(x_i) \Delta x$$



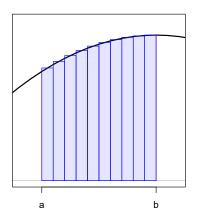
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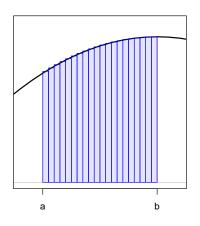
- Area of first rectangle:  $f(x_1)\Delta x$
- Area of second rectangle:  $f(x_2)\Delta x$
- ...
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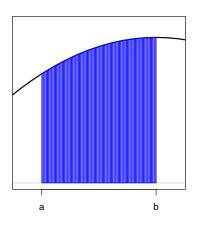
- By making  $\Delta x$  smaller and smaller (i.e., partitioning the interval [a,b] into smaller regions)...
- We can approximate the area closer and closer!
- Formally stated, we can find the area under the curve by taking the limit of the Riemann sum as  $\Delta x \rightarrow 0$ :

$$\lim_{\Delta x \to 0} \sum_{i=1}^{n} f(x_i) \Delta x$$



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• Riemann integral/Definite integral of function f(x) from a to b is defined as the limit of Riemann sum of f(x) on that interval as  $\Delta x \to 0$  and denoted as

$$\int_{a}^{b} f(x)dx = \lim_{\Delta x \to 0} \sum_{i=1}^{n} f(x_i) \Delta x$$

#### Fundamental Theorem of Calculus

• (First) Fundamental Theorem of Calculus: Let f(x) be a function on an interval [a,b], and F(x) be a function defined on [a,b] by

$$F(x) = \int_{a}^{x} f(x)dx$$

Then,

$$F'(x) = f(x)$$

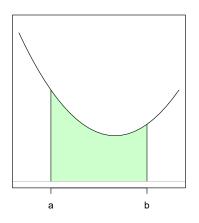
for all  $x \in (a, b)$ .

• The definite integral of f(x) is one of its antiderivatives!

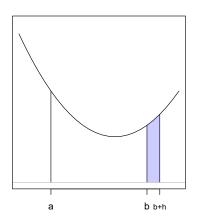
• (Second) Fundamental Theorem of Calculus: Let f(x) be a function on an interval [a,b], and F(x) be an antiderivative of f(x) on [a,b]. Then,

$$\int_{a}^{b} f(x)dx = F(b) - F(a)$$

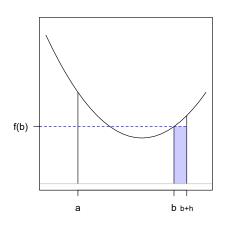
 Therefore, we can calcuate the definite integral (i.e., area under the curve) from b and a by subtracting the indefinite integral evaluated at a from the indefinite integral evaluated at b!



- But why?
- Let S(b) be a function representing the area under the curve defined by the function f(x) and interval  $x \in [a,b]$ .

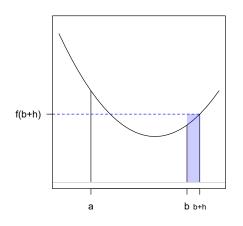


- Let's consider how much the area changes if we move rightward from b by h.
- The area shown in blue can computed as S(b+h)-S(b)



- Here let's assume that f(x) is increasing around b.
- Then, as we can see from the figure, S(b+h)-S(b) is larger than f(b)h and smaller than f(b+h)h. Dividing each by h, we get

$$f(b) < \frac{S(b+h) - S(b)}{h} < f(b+h)$$



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$$f(b) < \frac{S(b+h) - S(b)}{h} < f(b+h)$$

• Take the limit of each as  $h \to 0$ .

$$\lim_{h \to 0} f(b) < \lim_{h \to 0} \frac{S(b+h) - S(b)}{h} < \lim_{h \to 0} f(b+h)$$

• Since  $\lim_{h\to 0} f(b) = \lim_{h\to 0} f(b+h) = f(b)$ ,

$$\lim_{h \to 0} \frac{S(b+h) - S(b)}{h} = f(b)$$

• From the definition of derivative,

$$S'(b) = f(b)$$

Find the antiderivative of both:

$$S(b) = F(b) + C$$

• Since S(a) = 0, C = -F(a). Therefore,

$$S(b) = F(b) - F(a)$$

 We can compute the area under the curve by calculating the differences in indefinite integrals!

