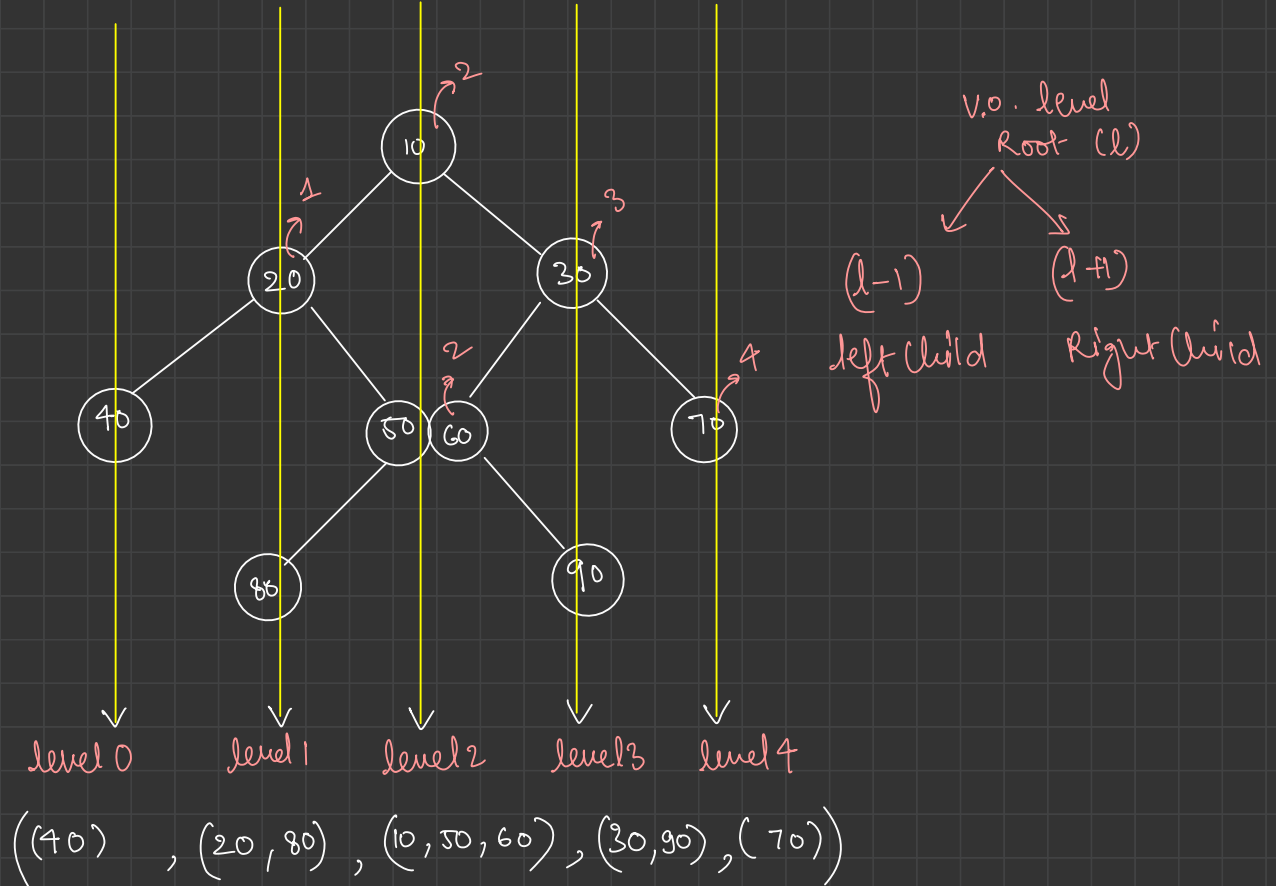
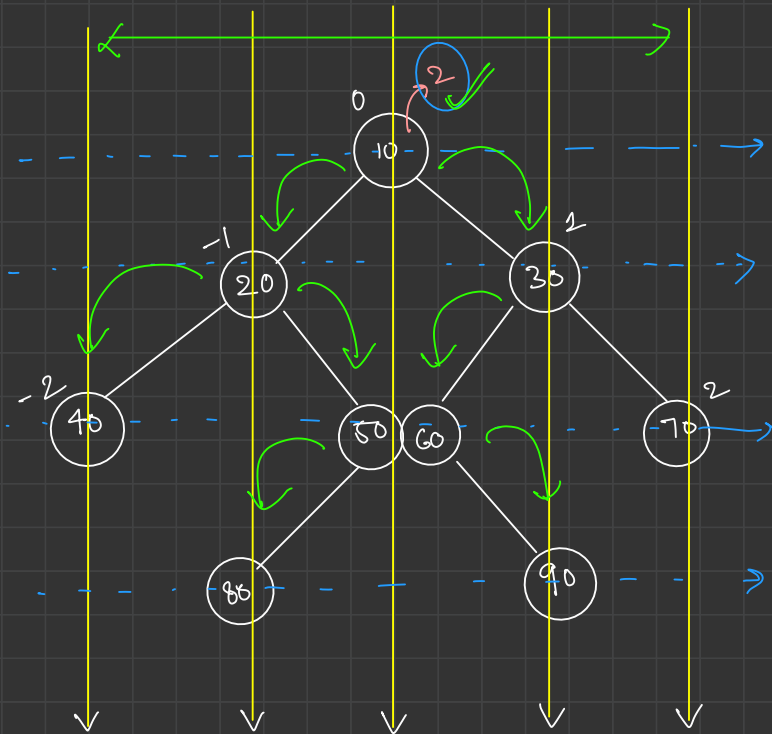




