



INDIAN INSTITUTE OF INFORMATION **TECHNOLOGY** 



### **Decision Tree Learning**





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**Pingala Interactions In Computing** 

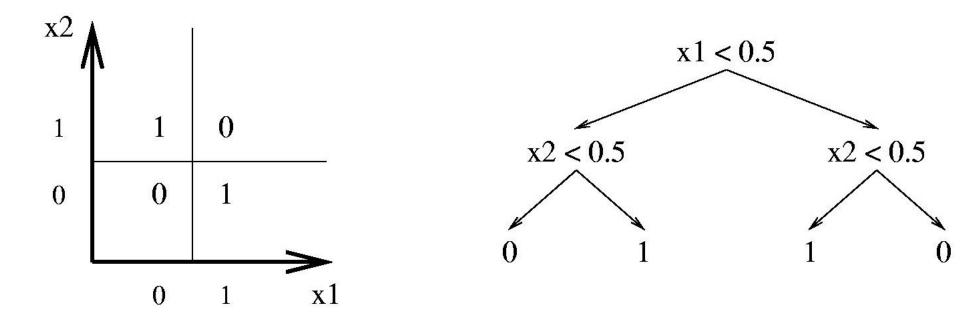
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#### **Decision Trees**

- Convenient Representation
  - Developed with learning in mind
  - Deterministic
  - Comprehensible output
- Expressive
  - Equivalent to propositional Disjunctive Normal Form (DNF)
  - Handles discrete and continuous parameters
- Simple learning algorithm
  - Handles noise well
  - Classify
  - Constructive (build DT by adding nodes)

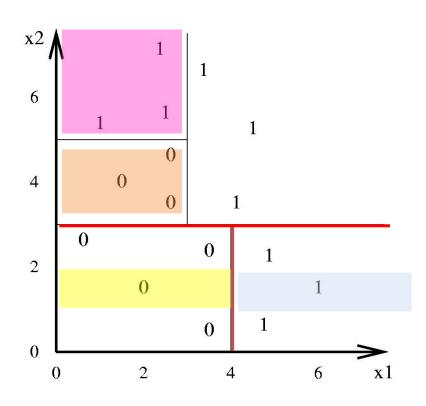
# Boolean function can represents Decision tree

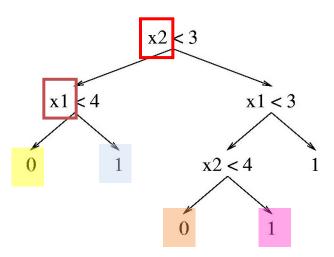


The tree will in the worst case require exponentially many nodes, however.

#### Decision tree to make Decision Boundaries

• Decision trees divide the feature space into axis-parallel rectangles, and label each rectangle with one of the K classes.





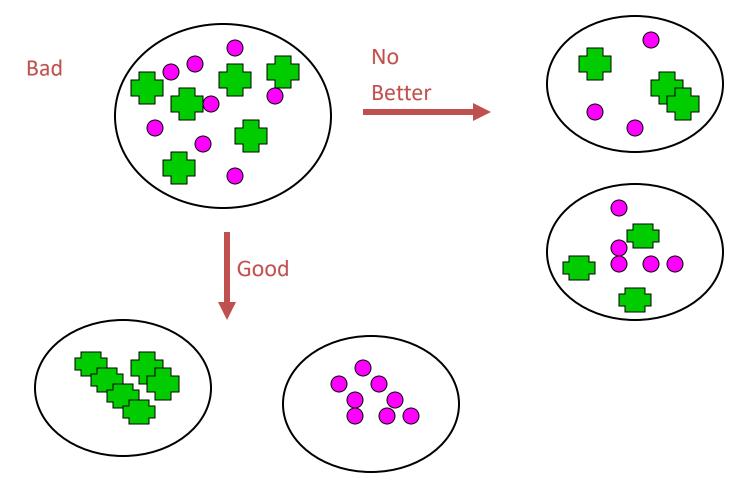
### Depth of Decision tree and Boolean functions

Decision Trees Provide Variable-Size Hypothesis Space

As the number of nodes (or depth) of tree increases, the hypothesis space grows

- depth 1 ("decision stump") can represent any boolean function of one feature.
- **depth 2** Any boolean function of two features; some boolean functions involving three features (e.g.,  $(x_1 \land x_2) \lor (\neg x_1 \land \neg x_3)$
- etc.

#### Disorder is bad Homogeneity is good



Which attribute should we use to split?

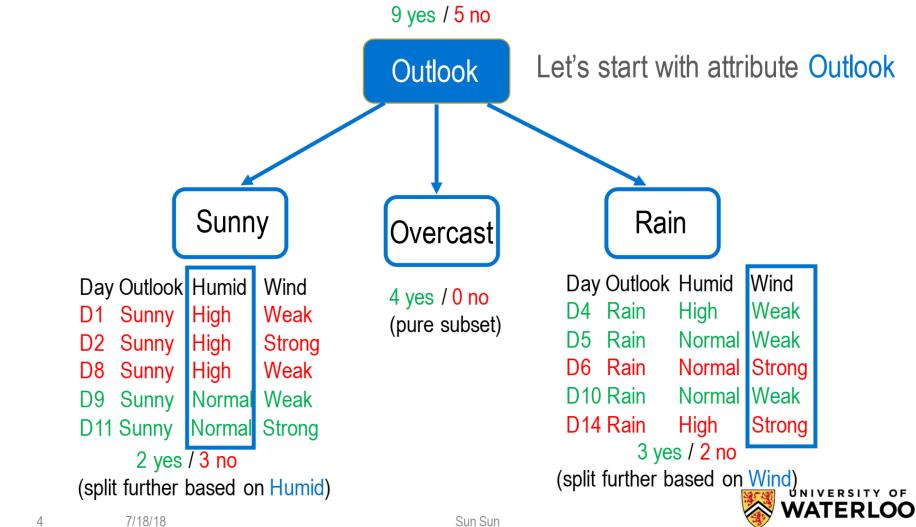
### Example: "Good day for tennis"

