SDS 383D Ex 03: Linear Smoothing and Gaussian Processes

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Basic Concepts

Bias-Variance Decomposition

Let $\hat{f}(x)$ be a noisy estimate of some function f(x), evaluated at some point x. Define the mean-squared error of the estimate as

$$MSE(\hat{f}, f) = E\{[f(x) - \hat{f}]^2\}$$

Prove that MSE $(f, \hat{f}) = B^2 + v$, where

$$B = E\{\hat{f}(x)\} - f(x) \text{ and } v = var\{f(x)\} = E\left[\left(\hat{f} - E\left(\hat{f}\right)\right)^2\right]$$

Begin with the definition of MSE.

$$MSE [f, \hat{f}] = E [(f - \hat{f})^{2}]$$

$$= E [(\hat{f} - f)^{2}]$$

$$= E [(\hat{f} - E(\hat{f}) + E(\hat{f}) - f)^{2}], \text{ adding/subtracting } E(\hat{f})$$

$$= E [(\hat{f} - E(\hat{f}) + E(\hat{f}) - f) (\hat{f} - E(\hat{f}) + E(\hat{f}) - f)]$$

$$= E [(\hat{f} - E(\hat{f}))^{2}] - E [(E(\hat{f}) - f)^{2}] + 2E [(\hat{f} - E(\hat{f})) (E(\hat{f}) - f)]$$

$$= E [(\hat{f} - E(\hat{f}))^{2}] - (E(\hat{f}) - f)^{2} + 2E [(\hat{f} - E(\hat{f})) (E(\hat{f}) - f)]$$

$$\text{since } E(E(X)) = E(X)$$

$$= Var(\hat{f}) - (Bias(\hat{f}, f))^{2} + 0$$

The last term reduces to zero as shown below.

$$2E\left[\left(\hat{f} - E\left(\hat{f}\right)\right)\left(E\left(\hat{f}\right) - f\right)\right]$$

$$= E\left[\hat{f}E\left(\hat{f}\right) - E\left(\hat{f}\right)E\left(\hat{f}\right) - \hat{f}f + E\left(\hat{f}\right)f\right]$$

Then $\hat{f} = E(\hat{f})$, giving us

$$= E\left[E\left(\hat{f}\right)E\left(\hat{f}\right) - E\left(\hat{f}\right)E\left(\hat{f}\right) - E\left(\hat{f}\right)f + E\left(\hat{f}\right)f\right]$$

= 0

Part A

Suppose we observe $x_1, ..., x_n$ from some distribution F, and want to estimate f(0), the value of the probability density function at 0. Let h be a small positive number, called the bandwidth, and define the quantity

$$\pi_h = P\left(-\frac{h}{2} < X < \frac{h}{2}\right) = \int_{-h/2}^{h/2} f(x) dx$$

Clearly $\pi_h \approx hf(0)$. Let Y be the number of observations in a sample of size n that fall within the interval (-h/2, h/2). What is the distribution of Y? What are its mean and variance in terms of n and π_h ? Propose a simple estimator $\hat{f}(0)$ involving Y.

Let Y be the number of x_i in $\left(-\frac{h}{2}, \frac{h}{2}\right)$. Then

$$Y \sim Binom(n, \pi_h)$$

To estimate $\hat{\pi}_h$,

$$\hat{\pi}_h = \frac{y}{n}$$
, the Binomial MLE

Therefore $y = n\pi_h$.

Then our simple estimator for $\hat{f}(0)$ is

$$\hat{f}(0) = \frac{\hat{\pi}_h}{h} = \frac{y}{nh}$$

Then, since $Y \sim Binom(n, \pi_h)$, expectation and variance are

$$E(Y) = n\pi_h$$
$$Var(Y) = n\pi_h(1 - \pi_h)$$

Part B

Suppose we expand f(x) in a second-order Taylor series about 0:

$$f(x) \approx f(0) + xf'(0) + \frac{x^2}{2}f''(0)$$
.

Use this in the above expression for π_h *, together with the bias–variance decomposition, to show that*

$$MSE\{\hat{f}(0), f(0)\} \approx Ah^4 + \frac{B}{nh}$$

for constants A and B that you should (approximately) specify. What happens to the bias and variance when you make h small? When you make h big?

