



SFI GEC PALAKKAD

MODULE 5

Rotation / circular motion

Thation of a body along a circular path.

The property of particle in circular motion is measured in terms of angular displacement of terms of angular displacement of terms of angular velocity, a = do attained to the property of the particle in the property of the particle in circular motion is measured in terms of angular velocity (revolution per sec.)

The property of the particle in circular path.

The particle in

tangential accelera, al = 7 d20 mgr soll=1

equations of motion and motion are children motion $\frac{\partial u_{2} = \omega_{1} + \alpha t}{\partial u_{2} = \omega_{1}^{2} + 2\alpha 0} = \frac{\partial u_{2} + 2\alpha 0}{\partial u_{2} + 2\alpha 0} = \frac{\partial u_{2} + 2\alpha 0}{\partial u_{2} + 2\alpha 0} = \frac{\partial u_{2} + 2\alpha 0}{\partial u_{2} + 2\alpha 0} = \frac{\partial u_{1} + \frac{1}{2}\alpha t^{2}}{\partial u_{2} + 2\alpha t} = \frac{\partial u_{1} + \frac{1}{2}\alpha t^{2}}{\partial u_{2} + 2\alpha t} = \frac{\partial u_{1} + \frac{1}{2}\alpha t^{2}}{\partial u_{2} + 2\alpha t} = \frac{\partial u_{1} + \frac{1}{2}\alpha t^{2}}{\partial u_{2} + 2\alpha t} = \frac{\partial u_{1} + \frac{1}{2}\alpha t^{2}}{\partial u_{2} + 2\alpha t} = \frac{\partial u_{1} + \frac{1}{2}\alpha t^{2}}{\partial u_{2} + 2\alpha t} = \frac{\partial u_{1} + \frac{1}{2}\alpha t^{2}}{\partial u_{2} + 2\alpha t} = \frac{\partial u_{1} + \frac{1}{2}\alpha t^{2}}{\partial u_{2} + 2\alpha t} = \frac{\partial u_{1} + \frac{1}{2}\alpha t^{2}}{\partial u_{2} + 2\alpha t} = \frac{\partial u_{1} + \frac{1}{2}\alpha t^{2}}{\partial u_{2} + 2\alpha t} = \frac{\partial u_{1} + \frac{1}{2}\alpha t^{2}}{\partial u_{2} + 2\alpha t} = \frac{\partial u_{1} + \frac{1}{2}\alpha t^{2}}{\partial u_{2} + 2\alpha t} = \frac{\partial u_{1} + \frac{1}{2}\alpha t^{2}}{\partial u_{2} + 2\alpha t} = \frac{\partial u_{1} + \frac{1}{2}\alpha t^{2}}{\partial u_{2} + 2\alpha t} = \frac{\partial u_{1} + \frac{1}{2}\alpha t^{2}}{\partial u_{2} + 2\alpha t} = \frac{\partial u_{1} + \frac{1}{2}\alpha t^{2}}{\partial u_{2} + 2\alpha t} = \frac{\partial u_{1} + \frac{1}{2}\alpha t^{2}}{\partial u_{1} + \frac{1}{2}\alpha t^{2}} = \frac{\partial u_{1} + \frac{1}{2}\alpha t^{2}}{\partial u_{1} + \frac{1}{2}\alpha t^{2}} = \frac{\partial u_{1} + \frac{1}{2}\alpha t^{2}}{\partial u_{1} + \frac{1}{2}\alpha t^{2}} = \frac{\partial u_{1} + \frac{1}{2}\alpha t^{2}}{\partial u_{1} + \frac{1}{2}\alpha t^{2}} = \frac{\partial u_{1} + \frac{1}{2}\alpha t^{2}}{\partial u_{1} + \frac{1}{2}\alpha t^{2}} = \frac{\partial u_{1} + \frac{1}{2}\alpha t^{2}}{\partial u_{1} + \frac{1}{2}\alpha t^{2}} = \frac{\partial u_{1} + \frac{1}{2}\alpha t^{2}}{\partial u_{1} + \frac{1}{2}\alpha t^{2}} = \frac{\partial u_{1} + \frac{1}{2}\alpha t^{2}}{\partial u_{1} + \frac{1}{2}\alpha t^{2}} = \frac{\partial u_{1} + \frac{1}{2}\alpha t^{2}}{\partial u_{1} + \frac{1}{2}\alpha t^{2}} = \frac{\partial u_{1} + \frac{1}{2}\alpha t^{2}}{\partial u_{1} + \frac{1}{2}\alpha t^{2}} = \frac{\partial u_{1} + \frac{1}{2}\alpha t^{2}}{\partial u_{1} + \frac{1}{2}\alpha t^{2}} = \frac{\partial u_{1} + \frac{1}{2}\alpha t^{2}}{\partial u_{1} + \frac{1}{2}\alpha t^{2}} = \frac{\partial u_{1} + \frac{1}{2}\alpha t^{2}}{\partial u_{1} + \frac{1}{2}\alpha t^{2}} = \frac{\partial u_{1} + \frac{1}{2}\alpha t^{2}}{\partial u_{1} + \frac{1}{2}\alpha t^{2}} = \frac{\partial u_{1} + \frac{1}{2}\alpha t^{2}}{\partial u_{1} + \frac{1}{2}\alpha t^{2}} = \frac{\partial u_{1} + \frac{1}{2}\alpha t^{2}}{\partial u_{1} + \frac{1}{2}\alpha t^{2}} = \frac{\partial u_{1} + \frac{1}{2}\alpha t^{2}}{\partial u_{1} + \frac{1}{2}\alpha t^{2}} = \frac{\partial u_{1} + \frac{1}{2}\alpha t^{2}}{\partial u_{1} + \frac{1}{2}\alpha t^{2}} = \frac{\partial u_{1} + \frac{1}{2}\alpha t^{2}}{\partial u_{1} + \frac{1}{2}\alpha t^{2}} = \frac{\partial u_{1} + \frac{1}{2}\alpha t^{2}}{\partial$

