

COMP20003 Workshop Week 4

It's about Complexity and ... A1

1. Complexity Analysis
2. Another ADT: Stack
3. Yet Another ADT: Queue

LAB:

- Finish Assignment 1 OR do Week 4 Extras

Concepts: Big-O: asymptotic evaluation of running time (or space)

$f(n) = O(g(n))$:

- **Def:** There are constants $c > 0$ and $n_0 \geq 0$ so that $f(n) \leq c \cdot g(n)$ for all $n > n_0$
- *Underlying meaning:* $f(n)$ grows slower than, or as the same rate as, $g(n)$

$f(n) = O(g(n))$ is *equivalent* to:

- ✓ $f(n) \leq c \cdot g(n)$ for some constant c and all large n
- ✓ $c \cdot g(n)$ is *one of* the upper bounds of $f(n)$ for all large n
- ✓ $f(n) = O(f(n))$
- ✓ $f(n) = O(h(n))$ for any function $h(n)$ that grows faster than $f(n)$ or $g(n)$

BE CAREFUL! Any of:

- $f(n) \leq g(n)$
- $f(n) \leq c \cdot g(n)$
- $f(n) \ll g(n)$ (sign \ll denotes: grows slower than)

implies $f(n) = O(g(n))$, but the *reverse is incorrect*. For example, $f(n) = O(g(n))$ does NOT imply that $f(n) \leq g(n)$.

Example: find $g(n)$ so that $f(n) = O(g(n))$ if

- $f(n) = 7n$
- $f(n) = 2n^2 + 5n + 1$

Concepts: from Big-O to Big- Ω and Big- θ

$$f(n) = \Omega(g(n)) \Leftrightarrow g(n) = O(f(n))$$

- **Def:** There are constants $c > 0$ and $n_0 \geq 0$ so that $f(n) \geq c \cdot g(n)$ for all $n > n_0$
→ $f(n) \geq c \cdot g(n)$ (for some constant c and all large n)

$$f(n) = \theta(g(n)) \Leftrightarrow f(n) = O(g(n)) \text{ AND } f(n) = \Omega(g(n))$$

→ $f(n)$ and $g(n)$ *grow at the same rate*

→ $f(n)$ is sandwiched between $c_1 \cdot g(n)$ and $c_2 \cdot g(n)$: $c_1 \cdot g(n) \leq f(n) \leq c_2 \cdot g(n)$
(for some constants c_1, c_2 and all large n)

Example: find some Ω and θ for:

- $f(n) = 7n$
- $f(n) = 2n^2 + 5n + 1$

Do
W4.4
Now

Application 1: Finding Complexity of C codes (and algorithms in general)

Rules from lectures/Skienna:

- Each simple operation takes exactly one time step.
- Each memory access takes exactly one time step.

So practically:

A finite number of assignments, arithmetic and logical expressions is just $\theta(1)$.
“finite” means “not depending on input size”

Examples: are they $\theta(1)$?

```
a= (b+c)*d - x;  
if ( a+b > c<<10 )  
    a= x + a*b;
```

```
for (i=0; i<1000; i++) {  
    a= a*(b+c)*d - x;  
}
```

Application 1: Find complexity of algorithms, including C codes

Rules from lectures/Skiena:

- Loops and subroutines/functions are not considered simple operations. Instead, they are the composition of many single-step operations.

1	for (i=0; i<n; i++)
2	sum = sum + i;

Method 1

- Loop body is $\theta(1)$, and *always* repeats n times
- So, it's $\theta(n \times 1) = \theta(n)$

Method 2

- Loop body is constant time, equivalent to 1
- Line 1 has i running from 0 to $n-1$
- So, total time is

$$\sum_{i=0}^{n-1} 1 = n$$

hence it's $\theta(n)$

Application 1: Find complexity of algorithms, including C codes

1	for (i=0; i<n; i++) {
2	if (x==A[i]) return i;
3	}
4	return -1;

Method 1:

Method 2:

Application 1: Find complexity of algorithms, including C codes

1	for (i=1; i<n; i++) {
2	if (x==A[i]) return i;
3	}
4	return -1;

Method 1:

- Loop body is $\theta(1)$ (or $O(1)$)
- Loop runs at least 1 times, at most n times

→ So $O(n)$, but not $\theta(n)$

Method 2:

