

# Nonlinear Optimization Lecture 4

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## Last time

**Theorem**  $S$  is a non-empty, closed convex set and  $y \notin S$ , then  $\bar{x} \in S$  is the min. distance point. And  $(y - \bar{x})^T(x - \bar{x}) \leq 0, \forall x \in S$ .

## Separation

Let  $S_1, S_2 \subset \mathbb{R}^n$  and  $H = \{x \in \mathbb{R}^n : p^T x = \alpha\}$ .

**Definition.**  $H$  separates  $S_1$  and  $S_2$  if

$$p^T x \geq \alpha \quad \forall x \in S_1$$

$$p^T x \leq \alpha \quad \forall x \in S_2$$

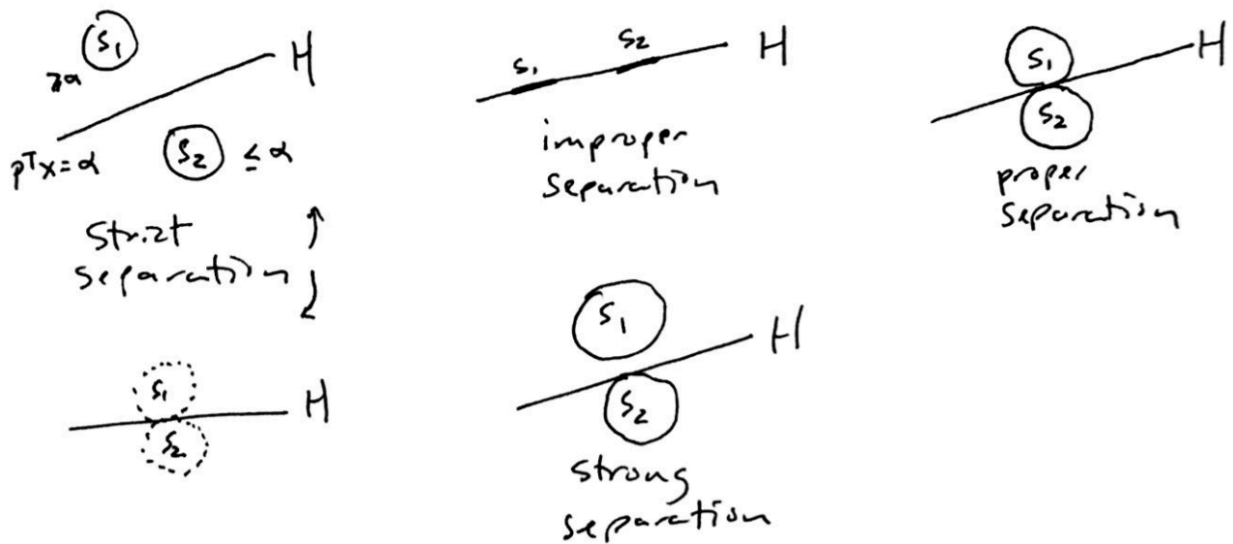


Figure 1: Types of separation

$H$  strictly separates  $S_1$  and  $S_2$  if

$$p^T x > \alpha \quad \forall x \in S_1$$

$$p^T x < \alpha \quad \forall x \in S_2$$

$H$  strongly separates  $S_1$  and  $S_2$  if

$$\begin{aligned} p^T x &\geq \alpha + \epsilon \quad \forall x \in S_1 \\ p^T x &\leq \alpha \quad \forall x \in S_2 \end{aligned}$$

for some  $\epsilon > 0$ .

**Theorem** If  $S$  is a non-empty, closed, convex set and  $y \notin S$ . Then there exists a hyperplane that strongly separates  $S$  and  $\{y\}$  (singleton).

