# Class notes for day 2 (raw and unpolished)

## 1 The Becker-Shapley-Shubik model / discrete optimal transport

If employee x matches with college y, then

job amenity  $\alpha_{xy}$  – GIVEN

production  $\gamma_{xy}$  – GIVEN

Assume that there are  $n_x$  employees of type x, and  $m_y$  colleges of type y. Total output generated by an xy pair

$$\Phi_{xy} = \alpha_{xy} + \gamma_{xy}$$

Introduce wages  $w_{xy}$  paid by y to x – ENDOGENOUS; DETERMINED AT EQUILIBRIUM.

After transfer,

x gets indidrect utility

$$u_x = \max_{y} \left\{ \alpha_{xy} + w_{xy}, 0 \right\}$$

and y gets indirect utility  $v_y$ 

$$v_y = \max_{x} \left\{ \gamma_{xy} - w_{xy}, 0 \right\}$$

If unmatched, then x and y get 0.

We are looking for an equilibrium / stable matching  $\mu_{xy}$ =number of xy pairs. Constraints are given by the populations:

$$\sum_{x} \mu_{xy} \le n_x$$
$$\sum_{x} \mu_{xy} \le m_y$$

Conditions for  $\mu_{xy}$  to be an equilibrium matching???

$$\mu_{xy} > 0 \implies \left\{ \begin{array}{l} y \in \arg\max_{y} \left\{ \alpha_{xy} + w_{xy} \right\} \\ x \in \arg\max_{x} \left\{ \gamma_{xy} - w_{xy} \right\} \end{array} \right.$$

$$\mu_{xy} > 0 \implies \begin{cases} u_x = \alpha_{xy} + w_{xy} \\ v_y = \gamma_{xy} - w_{xy} \end{cases}$$

$$\implies u_x + v_y = \alpha_{xy} + \gamma_{xy} = \Phi_{xy}$$

For any x and any y we have  $u_x + v_y \ge \Phi_{xy}$ .  $u_x \ge 0$ 

$$v_y \ge 0$$

To recap,  $(\mu, u, v)$  is an equilibrium matching iff

(1)  $\mu$  satisfies the populations constraints

$$\sum_{y} \mu_{xy} \le n_x$$

$$\sum_{x} \mu_{xy} \le m_y$$
(2) pairwise stability:

For any x and any y we have  $u_x + v_y \ge \Phi_{xy}$ .

$$u_x \ge 0$$

$$v_y \ge 0$$

$$v_{y} \ge 0$$

$$v_{y} \ge 0$$

$$(3) \ \mu_{xy} > 0 \implies u_{x} + v_{y} = \Phi_{xy}$$

$$\sum_{y} \mu_{xy} < n_{x} \implies u_{x} = 0$$

$$\sum_{x} \mu_{xy} < m_{y} \implies v_{y} = 0$$

$$\sum_{u} \mu_{xy} < n_x \implies u_x = 0$$

$$\sum_{x} \mu_{xy} < m_y \implies v_y = 0$$

These are optimality conditions associated with the linear programming problem whose primal formulation is

$$\begin{split} \max_{\mu \geq 0} & & \sum_{xy} \mu_{xy} \Phi_{xy} \\ & & \sum_{y} \mu_{xy} \leq n_x \ [u_x \geq 0] \\ & & \sum_{x} \mu_{xy} \leq m_y \ [v_y \geq 0] \end{split}$$

and dual formulation

$$\begin{aligned} \min_{u \geq 0, v \geq 0} & \sum n_x u_x + \sum m_y v_y \\ s.t. & u_x + v_y \geq \Phi_{xy} \ \left[ \mu_{xy} \geq 0 \right] \end{aligned}$$

$$\begin{array}{l} \mu_{xy} > 0 \implies u_x + v_y = \Phi_{xy} \\ \sum_y \mu_{xy} < n_x \implies u_x = 0 \ [u_x > 0 \implies \sum_y \mu_{xy} = n_x] \\ \sum_x \mu_{xy} < m_y \implies v_y = 0 \end{array}$$

#### 1.1 Recovering the wages

For any x and y,

$$u_x \geq \alpha_{xy} + w_{xy}$$
$$v_y \geq \gamma_{xy} - w_{xy}$$

this implies

$$u_x - \alpha_{xy} \ge w_{xy} \ge \gamma_{xy} - v_y$$

## 2 The Choo-Siow model / regularized optimal transport

Choo Siow JPE (2006) Galichon Salanie (2020)