- Loop body (line 2) is constant time, equivalent to 1
- *the best case*: the loop runs 1 time and is $O(1)$, so the total running time is $\theta(1)$ in the best case
- *the worst case*: The loop runs with i from 0 to $n-1$, so
$$T(n) = \sum_{i=0}^{n-1} 1$$
$$= n = \theta(n) \text{ in the worst case}$$
- *General case*: So $T(n) = \Omega(1)$, and $T(n) = O(n)$, no θ available

→ This algorithm is $O(n^2)$, its best case is $\theta(n)$, worst case is $\theta(n^2)$

Do W4.5 and W4.6 Now

Application 2: Comparing complexity functions using *complexity classes*

(One method) to compare $f(n)$ and $g(n)$ in terms of Big-O: first reduce $f(n)$ and $g(n)$ to their simplest form (ie. to their respective complexity classes) using:

Big-O Heuristics

- Ignore coefficient
(but not when inside a function)
- Drop lower-order terms

Big-O Arithmetic

- $O(f) + O(g) = O(f+g)$
 $= O(\max(f, g))$
- $O(f) * O(g) = O(f*g)$

then compare the simplest forms using:

Growth order from lectures/Skienna's

$$n! \gg 2^n \gg n^3 \gg n^2 \gg n \log n \gg n \gg \log n \gg 1$$

Notes:

- $\log_a n = \theta(\log_b n)$ for all $a, b > 0$
- $a^n \gg b^n$ if $a > b > 1$
- $n^a \gg n^b$ if $a > b > 0$

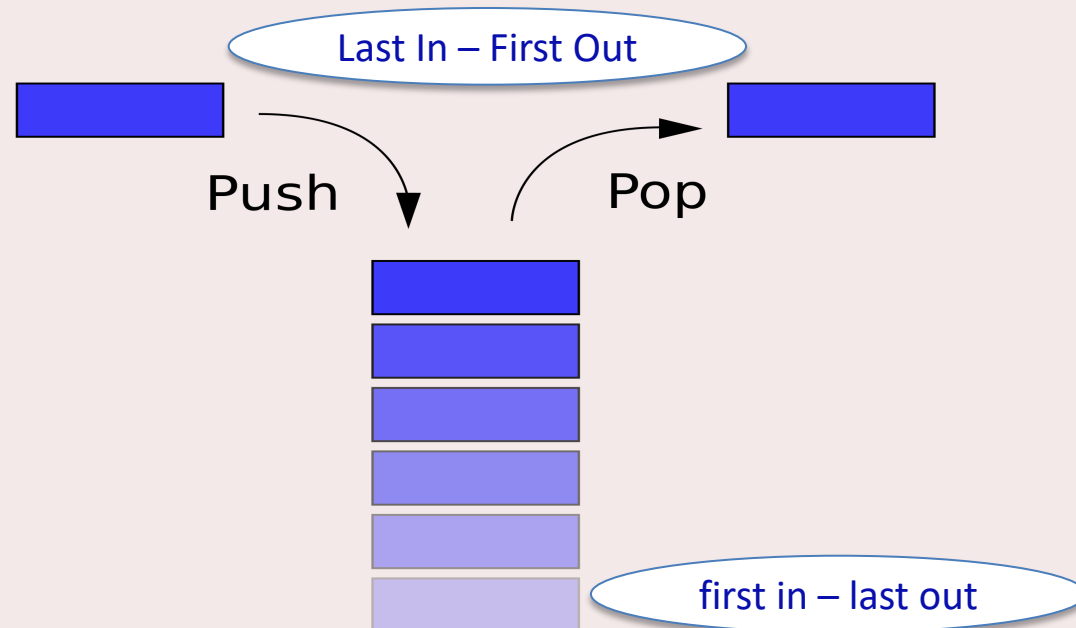
- Examples?
- Do W4.3
Now

Another ADT: Stack (LIFO) = W4.7



<http://www.123rf.com/stock-photo/tyre.html>

Stack Operations



[https://simple.wikipedia.org/wiki/Stack_\(data_structure\)](https://simple.wikipedia.org/wiki/Stack_(data_structure))

push: add an element into stack
pop: remove an element from stack
create: create a new, empty stack
delete: delete (free all associated memory)
isEmpty: check if stack is empty, or
size: return number of elements in stack

