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# Binary Heap and Priority Queue

Dr. Animesh Chaturvedi

Assistant Professor: IIIT Dharwad

Young Researcher: Heidelberg Laureate Forum

Postdoc: King's College London & The Alan Turing Institute

PhD: IIT Indore MTech: IIITDM Jabalpur



Indian Institute of Technology Indore  
भारतीय प्रौद्योगिकी संस्थान इंदौर



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# Binary Tree Data Structures

- **Unsorted list:**

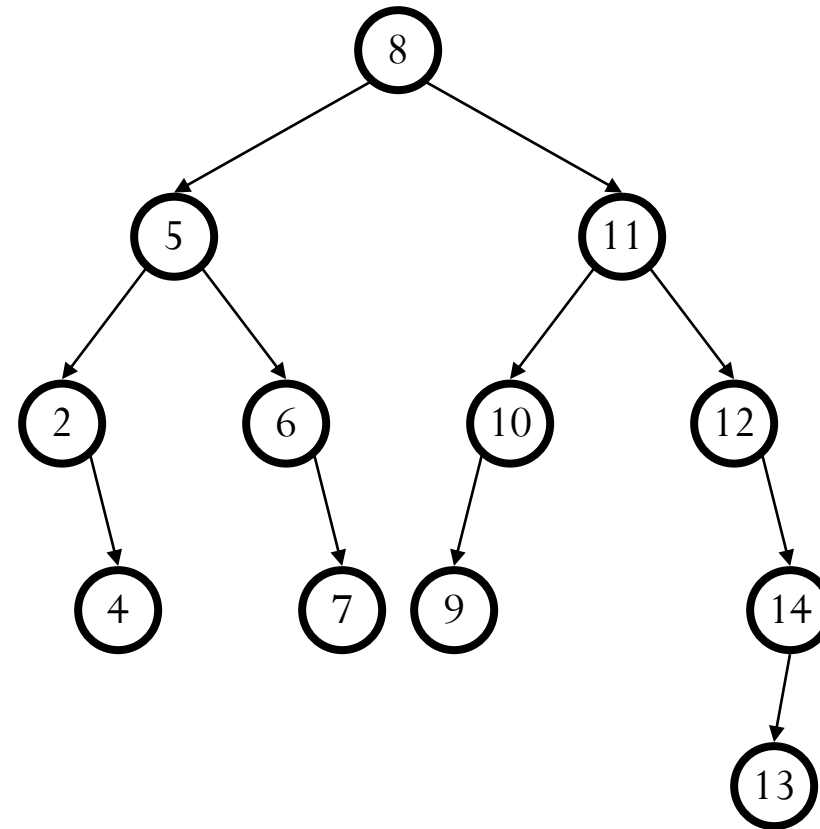
- *insert:*

- *deleteMin:*

- **Sorted list:**

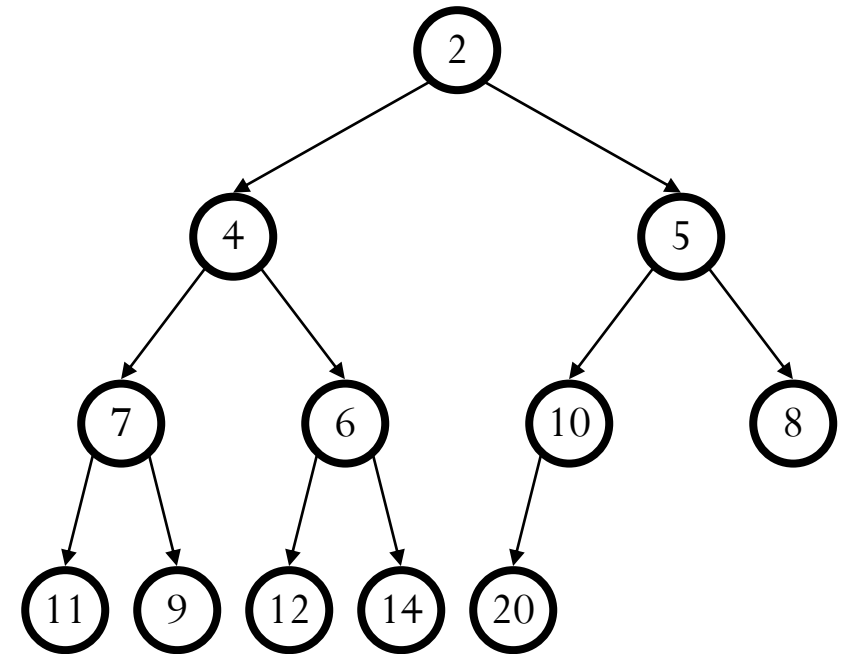
- *insert:*

- *deleteMin:*



# Binary Heap - Data Structure

- Heap-order property
  - parent's key is less than children's keys
  - result: minimum is always at the top
- Structure property
  - complete tree with fringe nodes packed to the left
  - result: depth is always  $O(\log n)$ ;
  - next open location always known



# Binary Heap - Data Structure

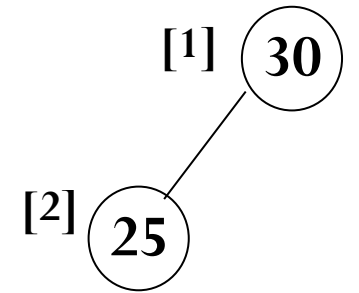
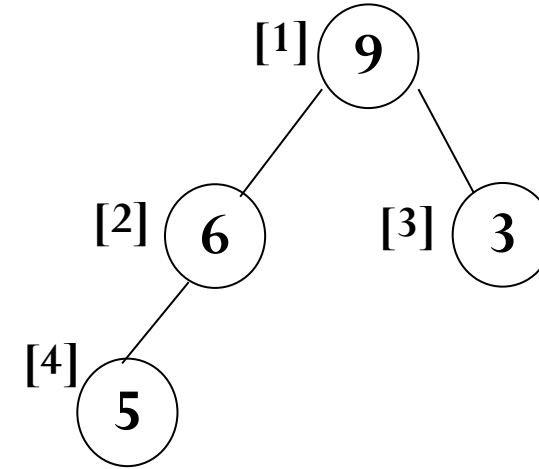
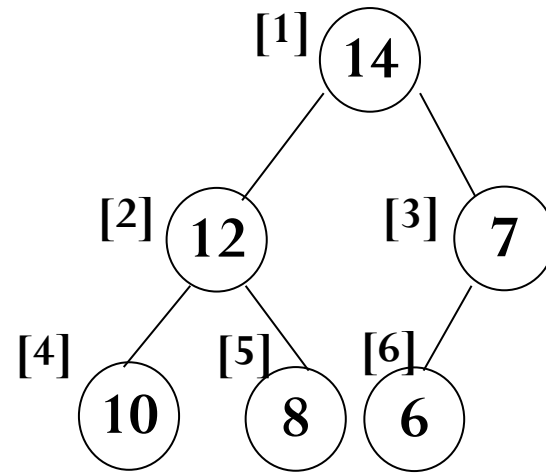
- A *heap* orders its node, but in a way different from a binary search tree
- A complete tree is a heap if
  - The value in the root is the smallest of the tree
  - Every subtree is also a heap
- Equivalently, a complete tree is a heap if
  - Node value  $<$  child value, for each child of the node
- **Note:** This use of the word “heap” is entirely different from the heap that is the allocation area in Java

