

Learn++

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Overview

- Introduction
- Implementation detail
- Evaluation
- Conclusion

1.

Introduction

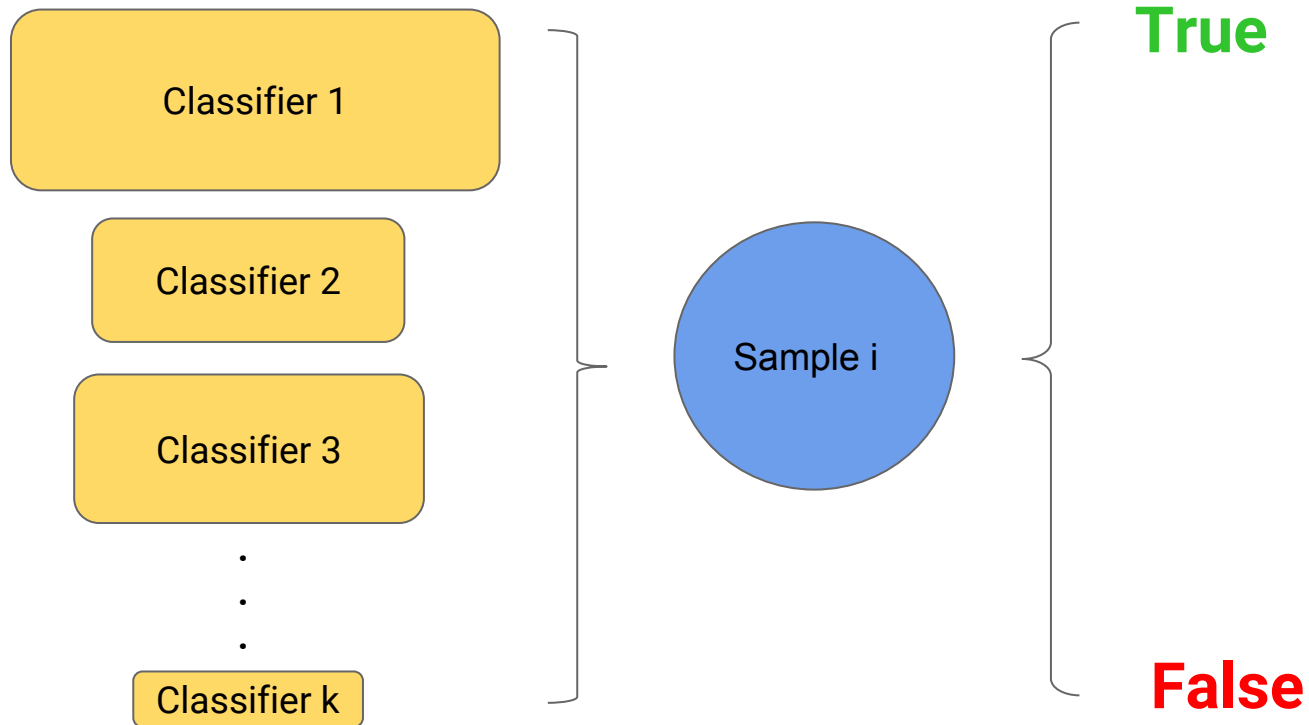


Learn additional information

No need for old data

Preserve previously acquired
knowledge

Incremental learning



Data set

Sample 3

Sample i

Sample 156

...