Vertical Order Traversal





for the left Most Node In tree

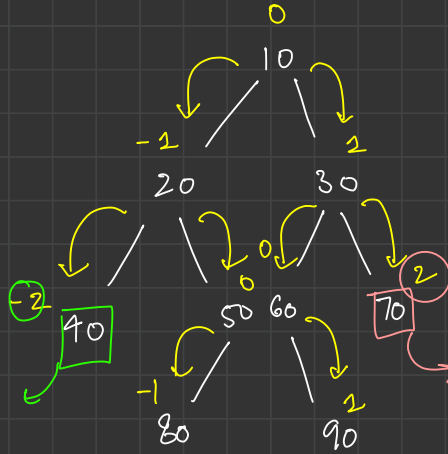
node
val. level
~~(10,2)~~ ~~(20,1)~~ ~~(30,3)~~ ~~(40,0)~~ ~~(50,2)~~
queue

~~(60,2)~~ ~~(70,4)~~ ~~(80,1)~~ ~~(90,3)~~

level 0 level 1 level 2 level 3 level 4

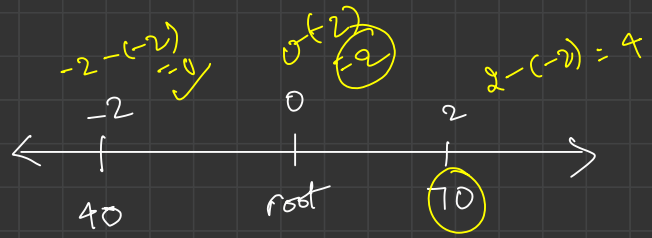
$((40), (20, 80), (10, 50, 60), (30, 90), (70))$

for rightmost Node in a tree



left Most Node

right Most Node



$$\checkmark \text{ No. of v. levels} = \text{right Most Idx} - \text{left Most Idx} + 1$$

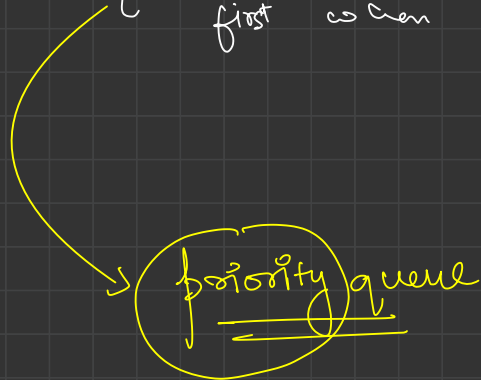
$$= 2 - (-2) + 1 = \underline{5} \text{ levels}$$

