COMP20003 Workshop Week 10

- 1 Graphs: concepts
- **2** Graph representation
- **3** DFS (and when to use?)
- 4 BFS & Dijkstra's Algorithm Lab: Implementation pq

Graphs

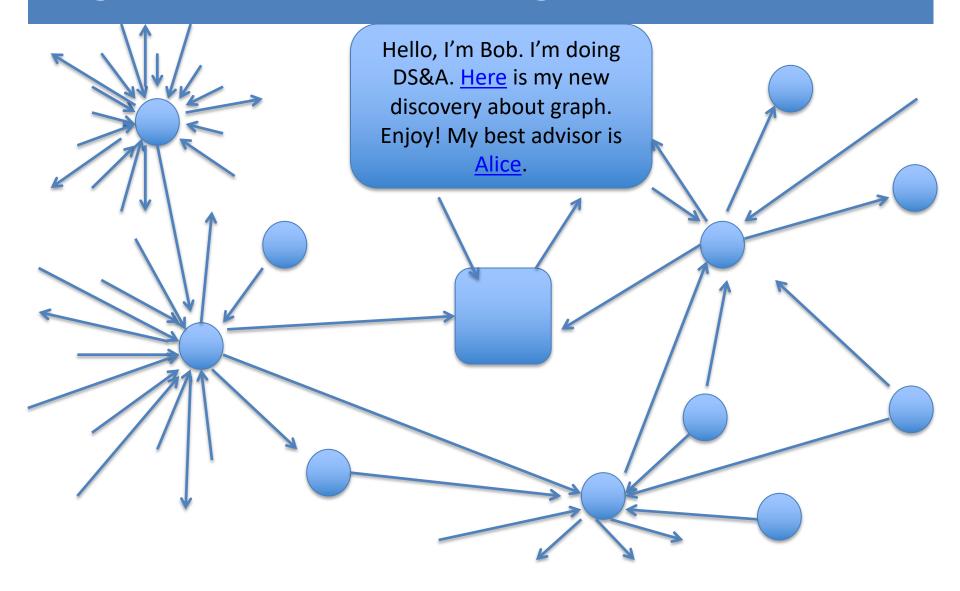


a small graph of covid-19...

An example of the type of graph produced by contact tracing. Each node represents an infected individual, and each line connects two individuals who have been in contact



PageRank: Bob becoming famous!

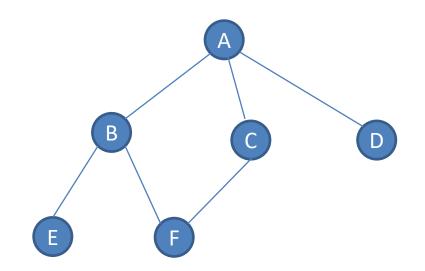


Graphs: Concepts

```
Formal definition: G= (V, E) where \( \nabla = \{\nabla_i\}\) : set of vertices, or nodes \( \text{E=} \{(\nabla_i, \nabla_j) | \nabla_i \in \nabla_j \in \nabla_j\}\) : set of edges, arcs, or links; \( \nabla \) is called the order of the graph \( \nabla \) is called the size of the graph
```

- dense and sparse graphs
- directed, di-graph, undirected,
- cyclic, acyclic, DAG
- connected and unconnected graph, connected component
- weakly and strongly connected components

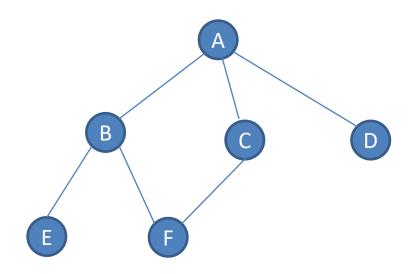
Graph representation: Example for unweighted, undirected graph

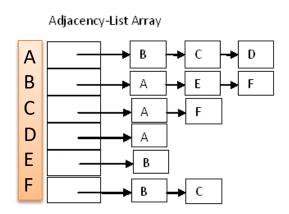


How to represent the graph using:

