Balanced Distributed Graph Processing

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Abstract

An abstract is like a movie trailer. It offers a preview, highlights key points, and helps the audience decide whether to view the entire work. Abstracts are the pivot of a research paper because many journal editorial boards screen manuscripts only on the basis of the abstract.

1 Introduction

The importance of balanced execution of big data frameworks (Papers to link: Osterhout[8], Themis[9], TritonSort[10]). Traditionally, while network was a part of the balancing equation, the network bandwidths considered were still less than 10gbps. However, with 40g networks becoming common and much higher bandwidths becoming available, we want to focus running balanced algorithms at these breakneck speeds.

Why we picked graph processing? Balanced sort has been well studied, there has been relatively less work in balanced performance for graph processing algorithms, especially at high bandwidths.

What we did or found out, in a nutshell.

2 Background

All about the graph processing frameworks and their computational models, basically a brief summary of [6]. And a bunch of related papers we have read, like comparison papers [5, 1] and some earlier graph processing systems these papers point to - such as Pregel[7], PowerGraph [4] and others.

Notes from Heidari et al. [6] Look at the paper for citations of all the statements below.

Q. Which algorithm to choose? Needs to be global, traversing the whole graph. Examples include page rank and connected components, degree distribution.

Q. Which programming model? Programming models used in existing frameworks (Section 3) - distributed vs shared memory architecture. While shared mem architectures work well for gigabtes of data (Scalability but at what cost paper), they don't scale to terabytes. There's also GPU and FPGA based acceleration proposed in some works, but we want to restrict ourselves to frameworks that run on commodity clusters.

Q. Which Programming abstraction?: 1. Vertex Centric: how it works and the shortcomings. Discuss some of the example frameworks. 2. Edge centric: how it works and the shortcomings. Discuss some of the example frameworks. 3. Component centric: how it works and the shortcomings. Discuss some of the example frameworks. 4. Others: Like MapReduce and other general purpose big-data processing frameworks.

Q. What sort of distributed coordination: 1. Synchronous - using barriers between iterations, makes life easier for programmer but sensitive to stragglers. 2. Asynchronous - better performance, but much complex to program and ensure error recovery. 3. Hybrid

Q. Input partitioning: 1. Static vs Dynamic: Do we reparition graph at runtime depending on algorithm or straggler issues. 2. Edge cut vs Vertex cut: How do we partition a non-uniform graph? What's best for the algorithm? This is one of the key design

choices that network performance could affect. Usually frameworks make one of these choices to minimize number of edges or vertices between to nodes to save on network, but is there a better way assuming infinite network bandwidth? (Think more about this!). This is something we could vary in our experiments.

Q. Others: Disk vs Memory based, fault tolerance with detection or recovery where choices are either clear or not important for our purposes.

3 Discussion

Here goes the discussion on what choices we made for our implementation w.r.t all the choices we discussed in the previous section. We will go with global algorithm like pagerank, on input graphs with uniform vertex and edge distribution to start with. We will go with synchronous model inspite of some performance disadvantages as it makes programming easier and is widely used. Since the kind of paritioning (vertex centric, edge centric or graph centric) should not matter that much for very uniform graphs, we will start with the most popular one i.e., vertex centric model. Choosing uniform graphs should help alleviate the skewed straggler problems affecting the synchronous model as well. We will go with static partitioning since page rank keeps all the vertices active throughout the run.

Then we do a theoretical analysis on the kind of network performance we could get. Given nodes of CPU c, memory m and network n for an input graph g = (v, e) what would a perfectly written distributed page rank program with above characteristics give us in terms of network performance?

Argue that while all of the design choices we discussed in background and in the first paragraph affects how balanced the resource usage of the run is going to be, the thing that seems to matter significantly is how input graph is partitioned. For the purposes of this project, we will look at how partitioning choices will affect the resource usage balance of a graph algorithm, particularly pagerank. More details on the partitioning is provided in the following section.

Instead of implementing distributed page rank from scratch, we decided to pick a one of the many graph processing frameworks available in the wild. We pickled giraph[3] for these reasons: very much in use, open sourced, matches much of the design choices we picked in the first paragraph, seen many recent optimizations from facebook [2], easier to plug in the partitioners, and more? Downside: takes too much time and tuning to setup, only allows vertex partitioning, and more?

4 Input Partitioning

Here goes the partitioning choices we chose to implement, how and why for each of those - and what we expect in terms of resource usage.

Giraph only supports vertex partitioning, so we are limited to that for now.

- Random Vertex
- Random edge
-

5 Apache Giraph

Description of Apache Giraph[3]. And bunch of optimizations made by Facebook[2].