- Attributes of instances
  - Outlook = {rainy (r), overcast (o), sunny (s)}
  - Temperature = {cool (c), medium (m), hot (h)}
  - Humidity =  $\{ \text{normal (n), high (h)} \}$
  - Wind =  $\{\text{weak (w), strong (s)}\}$
- Class value
  - Play Tennis? =  $\{don't play (n), play (y)\}$
- Feature = attribute with one value
  - E.g., outlook = sunny
- Sample instance
  - outlook=sunny, temp=hot, humidity=high, wind=weak

# Experience: "Good day for tennis"

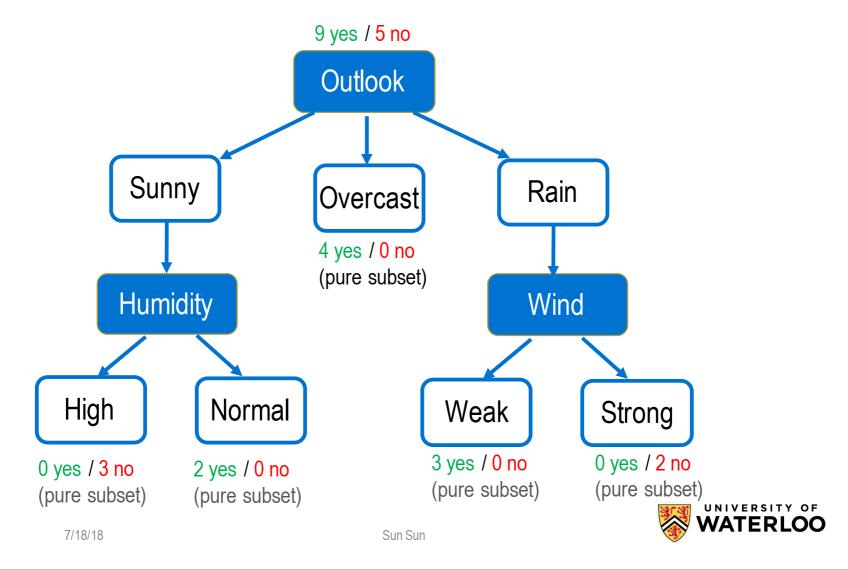
Day Outlook		Temp	Humid Wind		PlayTennis?
d1	S	h	h	W	n
d2	S	h	h	S	n
d3	O	h	h	W	y
d4	r	m	h	W	y
d5	r	c	n	W	y
d6	r	c	n	S	n
d7	O	c	n	S	y
d8	S	m	h	W	n
d9	S	c	n	W	y
d10	r	m	n	W	y
d11	S	m	n	S	y
d12	O	m	h	S	y
d13	O	h	n	W	y
d14	r	m	h	S	n

