# Adaptive Simplicial Interpolation

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based on

Johannes Brumm and Michael Grill (2014), Computing Equilibria in Dynamic Models with Occasionally Binding Constraints, Journal of Economic Dynamics and Control, Volume 38, 142-160, January 2014



#### Motivation

A global solution method for dynamic general equilibrium models with

- occasionally binding constraints,
- several continuous state variables.
- ⇒ Computational challenge: Kinks in policy functions

Main components of the algorithm:

- Adaptive grid scheme to add interpolation nodes at kinks
- Flexible interpolation technique based on Simplicial Interpolation
- ⇒ Called Adaptive Simplicial Interpolation (ASI).



# Main Findings

### The major advantage of ASI is that

- kinks are matched accurately, thus
- less grid points are needed for a good fit, and
- computation time is reduced up to 200 times compared to equidistant grids.

#### Furthermore,

- ASI is very stable
- and is applicable to n-dimensional state spaces.

## Overview

- Introduction
- Adaptive Simplicial Interpolation
- ASI and Time Iteration
- Endogenous Collateral Constraints
- Conclusion

# Adaptive Simplicial Interpolation

We explain ASI using a simple 2-period endowment economy:

- Three agents receive stochastic endowments in periods 1 and 2.
- In period 1, agents trade in a one period bond subject to ad hoc borrowing limits.
- We are interested in how policies of period 1 depend on the wealth distribution.
- We show how kinks induced by borrowing limits are identified by ASI.

**Endogenous Collateral Constraints** 

# 2-Period Bond Economy

#### Individual Problem:

Each agent chooses consumption  $c_1$  and bond holding  $b_1$  to solve

$$\max_{c_1,b_1} \frac{c_1^{1-\gamma}}{1-\gamma} + \beta \mathbb{E}\left[\frac{c_2^{1-\gamma}}{1-\gamma}\right]$$

s.t. the budget constraint

$$b_0 + e_1(x_1) = p_1b_1 + c_1, \quad b_1 + e_2(x_2) = c_2$$

and the borrowing limit

$$b_1 \geq b$$
 with  $b \in \mathbb{R}^-$ ,

where  $x_1, x_2 \in X = \{1, ..., K\}$  are realizations of random shocks.

#### State Space:

$$\mathcal{S} = X \times Y, \text{ where } Y \equiv \left\{ (b_0^1, b_0^2) \in [\underline{b}, -2\underline{b}]^2 \left| \sum_{i=1}^2 b_0^i \in [\underline{b}, -2\underline{b}] \right. \right\}.$$

Introduction

#### Equilibrium Problem:

Given state  $s = (x_1, b_0^1, b_0^2)$ ,

find policies and prices  $f(s) = (\{c_1^h, b_1^h\}_{h=1,2,3}, p_1)$  that satisfy

$$\begin{split} &\sum_{h \in \{1,2,3\}} b_1^h = 0, \\ &c_1^h + b_1^h p_1 - e_1^h - b_0^h = 0 \ \forall h \in \{1,2,3\}, \\ &- u'(c_t^h) p_1 + \mu^h + \mathbb{E}\left[\beta u'(e_2^h + b_1^h)\right] = 0 \ \forall h \in \{1,2,3\}, \\ &0 \leq b_1^h - \underline{b} \perp \mu^h \geq 0 \ \forall h \in \{1,2,3\}. \end{split}$$

#### Parametric Equilibrium Problem:

Find a policy function  $f: S \to \mathbb{R}^7$ 

s.t. for all  $s \in S$ , f(s) solves the equilibrium problem.

## Overview of ASI

Introduction

#### Adaptive Simplicial Interpolation:

- Initialization: Start with an initial grid  $G_{init}$  and solve for  $\{f(g)\}_{g \in G_{init}}$ .
- **3** Grid Adaptation: Use the information  $\{f(g)\}_{g \in G_{init}}$  to solve jointly for adapted points  $G_{adapt}$  that lie on the kinks and for the solutions  $\{f(k)\}_{k \in G_{adapt}}$  at these points.
- Simplicial Interpolation:
   Interpolate f on G = G<sub>init</sub> ∪ G<sub>adapt</sub>.
   To interpolate on such an irregular grid, use Delaunay interpolation.

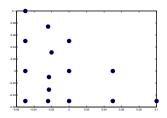
# Delaunay Interpolation

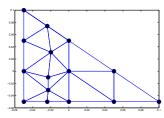
Introduction

Delaunay Interpolation consists of two steps:

### 1. Delaunay triangulation:

Covers an arbitrary set of grid points with triangles:





- Maximizes the minimal angle within the triangulation:
  - ⇒ Desirable for Interpolation.
- Popular in many areas, e.g. engineering:
  - ⇒ Code for n dimensions available.

