Design and Analysis of Algorithms (UE18CS251)

Unit III - Transform-and-Conquer

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Transform-and-Conquer:

problem's instance another representation or another problem's instance

Presorting:

Interest in sorting algorithms is due, to a significant degree, to the fact that many questions about a list are easier to answer if the list is sorted.

ist sorted list solution

Finding the **largest element** in an array of **n** numbers using the following approaches:

- 1. Brute Force
- 2. Decrease-n-Conquer
- 3. Divide-n-Conquer
- 4. Transform-n-Conquer (Presorting-based)

Checking element uniqueness in an array using presorting-based technique.

Analyze its time efficiency.

ALGORITHM PresortElementUniqueness(A[0..n-1])

//Solves the element uniqueness problem by sorting the array first //Input: An array A[0..n-1] of orderable elements //Output: Returns "true" if A has no equal elements, "false" otherwise sort the array A

for $i \leftarrow 0$ to n-2 do if A[i] = A[i+1] return false

return true

$$T(n) = T_{sort}(n) + T_{scan}(n) \in \Theta(n \log n) + \Theta(n)$$
$$= \Theta(n \log n)$$

Computing a mode in an array using presorting-based technique.

Analyze its time efficiency.

```
ALGORITHM PresortMode(A[0..n-1])
    //Computes the mode of an array by sorting it first
    //Input: An array A[0..n-1] of orderable elements
    //Output: The array's mode
    sort the array A
                               //current run begins at position i
    i \leftarrow 0
    modefrequency \leftarrow 0 //highest frequency seen so far
    while i \le n-1 do
        runlength \leftarrow 1; \quad runvalue \leftarrow A[i]
        while i + runlength \le n - 1 and A[i + runlength] = runvalue
             runlength \leftarrow runlength + 1
        if runlength > modefrequency
             modefrequency \leftarrow runlength;
                                                modevalue \leftarrow runvalue
        i \leftarrow i + runlength
    return modevalue
```

Computing a mode in an array using presorting-based technique.

Analyze its time efficiency.

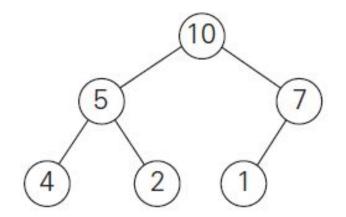
$$T(n) = T_{sort}(n) + T_{scan}(n) \in \Theta(n \log n) + \Theta(n)$$
$$= \Theta(n \log n)$$

Searching an element in an array using presorting-based technique.

Analyze its time efficiency.

$$T(n) = T_{sort}(n) + T_{search}(n) \in \Theta(n \log n) + \Theta(\log n)$$
$$= \Theta(n \log n)$$

Heaps:

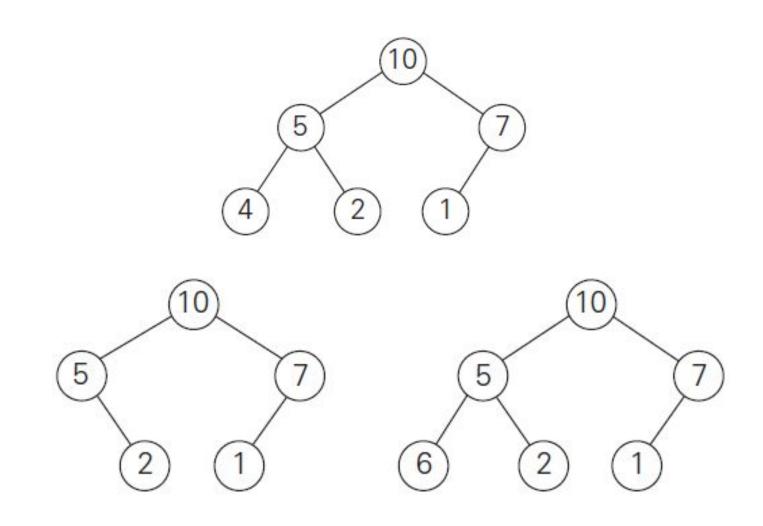


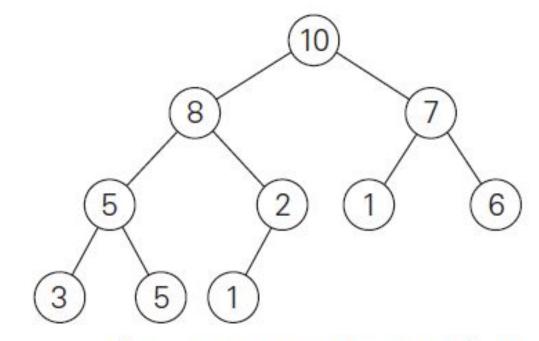
A *heap* can be defined as a binary tree with keys assigned to its nodes, one key per node, provided the following two conditions are met:

- 1. The *shape property*—the binary tree is *essentially complete* (or simply *complete*), i.e., all its levels are full except possibly the last level, where only some rightmost leaves may be missing.
- 2. The *parental dominance* or *heap property*—the key in each node is greater than or equal to the keys in its children. (This condition is considered automatically satisfied for all leaves.)

