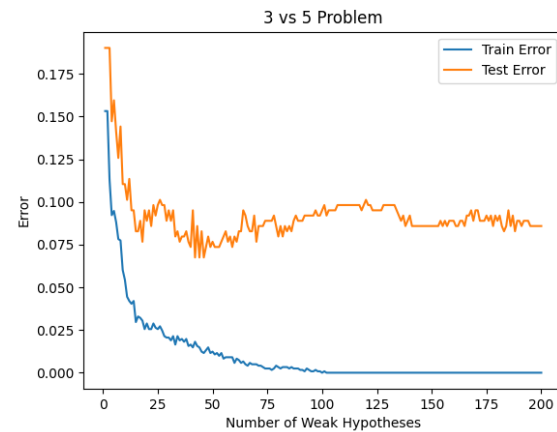
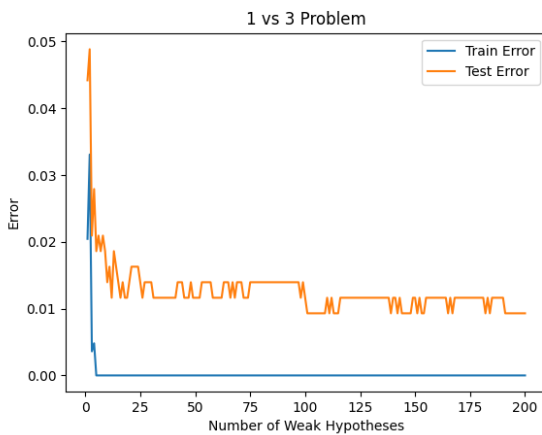


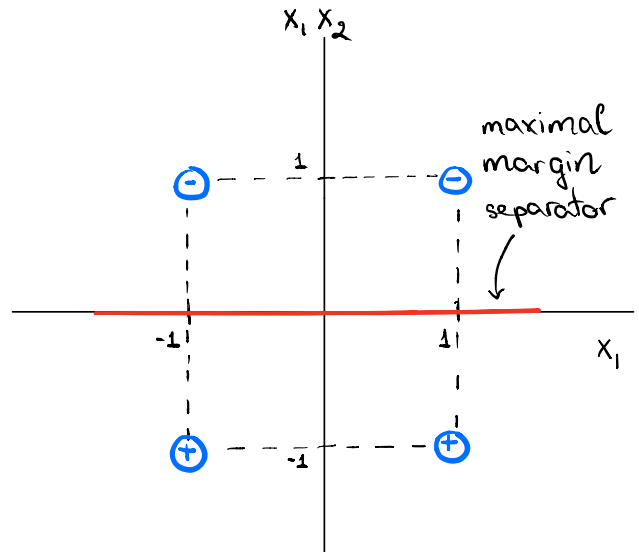
1,



As the number of weak hypothesis increases, both train & test error decreases for both 1 vs 3 and 3 vs 5 Problems. As I have concluded from previous homework and the 2 above graphs, 3 vs 5 problem seems to be more difficult to classify since its test error is higher compared to the 1 vs 3 Problem. I noticed that in both problems, when number of weak hypothesis increases, train error reaches 0 and stay 0 and test error sometimes goes up (especially in the 3 vs 5 Problem) so it seems like Adaboost is overfitting as the number of weak learners increases.

2,

x_1	x_2	$x_1 x_2$	$XOR(x_1, x_2)$
+1	+1	+1	-1
+1	-1	-1	+1
-1	+1	-1	+1
-1	-1	+1	-1

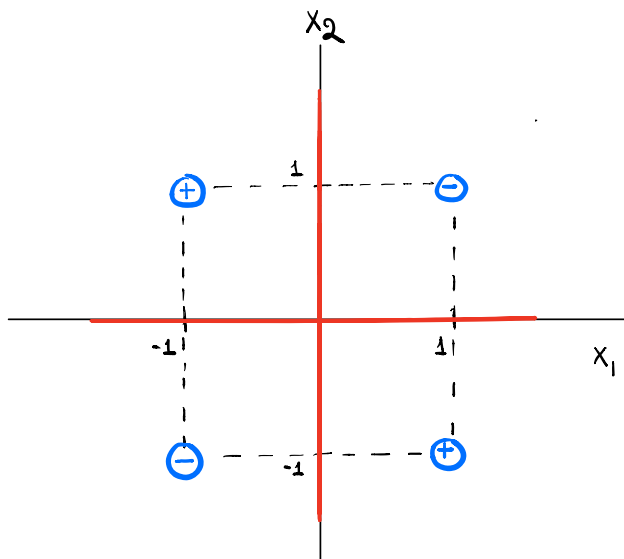


↳ Margin = 1

Linear separator : $h(\vec{x}) = \text{sign}(\vec{w}^T \vec{x}) = \text{sign}(-x_1 x_2)$

