Parking Lot Vacancy Detector – Report

1. Creating training dataset

- Utilised the xml ElementTree parser for parsing the given xml file.
- Located the directory containing training images(.jpg) and corresponding xml file.
- Extracted the individual elements of the xml file like id, occupied status, individual coordinate point for the location of various cars in the form of (x,y) to generate positive training images.
- Generated positive training images by cropping the actual generated image based on the ground truth file

Example:

Coordinates from the ground truth file(*.xml)

• The cropping is done to the scale of 5 along x axis and to the scale of 10 along y axis

crop_img = img[ymin-10:ymax+10, xmin-5:xmax+5]



<u>Cropped Positive training images</u>: Total number = 1,84,000



Downloaded the negative images dataset from the internet

Negative training images: Total number = 90,000



- Saved the cropped positive training images to a separate folder and the negative training images to a separate folder.
- Created 2 files namely "bg.txt" and "info.dat" containing the path of all the positive and negative training images.

```
hegative_training_images\negative0.jpg
negative_training_images\negative1.jpg
negative_training_images\negative10.jpg
negative_training_images\negative10.jpg
negative_training_images\negative100.jpg
negative_training_images\negative100.jpg
negative_training_images\negative1000.jpg
negative_training_images\negative1000.jpg
negative_training_images\negative1000.jpg
negative_training_images\negative1000.jpg
negative_training_images\negative1000.jpg
negative_training_images\negative1000.jpg
negative_training_images\negative10000.jpg
negati
```

• Created *.vec file containing nearly 80,000 samples of positive images using the command:

opencv_createsamples -info info.dat -vec positive3.vec -num 80000 -w 24 -h 24

2. Training the cascade classifier

• Now we train the classifier using the following command:

```
opencv_traincascade -data trial "folder" -vec pos.vec -bg bg.txt -
numPos " " -numNeg " " -numStages " " -featureType LBP/HAAR
-w 24 -h 24
```

Sample training scenarios

- A. Training Data 1:
 - Number of Positive samples 45,000(initial value)
 - Number of Negative samples 50,000
 - Number of stages 10
 - Feature Type LBP
- B. Training Data 2:
 - Number of Positive samples 2,700(initial value)
 - Number of Negative samples 3,000
 - Number of stages 5
 - Feature Type HAAR

C. Training Data -3:

- Number of Positive samples 67,500(initial value)
- Number of Negative samples 75,000
- Number of stages 10
- Feature Type LBP

D. Training Data-4:

- Number of Positive samples 9,000(initial value)
- Number of Negative samples 10,000
- Number of stages 8
- Feature Type HAAR

3. Car detection and Accuracy

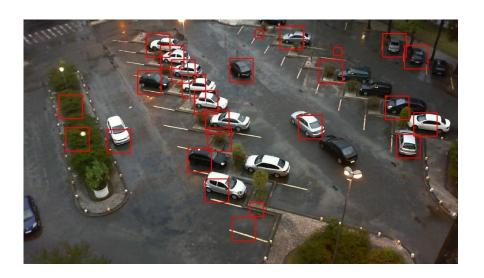
- Now after training phase, **cascade**(.xml) file is generated along with various stages as per the command
- Test images are the ones from rainy or cloudy folders as given before.
- Written a python file testing.py in which the testing image is loaded and passed to CascadeClassifier::detectMultiScale()
- Now the function **CascadeClassifier::detectMultiScale()** contains parameters like:
- **Note**: ALL parameters used are subject to each individual image.
 - I. scaleFactor tried between 1.1 and 1.9
 - II. minNeighbors tried from 6 to 20
 - III. minSize = (20,20)
 - IV. maxSize = (75,75)
- For detecting cars, I have retrieved the corresponding xml file of the passed testing image
- The function **CascadeClassifier::detectMultiScale()** returns a list of 4 elements [x,y,w,h]

- Initially extracted the "X", "Y" points from the corresponding ".xml" file
- Now generated 4 values Xmin, Xmax, Ymin, Ymax from a pre defined list containing above "X" and "Y"
- Calculated the area of bounding rectangle from xml file and also the area of detected rectangle.
- In order to associate these 2 rectangles for detection, used the midpoint of bounded rectangle.
- Now initialised a **threshold** value(default=60) and checked whether the ratio of the above calculated areas falls above the threshold.
- If yes, then it is a True Positive and else it is a False positive.

$$Accuracy = (TP + TN) / (TP + FP + TN + FN)$$

4. Results and Parking lot analysis

I. Pos_samples = 45k, neg_samples = 50k, LBP, stages = 10



Number of cars detected: 17

Number of vacant spots detected: 23

II. Pos_samples = 2.7k, neg_samples = 3k, HAAR, stages =5



Number of cars detected: 26

Number of vacant spaces detected: 14

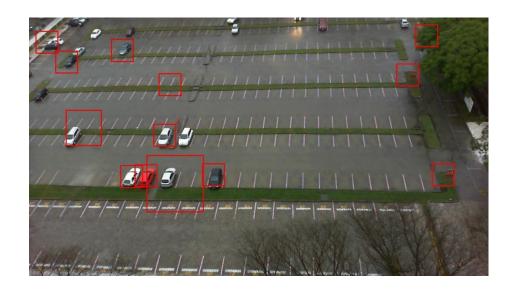
III. Pos_samples = 67.5k, neg_samples = 75k, LBP, stages =10