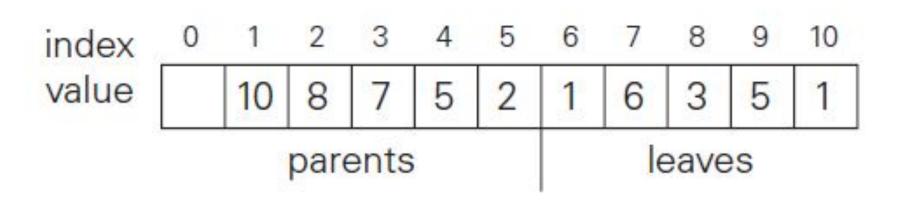
Heaps:

Which of the following are heaps?





the array representation

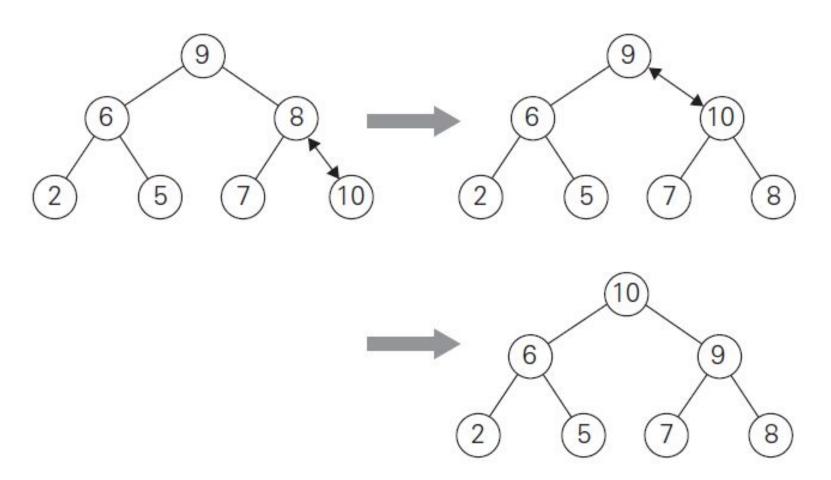


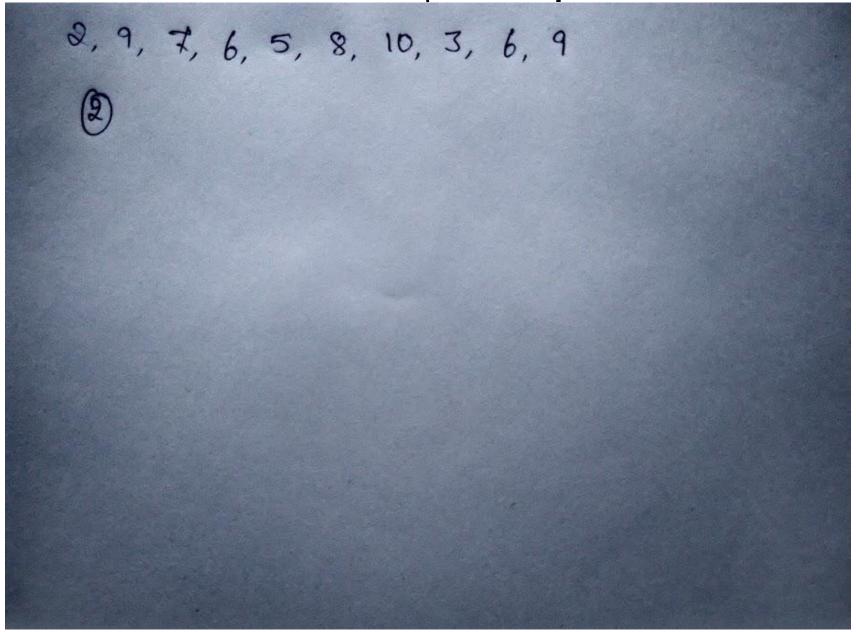
A heap can be implemented as an array by recording its elements in the top-down, left-to-right fashion (BFS-way). In such a representation (for convenience let's store the heap's elements in positions 1 through n of the array),

