# HPCSE II - Exercise 4

#### Anian Ruoss

April 25, 2019

## Task 1

As in Task 2 of Part 2 of Homework 3, we use the head2DSolver to model the temperature distribution on the steel sheets. For every torch we want to determine the optimal beam width, beam intensity and x- and y-coordinates meaning that we have 16 parameters in total for the 4 robotic torches. For all parameters we know the upper and the lower bounds given by:

- $x \in [0.0, 0.5]$  for torches 1 and 2
- $x \in [0.5, 1.0]$  for torches 3 and 4
- $y \in [0.0, 1.0]$  for all torches
- beam intensity  $\in [0.4, 0.6]$  for all torches
- beam width  $\in [0.04, 0.06]$  for all torches

Since we do not have any additional information about the parameter distributions, we model all parameters as being uniformly distributed within their respective bounds. We employ Korali's CMA-ES solver to maximize the posterior distribution of the parameters (even though we don't really have informative prior distributions, but the posterior was given in the template) to find the most likely parameter values and we display the results in Listing 1.

Listing 1: Korali output when maximizing the posterior distribution of the parameters for the model with four robotic torches.

```
Parameter 'torch_1_width' Value: 0.046153
Koralil
                                'torch_1_width' Value: 0.046153
'torch_2_x' Value: 0.251464
'torch_2_y' Value: 0.741347
'torch_2_intensity' Value: 0.479662
'torch_2_width' Value: 0.051501
              Parameter
Korali
Korali
              Parameter
Korali
              Parameter
              Parameter
Korali
                                'torch_3_x' Value: 0.757994
'torch_3_y' Value: 0.254470
'torch_3_intensity' Value: 0.474
'torch_3_width' Value: 0.054619
Korali
              Parameter
Korali
              Parameter
Korali
              Parameter
Korali
              Parameter
                                'torch_4_x' Value: 0.760434
'torch_4_y' Value: 0.770577
'torch_4_intensity' Value: 0.478
'torch_4_width' Value: 0.059926
Korali
              Parameter
Korali
               Parameter
Korali
              Parameter
                                                                     Value: 0.475872
              Parameter
Korali
              Total Elapsed Time: 234.156253s
```

Korali performs the optimization in roughly 4 minutes. We know from the lecture that CMA-ES is embarrassingly parallel since we can compute and evaluate every sample independently, which can be achieved by parallelizing the two for-loops at lines 11 and 14. Typically the evaluation is a lot more costly than random number generation, which is why we should already observe a considerable speedup from only parallelizing the loop at line 14.

### Task 2

We run the single tasking engine and display its output in Listing 2.

Listing 2: Output from executing the single tasking engine.

```
Processing 240 Samples each with 2 Parameter(s)...
Verification Passed
Total Running Time: 29.717s
```

a)

Since all samples are well-known at the beginning, they can be distributed evenly among all ranks and gathered back to one rank once the evaluations are completed. We implement this divide-and-conquer strategy with UPC++ and MPI and display the results obtained from running the implementations with 24 ranks on an Euler compute node in listings 3 and 4 respectively.

Listing 3: Output from executing the UPC++ tasking engine with the divide-and-conquer strategy.

```
Verification Passed
Total time: 1.37665
Average time: 1.17792
Load imbalance ratio: 0.144362
```

Listing 4: Output from executing the MPI tasking engine with the divideand-conquer strategy.

```
Verification Passed
Total time: 1.31242
Average time: 1.17451
Load imbalance ratio: 0.10508
```

We observe a speedup of  $\approx 21.5$  for UPC++ and  $\approx 22.5$  for MPI and thus we report efficiencies of  $\approx 90\%$  for UPC++ and  $\approx 94.5\%$  for MPI. Both implementations suffer from a relatively high load imbalance ratio ( $\approx 0.145$  for UPC++ and  $\approx 0.105$  for MPI) which results from the fluctuation in evaluation times and the static distribution schedule. The MPI approach is practically identical to that employed for the UPC++ code but the collective operations in MPI allow for a much cleaner implementation (especially using MPI\_Scatter since it eliminates the need to care about the global sample index of sample that is processed locally on a given rank). In general, MPI feels more natural since it requires very explicit communication.

#### b)

To solve the load imbalance problem observed in Task 2a) we implement the producer-consumer strategy which takes advantage of the fact that the evaluation times differ and distributes workloads according to rank availability and not according to a fixed scheme. We display the results obtained from running the UPC++ and MPI implementations with 24 ranks on an Euler compute node in listings 5 and 6 respectively.