# Binary Heap

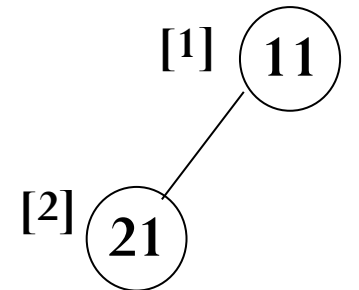
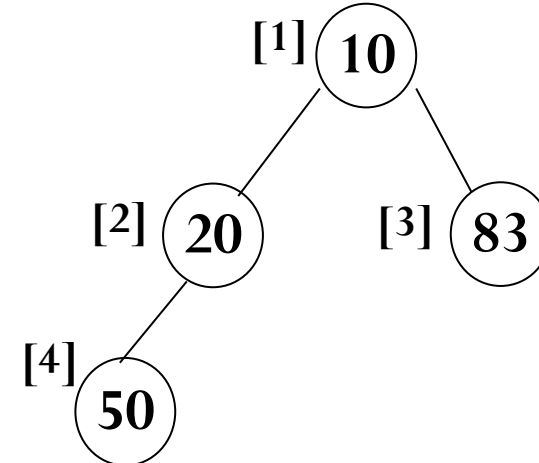
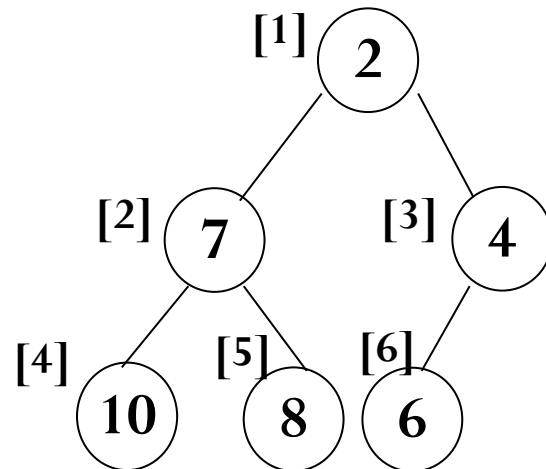
- *Max tree*: the key value in each node is **no smaller than** the key values in its children.
  - *Max heap* is a **complete binary tree** that is also a max tree.
- *Min tree*: the key value in each node is **no larger than** the key values in its children.
  - *Min heap* is a **complete binary tree** that is also a min tree.
- Operations on heaps
  - creation of an empty heap
  - insertion of a new element into the heap;
  - deletion of the largest element from the heap

# Binary Heap

- The root of **max heap** contains the **largest** element.

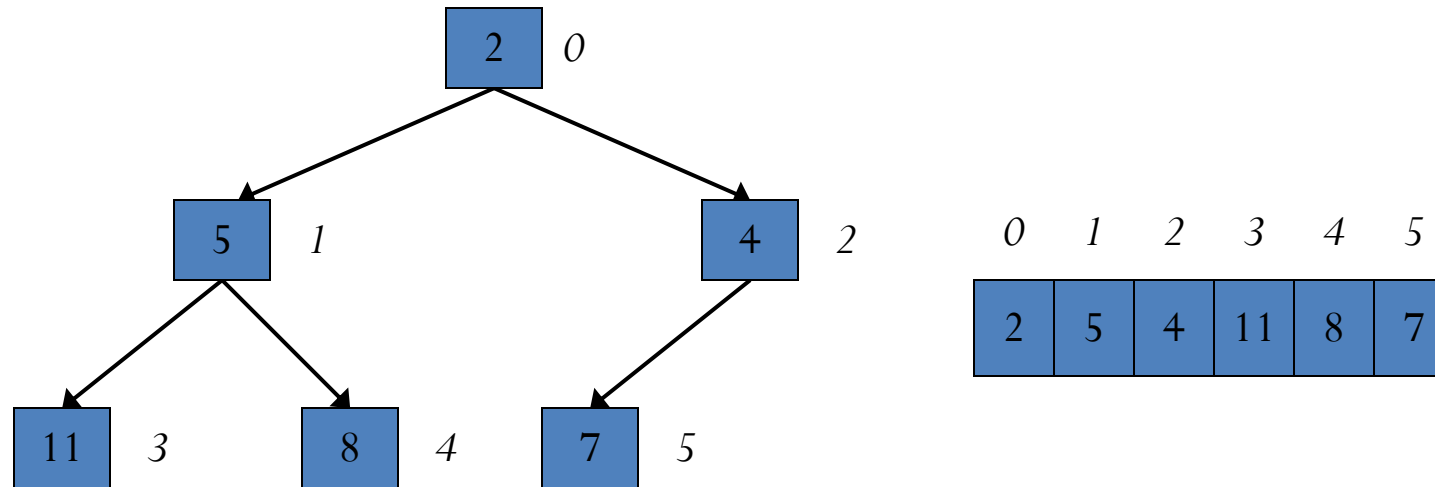


- The root of **min heap** contains the **smallest** element.



# Implementing a Heap

- Recall: a heap is a complete binary tree
  - (plus the heap ordering property)
- A complete binary tree fits nicely in an array:
  - The root is at index 0
  - Children of node at index  $i$  are at indices  $2i+1$ ,  $2i+2$



# Storage (Min Heap)

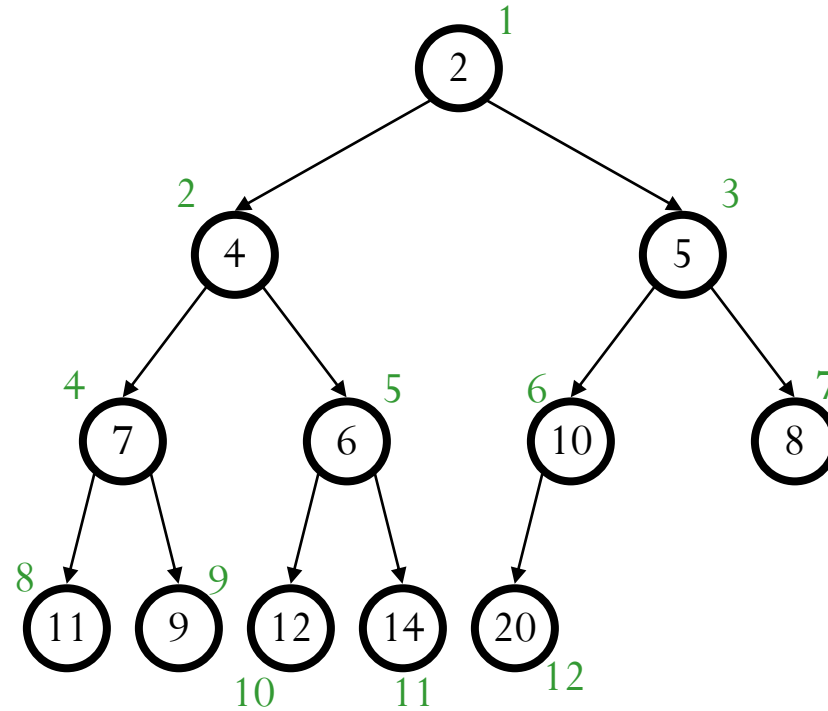
- Calculations:

- child:

- parent:

- root:

- next free:



0	1	2	3	4	5	6	7	8	9	10	11	12	
12	2	4	5	7	6	10	8	11	9	12	14	20	



# Removing an Item from a Heap

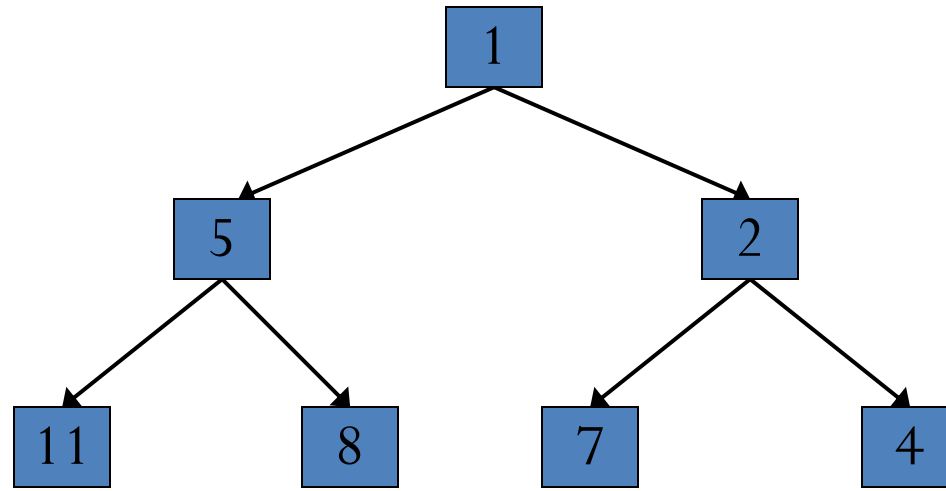
- Removing an item is always from the top:
  - Remove the root (minimum element):
    - Leaves a “hole”:
  - Fill the “hole” with the last item (lower right-hand) L
    - Preserve completeness
  - Swap L with smallest child, as necessary
    - Restore “heap-ness”