of 1800 rpm at the instant when the power is cut off.

If it comes to rest in 6 sec , calculate the angular deceleran assuming it is constant. How many revolutions does the angular make during this period.

New = 18001pm. $\omega_1 = \frac{2\pi N_1}{60} = 2\pi \times 30 \text{ rad/s}$ t = 6 Sec $\omega_2 = \omega_1 + \omega_1$

0 = 211 x30 + 0 x 6 0 = -314 rad 152

```
Angle turned, 0 = wit - 1 xt2
                      = 211 x 30 x 6 - 12 x 31 4 x 6
                      = 565.77 70d = 566 77 2012 | nathal co
                                         217
                        = 90 revolutions
 a parinding wheel is affached to the shall of an electric
   rooter of rated speed of 1800 pro when the power is
switched on the unit attains the nated speed in 5 sec
  a when the power is switched of the wall comes to rest in
    gosec pssuring uniformly accelerated motion, determine
    the no. of revolutions the unit turns,
     i) to affair the rated speed 200 Paratasasa
      11) to come to rest relepon proport
                      \omega = \frac{2\pi \times 1800}{60} = 2\pi \times 30 \text{ rad ls}.
         N= 1800 apm
                     Th = 60 1 radis
         t= 5 sec
                                 normal attelero.
   om TOS Wa = WI + &t
         60 1 20 + 50 Hom religion
                                      notion b enotioning
  PRE Sugar CE = 1211 rolof rad |s2.
 10 +) Bogular displacement, 0 = wit + 2 xt2
               $ 10 to 1 to 1 to 10 to 10
                                   = - x 12 11 x 5
                                   = 150 1 79 d
  true moter has adjular spend
    No. of revolutions ato office ? = 150 mutomo soll
                                     on teet in teet in
    deceleran dissuming it is constant linu many readlast.
       i) w3 = 0 act conces shot w2th + 2 at at cosb
    11 to 1 to E = 90 St
             w3 = w2+ &t
                                 mg = 60以入90+ 1人 - 音可×90°
               0 = 6011 + 900
                                    = 2700 1700
                a = - 2 1 rods =
                                   = 1350 revolutions
```

