COMP20007 Workshop Week 6

1 | **Topic 1:** DFS & Topological Sorting

Exercise: Q6.1 (toposort)

2 | **Topic 2:** Binary Trees & BST

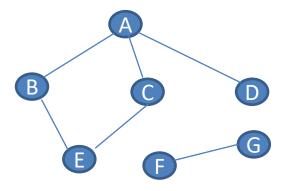
Group/Individual Exercises: Q 6.2, 6.4, 6.3

Lab: **ASSIGNMENT 1**

- Finish ass1 if not yet done, or
- on request: understanding BFS and Prim's, Dijkstra's, other exercises from Week 5 Workshop

DFS revisited: stack mechanism of recursion, time complexity

```
function DFS(G=(V,E))
  for each v in V do
    mark v with 0
  for each v in V do
    if v is marked with 0 then
      DfsExplore(v)
function DfsExplore(v)
  // implicit push at the start
  // start visiting V
  mark v with 1
  for each edge (v,w) in E do
    if w is marked with 0 then
      DfsExplore(w)
  // end visiting V
  // implicit pop at the end
```



Work out Time Complexity

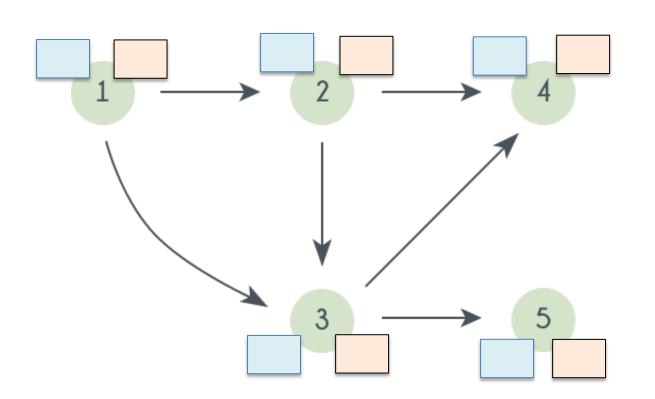
- for graphs with adjacency lists
- for graphs with adjacency matrix

DFS exercise: push- and pop-order (pre- and post-order)

Problem: For the graph below, write the push and pop order for DFS, starting from node 1

Method 1: Fill in the timestamp in yellow boxes for push-orders, pink boxes for pop-orders.

Method 2: Show the stack content and operations.



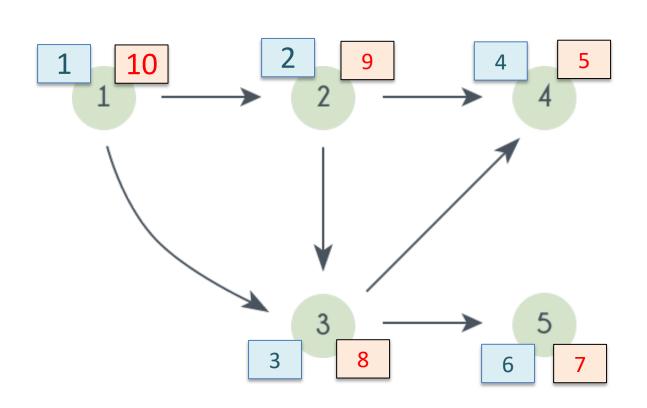
```
The PUSH and POP, using $
for the bottom of stacks.
        stack content
ops
init
push(1)
pop 1
```

Check soln DFS exercise: push- and pop-order (pre- and post-order)

Problem: For the graph below, write the push and pop order for DFS, starting from node 1

Method 1: Fill in the timestamp in yellow boxes for push-orders, pink boxes for pop-orders.

Method 2: Show the stack content and operations.