- Adjacency matrix
- Adjacency lists

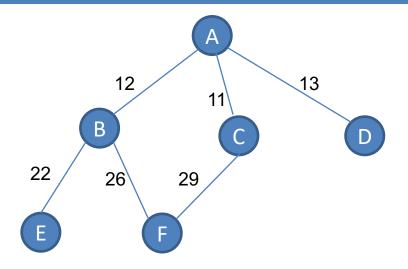
Example for unweighted, undirected graph





	Α	В	С	D	Ε	F
Α	0	1	1	1	0	0
В	1	0	0	0	1	1
С	1	0	0	0	0	1
D	1	0	0	0	0	0
Ε	0	1	0	0	0	0
F	0	1	1	0	0	0

Note: (Weighted) Graph presentation in programs

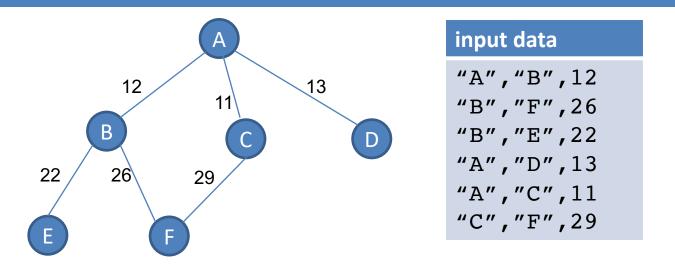


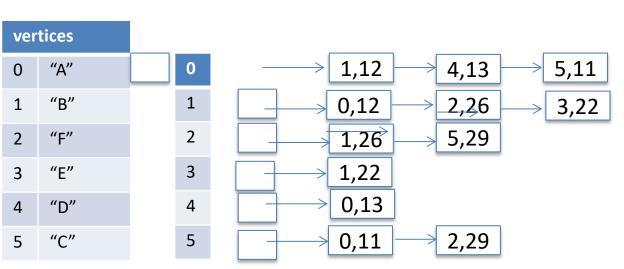
input data

0 "A"
$$[0] \rightarrow (1,12)$$

1 "B" $[1] \rightarrow (0,12), (2,26)$
2 "F" $[2] \rightarrow (1,26)$

(Weighted) Graph presentation in programs





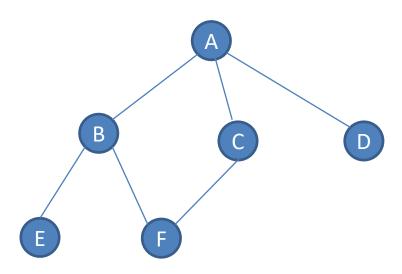
Graphs: Representation

What is a suitable representation method for:

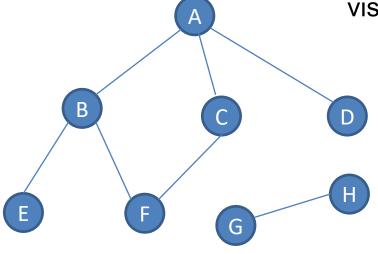
- a graph of this on-line class, where nodes represent students, edge (a,b) means "a knows b",
- a graph of this would-be-face-to-face class, where nodes represent students, edge (a,b) means "a knows b"
- the webgraph?
- social-distancing graph for people in Australia
- road network between major cities in Australia

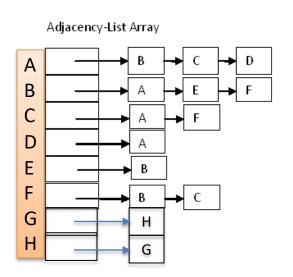
Is each graph directed/undirected, weighted/unweighted, cyclic/acyclic, dense/sparse?

Graph Traversal = What? How?