A wheel accelerates from rest to a speed of 180 spm uniformly in 0.4 sec. Rt then rotates at that speed for 2 sec before decelerating to rest in 0.3 sec Determine the total revolutions made by the wheel. N= 180 7Pro. W = 211 x 180 60 = 6 n rod 1s G∏ = 0.4 ℃ 0 = w, t + 2 at2 = = 1 47 1 1 0 4 ωg = ω2 (α=0) θ = ω2t = 3 6πx2 = 121 7ad " Los sat pu bontato es bon 0= wat + 1 age 1 were the diese of the disputered when these Potal angular displacement, 0 = 0, + 02 + 03 of term, prana = 377 + 128 + 283 = 44.28 794 |= 44.28 a B wheel rotates for 5 sec with a coast angular acceler & describes during that time lootad. It then notates with constant angular velocity & during the next 5 sec decribes 80 and find the Initial angular velocity & the ong wlar acceleran.

 $\begin{aligned} \omega_{2} &= \omega_{1} + \alpha_{1} + i, \\ \omega_{2} &= \omega_{1} + 5\alpha_{1} - 0, \\ 0 &= \omega_{1} + i + \frac{1}{2}\alpha_{1} + i\frac{7}{4}, \\ 100 &= 5\omega_{1} + \frac{1}{2}\alpha_{2} \times 5^{2}, \end{aligned}$

(2) 130 = 0, 7 2.50 = 0 C2) 130 mort setores 1000 1 in a 4 sec. of then volates at that speed for a see before 1 00 0 = w2 t 2 stort 2 02 t2 3 20 0 01 test of patt a 10 10 10 10 revolutions made hy the above - - -= 5 W2 +0 Wa = 1679als - UNIX RC = W MATORI = M 1. 0 = cu1 + 5 × 21 - (1) = 60 rad Is 20 = w, + 2.50, - (11) oc, = 47-17adls= dpr = -1.6 rad Is2 16 = w, + 50, (0=0) , w= gw PERS XI'S 34 radis of The notation of a flywheel is defined by the equi, ofter one Second from the start, the angular displacement was 4 rad. Determine the angular displacement, angular E angular acceleration of the flywheel when t=35. w=8+2-2++2 FF8 at t=15, 0=479d 0 = 1 (8t2-2t+2) dt. 4 = 1-1 + 2x 1 + C t=3 $\frac{t^3}{x} - 2\frac{t^2}{x} + 2t + c$ a B wheel rotates for see a sit Eax + Ess + Espondator acceler t seen set to and the por out set the course sadmisst a with constant angular velocity & ω| t= 3 = 3 x 3 + 2 x 3 + 2 bond boros tad root see = 28 radis Consission accelerate $\alpha = \frac{d\omega}{dt} = \frac{d}{dt} \left(3t^2 - 2t + 2\right)$ = 6t-2 = 16790152

west Kinetics of rolation is one pat bath was at accomplised to

Paroing moment / torque , T = Pa R = mass moment of accerd

=> 21 is analogues Newtons ilaw

forque, T = Fxr.

mostly interior and self was drive proven placed & c

work done in rotation

Workdone = TO

ke due to rotation

Ke = 1/2 Iw? I - mass moment of inertia

work-Energy equal for rotations

- (To = 1 T ω2 - 1 Tω,2.

SHM: Any motion which repeat after internal of time,

tp= aTT

the motion a is then removed from the system is said to undergo free vibration.

Force vibration. If the disturbing force act al periodic intervals on the system. The system is said to undergo forced vibran.

Degree of freedom: It is the no of independent, co-ordinates require to define the configuration of system

$$F = k \propto$$

$$\omega = \sqrt{\frac{k}{m}}$$

$$f_n = \frac{1}{20} \int_{-\infty}^{\infty} \frac{k}{m}$$

Ke = Ki + K2 + K3 Spring in series.

Ke = K, + K2 + K3 paallel.