Plug in Taylor series approximation to definition of π_h .

$$\hat{\pi}_h \approx \int_{-\frac{h}{2}}^{\frac{h}{2}} \left[f(0) + xf'(0) + \frac{x^2}{2} f''(0) \right] dx$$
$$= hf(0) + \frac{h^3 f''(0)}{24}$$

Plug in $\hat{\pi}_h$ to E(Y) and Var(Y) to obtain components of $MSE = Var + Bias^2$. Mean:

$$E\left[\hat{f}(0)\right] = E\left[\frac{Y}{nh}\right] = \frac{1}{nh}E\left[Y\right] = \frac{1}{nh}n\pi_h \approx \frac{1}{h}\left(\frac{h^2f''(0)}{24}\right) = f(0) + \frac{h^2f''(0)}{24}$$

Variance:

$$Var\left[\hat{f}(0)\right] = Var\left[\frac{Y}{nh}\right] = \frac{Var\left[Y\right]}{n^2h^2} = \frac{n\pi_h(1-\pi_h)}{n^2h^2} = \frac{\pi_h(1-\pi_h)}{nh^2} \approx \frac{\pi_h}{nh^2}^{(**)}$$
$$= \frac{hf(0) + \frac{h^3f''(0)}{24}}{nh^2} = \frac{f(0)}{nh} + \frac{hf''(0)}{24n} \approx \frac{f(0)}{nh}^{(***)}$$

(**) Because h small positive number, so π_h small, so $(1 - \pi_h) \approx 1$.

(***) Because h small and h < 1, first term bigger than second by 24x, so can simplify. Bias:

bias =
$$E\left[\hat{f}(0)\right] - f(0) = f(0) + \frac{h^2 f''(0)}{24} - f(0) = \frac{h^2 f''(0)}{24}$$

Then MSE is as follows.

$$MSE = var + bias^2 \approx \frac{f(0)}{nh} + \left(\frac{h^2 f''(0)}{24}\right)^2 = \frac{f(0)}{nh} + \frac{h^4 (f''(0))^4}{576}$$

- Smaller $h \rightarrow$ smaller bias, but larger variance.
- Large $h \rightarrow larger$ bias, but smaller variance.

Note: Could include all of the algebraic terms, but these two dominate in order of h.

Part C

Use this result to derive an expression for the bandwidth that minimizes mean-squared error, as a function of n. You can approximate any constants that appear, but make sure you get the right functional dependence on the sample size.

Could solve previous MSE expression for the optimal h by taking the first derivative, setting equal to zero, and getting an expression in terms of h. This expression would include n, so the optimal bandwidth depends on sample size.

Curve Fitting by Linear Smoothing

Consider a nonlinear regression problem with one predictor and one response: $y_i = f(x_i) + \epsilon_i$, where the ϵ_i are mean-zero random variables.

Part A

Suppose we want to estimate the value of the regression function y^* at some new point x^* , denoted $\hat{f}(x^*)$. Assume for the moment that f(x) is linear, and that y and x have already had their means subtracted, in which case $y_i = \beta x_i + \epsilon_i$. Return to your least-squares estimator for multiple regression. Show that for the one-predictor case, your prediction $y^* = f(x^*) = \hat{\beta}x^*$ may be expressed as a linear smoother of the following form:

$$\hat{f}(x^*) = \sum_{i=1}^n w(x_i, x^*) y_i$$

for any x^* . Inspect the weighting function you derived. Briefly describe your understanding of how the resulting smoother behaves, compared with the smoother that arises from an alternate form of the weight function $w(x_i, w^*)$:

$$w_K(x_i, x^*) = \begin{cases} 1/K, x_i \text{ one of the closest } K \text{ sample points to } x_i \\ 0, \text{ otherwise} \end{cases}$$

This is referred to as K-nearest-neighbor smoothing.

The weighting function for smoothing is derived using the following.

$$\begin{split} \hat{f}(x^*) &= \hat{\beta}x^* \\ &= X^*(X'X)^{-1}X'y \\ &= x^* \cdot \frac{\sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y})}{\sum_{i=1}^n (x_i - \bar{x})^2} \\ &= \frac{\sum_{i=1}^n x_i x^* y_i}{\sum_{i=1}^n x_i^2} \end{split}$$

since we are working in the single-predictor, single-response, mean-zero case.