(Connected) Graph Traversal = How: DFS vs BFS

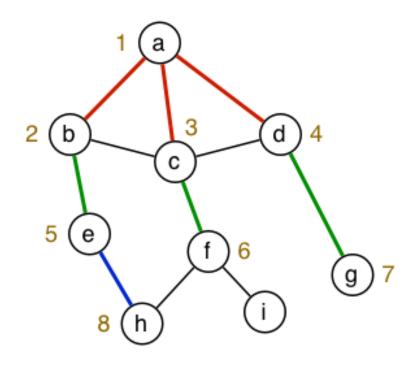




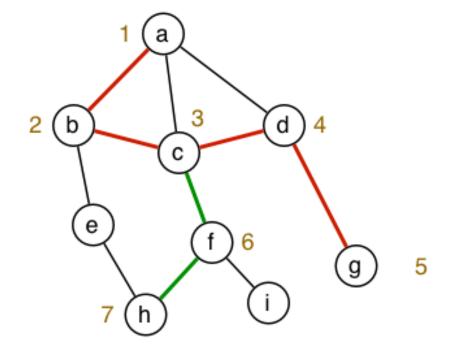
visit each node exactly once, in a systematic way

```
//mark all nodes as "unvisited":
visited[u]= 0 for each u= 0..|V|-1
order= 0; c=0;
for each node u {
  if (!visited(u)) {visit(u); c++;}
function visit(int u) {
  S= empty data structure
  insert u in S
  while (S not empty) {
    u = remove from S
    if (!visited[u]) {
       visited[i]= ++order;
       do job with u;
       insert all neighbours of u to S
```