Sample 55

Sample 77

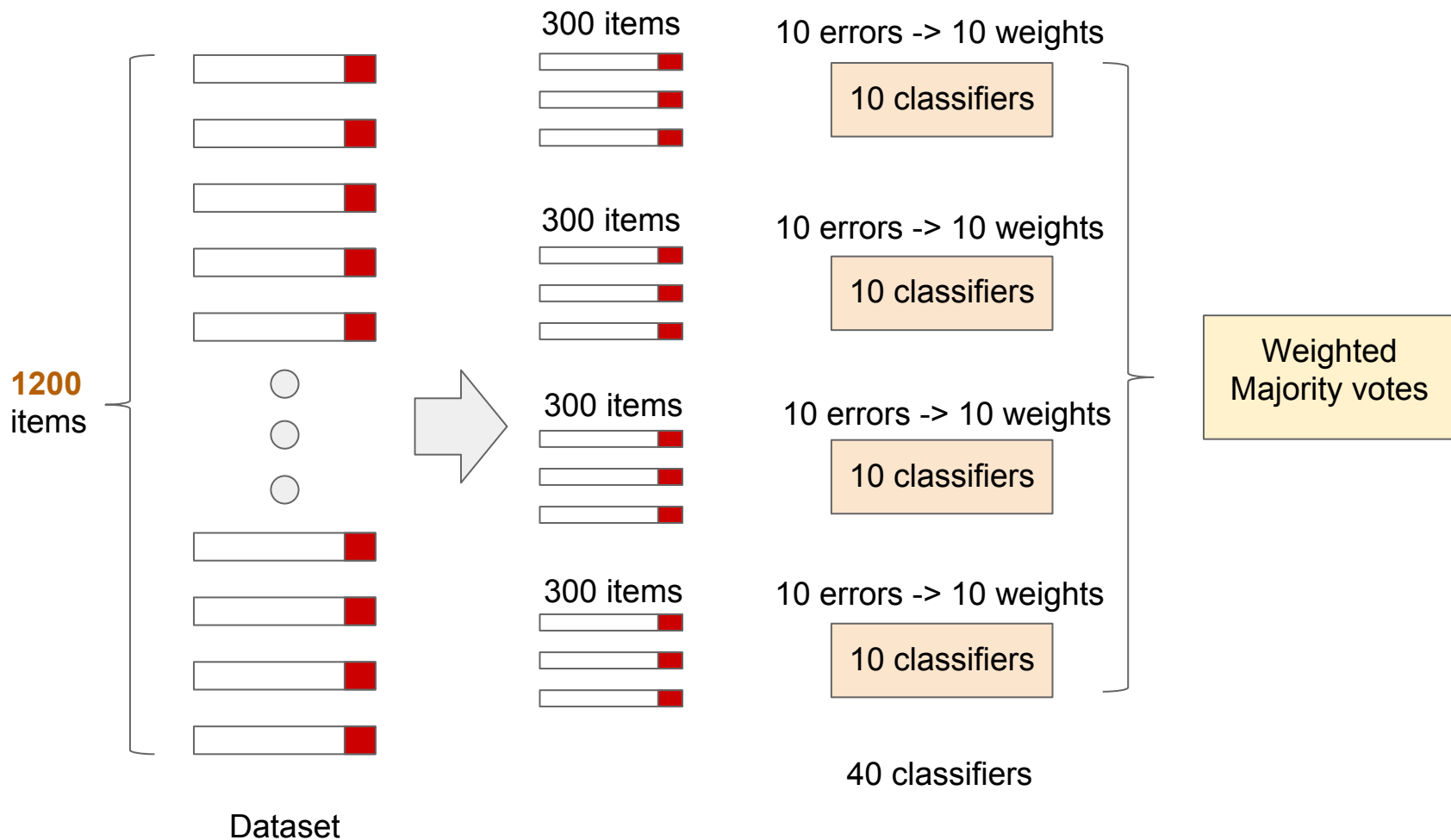
Sample i

Sample i

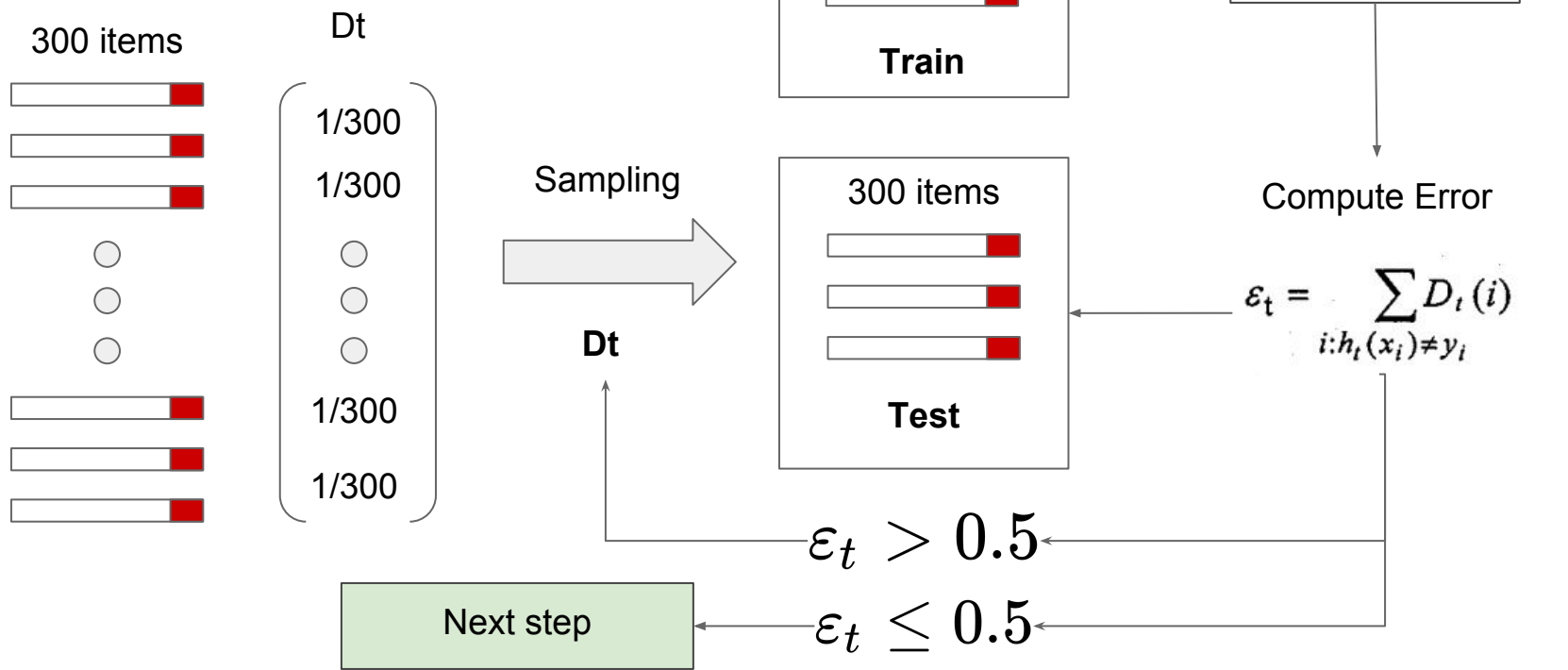
...

Sample i

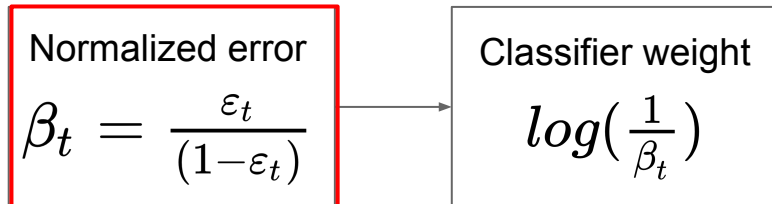
Implementation details



Step 1



Step 2



E.g. Iteration 3 ($t = 3$)

