A Numerical Simulation of the Smoluchowski Coagulation Equation

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Abstract

In this report, a simulation on a conservation-law numerical scheme of the Smoluchowski coagulation equation is presented.

Key words: Finite volume method (FVM).

1 Initialization

1.1 Parameter initialization

In order to verify the correctness of the results, main input values are forced to be declared exactly as given by Filbet[1]. More precisely, they are listed in the following table:

Parameter	Concept	${f Value}$
\overline{R}	Truncation size	50
I^h	Mesh size	≥ 125
${ m T}$	Finish time	2
N	Number of time nodes	21
a(x,x')	Coagulation coefficient	$a(x,x') \equiv 1$
$f_0(x)$	Initial value of $f(t,x)$	$f_0(x) = M_0 e^{-M_0 x}, M_0 \in \mathbb{R}_+^*$

Table 1: Parameter initialization

It should be noted in this small project that the chosen mesh is uniform. Hence, a quantity Δx is defined to put the calculation more simply:

$$\Delta x := \Delta x_i \text{ for all } i = 0, 1, ..., I^h - 1.$$
 (1)

Additionally, we would also like to mention that:

$$\Delta t := \frac{T}{N-1},\tag{2}$$

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where N is the number of nodes in the time domain.

1.2 Variable declaration

For any indices $i \in \{0, 1, ..., I^h\}$ and $n \in \{0, 1, ..., N-1\}$, the equality between the equations (12) and (13) both in [1] derives that a matrix $\mathbf{J} \in \mathbb{R}^{(Ih+1)\times N}$ could be declared to save the value of the approximate fluxes J so that:

$$\mathbf{J}_{i,n} := J_{i-1/2}^{h,n}. \tag{3}$$

As a result, for any value n we have:

$$\mathbf{J}_{0,n} := J_{-1/2}^{h,n} \approx J_{nc}^{R}(f)(x_{-1/2}) = \int_{0}^{x_{-1/2}} \{\text{function}\} = \int_{0}^{0} \{\text{function}\} = 0. \quad (4)$$

Similarly, for any indices $i \in \{0,...,I^h-1\}^1$ and $n \in \{0,1,...,N\}$, the equations (11) and (13) both in [1] derive that the matrix $\mathbf{G} \in \mathbb{R}^{Ih \times (N+1)}$ should be used to save the approximation of g(t,x) so that:

$$\mathbf{G}_{i,n} = g_i^n. \tag{5}$$

As a consequence, the values $G_{i,0}$ could be computed from the equation (10) in [1] as followed:

$$\mathbf{G}_{i,0} = g_i^{0,h} = \frac{1}{\Delta x} \int_{x_{i-1/2}}^{x_{i+1/2}} g_0(x) dx.$$
 (6)

Finally, from the equation (11) in [1] and the definition of matrices J and G:

$$\mathbf{G}_{i,n+1} = \mathbf{G}_{i,n} - \frac{\Delta t}{\Delta x} \left(\mathbf{J}_{i+1,n} - \mathbf{J}_{i,n} \right). \tag{7}$$

2 Implementation

2.1 Pseudo-codes

2.1.1 J-G Update

According to the equation (12) in [1], $J_{i+1/2}^{h,n}$ might be seen as a function J of the variables $\{g_i^n: i=0,...,I^h-1\}$. Consequently, from the equations (11) and (12) both in [1], the alternating updates of $\mathbf{J}_{i,n}$ and $\mathbf{G}_{i,n}$ could be described as the Algorithm 1 given below.

The most difficult part of this implementation is definitely to compute $\mathbf{J}_{i,n}$ using the equation (12) in [1]. This could be done by a deep-nested loop which will be shown at the end of this section.

 $^{^{1}}$ The last index $i=I^{h}$ is kindly skipped here, which will be explained afterward.