Listing 5: Output from executing the UPC++ tasking engine with the producer-consumer strategy.

```
Processing 240 Samples each with 2 Parameter(s)...

Verification Passed

Total time: 1.32383

Average time: 1.25486

Load imbalance ratio: 0.0520984
```

Listing 6: Output from executing the MPI tasking engine with the producer-consumer strategy.

```
Verification Passed
Total time: 1.32354
Average time: 1.24246
Load imbalance ratio: 0.0612577
```

We observe for both UPC++ and MPI that the load imbalance ratio drops significantly compared to the divide-and-conquer strategy, although more drastically for UPC++. For UPC++ we observe that the total time decreases slightly compared to the divide-and-conquer strategy (speedup:  $\approx 22.5$ , efficiency:  $\approx 93.5\%$ ), whereas for the MPI implementation the total running time increases marginally (speedup:  $\approx 22.5$ , efficiency:  $\approx 93.5\%$ ).

We take this as evidence that the UPC++ implementation has successfully solved the load imbalance problem. Even though the load imbalance has also dropped for MPI, the producer-consumer strategy requires a lot more communication which explains the slightly higher running time. The MPI approach differs slightly from the UPC++ approach:

- UPC++ employs a queue of consumers which contain a future among other data. The producer iterates over the queue and checks whether a RPC has completed before distributing another sample to the idling rank.
- The MPI implementation does not require a queue as the producer just sends samples and listens for results until all samples have been evaluated. Unlike the UPC++ implementation, we need to explicitly tell every rank that the evaluation has completed once all samples have been processed.

In general one can say that UPC++ is more suited for the implementation of the producer-consumer problem. Nevertheless, the MPI approach feels cleaner as its communication is more explicit<sup>1</sup>.

## Task 3

We run the single tasking engine and display its output in Listing 7.

Listing 7: Output from executing the single tasking engine.

```
Processing 240 Samples (24 initially available), each with 2 Parameter(s)... Verification Passed Total Running Time: 29.458s
```

Since not all samples are available at the beginning of the generation it does not make sense to have more ranks than initially available samples and we enforce this constraint with an assert. Apart from that our approaches are similar to those from Task 2b) and we display the results obtained from running the UPC++ and MPI implementations with 24 ranks on an Euler compute node in listings 8 and 9 respectively.

Listing 8: Output from executing the UPC++ tasking engine.

```
Processing 240 Samples (24 initially available), each with 2 Parameter(s)... Verification Passed Total Running Time: 1.355\,\mathrm{s}
```

<sup>&</sup>lt;sup>1</sup>From The Zen of Python, by Tim Peters: "Explicit is better than implicit.".

Listing 9: Output from executing the MPI tasking engine.

```
Verification Passed
Total Running Time: 1.311s
```

We observe speedups of  $\approx 21.5$  for UPC++ and  $\approx 22.5$  for MPI and correspondingly efficiencies of  $\approx 90.5\%$  for UPC++ and  $\approx 93.5\%$  for MPI. For the UPC++ implementation we faced the challenge that getSample() and updateEvaluation() have to be called from the root rank and that updateEvaluation() has to be called after the evaluation has completed on a consumer rank. This problem can be elegantly solved with the then() method from UPC++. Our MPI implementation is basically equivalent to that of Task 2b) and thus we refer to Task 2b) for a discussion of the differences between the UPC++ and MPI approaches. Using the then() function is definitely more elegant than sending data back and forth as is required for MPI.

### Task 4

To exploit full parallelism we increase the population size to 23 since we have 23 consumer ranks and 1 producer rank. We run Korali with the single conduit and display its output in Listing 10.

Listing 10: Korali output for the single conduit when running the code from Task 1 with population size 23.

```
Finished - Reason: Object variable changes < 1.00e-06
Parameter 'Sigma' Value: 0.937782
Parameter 'torch_1_x' Value: 0.251375
Parameter 'torch_1_y' Value: 0.741905
Parameter 'torch_1_intensity' Value: 0.414076
Parameter 'torch_1_width' Value: 0.060000
Parameter 'torch_2_x' Value: 0.242771
Parameter 'torch_2_y' Value: 0.242771
Parameter 'torch_2_intensity' Value: 0.435900
Parameter 'torch_2_width' Value: 0.053473
Parameter 'torch_3_x' Value: 0.760406
Koralil
 Korali
 Korali
 Korali
 Korali
 Korali
 Korali
 Korali
 Korali
 Korali
                                           'torch_3_x' Value: 0.760406
'torch_3_y' Value: 0.770098
'torch_3 intensity' Value:
                   Parameter
 Korali
 Korali
                   Parameter
                                           'torch_3_intensity' Value: 0.590
'torch_3_width' Value: 0.048075
'torch_4_x' Value: 0.756812
'torch_4_y' Value: 0.254229
                   Parameter
 Korali
 Korali
                   Parameter
 Korali
                   Parameter
 Korali
                   Parameter
                   Parameter 'torch_4_intensity' V
Parameter 'torch_4_width' Value
Total Elapsed Time: 441.061222s
                   Parameter
Korali
                                                                                         Value: 0.501190
                                                                                 Value: 0.051603
 Korali
```

Our UPC++ and MPI approaches are very similar to those of tasks 2b) and 3 and we display the results obtained from running the UPC++ and MPI implementations with 24 ranks on an Euler compute node in listings 11 and 12.