Example: stack in function calls

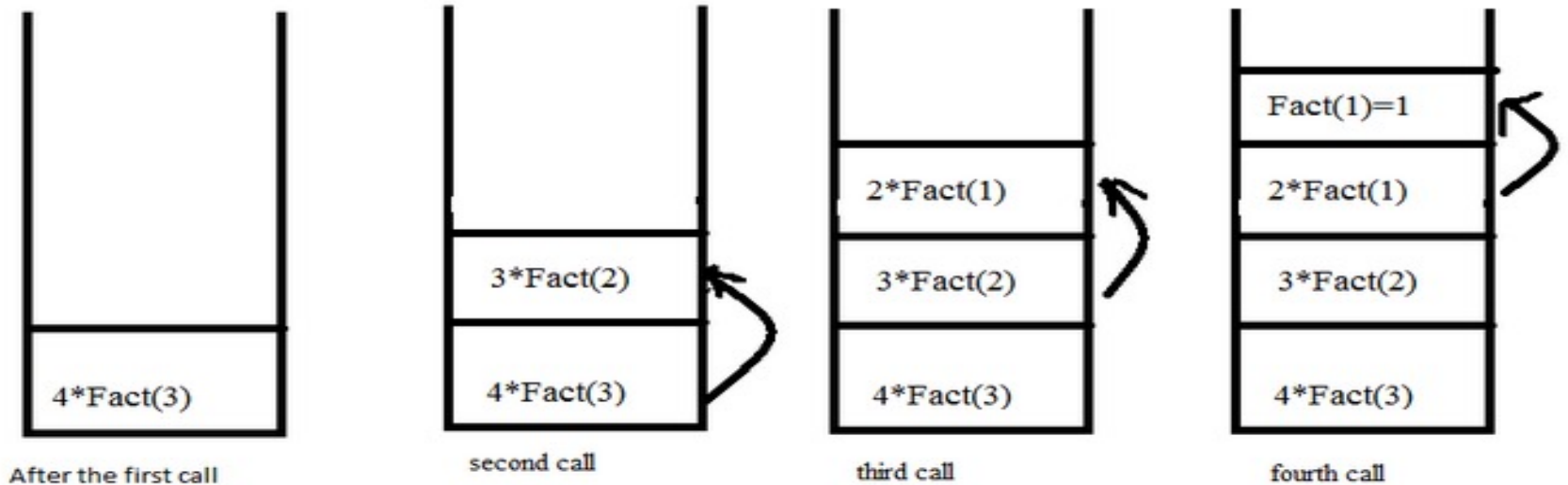
Stack is widely used in implementation of programming systems. For example, compilers employ stacks for keeping track of function calls and execution.

Stack for :

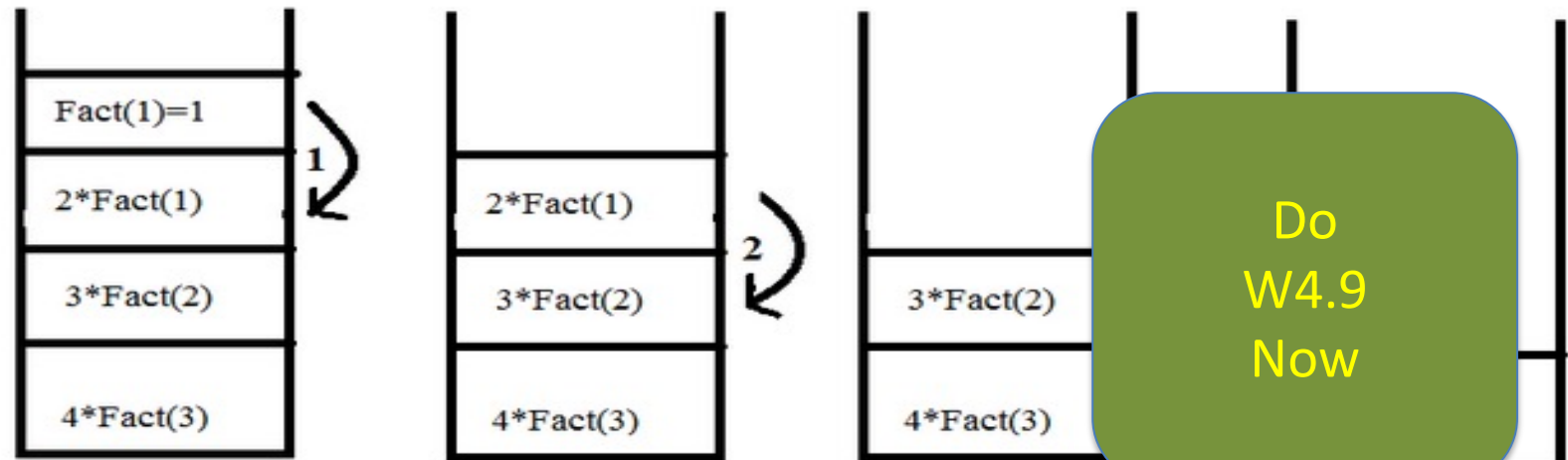
`fact(4)`

```
int fact( int n ) {  
    if ( n<=1 )  
        return 1;  
    return n*fact(n-1);  
}
```

