

Convolutional Layers

Convolutions on RGB image

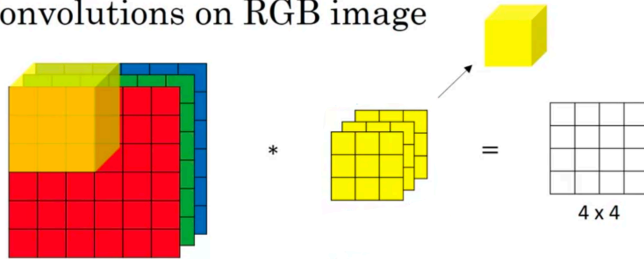


Figure from Andrew Ng

Convolutional layer:

- Apply filter at each location in input
 - Multiply all corresponding numbers
 - Sum results
- Input shape: $n_h \times n_w \times n_c$
- Output shape:

$$\left\lfloor \frac{n_h + 2p - f}{s} + 1 \right\rfloor \times \left\lfloor \frac{n_w + 2p - f}{s} + 1 \right\rfloor \times n_{filters}$$

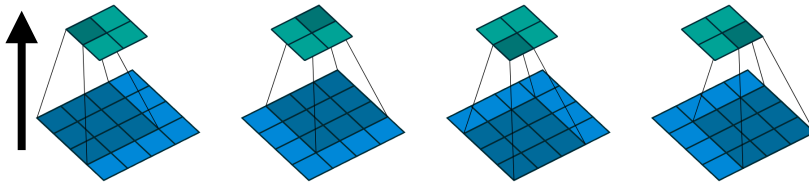


Figure from Dumoulin and Visin. "A guide to convolution arithmetic for deep learning" (2016)

Convolutional Layers

Convolutions on RGB image

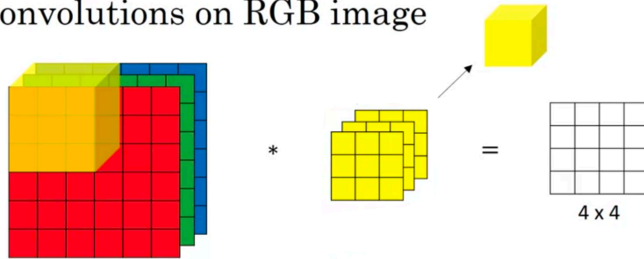
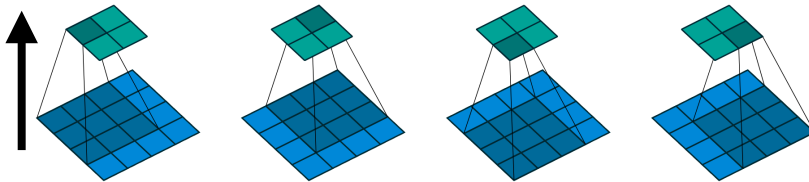


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Can we go backwards?

Figure from Dumoulin and Visin. "A guide to convolution arithmetic for deep learning" (2016)