## Split training data

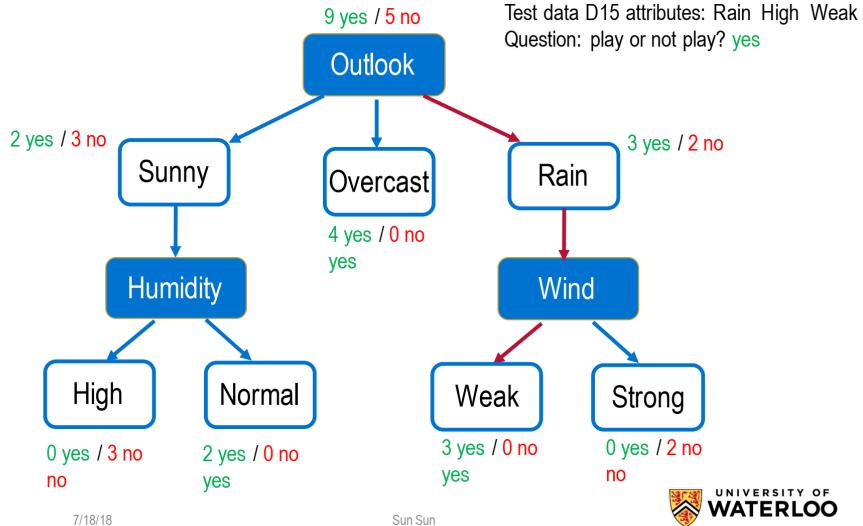


## Split training data

5

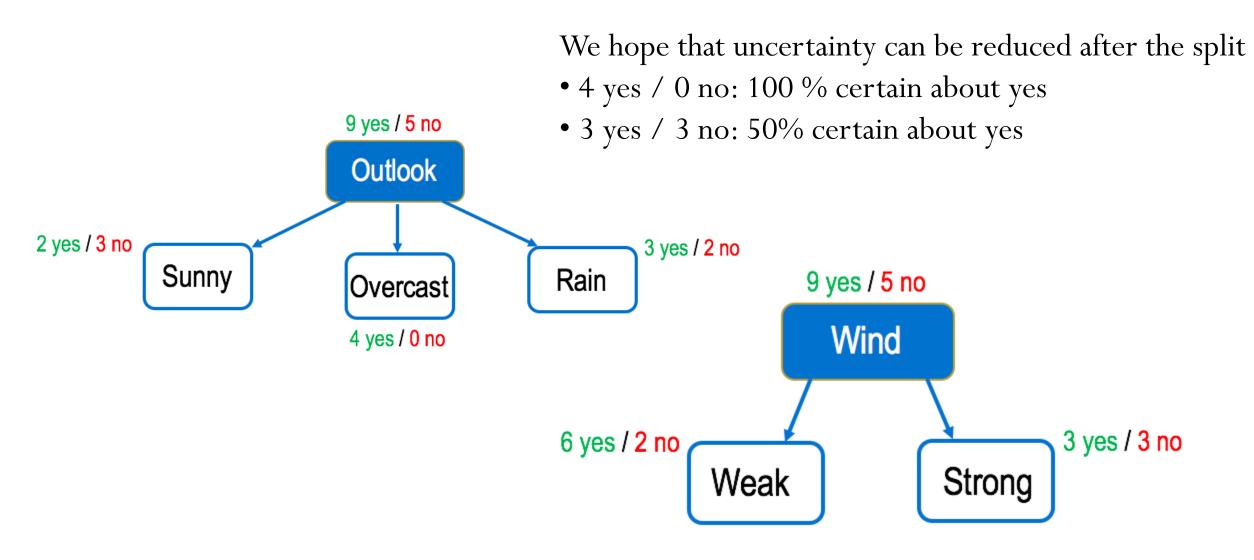


## Split training data



6

#### How to select an attribute?



## Decision Tree General Algorithm

```
BuildTree(TraingData)
       Split(TrainingData)
Split(D)
       If (all points in D are of the same class)
               Then Return
        For each attribute A
               Evaluate splits on attribute A
       Use best split to partition D into D1, D2
       Split (D1)
       Split (D2)
```

#### How to learn decision trees

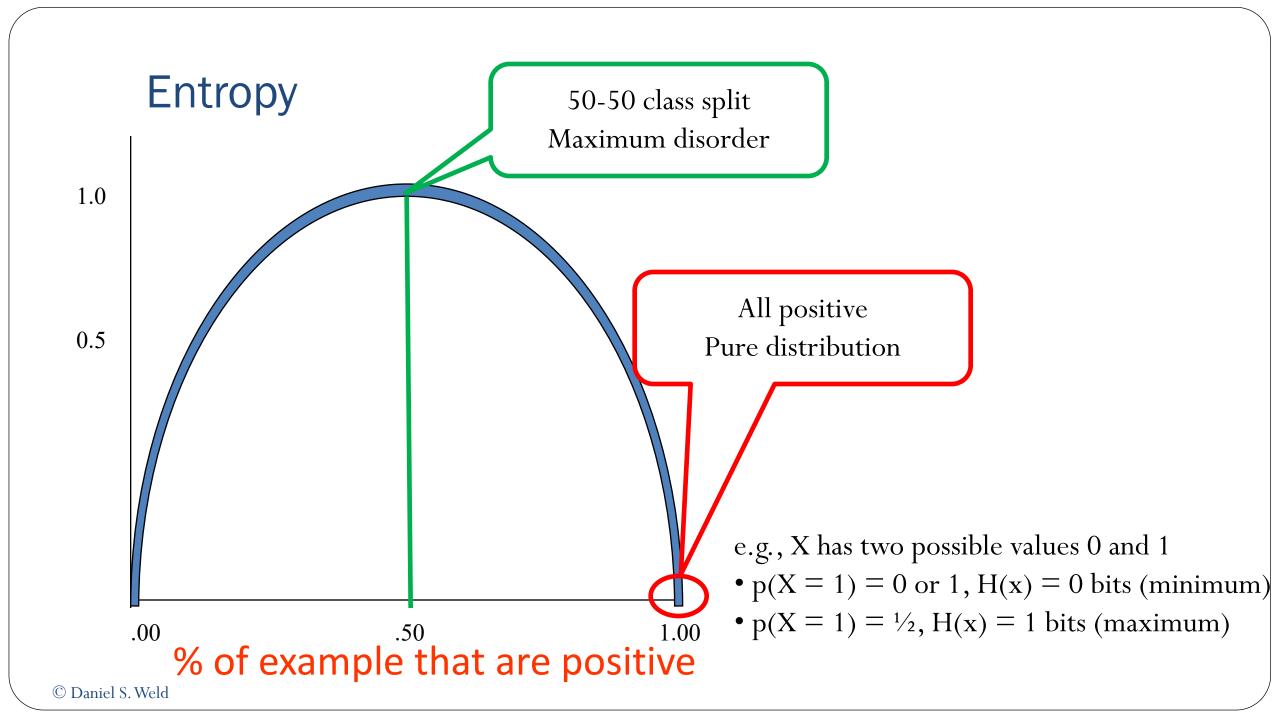
- Constructing optimal binary decision trees is an NP Complete problem
  - Optimal tree is one which minimizes the expected number of tests required to identify the unknown object
  - NP-complete: belongs to both NP and NP-hard; easy to verify a solution to NP-complete, but hard to find a solution
- Often resort to heuristic algorithms
  - Build an empty decision tree à split à recurse (choosing a good attribute for splitting is important)
  - Some examples: ID3, C4.5, CART

## ID3 (Iterative Dichotomiser 3) algorithm

- ID3 (node, {training data}) # Generate a DT
  - 1. Pick an attribute (A) with the maximum information gain for the considered training data
  - 2. For each value of A, create new child node
  - 3. Split training data to child nodes
  - 4. Check subset for each child node
    - If subset is pure: stop
    - Else: ID3 (child node, {subset data})

