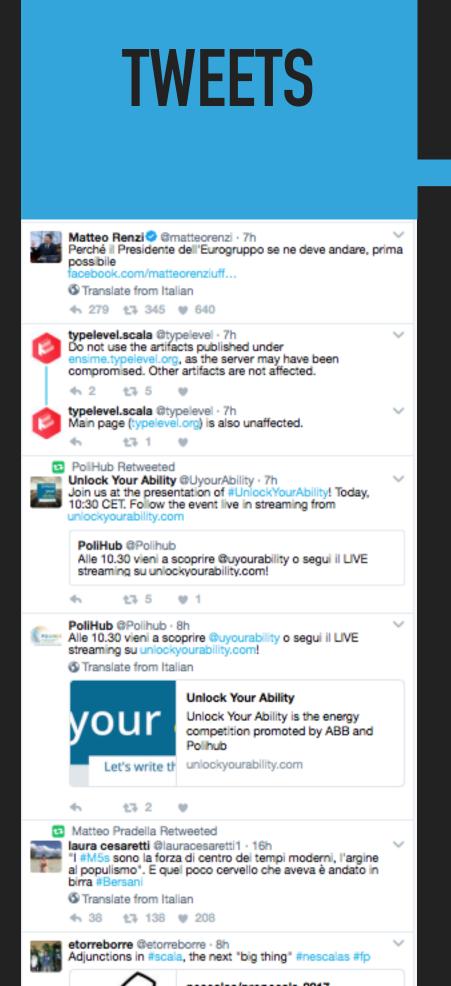
ANDREA LATTUADA, PHD CANDIDATE @ ETH SYSTEMS GROUP

PAPERS WE LOVE: ZÜRICH

NAIAD: A TIMELY DATAFLOW SYSTEM DEREK G. MURRAY, FRANK MCSHERRY, REBECCA ISAACS, MICHAEL ISARD, PAUL BARHAM, MARTÍN ABADI

NAIAD IS A DISTRIBUTED SYSTEM FOR EXECUTING DATA PARALLEL, CYCLIC DATAFLOW PROGRAMS.

CONTINUOUS INPUT



CONTINUOUS INPUT

TWEETS @ANOTHER: SOME STUFF

CONTINUOUS INPUT

TWEETS

@ONEMORE: THING

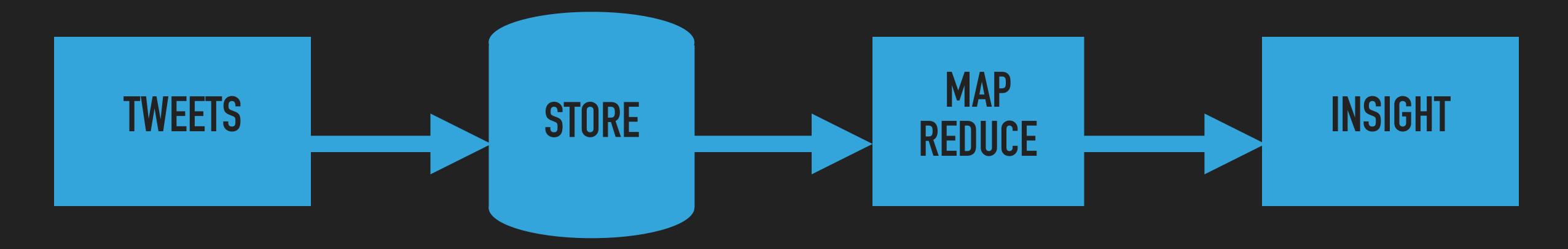
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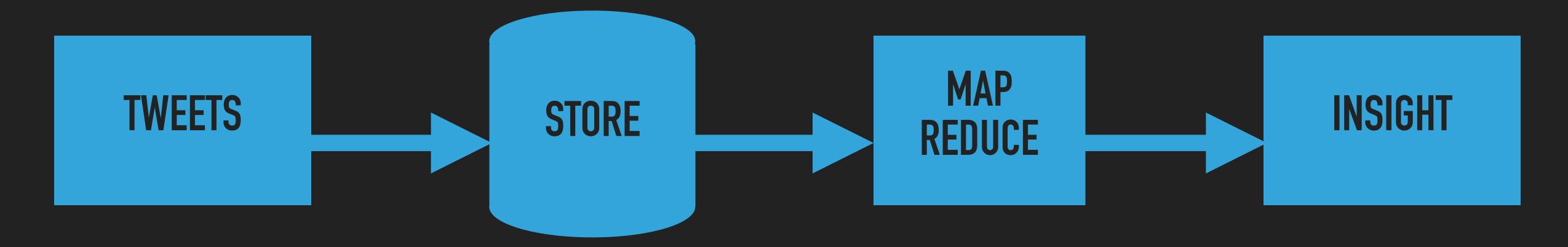
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TWEETS COMPUTATION INSIGHT