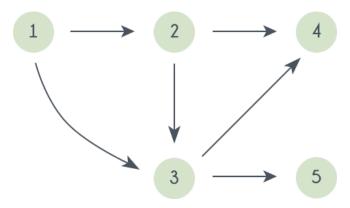


```
The PUSH and POP, using $
for the bottom of stacks.
        stack content
ops
init
push(1)
push(2)
            $12
push(3)
            $123
push(4)
            $1234
            $123
pop 4
push(5)
            $1235
pop 5
            $123
            $12
pop 3
            $1
pop 2
pop 1
```

DFS exercise: push- and pop-order, DFS complexity

Problem: Modify the DFS algorithm so that it also builds the arrays push [V] and pop [V] to store the push- and the pop-order of the vertices.

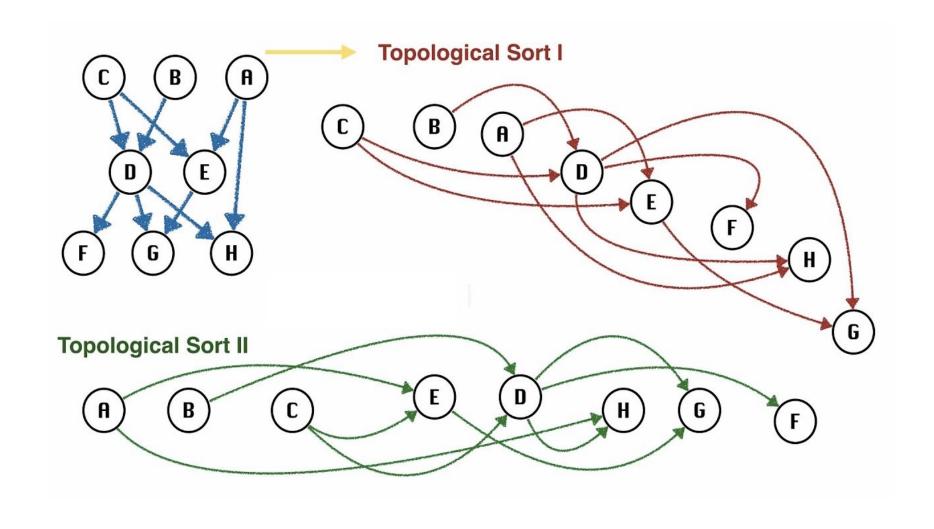
Example graph:



```
// building push[V] and pop[V]
function DFS(G=(V,E))
  for each v in V do
    mark v with 0
  for each v in V do
    if v is marked with 0 then
      DfsExplore(v)
function DfsExplore(v)
  mark v with 1
  for each edge (v,w) in E do
    if w is marked with 0 then
      DfsExplore(w)
```

Topological Sorting (for DAG only!)

A topological ordering: sorting the nodes of the graph such that all edges point in one direction, to nodes later in the ordering.



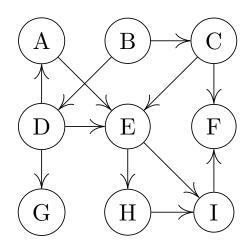
Group Work: Q 6.1

Q6.1: One of the algorithms discussed in lectures involves running a DFS on the DAG and keeping track of the order in which the vertices are popped from the stack. The topological ordering will be the reverse of this order.

→ Finding a topological order for the graph by running a DFS.

The reversed post-order is a topological order!

operation content	operation content
init stack \$ push(A) \$A	

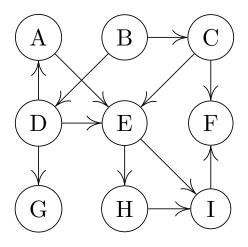


The topological order resulted from the above DFS run:

Check Soln: Q6.1

T1: Finding a topological order for the graph by running a DFS.

operation stack_content	operation	stack_ content
<pre>init stack \$ push (A) \$A push (E) \$AE push (H) \$AEH push (I) \$AEHI push (F) \$AEHIF pop F \$AEHI pop I \$AEH pop H \$AE pop E \$A pop A \$</pre>	push (B) push (C) pop C push (D) push (G) pop G pop D pop B	\$B \$BC \$B \$BD \$BDG \$BD \$B \$\$



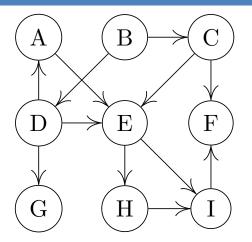
The topological order resulted from the above DFS run (= reversed pop order): B D G C A E H I F you can check by re-draw the graph in the above linear order.