↪ {0, 1, 2, 3, 4}

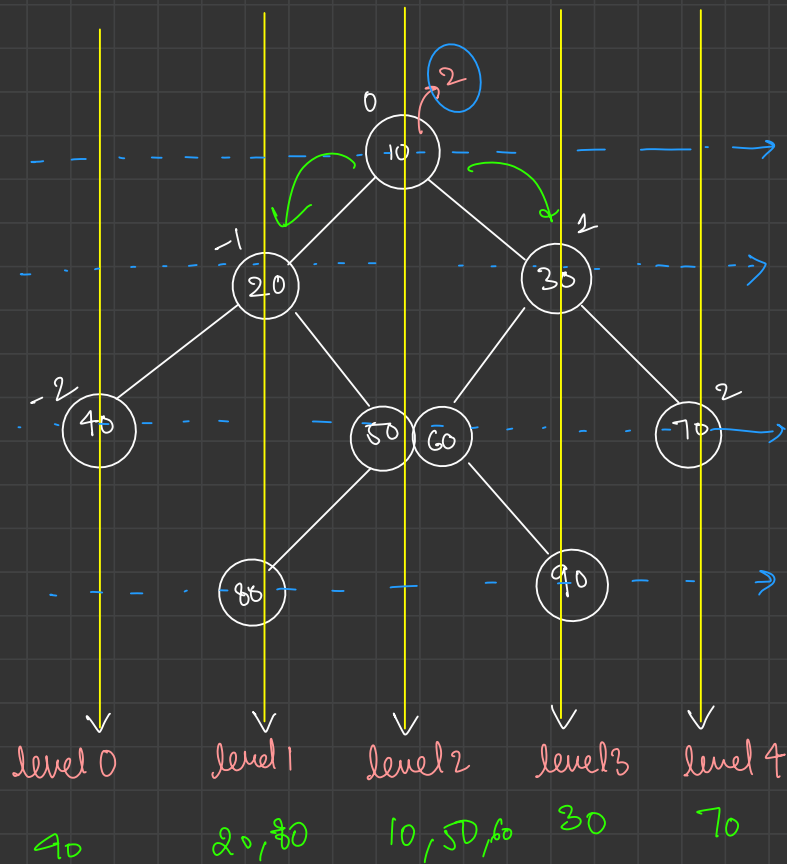
$$\checkmark \text{ V.O. level of root} = 0 - (\text{left Most Idx})$$

$$= - \text{left Most Idx}$$

{ we want some our own set of rules, applied to que, so min value exist first when v0 level, and level is same for 2 nodes



→ Our own custom priority!



(80, 1) (90, 3)

pa

temp

Rules

- Remove people with less v.o. level first
- If two nodes have same v-level remove person with smaller value

pre order
post order
In order

} traversal

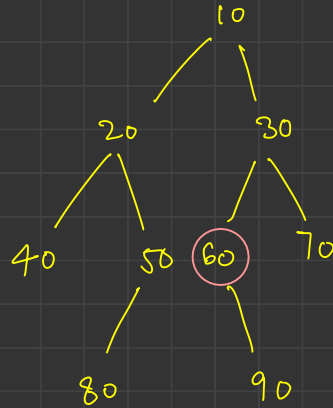
level order traversal
vertical order traversal
zigzag order traversal

}

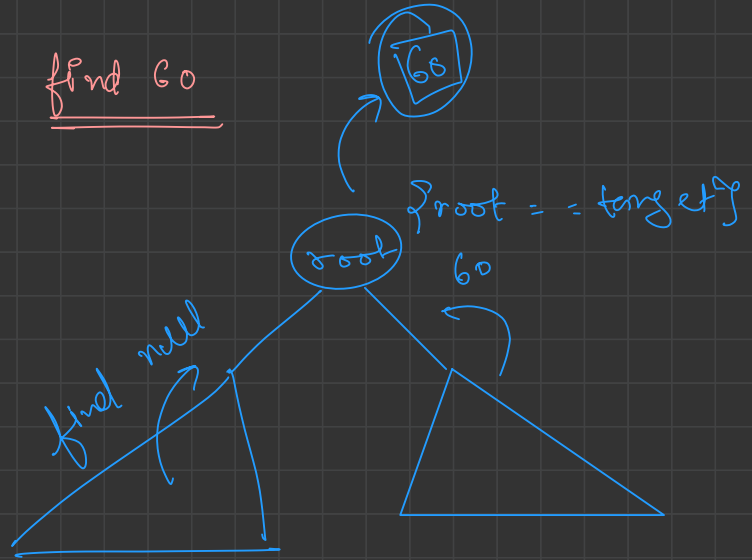
Views

{ left view
right view
top view
bottom view

Find a given node in a tree



find 60




```
boolean find (Node root, int target)
```

```
{  
  ① if (root == null) return false;
```

```
  ② if (root.data == target) return true;
```

