

# COMP20003 Workshop Week 12

Welcome to the last workshop!  
Good Luck!

- 1 MST & Greedy Algorithm for building MST
- 2 Prim's Algorithm
- 3 Kruskal's Algorithm

LAB: Assignment 2 || Pass exams

*Question of the Year: Do you still need time for assignment 3. Send me a letter Y or N 😊*

*Note: Grady is running consultation right now ...*

# MST & Greedy Algorithm

## **Greedy algorithm:**

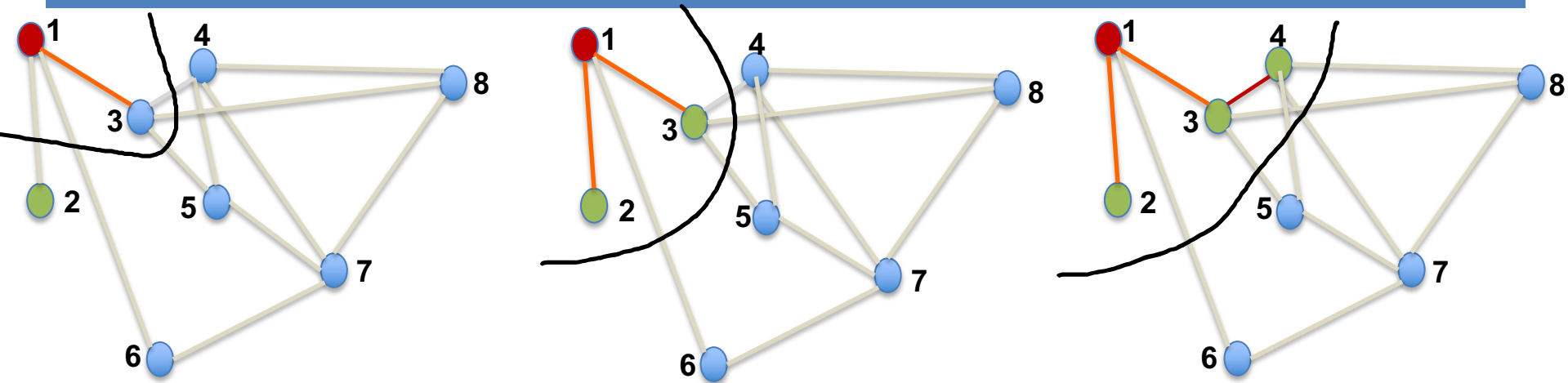
A myopic policy of always taking the “best” bite in each step.

NOT always works...

In many cases it's the best policy!

Dijkstra's algorithm is greedy.

# Greedy example: Dijkstra's Algorithms



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*Would you apply the greedy policy when applying for a job after graduation :-?*

# MST - overview

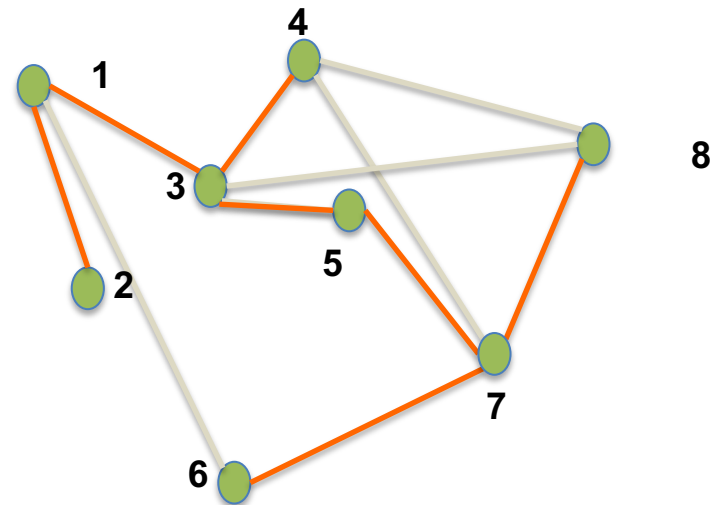
Task: give a *connected, weighted* graph  $G = (V, E, w)$ , find a MST for  $G$ .

What's a spanning tree? How many edges in a spanning tree?

What's a MST? Can  $G$  have more than one MST?

*Further Topics:*

- Which algorithms? Complexity = ?
- Which algorithm is better for:
  - dense graphs
  - sparse graphs



*In this graph, the visual length of an edge represent its weight. In particular edges (3,4), (4,5) and (5,3) have the same weight.*

# MST & Greedy Algorithm

**Greedy algorithm can be used for the MST task, for example:**

**Prim: MST built by taking a vertex at a time**

```
T= any vertex
while ( |T| < |V| ):
    add to T the vertex that
    has least distance to T
```

Note: distance between node  $u$  and set  $T$  is defined as the minimal distance between  $u$  and any member of  $T$