Therefore,

$$\hat{f}(x^*) = \sum_{i=1}^{n} w(x_i, x^*) y_i, \text{ with}$$

$$w(x_i, x^*) = \frac{\sum_{i=1}^{n} x_i x^*}{\sum_{i=1}^{n} x_i^2}$$

This is a linear smoother in the sense that all x^* points have their corresponding $y^* = \hat{f}(x^*)$ estimates 'smoothed' to the regression line represented by intercept 0, slope $\hat{\beta}$.

This is a different behavior than the *K-nearest-neighbor* smoothing. KNN smoothing is not fitting a line which is constructed by using all of the points. KNN smoothing is calculating each new y^* as the straight average of the closest K points y_i .

Part B

A kernel function K(x) is a smooth function satisfying

$$\int_{\mathbb{R}} K(x)dx = 1 , \quad \int_{\mathbb{R}} xK(x)dx = 0 , \quad \int_{\mathbb{R}} x^2K(x)dx > 0.$$

A very simple example is the uniform kernel,

$$K(x) = \frac{1}{2}I(x)$$
 where $I(x) = \begin{cases} 1, & |x| \le 1 \\ 0, & \text{otherwise}. \end{cases}$

Another common example is the Gaussian kernel:

$$K(x) = \frac{1}{\sqrt{2\pi}}e^{-x^2/2}$$
.

Kernels are used as weighting functions for taking local averages. Specifically, define the weighting function

$$w(x_i, x^*) = \frac{1}{h} K\left(\frac{x_i - x^*}{h}\right),$$

where h is the bandwidth. Using this weighting function in a linear smoother is called kernel regression. (The weighting function gives the unnormalized weights; you should normalize the weights so that they sum to 1.) Write your own R function that will fit a kernel smoother for an arbitrary set of x-y pairs, and arbitrary choice of (positive real) bandwidth h. Set up an R script that will simulate noisy data from some nonlinear function, $y = f(x) + \epsilon$; subtract the sample means from the simulated x and y; and use your function to fit the kernel smoother for some choice of h. Plot the estimated functions for a range of bandwidths large enough to yield noticeable changes in the qualitative behavior of the prediction functions.

See **R Appendix**, **R Functions**. Function is called **linear_smoother**. There are also functions to specify which kernel function the linear smoother should use. These functions are called **K_gaussian** and **K_uniform**.

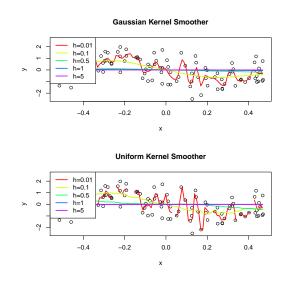


Figure 1: Kernel smoother for varying bandwidths *h*

Cross Validation

Left unanswered so far in our previous study of kernel regression is the question: how does one choose the bandwidth h used for the kernel? Assume for now that the goal is to predict well, not necessarily to recover the truth. (These are related but distinct goals.)

Part A

Presumably a good choice of h would be one that led to smaller predictive errors on fresh data. Write a function or script that will: (1) accept an old ("training") data set and a new ("testing") data set as inputs; (2) fit the kernel-regression estimator to the training data for specified choices of h; and (3) return the estimated functions and the realized prediction error on the testing data for each value of h. This should involve a fairly straightforward "wrapper" of the function you've already written.

See **R** Appendix, **R** Functions. Function is called **tune_h**.

Part B

Imagine a conceptual two-by-two table for the unknown, true state of affairs. The rows of the table are "wiggly function" and "smooth function," and the columns are "highly noisy observations" and "not so noisy observations." Simulate one data set (say, 500 points) for each of the four cells of this table, where the x's take values in the unit interval. Then split each data set into training and testing subsets. You choose the functions. Apply your method to each case, using the testing data to select a bandwidth parameter. Choose the estimate that minimizes the average squared error in prediction, which estimates the mean-squared error:

$$L_n(\hat{f}) = \frac{1}{n} \sum_{i=1}^{n^*} (y_i^* - \hat{y}_i^*)^2$$
,

where (y_i^*, x_i^*) are the points in the test set, and \hat{y}_i^* is your predicted value arising from the model you fit using only the training data. Does your out-of-sample predictive validation method lead to reasonable choices of h for each case?