Graphs: DFS & BFS



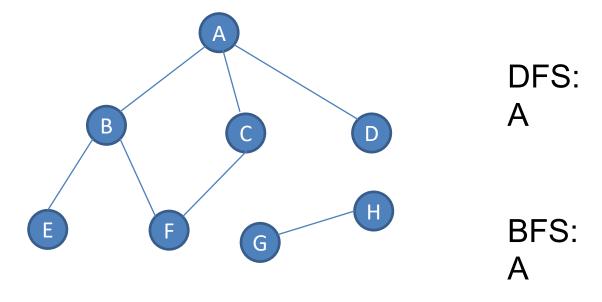
Breadth-first Search



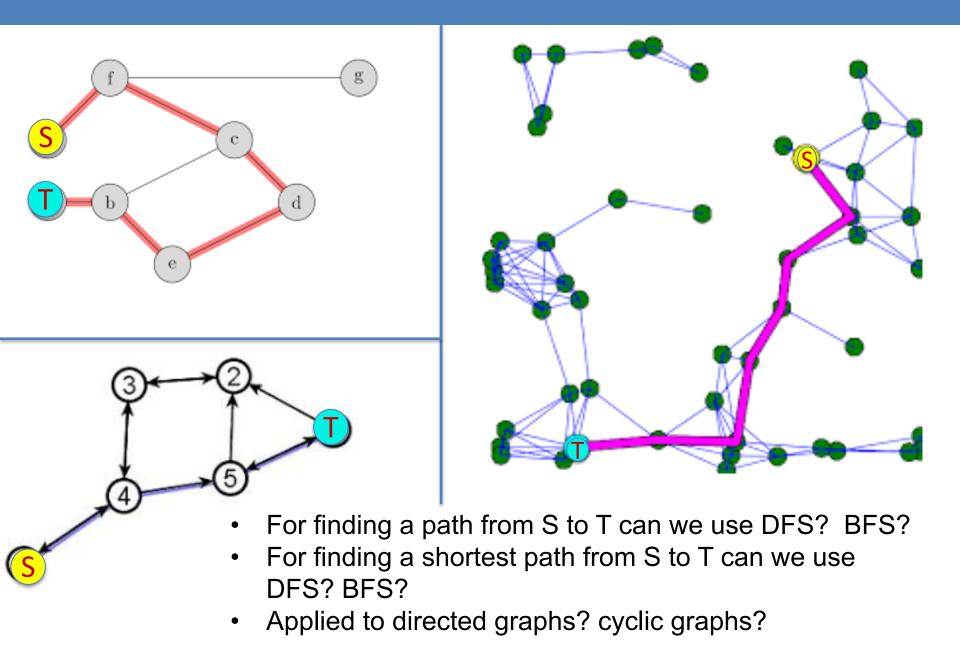
Depth-first Search

Exercise: List nodes in order visited by a)DFS and b)BFS

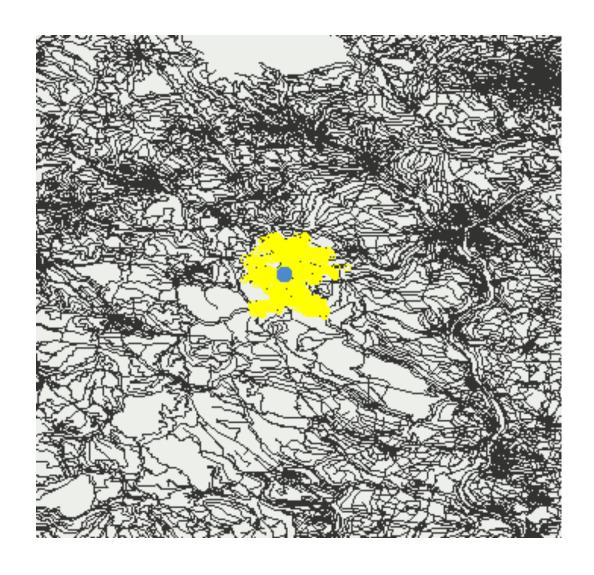
Notes: In exercises, ties should always be broken in alphabetical/ascending order



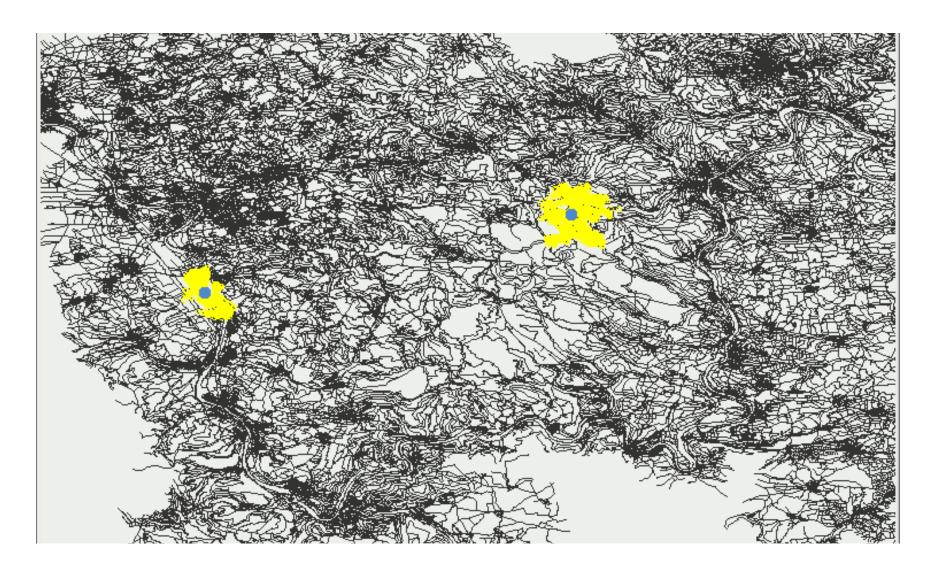
Paths in unweighted graphs: path length, shortest path



for shortest path: use Breath-first Search (BFS)



Breath-first Search (BFS): visit all neighbors first



visitBFS: BFS from a single vertex

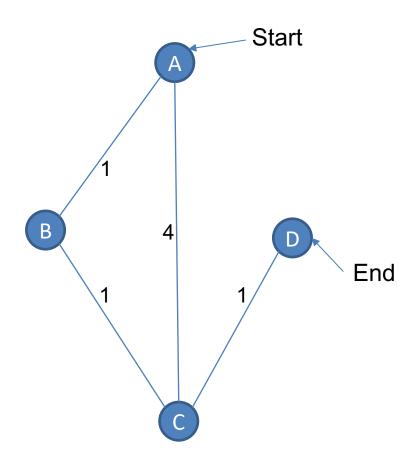
The task:

- Given a weighted graph G=(V,E), and $s\in V$
- In the BFS manner, visit all vertices which are reachable from s.
- supposing visited[] and order have been set

