

Nonlinear Optimization Lecture 13

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Theorem

$$\begin{array}{ll}
 \min & f(x) \\
 & g(x) \leq 0 \\
 \text{s.t.} & h(x) = 0 \\
 & x \in X
 \end{array}
 \quad
 \begin{array}{l}
 w = \begin{bmatrix} u \\ v \end{bmatrix} \\
 \beta(x) = \begin{bmatrix} g(x) \\ h(x) \end{bmatrix} \\
 \theta(w) = \inf_{x \in X} \{f(x) + w^T \beta(x)\}
 \end{array}$$

Def. *Lagrangian Dual Function* is the $\theta(w) = \inf_{x \in X} \{f(x) + w^T \beta(x)\}$.

Rewriting the theorem from last lecture:

- **If** X is a non-empty compact set.
- $X(w) = \{\bar{x} : f(\bar{x}) + w^T \beta(\bar{x}) = \inf \{f(x) + w^T \beta(x)\}\}$
- Suppose $X(\bar{w})$ is the singleton $\{\bar{x}\}$
- **Then** $\theta(w)$ is differentiable at \bar{w} and $\nabla \theta(\bar{w}) = \beta(\bar{x})$.

Theorem

- X : non-empty, compact
- f, β are continuous
- $X(\bar{w})$ is *not empty* for any \bar{w}
- If $\bar{x} \in X(\bar{w})$, then $\beta(\bar{x})$ is a *subgradient* of θ at \bar{w} .

Proof. $\theta(w)$ is a concave function $\Rightarrow \exists$ a subgradient for all w .

$$\begin{aligned}
 \theta(w) &= \inf_{x \in X} \{f(x) + w^T \beta(x)\} \\
 &\geq f(\bar{x}) + w^T \beta(\bar{x}) \\
 &= f(\bar{x}) + (w - \bar{w})^T \beta(\bar{x}) + \bar{w}^T \beta(\bar{x}) \\
 &= [f(\bar{x}) + \bar{w}^T \beta(\bar{x})] + (w - \bar{w})^T \beta(\bar{x}) \\
 &= \theta(\bar{w}) + \beta(\bar{x})^T (w - \bar{w}) \\
 &\Rightarrow \beta(\bar{x}) \text{ is a subgradient at } \bar{w}
 \end{aligned}$$

Example

$$\begin{aligned}
\min \quad & -x_1 - x_2 \\
\text{s.t} \quad & x_1 + 2x_2 - 3 \leq 0 \\
& x_1, x_2 \in \{0, 1, 2, 3\}
\end{aligned}$$

$$\begin{aligned}
\theta(u) &= \inf_{x \in X} \{-x_1 - x_2 + u(x_1 + 2x_2 - 3)\} \\
&= \inf_{x \in X} \{(u-1)x_1 + (2u-1)x_2 - 3u\} \\
&= \begin{cases} -6 + 6u & \text{if } u \leq \frac{1}{2} \\ -3 & \text{if } \frac{1}{2} \leq u \leq 1 \\ -3u & \text{if } u \geq 1 \end{cases}
\end{aligned}$$

Let $\bar{u} = \frac{1}{2}$. Then $X(\bar{u}) = \arg \min_{x \in X} \{f(x) + \bar{u}g(x)\}$.

$$\begin{aligned}
\min \quad & -x_1 - x_2 + \frac{1}{2}(x_1 + x_2 - 3) = -\frac{1}{2}x_1 - \frac{3}{2} \\
\text{s.t} \quad & x_1, x_2 \in \{0, 1, 2, 3\}
\end{aligned}$$

Then $X(\frac{1}{2}) = \{(3, 0), (3, 1), (3, 2), (3, 3)\}$.

The subgradients of $\theta(u)$ at $u = \frac{1}{2}$. From the theorem, $\beta(\bar{u}) \forall \bar{x} \in X(\bar{w})...$

$$\begin{aligned}
g(3, 0) &= 3 - 3 = 0 \\
g(3, 1) &= 3 + 2 - 3 = 2 \\
g(3, 2) &= 3 + 4 - 3 = 4 \\
g(3, 3) &= 3 + 6 - 3 = 6
\end{aligned}$$

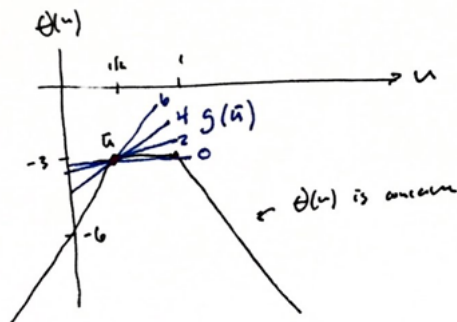


Figure 1:

Note that there are infinite subgradients at \bar{u} , for any line with slope between 0 and 6. The theorem states that *some* of the subgradients are given in the form above, but not all.

Theorem

- X : non-empty compact
- f, β : continuous
- ξ is a subgradient of θ at \bar{w} if and only if $\xi \in \text{convex hull of } \{\beta(\bar{x}) : \bar{x} \in X(\bar{w})\}$.