# Example Removing From a Heap

Remove: returns 1

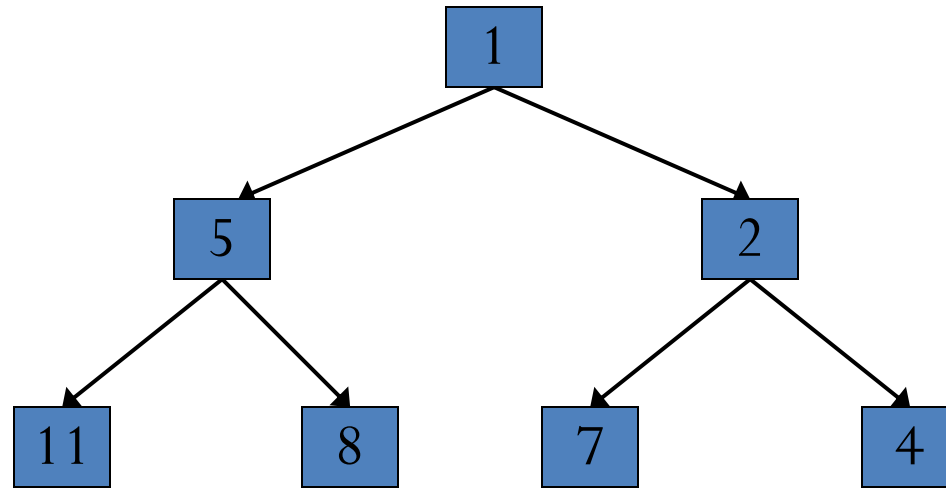
*Move 4 to root*

*Swap down*



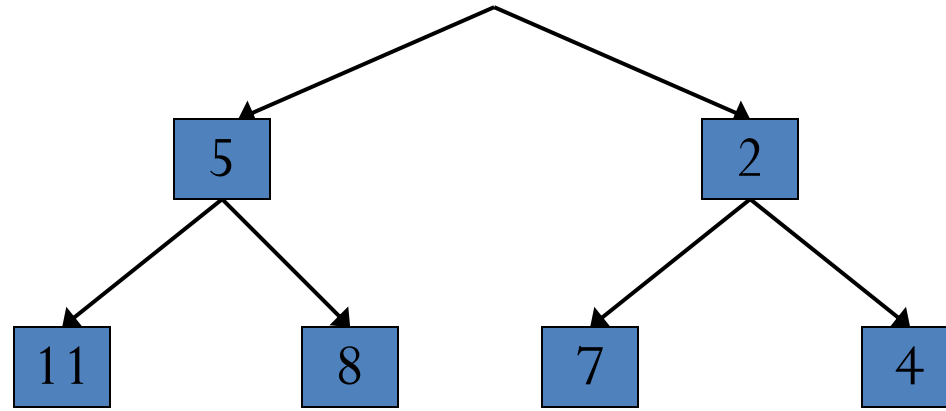
# Example Removing From a Heap

Remove: returns 1



# Example Removing From a Heap

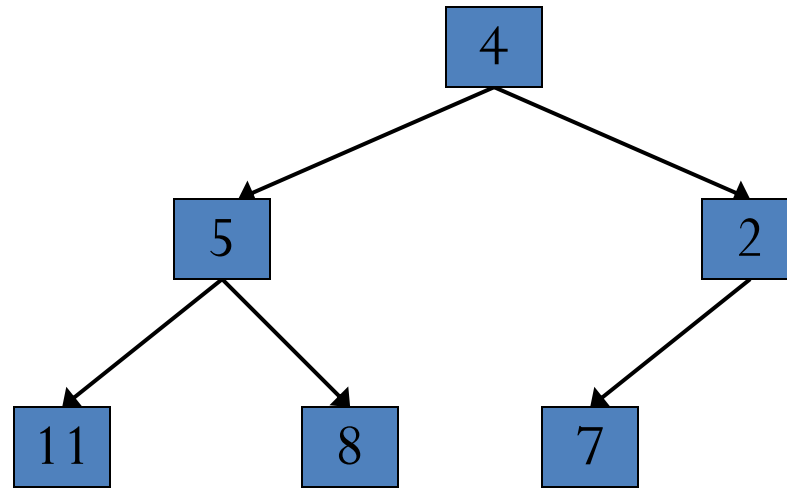
Remove: returns 1



# Example Removing From a Heap

Remove: returns 1

*Move 4 to root*

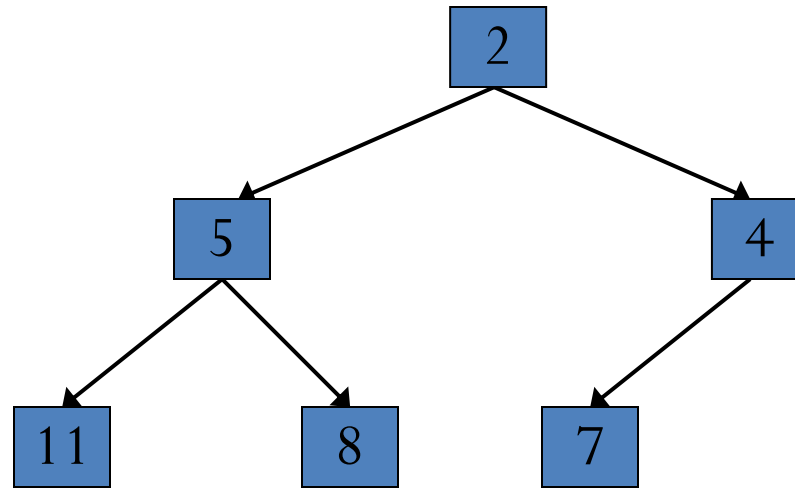


# Example Removing From a Heap

Remove: returns 1