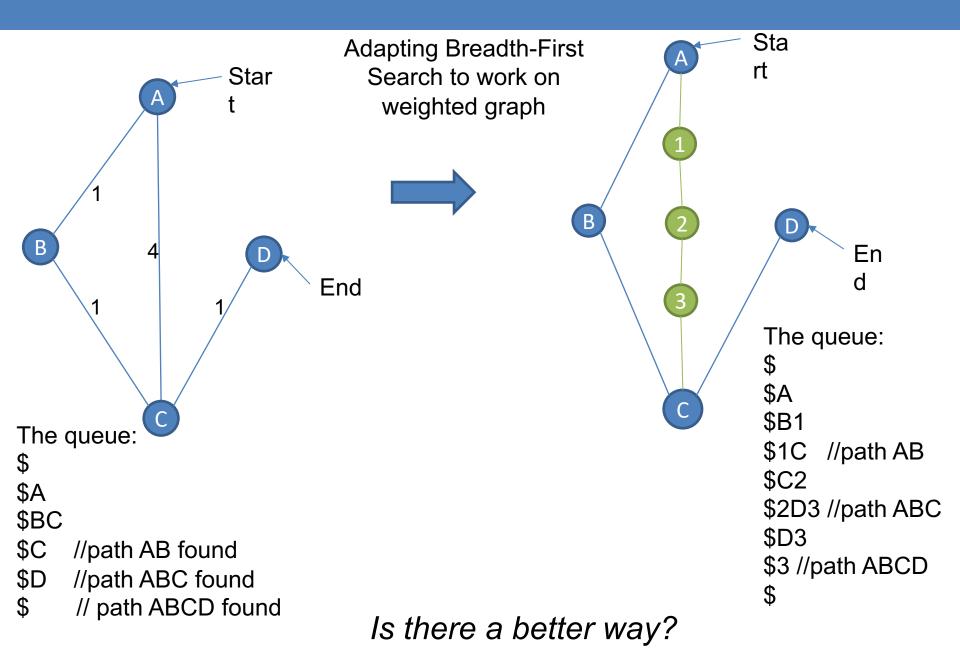
```
The algorithm (using global visited [|V|] = \{0\}, order= 0;)
visitBFS(s) {     // similar to visit(int u) seen before
   Q= makeEmptyQueue()
    enQ(Q,s)
   while (Q is not empty) {
       u = deQ(Q)
       if (!visited[u]) {
          visited[u]= ++order
          visit(u) // performs some operations on vertice x
          for all v that (u, v) \in E: enQ(Q,v)
```

Exercise: Using BFS to find shortest paths in weighted graphs?

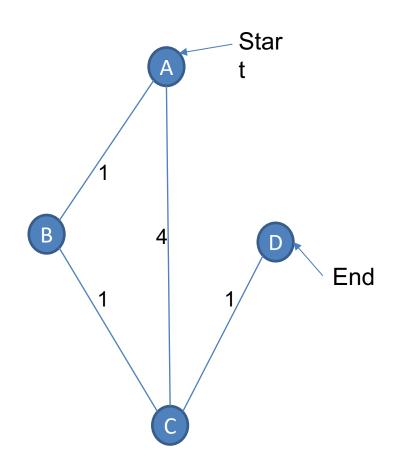
How to use BFS for finding shortest paths in weighted graphs, supposing weights are positive integers?



Exercise...

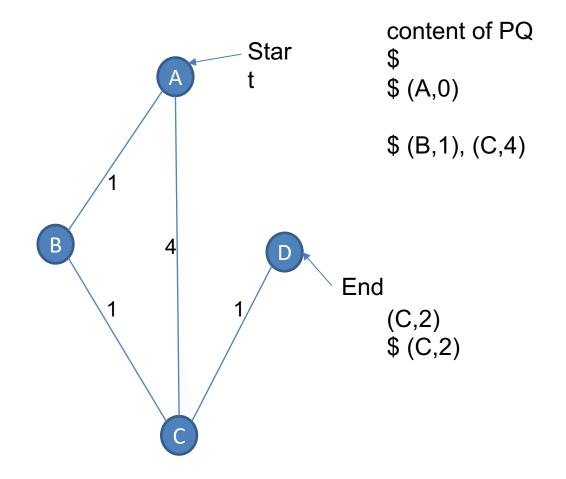


Finding shortest paths using priority queues



```
content of PQ
$ (A,0)
                     insert A with distance A \rightarrow A = 0
(B,1), (C,4) done with BA \rightarrow B:1
```

Finding shortest paths using priority queues



\$ is front of the PQ, PQ is empty now insert A with distance $A \rightarrow A = 0$ done with A, path $A \rightarrow A = 0$

