

# Introduction to Robotics CSE 461

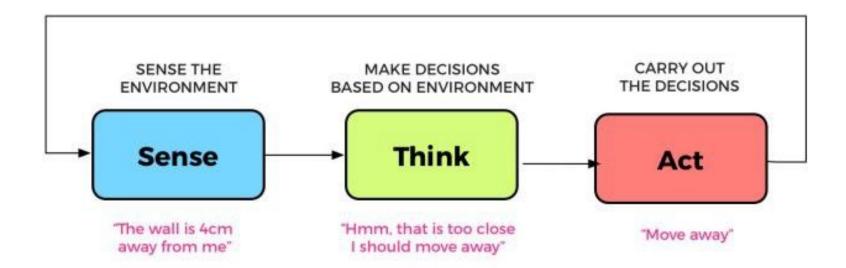
Lecture 3 : Chapter 1(Introduction to robotics: basics)

Niloy Irtisam Lecturer, Dept. of Computer Science and Engineering Brac University

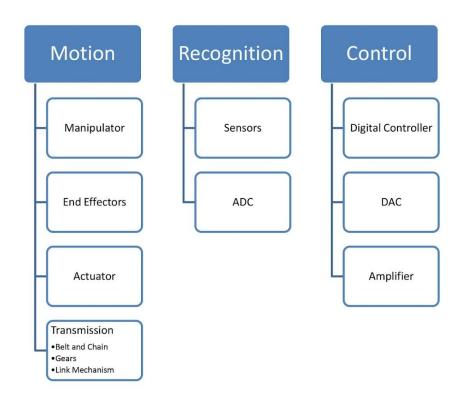
#### **Previous Class**

- 1. Primitives
- 2. Paradigms

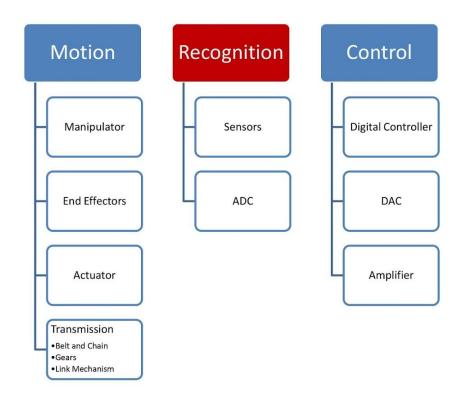
# Recall



# Subsystems

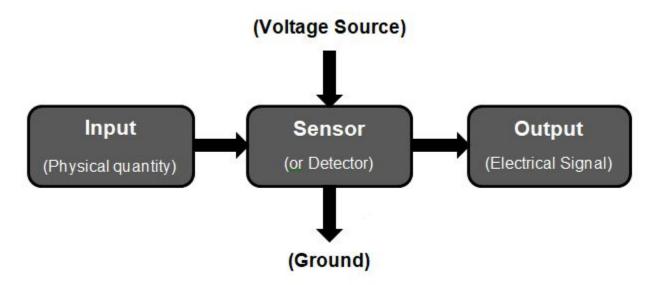


# Subsystems



#### Sensor

A sensor is a device that detects or measures physical, chemical, or biological properties of the environment or a system and converts them into a signal that can be processed or analyzed.



# Sensor Examples



Physical Property Sensor

contact switch

distance ultrasound, radar, infrared

light level photocells, cameras

sound level microphone

rotation encoders and potentiometers

acceleration accelerometers gyroscopes

# More Sensor Examples



Physical Property Sensor

magnetism compass

smell chemical

temperature thermal, infra red

inclination inclinometers, gyroscopes

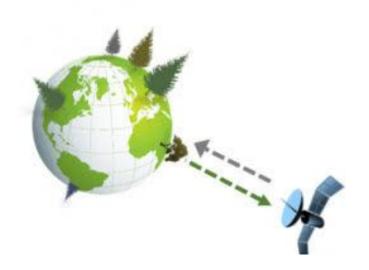
pressure pressure gauges

altitude altimeters

strain strain gauges

#### **Active sensors**

#### Passive sensors







#### Ultrasonic Sensor

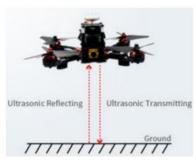
Converts electrical energy into acoustic wave, which is an ultrasonic wave travelling at above 18kHz frequency.

HC-SRo4 operates at 4okHz

a microcontroller is used for communication with an ultrasonic sensor.

#### Applications

- Measure wind speed and direction
- Navigation of UAV
- Measure tank depth





HC-SRo4 Ultrasonic Sensor (Source: Digikey)

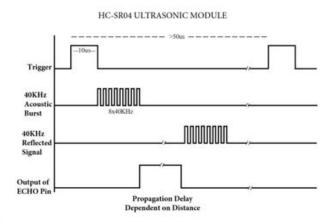
Ultrasonic sensor measuring height during drone's flight.