TWEETS COMPUTATION INSIGHT

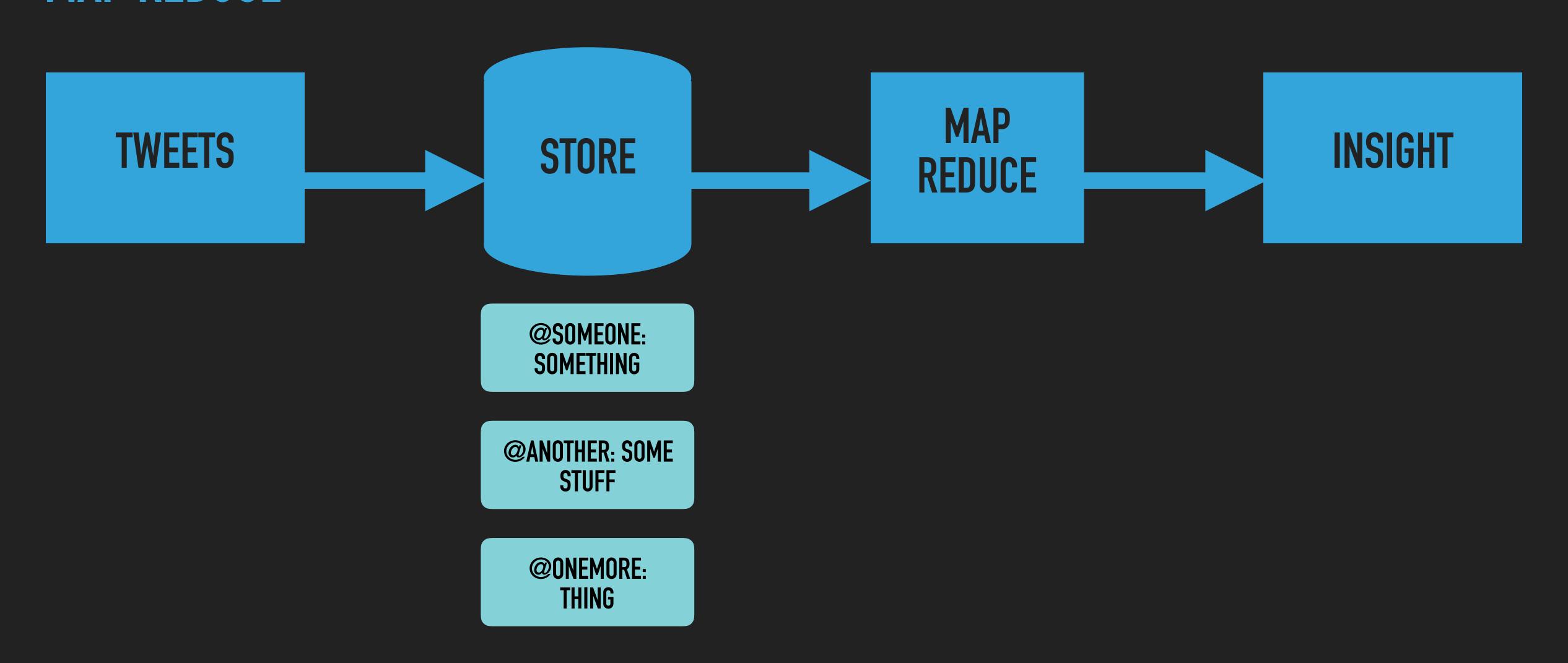