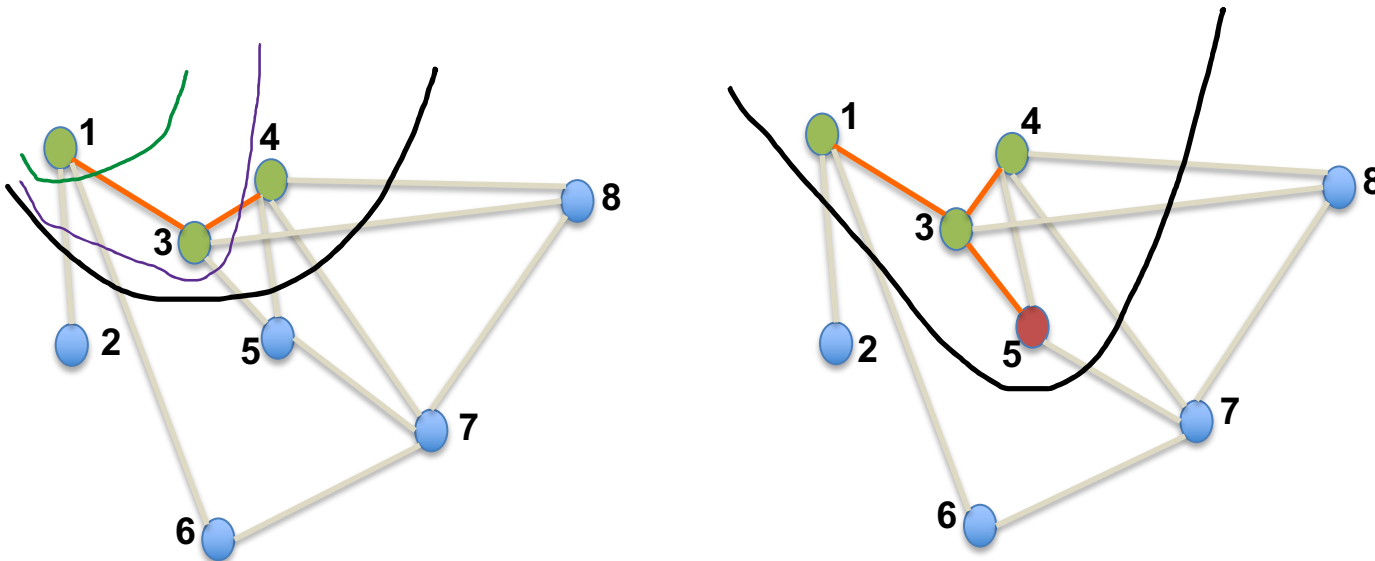
**Kruskal: MST built by taking an edge at a time**

```
T= EMPTY SET OF edges
while ( |T| < |V|-1 ):
    add to T the lightest edge
    that doesn't make cycle in T
```

# Prim's Algorithm

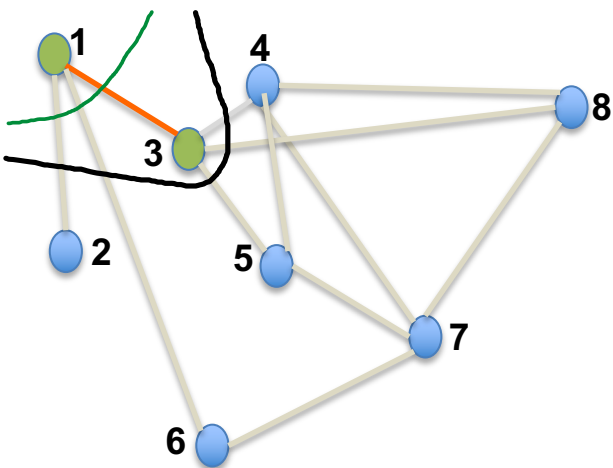
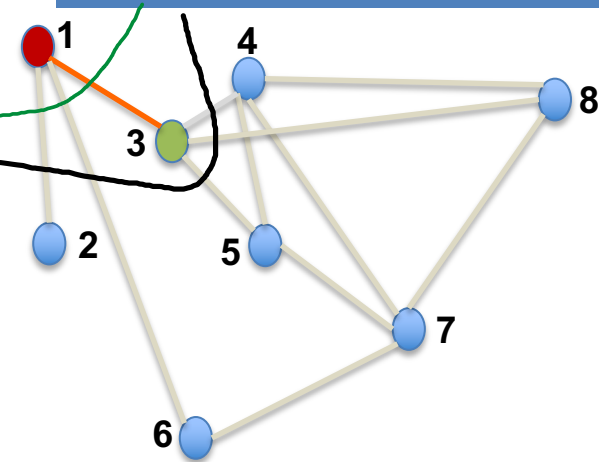
- Consider a randomly-chosen vertex as the MST-so-far.
- At each stage we, expand the MST-so-far by adding a vertex to that tree (the one that is closest to the so-far MST).

Sounds familiar? Similar to a studied algorithm?

