Theory Assignment-1: ADA Winter-2024

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1 Preprocessing

None

2 Algorithm Description

This algorithm is based on a median-of-medians divide and conquer approach. In each iteration of the algorithm, we are essentially able to reduce half the search space of any one of the array. This is done till we reach the base case, where only one array remains, and at that point, we return the (modified) kth element in that remaining array.

3 Recurrence Relation

The recurrence relation for the algorithm is given by:

$$T(n_1, n_2, n_3) = T\left(\frac{n_i}{2}, n_j, n_k\right) + O(1)$$

where i, j, k can take any permutation of the values 1, 2, 3.

4 Complexity Analysis

Note that computing the time complexity of the algorithm directly from the above recurrence may prove to be extremely difficult. Hence, we will compute the time complexity for the following simplified version of the recurrence:

$$T(n_1, n_2, n_3) = T\left(\frac{n_1}{2}, n_2, n_3\right) + O(1)$$

where $n_1 = n_2 = n_3$

Hence, our recurrence becomes:

$$T(N) = T(\frac{5N}{6}) + O(1)$$

where $N = n_1 + n_2 + n_3$

Thus, from the above recurrence relation, we can say that the time complexity of our algorithm is $O(\log(N))$, since there is a very clear reduction of the search space by a constant factor of $\frac{1}{6}$ in each iteration.

5 Pseudocode

Algorithm 1 Median

```
1: function Median(arr, low, high)
       len \leftarrow high - low + 1
       if len = 0 then
3:
           {f return} \ 0
4:
       end if
5:
       if len \mod 2 = 0 then
6:
           return arr[low + \frac{len}{2} - 1]
7:
8:
           return arr[low + \frac{len}{2}]
9:
        end if
10:
11: end function
```

Algorithm 2 Eliminate_right

```
1: function ELIMINATE_RIGHT(median, pivot, length, size, counter)
           if median > pivot then
 2:
                if length \mod 2 = 0 then
 3:
                     counter \leftarrow counter - \frac{\overline{length}}{2}
 4:
                      size \leftarrow size - \frac{length}{2}
 5:
 6:
                     \begin{aligned} & counter \leftarrow counter - (\frac{length}{2} + 1) \\ & size \leftarrow size - (\frac{length}{2} + 1) \end{aligned}
 7:
 8:
                end if
 9:
           end if
10:
           return \langle size, counter \rangle
11:
12: end function
```

Algorithm 3 Eliminate_left

```
1: function Eliminate_Left(median, pivot, length, size, counter, k)
 2:
             if median < pivot then
                   if length \mod 2 = 0 then
 3:
                         counter \leftarrow counter + \frac{\overline{length}}{2}
 4:
                        size \leftarrow size - \frac{length}{2}k \leftarrow k - \frac{length}{2}
 5:
 6:
                   else
 7:
                        \begin{aligned} & counter \leftarrow counter + (\frac{length}{2} + 1) \\ & size \leftarrow size - (\frac{length}{2} + 1) \\ & k \leftarrow k - (\frac{length}{2} + 1) \end{aligned}
 8:
10:
                   end if
11:
             end if
12:
            return \langle size, counter, k \rangle
13:
14: end function
```

