In this notebook we will train the best model obtained from experimentation, save that model, load it from memory. Then we will define a function that will give us the result for a given data point

```
In [1]: import numpy as np
import pandas as pd

In [2]: # Loading datasets
    train_df = pd.read_csv("training.csv")
    test_df = pd.read_csv("test.csv")
    agree_df = pd.read_csv("check_agreement.csv")
    corr_df = pd.read_csv("check_correlation.csv")
```

## **Check agrrement test**

```
In [3]: # agreement test as mentioned in kaggle resources#
        from sklearn.metrics import roc curve, auc
        def __roc_curve_splitted(data_zero, data_one, sample_weights_zero, sample_weights
            Compute roc curve
            :param data zero: 0-labeled data
            :param data one: 1-labeled data
            :param sample_weights_zero: weights for 0-labeled data
            :param sample weights one: weights for 1-labeled data
            :return: roc curve
            labels = [0] * len(data_zero) + [1] * len(data_one)
            weights = np.concatenate([sample weights zero, sample weights one])
            data_all = np.concatenate([data_zero, data_one])
            fpr, tpr, _ = roc_curve(labels, data_all, sample_weight=weights)
            return fpr, tpr
        def compute_ks(data_prediction, mc_prediction, weights_data, weights_mc):
            Compute Kolmogorov-Smirnov (ks) distance between real data predictions cdf ar
            :param data_prediction: array-like, real data predictions
            :param mc prediction: array-like, Monte Carlo data predictions
            :param weights data: array-like, real data weights
            :param weights mc: array-like, Monte Carlo weights
            :return: ks value
            assert len(data prediction) == len(weights data), 'Data length and weight one
            assert len(mc_prediction) == len(weights_mc), 'Data length and weight one mus
            data prediction, mc prediction = np.array(data prediction), np.array(mc predi
            weights data, weights mc = np.array(weights data), np.array(weights mc)
            assert np.all(data prediction >= 0.) and np.all(data prediction <= 1.), 'Data
            assert np.all(mc prediction >= 0.) and np.all(mc prediction <= 1.), 'MC predi
            weights data /= np.sum(weights_data)
            weights mc /= np.sum(weights mc)
            fpr, tpr = __roc_curve_splitted(data_prediction, mc_prediction, weights_data)
            Dnm = np.max(np.abs(fpr - tpr))
            return Dnm
```

## check correlation test

```
In [4]: # correlation test as mentioned in kaggle resources
        def __rolling_window(data, window_size):
            Rolling window: take window with definite size through the array
            :param data: array-like
            :param window size: size
            :return: the sequence of windows
            Example: data = array(1, 2, 3, 4, 5, 6), window_size = 4
                Then this function return array(array(1, 2, 3, 4), array(2, 3, 4, 5), arr
            shape = data.shape[:-1] + (data.shape[-1] - window_size + 1, window_size)
            strides = data.strides + (data.strides[-1],)
            return np.lib.stride_tricks.as_strided(data, shape=shape, strides=strides)
        def __cvm(subindices, total_events):
            Compute Cramer-von Mises metric.
            Compared two distributions, where first is subset of second one.