My function found optimal bandwidths of h as below, using a 70/30 train-test split. My functions were $sin(2\pi x)$ for smooth, and $sin(2\pi x)$ for wiggly.

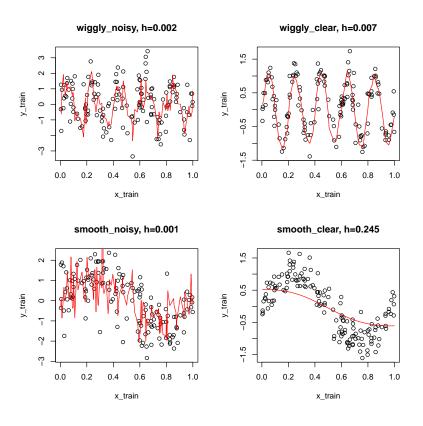


Figure 2: Bandwidth selection for various function types

These bandwidths look generally reasonable in terms of recovering the underlying functions, though the smooth/noisy function's bandwidth was smaller than I anticipated, and looks rather overfitted. My results also varied noticeably in quality as I reran the simulations for various random test/train splits, enough that I would recommend cross-validation each bandwidth selection via a few different test/train splits.

Part C

Splitting a data set into two chunks to choose h by out-of-sample validation has some drawbacks. List at least two. Then consider an alternative: leave-one-out cross validation. Define

LOOCV =
$$\sum_{i=1}^{n} \left(y_i - \hat{y}_i^{(-i)} \right)^2,$$

where $\hat{y}_i^{(-i)}$ is the predicted value of y_i obtained by omitting the ith pair and fitting the model to the reduced data set.

The intuition here is straightforward: for each possible choice of h, you have to predict each data point using all the others. The bandwidth that with the lowest prediction error is the "best" choice by the LOOCV criterion. This is contingent upon a particular bandwidth, and is obviously a function of x_i , but these dependencies are suppressed for notational ease. This looks expensive to compute: for each value of h, and for each data point to be held out, fit a whole nonlinear regression model. But you will derive a shortcut!

Observe that for a linear smoother, we can write the whole vector of fitted values as $\hat{y} = Hy$, where H is called the smoothing matrix (or "hat matrix") and y is the vector of observed outcomes.

Remember that in multiple linear regression this is also true:

$$\hat{y} = X\hat{\beta} = X(X^TX)^{-1}X^Ty = Hy.$$

Write \hat{y}_i in terms of H and y, and show that $\hat{y}_i^{(-i)} = \hat{y}_i - H_{ii}y_i + H_{ii}\hat{y}_i^{(-i)}$. Deduce that, for a linear smoother,

LOOCV =
$$\sum_{i=1}^{n} \left(\frac{y_i - \hat{y}_i}{1 - H_{ii}} \right)^2.$$

Test/Train Split Issues:

A few problems regarding splitting the data into test/train chunks as in previous problem:

- 1. Lose potentially valuable information about outliers or patterns in the data by only using a portion of your data to train the model.
- 2. As mentioned previously, optimal bandwidth selection and the resulting model fit depended on the test/train split.

Plotting of Optimal Bandwidth h:

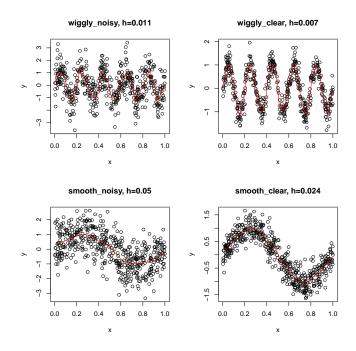


Figure 3: LOOCV Bandwidth selection for various function types

Derivation of H Matrix

Begin with definition of \hat{y} for a single x^* value.

$$\hat{y} = \sum_{i=1}^{n} w(x_i, x^*) y_i$$
 for any value of x^*

Extend to a vector of x^* values, and expression $\hat{y} = Hy$.

$$\begin{bmatrix} \hat{y}_1 \\ \vdots \\ \hat{y}_n \end{bmatrix}_{(nx1)} = \begin{bmatrix} w(x_1, x_1^*) \dots w(x_n, x_1^*) \\ \vdots & \vdots \\ w(x_1, x_p^*) \dots w(x_n, x_p^*) \end{bmatrix}_{(nxp)} \begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix}_{(nx1)}$$

Note that p is the length of the x^* vector, which will be n in the case of LOOCV, since we are using the x values in the existing data set to compute LOOCV prediction error. So H is (nxn).