Algorithm 4 find_k

```
1: function FIND_K(arr1, arr2, arr3, l1, r1, l2, r2, l3, r3, k, valid1, valid2, valid3)
 2:
         len1 \leftarrow 0, len2 \leftarrow 0, len3 \leftarrow 0, T \leftarrow 0, m1 \leftarrow 0, m2 \leftarrow 0, m3 \leftarrow 0
 3:
         M \leftarrow 0.0
 4:
         if valid1 then
              len1 \leftarrow r1 - l1 + 1
 5:
 6:
              m1 \leftarrow \text{Median}(arr1, l1, r1)
 7:
         end if
 8:
         if valid2 then
 9:
              len2 \leftarrow r2 - l2 + 1
10:
              m2 \leftarrow \text{Median}(arr2, l2, r2)
11:
          end if
12:
         if valid3 then
              len3 \leftarrow r3 - l3 + 1
13:
14:
              m3 \leftarrow \text{Median}(arr3, l3, r3)
15:
         end if
16:
         T \leftarrow len1 + len2 + len3
         if m1 = 0 and m2 = 0 then
17:
18:
             M \leftarrow m3
         else if m2 = 0 and m3 = 0 then
19:
20:
              M \leftarrow m1
21:
         else if m1 = 0 and m3 = 0 then
22:
              M \leftarrow m2
23:
          else if m1 \times m2 \times m3 = 0 then
              M \leftarrow \frac{m1+m2+m3}{2.0}
24:
25:
         else
26:
              arr \leftarrow [m1, m2, m3]
27:
              Sort(arr)
28:
              M \leftarrow arr[1]
29:
         end if
30:
         if k \leq \frac{T}{2} then
31:
              if valid1 then
32:
                  \langle T, r1 \rangle \leftarrow \text{Eliminate\_right}(m1, M, len1, T, r1)
33:
              end if
34:
              if valid2 then
35:
                  \langle T, r2 \rangle \leftarrow \text{Eliminate\_right}(m2, M, len2, T, r2)
36:
              end if
37:
              if valid3 then
                  \langle T, r3 \rangle \leftarrow \text{Eliminate\_right}(m3, M, len3, T, r3)
38:
39:
              end if
40:
         _{
m else}
41:
              if valid1 then
42:
                  \langle T, l1, k \rangle \leftarrow \text{Eliminate\_left}(m1, M, len1, T, l1, k)
              end if
43:
44:
              if valid2 then
                  \langle T, l2, k \rangle \leftarrow \text{Eliminate\_left}(m2, M, len2, T, l2, k)
45:
46:
              end if
47:
              \mathbf{if}\ valid 3\ \mathbf{then}
                  \langle T, l3, k \rangle \leftarrow \text{Eliminate\_left}(m3, M, len3, T, l3, k)
48:
              end if
49:
50:
              if l1 > r1 then
51:
                  valid1 \leftarrow \mathbf{false}
52:
              end if
              if l2 > r2 then
53:
54:
                  valid2 \leftarrow \mathbf{false}
55:
              end if
56:
              if l3 > r3 then
57:
                  valid3 \leftarrow \mathbf{false}
58:
              end if
59:
              if valid1 and not valid2 and not valid3 then
                  return arr1[l1+k-1]
60:
61:
              end if
62:
              if valid2 and not valid1 and not valid3 then
63:
                  return arr2[l2 + k - 1]
64:
              if valid3 and not valid1 and not valid2 then
65:
66:
                  return arr3[l3+k-1]
67:
              end if
              return find_k(arr1, arr2, arr3, l1, r1, l2, r2, l3, r3, k, valid1, valid2, valid3)
68:
69:
```

6 Assumptions

- The indexing is zero-based.
- No two arrays should have any common elements.
- Assume that we have only floor division in the code in case of integers, since the code is derived from cpp.

7 Proof of Correctness

In this algorithm we first compute the approximate median of all three arrays individually, followed by computing the median of those three medians. We then make a check, if the kth element is less than half the total number of elements in all three arrays. If it is, then we eliminate the right half of the array with the largest median, else we eliminate the left half of the array with the smallest median and accordingly adjust the value of k too. We then recursively call the function again with the updated values of the arrays and k. We keep doing this until we reach the base case, where we have only one array left. At this point we simply return the kth element of the array.

This algorithm might not work in the cases where any two arrays have common elements. This is because, the medians of two or more arrays might come out to be same, and the program might not be able to distinguish the array with the largest, or the array with the smallest median and enter into an infinite recursion call.

8 References and Collaborations

During the development and exploration of the algorithms presented in this document, the following references and collaborations were invaluable:

1. CS Stack Exchange Discussion:

Title: Kth smallest element in 2 sorted arrays

Link: https://stackoverflow.com/questions/4607945/how-to-find-the-kth-smallest-element-in-the-union-of-two-sorted-arrays

umon-or-two-sorted-arrays

The discussion on CS Stack Exchange provided insights and discussions related to the kth smallest element in 2 sorted arrays.

2. YouTube Video Tutorial:

Title: Algorithm Explanation: Find Kth Element in Two Sorted Arrays

Link: https://www.youtube.com/watch?v=nv7F4PiLUzohttps://www.youtube.com/watch?v=nv7F4PiLUzo

This video tutorial offered a detailed explanation of the algorithm for finding the kth element in two sorted arrays.