Classifier 1

Classifier 2

Classifier 3

$$\log\left(\frac{1}{\beta_1}\right)$$

$$\log\left(\frac{1}{\beta_2}\right)$$

$$\log\left(\frac{1}{\beta_3}\right)$$

Weighted
Majority votes

$$H_3(x)$$

Step 3

Step 1

Save the classifier
and normalized error

$$E_t > 0.5$$

$$E_t \leq 0.5$$

Composite Error

$$E_t = \sum_{i=1}^m D_t(i) [H_t(x_i) \neq y_i]$$

$$H_3(x)$$

Step 3

Composite Error

$$E_t = \sum_{i=1}^m Dt(i)[H_t(x_i) \neq y_i]$$

Normalized
Composite Error

$$B_t = \frac{1}{1-E_t}$$

Update Dt

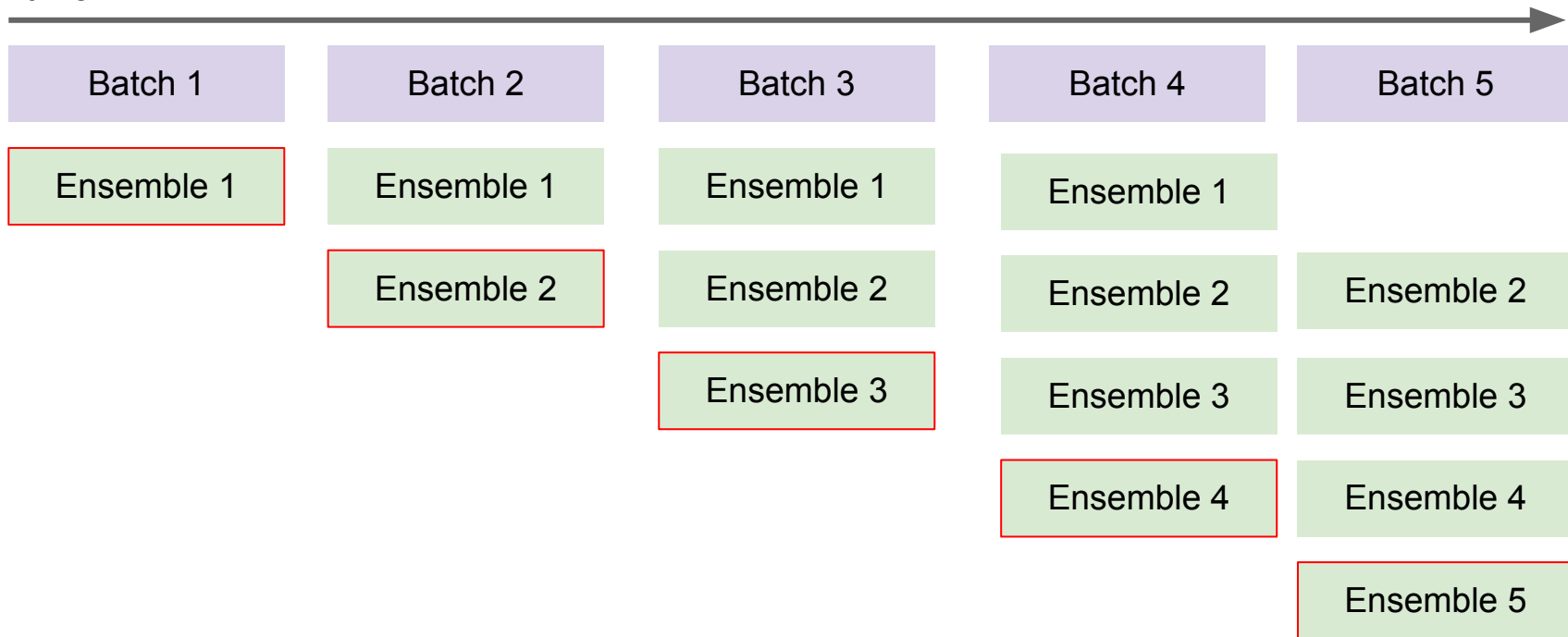
$$Dt = Dt \times \begin{cases} B_t, & \text{if } H_t(x_i) = y_i \\ 1, & \text{otherwise} \end{cases}$$