(Source: RadioLink)



#### Ultrasonic Sensor: How It Works??

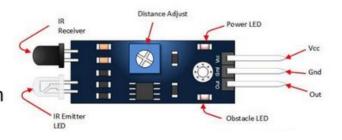
- a microcontroller is used for communication with an ultrasonic sensor.
- To begin measuring the distance, the microcontroller sends a trigger signal to the ultrasonic sensor. The duty cycle of this trigger signal is 10µS for the HC-SR04 ultrasonic sensor.
- When triggered, the ultrasonic sensor generates eight acoustic (ultrasonic) wave bursts and initiates a time counter.
- 4. As soon as the reflected (echo) signal is received, the timer stops. The output of the ultrasonic sensor is a high pulse with the same duration as the time difference between transmitted ultrasonic bursts and the received echo signal.



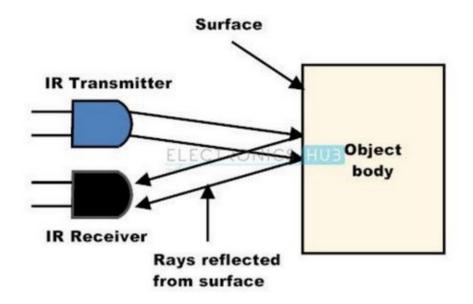


#### **Infrared Sensors**

- An electronic device that can detect and measure infrared (IR) radiation in the environment
- Anything that emits heat (everything that has a temperature above around five degrees Kelvin) gives off infrared radiation
- Applications
  - TV Remote
  - Motion Sensing
  - Proximity Sensing



## Infrared Sensors: How Active Sensing Works

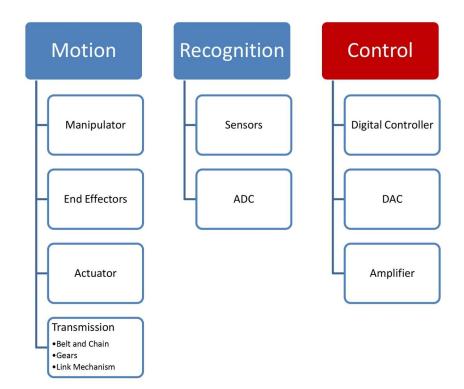


## Lidar



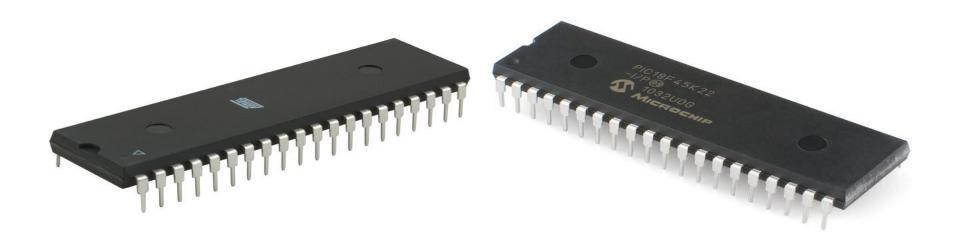
- Laser generates an optical pulse(Up to 200,000+ pulses/second)
- After reflecting off an object, the pulse returns to the receiver sensor
- High-speed counter measures the time of flight from the start pulse to the return pulse
- Time measurement is converted to a distance
- An onboard computer records each laser's reflection point, translating this rapidly updating "point cloud" into an animated 3D representation of its surroundings.

# Subsystems



#### Microcontrollers

A microcontroller is a small, integrated circuit that contains a processor, memory, and input/output peripherals.



## Arduino

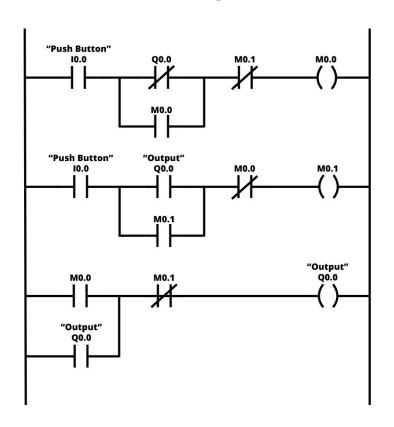




#### **Arduino**



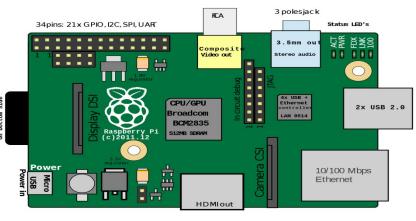
# Programmable Logic Controller (PLC)





# Single board Computer





# Raspberry PI 4, Tinkerboard





## Little Panda and Jetson nano





### **Next Class**

• Subsystem (Motion)

# Thank You