view\_frames Result Recorded at time: 41.084 Broadcaster: /map\_ekf Average rate: 60.196 Hz Most recent transform: 41.061 (0.023 sec old) Buffer length: 4.801 sec odom Broadcaster: /odom\_ekf Average rate: 60.196 Hz Most recent transform: 41.061 (0.023 sec old) Buffer length: 4.801 sec base\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 50.208 Hz Average rate: 50.208 Hz Average rate: 50.208 Hz Average rate: 50.208 Hz Most recent transform: 41.073 (0.011 sec old) Buffer length: 4.800 sec Buffer length: 4.800 sec Buffer length: 4.800 sec Buffer length: 4.800 sec left\_back\_wheel left\_front\_wheel right\_back\_wheel right\_front\_wheel Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (41.084 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec left\_back\_wheel1 right\_back\_wheel1 left\_front\_wheel1 right\_front\_wheel1