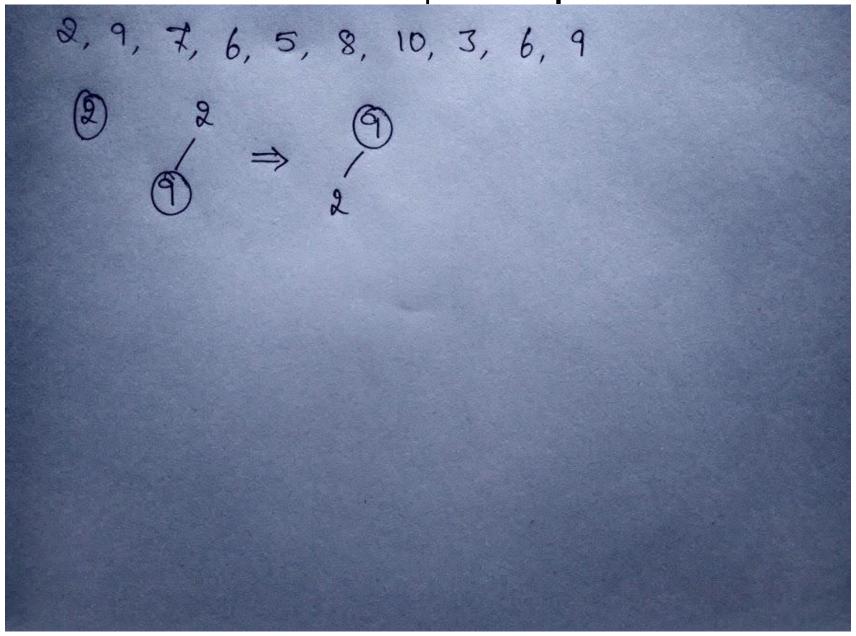
- the parental node keys will be in the first Ln/2J positions of the array, while the leaf keys will occupy the last Γn/21 positions.
- the children of a key in the array's parental position i
 (1 ≤ i ≤ Ln/2J) will be in positions 2i and 2i+1, and,
 correspondingly, the parent of a key in position j
 (2 ≤ j ≤ n) will be in position Lj/2J.

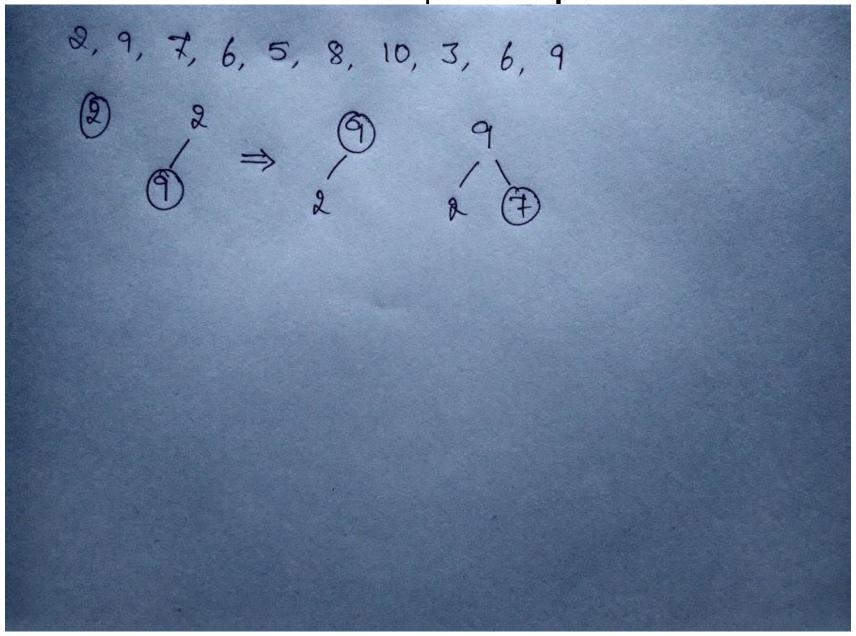
Inserting a new element in the heap:

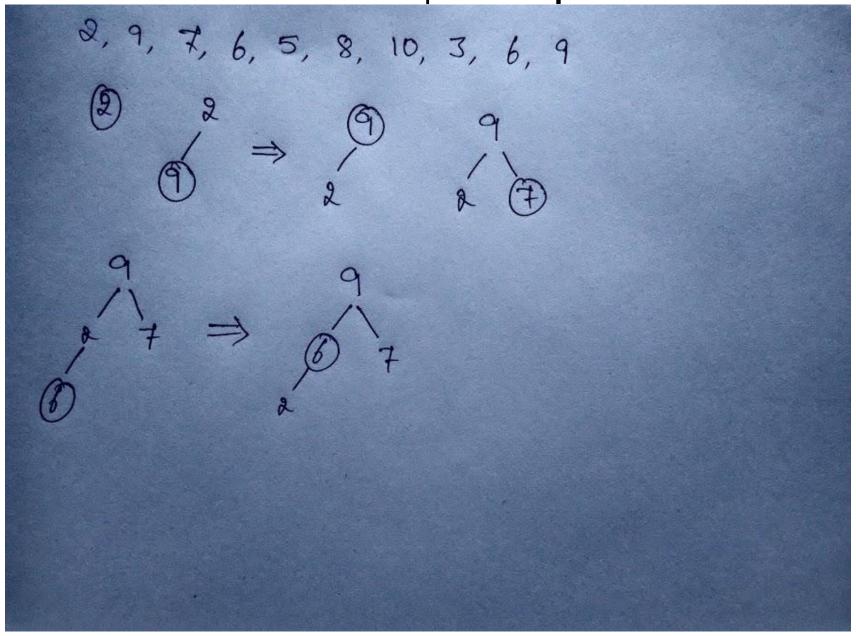
Add new element '10' to the existing heap.