#### 2.1 Smooth-max

Replace the max  $\begin{aligned} \max_y \left\{ a_y \right\} \\ \text{By the smooth-max} \\ T > 0 \\ T \log \sum_y \exp\left(a_y/T\right) = \max_y \left\{ a_y \right\} + T \log \sum_y \exp\left(\frac{a_y - \max_y \left\{ a_y \right\}}{T}\right) \\ 0 \leq T \log \sum_{y \in Y} \exp\left(\frac{a_y - \max_y \left\{ a_y \right\}}{T}\right) \leq T \log |Y| \end{aligned}$ 

#### 2.2 Smooth version of the above model

$$\begin{aligned} u_x &= T \log \left( 1 + \sum_y \exp \left( \frac{\alpha_{xy} + w_{xy}}{T} \right) \right) = E \left[ \max_y \left\{ \alpha_{xy} + w_{xy} + T \varepsilon_y, T \varepsilon_0 \right\} \right] \\ v_y &= T \log \left( 1 + \sum_x \exp \left( \frac{\gamma_{xy} - w_{xy}}{T} \right) \right) \end{aligned}$$

$$\Pr\left(y \in \arg\max_{y} \left\{\alpha_{xy} + w_{xy} + T\varepsilon_{y}, T\varepsilon_{0}\right\}\right) = \frac{\exp\left(\frac{\alpha_{xy} + w_{xy}}{T}\right)}{1 + \sum_{y} \exp\left(\frac{\alpha_{xy} + w_{xy}}{T}\right)}$$

$$= \exp\left(\frac{\alpha_{xy} + w_{xy} - u_{x}}{T}\right)$$

and

$$\Pr\left(0 \in \arg\max_{y} \left\{\alpha_{xy} + w_{xy} + T\varepsilon_{y}, T\varepsilon_{0}\right\}\right) = \frac{1}{1 + \sum_{y} \exp\left(\frac{\alpha_{xy} + w_{xy}}{T}\right)}$$
$$= \exp\left(-u_{x}/T\right)$$

But  $\Pr(y \in \arg\max_y \{\alpha_{xy} + w_{xy} + T\varepsilon_y, T\varepsilon_0\}) = \mu_{xy}/n_x$ , thus

$$\mu_{xy} = \exp\left(\frac{\alpha_{xy} + w_{xy} - u_x + T \ln n_x}{T}\right)$$

$$\mu_{x0} = \exp\left(-u_x + T \ln n_x\right)$$

similarly,

$$\begin{array}{rcl} \mu_{xy} & = & \exp\left(\frac{\gamma_{xy} - w_{xy} - v_y + T \ln m_y}{T}\right) \\ \mu_{0y} & = & \exp\left(-v_y + T \ln m_y\right) \end{array}$$

Introduce

$$a_x = u_x - T \ln n_x$$
  
$$b_y = v_y - T \ln m_y$$

so that we have

$$\mu_{xy} = \exp\left(\frac{\alpha_{xy} + w_{xy} - a_x}{T}\right)$$

similarly,

$$\mu_{xy} = \exp\left(\frac{\gamma_{xy} - w_{xy} - b_y}{T}\right)$$

Multiplying the previous two equations pairwise, we get

$$\mu_{xy}^2 = \exp\left(\frac{\Phi_{xy} - a_x - b_y}{T}\right)$$

where it is recalled that  $\Phi_{xy} = \alpha_{xy} + \gamma_{xy}$  is the total output. Similarly,

$$\mu_{x0} = \exp\left(-\frac{a_x}{T}\right)$$
 and  $\mu_{0y} = \exp\left(-\frac{b_y}{T}\right)$ 

To summerize, we arrive at Choo and Siow's formula

$$\mu_{xy} = \sqrt{\mu_{x0}\mu_{0y}} \exp\left(\frac{\Phi_{xy}}{2T}\right).$$

Recall the population equations:

$$\begin{array}{l} \sum_y \mu_{xy} + \mu_{x0} = n_x \\ \sum_x \mu_{xy} + \mu_{0y} = m_y \end{array} \label{eq:local_equation}$$

Plug in Choo-Siow's formula into the population equations

$$\begin{cases} \sum_{y} \sqrt{\mu_{x0}\mu_{0y}} \exp\left(\frac{\Phi_{xy}}{2T}\right) + \mu_{x0} = n_x \\ \sum_{x} \sqrt{\mu_{x0}\mu_{0y}} \exp\left(\frac{\Phi_{xy}}{2T}\right) + \mu_{0y} = m_y \end{cases}$$

## 3 Computation issues

Given  $\alpha_{xy}$  and  $\gamma_{xy}$ , compute  $w_{xy}$  and  $\mu_{xy}$ .

