



# OPERATING SYSTEMS

## Classical Problems of Synchronization

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**Nitin V Pujari**  
**Faculty, Computer Science**  
**Dean - IQAC, PES University**

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## Course Syllabus - Unit 2

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**12 Hours**

### Unit 2: Threads & Concurrency

Introduction to Threads, types of threads, Multicore Programming, Multithreading Models, Thread creation, Thread Scheduling, PThreads and Windows Threads, Mutual Exclusion and Synchronization: software approaches, principles of concurrency, hardware support, Mutex Locks, Semaphores. Classic problems of Synchronization: Bounded-Buffer Problem, Readers -Writers problem, Dining Philosophers Problem concepts. Synchronization Examples - Synchronisation mechanisms provided by Linux/Windows/Pthreads. Deadlocks: principles of deadlock, tools for detection and Prevention.

# OPERATING SYSTEMS

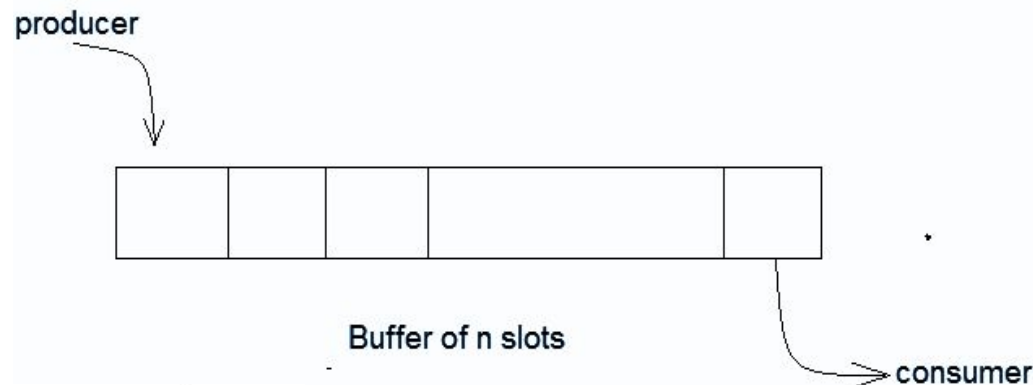
## Course Outline



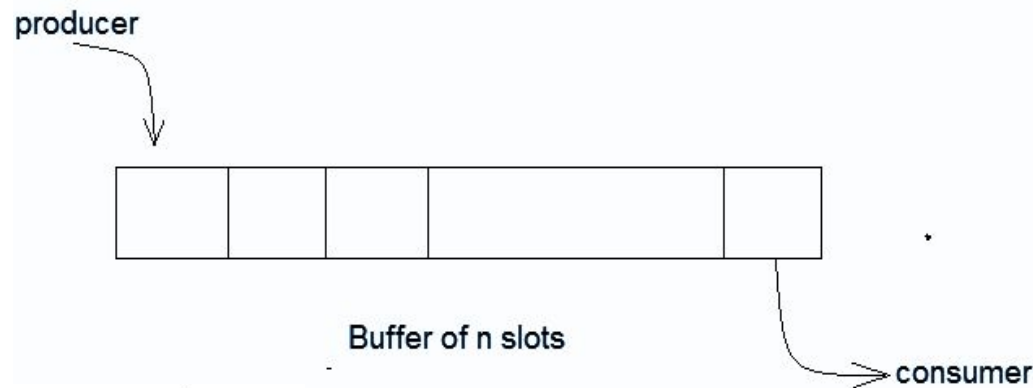
13	Introduction to Threads, types of threads, Multicore Programming, Multithreading Models	4.1 – 4.3	42.8
14	Thread creation, Thread Scheduling	5.4	
15	Pthreads and Windows Threads	4.4	
16	Mutual Exclusion and Synchronization: software approaches,	6.1-6.2	
17	principles of concurrency, hardware support	6.3-6.4	
18	Mutex Locks, Semaphores	6.5, 6.6	
19	Classic problems of Synchronization: Bounded-Buffer Problem, Readers-Writers problem	6.7-6.8	
20	Dining-Philosophers Problem	6.8	
21	Synchronization Examples: Synchronisation mechanisms provided by Linux/Windows/Pthreads.	6.9	
22	Deadlocks: principles of deadlock, Deadlock Characterization	7.1-7.3	
23	Deadlock Prevention, Deadlock example	7.4-7.5	
24	Deadlock Detection, Algorithm	7.6	

- Bounded Buffer Problem
- The Readers – Writers Problem

- Bounded buffer problem, which is also called **producer consumer problem**, is one of the classical problems of synchronization.
- There is a buffer of  $n$  slots and each slot is capable of storing one unit of data.
- There are two processes running, namely, **producer** and **consumer**, which are operating on the buffer.