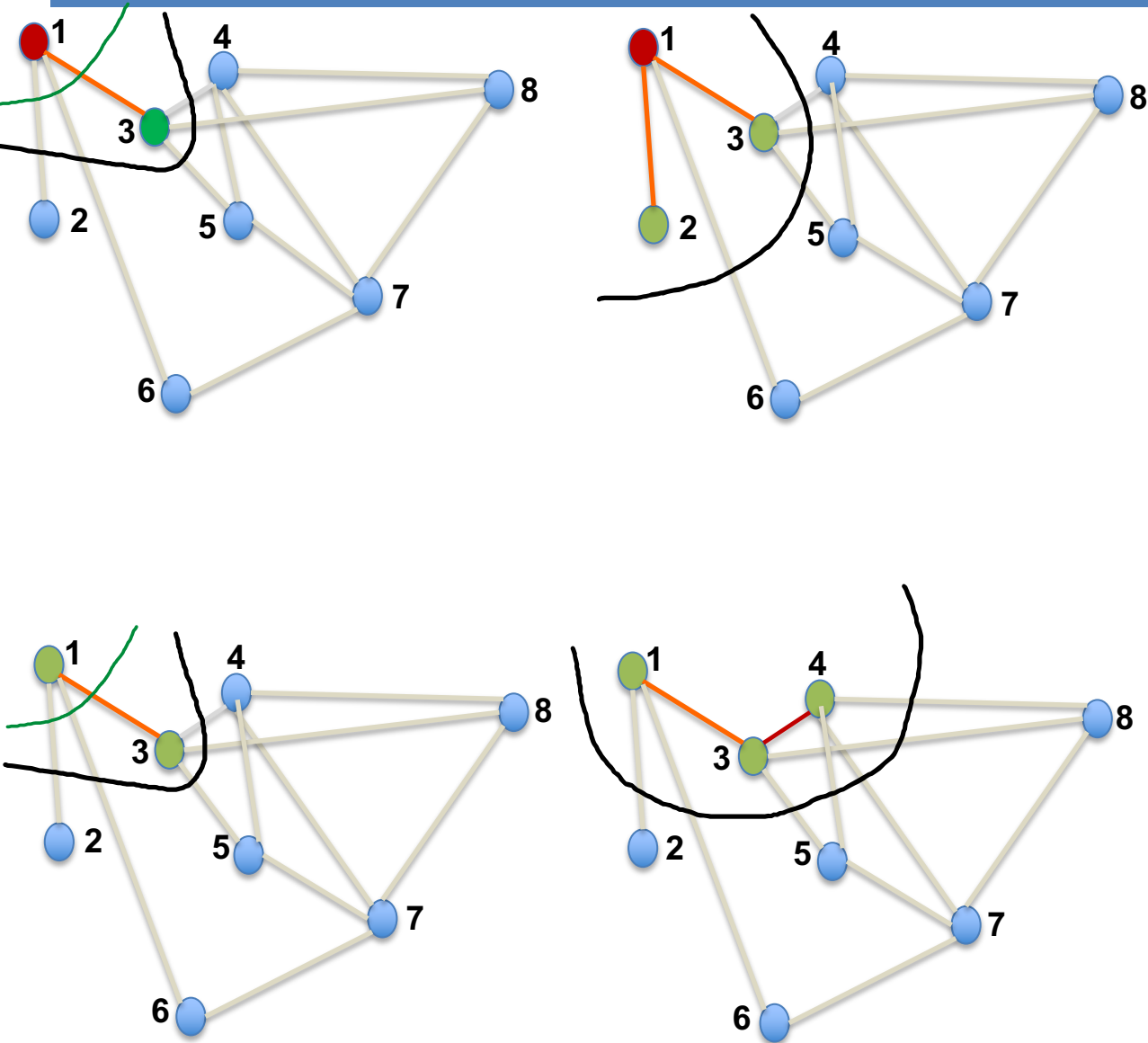


Note: in the graph: the visual length of an edge represents its weight. For example, edge (3,4) has the smallest weight, and the next is (3,5).

# Comparing: Dijkstra's & Prim's Algorithms

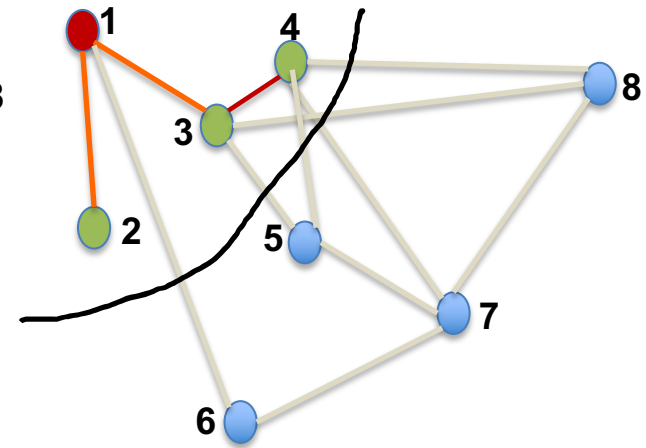
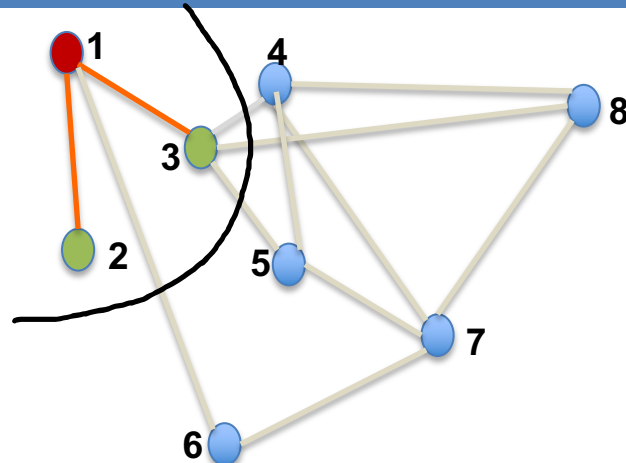
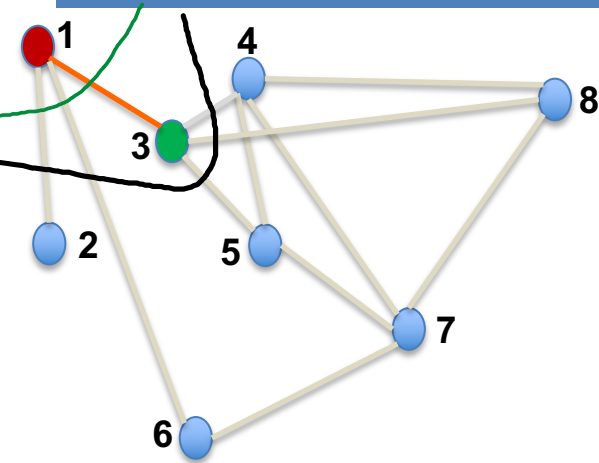