We will see 2 directions to solve this system

• the "optimization way" – see this system as foc of a convex optimization problem

$$\min_{a,b} F\left(a,b\right)$$

where F is convex

• the "gross substitute way" – see this system as an equilibrium problem with gross substitutes

$$e(p) = q$$

where e has the GS property – and hence Coordinate Update algorithms (such as Gauss-Seidel or Jacobi) can be used.

#### 3.1 Convex optimization formulation

Recall the system to be solved

$$\begin{array}{lcl} \mu_{xy} & = & \exp\left(\frac{\Phi_{xy} - a_x - b_y}{2T}\right) \\ \\ \mu_{x0} & = & \exp\left(-\frac{a_x}{T}\right) \text{ and } \mu_{0y} = \exp\left(-\frac{b_y}{T}\right) \end{array}$$

we have

$$\begin{cases} -\sum_{y} \exp\left(\frac{\Phi_{xy} - a_x - b_y}{2T}\right) - \exp\left(-\frac{a_x}{T}\right) + n_x = 0\\ -\sum_{x} \exp\left(\frac{\Phi_{xy} - a_x - b_y}{2T}\right) - \exp\left(-\frac{b_y}{T}\right) + m_y = 0 \end{cases}$$

I want to interpret as

$$\frac{\partial F(a,b)}{\partial a_x} = 0$$

$$\frac{\partial F(a,b)}{\partial b_y} = 0$$

Exercise. What is F such that

$$\frac{\partial F(a,b)}{\partial a_x} = n_x - \sum_y \exp\left(\frac{\Phi_{xy} - a_x - b_y}{2T}\right) - \exp\left(-\frac{a_x}{T}\right)$$

$$\frac{\partial F(a,b)}{\partial b_y} = m_y - \sum_x \exp\left(\frac{\Phi_{xy} - a_x - b_y}{2T}\right) - \exp\left(-\frac{b_y}{T}\right)$$

it is

$$F(a,b) = \sum_{x} n_x a_x + \sum_{y} m_y b_y$$

$$+2T \sum_{x,y} \exp\left(\frac{\Phi_{xy} - a_x - b_y}{2T}\right)$$

$$+T \sum_{x} \exp\left(-\frac{a_x}{T}\right) + T \sum_{y} \exp\left(-\frac{b_y}{T}\right)$$

when  $T \to 0$ ?

the smooth penalization  $2T \sum_{x,y} \exp\left(\frac{\Phi_{xy} - a_x - b_y}{2T}\right)$  becomes a hard penalization that is equal to zero if  $\Phi_{xy} - a_x - b_y \leq 0$ and  $+\infty$  else

therefore enforcing the constraint  $a_x + b_y \ge \Phi_{xy}$ . Similarly, the smooth penalization  $T \sum_x \exp\left(-\frac{a_x}{T}\right)$ 

becomes  $a_x > 0$ 

Therefore the problem becomes

$$\begin{aligned} & \min \sum_{x} n_x a_x + \sum_{y} m_y b_y \\ & \text{s.t. } a_x + b_y \geq \Phi_{xy}, \ a_x \geq 0 \ b_y \geq 0 \end{aligned}$$

#### 3.2 Equilibrium with gross substitutes formulation

How can we reformulate the system of equations in (a, b)

$$\begin{cases} -\sum_{y} \exp\left(\frac{\Phi_{xy} - a_x - b_y}{2T}\right) - \exp\left(-\frac{a_x}{T}\right) + n_x = 0\\ -\sum_{x} \exp\left(\frac{\Phi_{xy} - a_x - b_y}{2T}\right) - \exp\left(-\frac{b_y}{T}\right) + m_y = 0 \end{cases}$$
$$\begin{cases} -\sum_{y} \exp\left(\frac{\Phi_{xy} - a_x - b_y}{2T}\right) - \exp\left(-\frac{a_x}{T}\right) = -n_x\\ \sum_{x} \exp\left(\frac{\Phi_{xy} - a_x - b_y}{2T}\right) + \exp\left(-\frac{b_y}{T}\right) = m_y \end{cases}$$

as

$$e_z(p) = q_z$$

where  $e_z(p)$  is increasing in  $p_z$  and weakly decreasing in  $p_{z'}$ , for  $z' \neq z$ ?  $Z = X \cup Y$ 

$$p_x = a_x \text{ for } x \in X$$

$$e_x(p) = -\sum_y \exp\left(\frac{\Phi_{xy} - a_x - b_y}{2T}\right) - \exp\left(-\frac{a_x}{T}\right)$$

$$q_x = -n_x$$

$$q_y = m_y$$

#### 3.3 Initialization

Let's initialize  $p_x^0 = -T \ln n_x$  and  $p_y^0 = -\infty$ .