Next iteration

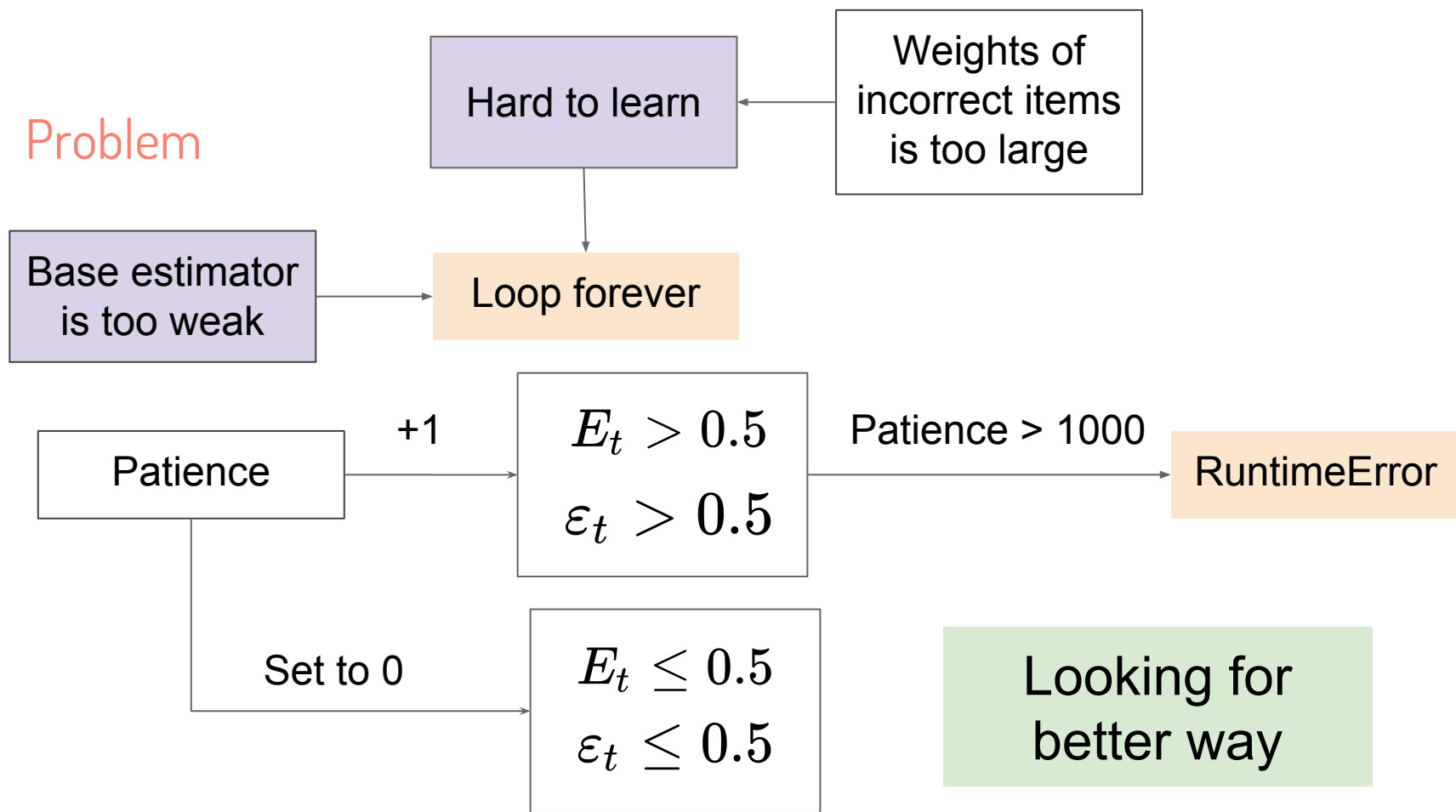
Adapt to data stream

 $N_{\text{ensembles}} = 3$

time



Problem

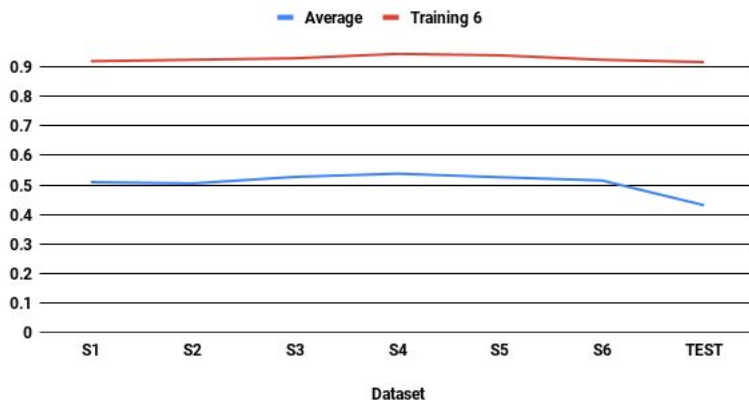


3. Evaluation

Optical digits dataset

Dataset	Average	Training 1	Training 2	Training 3	Training 4	Training 5	Training 6
S1	0.5095	0.915	0.935	0.905	0.905	0.91	0.92
S2	0.5053		0.895	0.915	0.92	0.9	0.925
S3	0.5275			0.925	0.93	0.925	0.93
S4	0.5383				0.945	0.94	0.945
S5	0.5263					0.95	0.94
S6	0.5153						0.925
TEST	0.4313	0.803	0.852	0.867	0.899	0.903	0.917