Q 6.1: Discuss other methods for toposort?

Alternative method for Finding a topological order.

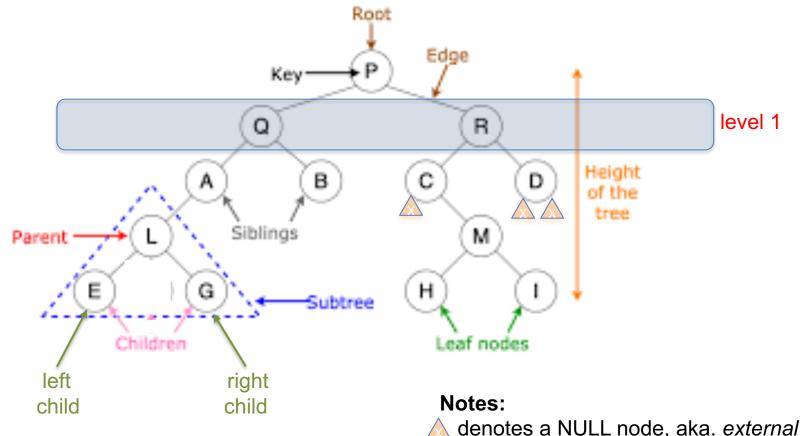
Def: a source node is a node that have no incoming edge.

Algorithm based on source nodes=?



Topic 2

Binary Trees as Special Graphs



denotes a NULL node, aka. external node, only a few of them drawn here. If the tree has n internal nodes, it has n+1 external nodes

Make differences between:

- leaf nodes and external nodes
- none-leaf nodes and internal nodes

Binary Tree: Recursive Definition

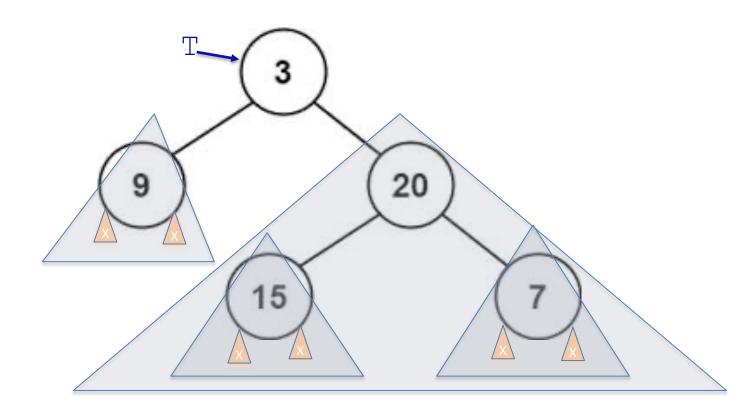
A binary tree is:

- NULL, or
- a node, called the tree's root node, that contains:
 - some data, normally including a key,
 - a link to another binary tree called the root's *left child*, and
 - a link to another binary tree called the root's right child

Side note: a non-empty tree is fully defined by its root. For pseudocode simplicity we use:

tree T = its root node

= pointer to its root node.