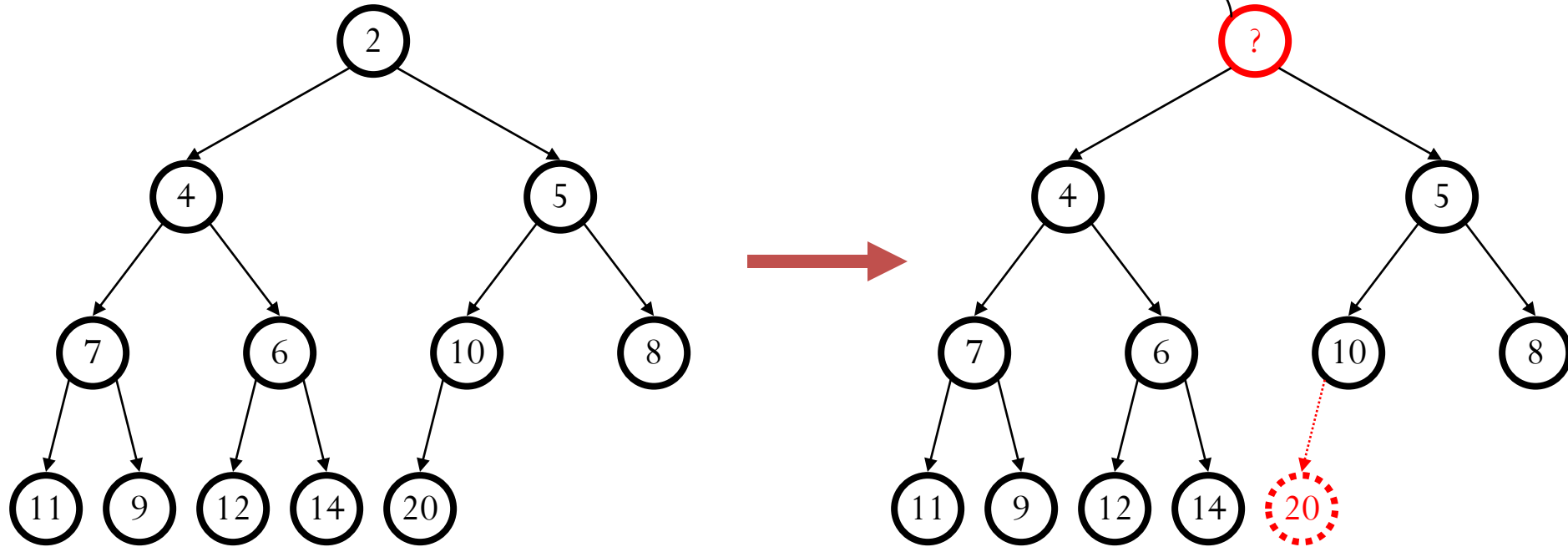
*Move 4 to root*

*Swap down*

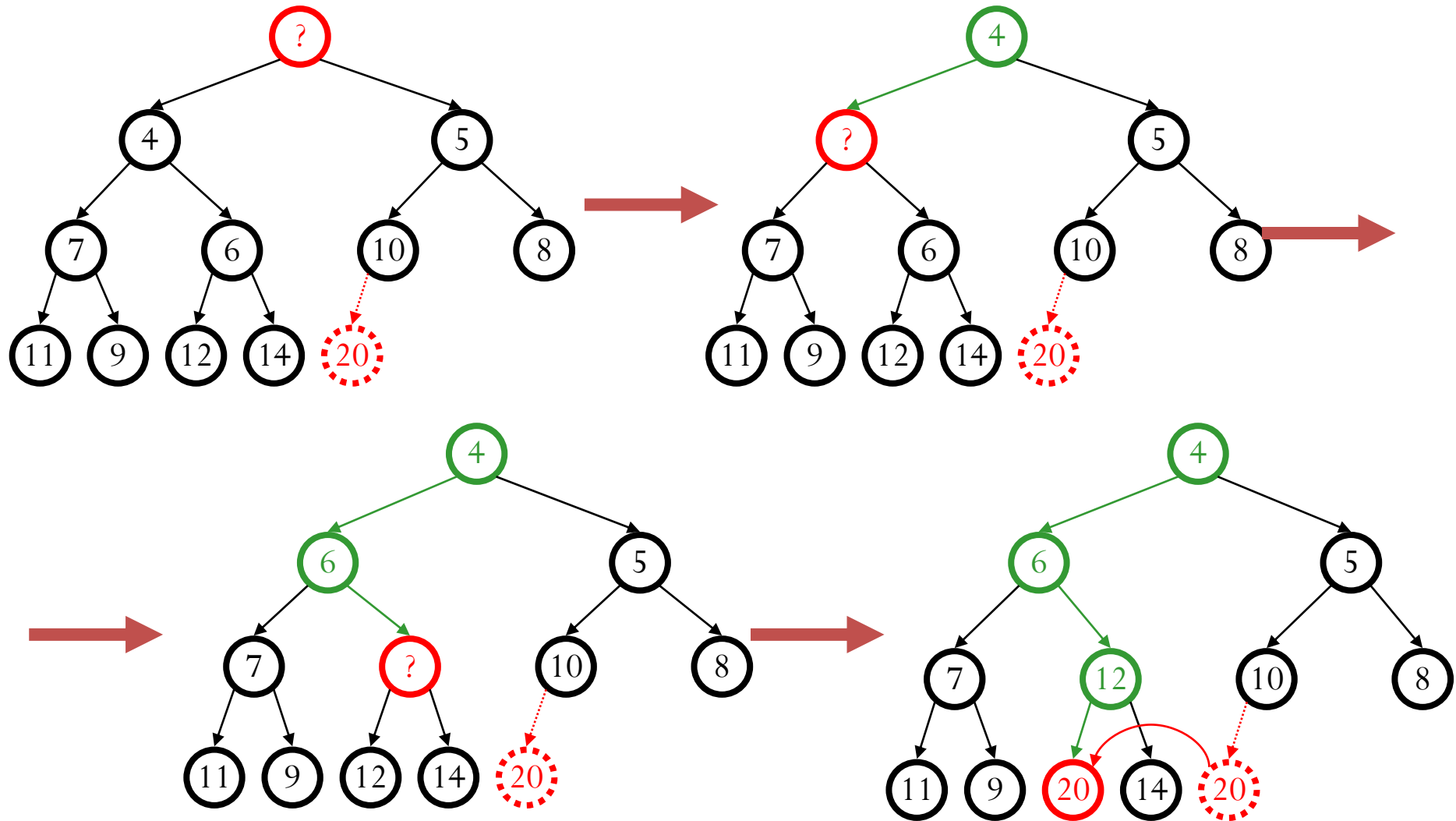


# DeleteMin

`pqueue.deleteMin()`

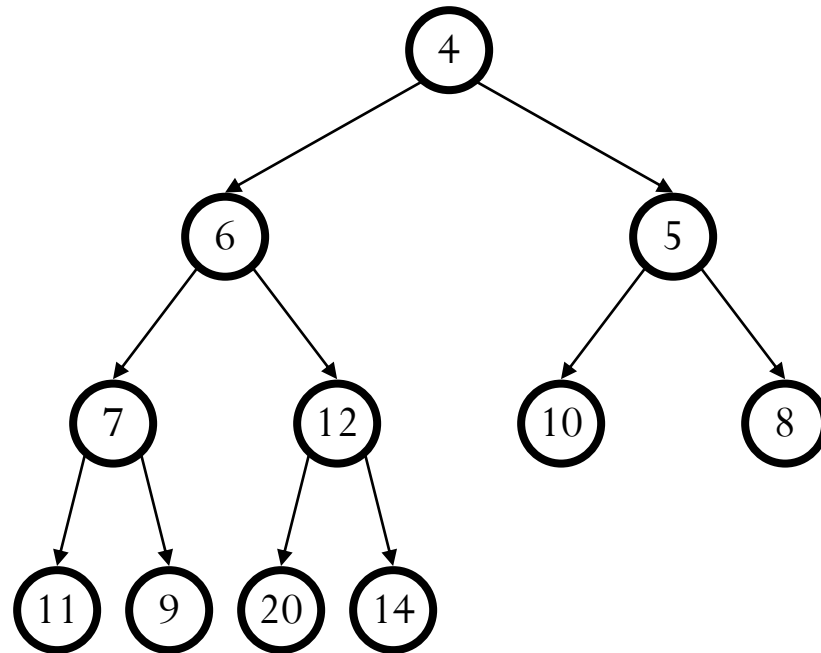


# Percolate Down





Finally...

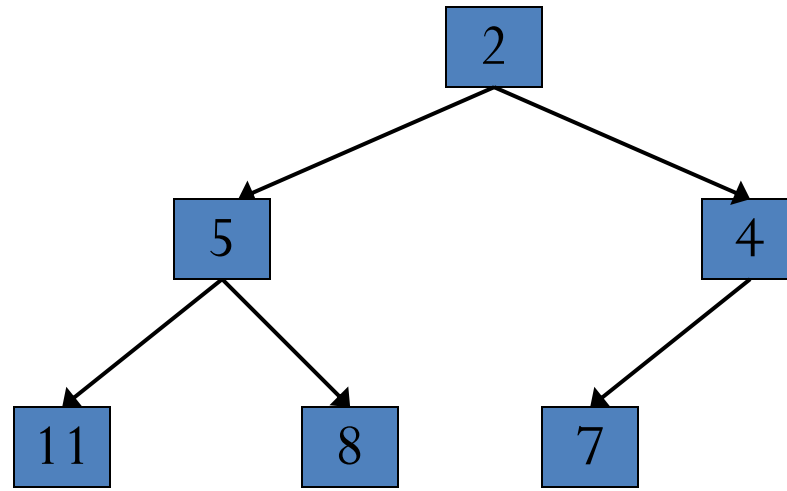


# Inserting an Item into a Heap

1. Insert the item in the next position across the bottom of the complete tree:  
preserve completeness
2. Restore “heap-ness”:
  1. **while** new item not root and  $<$  parent
  2. swap new item with parent

