# COMP20003 Workshop Week 6 Hashing + Assignment 2

Distribution Counting (aka. Counting Sort)

Hashing

2-3-4 Trees

#### LAB

- Implementation W6.5 (a small exercise)
- Assignment 2

### Distribution Counting: An Unusual Sorting Algorithm

### **Strengths**

Does not rely on key comparisons

Runs in linear time  $\Theta(n + k)$ , where k is the key range  $\Rightarrow \Theta(n)$  time if  $k \in O(n)$ Stable (preserves the order of equal keys)

#### Limitations

Requires  $\Theta(n+k)$  extra memory

Inefficient when the key range k is much larger than  $n \rightarrow \text{not a general-purpose sort}$ 

#### **Constraints**

Keys must be integers (or mapped to integers) in small range k

#### **Operation**

counts the frequency of each key builds the cumulative array to determine positions places elements into the output array in order

### Example

Special Example: sort an array where the keys are non-negative integers, each  $\leq 2$ :

input keys: 
$$\{0,1,2,0,0,1,2,1,1,0,0,0\}$$

freq(0) = 6

keys 0 start from index 0

freq(1)=4

keys 1 starts from index

freq(2)=2

keys 2 starts from index 10

2, 2 }

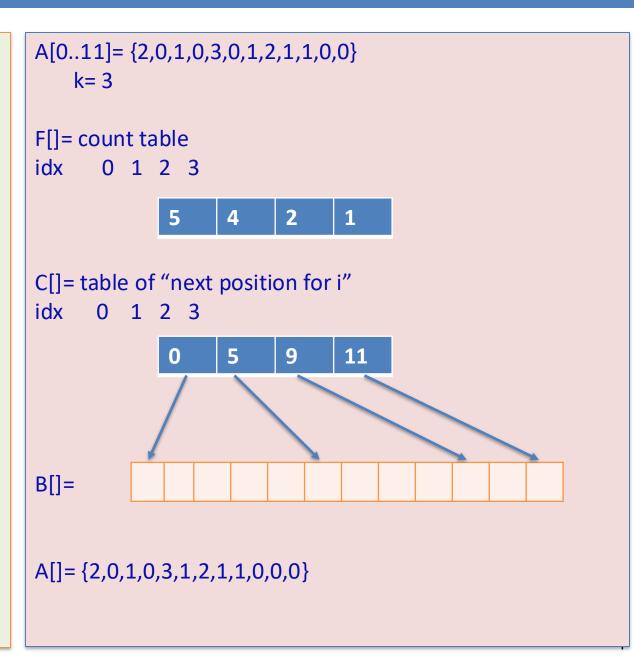
Note: here k= 2

Array  $F[] = \{6, 4, 2\}$  is the frequency array

Array  $C[] = \{0, 6, 10\}$  is the cumulative array

### Counting Sort for sorting array A[0..n-1]

```
Input: A[0..n-1], k (such that 0 \le A[i] \le k)
Output: B[0..n-1] which is the sorted version of A[]
Step 1a: build the count array F[] such that
          F[x] = frequency of x in A[]
Step 1b: transfer F[] to the cumulative array C[]:
     C[x] = starting position of value x
              in the sorted array B[].
Step 2: scan A[] from let to right and copy elements A to
sorted array B[]. For each A[i]:
B[C[A[i]] + +] = A[i] \Leftrightarrow B[C[x]] = x;
```



### Peer Activity: Sorting Numbers

Suppose that we have a sequence of binary numbers (either 0 or 1).

Which sorting algorithm is best suited for sorting this sequence of numbers?

- a. Quick sort
- b. Selection sort
- c. Insertion sort
- d. Distribution counting

### Hashing – Key Features

#### **Concept:**

Maps keys to indices in an array (hash table) using a hash function.

Aims for near-constant time insertion, deletion, and search.

#### Strengths:

Fast average-case operations: O(1) for insert, search, delete.

Flexible: can store integers, strings, or complex objects via suitable hash functions.

#### **But:**

O(n) worst case for insert, search, delete.

#### **Typical Use Cases:**

Implementing dictionaries, sets, symbol tables, caches.

Fast membership testing and lookups.

### Example of Hashing

```
// hash function
int hash(int key) {
    return key % 13;
```

```
Want to insert:
  14, 30, 17, 55, 31, 29, 16
hash(14) == 1
hash(30) ==
hash(17) ==
```

Index	0	1	2	3	4	5	6	7	8	9	10	11
Key												

### Example of Collision

```
// hash function
                              Want to insert:
int h(int key) {
                                 14, 20, 33, 46, 31, 29, 16
    return key % 13;
                         h(20) == 7
   h(14) == 1
                                                              10
                                   5
                                                         9
                                                                   11
 Index
                              4
                                                   8
             14
                                             20
 Key
```

where to put 7?

