

# Training an RNN with a Low-Rank Structure

Aniket Deshpande

## CONTENTS

<b>1 Training an RNN with a Low-Rank Structure</b>	<b>2</b>
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footnote

## 1. Training an RNN with a Low-Rank Structure

*Setup.* The model is a continuous time recurrent neural network

$$\tau \dot{h}(t) = -h(t) + J\phi(h(t)) + Bu(t), \quad y(t) = w^T \phi(h(t))$$

where  $J$  is the recurrent weight matrix,  $\phi$  is ReLU or tanh,  $u(t)$  is a low-dimensional input (one or two OU stimuli), and  $y(t)$  is a 1-2D readout. The task being learned is tracking/denoising the driving OU signals (and possibly switch between two stimuli), i.e. make  $y(t)$  match a target trace  $y^*(t)$  generated by the OU signals. The loss function would be the mean-squared error over a time window (with light regularization)

$$\mathcal{L} = \frac{1}{T} \int_0^T \|y(t) - y^*(t)\|^2 dt + \lambda_W \|J\|_F^2 + \lambda_{\text{bal}} \underbrace{\left\| \frac{1}{N} \mathbf{1}^T J \right\|_2^2}_{\text{row/col balance}}$$

The balance term nudges  $J$  towards zero row/column sums so that the random bulk stays centered. Our optimizer will be standard gradient descent through time (BPTT) on  $J$  (and often the readout  $w$ , occasionally  $B$ ). We can backpropagate the MSE through the RNN unrolled over time. We should monitor the spectrum of  $J - I$  (or the linearized Jacobian) to see whether/when an outlier separates from the circular bulk. Additionally, some simple weight stats (row/col means, within/between clusters) to visualize emerging structure, also task error.

*Goal.* The goal of this side project is to supplement the original DMFT analysis. Our current work analyzes fixed low-rank perturbations  $J = gW - b/N \mathbf{1}\mathbf{1}^T + muv^T$  and their dynamical consequences. The training goal is to learn: if we *do not* impose  $muv^T$  structure, but instead train the RNN to do the OU-tracking task, does learning spontaneously add a low-rank component that looks like  $uv^T$ ? How does the magnitude  $m$  and alignment compare with the task geometry?

After training, we can project the learned change  $\Delta J = J - J_0$  onto a low-rank model. We fit  $\Delta J \approx \sum_{r=1}^R m_r u_r v_r^T$  (e.g. SVD with sign/scale conventions). Check whether  $R = 1$  or  $2$  suffices for most of the variance. We also should compare spectra: the bulk stays roughly circular, and we should see an outlier emerge and move with training, exactly the same object we analyzed in the DMFT (the  $\Re \lambda_{\text{out}}$  crossing).