We can observe that $x_1 x_2 = 0$ (horizontal separator)

$$\hookrightarrow \begin{cases} x_1 = 0 \\ x_2 = 0 \end{cases}$$



3,

$$\begin{aligned}d(\phi(\vec{x}_i), \phi(\vec{x}_j)) &= (\phi(\vec{x}_i) - \phi(\vec{x}_j))^T (\phi(\vec{x}_i) - \phi(\vec{x}_j)) \\&= (\phi(\vec{x}_i)^T - \phi(\vec{x}_j)^T) (\phi(\vec{x}_i) - \phi(\vec{x}_j)) \\&= \phi(\vec{x}_i)^T \phi(\vec{x}_i) - \phi(\vec{x}_i)^T \phi(\vec{x}_j) - \phi(\vec{x}_j)^T \phi(\vec{x}_i) + \phi(\vec{x}_j)^T \phi(\vec{x}_j) \\&= \phi(\vec{x}_i)^T \phi(\vec{x}_i) - 2\phi(\vec{x}_i)^T \phi(\vec{x}_j) + \phi(\vec{x}_j)^T \phi(\vec{x}_j) \\&= K(\vec{x}_i, \vec{x}_i) - 2K(\vec{x}_i, \vec{x}_j) + K(\vec{x}_j, \vec{x}_j)\end{aligned}$$

4,

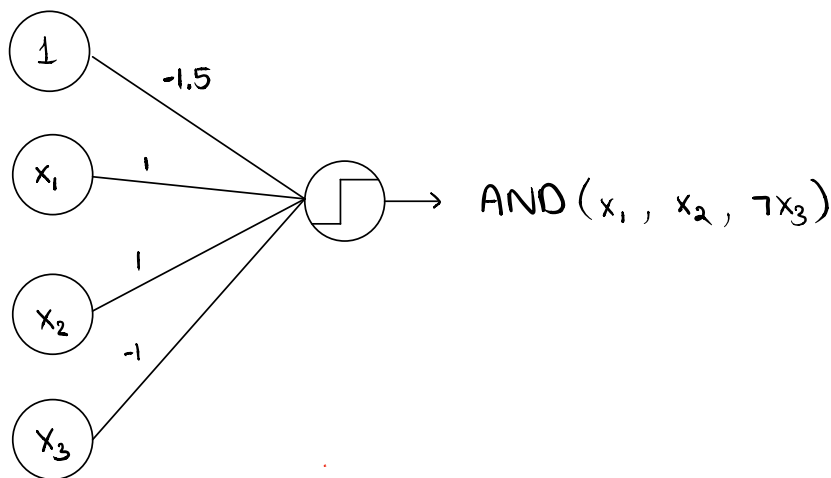
$$\text{XOR}((x_1 \wedge x_2), x_3)$$

$$= ((x_1 \wedge x_2) \wedge \neg x_3) \vee (\neg(x_1 \wedge x_2) \wedge x_3)$$

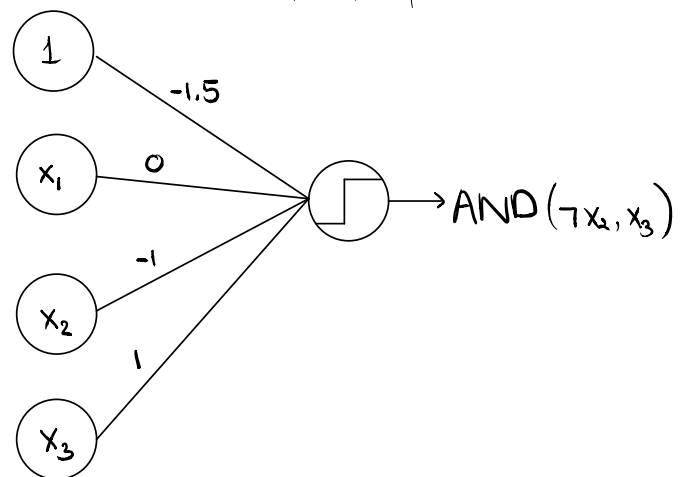
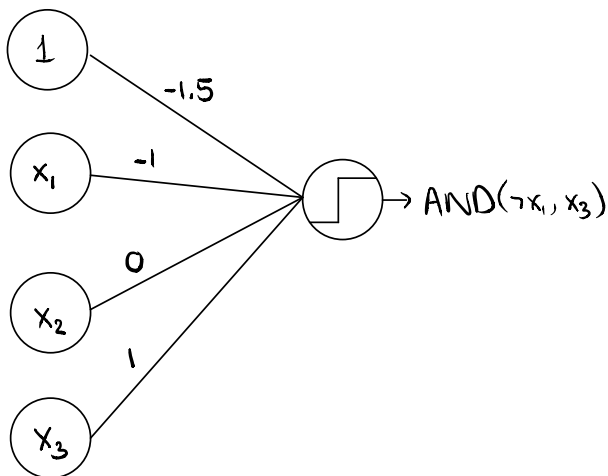
$$= (x_1 \wedge x_2 \wedge \neg x_3) \vee ((\neg x_1 \vee \neg x_2) \wedge x_3)$$