# Entropy (disorder) is bad Homogeneity is good

- Let S be a set of examples
- Entropy(S) = -P  $\log_2(P)$  N  $\log_2(N)$ 
  - P is proportion of pos example
  - N is proportion of neg examples
  - $0 \log 0 == 0$
- Example: S has 9 pos and 5 neg Entropy([9+, 5-]) =  $-(9/14) \log_2(9/14) - (5/14) \log_2(5/14)$ = 0.940



## Information gain

Expected drop in entropy after split

$$\mathrm{Gain}(S,A) = H(S) - \sum_{V \in \mathrm{Values}(A)} \frac{|S_V|}{|S|} H(S_V)$$
 uncertainty before split

A: attribute

uncertainty after split

- S: set of training examples
- V: possible values of attribute A
- $S_V$ : set of training examples with the value of attribute A = V
- Subsets with more examples have a larger effect

Maximizing Gain(S, A) is equivalent to minimizing uncertainty after split



## Gain of Splitting on Wind

Values(wind)=weak, strong S = [9+, 5-]

$$S_{\text{weak}} = [6+ 2-]$$
  
 $S_{\text{s}} = [3+, 3-]$ 

Gain(S, wind)

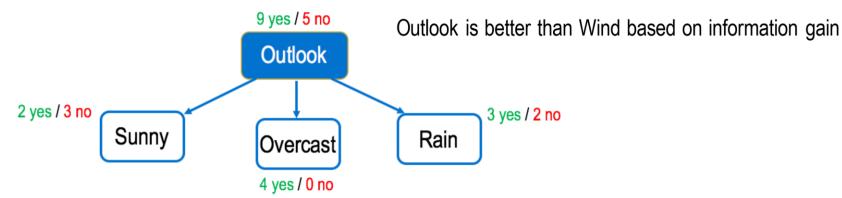
= Entropy(S) - 
$$\sum (|S_v| / |S|)$$
 Entropy(S<sub>v</sub>)

$$v \in \{weak, s\}$$

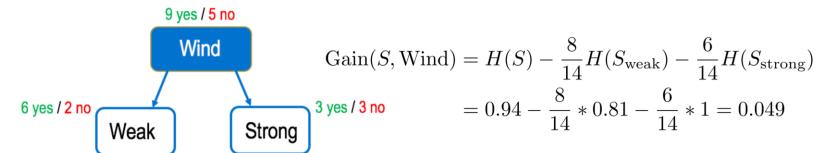
- = Entropy(S) 8/14 Entropy(S<sub>weak</sub>) - 6/14 Entropy(S<sub>s</sub>)
- $= 0.940 (8/14) \ 0.811 (6/14) \ 1.00$
- = .048

Day	Wind	Tennis?
d1	weak	n
d2	S	n
d3	weak	yes
d4	weak	yes
d5	weak	yes
d6	S	n
d7	S	yes
d8	weak	n
d9	weak	yes
d10	weak	yes
d11	S	yes
d12	S	yes
d13	weak	yes
d14	S	n

### Information gain

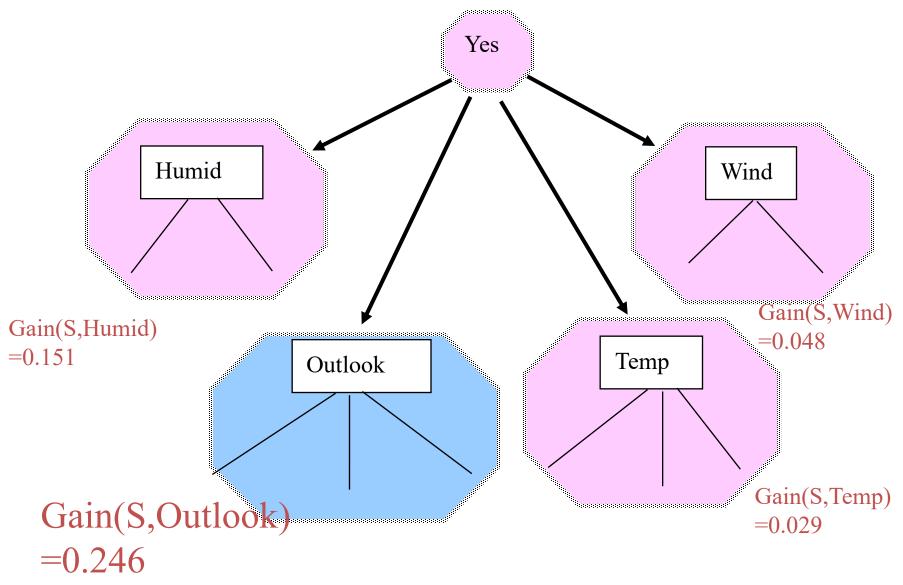


Gain(S, Outlook) = 
$$H(S) - \frac{5}{14}H(S_{\text{sunny}}) - \frac{4}{14}H(S_{\text{overcast}}) - \frac{5}{14}H(S_{\text{rain}})$$
  