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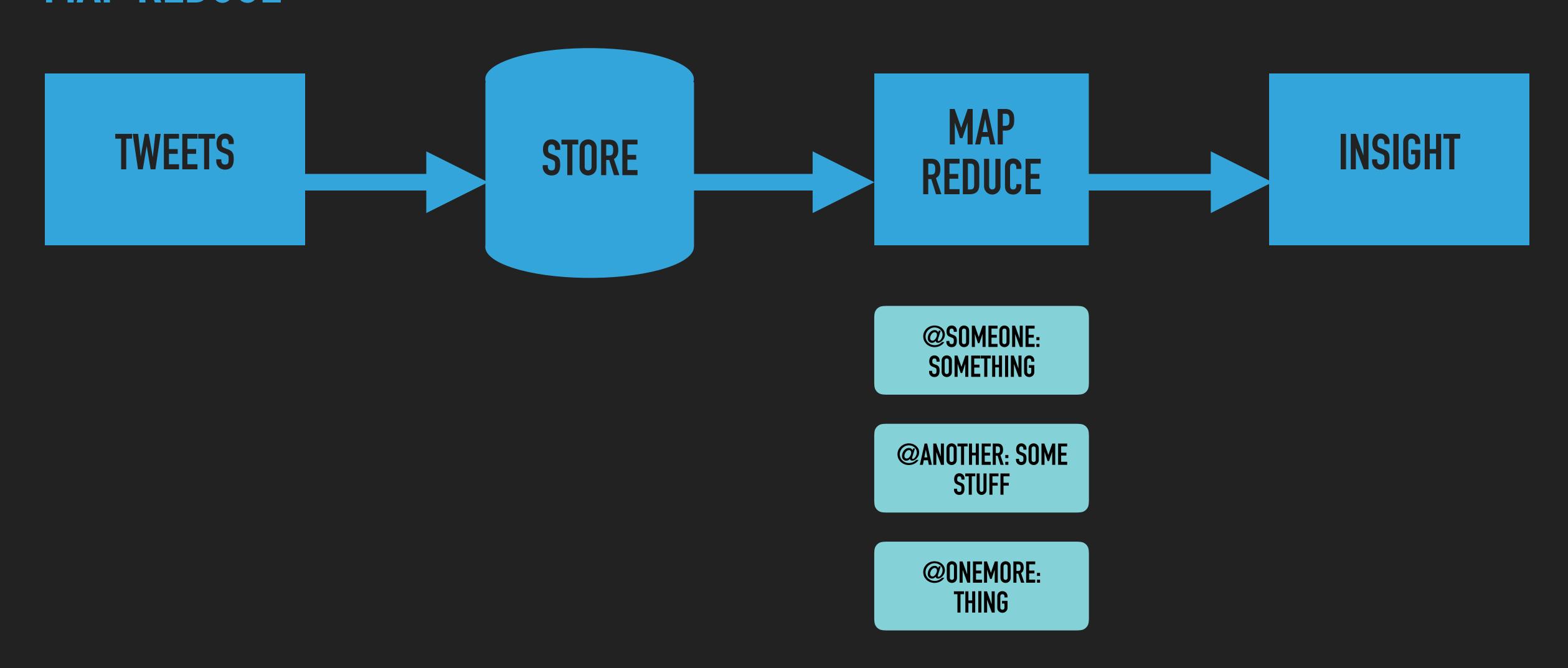