# Example Inserting into a Heap

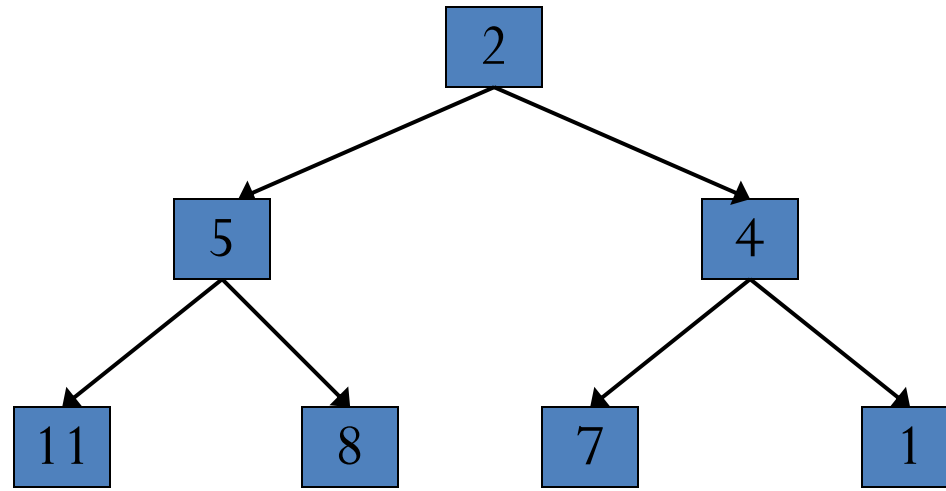
Insert 1



# Example Inserting into a Heap

Insert 1

*Add as leaf*

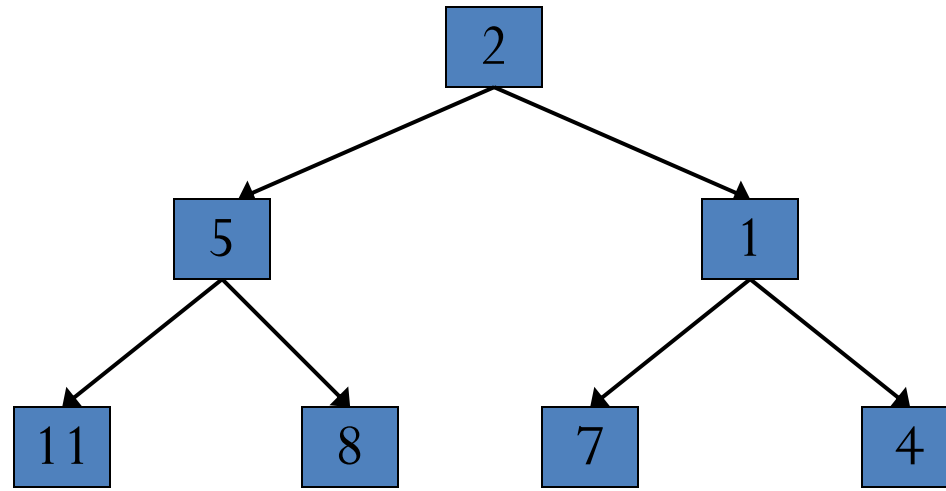


# Example Inserting into a Heap

Insert 1

*Add as leaf*

*Swap up*



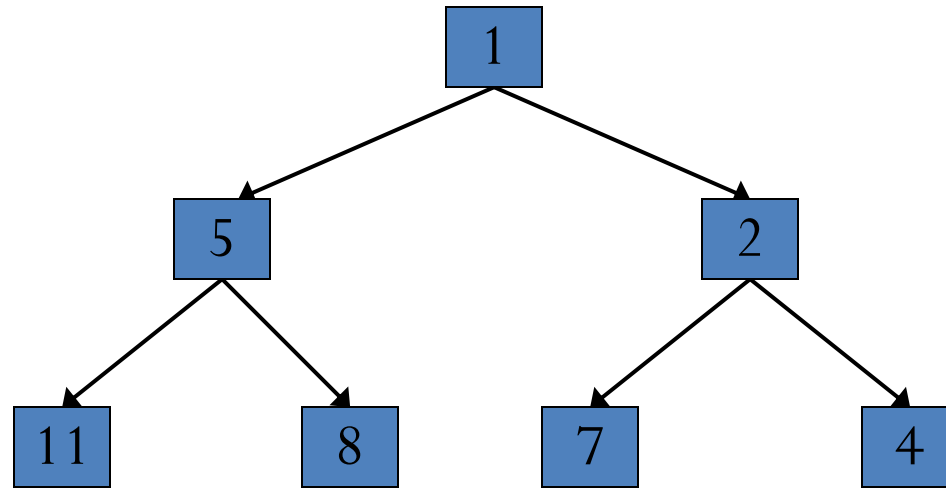
# Example Inserting into a Heap

Insert 1

*Add as leaf*

*Swap up*

*Swap up*