6 Results

6.1 Input Graph Characteristics

We selected eleven graphs to analyze. Although we originally chose several others, we were limited by the hardware we had the funds to rent to analyzing relatively small graphs. A tradeoff exists between the size of a graph, the number of workers assigned to handle its vertices, and the amount of memory on a server. First, there is a minimum amount of memory that a Giraph worker requires in order to run. This puts an upper bound on the number of workers that can be run on any machine. Second, there appears

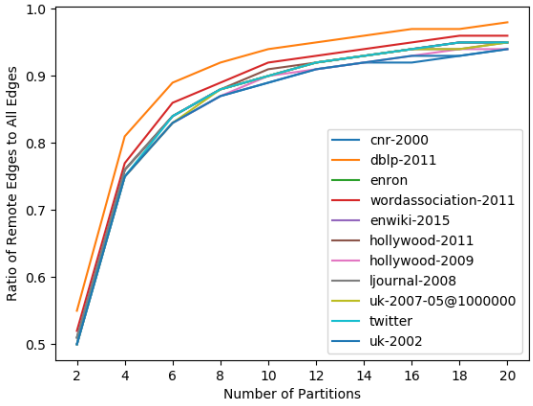

Figure 2: Ratio of remote edges (requiring messages to be sent across the network) to all edges for various numbers of partitions, where partitioning is done by taking the modulus of the vertex ID and number of workers.

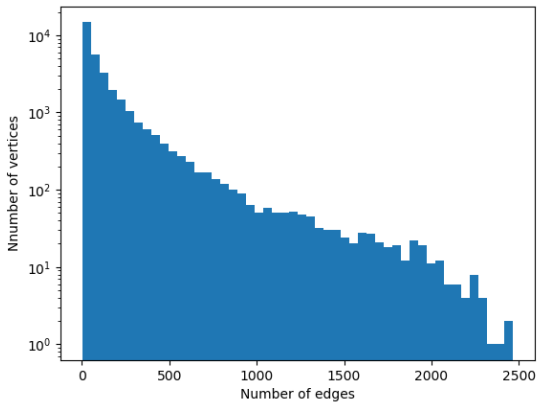

Figure 1: Degree distribution for a representative graph in our dataset, demonstrating that the graphs we chose are power-law graphs.

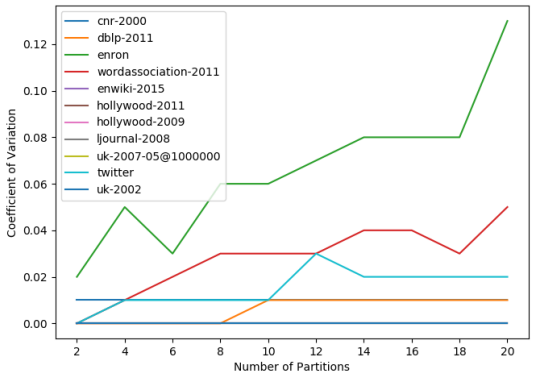

Figure 3: Range of the maximum number of edges handled by each worker to the minimum handled by any worker, expressed by the coefficient of variation, for various numbers of partitions, with modulo partitioning.

to be a minimum number of workers that can be assigned to a graph of a given size in Giraph: when too few are assigned, the job fails. Presumably, this is because each worker can only feasibly handle a certain number of vertices, although it is unclear why Giraph chooses to terminate jobs rather than allowing them to eventually complete. This factor puts a lower bound on the number of workers that can be assigned to a graph, which is dependent on the size of the graph. Given these constraints, we restricted ourselves to graphs with approximately 200 million edges or fewer.

6.2 Setting up Giraph

1. Look at all the settings file and decribe important settings 2. JNI error due to Java version mismatch 3. Lot of effort spent in adjusting getting the resource limits right - too many files to set configurations - no facilities for fine-tuned resource allocation - lot of out of memory exceptions due to tuning errors - incomprehensible error messages or errors hidden in remote corners of unknown log files - super-fragile, one change in setting causes an error in a completely unrelated place. - 8 hours from getting giraph built to getting the first job running without excepts 4.

6.3 Effect of different partition schemes

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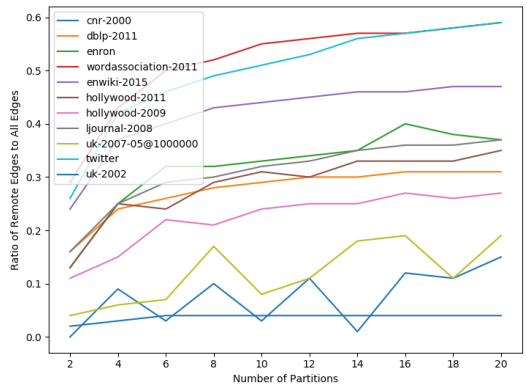

Figure 5: Ratio of remote edges to all edges for various numbers of partitions, where partitioning is done by segmenting the vertex IDs into approximately equal groups.

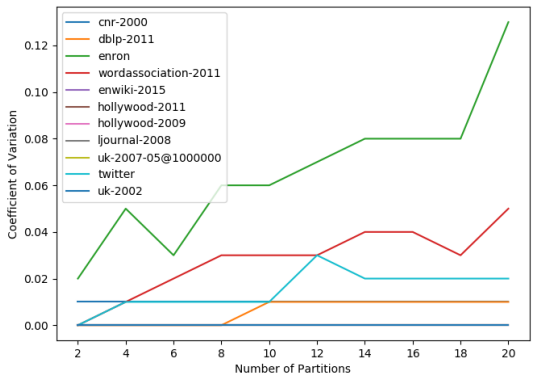

Figure 4: Range of the maximum number of edges handled by each worker to the minimum handled by any worker, expressed by the coefficient of variation, for various numbers of partitions, with segmented partitioning.

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