#### 2. Simplicial interpolation:

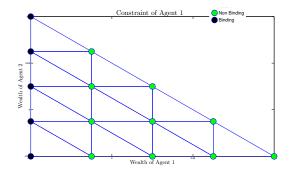
On each triangle, interpolate linearly between the corners.



# Grid Adaptation 1: How to Detect Kinks

For each constraint do the following:

- From the solutions on the initial grid, observe where the constraint is binding or non-binding.
- Consider each edge of the triangulation and check whether the constraint changes from binding to non-binding
- If yes, put an adapted point on the edge.





# Grid Adaptation 2: How to Put Points Precisely on the Kink

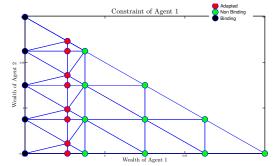
## Note: The Kink is where the constraint is just binding!

To search on an edge for the point that lies exactly on the kink, solve a modified version of the equilibrium problem:

Let the state variable vary on the edge;

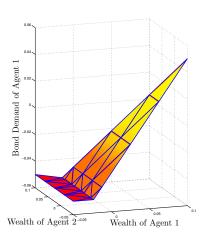
Introduction

- fix the Lagrange multiplier associated with the kink at zero:  $\mu^h = 0$ ;
- and force the associated inequality constraint to be binding:  $b^h = \underline{b}$ .

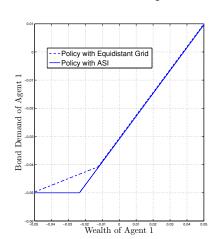


# A Policy Function

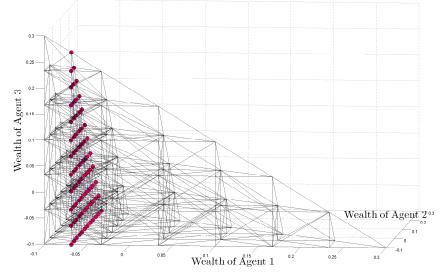
## Bond demand of Agent 1:



#### Cut at Zero Wealth of Agent 2:



# Adapted Grid with 3 Continuous State Variables





## Overview

Introduction

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- 3 ASI and Time Iteration
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Conclusion

**Endogenous Collateral Constraints** 

## ASI and Time Iteration

Introduction

We consider the Bond economy with infinite horizon: Given next period's policy function  $f^{next} = (\{c_{t+1}^h, b_{t+1}^h\}, p_{t+1}),$ the Period-to-Period Equilibrium Problem has the same structure as in the 2-period economy (Details).



We may solve this model using a time iteration algorithm, and use ASI for each time iteration step.

## The Algorithm

Introduction

## Time Iteration with Adaptive Simplicial Interpolation:

- Select a grid  $G_{init}$ , and a policy function  $f^{start}$ . Set  $f^{next} \equiv f^{start}$ .
- Make one time iteration step using ASI:
  - 1. For all  $g \in G_{init}$ , find f(g) that solves the Period-to-Period Equilibrium Problem given  $f^{next}$ .
  - 2. Use  $\{f(g)\}_{g \in G_{init}}$  to solve for kink points  $k \in G_{adapt}$  and for the respective policies  $\{f(k)\}_{k \in G_{adapt}}$ .
  - 3. Use solutions at all grid points  $G = G_{init} \cup G_{adapt}$  to interpolate f by simplicial interpolation.
  - If  $\|f f^{\text{next}}\|_{\infty} < \epsilon$ , go to step 3. Else set  $f^{\text{next}} \equiv f$  and repeat step 2.
- **3** Set the numerical solution to the infinite horizon problem:  $\tilde{f} = f$ .

## **Euler Error Table**

Introduction

- To check accuracy we calculate relative errors in Euler equations (EEs) as proposed by Judd (1992 JET)
- For each exogenous state we draw 5000 random points and get the following EE-results (in log10-scale) for ASI:

	grid points	max EE	average EE	age EE   time (min)	
3 agents	40	-3.0	-4.1	0.5	
4 agents	112	-2.7	-3.3	4.5	

Using equidistant grids we try to match the maximum EE:

	grid points	max EE	average EE	time (min)
3 agents	20301	-2.8	-5.3	79
4 agents	20825	-2.0	-3.6	895

 Hence, with respect to the max EE, the adaptive grid needs up to 500 times less points for the same accuracy!