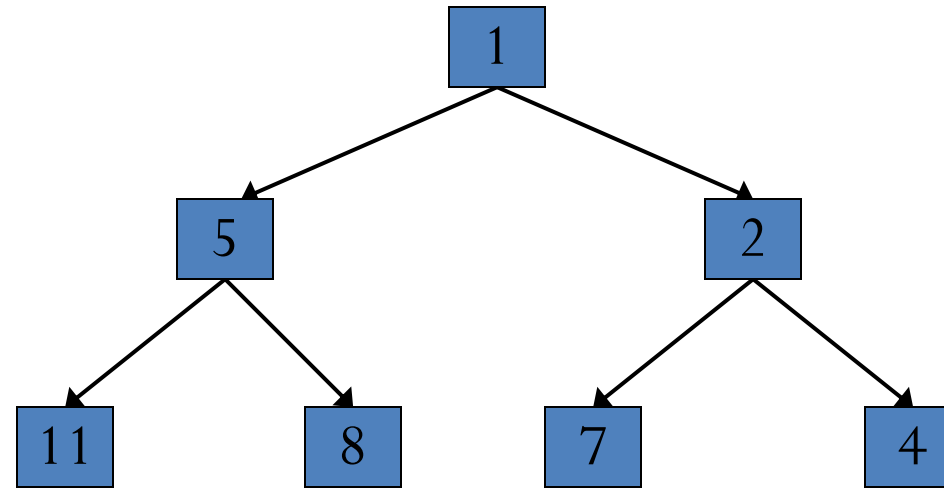
# Example Inserting into a Heap

Insert 1

*Add as leaf*

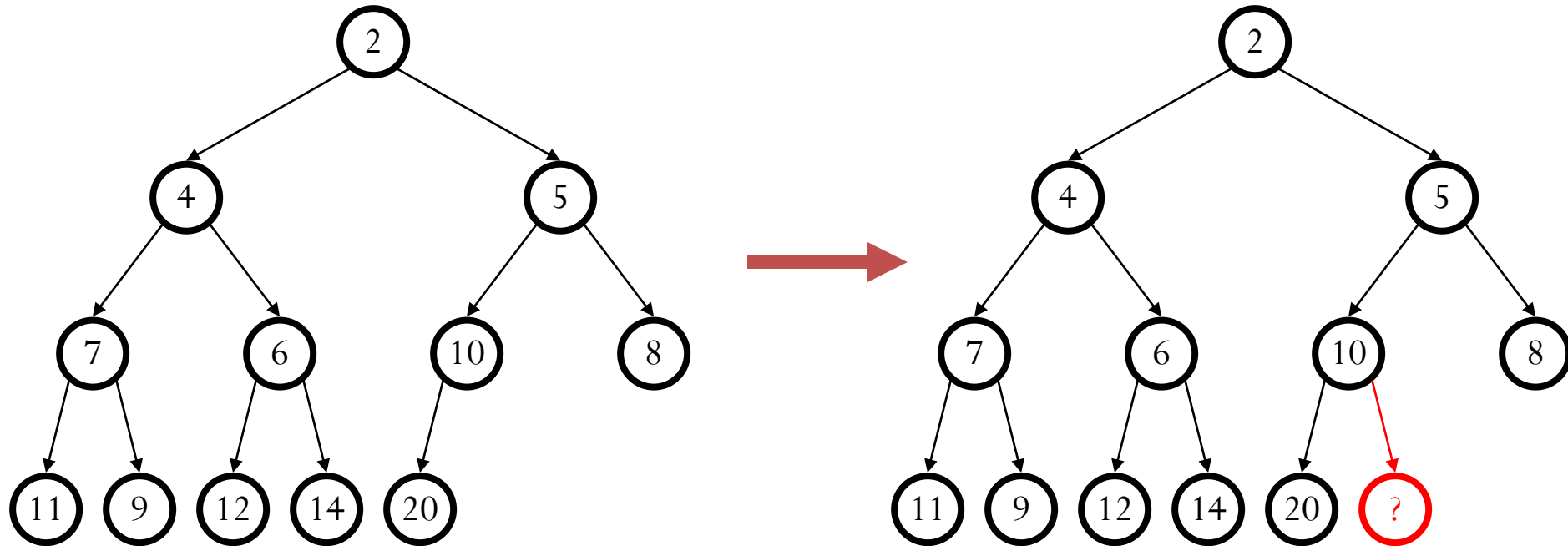
*Swap up*

*Swap up*



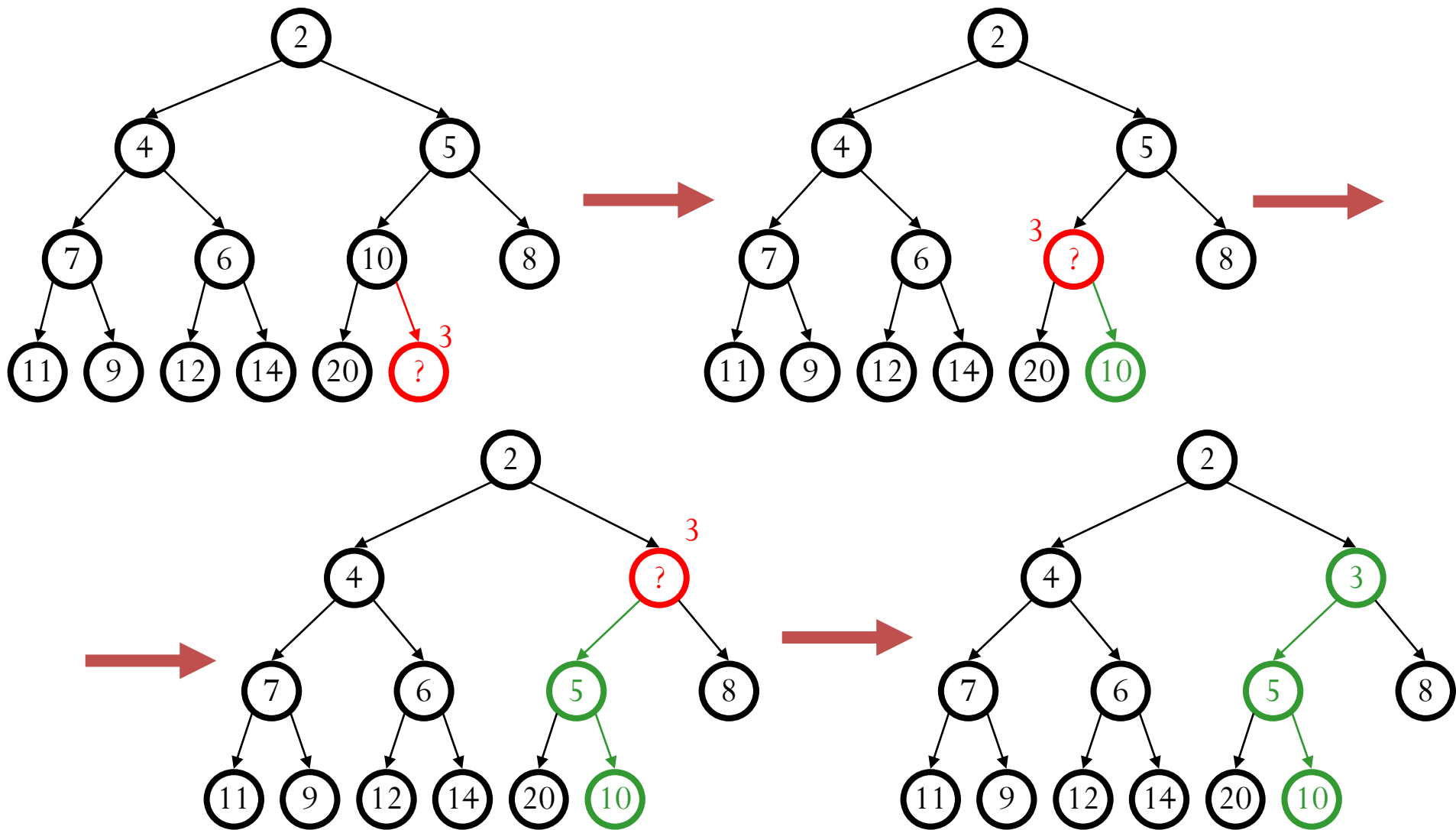
# Insert

`pqueue.insert(3)`





# Percolate Up

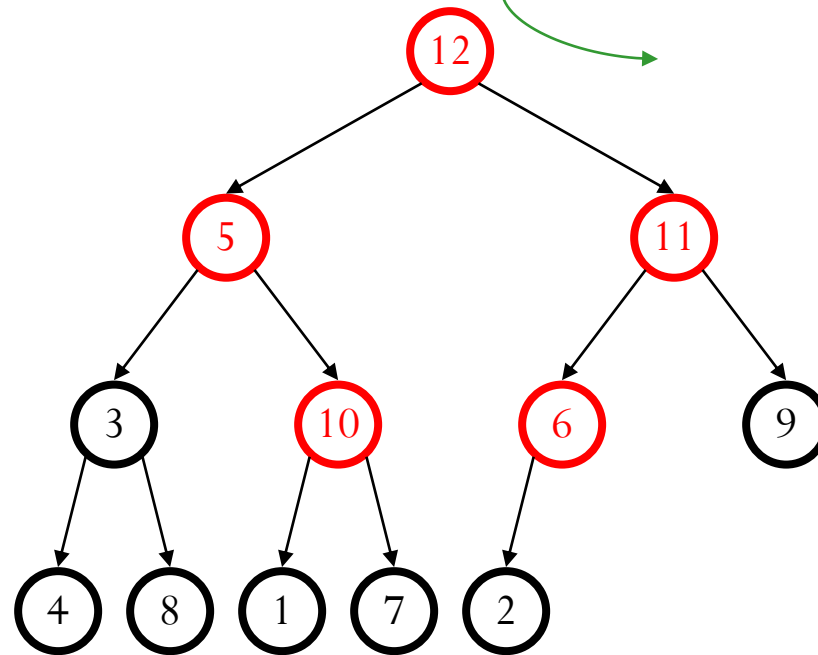


# Build Heap

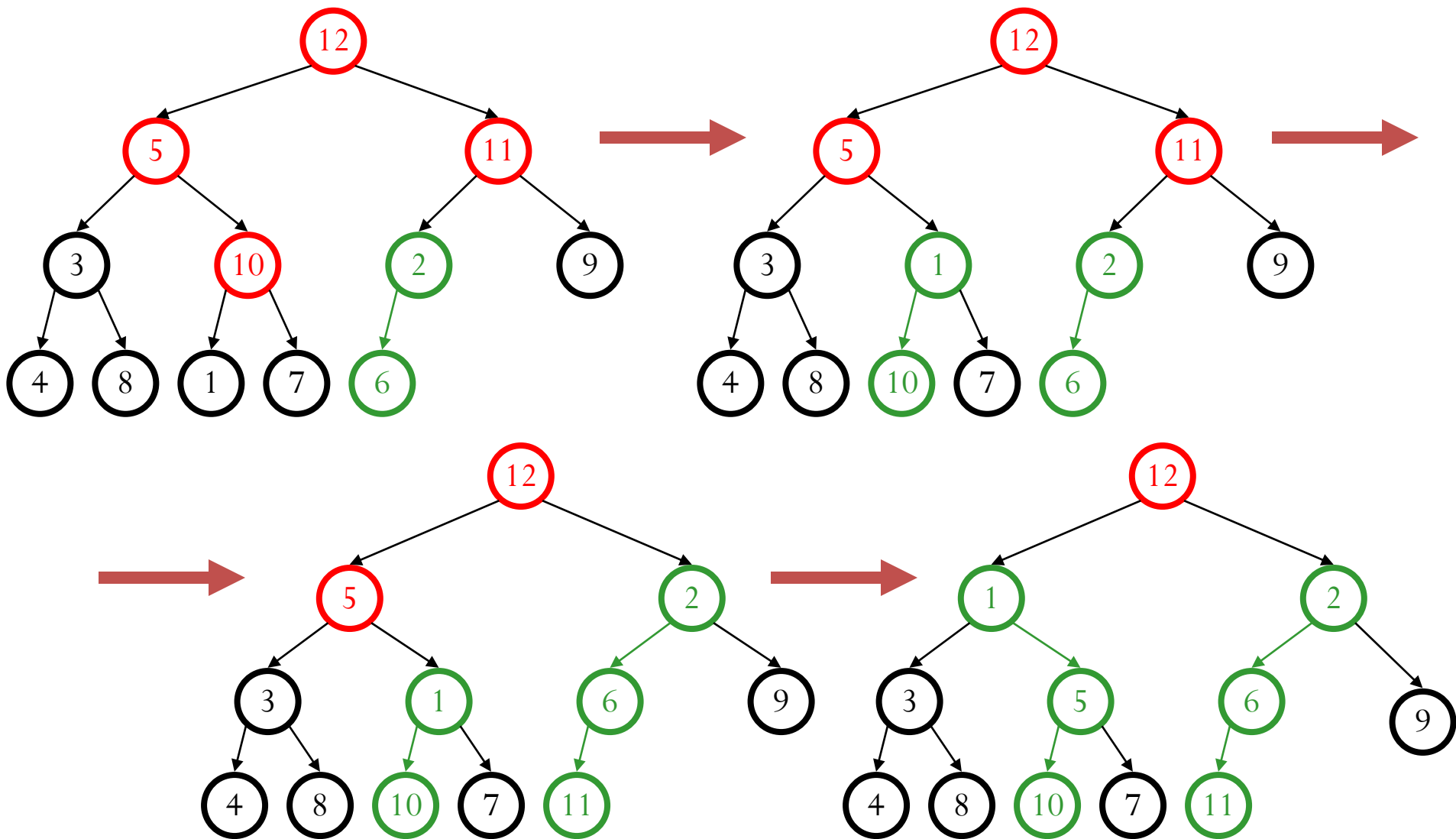
Floyd's Method.