When function call happens previous variables gets stored in stack



Returning values from base case to caller function

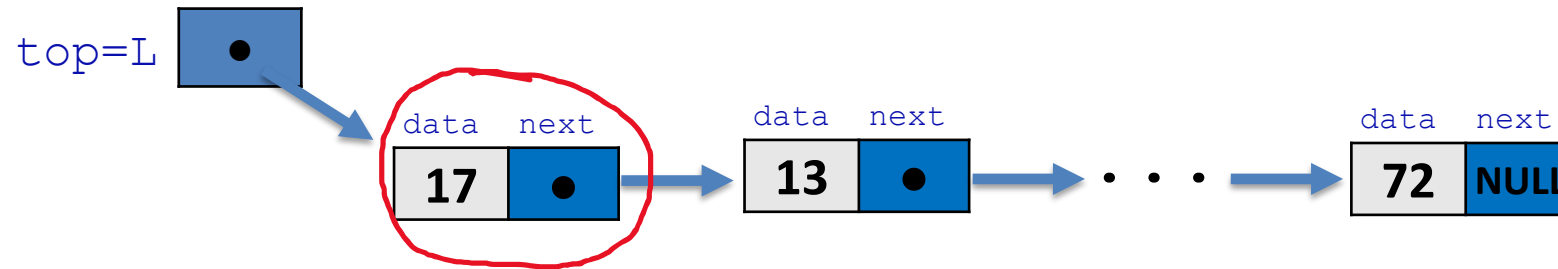


Do
W4.9
Now

Stacks: Implementation using linked lists

push and pop are $O(1)$

Is simpler than using array: no need to worry about size.

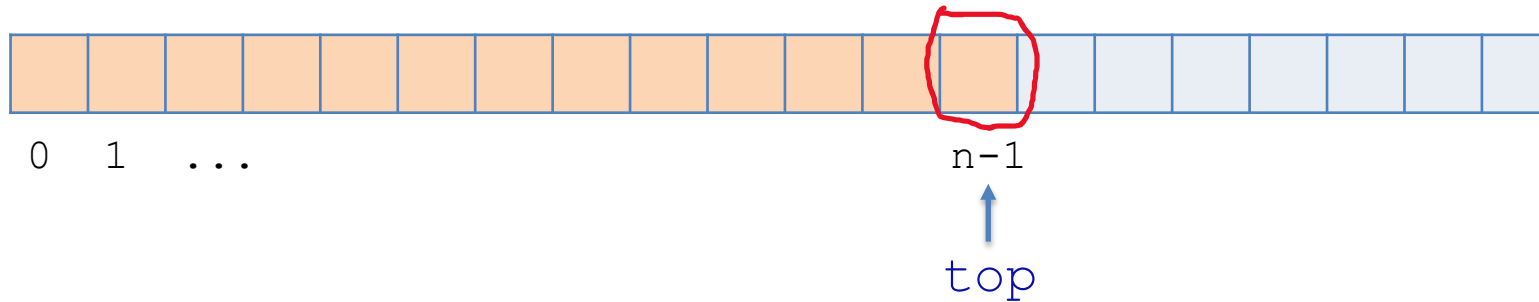


`push(x)` = insert `x` to the start of the list = `listPrepend` : $O(?)$

`pop` = remove (and return) the head of the list = `listDeleteHead` : $O(?)$

Stacks: Implementation using arrays

Should be straight-forward.