Accuracy

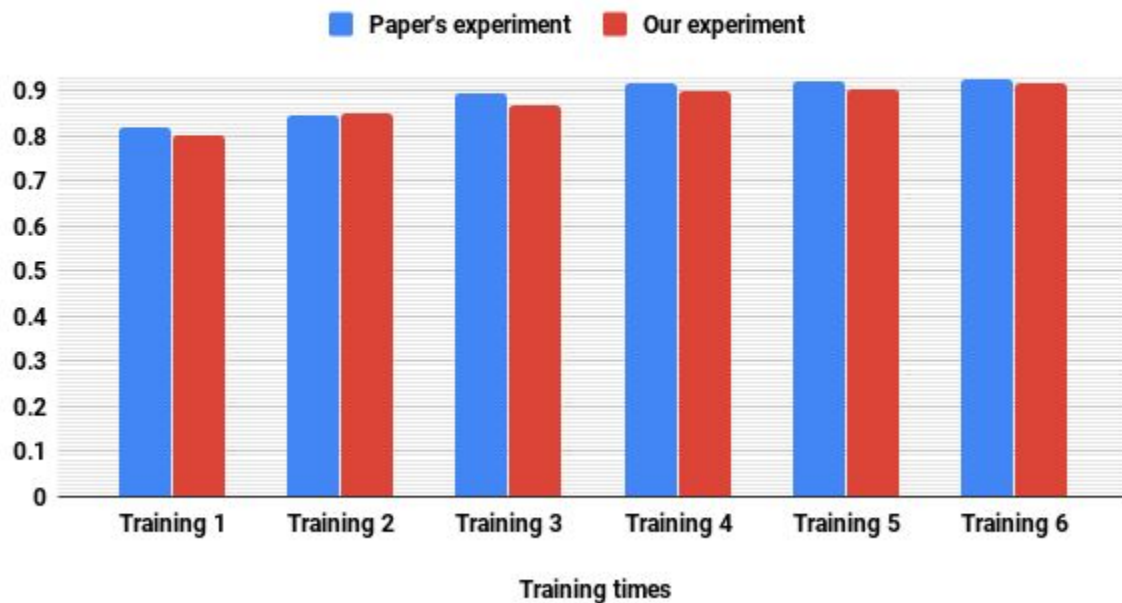


Base Learner: MLP Classifier
hidden_layer_sizes=(30,)
tol=0.1
max_iter=default

Number of estimators: 30

Performance comparison

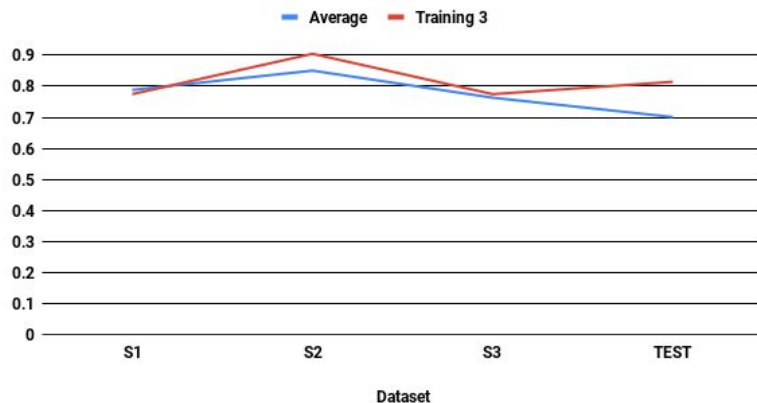
Performance on Optical digits dataset



Vehicle dataset

Dataset	Average	Training 1	Training 2	Training 3
S1	0.7886	0.915	0.795	0.775
S2	0.8509		0.895	0.905
S3	0.7635			0.775
TEST	0.7012	0.8194	0.7731	0.8148

