DSGE- OSE Bootcamp 2019

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Contains answers to the exercises on DSGE (Part-2 & 3), taught by Kerk Phillips as a part of the OSE Lab Summer Camp 2019.

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1 Homework 2

Exercise 3 (Dynamic Behavior)

We do the necessary matrix algebra here to transform

$$E_t[F\tilde{X}_{t+1} + G\tilde{X}_t + H\tilde{X}_{t-1} + L\tilde{Z}_{t+1} + M\tilde{Z}_t] = 0$$
(1)

into

$$[(FP+G)P+H]\tilde{X}_{t-1} + [(FQ+L)N + (FP+G)Q+M]\tilde{Z}_t$$
 (2)

By observation, we can see that eq.(2) is expressed in \tilde{X}_{t-1} and \tilde{Z}_t . We substitute in eq.(1) the expression for \tilde{X}_{t+1} and \tilde{Z}_{t+1} .

$$E_t[F\tilde{X}_{t+1} + G\tilde{X}_t + H\tilde{X}_{t-1} + L\tilde{Z}_{t+1} + M\tilde{Z}_t] = 0$$
(3)

$$E_{t}[F(P(P\tilde{X}_{t-1} + Q\tilde{Z}_{t}) + Q(N\tilde{Z}_{t} + \epsilon_{t+1})) + G(P\tilde{X}_{t-1} + Q\tilde{Z}_{t}) + H\tilde{X}_{t-1} + L(N\tilde{Z}_{t-1} + \epsilon_{t}) + M\tilde{Z}_{t}] = 0$$
(4)

$$[(FP+G)P+H]\tilde{X}_{t-1} + [(FQ+L)N + (FP+G)Q+M]\tilde{Z}_t = 0$$
(5)

2 Homework 3

Exercise 1 (Perturbation Methods)

We differentiate expression (5) involving terms with F(x,u) with respect to u and find,

$$x_{uuu} = -\frac{F_{uuu} + F_{xxx}x_u^3 + 3(F_{xxu}x_u^2 + F_{uux}x_u + F_{xu}x_{uu} + F_{xx}x_ux_{uu})}{F_x}$$
(6)

where the derivative is evaluated at u_0 , $x(u_0)$.