# Comparing: Dijkstra's & Prim's Algorithms

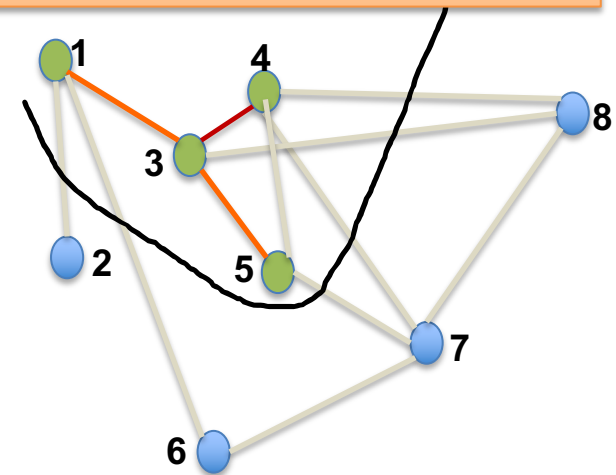
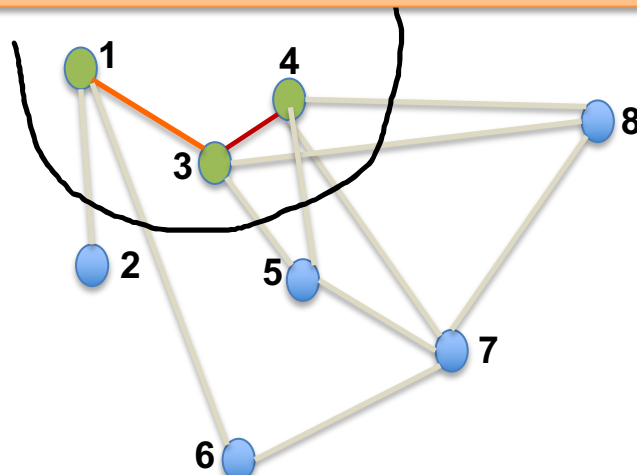
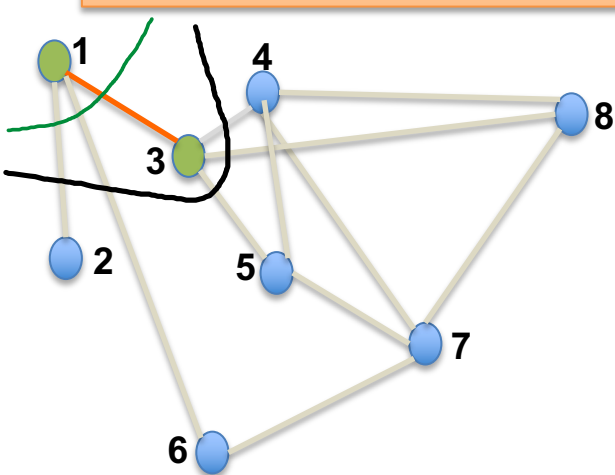




# Comparing: Dijkstra's & Prim's Algorithms



- Dijkstra's: choose node with the shortest distance to the red node
- Prim's: choose node with the shortest distance to any of the green nodes



# Prim's algorithm: operates vertex-by-vertex

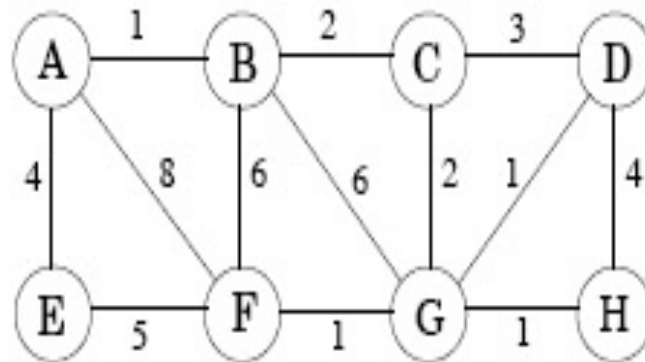
Given a (connected) weighted graph  $G$

Prim( $G$ ): Find a MST of $G$	Dijkstra( $G, s$ ): find shortest paths from $s$
<pre>for each <math>u</math> in <math>V</math>:     <math>cost[u] = \infty</math>     <math>prev[u] = nil</math>     <math>done[u] = FALSE</math> // =1 if in MST <math>s = \text{any vertex in } V</math> <math>cost[s] = 0</math> <math>H = \text{makePQ}(V)</math> while (<math>H \neq \emptyset</math>):     <math>u = \text{deleteMin}(H)</math>     <math>done[u] = TRUE</math> // add <math>u</math> to MST     for each <math>v</math> adjacent to <math>u</math>:         if (<math>!done[v]</math>             &amp;&amp; <math>cost[v] &gt; w(u, v)</math> ):             <math>cost[v] = w(u, v)</math> // <math>\downarrow</math> in <math>H</math>             <math>prev[v] = u</math></pre>	<pre>for each <math>u</math> in <math>V</math>:     <math>dist[u] = \infty</math>     <math>prev[u] = nil</math>     <math>done[u] = FALSE</math> // =1 if shortest path found  <math>dist[s] = 0</math> <math>H = \text{makePQ}(V)</math> while (<math>H \neq \emptyset</math>):     <math>u = \text{deleteMin}(H)</math>     <math>done[u] = TRUE</math> // shortest path to <math>u</math> found     for each <math>v</math> adjacent to <math>u</math>:         if (<math>!done[v]</math>             &amp;&amp; <math>dist[v] &gt; dist[u] + w(u, v)</math>):             <math>dist[v] = dist[u] + w(u, v)</math> // <math>\downarrow</math> in <math>H</math>             <math>prev[v] = u</math></pre>