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Conclusion

# **Endogenous Collateral Constraints**

We extend the above model by including the following features:

- Additional asset: Lucas tree in unit net supply paying a fixed fraction of aggregate endowment as dividends.
- Short selling constraints on the Lucas Tree.
- Endogenous collateral constraints: Short positions in the bond need to be collateralized by stock holdings.

## Details Endogenous Collateral Constraints

#### Individual Problem:

Introduction

Choose  $c_t$ ,  $b_t$ , and Lucas tree holding,  $l_t$ , to maximize lifetime utility s.t. the *budget constraint* 

$$b_{t-1} + l_{t-1} (q_t + d_t) + e_t = p_t b_t + q_t l_t + c_t,$$

the short-selling constraint and the collateral constraint

$$l_t \geq 0, \quad -b_t \leq \min_{s_{t+1} > s_t} \left\{ \left( q_{t+1}(s_{t+1}) + d_{t+1}(s_{t+1}) \right) l_t \right\},$$

where the min is over all states that succeed  $s_t$  with positive probability.

#### State Space:

Define wealth  $w_t^h \equiv l_{t-1}^h (q_t + d_t) + b_{t-1}^h$ , and fraction of wealth:  $y_t^h = w_t^h/q_t$ .

$$S = X \times Y, \text{ where } Y \equiv \left\{ \left(y_t^1,...,y_t^{H-1}\right) \in \mathbb{R}_+^{H-1} \left| \sum_{i=1}^{H-1} y^i \leq 1 \right. \right\}.$$

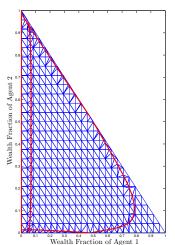
Parametrization: Like Bond economy, but  $\alpha = 0.1$ .



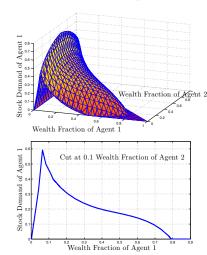
Conclusion

## Grid and Stock Demand

### Adapted Grid with 5 Kinks:



#### Stock Demand of Agent 1:



## **Euler Error Table**

 For each exogeneous state we draw 5000 random points and get the following EE-results (in log10-scale) for ASI:

$\alpha$	grid points	max EE	average EE	time (min)
0.1	1235	-2.5	-3.7	310

Using equidistant grids we try to match the maximum EE:

$\alpha$	grid points	max EE	average EE	time (min)
0.1	25400	-2.4	-4.0	4500

- Hence, with respect to the max EE, the adaptive grid needs at least 20 times less points for the same accuracy
- We improved this performance further by adapting the grid to non-linearities.



### Conclusion

- We develop ASI, an algorithm that solves dynamic models with occasionally binding constraints and several continuous state variables.
- ASI uses Delaunay Interpolation, which allows for flexible grids.
- ASI includes an adaptive grid scheme that adjusts precisely to kinks.

# Appendix: Parameterization

 $x_t \in X = \{1, ..., K\}$  follows a Markov process with  $2 \times H$  states:

2 aggregate endowments 
$$\times$$
  $H$  endowment distributions (ahigh/alow =  $\nu_{aaa}$ ) (ihigh/ilow =  $\nu_{idio}$ )

#### Parametrization:

-	γ	$ u_{idio}$	$ u_{agg}$	$ ho_{ ext{idio}}$	$ ho_{agg}$	β	<u>b</u>
1	.5	1.6	1.06	0.9	0.65	0.95	-0.10

BondEcor

Introduction

**Endogenous Collateral Constraints** 

# Infinite Horizon Bond Economy

#### Period-to-Period Equilibrium Problem:

Given next period's policy function  $f^{next} = (\{c_{t+1}^h, b_{t+1}^h\}_{h=1,\dots,H}, p_{t+1})$ , and given state  $s_t = (x_t, b_{t-1}^1, ..., b_{t-1}^{H-1}),$ 

find policies  $f(s_t) = (\{c_t^h, b_t^h\}_{h=1,...H}, p_t)$  that satisfy

$$\begin{split} &\sum_{h=1}^{H} b^h(s) = 0, \\ &c_t^h(s) + b_t^h(s) p_t(s) - e_t^h(s) - b_{t-1}^h(s) = 0, \ \forall h \in \{1, ..., H\}, \\ &- u'(c_t^h(s)) p_t(s) + \mu_t^h(s) + \mathbb{E}\left[\beta u'\left(c_{t+1}^h\left(s_{t+1}\right)\right)\right] = 0, \ \forall h \in \{1, ..., H\}, \\ &0 \leq b_t^h(s) - \underline{b} \perp \mu_t^h(s) \geq 0, \ \forall h \in \{1, ..., H\}, \end{split}$$