12	5	11	3	10	6	9	4	8	1	7	2
----	---	----	---	----	---	---	---	---	---	---	---

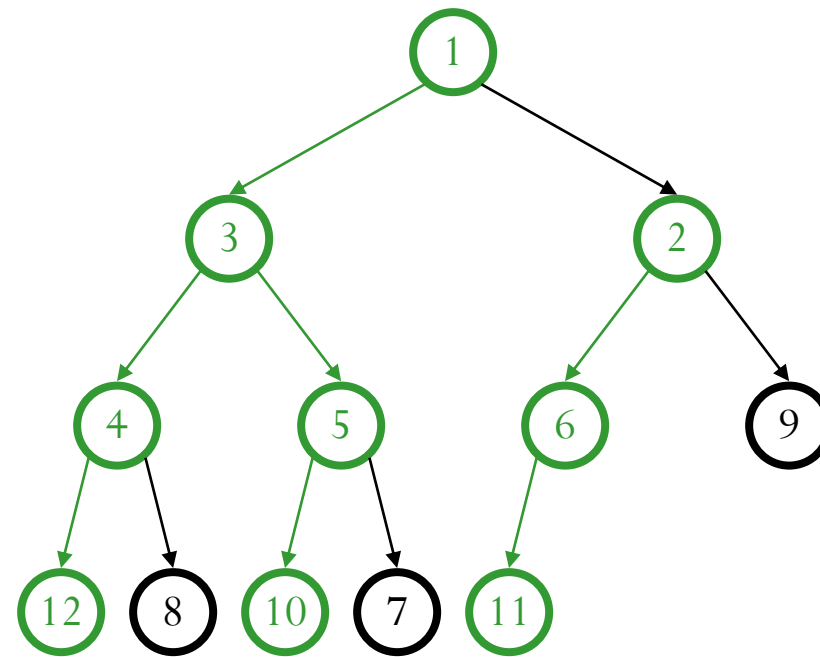
pretend it's a heap and fix the heap-order property!



# Build Heap



# Build Heap

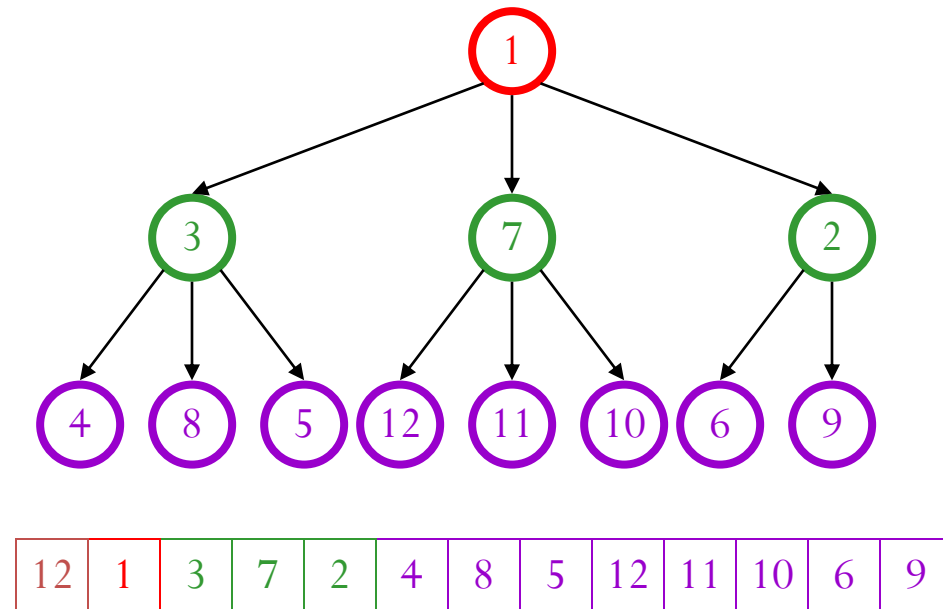


# Thinking about Heaps

- Observations
  - finding a child/parent index is a multiply/divide by two
  - operations jump widely through the heap
  - each operation looks at only two new nodes
  - inserts are at least as common as deleteMins
- Realities
  - division and multiplication by powers of two are **fast**
  - looking at one new piece of data sucks in a cache line
  - with **huge** data sets, disk accesses dominate

# Solution: d-Heaps

- Each node has  $d$  children
- Still representable by array
- Good choices for  $d$ :
  - optimize performance based on # of inserts/removes
  - choose a power of two for efficiency
  - fit one set of children in a cache line
  - fit one set of children on a memory page/disk block

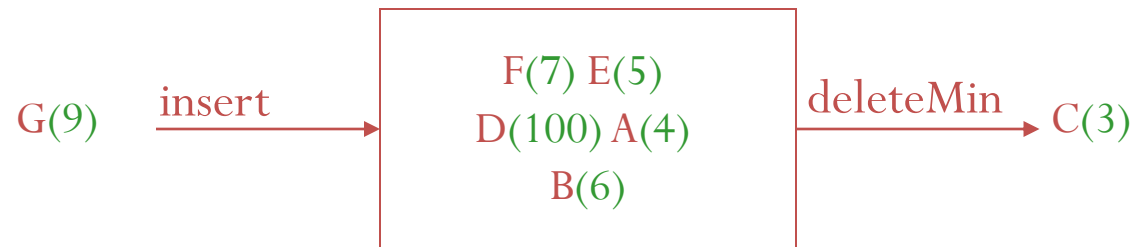


# Priority Queue

# Priority Queue ADT

- Priority Queue operations

- create
- destroy
- insert
- deleteMin
- is\_empty



- Priority Queue property: for two elements in the queue,  $x$  and  $y$ , if  $x$  has a lower **priority value** than  $y$ ,  $x$  will be deleted before  $y$



# Changing Priorities

- In many applications the priority of an object in a priority queue may change over time
  - if a job has been sitting in the printer queue for a long time increase its priority
  - unix “renice”
- Must have some (separate) way of find the position in the queue of the object to change (*e.g.* a hash table)

# Other Priority Queue Operations

- buildHeap
  - given a set of items, build a heap
- decreaseKey
  - given the position of an object in the queue, reduce its priority value
- increaseKey
  - given the position of an object in the queue, increase its priority value
- remove
  - given the position of an object in the queue, remove it

# Applications of the Priority Q

- Hold jobs for a printer in order of length
- Store packets on network routers in order of urgency
- Simulate events
- Select symbols for compression
- Sort numbers
- Anything *greedy*

# References

- Donald E. Knuth, The Art of Computer Programming, Volume 1: Fundamental Algorithms, 3rd Ed., Addison Wesley, 1997, §2.2.1, p.238.
- Weiss, Data Structures and Algorithm Analysis in C++, 3rd Ed., Addison Wesley, §3.3.1, p.75.
- Donald E. Knuth, The Art of Computer Programming, Volume 1: Fundamental Algorithms, 3rd Ed., Addison Wesley, 1997, §2.2.1, p.238.
- Cormen, Leiserson, and Rivest, Introduction to Algorithms, McGraw Hill, 1990, §11.1, p.200.
- Weiss, Data Structures and Algorithm Analysis in C++, 3rd Ed., Addison Wesley, §3.3.1, p.75.
- Koffman and Wolfgang, “Objects, Abstraction, Data Structures and Design using C++”, John Wiley & Sons, Inc., Ch. 6.
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- CSE326: Data Structure, Department of Computer Science and Engineering, University of Washington <https://courses.cs.washington.edu/courses/cse326>
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