

Bayesian Basics

We are interested in obtaining the posterior distribution for making inferences.

$$\text{posterior} = \frac{\text{likelihood} * \text{prior}}{\int \text{likelihood} * \text{prior}}$$

It is often easier to work without the denominator, and recognize the posterior density.

$$\text{posterior} \propto \text{likelihood} * \text{prior}$$

Want to know characteristics about the posterior (such as posterior mean), and sample from the posterior.

Review of Marginal and Conditional Distributions

$$p(y|x) = \frac{p(x,y)}{p(y)} \text{ is conditional of } y \text{ given } x$$

$$p(x) = \int p(x,y) \delta y = \int p(y|x) p(x) \delta y \text{ is marginal of } x$$

$$\text{Under independence, } p(x,y) = p(y|x)p(x)$$

Basic Hierarchical Model Setup

Normal-Gamma Gaussian Linear Model:

$$(y_i|\theta, \sigma^2) \sim N(\theta, \sigma^2), i = 1, \dots, n$$

$$(\theta|\sigma^2) \sim N(\mu, \tau\sigma^2)$$

$$\sigma^2 \sim \text{Inv-Gamma}(\frac{d}{2}, \frac{\eta}{2})$$

Reframed to work with precision $\omega = 1/\sigma^2$, called the Normal-Gamma Prior for (θ, ω) :

$$(y_i|\theta, \omega) \sim N(\theta, (\omega)^{-1}), i = 1, \dots, n$$

$$(\theta|\omega) \sim N(\mu, (k\omega)^{-1})$$

$$\omega \sim \text{Gamma}(\frac{d}{2}, \frac{\eta}{2})$$

Hyperparameter interpretation:

- μ = Prior guess for θ .
- τ = Prior signal-to-noise ratio for σ^2 .
- d = Prior sample size for σ^2 .
- η = Prior sum of squares for σ^2 ; $\frac{\eta}{d} \approx$ prior guess for σ^2 .
- $k = \frac{1}{\tau^2}$ is prior sample size for θ .

Prior

Joint prior:

$$p(\theta, \omega) = p(\theta|\omega)p(\omega)$$

Marginal priors:

$$\begin{aligned} p(\omega) &= p(\omega) \\ p(\theta|\omega) &= \int p(\theta, \omega) \delta\omega = \int p(\theta|\omega)p(\omega) \delta\omega \end{aligned}$$

Likelihood (Sampling Model)

$$p(y|\theta, \omega) = \prod_{i=1}^n p(y_i|\theta, \omega)$$

Posterior

Joint posterior (up to a constant of proportionality):

$$\begin{aligned} p(\theta, \omega|y) &\propto p(y|\theta, \omega)p(\theta, \omega) \\ &= p(y|\theta, \omega)p(\theta|\omega)p(\omega) \end{aligned}$$

Marginal posteriors.

$$\begin{aligned} p(\theta|y) &= \int p(\theta, \omega|y) \delta\omega \\ p(\omega|y) &= \int p(\theta, \omega|y) \delta\theta \end{aligned}$$

Conditional posteriors. (Full conditionals.)

$$\begin{aligned} p(\theta|y, \omega) &\propto p(y|\theta, \omega)p(\theta) \\ p(\omega|y, \theta) &\propto p(y|\theta, \omega)p(\omega) \end{aligned}$$

- Obtain the joint posterior, and read off forms of conditionals by considering all other variables constant.
- Need all full conditionals to sample from joint posterior using Gibbs Sampler or similar. (Is easier than sampling from joint posterior.)

More Complex Hierarchical Model Setup

Normal-Gamma Gaussian Multivariate Linear Model (Bayesian Regression):

$$\begin{aligned}
 (y|\beta, \omega, \Lambda) &\sim N\left(X\beta, (\omega\Lambda)^{-1}\right) \\
 \lambda_i &\stackrel{iid}{\sim} \text{Gamma}\left(\frac{h}{2}, \frac{h}{2}\right) \\
 (\beta|\omega) &\sim N\left(m, (\omega K)^{-1}\right) \\
 \omega &\sim \text{Gamma}\left(\frac{d}{2}, \frac{\eta}{2}\right)
 \end{aligned}$$

Prior

Joint prior:

$$p(\beta, \omega, \Lambda) = p(\beta|\omega)p(\omega)p(\Lambda)$$

Likelihood

$$p(y|\beta, \omega, \Lambda) \propto N\left(X\beta, (\omega\Lambda)^{-1}\right)$$

Posterior

Joint posterior:

$$p(\beta, \omega, \Lambda|y) \propto p(y|\beta, \omega, \Lambda)p(\beta|\omega)p(\omega)p(\Lambda)$$

Full posterior conditionals.

$$\begin{aligned}
 p(\beta|\omega, \Lambda, y) &\propto p(y|\beta, \omega, \Lambda)p(\beta|\omega)p(\omega)p(\Lambda) \\
 &\propto p(y|\beta, \omega, \Lambda)p(\beta|\omega)
 \end{aligned}$$

$$\begin{aligned}
 p(\omega|\beta, \Lambda, y) &\propto p(y|\beta, \omega, \Lambda)p(\beta|\omega)p(\omega)p(\Lambda) \\
 &\propto p(y|\beta, \omega, \Lambda)p(\beta|\omega)p(\omega)
 \end{aligned}$$

$$\begin{aligned}
 p(\lambda_i|y, \beta, \omega) &\propto p(y|\lambda_i, \beta, \omega)p(\lambda_i|\beta, \omega)p(\beta|\omega)p(\omega) \\
 &\propto p(y|\lambda_i, \beta, \omega)p(\lambda_i)
 \end{aligned}$$

- For full conditionals, read these off of the joint posterior, by considering all variables on the right side of the | to be constant.