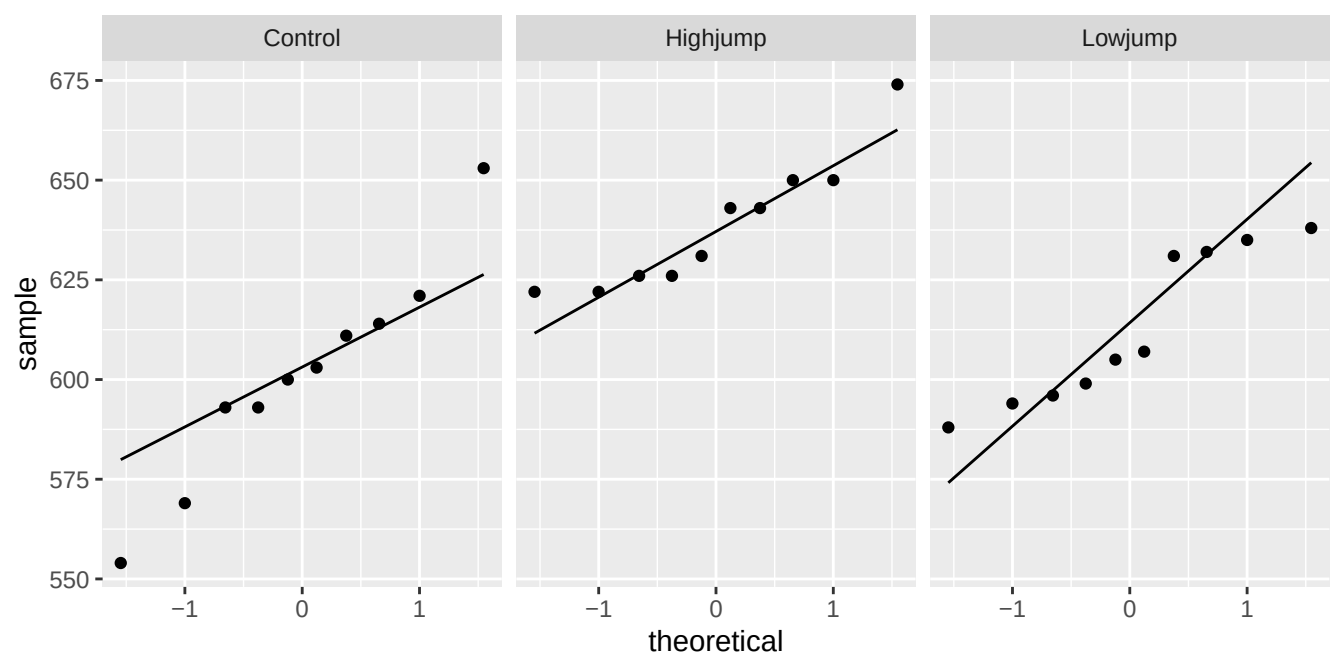
Control
Highjump
Lowjump
675
650
625
600
575
550
sample
−1
0
1
theoretical