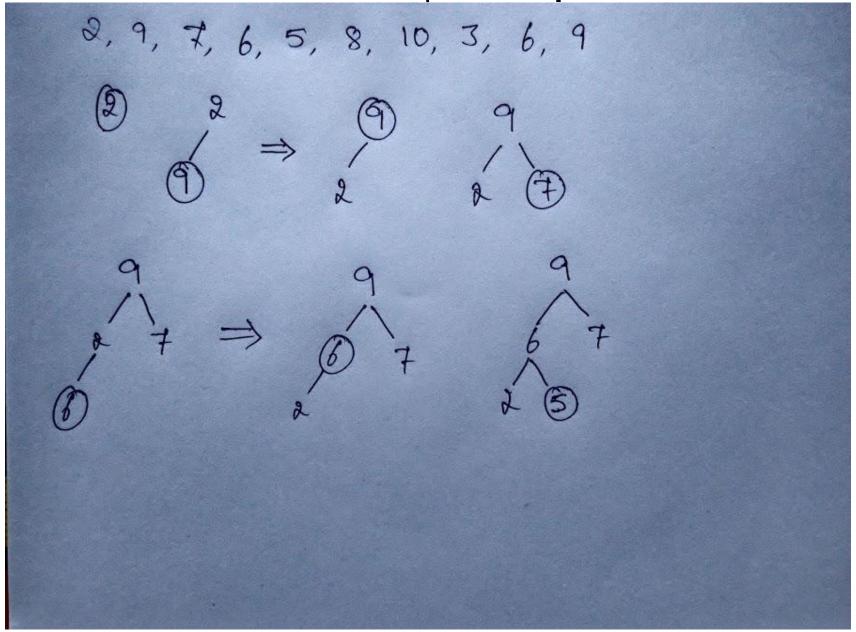


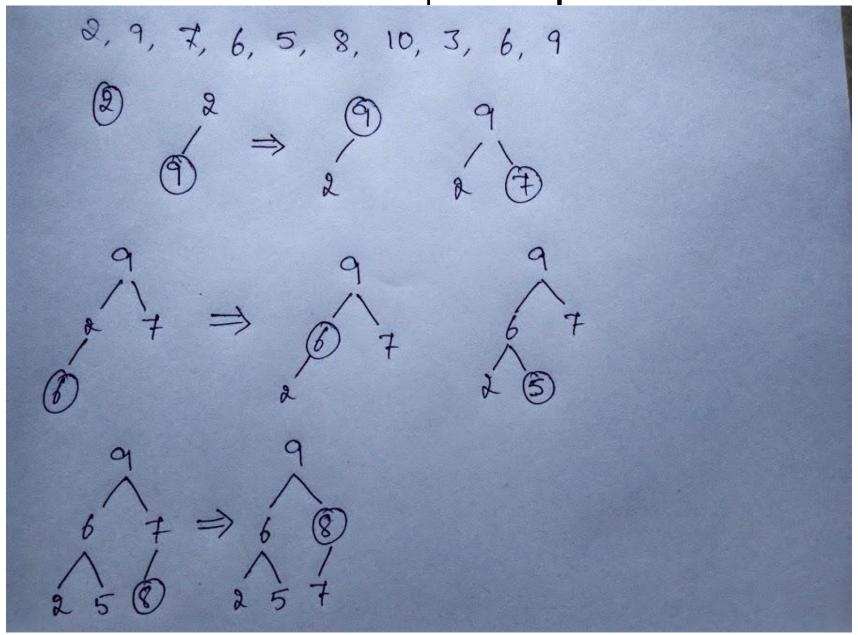


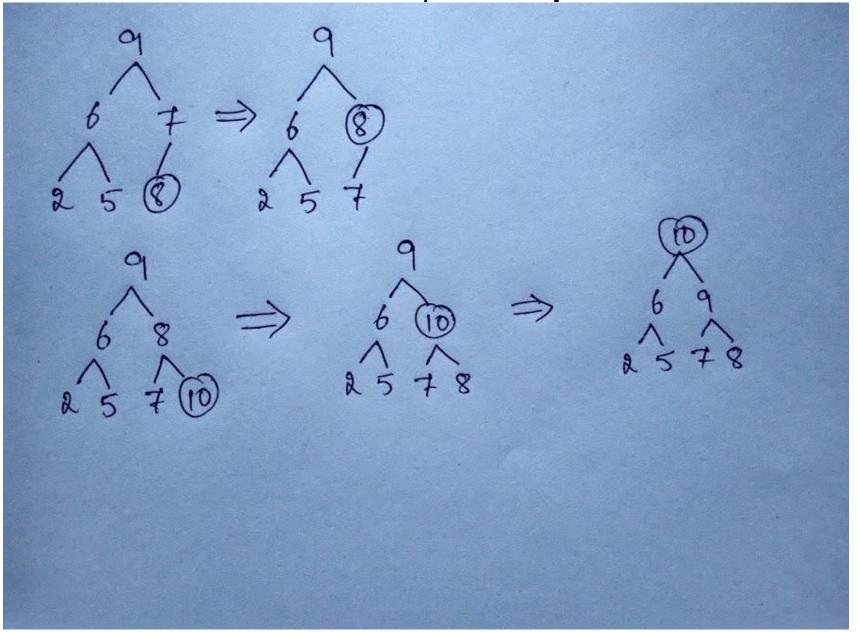


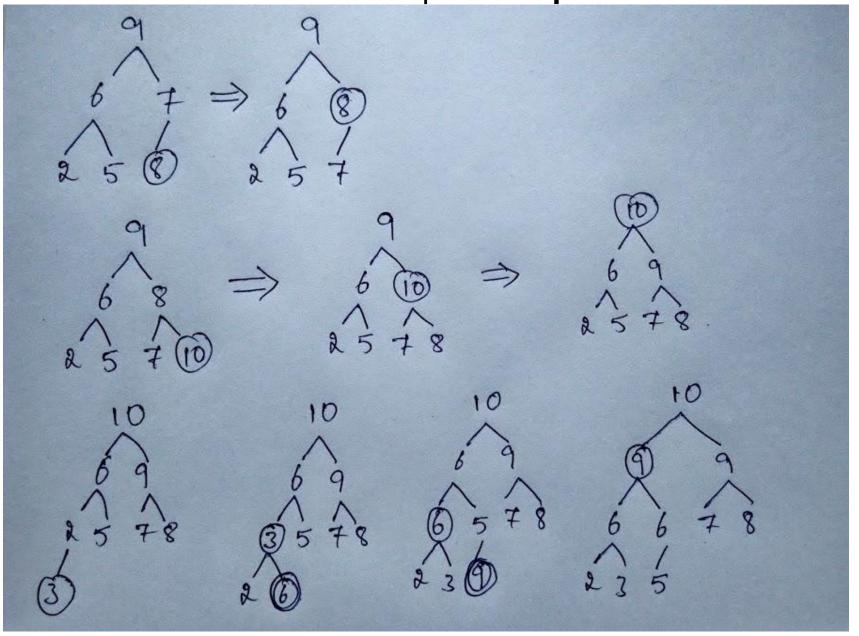


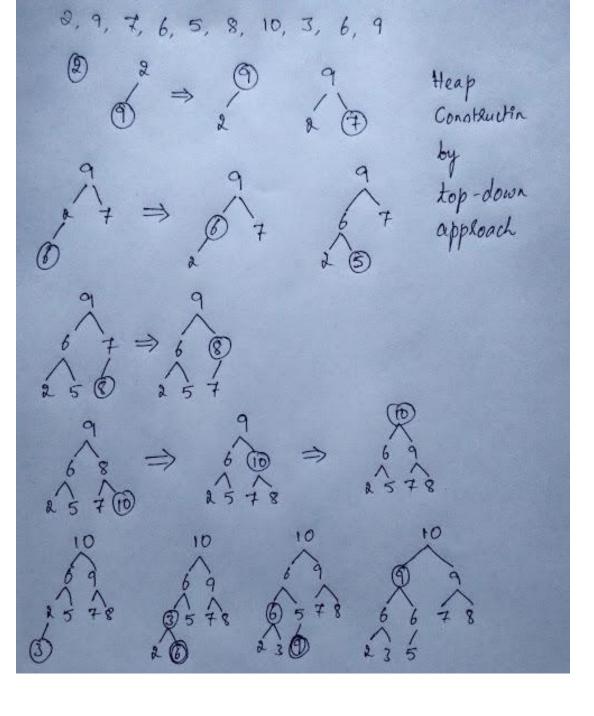




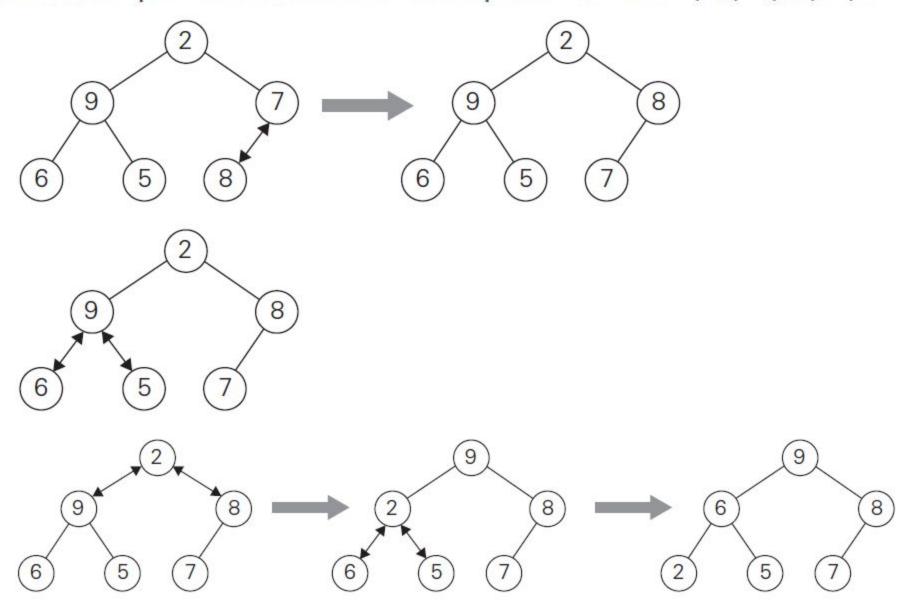








Bottom-up construction of a heap for the list 2, 9, 7, 6, 5, 8.



2 7 6 8 10

Heap Constluction by bottom-up apphach.

Heap Constluction by 10, 3, 6, 9

Heap Constluction by

Heap Constluction by bottom-up approach.

```
HeapBottomUp(H[1..n])
   if (n \le 1) return
    for i \leftarrow |n/2| downto 1 do
       Heapify(H, i)
//For the subtree rooted at k, it sifts down H[k]
//as much as possible until it becomes a heap.
Heapify (H[1..n], k)
    if (2*k > n) return //if H[k] is a leaf
    \mathbf{j} \leftarrow 2 \mathbf{k} //j points to left child of H[k]
    if (j+1 \leq n) //if there exists a right child of H[k]