=  $0.94 - \frac{5}{14} * 0.97 - \frac{4}{14} * 0 - \frac{5}{14} * 0.97 = 0.25$ 



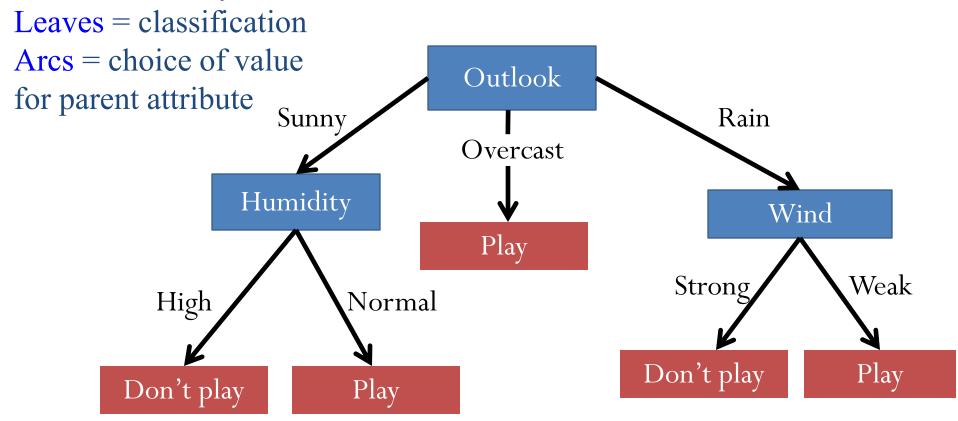


# **Evaluating Attributes**



### **Decision Tree Representation**

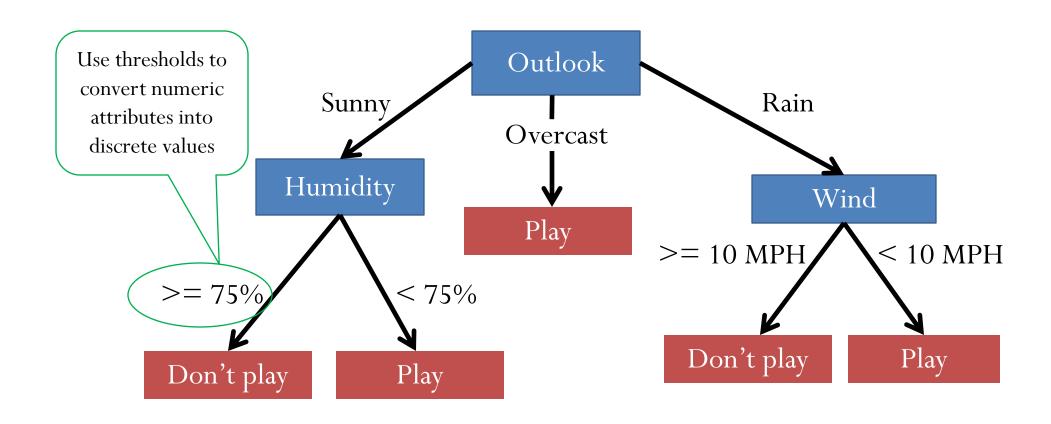
Good day for tennis?



Decision tree is equivalent to logic in disjunctive normal form

 $Play \Leftrightarrow (Sunny \land Normal) \lor Overcast \lor (Rain \land Weak)$ 

#### Numeric Attributes

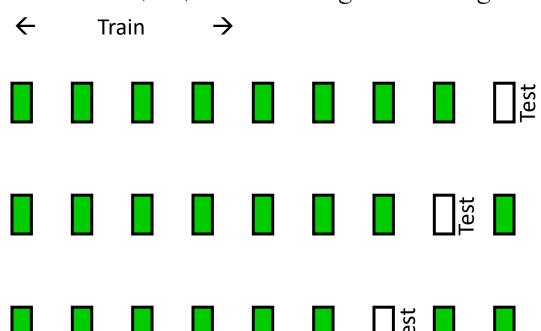


### Issues

- Missing data
- Real-valued attributes
- Many-valued features
- Evaluation
- Overfitting

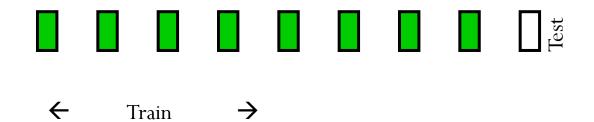
#### **Evaluation: Cross Validation**

- Partition examples into *k* disjoint sets
- Now create *k* training sets
  - Each set is union of all equiv classes except one
  - ullet So each set has (k-1)/k of the original training data



#### **Cross validation**

- Partition examples into *k* disjoint sets
- Now create *k* training sets
  - Each set is union of all equiv classes except one
  - So each set has (k-1)/k of the original training data



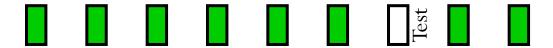
#### **Cross Validation**

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  - Each set is union of all equiv classes except one
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#### **Cross Validation**

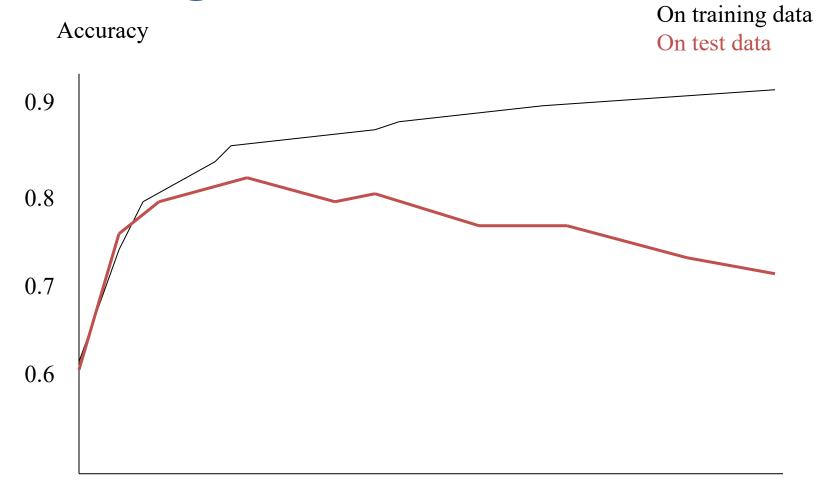
- Partition examples into *k* disjoint sets
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  - Each set is union of all equiv classes except one
  - So each set has (k-1)/k of the original training data