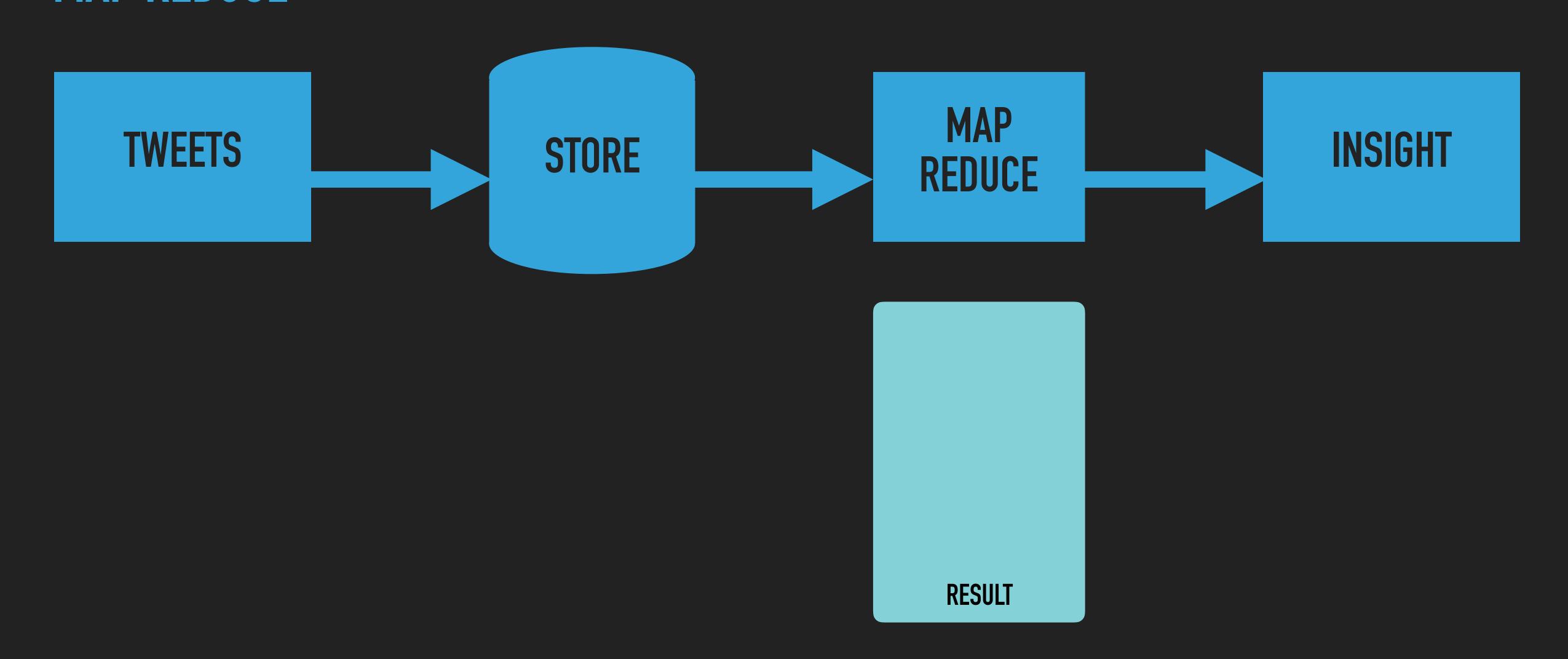


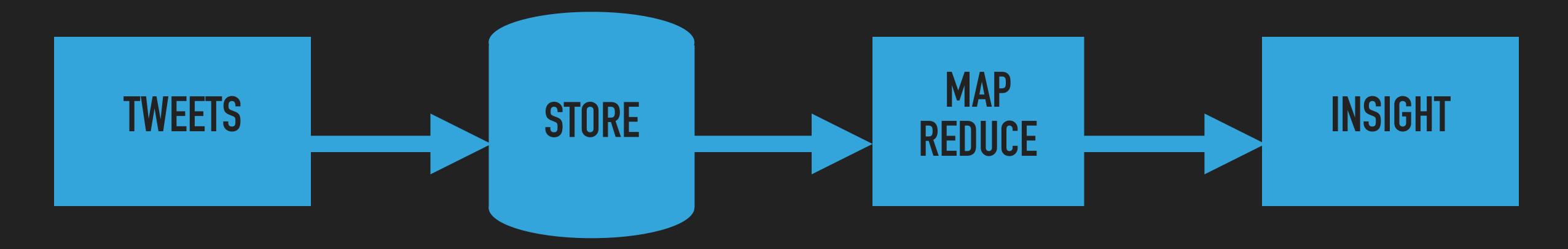
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