       if(H[j+1] > H[j]) j \leftarrow j+1
    if (H[j] > H[k]) //if greater child is greater than H[k]
       H[\dot{j}] \leftrightarrow H[k]
       Heapify (H, j) //Heapify the subtree rooted at j
```

```
ALGORITHM HeapBottomUp(H[1..n])
     //Constructs a heap from elements of a given array
     // by the bottom-up algorithm
     //Input: An array H[1..n] of orderable items
     //Output: A heap H[1..n]
     for i \leftarrow \lfloor n/2 \rfloor downto 1 do
          k \leftarrow i; \quad v \leftarrow H[k]
          heap \leftarrow false
          while not heap and 2 * k \le n do
               i \leftarrow 2 * k
               if j < n //there are two children
                    if H[j] < H[j+1] \ j \leftarrow j+1
               if v \geq H[j]
                    heap \leftarrow true
               else H[k] \leftarrow H[j]; \quad k \leftarrow j
          H[k] \leftarrow v
```

Efficiency of construction of heap from bottom-up:

Let h be the height of the tree.

Two key comparisons at level of trickle down of an element.

$$h = \lfloor \log_2 n \rfloor$$

$$C_{worst}(n) = \sum_{i=0}^{h-1} \sum_{\text{level } i \text{ keys}} 2(h-i)$$

$$= \sum_{i=0}^{h-1} 2(h-i)2^{i}$$

$$\cong 2n \subseteq \Theta(n)$$

$$C(n) = \sum_{i=0}^{h-1} 2^{i}(h-i)$$

$$= (h \sum_{i=0}^{h-1} 2^{i}) - (\sum_{i=0}^{h-1} 2^{i} \cdot 2^{i})$$

$$= h (2h-1) - ((h-2)2h+2)$$

$$\vdots \sum_{i=1}^{n} 2^{i} = (n-1)2^{n+1}+2$$

$$C(n) = h 2h - h - h 2h + 2h + 1 - 2$$

$$= 2^{h+1} - h - 2$$

$$h = \lfloor \log_{2} n \rfloor$$

$$C(n) = 2^{1+\lfloor \log_{2} n \rfloor} - h - 2 \in O(n)$$

$$\sum_{i=1}^{n} i \, 2^{i} = (n-1) \, 2^{n+1} + 2$$

$$= 1 \cdot 2^{i} + 2 \cdot 2^{2} + 3 \cdot 2^{3} + 4 \cdot 2^{4} + \dots + n \cdot 2^{n}$$