Then update  $p_y^1$  so that  $e_y\left(\left(p_x^0\right)_x^y, p_y^1\right) = q_y(=m_y)$ . we solve  $\sum \exp\left(\Phi_{xy} - p_x^0 + p_y^1\right) + \exp\left(p_y^1\right) = m_y$ . Because the value of  $p_y^1$  is finite,

$$p_y^0 = -\infty \le p_y^1$$

Then update  $p_x^1$  so that  $e_x\left(p_x^1,\left(p_y^1\right)_y\right)=q_x(=-n_x)$ . We have

$$\sum_{y} \exp\left(\Phi_{xy} - p_x^1 + p_y^1\right) + \exp\left(-\frac{p_x^1}{T}\right) = n_x \ge \exp\left(-\frac{p_x^1}{T}\right)$$

thus  $\exp\left(-\frac{p_x^0}{T}\right) = n_x \ge \exp\left(-\frac{p_x^1}{T}\right)$ 

$$p_x^0 \le p_x^1$$

We have  $m_y \ge \exp(p_y/T)$ , thus  $p_y \le T \ln m_y$ .

$$p_y = -b_y \text{ for } y \in Y$$

$$e_x(p) = -\sum_y \exp\left(\frac{\Phi_{xy} - p_x + p_y}{2T}\right) - \exp\left(-\frac{p_x}{T}\right)$$
 $e_y(p) = \sum_x \exp\left(\frac{\Phi_{xy} - p_x + p_y}{2T}\right) + \exp\left(\frac{p_y}{T}\right)$ 

We have

$$De = \begin{pmatrix} \frac{\partial e_x}{\partial p_x} & \frac{\partial e_x}{\partial p_y} \\ \left(\frac{\partial e_x}{\partial p_y}\right)^{\mathsf{T}} & \frac{\partial e_y}{\partial p_y} \end{pmatrix} = \begin{pmatrix} diag\left(\frac{1}{2T}\exp\left(\frac{\Phi_{xy} - p_x + p_y}{2T}\right) + \frac{1}{T}\exp\left(-\frac{p_x}{T}\right)\right) \\ -\frac{1}{2T}\exp\left(\frac{\Phi_{xy} - p_x + p_y}{2T}\right) & diag\left(\frac{1}{2T}\exp\left(\frac{\Phi_{xy} - p_x + p_y}{2T}\right) + \frac{1}{T}\exp\left(\frac{\Phi_{xy} - p_x + p_y}{2T}\right) \end{pmatrix}$$

Let's run the Gauss-Seidel algorithm

• Solve for  $a_x$  in the first set of equations

$$-\sum_{y} \exp\left(\frac{\Phi_{xy} - a_x - b_y}{2T}\right) - \exp\left(-\frac{a_x}{T}\right) + n_x = 0$$

ullet Solve for  $b_y$  in the second set of equations

$$\sum_{x} \exp\left(\frac{\Phi_{xy} - a_x - b_y}{2T}\right) + \exp\left(-\frac{b_y}{T}\right) = m_y$$

Introduce new unknowns  $A_x = \exp\left(-\frac{a_x}{2T}\right)$  and  $B_y = \exp\left(-\frac{b_y}{2T}\right)$  and  $K_{xy} = \exp\left(\frac{\Phi_{xy}}{2T}\right)$ , we have

$$\sum_{y} K_{xy} A_x B_y + A_x^2 = n_x$$

$$\sum_{y} K_{xy} A_x B_y + B_y^2 = m_y$$

thus

$$A_x^2 + 2A_x \left(\frac{1}{2} \sum_{y} K_{xy} B_y\right) + \left(\frac{1}{2} \sum_{y} K_{xy} B_y\right)^2 = n_x + \left(\frac{1}{2} \sum_{y} K_{xy} B_y\right)^2$$

thus

$$A_{x} = \sqrt{n_{x} + \left(\frac{1}{2}\sum_{y}K_{xy}B_{y}\right)^{2} - \frac{1}{2}\sum_{y}K_{xy}B_{y}}$$

$$B_{y} = \sqrt{m_{y} + \left(\frac{1}{2}\sum_{x}K_{xy}A_{y}\right)^{2} - \frac{1}{2}\sum_{x}K_{xy}A_{y}}$$