### Collision Resolution: Method 1A – Open Addressing with Linear Probing

**Open Addressing:** store all elements in the table itself; on collision, probe for next empty slot.

 $h(k,i)=(h(k)+i) \mod m$ **1A - Linear Probing:** check slots sequentially:

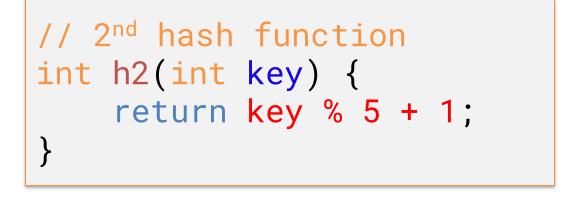
```
// hash function
                               Want to insert:
int h(int key) {
                                  14, 20, 33, 46, 31, 29, 16
    return key % 13;
                                                    h(33) == 7
                                                    index 7 is busy
                          h(20) == 7
  h(14) == 1
                                                    found vacant
                                                    location 8 when i==1
Index
        0
                         3
                                          6
                                                           9
                                                                10
                                                                      11
                              4
                                               20
Key
             14
                                                     33
```

### Collision Resolution: Method 1A – Open Addressing with Double Hashing

 1B- Double Hashing: use second hash for step:  $h(k,i) = (h1(k) + i*h2(k)) \mod m$ 

```
// hash function
int h(int key) {
    return key % 13;
```

$$h(20) == 7$$



h(33) == 7index 7 is busy found vacant location 7+4= 11 when i==1

Index	0	1	2	3	4	5	6	7	8	9	10	11
Key		14						20				33

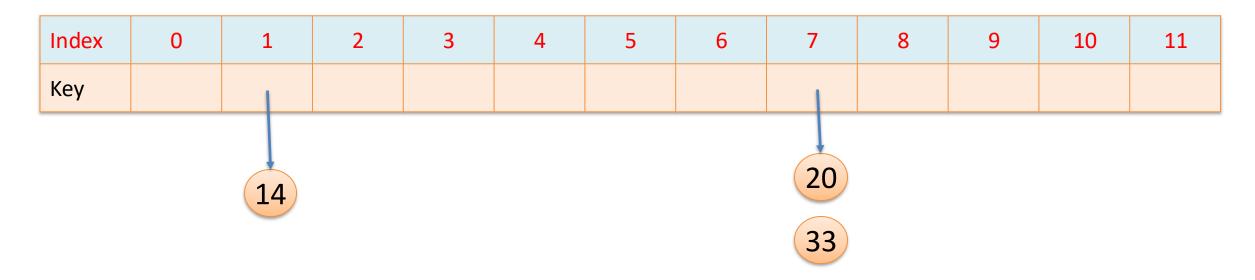
Want to insert:14, 20, **33**, 46, 31, 29, 16

### Collision Resolution: Method 2 – Separate Chaining

**Separate Chaining:** store a linked list (or other dynamic structure) at each hash table slot; all keys that hash to the same index are inserted into that list.

```
// hash function
int h(int key) {
   return key % 13;
```

```
Want to insert:
14, 20, 33, 46, 31, 29, 16 h(20) == 7
```



### Peer Activity: Overfilled Hash Table

### Suppose that we have a **hash table** that:

- uses linear probing/double hashing for collision resolution
- is currently full

#### What should be done to insert another item into the hash table?

- a. Give up; nothing can be inserted into an overfilled hash table.
- b. realloc() the key array and insert the new item into this hash table.
- c. realloc() the key array, rehash the existing keys, and insert the new item into this hash table.
- d. Create another identical, empty hash table and insert the new item there.

### Peer Activity: Overfilled Hash Table

# What should be done to insert another item into the hash table?

c. realloc() the key array, rehash the existing keys, and insert the new item into this hash table.

#### Why?

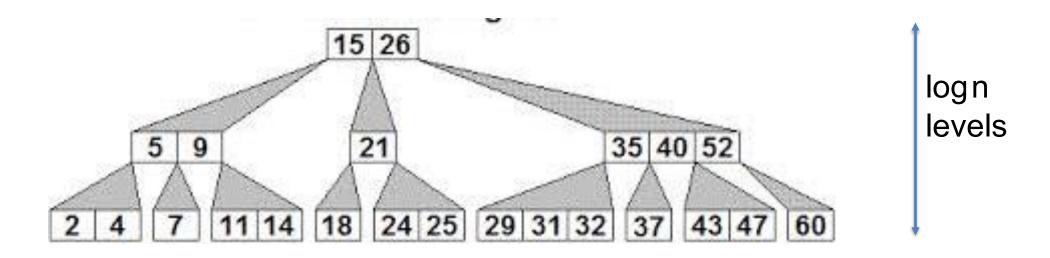
- realloc() the key array to get more space to store keys
- rehash existing keys to redistribute them over the enlarged key array

Suppose that we have a **hash table** that:

- uses linear probing/double hashing for collision resolution
- is currently full

### 2-3-4 Trees (B-trees of order 4)

What? It's a search tree, but not a binary tree! Each node might have 1 to 3 keys, and hence 2 to 4 children.