            Assuming that second is ordered by ascending
            :param subindices: indices of events which will be associated with the first
            :param total events: count of events in the second distribution
            :return: cvm metric
            target distribution = np.arange(1, total events + 1, dtype='float') / total €
            subarray distribution = np.cumsum(np.bincount(subindices, minlength=total ev€
            subarray distribution /= 1.0 * subarray distribution[-1]
            return np.mean((target_distribution - subarray_distribution) ** 2)
        def compute cvm(predictions, masses, n neighbours=200, step=50):
            Computing Cramer-von Mises (cvm) metric on background events: take average of
            In each mass bin global prediction's cdf is compared to prediction's cdf in n
            :param predictions: array-like, predictions
            :param masses: array-like, in case of Kaggle tau23mu this is reconstructed ma
            :param n neighbours: count of neighbours for event to define mass bin
            :param step: step through sorted mass-array to define next center of bin
            :return: average cvm value
            predictions = np.array(predictions)
            masses = np.array(masses)
            assert len(predictions) == len(masses)
            # First, reorder by masses
            predictions = predictions[np.argsort(masses)]
            # Second, replace probabilities with order of probability among other events
            predictions = np.argsort(np.argsort(predictions, kind='mergesort'), kind='mergesort')
            # Now, each window forms a group, and we can compute contribution of each gro
            cvms = []
            for window in __rolling_window(predictions, window_size=n_neighbours)[::step]
```

cvms.append(\_\_cvm(subindices=window, total\_events=len(predictions)))
return np.mean(cvms)

```
In [5]: # feature engineering
        def new feats(df):
            df2 = df.copy()
            df2['isolation abc'] = df['isolationa'] + df['isolationb'] + df['isolationc']
            df2['isolation_def'] = df['isolationd'] + df['isolatione'] + df['isolationf']
            df2['p_IP'] = df['p0_IP']+df['p1_IP']+df['p2_IP']
            df2['p p'] = df['p0 p']+df['p1 p']+df['p2 p']
            df2['IP_pp'] = df['IP_p0p2'] + df['IP_p1p2']
            df2['p_IPSig'] = df['p0_IPSig'] + df['p1_IPSig'] + df['p2_IPSig']
            #new feature using 'FlightDu=istance' and LifeTime(from literature)
            df2['FD_LT']=df['FlightDistance']/df['LifeTime']
            #new feature using 'FlightDistance', 'po_p', 'p1_p', 'p2_p'(from literature)
            df2['FD_p0p1p2_p']=df['FlightDistance']/(df['p0_p']+df['p1_p']+df['p2_p'])
            #new feature using 'LifeTime', 'p0_IP', 'p1_IP', 'p2_IP'(from literature)
            df2['NEW5_lt']=df['LifeTime']*(df['p0_IP']+df['p1_IP']+df['p2_IP'])/3
            #new feature using 'p0 track Chi2Dof', 'p1 track Chi2Dof', 'p2 track Chi2Dof
            df2['Chi2Dof_MAX'] = df.loc[:, ['p0_track_Chi2Dof', 'p1_track_Chi2Dof', 'p2_t
            # features from kaggle discussion forum
            df2['flight_dist_sig2'] = (df['FlightDistance']/df['FlightDistanceError'])**;
            df2['flight_dist_sig'] = df['FlightDistance']/df['FlightDistanceError']
            df2['NEW_IP_dira'] = df['IP']*df['dira']
            df2['p0p2 ip ratio']=df['IP']/df['IP_p0p2']
            df2['p1p2 ip ratio']=df['IP']/df['IP p1p2']
            df2['DCA_MAX'] = df.loc[:, ['DOCAone', 'DOCAtwo', 'DOCAthree']].max(axis=1)
            df2['iso_bdt_min'] = df.loc[:, ['p0_IsoBDT', 'p1_IsoBDT', 'p2_IsoBDT']].min(a
            df2['iso min'] = df.loc[:, ['isolationa', 'isolationb', 'isolationc','isolati
            return df2
```

```
In [6]: # adding engineered features to training and test datasets
    train_df_1 = new_feats(train_df)
    test_df_1 = new_feats(test_df)
```

```
In [9]: # training the actual model
         from hep ml.gradientboosting import UGradientBoostingClassifier
         from hep ml.losses import BinFlatnessLossFunction
         loss = BinFlatnessLossFunction(['mass'], n bins=15, uniform label=0 , fl coeffici
         model = UGradientBoostingClassifier(loss=loss, n estimators=900,
                                           max_depth=6,
                                           learning rate=0.15,
                                           train features=features,
                                           subsample=0.7)
         model.fit(train_df_1[features + ['mass']], train_df_1['signal'])
 Out[9]: UGradientBoostingClassifier(learning_rate=0.15,
                                      loss=BinFlatnessLossFunction(allow_wrong_signs=Tru
         e,
                                                                    fl coefficient=15,
                                                                    n_bins=15, power=2,
                                                                    uniform features=['mas
         s'],
                                                                    uniform_label=array
         ([0]),
                                      max_depth=6, max_features=None, max_leaf_nodes=Non
         e,
                                      min_samples_leaf=1, min_samples_split=2,
                                      n estimators=900,
                                      random state=RandomState(MT19937) at 0x259BE7B3740,
                                      splitter...