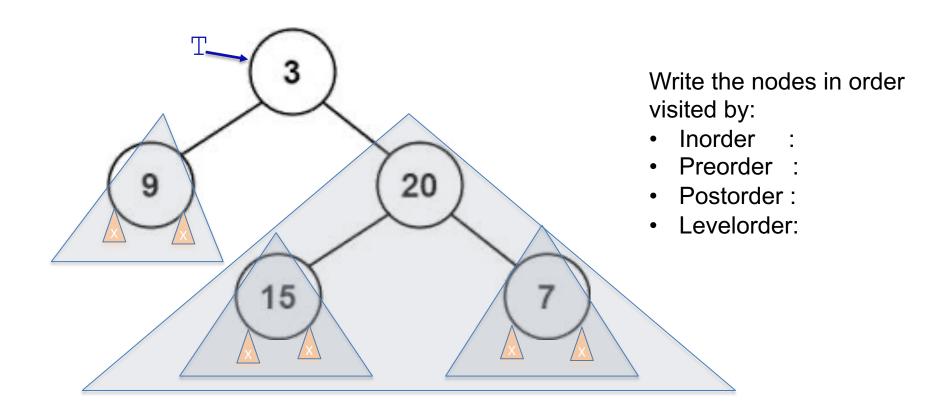


Binary tree traversal

Understand:

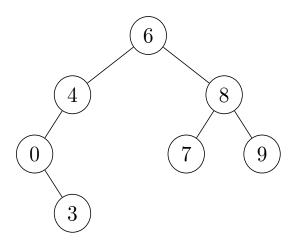
tree traversal?

inorder, *preorder*, *postorder* traversal? Are they BFS or DFS? What is *level-order* traversal? Is it BFS or DFS?



Q 6.4: Binary Tree Sum

Write an algorithm to calculate the sum of a binary tree where each node contains a number.



YOUR ANSWER: The pseudocode: function ???

Binary Search Tree

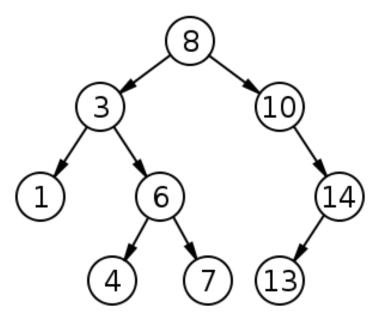
Review: What's a BST?

How to:

- 1. print the keys in increasing order?
- 2. print in decreasing order?
- 3. copy the tree?
- 4. free the tree?

Your answers:

- 1
- 2.
- 3.
- 4.

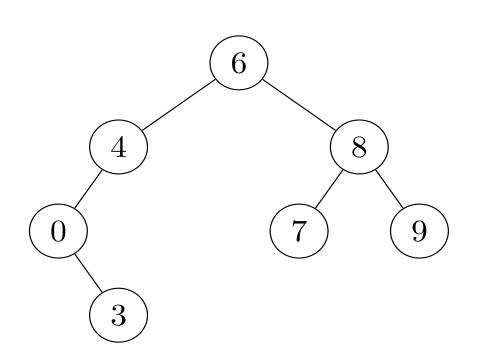


Group/Individual work

Questions 6.2, 6.3.

Q 6.2: conventional traversal

Write the *inorder*, *preorder* and *postorder* traversals of the following binary tree:



YOUR ANSWER:

In-order:

?

Pre-order:

?

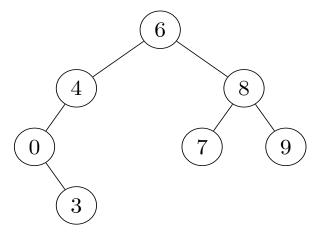
Post-order:

?

Q 6.3: level-order traversal

Level-order: visit level-by-level, left-toright, starting from the root (which is in 0-th level).

- a) For the tree below, what's the visited order?
- b) Write the level-order pseudo-code.



YOUR ANSWER:

a) Level-order: ???