### 4 Identification issues

Given  $\mu_{xy}$  and possibly  $w_{xy}$ , can we compute  $\alpha_{xy}$  and  $\gamma_{xy}$ . Recall Choo and Siow's formula

$$\mu_{xy} = \sqrt{\mu_{x0}\mu_{0y}} \exp\left(\frac{\Phi_{xy}}{2T}\right).$$

Scale T = 1, and we get

$$\alpha_{xy} + \gamma_{xy} = \Phi_{xy} = \ln \frac{\mu_{xy}^2}{\mu_{x0}\mu_{0y}}.$$

Assume  $\mu_{xy}$  is observed, then one can identify  $\alpha + \gamma$  only.

Now assume  $\mu_{xy}$  and  $w_{xy}$  are observed, we have

$$\alpha_{xy} = \ln \frac{\mu_{xy}}{\mu_{x0}} - w_{xy}$$

$$\gamma_{xy} = w_{xy} + \ln \frac{\mu_{xy}}{\mu_{0y}}$$

### 5 Taxes

Assume "flat tax" ie x gets indidrect utility

$$u_x = \max_{y} \{\alpha_{xy} + (1 - \tau) w_{xy}, 0\}$$

and y gets indirect utility  $v_y$ 

$$v_y = \max_{x} \left\{ \gamma_{xy} - w_{xy}, 0 \right\}$$

Equilibrium:

$$\begin{split} &\sum_{y} \mu_{xy} + \mu_{x0} = n_x \\ &\sum_{x} \mu_{xy} + \mu_{0y} = m_y \\ &u_x \geq 0, v_y \geq 0 \\ &u_x \geq \alpha_{xy} + (1-\tau) \, w_{xy} \text{ with equality if } \mu_{xy} > 0 \\ &v_y \geq \gamma_{xy} - w_{xy} \text{ with equality if } \mu_{xy} > 0. \end{split}$$

Rewrite as:

$$\begin{split} &\sum_y \mu_{xy} + \mu_{x0} = n_x \\ &\sum_x \mu_{xy} + \mu_{0y} = m_y \\ &u_x \geq 0, v_y \geq 0 \\ &u_x \geq \alpha_{xy} + (1-\tau) \, w_{xy} \text{ with equality if } \mu_{xy} > 0 \\ &(1-\tau) \, v_y \geq (1-\tau) \, \gamma_{xy} - (1-\tau) \, w_{xy} \text{ with equality if } \mu_{xy} > 0. \end{split}$$

Denote  $\tilde{v}_y = (1 - \tau) v_y$  and  $\tilde{\gamma}_{xy} = (1 - \tau) \gamma_{xy}$  and  $\tilde{w}_{xy} = (1 - \tau) w_{xy}$  the indirect utility of the firm and the output measured in post-tax dollars, then we have

$$\begin{split} &\sum_y \mu_{xy} + \mu_{x0} = n_x \\ &\sum_x \mu_{xy} + \mu_{0y} = m_y \\ &u_x \geq 0, v_y \geq 0 \\ &u_x \geq \alpha_{xy} + \tilde{w}_{xy} \text{ with equality if } \mu_{xy} > 0 \\ &\tilde{v}_y \geq \tilde{\gamma}_{xy} - \tilde{w}_{xy} \text{ with equality if } \mu_{xy} > 0. \\ &\text{THEREFORE} \\ &\sum_y \mu_{xy} + \mu_{x0} = n_x \\ &\sum_x \mu_{xy} + \mu_{0y} = m_y \\ &u_x \geq 0, v_y \geq 0 \\ &u_x + \tilde{v}_y \geq \alpha_{xy} + \tilde{\gamma}_{xy} \text{ with equality if } \mu_{xy} > 0 \end{split}$$

Thus  $\mu_{xy}$  and  $(u_x, \tilde{v}_y)$  are solution to

$$\max \sum_{xy} \mu_{xy} \left( \alpha_{xy} + (1 - \tau) \gamma_{xy} \right)$$

$$s.t. \qquad \sum_{y} \mu_{xy} \le n_x$$

$$\sum_{x} \mu_{xy} \le m_y$$

and

$$\begin{aligned} \min \sum_{x} n_x u_x + \sum_{y} m_y \tilde{v}_y \\ s.t. \qquad u_x + \tilde{v}_y &\geq \alpha_{xy} + \tilde{\gamma}_{xy} \\ u_x &\geq 0, \tilde{v}_y \geq 0 \end{aligned}$$