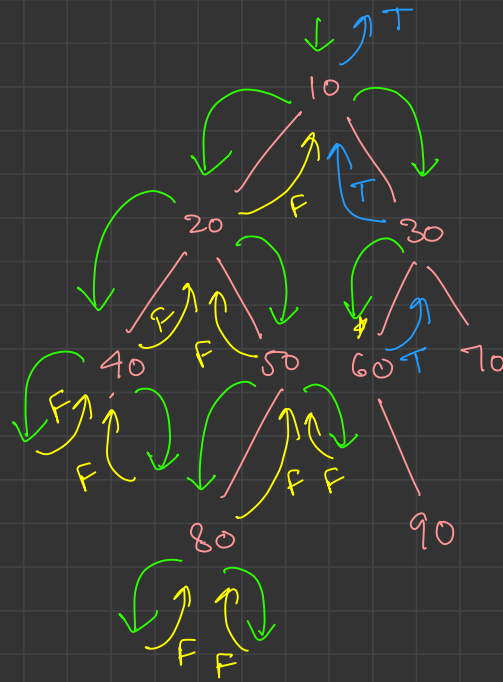
```
  ③ boolean file = find (root.left, target);
```

```
  ④ if (file == true) return true;
```

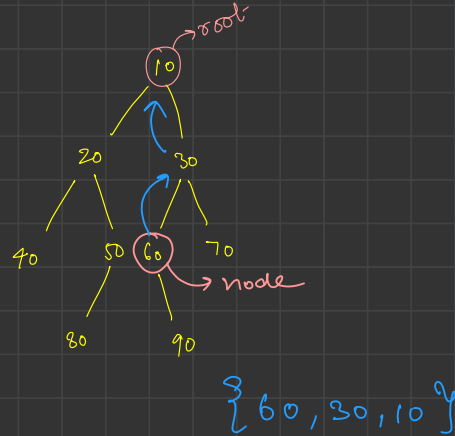
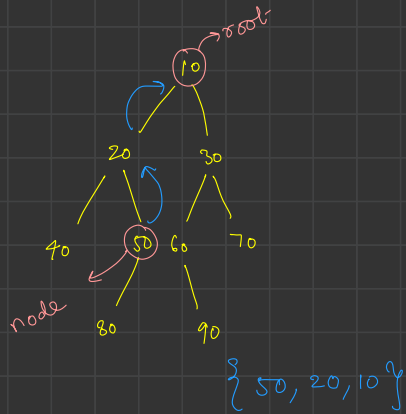
```
  ⑤ boolean file = find (root.right, target);
```

```
  ⑥ if (file == true) return true;
```

```
  ⑦ return false;  
}
```



Node To Root Path



```

ArrayList<Integer> n2r = new ArrayList<>();

boolean node2rootPath (Node root, int target) {
    if (root == null) {
        return false;
    }

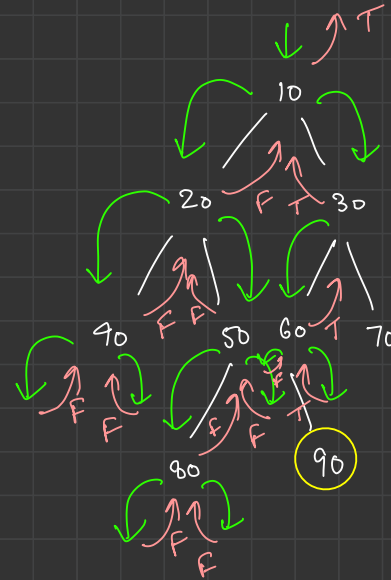
    if (root.data == target) {
        n2r.add(root.data);
        return true;
    }

    boolean filc = node2rootPath(root.left, target);
    if (filc == true) {
        n2r.add(root.data);
        return true;
    }

    boolean firr = node2rootPath(root.right, target);
    if (firr == true) {
        n2r.add(root.data);
        return true;
    }

    return false;
}

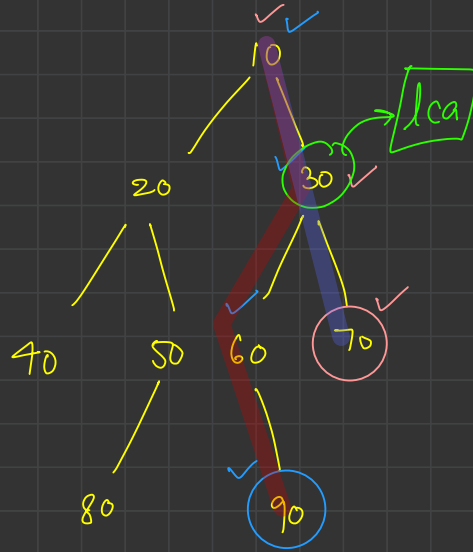
```



