

# Animesh Srivastava

17 Whitby Court, London N7 0SU  
+44 (0)7407 742 303

[animsriva@gmail.com](mailto:animsriva@gmail.com)  
[www.animesh-77.github.io](http://www.animesh-77.github.io)

## Education

**University College London - MSc in Machine Learning** 2023 - 2024

- Final grades: Merit
- Relevant modules: Machine Vision, Robot Vision and Navigation, Applied DL, Supervised Learning, Applied ML, Bayesian Deep Learning, Graphical Models, Information Retrieval and Data Mining
- Relevant coursework topics: SLAM, SfM, 2-view geometry, Feature extraction and matching, Data Augmentation, CNNs, VAE, GANs, RNNs, CNNs, Vision Transformers
- Dissertation: "High Resolution Novel View Synthesis with 3D Gaussian Splatting" under UCL's Industry Exchange Network

**St Stephen's College, University of Delhi - BSc in Physics (Hons)** 2019 - 2022

- Final grades: **8.42/10**, equivalent to First-Class Honours, UK
- Selected modules: Quantum mechanics, Astrophysics, Linear Algebra and Tensor Analysis, Advanced Calculus, Computational Physics and Probability and Statistics
- Recipient of the INSPIRE scholarship, awarded by Government of India

**St Dominic Savio College, India - Secondary Education** 2017 - 2019

- Class 12<sup>th</sup> (equivalent to A-levels, UK): **97.6%** Physics, Chemistry, Mathematics, English, Computer Science
- Class 10<sup>th</sup> (equivalent to GCSE, UK): **95.5%**

## Experience

**Machine Learning Intern - Bodymetrics, London, UK** May 2024 - Sep 2024

- Optimised 3D gaussian splatting pipeline for high resolution Novel View Synthesis (NVS) of fashion models from ultra-high resolution training images
- Created a new custom dataset, performed data pre-processing, hyperparameter tuning and refined training loss functions to enhance PSNR, SSIM and LPIPS metrics of NVS
- Integrated GroundingDino, a zero-shot object detection model into the pipeline, reducing model size by 50% while preserving the rendering quality of foreground subjects in NVS
- Developed an interactive website to show differences in NVS across models, providing insights into model parameters and highlighting areas where the model failed

**Geospatial Analyst - Pixxel, Bengaluru, India** Jan 2023 - Jul 2023

- Designed a regression based ML model to monitor farm level crop growth from satellite images
- Implemented semantic segmentation, NDVI extraction, time series analysis and K-means clustering algorithms
- Built an interactive dashboard for real-time monitoring and decision-making
- Optimised and scaled the model for deployment on the company's Earth monitoring platform, enabling global real-time crop growth monitoring

**Machine Learning Intern - Spartificial, India** Nov 2022 - Jan 2023

- Developed a U-Net based CNN to detect active fire regions with multispectral satellite images
- Engineered and utilised custom spectral indices and other band-specific thresholds to enhance the detection of active fire pixels
- Evaluated model performance on IoU, precision, recall and dice coefficient metrics

**Summer Research Fellow - Raman Research Institute, Bengaluru, India** Jul 2021 - Sep 2021

- Solved differential equations and simulated satellite trajectories to optimise lunar orbits, eliminate station-keeping manoeuvres and fulfil mission objectives
- Presented findings on lunar orbit design and analysis at the Astronomy and Astrophysics Club at RRI and the Indian Academy of Sciences

## Skills

**Programming Languages:** Python, C++, JAVA, SQL, C#, MATLAB, ARDUINO, ESP32

**ML and DS tools:** OpenCV, Numpy, PyTorch, TensorFlow, Scikit-learn, Pandas, Matplotlib, Plotly/Dash, SciPy, GDAL, Rasterio, pySTAC, GeoPandas, xarray/rioxarray

**Other:** Git and GitHub, Docker, FastAPI, VSCode, QGIS, Meshlab, CloudCompare, COLMAP, Unity, LaTeX, Linux (Ubuntu), JIRA

## Certificates

- Advanced Techniques with TensorFlow (Coursera): Specialisation in custom models, distributed training, computer vision, autoencoders, and generative deep learning
- IELTS score 8.0

## Visa sponsorship

Eligible to work in the UK without the need for visa sponsorship