Must also normalize the weights, so that H = H/rowsums(H). Can formalize this properly as follows.

$$H = \{H_{ij}\} = \frac{w(x_j, x_i^*)}{\sum_{j=1}^n w(x_j, x_i^*)}$$

Accompanying Proof

Goal: Show

$$\hat{y}_i^{(-i)} = \hat{y}_i - H_{ii}y_i + H_{ii}\hat{y}_i^{(-i)}$$

Begin with the following two definitions.

$$\hat{y}_i = H_{ii} y_i \tag{1}$$

$$\hat{y}_i^{(-i)} = \sum_j H_{ij} a_j \tag{2}$$

where we define

$$a_{j} = \begin{cases} y_{i} & \text{if } i \neq j \\ \hat{y}_{i}^{(-i)} & \text{if } i = j \end{cases}$$

We define a_i in this way because we are fixing i, and

$$y^{(-i)} = \begin{bmatrix} y_1 \\ \vdots \\ y_{i-1} \\ y_i^{(-i)} \\ y_{i+1} \\ \vdots \\ y_n \end{bmatrix}$$
, where $y_i^{(-i)}$ is the LOOCV obs calculated using the non-i data.

Then

$$\hat{y}_{i} - \hat{y}_{i}^{(-i)} = \sum_{j} H_{ij} y_{i} - \sum_{j} H_{ij} a_{j}$$

$$= \sum_{j} H_{ij} (y_{i} - a_{j})$$

$$= \begin{cases} \sum_{j} H_{ij} (y_{i} - y_{i}) = 0 & \text{if } i \neq j \\ \sum_{j} H_{ij} (y_{i} - \hat{y}_{i}^{(-i)}) & \text{if } i = j \end{cases}$$

This zeros out all non-diagonal terms, and we have chosen a fixed *i*, so are left with this expression.