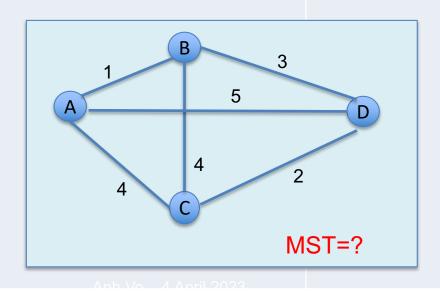
```
// level order traversal for binary tree T
function LevelOrder(T)
```

Prim's Algorithm vs Dijkstra's Algorithm. Discuss concepts

	Prim's	Dijkstra's
Aim	find a MST	find SSSP from a vertex s
Applied to	connected weighted graphs with weights ≥ 0	weighted graphs with weights ≥ 0
Works on directed graphs?	5	
Works on unweighted graph?	?	

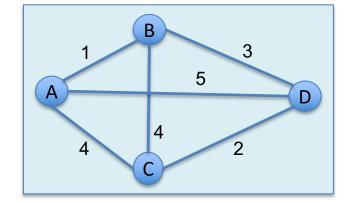
Related concepts for Prim's

- spanning trees = ?
- MST = ?
- is MST unique?



Dijkstra's and Prim's are similar

Dijkstra(G=(V,E),S)	Prim(G=(V,E))
Task: Find SSSP from S (that involves all nodes of a connected graph)	Task: MST (that involves all nodes of a connected graph)
<pre>for each v ∈V do cost[v]:= ∞ prev[v]:= nil cost[S]= 0 PQ:= create_priority_queue(V,cost) with cost[v] as priority of v∈V</pre>	<pre>for each v ∈V do cost[v]:= ∞ prev[v]:= nil pick initial S cost[S]:=0 PQ:= create_priority_queue(V, cost) with cost[v] as priority of v∈V</pre>
<pre>while (PQ is not empty) do u := ejectMin(PQ)</pre>	<pre>while (PQ is not empty) do u := ejectMin(PQ)</pre>
<pre>for each neighbour v of u do if dist[u]+w(u,v) < cost[v] then cost[v]:= cost[u]+w(u,v) update (v, cost[v]) in PQ prev[v]:= u</pre>	<pre>for each neighbour v of u do if w(u,v) < cost[v] then cost[v]:= w(u,v) update (v, cost[v]) in PQ prev[v]:= u</pre>



Running Prim's Algorithm to find a MST

At each step, we add a node to MST.

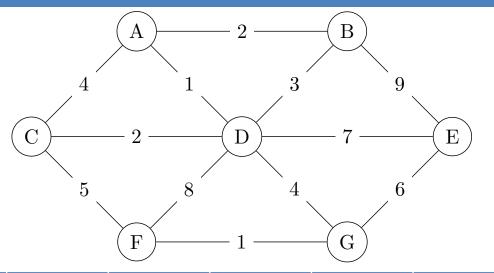
We choose the node with **minimal edge cost**.

We start with A according to the alphabetical order.

step	node added to MST	A	В	С	D
<mark>O</mark>		<mark>0,nil</mark>	∞,nil	∞,nil	∞,nil
<mark>1</mark>					
<mark>2</mark>					
<mark>3</mark>					
<mark>4</mark>					

Question 5.8: Minimum Spanning Tree with Prim's Algorithm

Prim's algorithm finds a minimum spanning tree for a weighted graph. Discuss what is meant by the terms 'tree', 'spanning tree', and 'minimum spanning tree'. Run Prim's algorithm on the graph below, using A as the starting node. What is the resulting minimum spanning tree for this graph? What is the cost of this minimum spanning tree?



step	node done	A	В	С	D	E	F	G
0		0/nil	∞/nil	∞/nil	∞/nil	∞/nil	∞/nil	∞/nil
1								
2								
3								
4								
5								
6								
7								

LAB

Questions on Dijkstra's and BFS?

Assignment 1:

- do assignment 1 if not yet done
- make sure that you can finish on time
- note that you can discuss general problems with your friends but please do not reveal or show your solution and code

OR:

do/ask_questions_on not-yet-done problems (if any) of previous workshops/lab/lectures

Additional Slides

How to use valgrind in Ed to check for possible bugs?