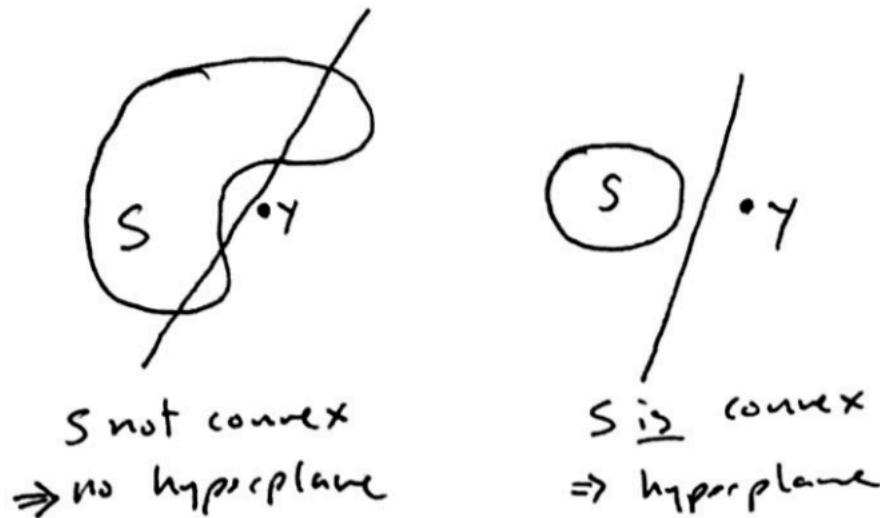


Figure 2: Requirement of convexity for theorem

*Proof.* There exists an  $\bar{x} \in S$  such that  $(y - \bar{x})^T(x - \bar{x}) \leq 0, \forall x \in S$ .

Let

$$\begin{aligned} p &= y - \bar{x} \\ \Rightarrow p^T(x - \bar{x}) &\leq 0 \quad \forall x \in S \\ p^T x &\leq p^T \bar{x} \quad \forall x \in S \\ p^T x &\leq \alpha \quad \forall x \in S \end{aligned}$$

where  $\alpha = p^T \bar{x}$ .

Now we want to show that

$$p^T x \geq \alpha + \epsilon \quad \forall x = y$$

for some  $\epsilon > 0$ , or

$$p^T y > \alpha$$

.

$$\begin{aligned}
& p^T y - \alpha \ (> 0) \\
&= (y - \bar{x})^T y - (y - \bar{x})^T \bar{x} \\
&= (y - \bar{x})^T (y - \bar{x}) \\
&= \|y - \bar{x}\|^2 > 0
\end{aligned}$$

(Note that all norms satisfy  $\|a\| = 0$  iff  $a = 0$ .)

This proves the two conditions listed above for *strong separation*.

## Supporting Hyperplane

Let  $S \in \mathbb{R}^n$ ,  $S \neq \emptyset$ ,  $\bar{x} \in \delta S$ , and  $H = \{x \in \mathbb{R}^n : p^T(x - \bar{x}) = 0\}$ . Note that  $H$  is a hyperplane that passes through  $\bar{x}$  because setting  $x = \bar{x}$  satisfies  $p^T(x - \bar{x}) = 0$ .

$$H^+ = \{x \in \mathbb{R}^n : p^T(x - \bar{x}) \geq 0\}$$

$$H^- = \{x \in \mathbb{R}^n : p^T(x - \bar{x}) \leq 0\}$$

$H$  is a *supporting hyperplane* for  $S$  at  $\bar{x}$  if  $S \subset H^+$  or  $S \subset H^-$ .

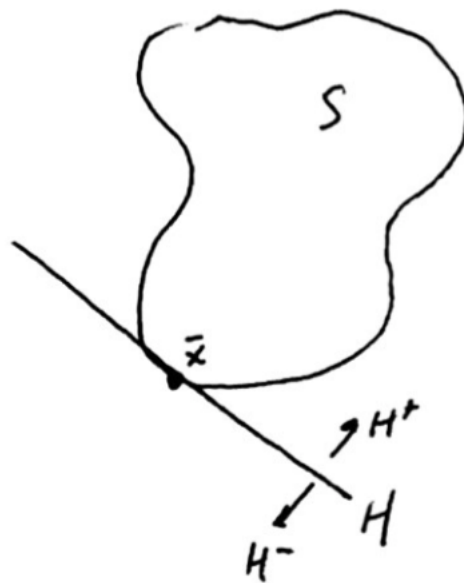


Figure 3:

**Theorem** Let  $S \subset \mathbb{R}^n$  be a closed, non-empty convex set,  $y \notin S$  and  $\bar{x} \in S$  is the closest point to  $y$ .

Then there exists a supporting hyperplane at  $\bar{x}$ .