$$\hat{y}_i - \hat{y}_i^{(-i)} = H_{ii} \left(y_i - \hat{y}_i^{(-i)} \right)$$

Distribute H_{ii} and rearrange to obtain our goal

$$\hat{y}_i^{(-i)} = \hat{y}_i - H_{ii}y_i + H_{ii}\hat{y}_i^{(-i)}$$

Appendix: R Code

R Functions

```
#SDS 383D - Exercise 3
  #Functions
  #Jennifer Starling
  #Feb 15, 2017
   ### Kernel-Related Functions (Data simulation, linear smoother)
  sim_noisy_data = function(x,f,sig2){
       \#FUNCTION: Simulates noisy data from some nonlinear function f(x).
       #INPUTS:
                x = independent observations.
                  f = function f(x) to simulate from
                  sig2 = variance of the e^{N(0, sig2)} noise.
       #OUTPUTS: x = generated x values.
                   y = generated y = f(x) + e values.
15
      fx = f(x)
      e = rnorm(length(x),0,sqrt(sig2))
       return(y = fx+e)
  }
20
  linear_smoother = function(x,y,x_star,h=1,K){
       #FUNCTION: Linear smoothing function for kernel regression.
       #INPUTS:
                x = a scalar or vector of regression covariates.
                  x_star = scalar or vector of new x values for prediction.
                  h = a positive bandwidth.
                  K = a kernel function. Default is set to Gaussian kernel.
       #OUTPUT:
                  yhat = a scalar or vector of smoothed x values.
      yhat=0 #Initialize yhat.
       for (i in 1:length(x_star)){
          w = (1/h) * K((x-x_star[i])/h) #Calculates weights.
          w = w / sum(w)
                                           #Normalize weights.
          yhat[i] = crossprod(w,y)
35
      return(yhat)
  ### Kernel Functions
  K_uniform = function(x){
      #FUNCTION: Uniform kernel.
       #INPUTS:
                  x = a scalar or vector of values.
                  k = a scalar or vector of smoothed x values.
      k = .5 * ifelse(abs(x) \le 1, rep(1, length(x)), rep(0, length(x)))
      return(k)
  K_gaussian = function(x){
      #FUNCTION: Gaussian kernel.
       #INPUTS:
                 x = a scalar or vector of values.
```

```
k = a scalar or vector of smoothed x values.
55
       k = (1/sqrt(2*pi)) * exp(-x^2/2)
       return(k)
   ### Cross-Validation Functions (tuning bandwidth)
   tune_h = function(test, train, K, h){
       #FUNCTION: Function to tune bandwidth h for
                       specified test/train data sets and
                       specified kernel K.
       #INPUTS:
                   test = a test data set. Must have two cols, x and y.
                   train = a training data set. Must have two cols, x and y.
                   K = the kernel function
70
                   h = a scalar or vector of bandwidths to try.
       #OUTPUTS:
                   pred_err_test = prediction error for testing data for each h.
                   fhat_test = predicted values for testing data's x vals.
       #Extract training and test x and y vectors.
       x = train[,1]
       y = train[,2]
       x_star = test[,1]
       y_star = test[,2]
80
       #Calculate predicted points for test data set, and prediction error.
       fhat_star = linear_smoother(x,y,x_star,h,K)
       #Calculate predicted points for test data set, and prediction error.
       pred_err_test = sum(fhat_star-y_star)^2 / (length(x))
       #Return function outputs:
       return(list(fhat_star=fhat_star, pred_err_test = pred_err_test))
90
   tune_h_loocv = function(x,y,K,h){
       #FUNCTION: Function to use leave on out cross-validation to tune
                       bandwidth h for specified test/train data sets and
                       specified kernel K.
       #INPUTS:
                   x = a scalar or vector; the dependent variable.
                   y = a scalar or vector; the independent var. Same length as x.
                   K = the kernel function
                   h = a scalar or vector of bandwidths to try.
       #OUTPUTS:
                   pred_err_test = prediction error for testing data for each h.
                   fhat_test = predicted values for testing data's x vals.
100
       #Define ppm H, the 'smoothing matrix'.
       \# \{H_{ij}\} = 1/h * K((xi-xj*)/h)
       #For loocv, x=x*, since calculating on single data set instead of test/train.
       Hat = matrix(0, nrow=length(x), ncol=length(x)) #Empty matrix.
       for (i in 1:length(x)){
                                        #Loop through H rows.
           for (j in 1:length(x)){
                                       #Loop through H cols.
               Hat[i,j] = (1/h) * K((x[j] - x[i])/h)
110
           #Normalize weights by dividing H by rowsums(H).
           Hat[i,] = Hat[i,] / sum(Hat[i,])
```

```
#Calculate predicted values.
yhat = Hat %*% y

#Calculate loocv prediction error.
loocv_err = sum(((y-yhat)/(1-diag(Hat)))^2)

#Return function outputs:
return(list(yhat=yhat,loocv_err=loocv_err))
}
```