When opening a programming terminal. Now, suppose you want to run problem2a with input data test_cases/2a-1.txt, you normally do with:

```
make problem2a
./problem2a <test_cases/2a-1.txt</pre>
```

Now, if you want to test with valgrind, just run:

```
valgrind -leak-check=full ./problem2a <test_cases/2a-1.txt</pre>
```

valgrind will give some output. If at the end of the output, you see lines:

```
==??== All heap blocks were freed -- no leaks are possible
==??== ERROR SUMMARY: 0 errors from 0 contexts (suppressed: 0 from 0)
```

then your probably doesn't have bugs (well, you need to check for correctness yourself). Otherwise, you need to scroll up and look at the start of the valgrind output, you will see valgrind reports some line numbers from some • C files that might cause problems. Only solve the first error, then try valgrind again.

Short intro to valgrind:

- https://epitech-2022-technical-documentation.readthedocs.io/en/latest/valgrind.html
- https://zoo.cs.yale.edu/classes/cs323/doc/Valgrind

Q5.6: Finding Cycles – do in group of 2-3

a) Explain how one can use BFS to see whether an undirected graph is cyclic.

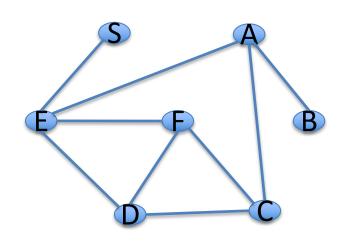
```
Transform function BFS to:
    isCyclic(G=(V,E))
```

b) Can we use DFS for the task? Which one is better: DFS or BFS?

BFS algorithm – as in lecture

```
function BFS (G = (V, E))
  mark each node in V with 0
  Q := empty queue
  for each v in V do
    if v is marked with 0 then
      mark v with 1
      INJECT (Q, \forall)
      while \bigcirc \neq \emptyset do
         u := EJECT(Q)
         for each edge (u,w) do
         if w is marked with 0 then
           mark w with 1
           INJECT (Q, W)
```

5.7: 2-Colourability – do in group of 2-3



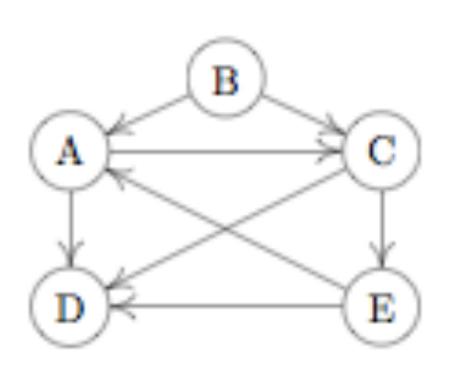
Design an algorithm to check whether an undirected graph is 2-colourable, that is, whether its nodes can be coloured with just 2 colours in such a way that no edge connects two nodes of the same colour.

To get a feel for the problem, try to 2-colour the following graph (start from **S**).

Do you expect we could extend such an algorithm to check if a graph is 3-Colourable, or in general: k-Colourable?

```
// transform this to is2Colorable
function DFS(G=(V,E))
  mark each node in V with 0
  for each v in V do
    if v is marked with 0 then
      DfsExplore(v)
function DFsExplore(v)
  mark v with 1
  for each edge (v,w) do
    if w is marked with 0 then
      DfsExplore(w)
// Can we use BFS?
```

Q5.5: Tree, Back, Forward and Cross Edges



A DFS of a di-graph can be represented as a collection of trees. Each edge of the graph can then be classified as a tree edge, a back edge, a forward edge, or a cross edge. A tree edge is an edge to a previously un-visited node, a back edge is an edge from a node to an ancestor, a forward edge is an edge to a non-child descendent and a cross edge is an edge to a node in a different sub-tree (i.e., neither a descendent nor an ancestor)

Draw a DFS tree based on the following graph, and classify its edges into these categories.

In an undirected graph, you wont find any forward edges or cross edges. Why is this true? You might like to consider the graph above, with each of its edges replaced by undirected edges.