                                      train features=['LifeTime', 'dira',
                                                       'FlightDistance',
                                                      'FlightDistanceError', 'IP',
                                                       'IPSig', 'VertexChi2', 'pt', 'iso',
                                                       'ISO_SumBDT', 'isolation_abc',
                                                       'isolation_def', 'p_IP', 'p_p',
                                                       'IP_pp', 'p_IPSig', 'FD_LT',
                                                      'FD_p0p1p2_p', 'NEW5_lt',
                                                       'Chi2Dof_MAX', 'flight_dist_sig2',
                                                       'flight_dist_sig', 'NEW_IP_dira',
                                                       'p0p2_ip_ratio', 'p1p2_ip_ratio',
                                                       'DCA_MAX', 'iso_bdt_min',
                                                       'iso min'],
                                      update tree=True)
In [10]:
         # saving the model to the memory
         import pickle
         filename = 'finalized model.sav'
         pickle.dump(model, open(filename, 'wb'))
In [12]: # Loading the model from memory
         loaded_model = pickle.load(open(filename, 'rb'))
```

```
In [13]: # conducting agreement check test
         check agreement = pd.read csv("check agreement.csv")
         check_agreement = new_feats(check_agreement)
         #check_agreement = pandas.read_csv(folder + 'check_agreement.csv', index_col='id
         agreement_probs = loaded_model.predict_proba(check_agreement[features])[:, 1]
         ks = compute ks(
             agreement_probs[check_agreement['signal'].values == 0],
             agreement_probs[check_agreement['signal'].values == 1],
             check_agreement[check_agreement['signal'] == 0]['weight'].values,
             check_agreement[check_agreement['signal'] == 1]['weight'].values)
         #print 'KS metric', ks, ks < 0.09</pre>
         print("KS metric {}".format(ks))
         print(ks < 0.09)</pre>
         KS metric 0.0777479828637741
         True
In [14]: # conducting the correlation test
         #check correlation = pandas.read csv(folder + 'check correlation.csv', index col-
         check_correlation = pd.read_csv("check_correlation.csv", index_col = "id")
         check correlation = new feats(check correlation)
         correlation_probs = loaded_model.predict_proba(check_correlation[features])[:, 1]
         cvm = compute cvm(correlation probs, check correlation['mass'])
         #print 'CvM metric', cvm, cvm < 0.002</pre>
         print("CvM metric {}".format(cvm))
         print(cvm < 0.002)</pre>
         CvM metric 0.0018304056413095619
         True
In [15]: # making submission file with test dataset to be submitted on kaggle
         test probs = loaded model.predict proba(test df 1[features])[:,1]
         result = pd.DataFrame({"id": test df["id"], "prediction": test probs})
         result.to_csv("final_result.csv", index=False)
 In [ ]:
In [42]: # defining the function which when given a a data point as a list returns the res
         def compute(x):
             """given a data point, x, as a list of values this function returns the label
             df = pd.DataFrame(data = np.array(x).reshape(1, len(x)), columns = list(test
             df 1 = new feats(df)
             output = loaded_model.predict(df_1[features])[0]
             if output == 0:
                 print("the given point belongs to class {} i.e. it is a background event"
             elif output == 1:
                 print("the given point belongs to class {} i.e. it is a signal event".for
```

return output

```
In [43]: # testing the function with some test point
    test_1 = list(test_df.iloc[0].values)

In [44]: output_1 = compute(test_1)
    the given point belongs to class 0 i.e. it is a background event

In [45]: output_1

Out[45]: 0

In [46]: test_2 = list(test_df.iloc[222].values)

In [47]: output_2 = compute(test_2)
    the given point belongs to class 0 i.e. it is a background event

In [48]: test_3 = list(test_df.iloc[111].values)
    output_3 = compute(test_3)
    the given point belongs to class 1 i.e. it is a signal event

In []:
```