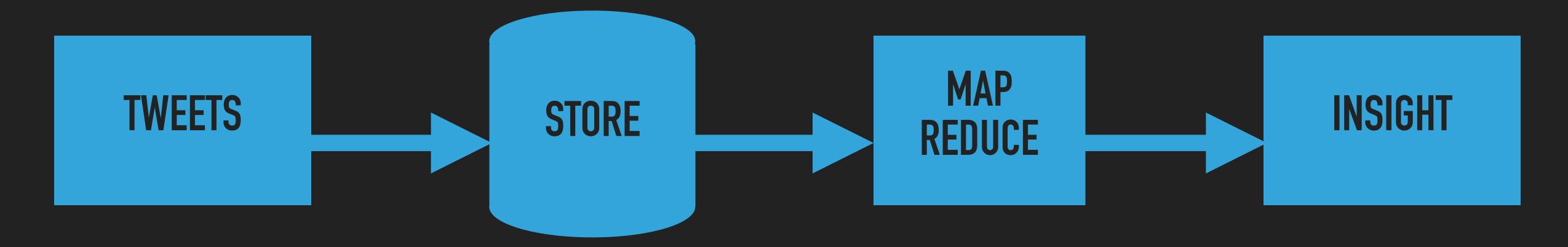
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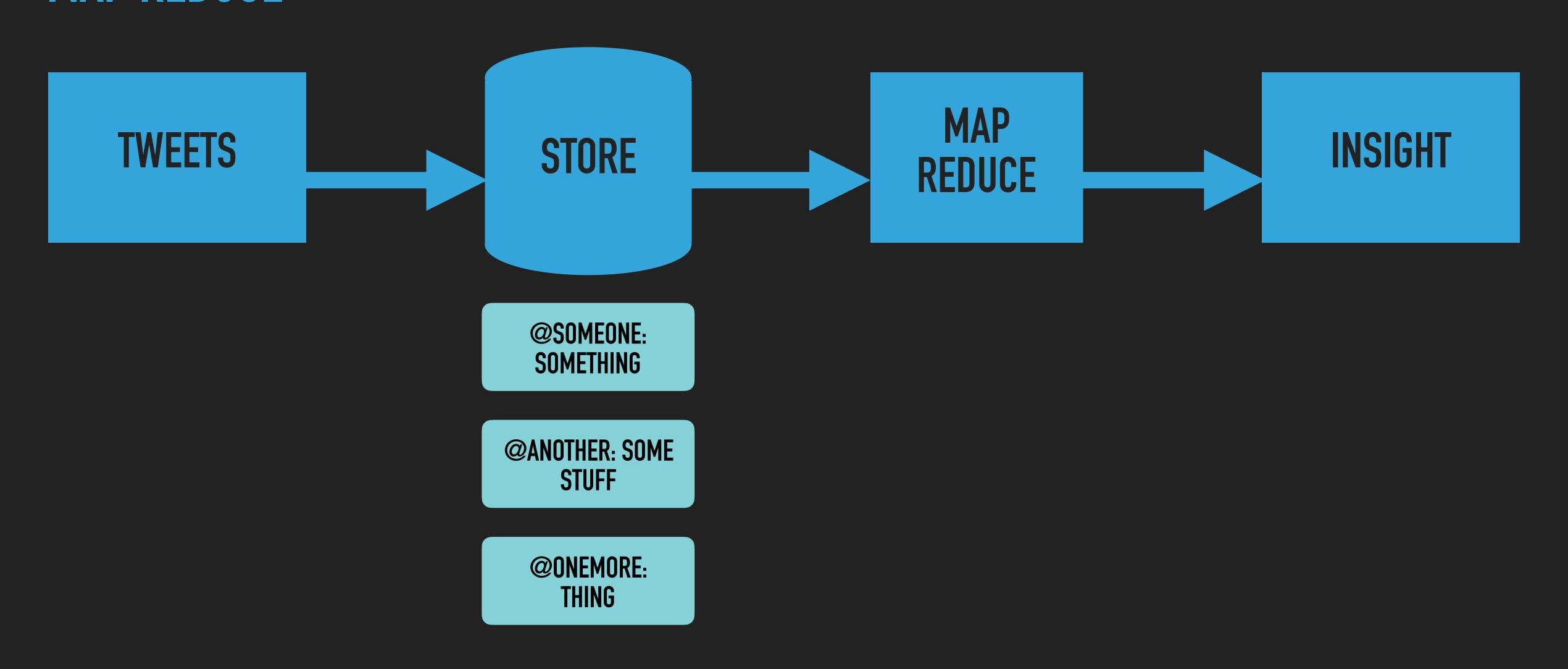