Number of cars detected: 81

Number of vacant spaces detected: 19

IV. Pos_samples = 9k , neg_samples = 10k , HAAR , stages =8



Number of cars detected: 10

Number of vacant spaces detected: 88

Test Image	Classifier	Training			TP	FP	Accuracy
	Feature						
		Stages	No. of	No. of			
			Positives	Negatives			
2013-04- 12_17_55_13.jpg	LBP	10	45k	50k	17	23	85.0
2013-02- 26_13_04_33.jpg	HAAR	5	2.7k	3k	26	0	65.0
2012-11- 10 11 12 51.jpg	LBP	10	67.5k	75k	81	19	93.0
2012-09- 21 07 05 12.jpg	HAAR	8	9k	10k	12	16	92.0
2012-12- 12 10 00 05.jpg	HAAR	5	2.7k	3k	18	0	64.2
2012-12- 08 18 25 14.jpg	HAAR	8	9k	10k	0	6	78.5
2012-12- 22 12 00 08.jpg	HAAR	5	2.7k	3k	1	4	85.7
2012-12- 22 12 00 08.jpg	HAAR	8	9k	10k	1	5	82.2
2013-01- 18_17_05_13.jpg	HAAR	5	2.7k	3k	4	4	82.0
2013-01- 18 17 05 13.jpg	HAAR	8	9k	10k	0	0	82.0
2013-03- 05_08_20_02.jpg	HAAR	5	2.7k	3k	24	0	60.0
2013-03- 05 08 20 02.jpg	HAAR	8	9k	10k	29	0	72.5
2013-03- 19_07_25_01.jpg	HAAR	5	2.7k	3k	18	8	65.0

2013-03-	11000	0	OL:	401.	1.0	_	75.0
19_07_25_01.jpg	HAAR	8	9k	10k	16	2	75.0
2012-12- 17_09_50_05.jpg	HAAR	5	2.7k	3k	17	0	60.7
2012-12- 14_09_20_04.jpg	HAAR	8	9k	10k	21	0	75.0
2012-12- 08 18 25 14.jpg	HAAR	5	2.7k	3k	0	0	100.0
2012-12- 08_19_30_16.jpg	HAAR	8	9k	10k	0	0	100.0
2013-01- 16_09_05_04.jpg	HAAR	5	2.7k	3k	1	3	85.7
2013-01- 16_11_15_07.jpg	HAAR	8	9k	10k	9	6	75.0
2013-02- 26_13_19_33.jpg	HAAR	5	2.7k	3k	23	0	60.0
2013-02- 26_13_19_33.jpg	HAAR	8	9k	10k	33	0	85.0
2012-09- 12_10_11_12.jpg	HAAR	5	2.7k	3k	59	4	60.0
2012-09- 12_10_16_27.jpg	HAAR	8	9k	10k	82	0	87.0
2012-10- 11_07_36_48.jpg	HAAR	5	2.7k	3k	12	14	74.0
2012-10- 11_07_41_49.jpg	HAAR	8	9k	10k	21	6	80.0
2012-11- 11_12_49_03.jpg	HAAR	8	9k	10k	3	4	96.0
2012-11- 11_12_54_03.jpg	LBP	10	45k	50k	4	1	99.0
2012-11- 11_12_44_02.jpg	LBP	10	67.5k	75k	2	3	97.0
2013-01- 17_07_50_03.jpg	LBP	10	45k	50k	0	1	96.4
2013-01- 17 07 55 03.jpg	LBP	10	67.5k	75k	0	2	92.8
2012-11- 08 07 05 26.jpg	LBP	10	45k	50k	8	4	96.0
2012-12- 07_16_42_25.jpg	LBP	10	67.5k	75k	24	0	92.8
2012-12- 15 07 30 02.jpg	LBP	10	45k	50k	0	2	92.2
2012-12- 15 07 35 02.jpg	LBP	10	67.5k	75k	0	1	96.4
2012-10- 26_06_59_26.jpg	LBP	10	45k	50k	4	0	93.0
2012-10- 26_07_04_26.jpg	LBP	10	67.5k	75k	13	0	99.0
2012-10- 26_09_14_33.jpg	LBP	10	45k	50k	95	0	99.0
2012-10- 26_09_19_33.jpg	LBP	10	67.5k	75k	86	0	90.0
2012-10- 28 06 31 45.jpg	LBP	10	45k	50k	1	0	100.0
2012-10- 28_06_36_45.jpg	LBP	10	67.5k	75k	1	0	100.0
2012-09- 28_17_26_29.jpg	LBP	10	45k	50k	53	0	90.0
2012-09- 28_17_31_29.jpg	LBP	10	67.5k	75k	49	8	80.0
2012-09- 28 17 56 30.jpg	LBP	10	45k	50k	31	2	81.0
2012-09- 28_18_01_30.jpg	LBP	10	67.5k	75k	46	1	97.0
2012-11- 09 11 56 47.jpg	LBP	10	67.5k	75k	56	2	88.0
	<u> </u>	<u> </u>	<u> </u>	<u> </u>			<u> </u>

2012-11-	LBP	10	7.2k	8k	39	1	79.0
09_12_06_47.jpg			7.21	O.K	9	_	7 3.0
2013-01-	LBP	10	7.2k	8k	21	2	78.5
22_12_40_08.jpg	LDI	10	7.ZK	OK .	21)	70.5
2013-03-	LBP	10	7.2k	8k	27	1	70.0
13_13_05_08.jpg	LDI	10	7.ZK	OK	21	_	70.0
2012-11-	LBP	10	7.2k	8k	63	Λ	75.0
10_11_12_51.jpg	LDF	10	/ . Z N	OK	U.S	U	75.0