

# Verification of Toffoli Circuit Equivalence

## The tomography circuit

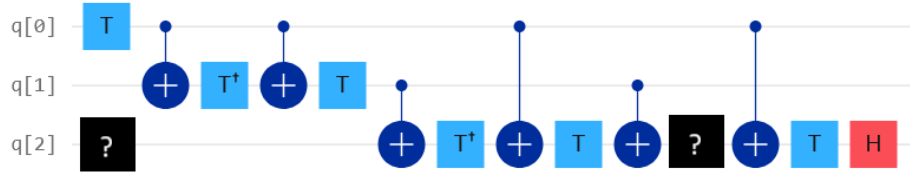


Figure 1: Toffoli Equivalent Circuit

The left unknown gate is considered as  $U_A$  and the left one  $U_B$ . The full operation on  $|q_2\rangle$  is:

$$U_{\text{total}} = H \cdot T \cdot \text{CNOT}_{0,2} \cdot U_B \cdot \text{CNOT}_{1,2} \cdot T \cdot \text{CNOT}_{0,2} \cdot T^\dagger \cdot \text{CNOT}_{1,2} \cdot U_A$$

Upon which we apply the 4 possible control combinations.

## Possible Control Combinations

### Controls $|00\rangle$

All CNOTs are inactive (they act as the Identity  $I$ ).

$$\begin{aligned} U_{00} &= H \cdot T \cdot I \cdot U_B \cdot I \cdot T \cdot I \cdot T^\dagger \cdot I \cdot U_A \\ U_{00} &= HTU_B(TT^\dagger)U_A = HTU_BIU_A = HTU_BU_A \end{aligned}$$

### Controls $|01\rangle$

CNOTs from  $q_0$  are inactive ( $I$ ). CNOTs from  $q_1$  are active ( $X$ ).

$$\begin{aligned} U_{01} &= H \cdot T \cdot I \cdot U_B \cdot X \cdot T \cdot I \cdot T^\dagger \cdot X \cdot U_A \\ U_{01} &= HTU_B(XTT^\dagger X)U_A \\ U_{01} &= HTU_B(XIX)U_A = HTU_B(X^2)U_A \\ U_{01} &= HTU_BIU_A = HTU_BU_A \end{aligned}$$

### Controls $|10\rangle$

CNOTs from  $q_0$  are active ( $X$ ). CNOTs from  $q_1$  are inactive ( $I$ ).

$$\begin{aligned}U_{10} &= H \cdot T \cdot X \cdot U_B \cdot I \cdot T \cdot X \cdot T^\dagger \cdot I \cdot U_A \\U_{10} &= HTXU_BTXT^\dagger U_A\end{aligned}$$

### Controls $|11\rangle$

All CNOTs are active ( $X$ ). The requirement is  $U_{11} = \alpha X$ .

$$U_{11} = H \cdot T \cdot X \cdot U_B \cdot X \cdot T \cdot X \cdot T^\dagger \cdot X \cdot U_A$$

## Observation

From equations of  $|00\rangle$  &  $|01\rangle$ , we can observe that the equation holds perfectly if:

$$U_A = H \quad U_B = T^\dagger$$

We will substitute this into each control case.

## Verification

### Controls $|00\rangle$

Substitute  $U_A = H$  and  $U_B = T^\dagger$ :

$$\begin{aligned}U_{00} &= HT(T^\dagger)(H) \\U_{00} &= H(TT^\dagger)H = H I H = H^2 \\U_{00} &= I \quad (\text{Correct})\end{aligned}$$

### Controls $|01\rangle$

This is identical to Case 1, so:

$$U_{01} = I \quad (\text{Correct})$$

### Controls $|10\rangle$

Substitute  $U_A = H$  and  $U_B = T^\dagger$ :

$$\begin{aligned}
 U_{10} &= HTX(T^\dagger)TXT^\dagger(H) \\
 U_{10} &= HTX(T^\dagger T)XT^\dagger H = HTX(I)XT^\dagger H \\
 U_{10} &= HT(X^2)T^\dagger H = HT(I)T^\dagger H \\
 U_{10} &= H(TT^\dagger)H = HIH = H^2 \\
 U_{10} &= I \quad (\text{Correct})
 \end{aligned}$$

### Controls $|11\rangle$

Substitute  $U_A = H$  and  $U_B = T^\dagger$ :

$$U_{11} = HTX(T^\dagger)XTXT^\dagger X(H)$$

Let's analyze the large central matrix  $M = TXT^\dagger XTXT^\dagger X$ :

$$M = T \cdot (XT^\dagger X) \cdot T \cdot (XT^\dagger X)$$

We use the identities  $XT^\dagger X = \begin{pmatrix} e^{-i\pi/4} & 0 \\ 0 & 1 \end{pmatrix}$  and  $T = \begin{pmatrix} 1 & 0 \\ 0 & e^{i\pi/4} \end{pmatrix}$ . Let  $A = XT^\dagger X$ . Since  $T$  and  $A$  are diagonal, they commute:  $TA = AT$ .

$$\begin{aligned}
 M &= TATA = T^2 A^2 \\
 T^2 &= S = \begin{pmatrix} 1 & 0 \\ 0 & i \end{pmatrix} \quad A^2 = \begin{pmatrix} (e^{-i\pi/4})^2 & 0 \\ 0 & 1^2 \end{pmatrix} = \begin{pmatrix} -i & 0 \\ 0 & 1 \end{pmatrix} \\
 M &= T^2 A^2 = \begin{pmatrix} 1 & 0 \\ 0 & i \end{pmatrix} \begin{pmatrix} -i & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} -i & 0 \\ 0 & i \end{pmatrix} \\
 M &= -i \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = -iZ
 \end{aligned}$$

Now substitute  $M$  back into the equation for  $U_{11}$ :

$$\begin{aligned}
 U_{11} &= H \cdot M \cdot H = H(-iZ)H \\
 U_{11} &= -i(HZH)
 \end{aligned}$$

Using the identity  $HZH = X$ :

$$U_{11} = -iX \quad (\text{Correct})$$

This is equivalent to  $X$  with a global phase of  $\alpha = -i$ .

## Conclusion

All four control cases produce the required operations ( $I, I, I$ , and  $\alpha X$ ). Therefore, the solution is correct:

- **First U3 Gate:**  $U_A = H = U3(\pi/2, 0, \pi)$
- **Second U3 Gate:**  $U_B = T^\dagger = U3(0, x, \phi + \lambda - \pi/4)$

where choosing  $\phi = 0$  for simplicity, we get,

- **First U3 Gate:**  $U_A = H = U3(\pi/2, 0, \pi)$
- **Second U3 Gate:**  $U_B = T^\dagger = U3(0, 0, -\pi/4)$