Complexity of Prim's: same as Dijkstra's,  $O((E+V) \log V)$

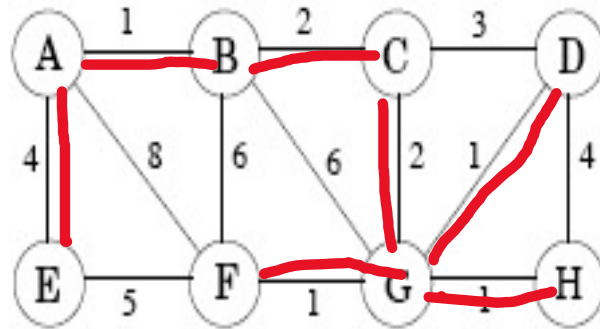
# Example

Suppose we want to find the minimum spanning tree of the following graph.



- (a) Run Prim's algorithm; whenever there is a choice of nodes, always use alphabetic ordering (e.g., start from node A).

# Example



	a	b	c	d	e	f	g	h
	0,nil	-	-	-	-	-	-	-
a		<u>1,a</u>	-	-	4,a	8,a	-	-
b			2,b	-	4,a	6,b	6,b	-
c				3,c	4,a	6,b	<u>2,c</u>	-
g				<u>1,g</u>	4,a	1,g		1,g
d					4,a	<u>1,g</u>		1,g
f					4,a			<u>1,g</u>
h					<u>4,a</u>			
<u>a</u>								



# Kruskal's algorithm

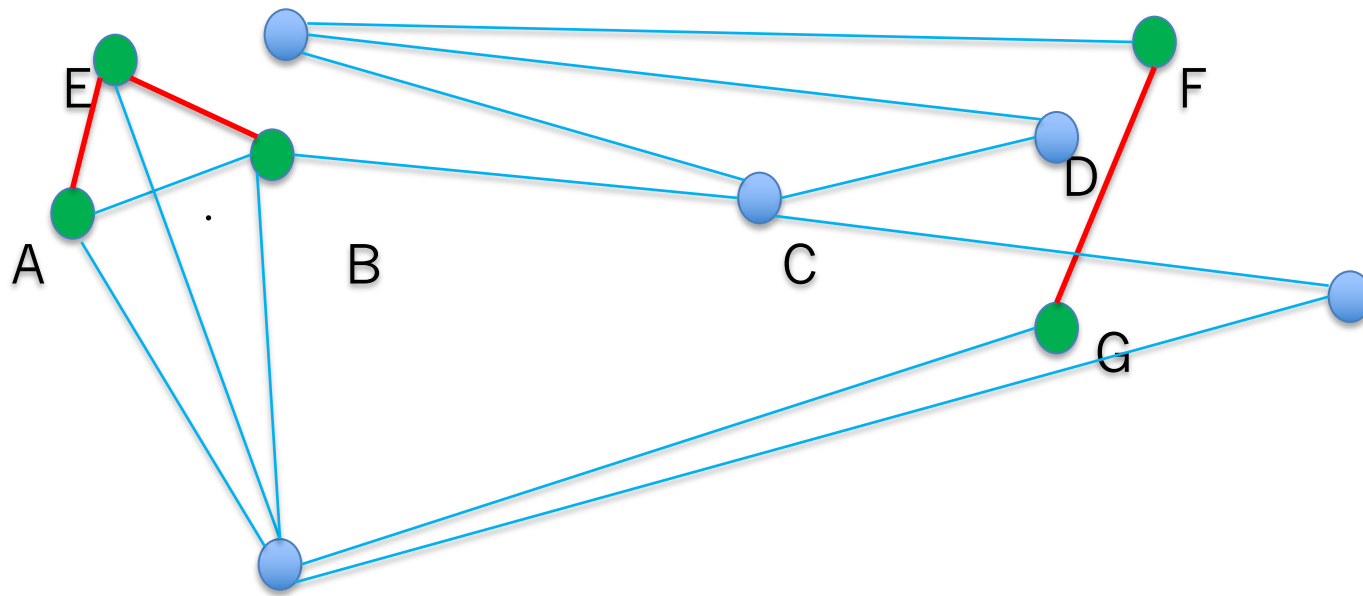
Purpose: Find MST of  $G = (V, E, w)$

Prim's algorithm: processing node-by-node, ie. adding a new node to MST at each step.

**Kruskal's** algorithm: operates edge-by-edge.

```
0  set MST-so-far to empty
3  for each  $(u, v)$ , in increasing order of weight:
4      if  $(u, v)$  does not form a cycle in MST-so-far:
5          add edge  $(u, v)$  to MST
```