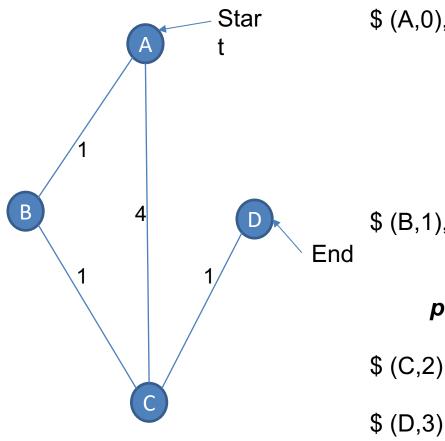
done with B, path $A \rightarrow B = 1$ would insert C with distance= dist(A,B) + dist(B,C) = 2But ... we should replace (C,4) with

→ it would be easier just to populate the PQ with all vertices from the very start

Finding shortest paths using priority queues

\$

Now we put all vertices into the queue at the start. The content of PQ will be:



```
(A,0),(B,\infty),(C,\infty),(D,\infty)
              populate queue with all nodes
              then remove min-dist A
                 Done= \{ (A,0) \}
              and update distance for the
                 neighbours of A
$ (B,1), (C,4), (D,∞)
              remove B that has min dist
                 Done= \{(A,0), (B,1)\}
      prove that : A→B is a shortest from A to B
               update...
$ (C,2), (D,∞)
                 Done= \{(A,0), \{B,1\}, (C,2)\}
```

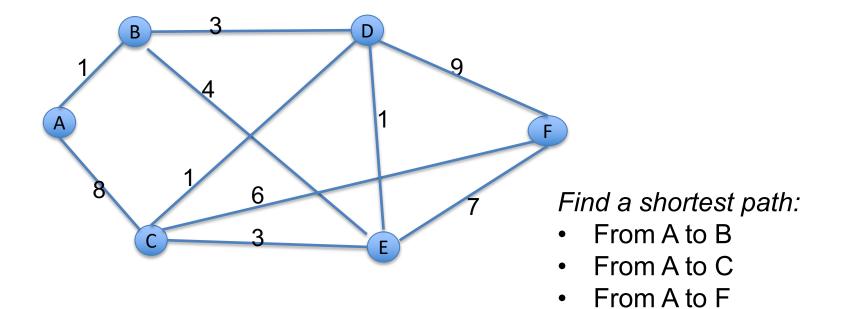
So the shortest path A→D has length 3, but what is the path?

Done= $\{(A,0), \{B,1\}, (C,2), (D,3)\}$

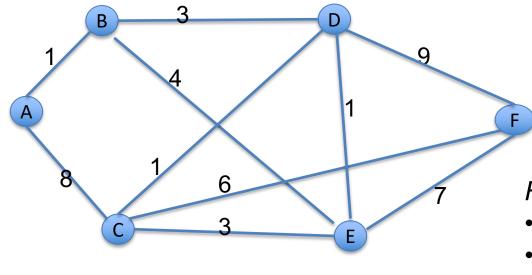
Dijkstra's Algorithm: Single Source Shortest Path SSSP

The task:

- Given a weighted graph G=(V,E,w(E)), and s∈V, and supposing that all weights are positive.
- Find shortest path (path with min total weight) from s to all other vertices.



From A to any other node



Find a shortest path:

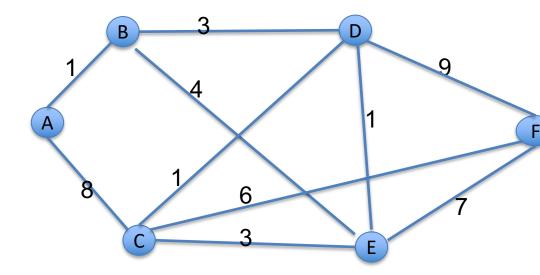
- From A to B
- From A to C
- From A to F
- From A to any other node

done	Α	В	С	D	E	F
	0, nil	∞,nil	∞,nil	∞,nil	∞,nil	∞,nil
А						

this column: nodes with shortest path found

dist[B]:
shortest-so-far
distance from

pred[D]: node that precedes D in the path A→D



4 The dist at SA is 0, there is an edge A->C with length 8, so we can reach C from A with distance 0+8, and 8 is better than previuosly-found distance of ∞