Algorithm for Convolutions

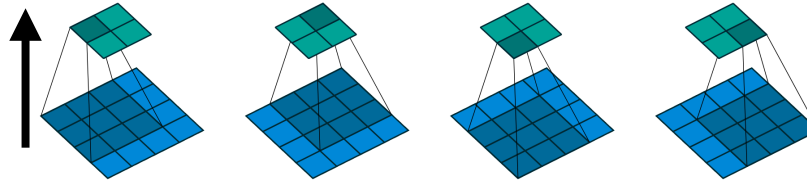
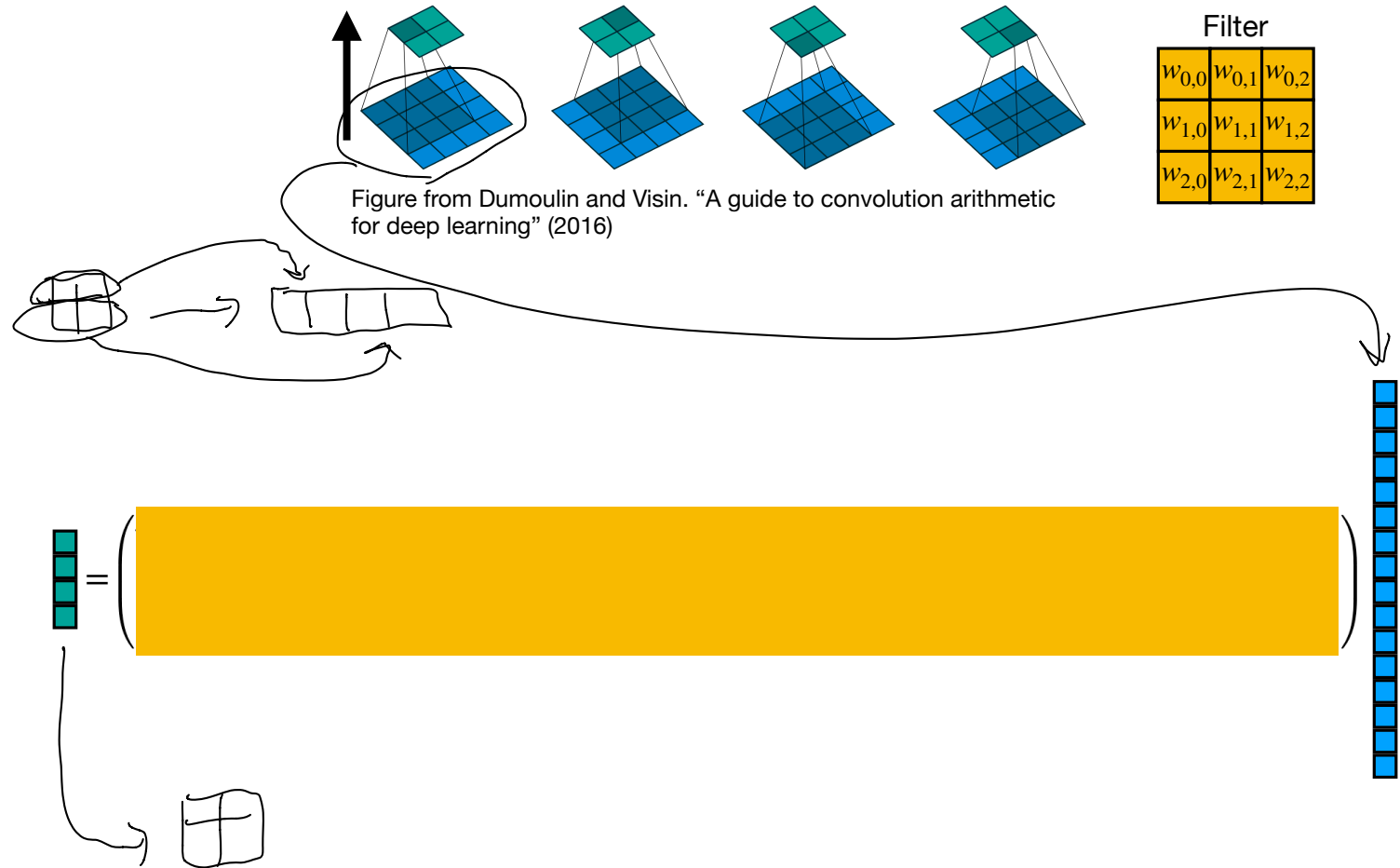


Figure from Dumoulin and Visin. “A guide to convolution arithmetic for deep learning” (2016)

Filter		
$w_{0,0}$	$w_{0,1}$	$w_{0,2}$
$w_{1,0}$	$w_{1,1}$	$w_{1,2}$
$w_{2,0}$	$w_{2,1}$	$w_{2,2}$

- For $i = 0, \dots, \left\lfloor \frac{n_H + 2p - f}{s} + 1 \right\rfloor$
 - For $j = 0, \dots, \left\lfloor \frac{n_W + 2p - f}{s} + 1 \right\rfloor$
 - * $\text{start_row} = i * s, \text{end_row} = \text{start_row} + f$
 - * $\text{start_col} = j * s, \text{end_col} = \text{start_col} + f$
 - * $\text{output}[i, j] = \text{np.sum}(W * A[\text{start_row}:\text{end_row}, \text{start_col}:\text{end_col}])$

Convolutions via Matrices



Convolutions via Matrices

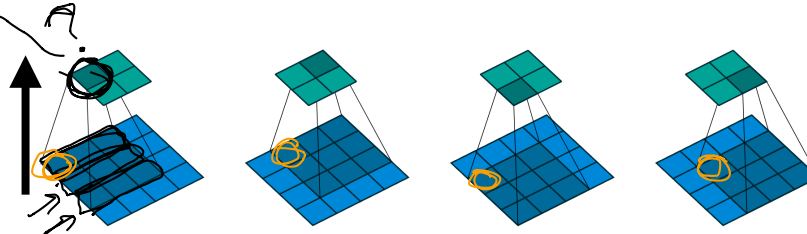


Figure from Dumoulin and Visin. "A guide to convolution arithmetic for deep learning" (2016)