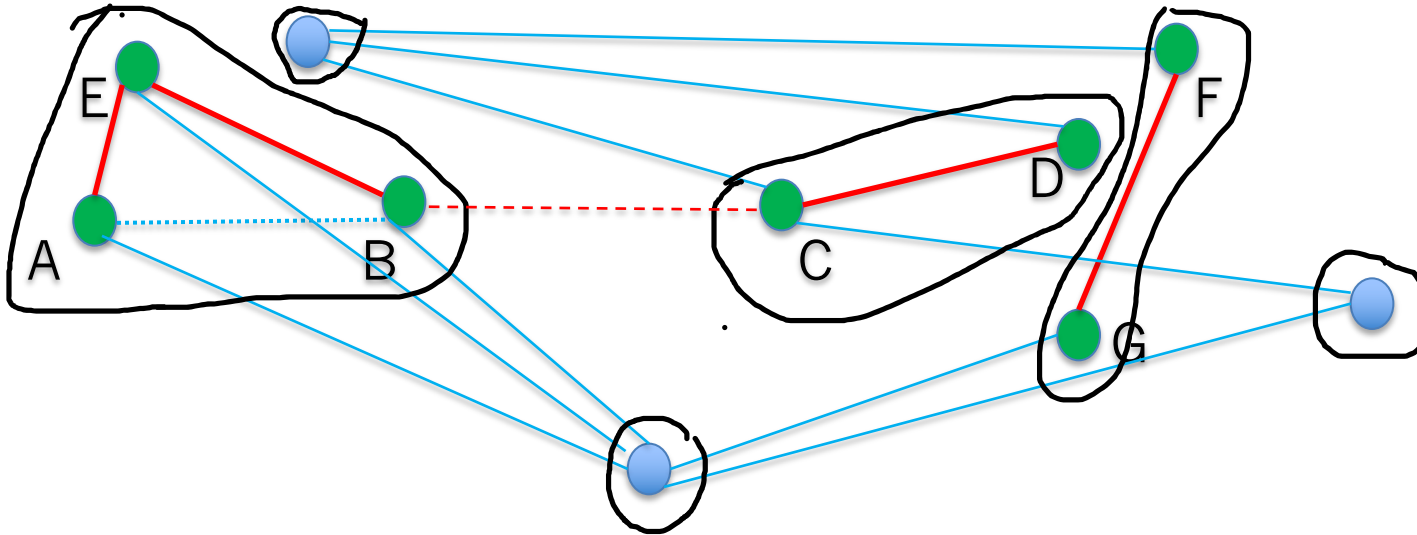
How do we implement?



Suppose that the above 5 green vertices and 3 red edges are in our MST-so-far. The next lightest are AB (should be rejected), then CD.

*How can we recognize that inclusion of AB would create a cycle in the MST-so-far?*

# Using disjoint sets



*How can we recognize that inclusion of AB would create a cycle in the MST-so-far?*

Think about disjoint sets:

- After adding (C,D) to MST, we have 6 disjoint sets.
- After adding (B,C) the sets ABE and CD are joined into ABCDE → we will have 5 disjoint sets

Needed:

- an ID for each set ?
- Operator **Find(u)** : find the set the set a node u belongs to
- Operator **Union(u,v)** : join the disjoint sets of u and v into a single set



# Kruskal's algorithm

```
3  for each (u,v), in increasing order of weight:
4      if ( (u,v) does not form a cycle in MST-so-far):
5          add edge (u,v) to MST
```

Implement step 3-5 using disjoint set:

- Before the loop: Make  $|V|$  disjoint subsets, each contains a single node of  $V$ .
- In the loop body:
  - $u$  and  $v$  not belong to a same set  $\Leftrightarrow (u,v)$  does not form a cycle in the MST.
- Step 3: The algorithm stops when we have  $V-1$  edges in MST

Operations:

$\text{makeset}(u)$  - return a tree that contains single  $u$

$\text{find}(u)$  - return the root (means, ID) of the tree that contains  $u$ ;

$\text{union}(u,v)$  - joins trees containing  $u$  and  $v$ .

# Kruskal's algorithm

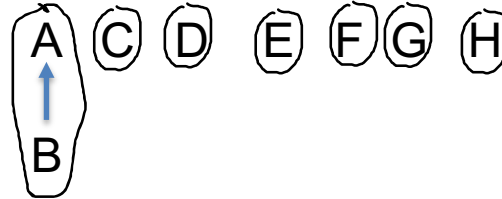
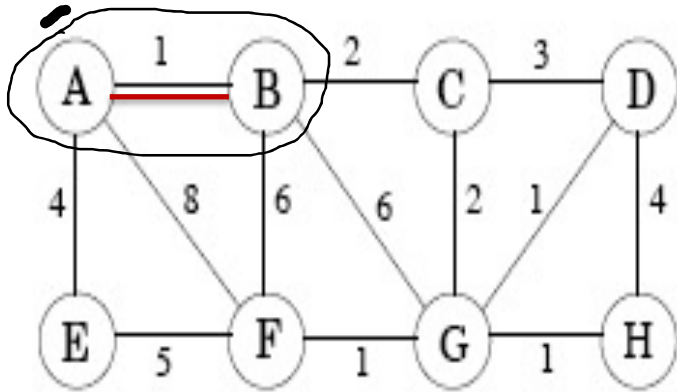
Purpose: generate MST with Efficient checking for cycle in finding MST

```
0 set X= empty. X is the MST-so-far
1 E1 = E, but sorted in increasing order of weights
2 for each u: makeset(u) (build single-element set {u})
3 while ( |X| < |V|-1 ) :
3a  set (u,v)= the next edge in E1
4   if (find(u) ≠ find(v) ):    // u & v do not belong to a same set
5       add edge (u,v) to X
6       union(u,v)
```

Watch online lecture for how to actually implement `makeset(u)`, `find(u)`, `union(u,v)`

- We can implement with  $O(V+E \log V)$  or even  $O(V+E)$  for steps 2-6
- The cost of KA is dominated by  $E \log E$  of the sorting phase in step 0