#### Rules of Integration

- Common rules of integration
  - 1. Linearity:  $\int \{\alpha f(x) + \beta g(x)\} dx = \alpha \int f(x) dx + \beta \int g(x) dx$
  - 2. Reverse power rule:  $\int x^n dx = \frac{1}{n+1}x^{n+1} + C \ (n \neq -1)$
  - 3. Exception to 2. when n=-1:  $\int \frac{1}{x} dx = \log|x| + C$
  - 4. Exponential rule:  $\int a^x dx = \frac{a^x}{\log a} + C$
  - 5. Special case of 4.:  $\int e^x dx = e^x + C$

# Rules of Integration (cont.)

- To calculate the definite integral  $\int_a^b f(x)dx$ :
  - 1. Find the indefinite integral F(x)
  - 2. Calculate F(b) F(a)
  - ▶ We often write the second step as  $\int_a^b f(x)dx = F(x)\Big|_a^b$
- Common rules for definite integral
  - 1.  $\int_{a}^{a} f(x) dx = 0$
  - 2.  $\int_a^b f(x)dx = -\int_a^a f(x)dx$
  - 3.  $\int_{a}^{b} f(x)dx = \int_{a}^{c} f(x)dx + \int_{c}^{b} f(x)dx \ (c \in [a, b])$ 4.  $\int_{a}^{b} \{\alpha f(x) + \beta g(x)\} dx = \alpha \int_{a}^{b} f(x)dx + \beta \int_{a}^{b} g(x)dx$

## Rules of Integration: Example

- Find the antiderivative of  $f(x) = 3x^3 4x^2 + x + 6$ 
  - Answer:

$$\int f(x)dx = \int (3x^3 - 4x^2 + x + 6)dx$$

$$= 3 \int x^3 dx - 4 \int x^2 dx + \int x dx + 6 \int dx$$

$$= \frac{3}{4}x^4 - \frac{4}{3}x^3 + \frac{1}{2}x^2 + 6x + C$$

# Rules of Integration: Example (cont.)

- Calculate the definite integral  $\int_{-1}^{4} (3x^2 + 2x 1) dx$ 
  - Answer:

$$\int_{-1}^{4} (3x^{2} + 2x - 1) dx$$

$$= 3 \int_{-1}^{4} x^{2} dx + 2 \int_{-1}^{4} x dx - \int_{-1}^{4} dx$$

$$= 3 \cdot \frac{1}{3} x^{3} \Big|_{-1}^{4} + 2 \cdot \frac{1}{2} x^{2} \Big|_{-1}^{4} - x \Big|_{-1}^{4}$$

$$= \{64 - (-1)\} + (16 - 1) - \{4 - (-1)\}$$

$$= 65 + 15 - 5 = 75.$$

## Rules of Integration: Exercises

- 1. Calculate the following integrals.
  - 1.1  $\int (4x^5 + 2x^2 + 5)dx$
  - 1.2  $\int (\sqrt{x} + 2x^3) dx$
  - 1.3  $\int (3x^{\frac{3}{2}} + 4^x) dx$
  - 1.4  $\int_{-2}^{2} (3x^2 + x) dx$
  - 1.5  $\int_2^4 (3x^2 + x + 5) dx$
  - 1.6  $\int_{1}^{16} (5x^{\frac{3}{2}} 2x^{-\frac{5}{4}}) dx$
- 2. Find the area surrounded by  $f(x) = x^2 3x + 3$  and  $g(x) = -x^2 + 5x + 13$ .

## Integration Techniques

- 1. Integration by parts
- 2. Integration by substitution
- 3. L'Hopital's rule

#### Integration by Parts

• If the integrand h(x) can be represented as the product of two functions, f(x) and g'(x), then

$$\int h(x)dx = \int f(x)g'(x)dx = f(x)g(x) - \int f'(x)g(x)dx$$

• In the case of definite integral:

$$\int_{a}^{b} h(x)dx = \int_{a}^{b} f(x)g'(x)dx = f(x)g(x)\Big|_{a}^{b} - \int_{a}^{b} f'(x)g(x)dx$$

 This formula can easily be derived from the product rule of derivative calculation.

#### Integration by Parts: Example

- Question: find the indefinite integral of  $\log(x)$ .
  - Answer: As  $\log(x) = \log(x) \cdot (x)'$ ,

$$\int \log(x)dx = \int \log(x) \cdot (x)'dx$$
$$= x \log(x) - \int \frac{1}{x} \cdot xdx$$
$$= x \log(x) - \int dx$$
$$= x \log(x) - x + C.$$

#### Integration by Substitution

• If we can find a function t(x) and write the integrand f(x) as

$$f(x) = f(t)\frac{dt}{dx},$$

we can apply the integration by substitution formula

$$\int f(x)dx = \int f(t)\frac{dt}{dx}dx = \int f(t)dt$$

• In the case of definite integral: if t moves from  $\alpha$  to  $\beta$  when x moves from a to b, then

$$\int_{a}^{b} f(x)dx = \int_{a}^{b} f(t)\frac{dt}{dx}dx = \int_{\alpha}^{\beta} f(t)dt$$

▶ Note that the interval of integration can change due to the variable transformation.