$$= 2^{i} + 2^{2} + 2^{3} + 2^{4} + \dots + 2^{n}$$

$$+ 2^{3} + 2^{4} + \dots + 2^{n}$$

$$+ 2^{n+1} + 2^{n} + 2^{n} + 2^{n}$$

$$= n \cdot 2^{n+1} - (2^{n+1} - 2^{n}) = (n-1) 2^{n+1} + 2$$

$$= n \cdot 2^{n+1} - (2^{n+1} - 2^{n}) = (n-1) 2^{n+1} + 2$$

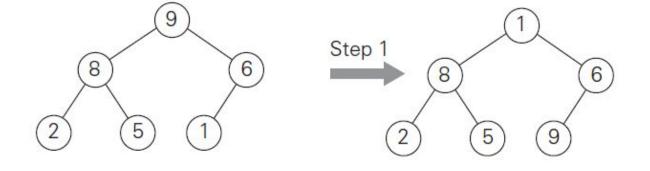
Heapsort discovered by J. W. J. Williams

This is a two-stage algorithm

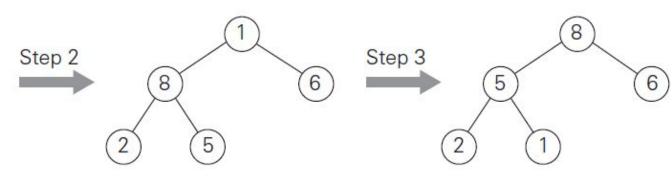
- Stage 1 (heap construction):

 Construct a heap for a given array.
- Stage 2 (maximum deletions): Apply the root-deletion operation n-1 times to the remaining heap.

Maximum Key Deletion from a heap



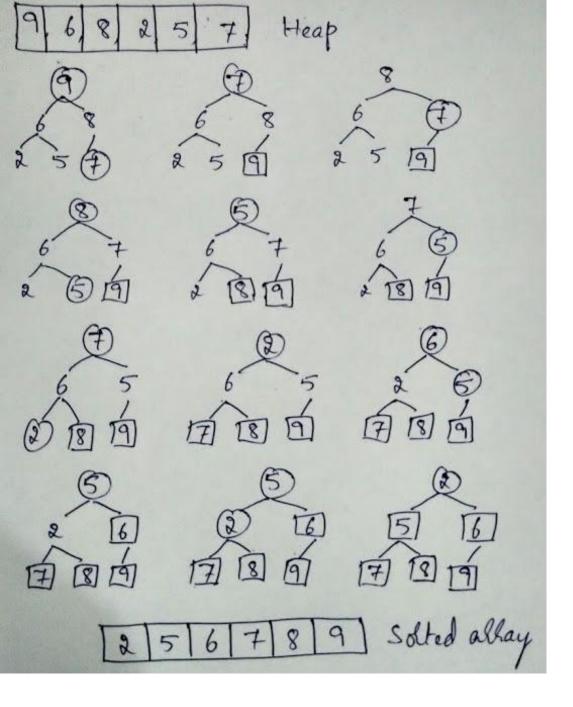
 Exchange the root's key with the last key K of the heap.

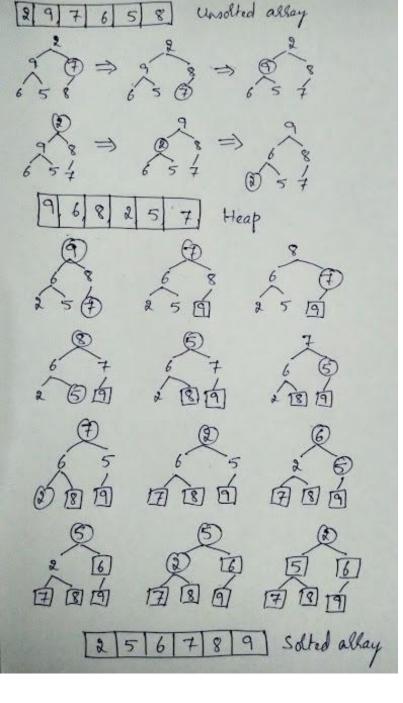


- 2. Decrease the heap's size by 1.
- 3. "Heapify" the smaller tree by sifting K down the tree exactly in the same way we did it in the bottom-up heap construction algorithm.

```
HeapSort(H[1..n])
   HeapBottomUp(H[1..n]) //Construct heap
    for i ← n downto 2 do
       H[1] \leftrightarrow H[i] //H[1] has the max element.
       Heapify (H[1..i-1], 1) //Sift down H[1]
HeapBottomUp(H[1..n])
   if (n \le 1) return
    for i \leftarrow \lfloor n/2 \rfloor downto 1 do
       Heapify(H, i)
Heapify (H[1..n], k)
    if(2*k > n) return //if H[k] is a leaf
    j ← 2*k //j points to left child of H[k]
    if (j+1 \le n) //if there exists a right child of H[k]
       if(H[j+1] > H[j]) j \leftarrow j+1
    if(H[j] > H[k]) //if greater child is greater than H[k]
       H[j] \leftrightarrow H[k]
       Heapify (H, j) //Heapify the subtree rooted at j
```