Part B Script - Curve Fitting by Linear Smoothing

```
#Stats Modeling 2
   #Exercise 3
  #Curve Fitting by Linear Smoothing - Part B
  #Jennifer Starling
  #Feb 15, 2017
   ###
           Simulate noisy data from a non-linear function,
           subtract the sample means from the simulated x and y,
   ###
  ###
           and use the smoother function to fit the kernel smoother
   ###
          for some choice of h. Plot estimated functions for a
          range of bandwidths large enough to yield noticeable changes
   ###
   ###
          in the qualitative behavior of the prediction functions.
   ### Environment setup.
   #Housekeeping.
  rm(list=ls())
   #Load functions.
   source("/Users/jennstarling/UTAustin/2017S_Stats Modeling 2/Exercise-03/R Files/
      SDS383D_Ex3_FUNCTIONS.R")
  ### Data generation.
   \# Simulate x and y from a non-linear function x.
  x = runif(100,0,1) #Generate a sample of x values.
  f = function(x) sin(2*pi*x) #Set the non-linear function.
  #Generate noisy data, and extract x and y.
  y = sim_noisy_data(x, f, sig2=.75)
  #Subtract means from simulated x and y.
  x = x - mean(x)
  y = y - mean(y)
   #Plot noisy data, with means subtracted.
  pdf(file='/Users/jennstarling/UTAustin/2017S_Stats Modeling 2/Exercise-03/Figures/
      noisydata.pdf')
  plot(x,y,main='Noisy data',xlab='x',ylab='y')
  dev.off()
  #Set up a vector of x_star values, and estimate function value at these points.
  x_star = seq(min(x), max(x), by=.01)
  fhat_star = linear_smoother(x,y,x_star,h=.01,K=K_gaussian)
  plot(x,y,main='Gaussian Kernel Smoother')
  lines(x_star, fhat_star, col='red')
   ### Plot linear smoothing output for various bandwidths.
   #Set up bandwidths to try, and corresponding colors.
  H = c(.01,.1,.5,1,5)
55 | col = rainbow(length(H))
```

```
#Open pdf file for two plots.
pdf(file='/Users/jennstarling/UTAustin/2017S_Stats Modeling 2/Exercise-03/Figures/
    Smoothers.pdf')
par(mfrow=c(2,1))
#Plot for a variety of bandwidths using Gaussian kernel.
plot(x,y,main='Gaussian Kernel Smoother')
for (i in 1:length(H)){
    fhat\_star = linear\_smoother(x,y,x\_star,h=H[i],K=K\_gaussian)
    lines(x_star,fhat_star,col=col[i],lwd=2)
legend('topleft',legend=paste("h=",H,sep=''),lwd=2,lty=1,col=col,bg='white')
#Plot for a variety of bandwidths using uniform kernel.
plot(x,y,main='Uniform Kernel Smoother')
for (i in 1:length(H)){
    fhat_star = linear_smoother(x,y,x_star,h=H[i],K=K_uniform)
    lines(x_star,fhat_star,col=col[i],lwd=2)
legend('topleft',legend=paste("h=",H,sep=''),lwd=2,lty=1,col=col,bg='white')
dev.off() #Close pdf file for two plots.
```