1)
$$r = 100$$

$$tp = 25$$

$$t = 0.45$$

$$\omega = \frac{2\pi}{tp} = \frac{2\pi}{2} = \pi rad/s$$

$$\omega t = 0.4\pi rad$$

$$= (\frac{180}{\pi} \times 0.4\pi)^{0} = \frac{12^{\circ}}{2}$$

present = relocat arms 1 x 2 Sio 72 = 0:95m

> Velocity, V= w J72 = = T x J 12 (0.95)2 = 0098 rols Accelero", a = 62 x = 112 x 0.95 = 9.80 | 52

11) 1 x = 7 cos wb = 1 x cos 72 = 0.31w

$$V = \omega \sqrt{r^2 - x^2} = \pi \sqrt{1^2 - 0.31^2} = 2.99 \text{ m/s}$$

$$\alpha = \omega^2 x = \pi^2 x 0.31 = 3.06 \text{ m/s}^2$$

A pody moving with SHM has relocities of lomis & 4 mls at 2 & 4 m distance from the mean position. Find the amplitude & time period of the body

$$X = 2m$$
, $V = 10m | s$
 $X = 4m$, $V = 4m | s$
 $V = \omega \sqrt{Y^2 - X^2}$
 $10 = \omega \sqrt{Y^2 - 16}$
 $\frac{10}{4} = \frac{\sqrt{Y^2 - 16}}{\sqrt{Y^2 - 16}}$
 $\frac{10}{4} = \frac{\sqrt{Y^2 - 16}}{\sqrt{Y^2 - 16}}$
 $6 = 25 = \frac{\sqrt{2} - 4}{\sqrt{2} - 100} = 7^2 - 4$
 $5 = 257^2 = 96$

7 = 4.28 m

$$t_{p} = \frac{2\pi}{\omega} = \frac$$

- o a flywheel weighing soun & having radius of gy ration im loses its speed from 400 pm in 120 sec. calculate
 - 1) The retarding torque acting on it.
 - ") change in the KE during the above period.

$$N_1 = 400 \text{ rpm}$$
 $N_2 = 300 \text{ rpm}$
 $t = 120 \text{ }$ $W = 50 \times 10^3 \text{ }$
 $K = 1 \text{ m}$

$$\omega_1 = \frac{2\pi N}{60} = \frac{2\pi \times 400}{60} = 41.89 \text{ rad/s}.$$

$$\omega_2 = \frac{2\pi \times 300}{60} = 81.42 \text{ rad/s}.$$

$$\omega_2 = \omega_1 + \omega t$$
 = $\frac{50 \times 10^3}{9.81} \times 1 \times 0.087$
 $\omega_3 = \omega_1 + \omega t$ = $\frac{50 \times 10^3}{9.81} \times 1 \times 0.087$
 $\omega_4 = -0.087700015^2$ = $\frac{44.8.43}{9.81}$ Nm

(i) change in ke = initial ke - final ke
=
$$\frac{1}{2} P \omega_1^2 - \frac{1}{2} P \omega_2^2$$

= $\frac{1}{2} T (\omega_1^2 - \omega_2^2)$
= $\frac{1}{2} m k^2 (\omega_1^2 - \omega_2^2)$
= $\frac{1}{2} k \frac{50 k 10^3}{9 \cdot 51} \times 1 (41 \cdot 59^3 - 31 \cdot 42^2)$
= $1956 \cdot 05 k Nm$

o pright circular disc of weight 1500 in & 750 mm diameter is free to rotate about its geometrisc axis & is constantly accelerated from rest to 300 pm in 205.

Determine the constant torque required to produce this accelerate.

$$W = 1500 N$$
 $\omega_1 = 0$, $t = 20 S$
 $\omega_2 = \frac{2\pi N}{60} = \frac{2\pi \times 300}{60} = 3141 mls$
 $T = R \infty$
moment of inertia, $T = \frac{mr^2}{2}$

$$= \frac{\omega}{4} \frac{\gamma^2}{2}$$

$$= \frac{1500}{9.81} \times \left(\frac{0.79}{2}\right)^2$$

$$= 10.75 \text{ kgm}^2$$

$$\omega_2 = \omega_1 + \omega t$$

$$= 10.75 \text{ kgm}^2$$

of shaff of radius is rotates with constant angular speed win bearinges for which the co-efficient of friction is a Through what angle o will it rotate after the arriving torque is removed.