`push(x)` = insert `x` to the end of the array = `arrayAppend`: $O(?)$

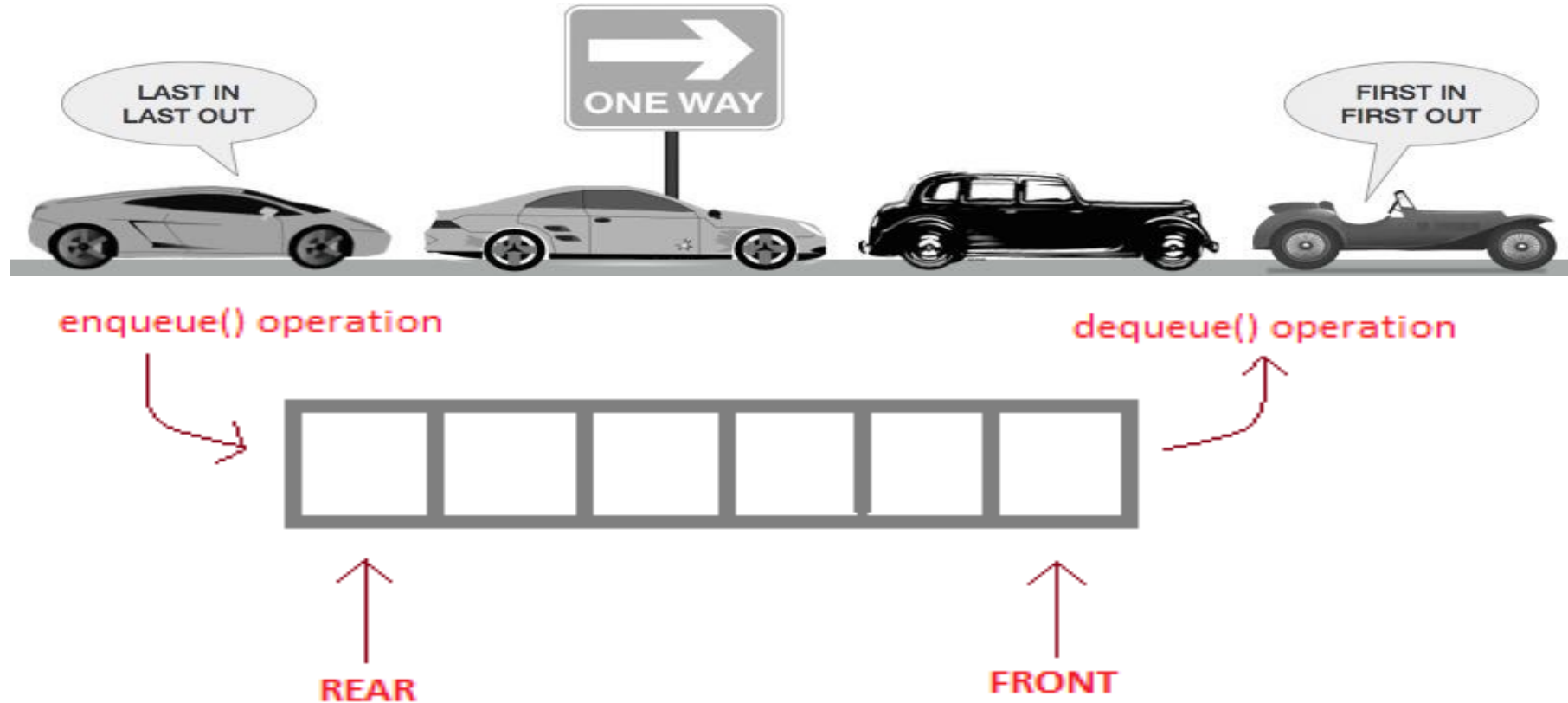
`pop` = remove (and return) the last element of the array: $O(?)$

What is the complexity of `push(x)` in case of:

- using a static array
- using a dynamic array

What about `pop`?