*Intuition:* Consider  $y$  and  $\bar{x}$ . If you move  $y$  closer and closer to  $\bar{x}$ , then eventually you move the hyperplane up to the boundary of  $S$ . This “process” would converge to the supporting hyperplane.

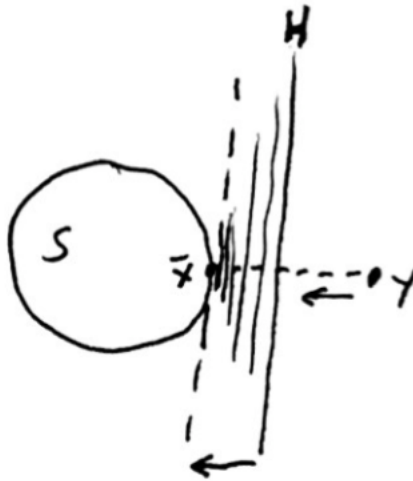


Figure 4: Intuition illustrated

## Convex Functions

$f$  is convex on  $S$  if

$$f(\lambda x_1 + (1 - \lambda)x_2) \leq \lambda f(x_1) + (1 - \lambda)f(x_2)$$

$$\forall x_1, x_2 \in S, \lambda \in [0, 1]$$

## Level Set

Let  $\alpha \in \mathbb{R}$ , then  $S_\alpha = \{x \in S: f(x) \leq \alpha\}$  is the level set.

**Theorem** If  $f$  is convex on  $S$ , then  $S_\alpha$  is a convex set for all  $\alpha \in \mathbb{R}$ .

*Proof.* Let  $x_1, x_2 \in S_\alpha$  and  $\lambda \in [0, 1]$ . We need to show that  $\lambda x_1 + (1 - \lambda)x_2 \in S_\alpha$  for all  $\alpha \in \mathbb{R}$ .

We know that

$$\begin{aligned} f(x_1) &\leq \alpha \\ f(x_2) &\leq \alpha \\ \Rightarrow \lambda f(x_1) &\leq \lambda \alpha \\ (1 - \lambda)f(x_2) &\leq (1 - \lambda)\alpha \end{aligned}$$

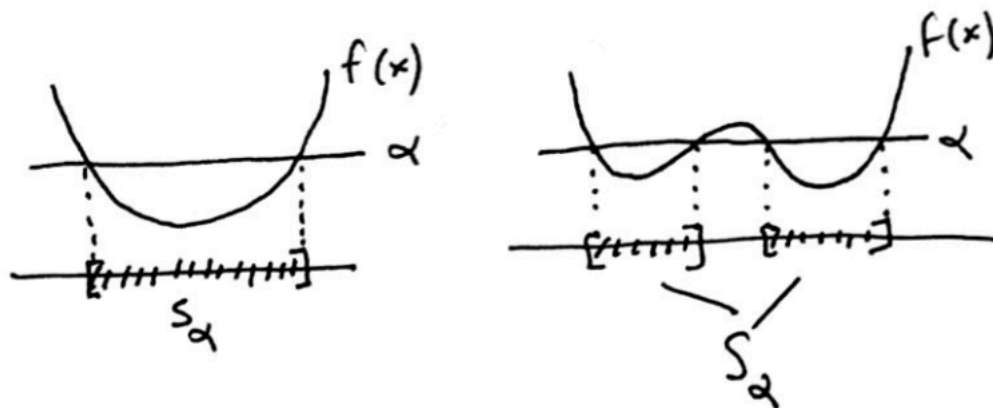


Figure 5: Level sets

$f$  is convex, so

$$\begin{aligned} f(\lambda x_1 + (1 - \lambda)x_2) &\leq \lambda f(x_1) + (1 - \lambda)f(x_2) \\ &\leq \lambda \alpha + (1 - \lambda)\alpha \\ &= \alpha \end{aligned}$$

## Epigraph

**Definition.** An *epigraph* of  $f = \text{epi} f = \{(x, y) : x \in \mathbb{R}^n, y \in \mathbb{R}^1, y \geq f(x)\}$ .

Thus,  $f: \mathbb{R}^n \rightarrow \mathbb{R}$  and  $\text{epi} f \subset \mathbb{R}^{n+1}$ .



Figure 6: Epigraph

**Theorem**  $f: \mathbb{R}^n \rightarrow \mathbb{R}$ .  $f$  is a convex function  $\Leftrightarrow \text{epi} f$  is a convex set.