Accuracy

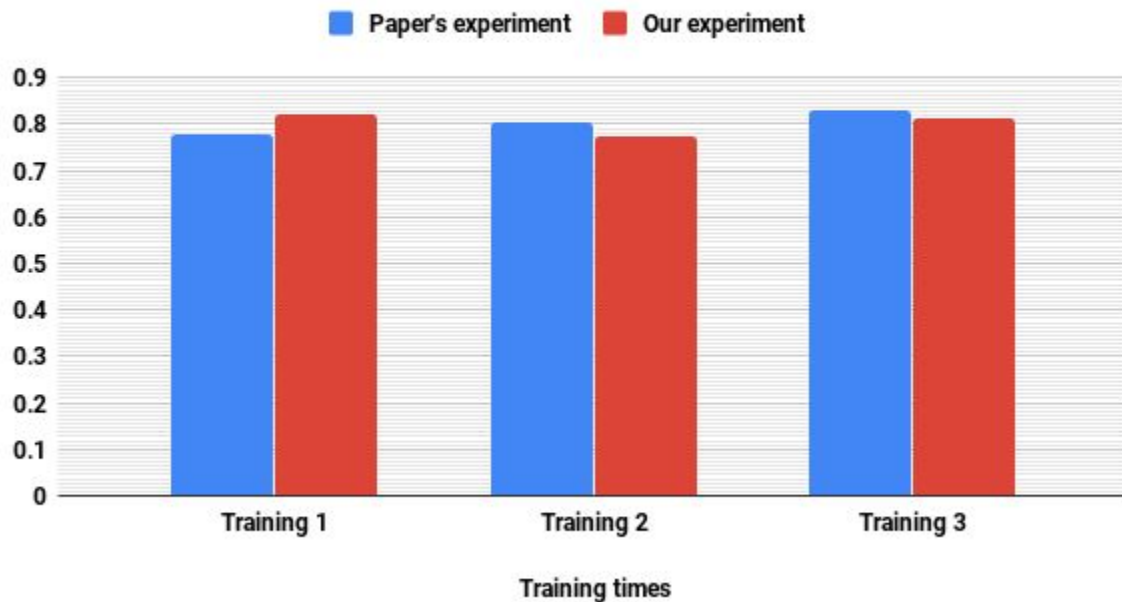


Base Learner: MLPClassifier
hidden_layer_sizes=(100,)
tol=1e-3,
max_iter=500

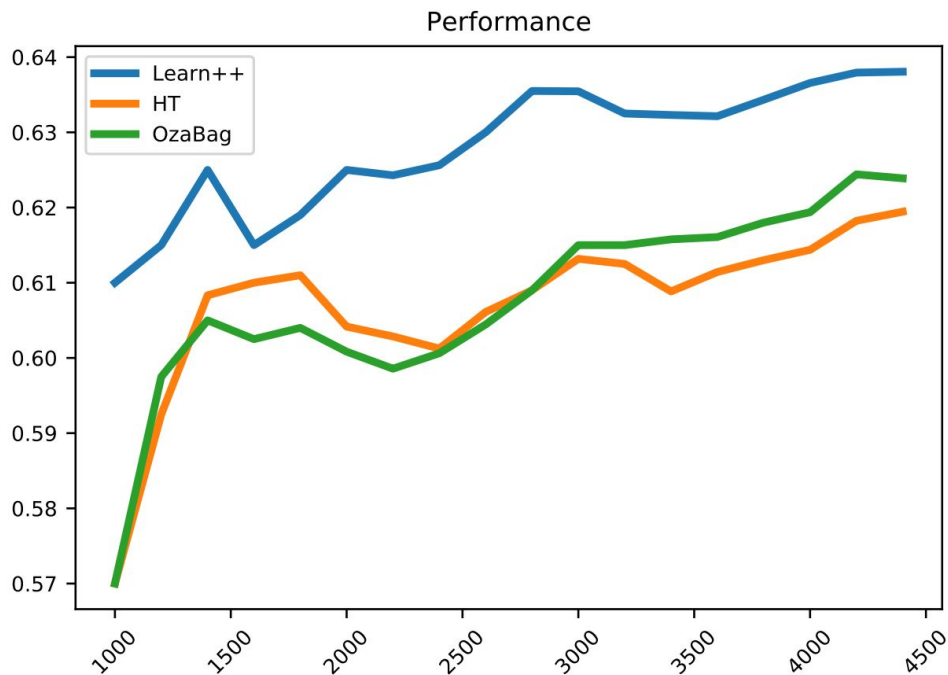
Number of estimators: 30

Performance comparison

Performance on Vehicle dataset



Performance on Data Stream



Configuration:

Learn++: MLP (128 hidden layer)
30 estimator

OzaBagging: Hoeffding Tree
5 estimator

Stream: RandomTreeGenerator

4.

Conclusion

Summary

1. Motivation
2. Explanation of main idea
3. Implementation
4. Evaluation on different dataset

Future work

1. Make more tests with data stream
2. Optimize the codes.
3. Better way to adapt to data stream.
4. Integrate in Scikit Multiflow.