## Cross-Validation (2)

- Training and validation sets
  - training set is used to build the tree
  - a separate validation set is used to evaluate the accuracy over subsequent data, and to evaluate the impact of pruning
  - justification: validation set is unlikely to exhibit the same noise and spurious correlation
  - rule of thumb: 2/3 to the training set, 1/3 to the validation set
- Leave-one-out
  - Use if < 100 examples (rough estimate)
  - Hold out one example, train on remaining examples
- M of N fold
  - Repeat M times
  - Divide data into N folds, do N fold cross-validation

# Overfitting



Number of Nodes in Decision tree

## Overfitting Definition

- DT is *overfit* when exists another DT' and
  - DT has *smaller* error on training examples, but
  - DT has *bigger* error on test examples
- Causes of overfitting
  - Noisy data, or
  - Training set is too small
- Solutions
  - Reduced error pruning
  - Early stopping
  - Rule post pruning

## **Avoid Overfitting**

- How to avoid overfitting?
  - Stop growing the tree
    - before it perfectly classifies the training data
    - when data split is not statistically significant
  - Allow overfitting, but post-prune the tree
  - Grow full tree, then post-prune
  - Acquire more training data
  - Remove irrelevant attributes (manual process not always possible)
- How to select "best" tree:
  - Measure performance over training data
  - Measure performance over separate validation data set
  - Add complexity penalty to performance measure (heuristic: simpler is better)

## Reduced Error Pruning

• Split data into train and validation set



- Repeat until pruning is harmful
  - Remove each subtree and replace it with majority class and evaluate on validation set
  - Remove subtree that leads to largest gain in accuracy

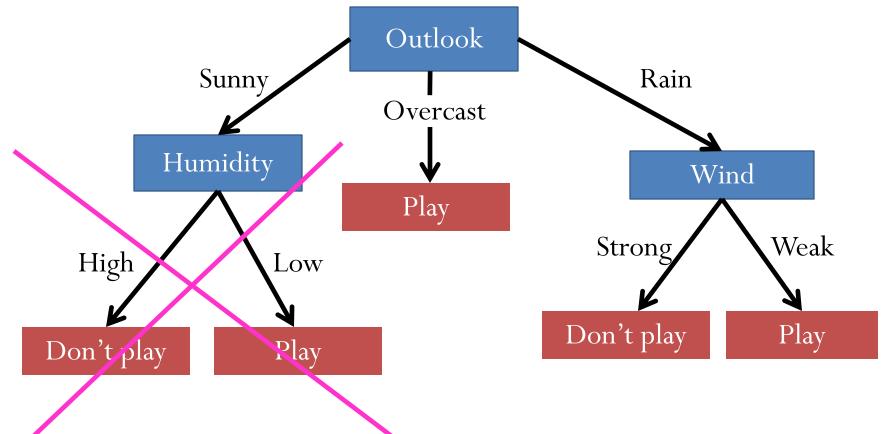
### Reduced-Error Pruning

Split data into training and validation set

Do until further pruning is harmful:

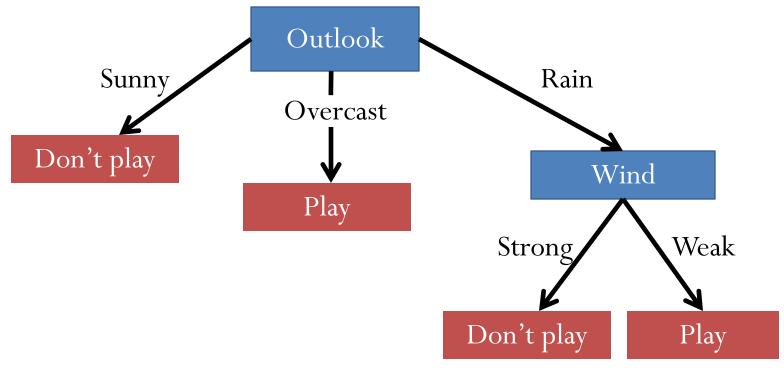
- 1. Evaluate impact on *validation* set of pruning each possible node (plus those below it)
- 2. Greedily remove the one that most improves *validation* set accuracy