Filter

$w_{0,0}$	$w_{0,1}$	$w_{0,2}$
$w_{1,0}$	$w_{1,1}$	$w_{1,2}$
$w_{2,0}$	$w_{2,1}$	$w_{2,2}$

$$\begin{bmatrix} \text{4x1 vector} \end{bmatrix} = \begin{bmatrix} w_{0,0} & w_{0,1} & w_{0,2} & 0 & w_{1,0} & w_{1,1} & w_{1,2} & 0 & w_{2,0} & w_{2,1} & w_{2,2} & 0 & 0 & 0 & 0 & 0 \\ 0 & w_{0,0} & w_{0,1} & w_{0,2} & 0 & w_{1,0} & w_{1,1} & w_{1,2} & 0 & w_{2,0} & w_{2,1} & w_{2,2} & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & w_{0,0} & w_{0,1} & w_{0,2} & 0 & w_{1,0} & w_{1,1} & w_{1,2} & 0 & w_{2,0} & w_{2,1} & w_{2,2} & 0 \\ 0 & 0 & 0 & 0 & 0 & w_{0,0} & w_{0,1} & w_{0,2} & 0 & w_{1,0} & w_{1,1} & w_{1,2} & 0 & w_{2,0} & w_{2,1} & w_{2,2} \end{bmatrix} \begin{bmatrix} \text{16x1 vector} \end{bmatrix}$$

16 columns

because 4x4 input to convolution

4 rows because 2x2 output from convolution

Transposed Convolutions (aka “Deconvolutions”)

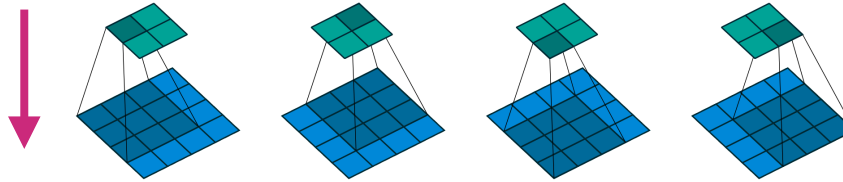
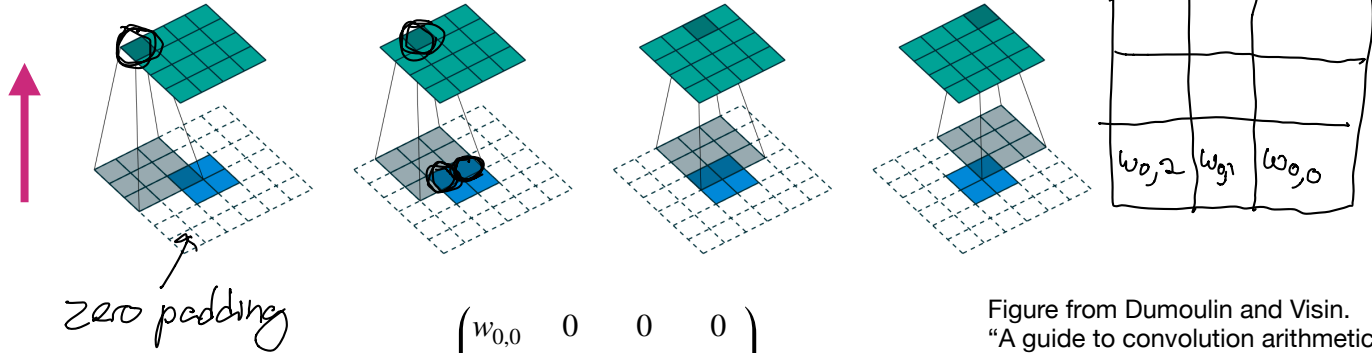