Line Search without Derivative

$\min f(x)$, $f: \mathbb{R} \rightarrow \mathbb{R}$. Let f be strictly quasiconvex (monotonically decreasing, and then monotonically increasing).

Strictly quasiconvex function: $f(\lambda\bar{x} + (1-\lambda)\hat{x}) < \max\{f(\bar{x}), f(\hat{x})\}$, $\forall \lambda \in (0, 1)$, $f(\bar{x}) \neq f(\hat{x})$.

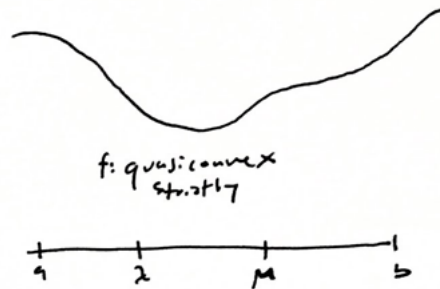


Figure 2: Quasiconvex function illustration and first line search algorithm layout.

Theorem

- (1) If $f(\lambda) \leq f(\mu)$, then $f(x) \geq f(\lambda) \forall x \in (\mu, b]$.
- (2) If $f(\lambda) \geq f(\mu)$, then $f(x) \geq f(\mu) \forall x \in [a, \lambda)$.

Point (1) states that if $f(b)$ is highest and $f(\mu)$ and $f(\lambda)$ are lower (in that order), then the inflection point is definitely not between μ and b . Point (2) says the same thing but on the side of $f(a)$, discarding the points between a and λ .

Proof. Suppose not: assume $\exists \bar{x} \in (\mu, b]$ such that $f(\bar{x}) < f(\lambda)$. Then $f(\lambda) < f(\mu) < f(\bar{x}) \leq f(b)$. Consider the definition of strong quasiconvex functions:

$$\begin{aligned} f(\mu) &< \max\{f(\lambda), f(\bar{x})\} \\ &= f(\lambda) \end{aligned}$$

But this is a contradiction.

Dichotomous Search

Intuition: We would like to maximize the search area that is being abandoned in each step. In the above line search if λ, μ, a, b are all highly separated, then each iteration discards a small portion of the search space.

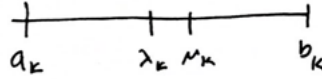


Figure 3:

Let $\lambda_k = \frac{a_k + b_k}{2} - \epsilon$ and $\mu_k = \frac{a_k + b_k}{2} + \epsilon$

Step 0 Choose an interval $[a_1, b_1]$ that contains an optimal solution. Choose $\epsilon > 0, \delta > 0$. Set $k = 1$.

Step 1 Compute λ_k, μ_k .

Step 2 If $f(\lambda_k) < f(\mu_k)$ let

$$a_{k+1} = a_k$$

$$b_{k+1} = \mu_k$$

Otherwise, let

$$a_{k+1} = \lambda_k$$

$$b_{k+1} = b_k$$

Step 3 If $b_{k+1} - a_{k+1} < \delta$, then stop:

$$x^* \approx \frac{a_{k+1} + b_{k+1}}{2}$$

Otherwise, set $k = k + 1$ and go to **Step 1**.

Note that we need $\epsilon < \frac{\delta}{2}$ for this to work. But that this algorithm requires a significant number of function evaluations, which will add computation time. This leads us to the next algorithm.

Golden Section Search

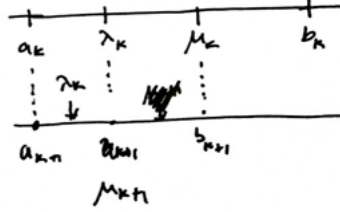


Figure 4:

In the previous algorithm, new function evaluations are needed for every point evaluated at every iteration. In the golden section search, we want to re-use previous function evaluations, and only evaluate one new point at each search.

Position so that $\mu_{k+1} = \lambda_k$ or $\lambda_{k+1} = \mu_k$.

$$\lambda_k = \alpha a_k + (1 - \alpha)b_k$$

$$\mu_k = (1 - \alpha)a_k + \alpha b_k$$

Find α so that $\mu_{k+1} = \lambda_k$

$$\begin{aligned} \mu_{k+1} &= (1 - \alpha)a_{k+1} + \alpha b_{k+1} \\ &= (1 - \alpha)a_k + \alpha \mu_k \\ &= (1 - \alpha)a_k + \alpha((1 - \alpha)a_k + \alpha b_k) \\ &= (1 - \alpha^2)a_k + \alpha^2 b_k \\ \lambda_k &= \alpha a_k + (1 - \alpha)b_k \end{aligned}$$

So we want $1 - \alpha^2 = \alpha \Rightarrow \alpha = \frac{-1+\sqrt{5}}{2} \approx 0.618$

If we do n function evaluations the length of the interval is reduced by $(0.618)^{n-1}$. Dichotomous search is only $\approx (0.5 - \epsilon)^{\frac{n}{2}}$.