Unsolted allay 8





Analysis of Heapsort:

 $T_{Heapsort}(n) = T_{Heap}(n) + T_{Sort}(n)$

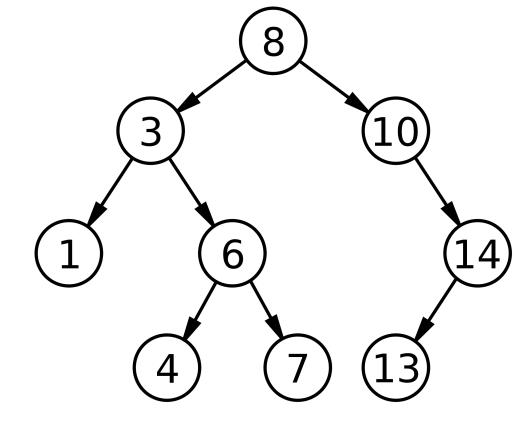
 $T_{\text{Heapsort}}(n) \in \max\{\Theta(n), \Theta(n \log n)\}$

 $T_{\text{Heapsort}}(n) \in \Theta(n \log n)$

Binary Trees

Binary Search Trees (BST)

What do we "conquer" by transforming a Binary Tree into a BST?



[Optional]

- Boolean isBST(BinaryTree t);
- BST BT2BST(BinaryTree t); //do it in-place

Binary Trees

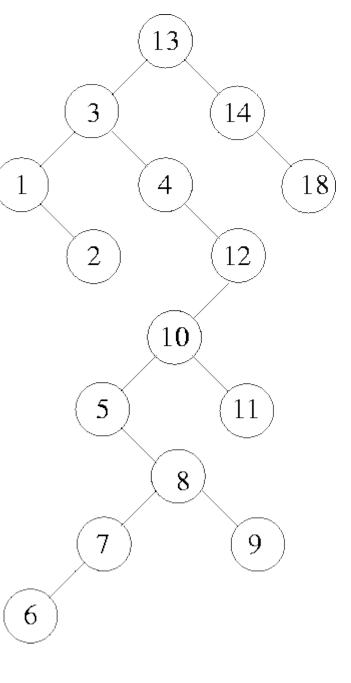
Binary Search Trees (BST)

What do we "conquer" by transforming a Binary Tree into a BST?

Search!

Time complexity of

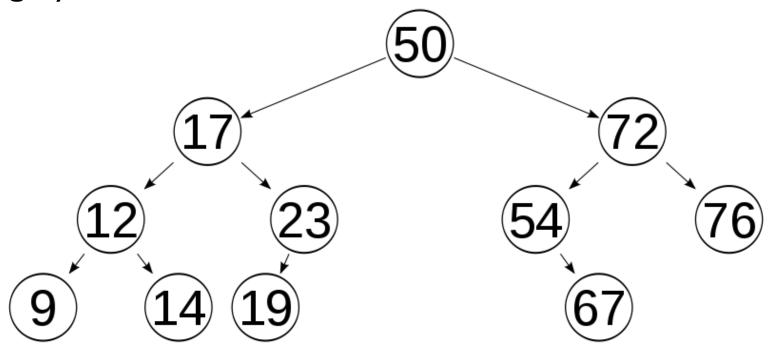
- Inserting an element into a BST:
- Searching for an element in a BST:
 - Average case:
 - O Worst case:



Balanced Binary Search Trees:

Time complexity of worst-case of search in a BST is O(n)

How can we keep the BST balanced so that the worst-case is just **O(log n)** because the height of the tree is limited to **O(log n)**?



Balanced Binary Search Trees:

Time complexity of worst-case of search in a BST is O(n)

How can we keep the BST balanced so that the worst-case is just **O(log n)** because the height of the tree is limited to **O(log n)**?

- 1. AVL Trees
- 2. Red-Black Trees
- 3. Splay Trees
- 4. 2-3 Trees
 - a. Not exactly a BST.

It's not even a Binary Tree.

It's a **Balanced Search Tree**.

Transform for good!

</ End of Transform-n-Conquer >