Algorithm 1: J - G Update

```
Input: I^{h}, \Delta t, \Delta x, \left\{ \mathbf{G}_{i,0} : i = 0, ..., I^{h} - 1 \right\}, \left\{ \mathbf{J}_{0,n} : n = 0, ..., N - 1 \right\}.

Output: Matrices \mathbf{G} and \mathbf{J}.

1 for n = 0 : N - 1

2 for i = 0 : I^{h} - 1

3 Update \mathbf{J}_{i+1,n} \leftarrow J\left( \left\{ \mathbf{G}_{i,0} : i = 0, ..., I^{h} - 1 \right\} \right)

Update \mathbf{G}_{i,n+1} \leftarrow \mathbf{G}_{i,n} - \frac{\Delta t}{\Delta x} \left( \mathbf{J}_{i+1,n} - \mathbf{J}_{i,n} \right)
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For any fixed value i, the finite sequences $\{F1_k\}_{k=0,1,...,i}$ and $\{F2_k\}_{k=0,1,...,i}$ are declared to save the sum-of-integral and the integral in the deepest inner loops. In detail, from the equation (12) in [1] we define:

$$F1_k := \sum_{j=\alpha_{i,k}}^{I^h} \int_{\Lambda_j^h} \frac{a(x', x_k)}{x'} dx' g_j^n,$$
 (8)

$$F2_k := \int_{x_{i+1/2} - x_k}^{x_{\alpha_{i,k}} - 1/2} \frac{a(x', x_k)}{x'} dx' g_{\alpha_{i,k} - 1}^n.$$
(9)

There is a confusion here in Filbet's convention: For the value $j=I^h$, the interval Λ_j^h will be $\Lambda_{I^h}^h = \left[x_{I^h-1/2}, x_{I^h+1/2}\right)$, which is invalid since $x_{I^h-1/2} = R$ is the last x-node in the mesh (0,R). This happened at all the mathematical equations in [1] having the term " $\Lambda_{I^h}^h$ ". Therefore, in the above the author of this report removed all invalid terms whose index $i=I^h$. Fortunately, the implementation (will be given at the end of the report) seems to return the correct simulation as though skipping this term.

The sequence $\{F1_k\}_{k=0,1,\ldots,i}$ is now re-defined as followed:

$$F1_k := \sum_{j=\alpha_{i,k}}^{I^h - 1} \int_{\Lambda_j^h} \frac{a(x', x_k)}{x'} dx' g_j^n.$$
 (10)

Since the mesh is chosen uniformly, it's easy to derive from the dependence $x_{i+1/2}-x_k\in\Lambda^h_{\alpha_{i,k}}$ that:

$$\alpha_{i,k} = i - k + 1. \tag{11}$$

2.1.2 Filbet's numerical scheme

Consequently, an 4-nested loop is in needed to calculate $\mathbf{J}_{i,n}$, which is expressed in the Algorithm 2 below.

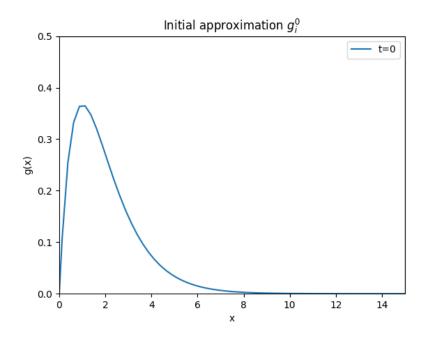
It should be noted that the bolded **0** stands for a vector containing zeros only.

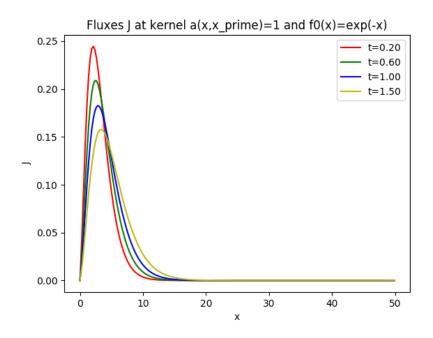
Algorithm 2: Filbet's numerical scheme

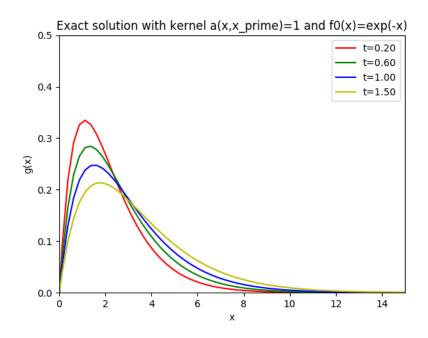
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Input: R, I^h, T, N, a(x, x'), g_0(x) = x f_0(x), \Delta t, \Delta x,
                              \{\mathbf{G}_{i,0}: i=0,...,I^h-1\}, \{\mathbf{J}_{0,n}: n=0,...,N-1\}.
        Output: Matrices G and J.
  1 for n = \overline{0:N-1}
                 for i = \overline{0: I^h - 1}
  2
                           \mathbf{J}_{i+1,n} \leftarrow 0
  3
                           F2 \leftarrow \mathbf{0}
  4
                           F1 \leftarrow \mathbf{0}
  5
                           for k = \overline{0:i}
   6
                            For k = 0: i
F2_k \leftarrow \int_{\frac{x_{i+1/2} - x_k}{x'}}^{x_{\alpha_{i,k}} - 1/2} \frac{a(x', x_k)}{x'} dx' \mathbf{G}_{\alpha_{i,k} - 1, n}
for j = \alpha_{i,k}: I^h - 1
F1_k \leftarrow F1_k + \int_{\Lambda_j^h} \frac{a(x', x_k)}{x'} dx' \mathbf{G}_{j,n}
\mathbf{J}_{i+1,n} \leftarrow \mathbf{J}_{i,n} + \Delta x \cdot \mathbf{G}_{k,n} (F1_k + F2_k)
   8
10
                          \mathbf{G}_{i,n+1} \leftarrow \mathbf{G}_{i,n} - \frac{\Delta t}{\Delta x} \left( \mathbf{J}_{i+1,n} - \mathbf{J}_{i,n} \right)
11
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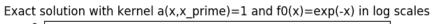
2.2 Results

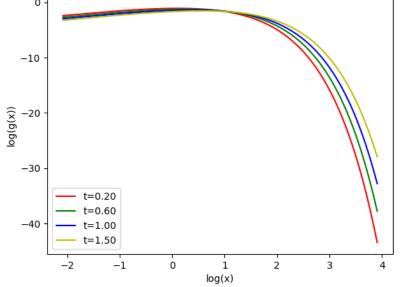
The values of t are chosen as closed as Filbet's [1]. The implementation is performed on a computer with Intel® Core i7-8700 CPU@3.20GHz x 12, RAM 31,3 GB working in Linux operating system. The running time is around 5 minutes in the case that $I^h = 200$ and N = 21. The first, second and third pictures are corresponding to the equations (10), (12) and (11)+(13) in [1], respectively.











3 Conclusion

Comparing to the results by Filbet, the simulation in this report is exactly the same.

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References

[1] FILBET, F., LAURENCOT, P.. Numerical simulation of the Smoluchowski coagulation equation. SIAM J. Sci. Comput., 25, (6), pp. 2004-2028, (2004).