COMP10002 Workshop Week 6

	lec05.pdf : what's there?	
1	Arrays & Pointers Binary Search: Exercise 1 (at the end of lec05.pdf) Quicksort: Exercise 4 (at the end of lec05.pdf)	
2	Main Room: do 7.8 together BreakOut Rooms: do LAB	
LAB	7.3, 7.4, 7.6, 7.7, 7.8, 7.9, 7.10, and 7.11;	
Canvas	 Workshops: Discuss Exercises 1 and 4 at the end of the lec05.pdf slides; then Continue on with the Chapter 7 exercises from last week, you need to be "array-peaking" this week ready to tackle Assignment 1 next week; ASSIGNMENT 1 	

Topics in lec05.pdf

```
Chapter 7 (Part I)
```

Chapter 12 (Part I)

Assertions and correctness

Measuring efficiency

Binary search

Quicksort

Program examples

Exercises

- Arrays:
 - Array function pointer
 - 2D arrays
 - Array Search
 - Linear Search and Correctness (using assertions)
- Defining efficiency with big-O, efficiency of linear search
- Binary Search (in sorted arrays):
 - Algorithm & Correctness
 - Recursive binary search
 - Binary Search Efficiency
 - Note: C convention: function int cmp(data_t
 *x, data_t *y)
- Sorting: Quick Sort (with fe, fg):
 - algorithm
 - partition & analysis
 - picking *pivot*: random is good

array name is a pointer

int A[10], n=0;

Here the name A:

represents the address of the first element of the block of 10 integer cells reserved for the array → A is a pointer

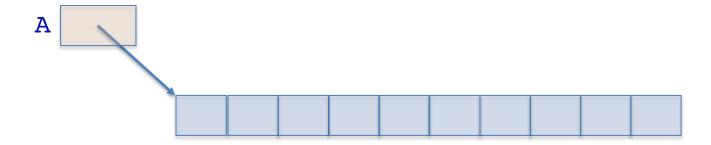


array name is a constant pointer

int
$$A[10]$$
, $B[10]$, $n=0$;

Here the name A:

• represents the address of the first element of the block of 10 integer cells reserved for the array \rightarrow A is a *constant* pointer



- We cannot change A, for example by (wrong) A= &n;, or by A= B;
- but we can change the value at address A, we can change the values in the array.

Chorus: "array names are constant pointers"

With declaration:

```
#define MAX N 1000
int A[MAX N] = \{10, 20, 30\}, n = 3, i = 1;
int *p; // p is a variable pointer
p= A; // p now points to A[0], just like A
```

- now variable p can be used as a substitute for constant A
- $p \Leftrightarrow A$, $p[i] \Leftrightarrow A[i]$ but p++ is valid, while A++ isn't

Array Notation and Pointer Notation "array names are constant pointers"

With declaration:

```
#define MAX_N 1000
int A[MAX_N]= {10, 20, 30}, n= 3, i= 1;
int *p= A;
```

- *A and *p both equivalent to A[0]
- A+1, as well as p+1, points to the next int cell, ie. to A[1]
- *(A+i), as well as *(p+i), is A[i]

```
Check your understanding

1. What is the value of * (A+2)?

2. What will be printed by the loop:
for (i=0, p=A; i<n; i++, p++) {
   printf("%d ", *p);
}
```

Searching in an array: Linear Search Revisited

The Task: searching for x in an array A[] of n elements.

Input: ?

Output: ?

Complexity of linear search: ?

```
Linear Search: search for x in array A of n element
```

algorithm= ???

Searching in an array: Linear Search

The Task: searching for x in an array A[] of n elements.

```
Input: (A, n), x
```

Output:

- index i such that A[i]==x, OR
- NOTFOUND (#define-ed as -1)

Complexity of linear search:

• O(n)

Searching in an array: Binary Search in Sorted Array

The Task: searching for x in a sorted array A[] of n elements.

```
Input: (A, n), x
```

Output:

- index i such that A[i]==x, OR
- NOTFOUND (#define-ed as -1)

Complexity of binary search:

O(?)

Binary Search: Recursive Algorithm

The Task: searching for x in a sorted array A[]

```
Recursive Binary Search: search for x in an array A which is sorted in non-decreasing order

int binSearch(int A[], int n, int x) {
   if (base cases) {
    }
   // general case
```

Exercise 1

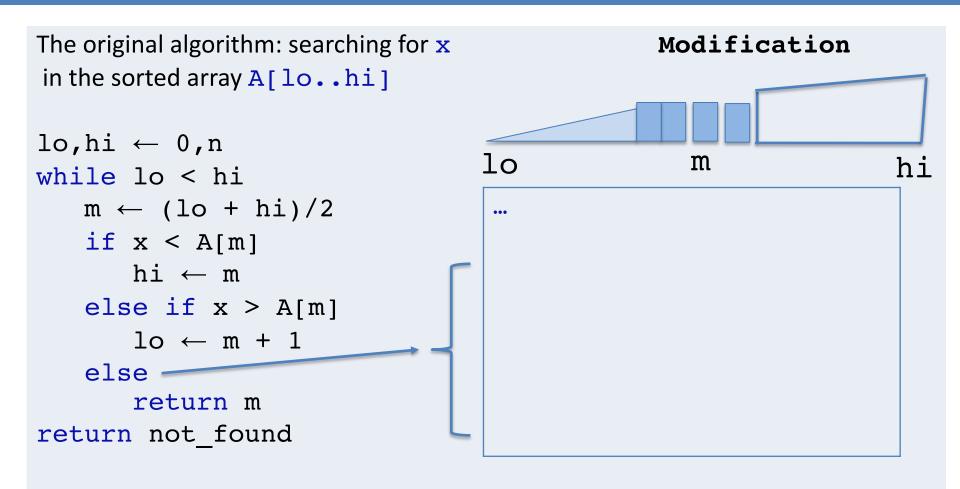
Suppose that the sorted array may contain duplicate items.