Figure from Dumoulin and Visin. “A guide to convolution arithmetic for deep learning” (2016)

$$\begin{array}{c} \text{1x16 vector} \end{array} = \begin{pmatrix} w_{0,0} & 0 & 0 & 0 \\ w_{0,1} & w_{0,0} & 0 & 0 \\ w_{0,2} & w_{0,1} & 0 & 0 \\ w_{0,0} & w_{0,2} & 0 & 0 \\ w_{1,0} & 0 & w_{0,0} & 0 \\ w_{1,1} & w_{1,0} & w_{0,1} & w_{0,0} \\ w_{1,2} & w_{1,1} & w_{0,2} & w_{0,1} \\ 0 & w_{1,2} & 0 & w_{0,2} \\ w_{2,0} & 0 & w_{1,0} & 0 \\ w_{2,1} & w_{2,0} & w_{1,1} & w_{1,0} \\ w_{2,2} & w_{2,1} & w_{1,2} & w_{1,1} \\ 0 & w_{2,2} & 0 & w_{1,2} \\ 0 & 0 & w_{2,0} & 0 \\ 0 & 0 & w_{2,1} & w_{2,0} \\ 0 & 0 & w_{2,2} & w_{2,1} \\ 0 & 0 & 0 & w_{2,2} \end{pmatrix} \begin{array}{c} \text{4x1 vector} \end{array}$$

Transposed Convolutions are Still Convolutions!



$$\left\lceil \frac{n_h + 2p - f}{s} + 1 \right\rceil$$

$$\begin{matrix}
 \begin{matrix} \color{teal} \blacksquare \\ \color{teal} \blacksquare \\ \color{teal} \blacksquare \\ \color{teal} \blacksquare \\ \color{teal} \blacksquare \\ \color{teal} \blacksquare \\ \color{teal} \blacksquare \\ \color{teal} \blacksquare \\ \color{teal} \blacksquare \\ \color{teal} \blacksquare \\ \color{teal} \blacksquare \\ \color{teal} \blacksquare \end{matrix} & = & \begin{pmatrix}
 w_{0,0} & 0 & 0 & 0 \\
 \underline{w_{0,1}} & \underline{w_{0,0}} & 0 & 0 \\
 w_{0,2} & w_{0,1} & 0 & 0 \\
 w_{0,0} & w_{0,2} & 0 & 0 \\
 w_{1,0} & 0 & w_{0,0} & 0 \\
 w_{1,1} & w_{1,0} & w_{0,1} & w_{0,0} \\
 w_{1,2} & w_{1,1} & w_{0,2} & w_{0,1} \\
 0 & w_{1,2} & 0 & w_{0,2} \\
 w_{2,0} & 0 & w_{1,0} & 0 \\
 w_{2,1} & w_{2,0} & w_{1,1} & w_{1,0} \\
 w_{2,2} & w_{2,1} & w_{1,2} & w_{1,1} \\
 0 & w_{2,2} & 0 & w_{1,2} \\
 0 & 0 & w_{2,0} & 0 \\
 0 & 0 & w_{2,1} & w_{2,0} \\
 0 & 0 & w_{2,2} & w_{2,1} \\
 0 & 0 & 0 & w_{2,2}
 \end{pmatrix} & \begin{matrix} \color{blue} \blacksquare \\ \color{blue} \blacksquare \\ \color{blue} \blacksquare \end{matrix}
 \end{matrix}$$

Figure from Dumoulin and Visin.
 "A guide to convolution arithmetic
 for deep learning" (2016)

Transpose is not the Inverse!

Denote this matrix by C:

$$\begin{pmatrix} w_{0,0} & w_{0,1} & w_{0,2} & 0 & w_{1,0} & w_{1,1} & w_{1,2} & 0 & w_{2,0} & w_{2,1} & w_{2,2} & 0 & 0 & 0 & 0 & 0 \\ 0 & w_{0,0} & w_{0,1} & w_{0,2} & 0 & w_{1,0} & w_{1,1} & w_{1,2} & 0 & w_{2,0} & w_{2,1} & w_{2,2} & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & w_{0,0} & w_{0,1} & w_{0,2} & 0 & w_{1,0} & w_{1,1} & w_{1,2} & 0 & w_{2,0} & w_{2,1} & w_{2,2} & 0 \\ 0 & 0 & 0 & 0 & 0 & w_{0,0} & w_{0,1} & w_{0,2} & 0 & w_{1,0} & w_{1,1} & w_{1,2} & 0 & w_{2,0} & w_{2,1} & w_{2,2} \end{pmatrix}$$

- C is not a square matrix, so it is not invertible! (Does not have full column rank!)
- The transposed convolution C^T gets us back to the original dimensions
- The transposed convolution does not technically “undo” the original convolution

$$\text{result} = C^T C \cdot \text{input}$$

result and input have same dimension but are not equal!