## Reduced Error Pruning Example



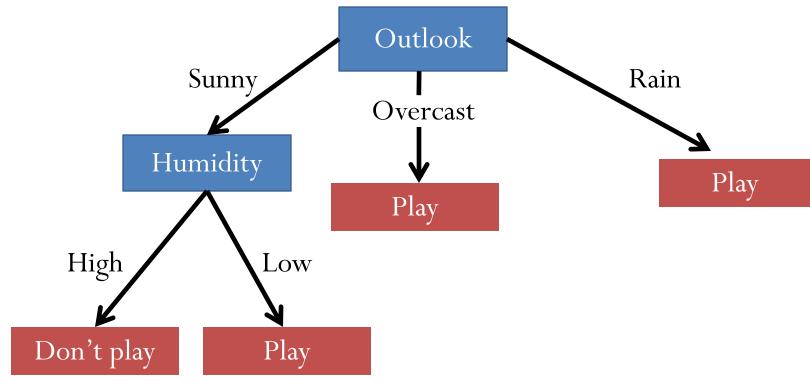
Validation set accuracy = 0.75

## Reduced Error Pruning Example



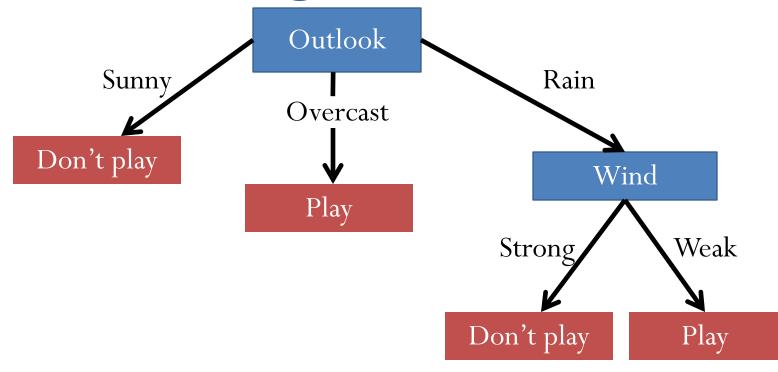
Validation set accuracy = 0.80

# Reduced Error Pruning Example



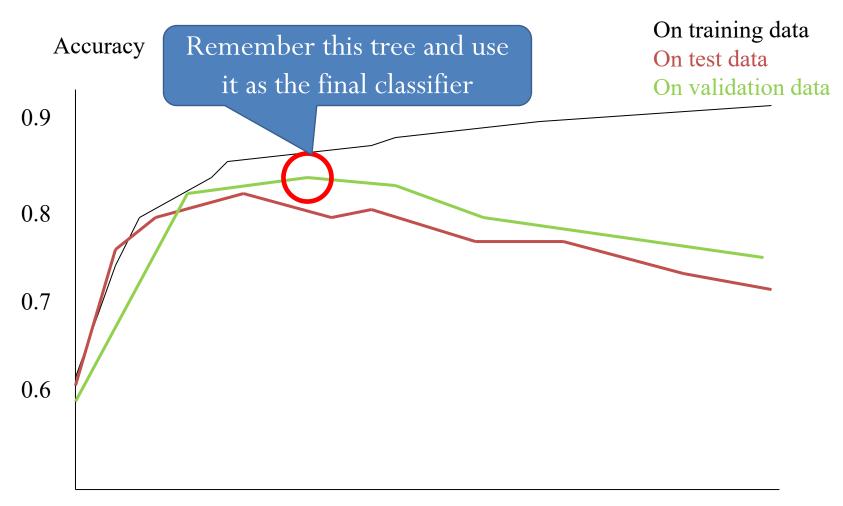
Validation set accuracy = 0.70

# Reduced Error Pruning Example



Use this as final tree

# **Early Stopping**

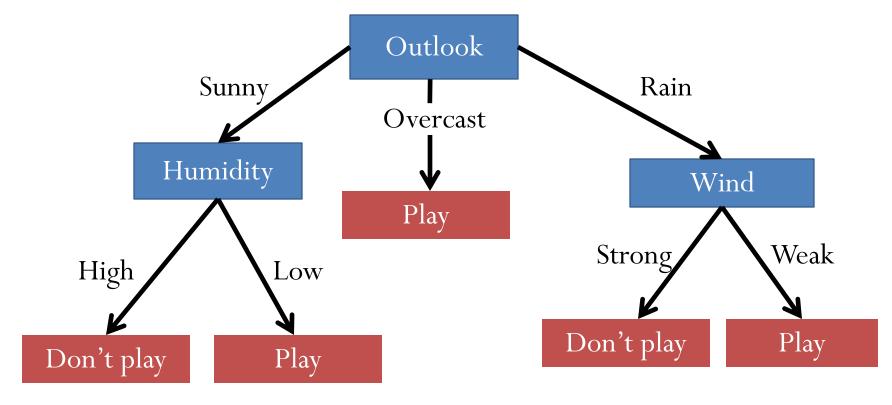


Number of Nodes in Decision tree

# Post Rule Pruning

- Split data into train and validation set
- Prune each rule independently
  - Remove each pre-condition and evaluate accuracy
  - Pick pre-condition that leads to largest improvement in accuracy
- Note: ways to do this using training data and statistical tests
  - 1. Convert tree to equivalent set of rules
  - 2. Prune each rule independently of others
  - 3. Sort final rules into desired sequence for use

### Conversion to Rule



```
Outlook = Sunny \land Humidity = High \Rightarrow Don't play
```

Outlook = Sunny 
$$\land$$
 Humidity = Low  $\Rightarrow$  Play

 $Outlook = Overcast \Rightarrow Play$ 

• • •

IF  $(Outlook = Sunny) \ AND \ (Humidity = High)$ 

THEN PlayTennis = No

IF  $(Outlook = Sunny) \ AND \ (Humidity = Normal)$ 

THEN PlayTennis = Yes

. . .