B

Δ

done

Find a shortest path:

- From A to B
- From A to C
- From A to F
- SP A->F=

F

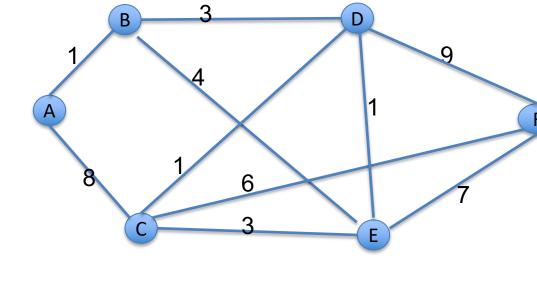
The "-" is shorthand for "∞,nil"

4 non-empty cells means there are 4 elements in the heap

done	^		C		-	•
	0, nil	∞,nil	∞,nil	∞,nil	∞,nil	∞,nil
А		1,A	8,A	-	-	-
В			8,A	4,B	5,B	-
D			5,D		5,B 🥿	13,D
С	Update this co				5,B	11,C
E	D with distanc 1 (of edge D→	e 4 (of D) +				11,C
С	better the					

D

At this pointy, we can reach E from D with distance 4 (of D) + 1 (of edge $D \rightarrow E$), but new distance 5 is **not better** than the previously found 5, so no update!



Find a shortest path:

- From A to B
- From A to C
- From A to F
- SP A->F=

What's the found shortest path from A to F?
distance= 11, path= $A \rightarrow B \rightarrow D \rightarrow C \rightarrow F$

done	Α	В	С	D	E	F
	0, nil	∞,nil	∞,nil	∞,nil	∞,nil	∞,nil
Α		1,A	8,A	-		-
В			8,A	4,B	5,B	_
D			5,D 🕶		5,B	13,D
С					5,B	11,C
E						11,C
С						

pred[B]= A: $A \rightarrow B \rightarrow D \rightarrow C \rightarrow F$

pred[D]= B: B \rightarrow D \rightarrow C \rightarrow F

> pred[C]= D: $D \rightarrow C \rightarrow F$

pred[F]= C, that is we came to F from C: C→F

the shortest distance from A to F is 11

Dijkstra's Algorithm as a (special) BFS

Basic idea

if $s \rightarrow A \rightarrow B$ is a shortest path then $s \rightarrow A$ is a shortest path.

Init:

 start with dist[s] = 0, and dist[*] = , set unvisited set = V

Round 1:

- choose node with min dist[], which is s;
- visit all nodes u adjacent to s and update dist[u];
- mark s as visited (remove it from the unvisited_set);

Round 2:

- choose the node with min dist[] from unvisited set
- do the other steps as in Round 1

Dijkstra's algorithm [conceptual only]

Purpose: Find shortest path from vertex s

```
set dist[u] = \infty, pred[u]=nil for all u,
set dist[s] = 0;
Insert all pair (dist[u], pred[u]) into a min PQ
while (PQ is not empty):
  remove u from PQ ( dist[u] is smallest)
  mark: found shortest path for u
   for all (u,v) in G:
     if (dist[v] > dist[u]+w(u,v):
            update (dist[v],pred[v]) in PQ
```

Dijkstra's Algorithm

Learn more about the algorithm, and its complexity in the lectures

Exercise

For a directed graph with the edges listed in LHS: **Data** a b 3 1. Draw a weighted directed graph that reflects these a d 7 edges and weights (logical representation). 2. Construct an adjacency matrix for the weighted digraph **b** d 2 you have just drawn, including the weights. Be explicit about how you are going to handle matrix cells for c e 6 which there is no information in the data. d b 2 3. Run through Dijkstra's Algorithm starting from the d c 5 vertex a. d e 4 e d 2

Lab: Peer Programming Exercises

- Do the exercise in previous page
- If you didn't do the priority queue exercise from the bonus workshop, the sample solution will likely solve you a lot of work
- A couple of sets of practice problems are also provided in week10-practice-problems.pdf — If you're struggling with the Dijkstra task, this may help with the conceptual lead-in
- Grady will also release his .ppt with some detailed slides

Lab:

- Implement priority queue (see LMS):
 - you can use your heap implementation from previous weeks