Yet another ADT: Queue (FIFO) = W4.8



Queue Operations

enqueue (x) : add **x** to the rear of the queue

dequeue () : remove (and return) the element at front

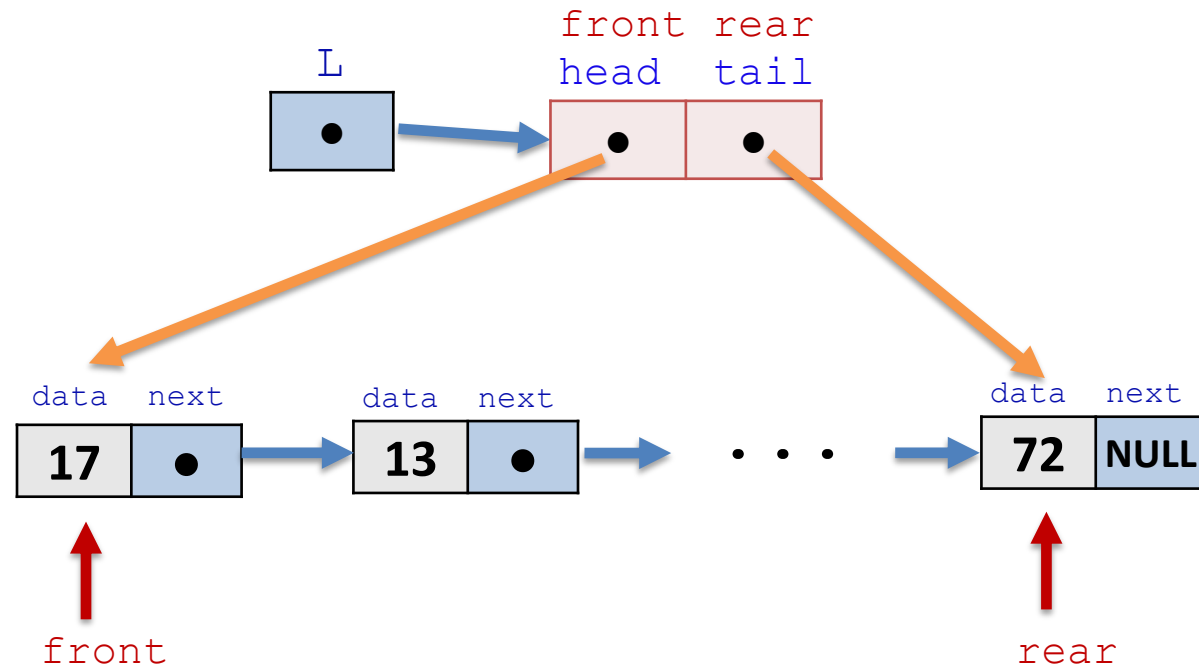
create () : create a new, empty queue

delete () : delete a queue (free all associated memory)

isEmpty () : check if queue is empty, or

size () : return number of elements in queue

Queue: implementation using linked list



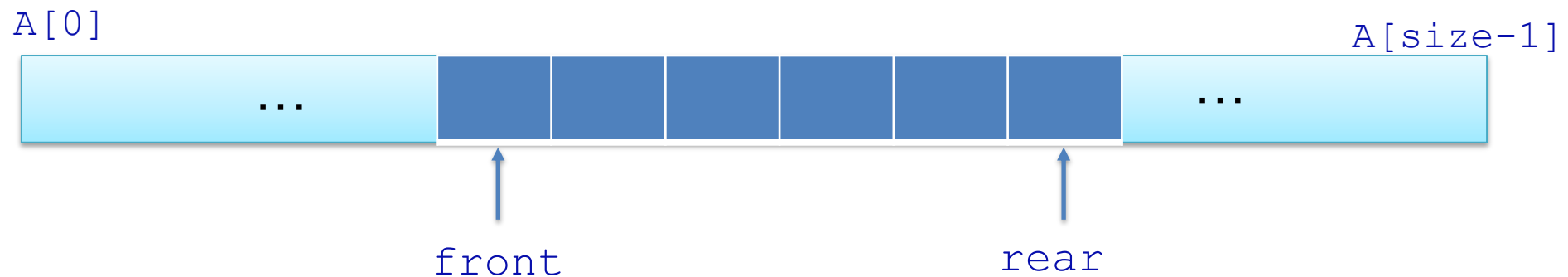
Convenient $O(1)$ for both enqueue and dequeue:

`enqueue == listAppend` (can it be `listPrepend`?)