*Proof. Homework assignment.* Sketch: show  $\Rightarrow$  and then show  $\Leftarrow$ . Intuition, if you have a non-convex function, then clearly  $\text{epi} f$  is going to be a non-convex set.

## Derivatives

When we talk about minimizing functions,  $\min f(x)$ , then the most obvious thing to do is to take the first derivative of  $f$  and setting equal to zero,  $f'(x) = 0$ .

## Partial Derivative and Gradient

Consider

$$\lim_{\lambda \rightarrow 0} \frac{f(x + \lambda e_i) - f(x)}{\lambda}$$

where  $e_i$  is the  $i^{\text{th}}$  unit vector  $= [0 \dots 1 \dots 0]^T$  with 1 at  $i^{\text{th}}$  element.

If the above limit exists

$$\frac{\partial f}{\partial x_i}(x) = \lim_{\lambda \rightarrow 0} \frac{f(x + \lambda e_i) - f(x)}{\lambda}$$

(which is the partial derivative of  $f(x)$  with respect to  $x_i$ ), then the *gradient* of  $f$  at  $x$  is

$$\nabla f(x) = \begin{bmatrix} \frac{\partial f}{\partial x_1}(x) \\ \vdots \\ \frac{\partial f}{\partial x_n}(x) \end{bmatrix} \in \mathbb{R}^n$$

(Note that in the single-variable case, we would typically have  $\Delta x$  in the denominator. But the multi-directional case, this term would be a vector. So we need to rely on the partial derivative instead.)

## Directional Derivative

For any  $d \in \mathbb{R}^n$  the *directional derivative* of  $f$  in the direction  $d$  is

$$f'(x; d) = \lim_{\lambda \rightarrow 0^+} \frac{f(x + \lambda d) - f(x)}{\lambda}$$

**Def.**  $f$  is *differentiable* at  $x$  if and only if  $\nabla f(x)$  exists and  $\nabla f(x)^T d = f'(x; d)$  for all  $d \in \mathbb{R}^n$ . This is *Gateaux-differentiability*.

We will be using this definition many times in discussing optimality conditions.

**Theorem** Given  $f: \mathbb{R}^n \rightarrow \mathbb{R}$  is convex and  $\bar{x} \in \mathbb{R}^n, d \in \mathbb{R}^n$  a non-zero direction.

Then the directional derivative

$$f'(\bar{x}; d)$$

exists.

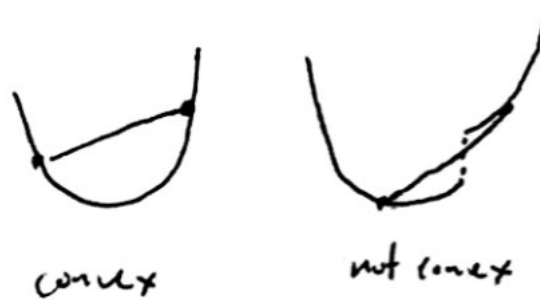


Figure 7:

*Remark.* Can a convex function be discontinuous on its own domain? (Answer is no.)

*Remark.* Can a convex function be non-differentiable? (Answer: yes, consider  $y = |x|$ . Notice that in this case,  $y$  is not differentiable at one point, but the *directional* derivative does exist. The directional derivative is a more “general” derivative.)

## Taylor Expansion

Given  $f(x): \mathbb{R}^n \rightarrow \mathbb{R}$ :

1.  $f(x) = f(\bar{x}) + f'(\bar{x})(x - \bar{x}) + \frac{1}{2!}f''(x)(x - \bar{x})^2 + \dots$
2.  $f(x) = f(\bar{x}) + (x - \bar{x})^T \nabla f(\bar{x}) + \frac{1}{2!}(x - \bar{x})^T H(x)(x - \bar{x}) + \dots$

- Where  $\nabla f(\bar{x})$  is the gradient and  $H(x)$  is the Hessian (look up!)

Precisely the  $(\dots)$  terms in (2) is a function  $\|x - \bar{x}\|^2 \cdot \alpha(\bar{x}; x - \bar{x})$  and  $\lim_{x \rightarrow \bar{x}} \alpha(\bar{x}; x - \bar{x}) = 0$ .