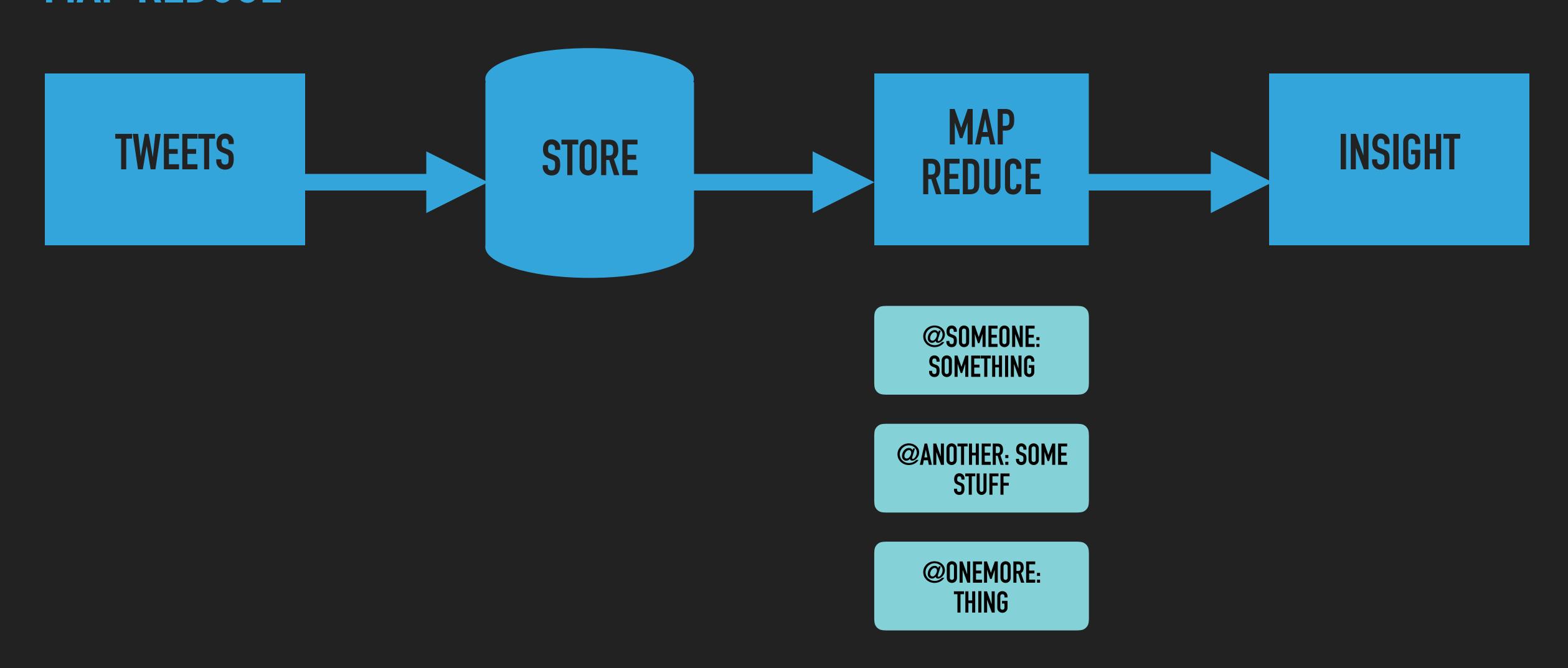


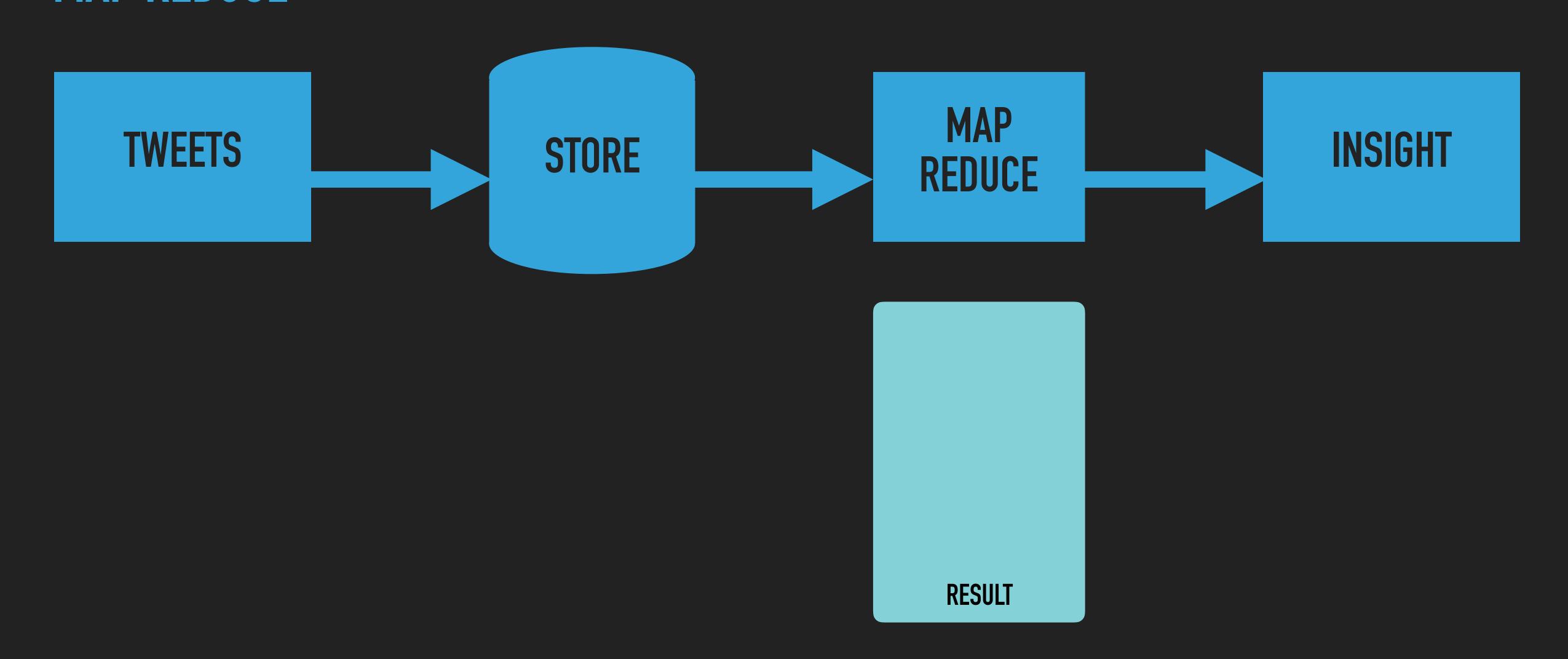


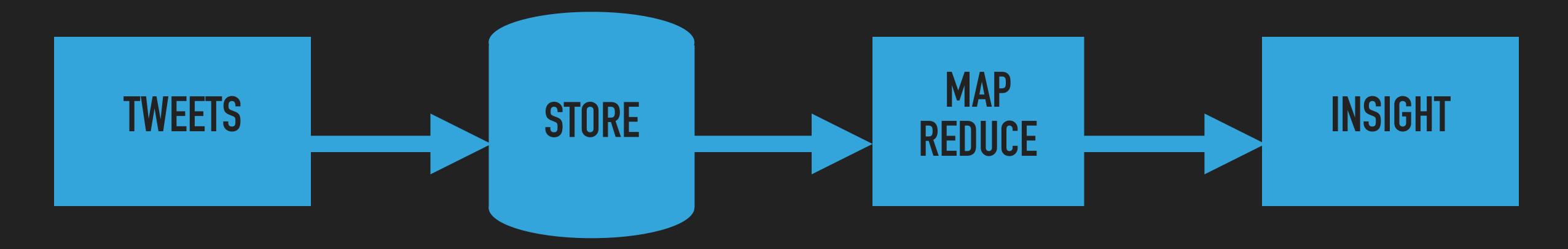
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