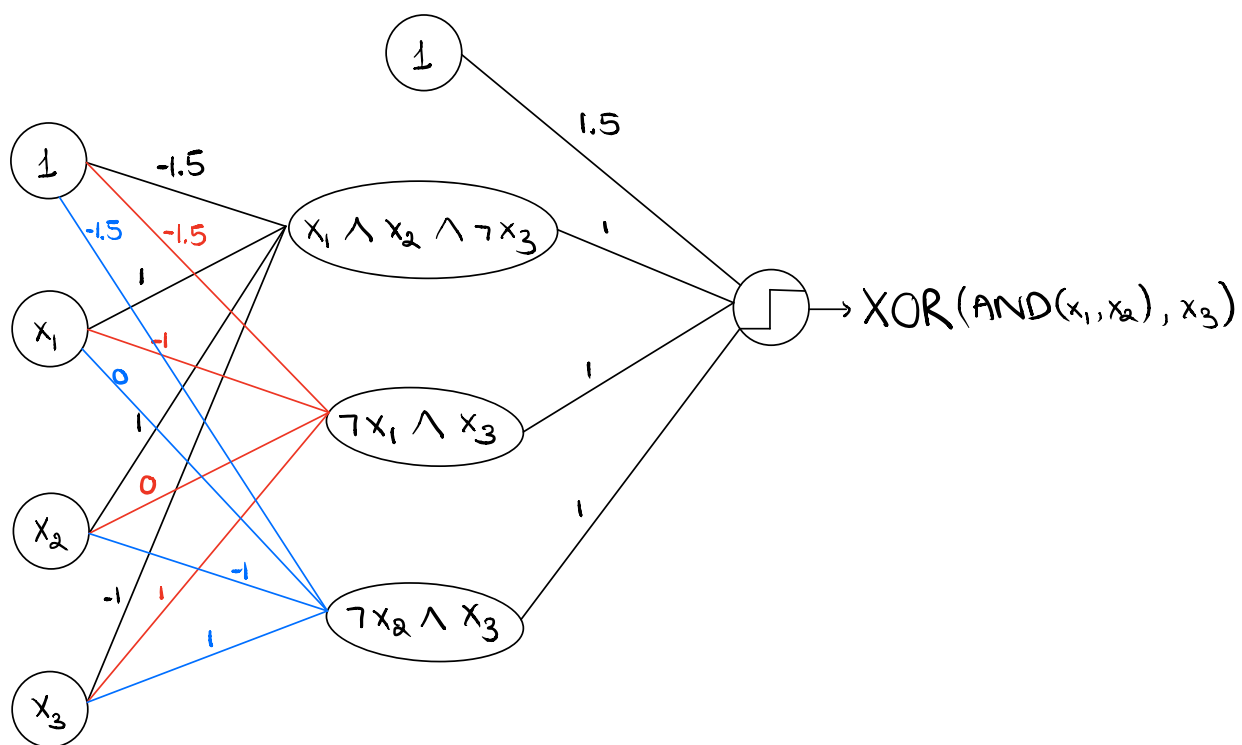
$$= (x_1 \wedge x_2 \wedge \neg x_3) \vee (\neg x_1 \wedge x_3) \vee (\neg x_2 \wedge x_3)$$

↳ 4 units in the hidden layer ($1, x_1 \wedge x_2 \wedge \neg x_3, \neg x_1 \wedge x_3, \neg x_2 \wedge x_3$)



x_1	x_2	x_3	$x_1 \wedge x_2 \wedge \neg x_3$
+	+	+	-
+	+	-	+
+	-	+	-
+	-	-	-
-	+	+	-
-	+	-	-
-	-	+	-
-	-	-	-





5, LFD Problem 7.10

If all weights are set to 0

$$\hookrightarrow W^{(l)} = 0, \quad l = 1, \dots, L$$

$$\Rightarrow s^{(l)} = (W^{(l)})^T x^{(l-1)} = 0$$

$$x^{(l)} = \theta(s^{(l)}) = \theta(0) = \tanh(0) = 0$$

$$\Rightarrow \frac{\partial e}{\partial W^{(l)}} = x^{(l-1)} (\delta^{(l)})^T = 0 \quad \text{for } l = 2, \dots, L$$

$$\text{at } l=1 \rightarrow \delta^{(1)} = \sum_{k=1}^{d^{(2)}} \underbrace{w_{jk}^{(2)}}_{=0} \delta_k^{(2)} \theta'(s_j^{(1)}) = 0 \quad \forall j$$

$$\Rightarrow \frac{\partial e}{\partial W^{(1)}} = 0 \quad \Rightarrow \quad \frac{\partial e_n}{\partial W^{(1)}} = 0 \quad \text{for } l = 1, \dots, L$$

\therefore It is not a good idea to initialize the weights to zero

since the weights remain unchanged after each

$$\text{iteration } (W^{(l)} \leftarrow W^{(l)} - \eta \underbrace{\frac{\partial e_n}{\partial W^{(l)}}}_{=0} = W^{(l)})$$