`dequeue == listDeleteHead` (can it be `listDeleteTail`?)

Queue: implementation using array

Describe how to implement **enqueue** and **dequeue** using an unsorted array, ensuring $\Theta(1)$ for enqueue & dequeue.

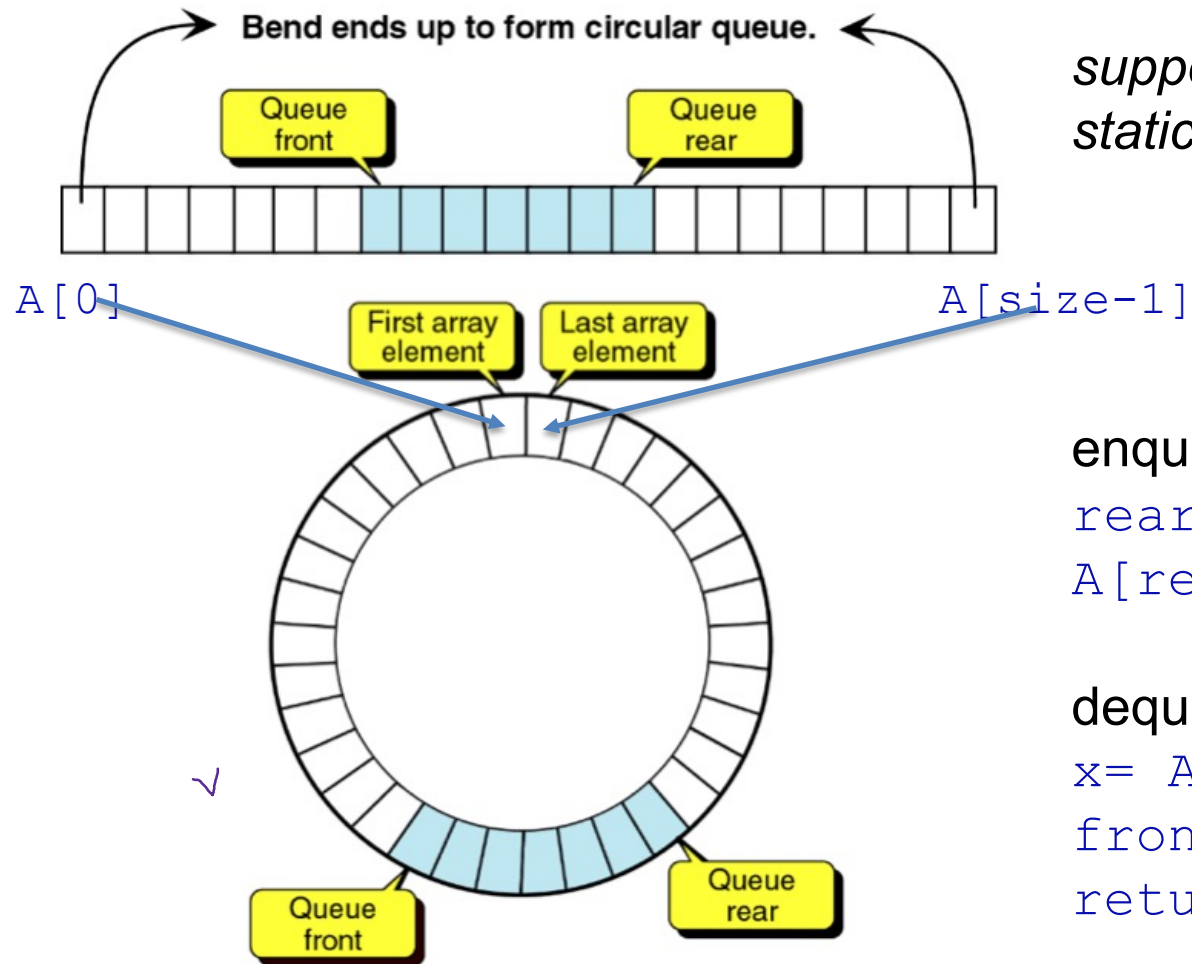


enqueue x : $rear = rear + 1$; $A[rear] = x$;

dequeue: $x = A[front]$; $front = front + 1$; return x ;

any problem?

Queue: using circular arrays



suppose using a big-enough static array

enqueue x:

`rear = rear + 1;` ??