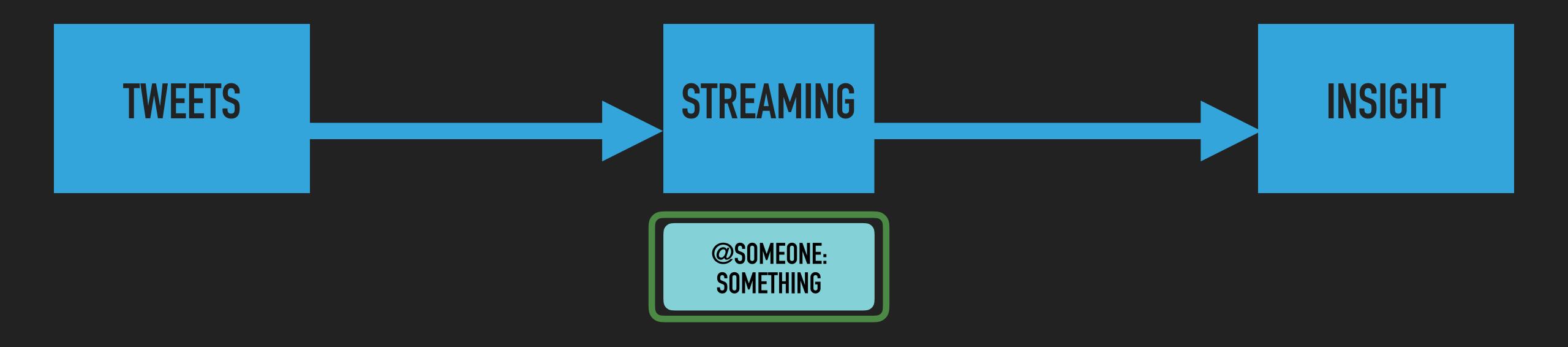
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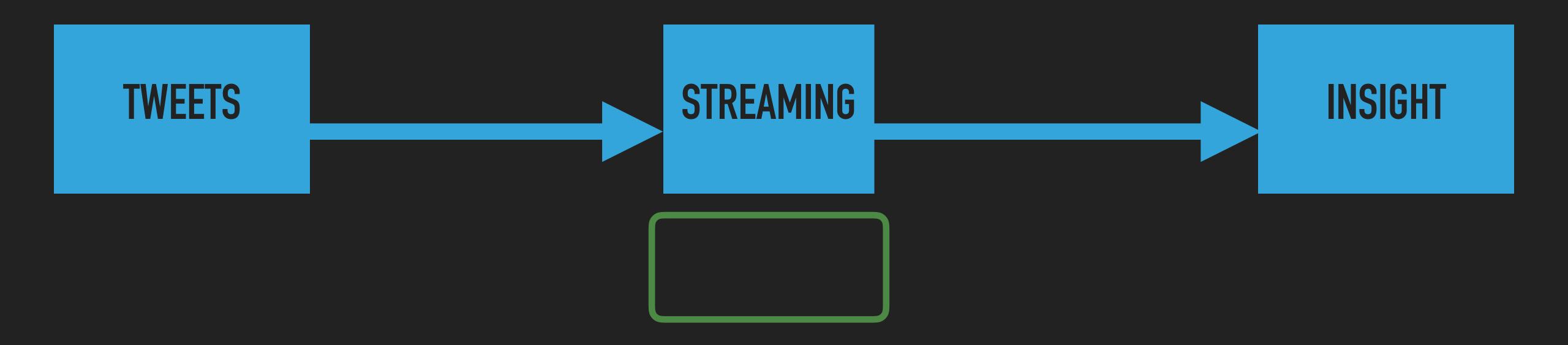