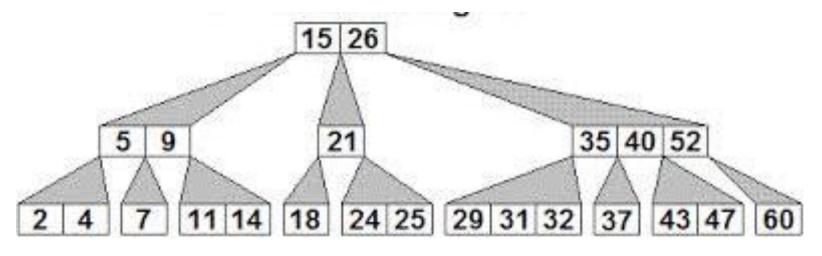
always balanced: all leaf nodes are in the same level

- → the height of the tree is O(log n)
- → search/insert/delete is O(log n)

#### 2-3-4 Trees: Insertion

### How to insert a new data **key**:

- start from root, use key to go down to a leaf node, and insert key to that leaf node
- if the *leaf node* has ≤ 2 data: insert to that node
- if the *leaf node* has 3 data: promote the median key to its parent *before insertion*
- the promoting might continue several levels upward until getting a parent with ≤ 3 data



insert 8 is easy: node [7] become [7,8]

insert 30:

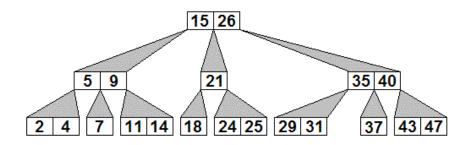
- $\rightarrow$  promote 31...  $\rightarrow$  promote 40
- $\rightarrow$  insert 30 to node 29  $\rightarrow$  (29,30)
- → promote 40 to the root

#### Class example:

Insert the following keys into an initially-empty 2-3-4 Tree.

20 10 5 15 30

### 2-3 Trees, 2-3-4 Trees, B-Tree



2-3 trees = B-trees of order 3 (order = max number of children)

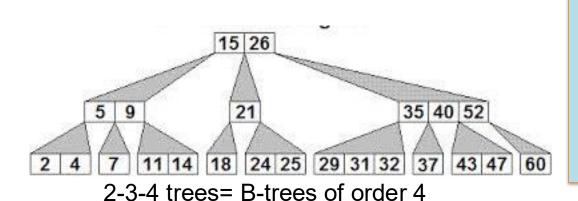
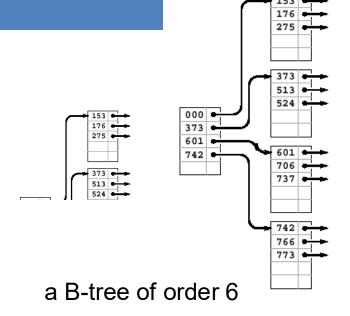


Image sources: ?? and http://anh.cs.luc.edu/363/notes/06DynamicDataStructures.html



#### **B-tree principles**

- Always insert at leaves
- When a node full: promote the median data to the node's parent [and walk up further if needed]

### Practice: W6.2

- Understanding linear probing & double hashing with W6.2
- Programming with W6.3:
  - hash table framework already implemented
  - just implement 3 functions in hashT.c

#### **Programming Notes:**

- functions insertLP and insertDH5 are used in insert,
- the parameter key in insertLP, insertDH5, insertDH is actually the first mapping position, value is the step (ie. value of h2(x))

### Tips:

- start with insertDH
- then, insertLP and insertDH5
- before implementing any function, read its comments in hashT.h

### ASS2: Q&A

## Requirements: Code & Report

- Report: perhaps next week
- what to consider when writing the code?

### How to Start A2 Coding?

- Use any good and working version of Assignment 1 at the starting point, for example:
  - your code (which is the best!)
  - Assignment 1 solution (needs more time to digest)

- If the A1 version is good, it should be easy to add just one single module for working with Patricia trie (with 2 main functions for search and insert)
- cp driver.c driver2.c then change driver2.c to be the main file for dict2
- Add .c and .h files for the Patricia trie
- Build the trie node structure, basically following the spec

### Additional Slides

### **Distribution Counting summary**

Unlike other sorting algorithms, Distribution Counting does not use key comparison.

Normally not applicable. Can only be useful when

- keys can be considered as integers in small range
- ie. when min  $\leq$  keys  $\leq$  max and max-min  $\in$  O(n)

#### *Time complexity, supposing* r= max-min+1:

- **P**(n+r), or
- P(n) if  $r \in O(n)$

### Special properties:

- *not in-place*, ie. requiring additional arrays for data records
- additional memory: P(n+r), or P(n) if  $r \in O(n)$
- the sorting is *stable*, ie. it preserves the relative order of equal keys