{ 90, 60, 30, 10 }

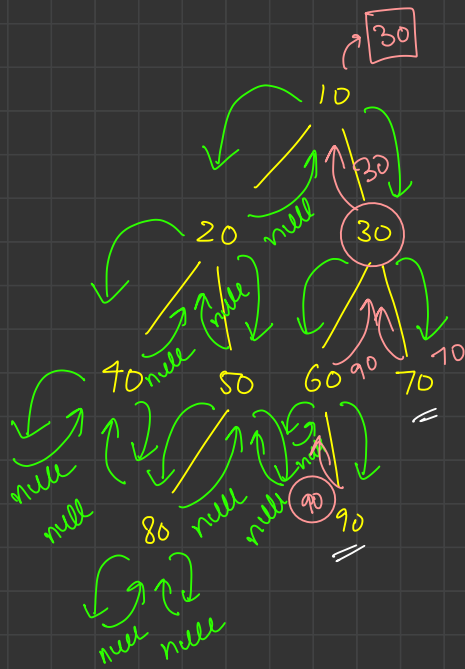
N2R

lca (lowest common ancestor)



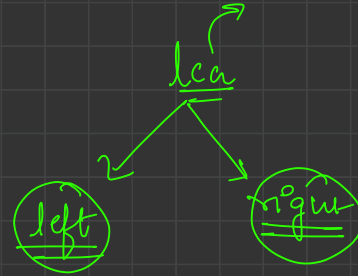
$90 \rightarrow \{90, 60, 30, 10\}$

$70 \rightarrow \{70, 30, 10\}$



$T.C: O(N)$
 $SC: O(H)$

$$(n_1 = 90, n_2 = 70)$$



Times of code

```

public static Node findLCA(Node node, int n1, int n2) {
    if (node == null) {
        return null;
    }

    if (node.data == n1 || node.data == n2) {
        return node;
    }

    Node lc = findLCA(node.left, n1, n2);
    Node rc = findLCA(node.right, n1, n2);

    if (lc != null && rc != null) {
        return node;
    }

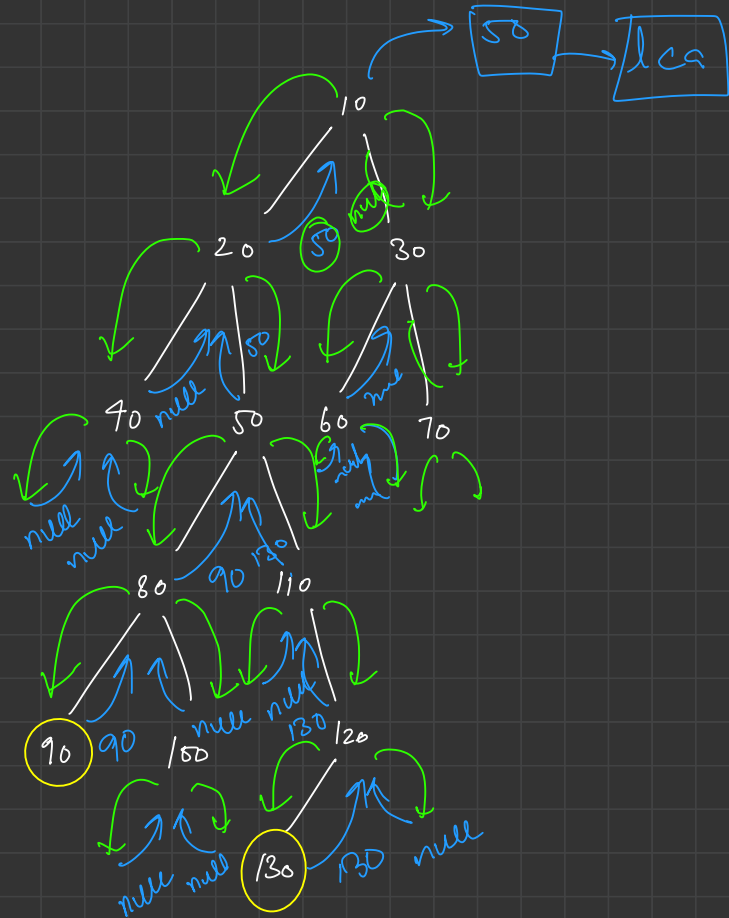
    if (lc != null) {
        return lc;
    }

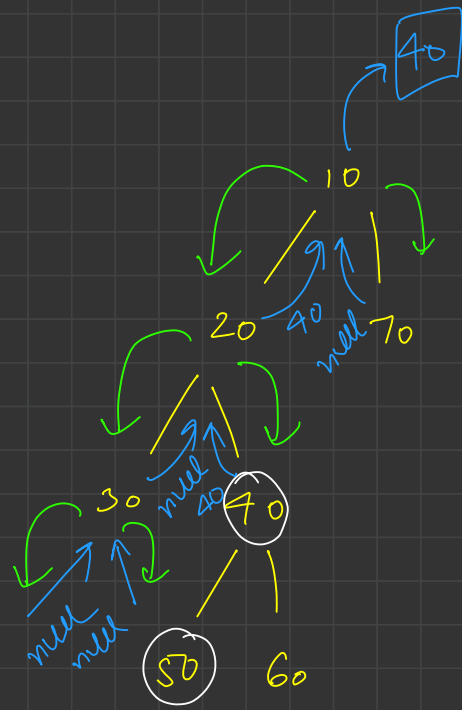
    if (rc != null) {
        return rc;
    }

    return null;
}

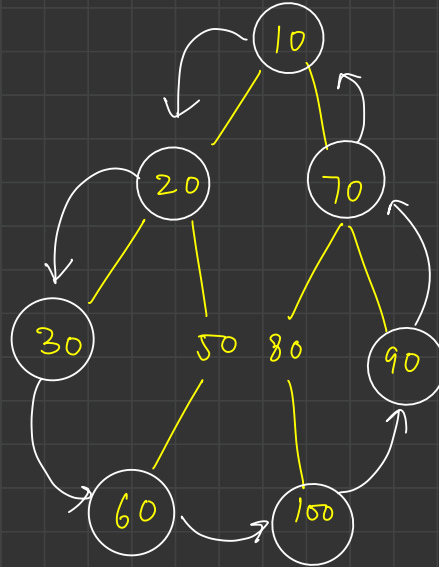
```

