Take Home Exam 3

## Regulations:

• Submission: We provide a latex template for your solutions. Use that template and submit a "the3.tex" file that creates a "the3.pdf" file with the following command:

pdflatex the3.tex

Not using the given template, or failing to generate a valid pdf with the above command will result in you receiving a zero grade. This command will be run on inek machines where you can try generating the pdf file yourselves.

- **Deadline:** 23:55, 8 January, 2022 (Sunday).
- Late Submission: The solutions will be available after the deadline. Therefore, late submissions will not be allowed.
- 1. (25 pts, 10 + 15 pts) Consider the following continuous time system.

$$\begin{bmatrix} \dot{x}_1(t) \\ \dot{x}_2(t) \end{bmatrix} = \begin{bmatrix} -x_1 + x_2^2 \\ -2x_2 + 3x_1^2 \end{bmatrix}$$

Determine the stability of the fixed point  $\tilde{x} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ ,

- (a) via linearization.
- (b) using the Lyapunov theorem. You can use the Lyapunov function  $V(x_1, x_2) = \frac{x_1^2}{2} + \frac{x_2^2}{4}$ . First, show that the Lyapunov theorem is applicable in this case.
- 2. (25 pts) Consider the following discrete time system. Determine the stability of the fixed point  $\tilde{x} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$  using the Lyapunov theorem. First, find a suitable Lyapunov function and show that the Lyapunov theorem is applicable in

Lyapunov theorem. First, find a suitable Lyapunov function and show that the Lyapunov theorem is applicable this case.

$$\begin{bmatrix} x_1(k+1) \\ x_2(k+1) \\ x_3(k+1) \end{bmatrix} = \begin{bmatrix} \frac{1}{2}x_1 + \frac{1}{2}x_2 \\ \frac{1}{2}x_3 \\ \frac{1}{2}x_1 - \frac{1}{2}x_2 \end{bmatrix}$$

3. (25 pts) Consider the following continuous time system.

$$\begin{bmatrix} \dot{x}_1(t) \\ \dot{x}_2(t) \end{bmatrix} = \begin{bmatrix} x_1 + x_2 - 4x_1(x_1^2 + x_2^2) \\ -x_1 + x_2 - 4x_2(x_1^2 + x_2^2) \end{bmatrix}$$

Show that the system has a periodic limit cycle by using the Poincare-Bendixson theorem. You can use the Lyapunov function  $V(x_1, x_2) = \frac{x_1^2}{2} + \frac{x_2^2}{2}$ . (*Hint:* Show that the origin is the only fixed point.)

4. (25 pts, 5 + 15 + 5 pts) Consider the following discrete time system.

$$x(k+1) = 3 - x(k)^2$$

- (a) Find the fixed points of this system.
- (b) Find the periodic points of prime period 2. Comment on the relation between the fixed points and the periodic points of prime period 2 in terms of the equations that you use to calculate them.
- (c) For each periodic point, determine its stability.