frictional force =
$$MR_N = M\omega$$

$$F_{\gamma} = M\omega_{\gamma}$$

$$\omega_{1} = \omega$$

$$\omega_{2} = 0$$

$$M = \frac{M\omega_{\gamma}}{2} = \frac{M\omega_{\gamma}}{2} = \frac{M\omega_{\gamma}}{2}$$

$$\omega_{1} = \frac{M\omega_{\gamma}}{2} = \frac{M\omega_{\gamma}}{2} = \frac{M\omega_{\gamma}}{2}$$

$$\omega_{2}^{2} = \omega_{1}^{2} - 2\omega_{1}\omega_{2}$$

$$\omega_{2}^{2} = \omega_{1}^{2} - 2\omega_{1}\omega_{2}$$

$$\omega_{3}^{2} = \omega_{1}^{2} - 2\omega_{2}\omega_{3}$$

$$\omega_{3}^{2} = \omega_{1}^{2} - 2\omega_{3}\omega_{3}$$

$$0 = \frac{\omega^2 r}{4 \mu g} \text{ rad}$$

The 75 kg crate is originally at rest on the smooth horizontal surface. It a touring force of 175 N, is alting a on angle of 30° is applied for 125, determine final velocity & cormal force which the surface exerts on the crate during ω 175 sip 3° 75 K 9 30° Ro x - direct steple plt solving (mv1) 2+ (impulse) = (mV2) x mv1 + E Poc xt = (m V2)x + to agri and (() 0 + 175 cos 30 + X 12 = 75 V2 y-direc? (m, v,) y + (impulse 1-2) y = (m v2) y (mv,)y + Efyxt = (mv2)y 75 x9.81 x,12 + 17551030 x 12 = 0 2) 10 man of weight 700N is standing on one end of a bood of weight 2200 N & 3m long. He then walks to the other end of the bow what is the corresponding displacement of the bow? (Neglect water resistance) Apply conservan of momentum initial momentum = Final momentum pood (van) + com (van) = 0 0 = 100 x Vman + 2000 Vboat = 700 (dx)mon + 2200 (dx) bow = 700 doc man + 2200 doc boat = 700 / daman + 2200 f da bood

$$0 = 700 \left[x mun \right]_{0}^{3+\infty} + 2200 \left[x bood \right]_{0}^{3+\infty}$$

$$0 = 100 \left[3+\infty \right] + 2200 \left[x bood \right]_{0}^{3+\infty}$$

$$\infty = -0.724 m \quad c backwards).$$

- B) B skg ball moving with osmls towards right collides bead on with another ball of moss skg, moving with orms towards left. Determine the velocities of the ball after impact & the corresponding % loss of ke when
 - 1) The impact is perfectly elastic e=1
 - 2) The impact is perfectly plastic e=0
 - 3) The impact is such that e=0.7.

0.5mls 20.7mls.

1) Using conservar of momentum

3kg (5kg)

using co-efficient of restitution equ

VB' = 0.2 mls.

since the impact is perfectly elastic there will be no loss of ke.

a) impact is perfectly plastic in e= 0

using conservar of momentum.

ke of the system before impact

$$V_{\theta t} = V_{\theta t}' = 2m | s \uparrow \qquad V_{\theta t} = V_{\theta t}' = | m | s \downarrow$$

$$V_{\theta}' = \sqrt{(v_{\theta \theta}')^2 + (V_{\theta t}')^2}$$

$$= \sqrt{(183)^2 + 2^2} = 2 \pi | m | s$$

$$\Theta_{\theta}' = t_{\theta \theta}' \left(\frac{V_{\theta t}'}{V_{\theta \theta}'} \right) = t_{\theta \theta}' \left(\frac{2}{183} \right) = 47.54^{\circ}$$

$$V_{\theta}' = 2\pi | m | s \qquad \Theta_{\theta}' = 47.54^{\circ}$$

A sphere of mass 3kg is released from rest It swings as a pendulum & strikes a block Bol mass 25kg resting on a borizontal surface Determine how for the block until move after impact. Pake M=0.3 b/w the block B& borizontal surface & e=0.75.

$$P_1 + \Sigma \mathcal{U}_{1-2} = T_2$$
 (1)

 $P_1 = 0$ since it starts from

 Test .