$\left. \begin{array}{l} TC: O(N) \\ SC: O(H) \end{array} \right\}$





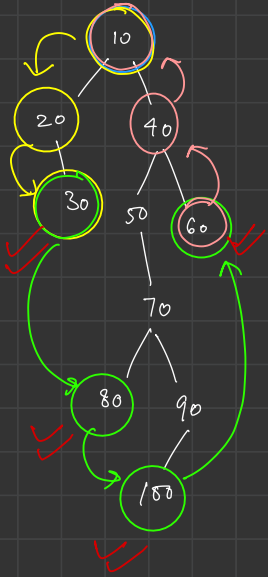
Boundary Traversal



$\{10, 20, 30, 60, 100, 90, 70, 10\}$

↓
Boundary

{10, 20, 30, 80, 100, 60, 70, 150}



Boundary of a tree

{ root + left wall + bottom wall + Right wall }

leaf Nodes from left to right

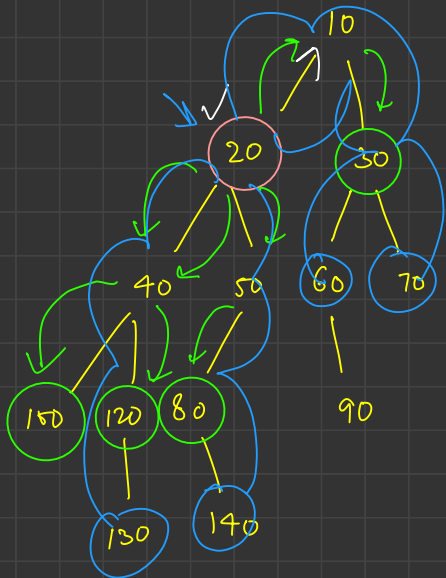
if left Not there they only go (right)
before call

if right is not there then only go (left)
add after call

All Nodes Distance K Away

node, Node
20 → 10

K=2



~~20~~ ~~40, 50, 10~~

{ 150, 120, 80, 30 }

150, 120, 80, 30

{ 150, 120, 80, 30 }