# Example (Kruskal's)

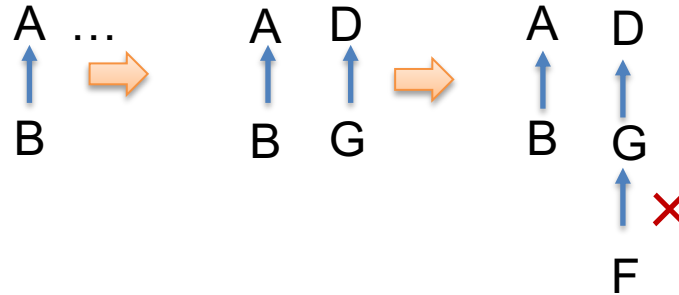
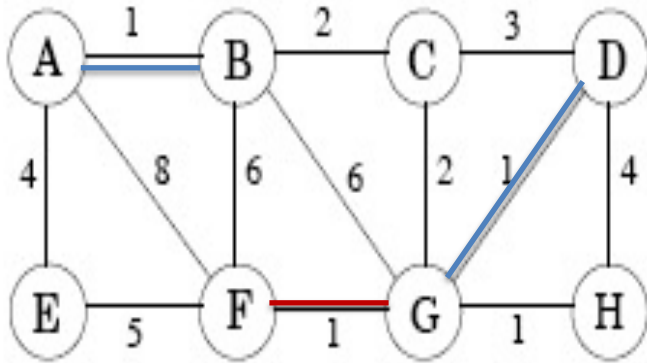


Edges in MST	A	B	C	D	E	F	G	H
	0	1	2	3	4	5	6	7
A---B	0	0	2	3	4	5	6	7



Note: number in table represents tree ID, if a tree ID is the same as node ID, then the node is the root of its tree

# Example (Kruskal's)

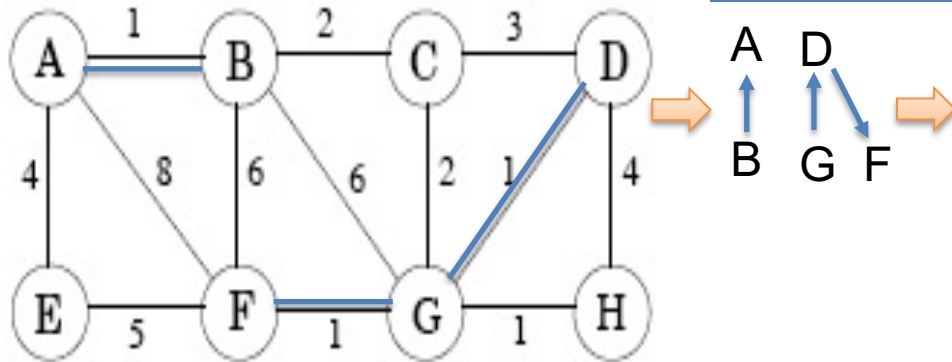


Edges in MST	A	B	C	D	E	F	G	H
	0	1	2	3	4	5	6	7
A---B	0	0	2	3	4	5	6	7
D---G	0	0	2	3	4	5	3	7
G---F	0	0	2	3	4	?	3	7

Note: number in table represents tree ID, if a tree ID is the same as node ID, then the node is the root of its tree

## Rules:

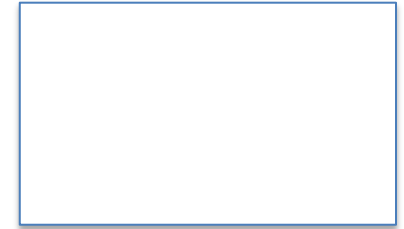
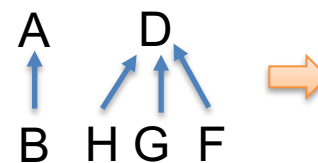
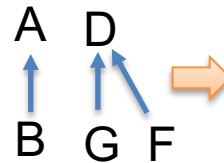
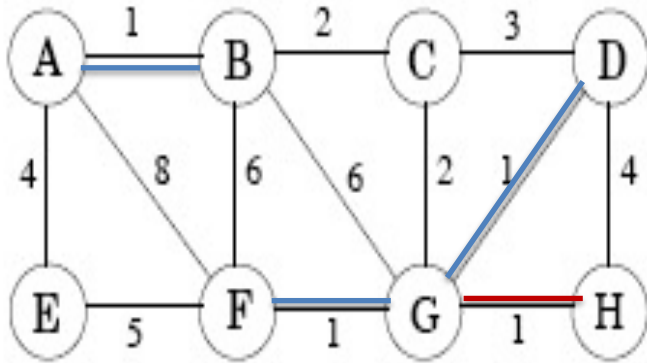
- 1) join smaller tree to bigger tree (*weighted*, or *join-by-rank* optimization)
- 2) when joins, joins to the root, ie.  $\text{id}[F] = \text{id}[G]$



Edges in MST	A	B	C	D	E	F	G	H
	0	1	2	3	4	5	6	7
A---B	0	0	2	3	4	5	6	7
D---G	0	0	2	3	4	5	3	7
G---F	0	0	2	3	4	6?	3	7
G---F	0	0	2	3	4	3	3	7

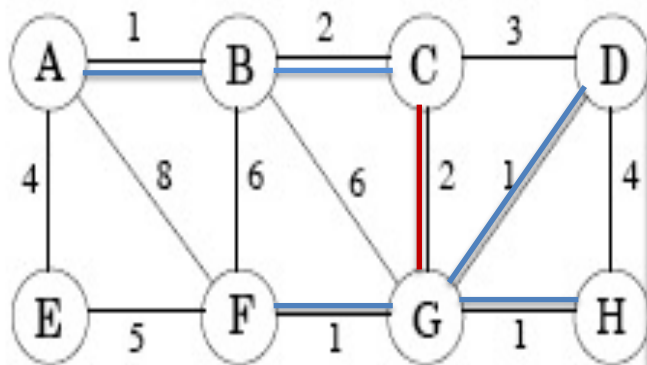
## Rules:

- 1) join smaller tree to bigger tree (*weighted*, or *join-by-rank* optimization)
- 2) when joins, joins to the root

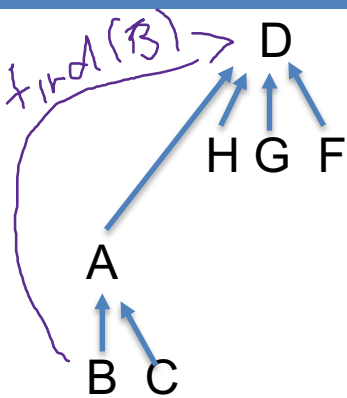


Edges in MST	A	B	C	D	E	F	G	H
	0	1	2	3	4	5	6	7
A---B	0	0	2	3	4	5	6	7
D---G	0	0	2	3	4	5	3	7
G---F	0	0	2	3	4	3	3	7
G---H	0	0	2	3	4	3	3	3

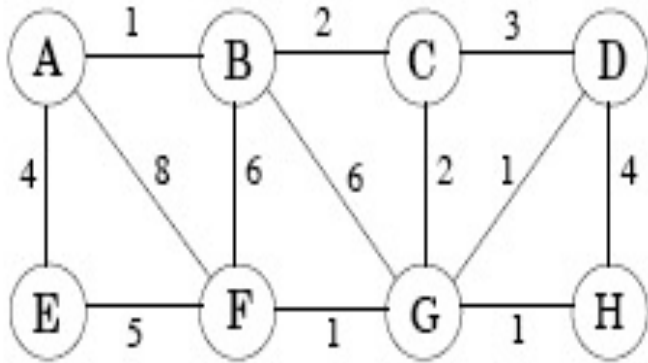
Rules:  
3) Path compression



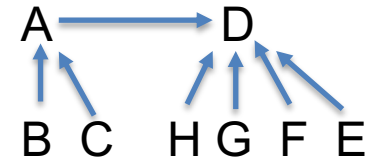
- Now, the pathlen of B,C is >1
- In the future, if we call find(B) we will have find(B)= D, and at that time we will make B point directly to D. That is called *path compression*.



Edges in MST	A	B	C	D	E	F	G	H
	0	1	2	3	4	5	6	7
A---B	0	0	2	3	4	5	6	7
D---G	0	0	2	3	4	5	3	7
G---F	0	0	2	3	4	3	3	7
G---H	0	0	2	3	4	3	3	3
B---C	0	0	0	3	4	3	3	3
C--G	3	0	0	3	4	3	3	3



After adding A---E to the MST-so-far, the latter has enough V-1 edges, and we stop. Note that in our tree-array, there is only a single tree at this stage.



Edges in MST	A	B	C	D	E	F	G	H
	0	1	2	3	4	5	6	7
A---B	0	0	2	3	4	5	6	7
D---G	0	0	2	3	4	5	3	7
G---F	0	0	2	3	4	3	3	7
G---H	0	0	2	3	4	3	3	3
B---C	0	0	0	3	4	3	3	3
C---G	3	0	0	3	4	3	3	3
A---E	3	0	0	3	3	3	3	3



In the lecture, weighted and path compression was mentioned, but probably without much of details.

Complexity of *a single* union and find using disjoint-set:

- find:  $O(1)$
- union: time for tracing depends on the depth of the tree
  - naïve:  $O(V)$
  - weighted:  $O(\log V)$
  - weighted + path compression:  $O(1)$

# Justify the Complexity

## Kruskal's: generate MST with Efficient checking for cycle in finding MST

```
0 set X= empty. X is the set of the MST-so-far
1 E1 = E, but sorted in increasing order of weights           O(E log E)
2 for each u:                                                 V ×
    add makeset(u) to X                                       O(1)
    (build set {u} and add to X with X= X ∪ {u})

3 while (|X| < |V| - 1) :                                     V ×      ???
    (u,v) = next edge in E1                                   O(1)
4   if (find(u) ≠ find(v)) :                                  O(1)
5     union(u,v)                                              O(1)
6     add (u,v) to X                                           O(1)
```

### True or False:

- Loop (3) is  $O(V)$ , and hence we don't need to fully sort  $E1$ , just make  $E1$  a minheap. As the result, step 1 is  $O(E)$ , step 3-6 is  $O(V \log E)$ ?
- We can use distribution counting and make Kruskal's to make step 1 be  $O(E)$
- Since  $E = O(V^2)$  in the worst case, Kruskal's is  $O(E \log V)$  just like Prim's.

# Justify the Complexity

## Kruskal's: generate MST with Efficient checking for cycle in finding MST

```
0 set X= empty. X is the set of the MST-so-far
1 E1 = E, but sorted in increasing order of weights          O(E log E)
2 for each u:                                                V ×
    add makeset(u) to X                                     O(1)
    (build set {u} and add to X with X= X {u})

3 for each edge (u,v) in E1 (in increasing order of weight): E ×
4   if (find(u) ≠ find(v) ):                                O(1)
5     union(u,v)                                             O(1)
6     add (u,v) to X                                         O(1)
```

	Prim	Kruskal
General	$(E+V) \log V$	$E \log E$
Dense Graph	$E \log V$	$E \log E$
$V \ll E$ , Prim's is faster		
Sparse Graph	$V \log V$	$V \log V$
Kruskal's is faster because of the data structures		

# Lab Time:

Learning experience from the semester?

LAB:

- finish ass2, or
- go through some questions, especially short questions, in past-exam papers,
- give questions to the in-lazy-mode Anh



Good luck!