Linear search will find the first match.

Modify the binary search algorithm so that it also identifies the first match if there are duplicates.

Modify the demonstration of correctness so that it matches your altered algorithm.

Modifying the following algorithm:



Question: Modify the above binary search algorithm so that it also identifies the first match if there are duplicates.

Correctness: Original → New Version

```
m \leftarrow (lo + hi)/2
assert: P and lo≤m<hi
if x < A[m]
   assert: P and x < A[m . . . n - 1]
   hi \leftarrow m
   assert: P
else if x > A[m]
   assert: P and x > A[0...m]
   lo \leftarrow m + 1
   assert: P
else
   assert: P and x \not < A[m] and x \not > A[m] \Rightarrow x = A[m]
   return m
```

Question: Modify the the above (for binary search algorithm) to fit the new version of returning the first match.

Exercise 4: on the partitioning of the quicksort

A slightly different approach to partition is described by this more relaxed specification:

```
assert: n > 1 and p \in A[0 ... n - 1]
f \leftarrow partition(A, n, p)
assert: 0 < f < n - 1 and
         A[0 . . . f - 1] \le p \text{ and}
         A[f] = p and
         A[f + 1 . . n - 1] \ge p
                     >. unsorted
```

- **4a.** Design a function that meets this specification.
- **4b.** Does this approach have any disadvantages or advantages compared to the first one presented?

Quicksort: The original logic with fe, fg

```
define R \equiv 0 \le fe < fg \le n and A[0 . . . fe - 1] < p and
A[fe...fg-1] = p and A[fg...n-1] > p
if n \le 1
   return
p \leftarrow any element in A[0 . . . n - 1]
assert: n>1 and p\in A[0...n-1]
(fe, fg) \leftarrow partition(A, n, p)
assert: R
quicksort (A[0 \cdot fe - 1])
quicksort (A[fg ... n - 1])
assert: A[0...fe-1]is sorted and A[fg...n-1]is sorted and
R \Rightarrow A[0...n-1] is sorted
```

Exercise 4

A slightly different approach to partition is described by this more relaxed specification:

```
assert: n > 1 and p \in A[0 ... n-1]
f \leftarrow partition(A, n, p)
assert: 0 < f < n-1 and
A[0 ... f-1] \le p and
A[f] = p and
A[f + 1 ... n-1] \ge p
```

- 4a. Design a function that meets this specification.
- **4b.** Does this approach have any disadvantages or advantages compared to the first one presented?

4a. Design a function that meets this specification.

```
assert: n > 1
         f \leftarrow partition(A, n)
         p \leftarrow A[f]
assert: A[f] = p and A[0 . . . f - 1] \le p and
                          A[f + 1 . . n - 1] \ge p
           0 1
                                                    n-1
                                 hi
                   ≤p
                                             ≥p
                           hi lo
                                    (return hi)
                   swap
```

Hoare's Partitionning

```
int partition(int A[], int n) {
   p= ?; lo=?, hi=?
}
```

4b. Does this approach have any disadvantages or advantages compared to the first one presented?

- The first version: partitioning into 3 segments: <p, ==p, and >p
- The new version: Partitioning into 3 segments: <=p, ==p, and
 >=p and the ==p segment has only one element.
- So ???:
 - is there any difference on complexity?
 - is there any difference on simplicity?
 - which one do you prefer?

Lab: Group+Individual Works: Ex 7.7-7.9 and others. Write a function that

- 7.2: [W06] sorts an array in deceasing order
- 7.3: [W06] sorts an array and removes duplicates
- 7.4: [W06] computes frequency of each value in an array

7.6: [W06]			
7.0. [\$\$ \$\$ \$\$	Main Room	Break-out Rooms	
7.7: [W05]			
array A of i	Together with Anh,	Do as many exercises as possible.	
	do (relatively low speed): • exercise 7.8, or	Summon Anh when having	
7.8: [W5X]	 any exercise you want 	questions	
7.9: [W05]	•		
For examp			

7.10: [W5X] returns the number of inversions in Int A[]. For example, the above array has 3 inversions: 2 caused by **15**, and 1 by **21**.

^{***} and all other exercises from W05, W05X, W06, W06X

Wrap-Up

Practice with processing arrays! Know the algorithms:

- Sequential Search
- Binary Search
- Insertion Sort
- Quick Sort

Assignment 1:

- Start early (ASAP)
- Do it incrementally!
- Be active in Discussion Forum
- Ask Questions
- By workshop next week: At least finish the first stage.