- A producer tries to insert data into an empty slot of the buffer. A consumer tries to remove data from a filled slot in the buffer. As discussed earlier, those two processes won't produce the expected output if they are being executed concurrently.
- There needs to be a way to make the producer and consumer work



- One solution of this problem is to use semaphores. The semaphores which will be used here are:
  - mutex - a **binary semaphore** which is used to acquire (wait) and release(signal) the lock.
  - empty a **counting semaphore** whose initial value is the number of slots in the buffer, since, initially all slots are empty.
  - full, a **counting semaphore** whose initial value is 0.
- At any instant, the current value of empty represents the number of empty slots in the buffer and full represents the number of occupied slots in the buffer.

- The structure of the producer process

```
do {  
    ...  
    /* produce an item in next_produced */  
    ...  
    wait(empty);  
    wait(mutex);  
    ...  
    /* add next produced to the buffer */  
    ...  
    signal(mutex);  
    signal(full);  
} while (true);
```

- The structure of the consumer process

```
Do {  
    wait(full);  
    wait(mutex);  
    ...  
    /* remove an item from buffer to next_consumed */  
    ...  
    signal(mutex);  
    signal(empty);  
    ...  
    /* consume the item in next consumed */  
    ...  
} while (true);
```



- The structure of the producer process

```
do {  
    ...  
    /* produce an item in next_produced */  
    ...  
    wait(empty);  
    wait(mutex);  
    ...  
    /* add next produced to the buffer */  
    ...  
    signal(mutex);  
    signal(full);  
} while (true);
```

- The structure of the consumer process

```
Do {  
    wait(full);  
    wait(mutex);  
    ...  
    /* remove an item from buffer to next_consumed */  
    ...  
    signal(mutex);  
    signal(empty);  
    ...  
    /* consume the item in next consumed */  
    ...  
} while (true);
```

- A data set is shared among a number of concurrent processes
  - Readers – only read the data set; they do not perform any updates
  - Writers – can both read and write
- Problem=> allow multiple readers to read at the same time
- Only one single writer can access the shared data at the same time

- Several variations of how readers and writers are considered => all involve some form of priorities
- Shared Data
  - Data set
  - Semaphore `rw_mutex` initialized to 1
  - Semaphore `mutex` initialized to 1
  - Integer `read_count` initialized to 0

- The structure of a reader process

```
do {
    wait(mutex);
    read_count++;
    if (read_count == 1)
        wait(rw_mutex);
    signal(mutex);

    /* reading is performed */
    ...

    wait(mutex);
    read_count--;
    if (read_count == 0)
        signal(rw_mutex);
    signal(mutex);
} while (true);
```

- The structure of a writer process

```
do {
    wait(rw_mutex);

    ...
    /* writing is performed */
    ...

    signal(rw_mutex);
} while (true);
```

- The structure of a reader process

```
do {  
    wait(mutex);  
    read_count++;  
    if (read_count == 1)  
        wait(rw_mutex);  
    signal(mutex);  
  
    /* reading is performed */  
    ...  
    wait(mutex);  
    read_count--;  
    if (read_count == 0)  
        signal(rw_mutex);  
    signal(mutex);  
} while (true);
```

- The structure of a writer process

```
do {  
    wait(rw_mutex);  
  
    ...  
    /* writing is performed */  
    ...  
    signal(rw_mutex);  
} while (true);
```

- First variation => no reader kept waiting unless writer has permission to use shared object
- Second variation => once writer is ready, it performs the write ASAP
- Both may have starvation leading to even more variations
- Problem is solved on some systems by kernel providing reader-writer locks



**THANK YOU**

**Nitin V Pujari**  
**Faculty, Computer Science**  
**Dean - IQAC, PES University**

**nitin.pujari@pes.edu**

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