 $T_2 = \frac{1}{2} \text{mV}^2 = \frac{1}{2} \times 3 \text{ V}^2$.

 $\mathcal{U}_{1-2} = \text{only weight force is acting}$
 $= \text{mgh} = 3 \times 9 \cdot 81 \times 1.5 = 44 \cdot 145 \text{ J}$.

(1) =)
$$0 + 44.145 = \frac{1}{2}3v^{2}$$

 $V = \frac{5.42m}{5}$
 $m_{B}V_{B} + m_{B}V_{B} = m_{B}V_{B}^{1} + m_{B}V_{B}^{1}$
 $3 \times 5.425 + 2.5 \times 0 = 3V_{B}^{1} + 2.5 V_{B}^{1}$
 $3 \times 5.425 + 2.5 \times 0 = 3V_{B}^{1} + 2.5 V_{B}^{1}$

Applying work-energy principle to block B

 $P_1 = \frac{1}{2} m V^2 = \frac{1}{2} \times 2.5 \times 5.1782 = 33.51$

T3=0 since the block comes to rest

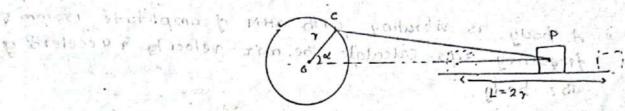
M2.3 = only friction force will act
= -Uk N.S = 0.3 x (2.5 x 9.81)

= -7.36 J

39.51 + [-7.36 x) =0

x = 4.55m

The piston of a ic engine moves with SHM. The crank rotates at 4207pm & the stacke length is 40cm. Find the velocity & accelerand the piston when it is at a distance of 10 cm from the mean position



on elicie on mere el :

Speed of crank = 420 7pm

Stroke length L = 2x craok radius

$$X = 10 \text{ cm} = 0.1 \text{ m}$$

o A particle moving with SHM has an amplitude of 4.5 mg period of oscillation is 3.5 sec. Find the time required by the particle to pass a points which are at a distance of 3.5mg 1.5m from the centre & on the same side of mean position.

Amplitude,
$$r = 4.5 \text{ m}$$
 $tp = 8.5 \text{ s}$

$$\omega = \frac{2\pi}{t_p} = \frac{2\pi}{3.5} = 1.8 \text{ rad/s}$$

Let x, & x2 be the distance of the 1st & 20d point from mean position

$$x = \gamma \cos \omega t$$

 $x_1 = \gamma \cos \omega t$,
 $3.5 = 4.5 \cos C \cdot 8 \times t_1 \times \frac{180}{\pi}$)
 $t_1 = 0.385$
 $x_2 = \gamma \cos \omega t_2$
 $1.5 \cdot 4.5 \cos C \cdot 8 \times t_2 \wedge \frac{180}{\pi}$)
 $t_2 = 0.685$.

time sequired to pass the 2 points
$$t = 1_2 - t_1$$

$$= 0.68 - 0.38$$

$$= 0.35$$

9. A body is vibrating with SHM of amplitude 150mm & frequency 3cps. calculate the max velocity & accelera of the body.

$$Y = 150 \text{ mm} = 0.15 \text{ m}$$
 $f = 3 \text{ cps}$
 $\omega = 2\pi f = 2\pi \times 3 = 6\pi \text{ rad/s}$
 $V_{\text{max}} = 7\omega = 0.15 \times 6\pi = 2.83 \text{ m/s}$
 $A_{\text{max}} = \omega^2 r = (6\pi)^2 \times 0.15 = 53.3 \text{ m/s}^2$

of son weight is bung on the end of a belical spring & is set vibrating vertically. The weight makes 4 oscillations per sec Determine the stiffness of the spring.