`A[rear] = x;`

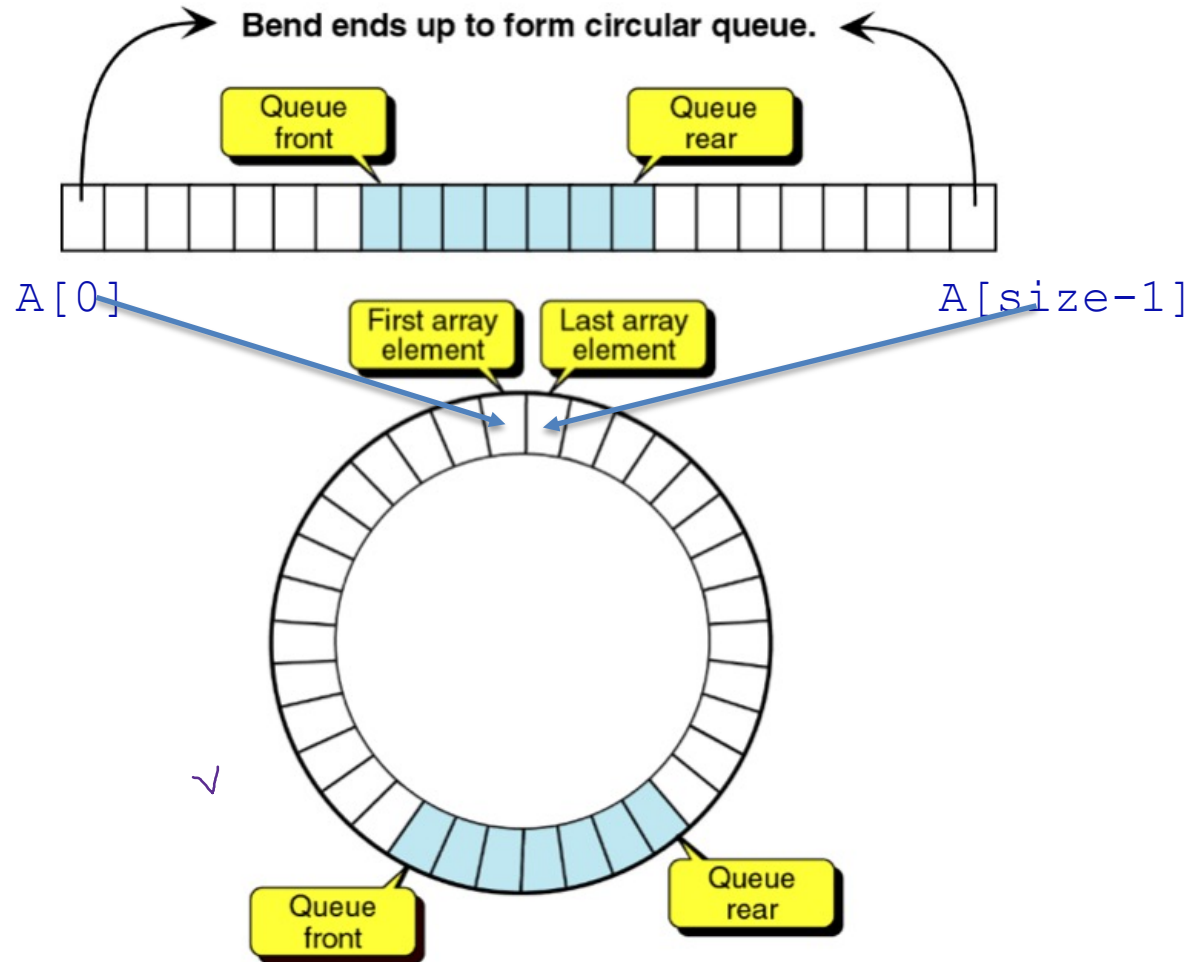
dequeue:

`x = A[front];`

`front = front + 1;` ??

`return x;`

Queue: using circular arrays



suppose using a big-enough static array

enqueue x:

```
rear= (rear+1)%size;  
A[rear]= x;
```

dequeue:

```
x= A[front];  
front= (front+1)%size;  
return x;
```

Finish and/or refine
Assignment 1

If Assignment 1 done:

- [Easy] get all green ticks for
Week 4 Workshop
- Do exercises in
Week 4 Extras