Listing 11: Korali output for the UPC++ conduit when running the code from Task 1 with population size 23.

```
Finished - Reason: Object variable changes < 1.00e-06
Parameter 'Sigma' Value: 0.937782
Parameter 'torch_1_x' Value: 0.251375
Parameter 'torch_1_y' Value: 0.741905
Korali
 Korali
 Korali
 Korali
                                'torch_1_intensity'
                                                                  Value:
 Korali
              Parameter
                               'torch_1_width' Value: 0.060000
'torch_2_x' Value: 0.242771
'torch_2_y' Value: 0.240310
'torch_2_intensity' Value: 0.435900
'torch_2_width' Value: 0.053473
Korali
              Parameter
              Parameter
Korali
Korali
              Parameter
              Parameter
 Korali
                               'torch_3_x' Value: 0.760406
'torch_3_y' Value: 0.770098
'torch_3_intensity' Value: 0.590
'torch_3_width' Value: 0.048075
              Parameter
Korali
              Parameter
              Parameter
 Korali
 Korali
              Parameter
                               'torch_4_x' Value: 0.756812
'torch_4_y' Value: 0.254229
'torch_4_intensity' Value: 0.501190
'torch_4_width' Value: 0.051603
Korali
              Parameter
 Korali
              Parameter
 Korali
              Parameter
 Korali
              Parameter
              Total Elapsed Time: 21.553523s
Korali]
```

Listing 12: Korali output for the MPI conduit when running the code from Task 1 with population size 23.

```
- Reason: Object variable changes < 1.00e-06
'Sigma' Value: 0.937782
'torch.1.x' Value: 0.251375
'torch.1.y' Value: 0.741905
'torch.1.intensity' Value: 0.414076
'torch.1.width' Value: 0.060000
'torch.2.x' Value: 0.442771
 Korali
                 Parameter
                 {\bf Parameter}
 Korali
 Korali
                 Parameter
 Korali
                 Parameter
                 Parameter
 Korali
                                      'torch_1_width' Value: 0.060000
'torch_2_x' Value: 0.242771
'torch_2_y' Value: 0.240310
'torch_2_intensity' Value: 0.435
'torch_2_width' Value: 0.053473
'torch_3_x' Value: 0.760406
'torch_3_y' Value: 0.770098
'torch_3_intensity' Value: 0.590
'torch_3_width' Value: 0.048075
'torch_4_x' Value: 0.756812
 Korali
                 Parameter
 Korali
                 Parameter
 Korali
                 Parameter
 Korali
                 Parameter
                 Parameter
 Korali
                 Parameter
 Korali
                 Parameter
                                                                                              0.590264
 Korali
                 Parameter
                                      'torch_4_x' Value: 0.756812
'torch_4_y' Value: 0.254229
'torch_4_intensity' Value:
'torch_4_width' Value: 0.05
 Korali
                 Parameter
 Korali
                 Parameter
 Korali
                  Parameter
                                                                      Value: 0.051603
                  Total Elapsed Time: 22.081863s
```

We observe that the results are identical for all three conduits and that UPC++ achieves a speedup of  $\approx 20.5$  with efficiency  $\approx 85.5\%$  whereas MPI achieves a speedup of  $\approx 20$  with efficiency  $\approx 83\%$ . Both implementations thus exceed the requirement of being at least 10x faster while producing results similar to those of the single conduit, implying that the CEO of the company will give us a raise. As mentioned above, both approaches are similar to those of tasks 2b) and 3 and can thus be easily adapted to the current task. However, for UPC++ we faced the new challenge that the number of parameters is not given as a constant. Consequently, we cannot use the *Consumer* struct from Task 3 as its sample array would have to be allocated dynamically, which in turn means that *Consumer* is not trivially copyable anymore. With UPC++ we can solve this problem by

simply using the local pointer of the global sample Array Pointer to access the sample data from every consumer rank. The MPI implementation for this task is basically identical to that of tasks 2b) and 3. For this reason, we refer to Task 2b) for a discussion on the difference between the implementations. As for Task 3, it was relatively easy to adapt the implementations to the current task for both frameworks. The most difficult part of the MPI conduit implementation is the integration with Korali which is described below:

• load the required modules and set the environment variables

```
module load new
module load gcc/6.3.0
module load intel/2018.1
module load impi/2018.1.163

export UPCXX_GASNET_CONDUIT=smp
export UPCXX_THREADMODE=seq
export UPCXX_CODEMODE=O3
export KORALL_CONDUIT=single
```

- replace single.cpp with mpi.cpp
- replace the Makefile in the conduits directory with this Makefile
- replace the Makefile in the task1 directory with this Makefile