#### Integration by Substitution: Example

- Question: find the indefinite integral of  $f(x) = 18x^2\sqrt[3]{6x^3 7}$ 
  - ▶ Answer: Let  $t = 6x^3 7$ . Then,  $\frac{dt}{dx} = 18x^2$ . Therefore,

$$\int f(x)dx = \int \frac{18x^2 \sqrt[3]{6x^3 - 7}dx}{18x^2 \sqrt[3]{6x^3 - 7}dx}$$

$$= \int \sqrt[3]{t} \frac{dt}{dx} dx$$

$$= \int t^{\frac{1}{3}} dt$$

$$= \frac{3}{4} t^{\frac{4}{3}} + C$$

$$= \frac{3}{4} (6x^3 - 7)^{\frac{4}{3}} + C$$

## Integration by Substitution: Summary of Steps

- 1. Identify some part of f(x) which can be simplified by substituting in a single variable t (which is a function of x)
- 2. Compute  $\frac{dt}{dx}$ , and reexpress f(x) using t and  $\frac{dt}{dx}$
- 3. Solve the indefinite integral
- 4. (For indefinite integration) Substitute back in for x
- 5. (For definite integration) Determine the new interval of integration  $[\alpha, \beta]$ , and evaluate the antiderivative at the boundary points.

## Integration by Substitution: Another Example

- Question: find the definite integral  $\int_0^1 x \sqrt{x^2 + 1} dx$ 
  - Answer: Let  $t = x^2 + 1$ . Then,  $\frac{dt}{dx} = 2x$ . Also, when x moves from 0 to 1, t moves from 1 to 2. Therefore,

$$\int_{0}^{1} x \sqrt{x^{2} + 1} dx$$

$$= \int_{0}^{1} \sqrt{t} \cdot \frac{1}{2} \frac{dt}{dx} dx$$

$$= \frac{1}{2} \int_{1}^{2} \sqrt{t} dt$$

$$= \frac{1}{2} \cdot \frac{2}{3} t^{\frac{3}{2}} \Big|_{1}^{2}$$

$$= \frac{1}{3} (2\sqrt{2} - 1)$$

## L'Hopital's Rule

• Let's calculate the definite integral  $\int_0^\infty x e^{-x} dx$ .

$$\int_{0}^{\infty} x e^{-x} dx = \int_{0}^{\infty} x (-e^{-x})' dx$$

$$= -(xe^{-x}|_{0}^{\infty}) - \int_{0}^{\infty} (x)' \cdot (-e^{-x}) dx$$

$$= -(xe^{-x}|_{0}^{\infty}) + \int_{0}^{\infty} e^{-x} dx$$

- How can we evaluate  $xe^{-x}$  at  $x \to \infty$ ?

  - ▶ In such cases, L'Hopital's rule help you circumvent the problem.

# L'Hopital's Rule (cont.)

• L'Hopital's rule: Let functions f(x) and g(x) be differentiable at an open interval close to c. If  $\lim_{x\to c} f(x) = \lim_{x\to c} g(x) = 0$  or  $\pm\infty$ , and  $\lim_{x\to c} \frac{f'(x)}{g'(x)}$  exists,

$$\lim_{x \to c} \frac{f(x)}{g(x)} = \lim_{x \to c} \frac{f'(x)}{g'(x)}$$

Applying the L'Hopital's rule, we can see that

$$\lim_{x \to \infty} \frac{x}{e^x} = \lim_{x \to \infty} \frac{x'}{(e^x)'} = \lim_{x \to \infty} \frac{1}{e^x} = 0$$

## Integration Techniques: Exercises

- Calculate the following integrals.
  - $1. \int \frac{1}{1 + \exp(-x)} dx$
  - 2.  $\int x \exp(x) dx$
  - 3.  $\int \frac{2x}{5x^2-7} dx$
  - 4.  $\int x^2(x^3+15)^{\frac{3}{2}}dx$
  - 5.  $\int_0^1 x \exp(x^2) dx$
  - 6.  $\int_{1}^{2} x \log x dx$
  - 7.  $\int_0^1 \log(1+\sqrt{x}) dx$  (Hint: set  $t=1+\sqrt{x}$  and perform integration by substitution)

#### **Tomorrow**

- Problem set 3 → review in the morning
- Tomorrow
  - Vector and matrix algebra
  - Vector/matrix notations for multivariate calculus
  - ▶ Geometric meanings of vector/matrix algebra
  - ▶ Moore & Siegel, Chapters 12, 13, 15.2.2, 15.2.4, & 16.1