# Example

```
Outlook = Sunny \land Humidity = High \Rightarrow Don't play
             Validation set accuracy = 0.68
   \rightarrow Outlook = Sunny \Rightarrow Don't play Validation set accuracy = 0.65
   \rightarrow Humidity = High \Rightarrow Don't play | Validation set accuracy = 0.75
                       Keep this rule
```

# Overfitting 2

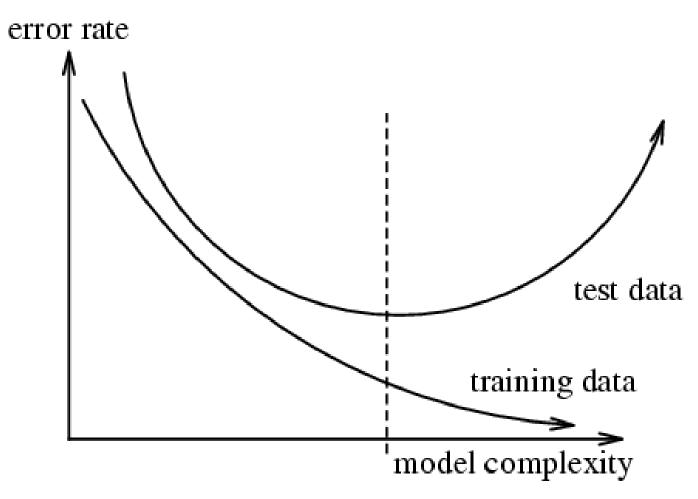
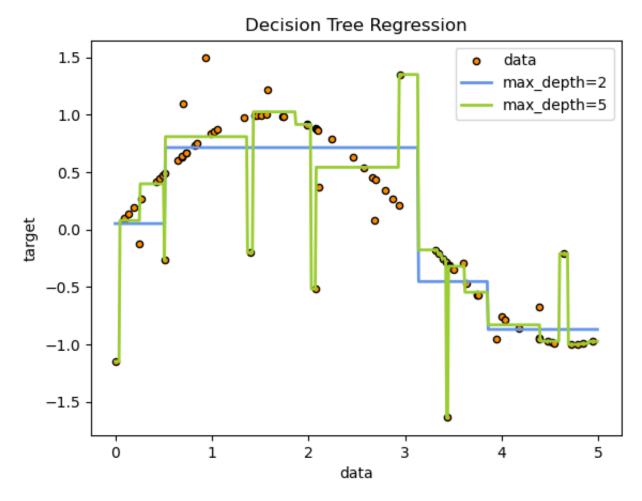


Figure from w.w.cohen

# Scikit Learn on Decision Trees

Regression



https://scikit-learn.org/stable/modules/tree.html

## Scikit Learn on Decision Trees

Given training vectors  $x_i \in \mathbb{R}^n$ , i=1,..., I and a label vector  $y \in \mathbb{R}^l$ , a decision tree recursively partitions the feature space such that the samples with the same labels or similar target values are grouped together.

Let the data at node m be represented by  $Q_m$  with  $n_m$  samples. For each candidate split  $\theta=(j,t_m)$  consisting of a feature j and threshold  $t_m$ , partition the data into  $Q_m^{left}(\theta)$  and  $Q_m^{right}(\theta)$  subsets

$$Q_m^{left}( heta) = \{(x,y)|x_j \leq t_m\} \ Q_m^{right}( heta) = Q_m \setminus Q_m^{left}( heta)$$

The quality of a candidate split of node m is then computed using an impurity function or loss function H(), the choice of which depends on the task being solved (classification or regression)

$$G(Q_m, heta) = rac{n_m^{left}}{n_m} H(Q_m^{left}( heta)) + rac{n_m^{right}}{n_m} H(Q_m^{right}( heta))$$

Select the parameters that minimises the impurity

$$\theta^* = \operatorname{argmin}_{\theta} G(Q_m, \theta)$$

Recurse for subsets  $Q_m^{left}(\theta^*)$  and  $Q_m^{right}(\theta^*)$  until the maximum allowable depth is reached,  $n_m < \min_{samples}$  or  $n_m = 1$ . https://scikit-learn.org/stable/modules/tree.html

### Scikit Learn on Decision Trees

• Gini and Log Loss or Entropy:

If a target is a classification outcome taking on values 0,1,...,K-1, for node m, let

$$p_{mk} = rac{1}{n_m} \sum_{y \in Q_m} I(y=k)$$

be the proportion of class k observations in node m. If m is a terminal node, predict\_proba for this region is set to  $p_{mk}$ . Common measures of impurity are the following.

Gini:

$$H(Q_m) = \sum_k p_{mk} (1-p_{mk})$$

Log Loss or Entropy:

$$H(Q_m) = -\sum_k p_{mk} \log(p_{mk})$$

https://scikit-learn.org/stable/modules/tree.html

# References

### References

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- Daniel S. Weld <a href="https://www.cs.washington.edu/people/faculty/weld">https://www.cs.washington.edu/people/faculty/weld</a>
- CS489/698: Intro to ML, Lecture 19: Decision Tree, Instructor: Sun Sun (17/18/18)
- "Introductory Applied Machine Learning" by Victor Lavrenko and Nigel Goddard University of Edinburgh.
- <a href="https://scikit-learn.org/stable/modules/tree.html">https://scikit-learn.org/stable/modules/tree.html</a>

תודה רבה

Ευχαριστώ

Hebrew

Greek

Спасибо

Danke

Russian

German

धन्यवादः

Merci

ধন্যবাদ Bangla Sanskrit

நன்றி

**Tamil** 

شكر أ Arabic

French

Gracias

Spanish

. . .

ಧನ್ಯವಾದಗಳು Kannada Thank You English

നന്ദ്വി

Malayalam

多謝

Grazie

Italian

ధన్యవాదాలు

Telugu

આભાર Gujarati Traditional Chinese

ਧੰਨਵਾਦ Punjabi

धन्यवाद

Hindi & Marathi

多谢

Simplified Chinese

https://sites.google.com/site/animeshchaturvedi07

Obrigado Portuguese

ありがとうございました Japanese

ขอบคุณ

Thai

감사합니다

Korean