$$m = \frac{80}{9}$$

$$F = 4 \text{ cps.}$$

$$f_0 = \frac{1}{2\pi i} \int \frac{k}{m}$$

$$K = \frac{f_0^2 \times m(4\pi)^2}{9.8i}$$

$$f_0^2 = \frac{1}{4\pi 2} \frac{k}{m}$$

$$= 4 \times \frac{90}{9.8i} \times 16 \times \pi^2$$

$$= 5.51 \text{ NI m}$$

? If a belical spring having a stiffness of 90 N cm is available what weight should be bug on it so that will oscillate with a periodic time of 1 sec.

$$K = 90 \text{ NICM} = 90 \times 10^{2} \text{ N/m}$$

$$tp = 1 \text{ Sec}$$

$$fo = \frac{1}{2\pi} = 1 \text{ Cps}$$

$$fo = \frac{1}{2\pi} \frac{1}{m}$$

$$m = \frac{k}{(2\pi)^{3} fo^{2}} = \frac{90 \times 10^{2}}{4 \times \pi^{2} \times 1^{2}}$$

$$= 227.97 \text{ kg}$$

- A weight of son suspended from a spring vibrales vertically with an amplitude of & cm & a frequency of 1 oscillation/sec Find a) the stiffness of the spring b) the max. tension included in the spring. c) Max. velocity of weight. x = 8 cm = 0.08 m F= 1 cps . 10 % AL 1875 (a) $F_0 = \frac{1}{2\pi} \int \frac{K}{m}$ K = fo2x 4112xm = 1x4x112x 50 = 201.22 N/m (b) max. leosion in the string = kx = 1000 = 201-22 X 0.08 the state of states of the city cat hite or barres a freed to w max. velocity, v= wx m com att valor = (27f) x x all months = 2T X I X 0.08 o p body of mass soky is suspended by a springs of stiffness 4 KN lm & 6KN lm. as shown in fig. The body is pulled sommodown from its equilibrium position athen released Calculate. a) frequency of oscillation. b) max. Velocity 6KNIM \$ c) max. accelera. 4kulm } 50K9 Fig A. (A) Ke = 1 + 1 = 10 + 4 = 10
 - Ke = 2.4 KN/m = 2.4x103 N/m
 - $f = \frac{1}{2\pi} \sqrt{\frac{k}{m}} = \frac{1}{2\pi} \sqrt{\frac{2.4 \times 10^3}{50}} = 1.10 \text{ cps}.$ ω = 211 = 6.9 a rad s.
 - b) Vmax = WX = 6.93 x 0.05 = 0.35 mls
 - amax = w2x = (6.93) 2x005 = 2.4 m/s2 ()

a)
$$f = \frac{1}{2\pi} \int \frac{K}{100} = \frac{1}{2\pi} \int \frac{10 \times 10^3}{50} = 2.25 \text{ CPs}$$

b) Vmax = wx = 27 x 2 25 x 0. 05 = 0 . Timls.

gently a more training out that by Tapies

is the higher ac

rapid and to make the way

c) $\alpha_{max} = \omega^2 x = (2\pi x \partial \theta 5)^2 x 0.05 = 10 \text{ m/s}^2$ Figc

Ke = loknim.

- a) F = 2.25 CPS
- b) Vm = 0.71 mls , Tx px 1 = m 1 m?
- c) ama = lomis = points soll al acreati
- a mass m. If the system vibrates with frequency 3Hz, determine the mass m.

F = 3H2 = 3CPS.

K = GKNIM = GX103 NIM

stiffness of spring a no. of coils ... when this spring is cut into a halves, the stiffness of each half is doubles.

Ki = K2 = 2xG = 12kNlm. Since the spring are in parallel, the equivalent stiffness, ke = ki + k2 = 24kNlm = 24x103Nlm

in his course the minery to

$$f = \frac{1}{2\pi} \int \frac{K}{m} = \frac{1}{2\pi} \int \frac{24 \times 10^3}{m}.$$

$$q = \frac{1}{2\pi} \ln^2 \frac{24 \times 10^3}{m}.$$

$$m = \frac{24 \times 10^3}{4\pi^2 \times 9} = 67.62 \text{ kg}$$