Part C Script - Cross Validation

```
#Stats Modeling 2
#Exercise 3
#Cross-Validation - Part B
#Jennifer Starling
#Feb 15, 2017
### CV PART B Script: Imagine a 2x2 tablefor the unknown, true
### state of affairs. Rows are 'wiggly' and 'smooth' functions,
### and cols are 'highly noisy obs' and 'less noisy obs'.
 ### Simulate one data set (n=500) for each of four cells of table.
### Split each data set into test and train sets. Apply method to
### each case. Apply function from part A to select bandwidth.
### Environment setup.
#Housekeeping.
rm(list=ls())
#Load latex table library.
library(xtable) #For table output to latex.
options(xtable.floating = FALSE)
options(xtable.timestamp = "")
#Load functions.
source('/Users/jennstarling/UTAustin/2017S_Stats Modeling 2/Exercise-03/RCode/SDS383D_
    Ex3_FUNCTIONS.R')
### Data and function generation.
#Set up wiggly and less-wiggly functions.
fwiggly = function(x) sin(10*pi*x)
fsmooth = function(x) sin(2*pi*x)
#Set up x values on the unit interval.
n = 500
x = runif(n, 0, 1)
#Generate noisy and less-noisy data for
#each fwiggly and fsmooth function.
y_wiggly_noisy = sim_noisy_data(x,fwiggly,sig2=.75)
y_wiggly_clear = sim_noisy_data(x,fwiggly,sig2=.1)
y_smooth_noisy = sim_noisy_data(x,fsmooth,sig2=.75)
y_smooth_clear = sim_noisy_data(x,fsmooth,sig2=.1)
#Combine into single matrix for convenience.
y = matrix(c(y_wiggly_noisy,y_wiggly_clear,y_smooth_noisy,y_smooth_clear),ncol=4,byrow
colnames(y) = c('wiggly_noisy','wiggly_clear','smooth_noisy','smooth_clear')
#Scatter plots of the four data sets.
pdf(file='/Users/jennstarling/UTAustin/2017S_Stats Modeling 2/Exercise-03/Figures/cv_
    function_grid.pdf')
    par(mfrow=c(2,2))
    for(j in 1:ncol(y)){
         plot(x,y[,j],main=paste(colnames(y)[j]),xlab='x',ylab='y',ylim=c(-5,5))
```

```
}
dev.off()
### Split each data set into train and test sets. (70-30)
test_idx = sample(1:n, size=n*.3, replace=F)
test = cbind(x[test_idx],y[test_idx,])
train = cbind(x[-test_idx],y[-test_idx,])
### Optimize bandwidth h.
# For each case, select a bandwidth parameter. (Used Gaussian kernel.)
h_{opt} = rep(0,4)
                  #Vector to hold optimal h values.
names(h_opt) = colnames(test)[-1]
H = seq(.001,1,by=.001) #Candidate h values.
fx_hat = list()
                        #To hold estimated function values.
x_star = test[,1]
#Iterate through each setup.
for (i in 1:4){
    #Extract x and just the y column required.
    tr = train[,c(1,i+1)]
    te = test[,c(1,i+1)]
    #Temp vector to hold prediction errors.
    temp_pred_err = rep(0,length(H))
    for (j in 1:length(H)){
        h = H[j]
        results = tune_h(test=te,train=tr,K=K_gaussian,h=h)
        temp_pred_err[j] = results$pred_err_test
    h_opt[i] = H[which.min(temp_pred_err)]
    fx_hat[[i]] = tune_h(te,tr,K=K_gaussian,h_opt[i])$fhat_star
}
### Output results as table and plot.
#Format optimal h results as matrix.
h_opt_mat = matrix(h_opt, nrow=2, byrow=T)
colnames(h_opt_mat) = c('noisy','clear')
rownames(h_opt_mat) = c('wiggly','smooth')
xtable(h_opt_mat, digits=3) #Output latex table.
#Plot output with fitted data using optimal h values.
#pdf('/Users/jennstarling/UTAustin/2017S_Stats Modeling 2/Exercise-03/Figures/
   Bandwidth_selection.pdf')
par(mfrow=c(2,2))
for (i in 1:4){
    \#Scatterplot\ of\ test\ x/y.
    plot(test[,1],test[,i+1],
        main=paste(names(h_opt)[i], ", h=",h_opt[i],sep=''),
        xlab='x_train',ylab='y_train')
    #Overlay estimated fit.
    idx = sort(x_star, index.return = T)$ix
```

```
lines(sort(x_star),fx_hat[[i]][idx],col='red') #Fitted line.
   #dev.off()
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   ### CV PART C Script: Find optimal bandwidths h for each
   ### combination of wiggly/smooth and noisy/clear functions using
   ### LOOCV.
   # For each case, select a bandwidth parameter. (Used Gaussian kernel.)
   h_{opt}loocv = rep(0,4) #Vector to hold optimal h values.
   names(h_opt_loocv) = colnames(y)
   H = seq(.001, 1, by=.001) #Candidate h values.
   fx_hat_loocv = list()
                                    #To hold estimated function values.
   #Iterate through each setup.
   for (i in 1:4){
       #Extract y column.
       ytemp = y[,i]
       #Temp vector to hold prediction errors.
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       temp_pred_err = rep(0,length(H))
       for (j in 1:length(H)){
           h = H[j]
           results = tune_h_loocv(x=x,y=ytemp,K=K_gaussian,h=h)
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           temp_pred_err[j] = results$loocv_err
       h_opt_loocv[i] = H[which.min(temp_pred_err)]
       fx_hat_loocv[[i]] = tune_h_loocv(x,ytemp,K=K_gaussian,h_opt_loocv[i])$yhat
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   #Sanity check
   cbind(y[,4],fx_hat_loocv[[4]])
   ### Output results as table and plot.
   #Format optimal h results as matrix.
   h_opt_mat_loocv = matrix(h_opt_loocv,nrow=2,byrow=T)
   colnames(h_opt_mat_loocv) = c('noisy','clear')
   rownames(h_opt_mat_loocv) = c('wiggly','smooth')
   xtable(h_opt_mat_loocv, digits=3) #Output latex table.
   #Plot output with fitted data using optimal h values.
   pdf('/Users/jennstarling/UTAustin/2017S_Stats Modeling 2/Exercise-03/Figures/Bandwidth
       _selection_loocv.pdf')
   par(mfrow=c(2,2))
   for (i in 1:4){
       \#Scatterplot\ of\ test\ x/y.
       plot(x,y[,i],
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           main=paste(names(h_opt_loocv)[i],", h=",h_opt_loocv[i],sep=''),
           xlab='x',ylab='y')
       #Overlay estimated fit.
       idx = sort(x, index.return = T)$ix
       lines(sort(x),fx_hat_loocv[[i]][idx],col='red') #Fitted line.
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```

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```
}
dev.off()
```