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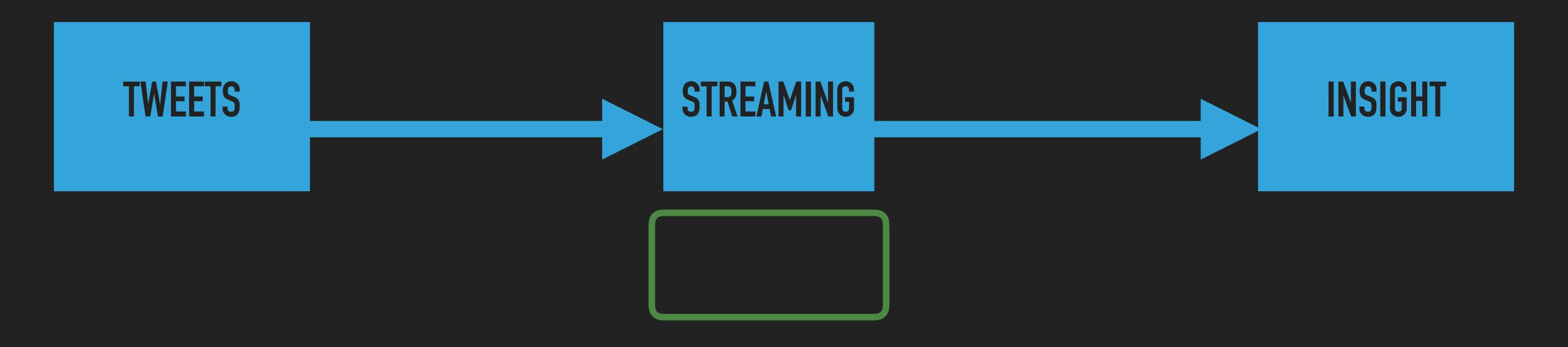
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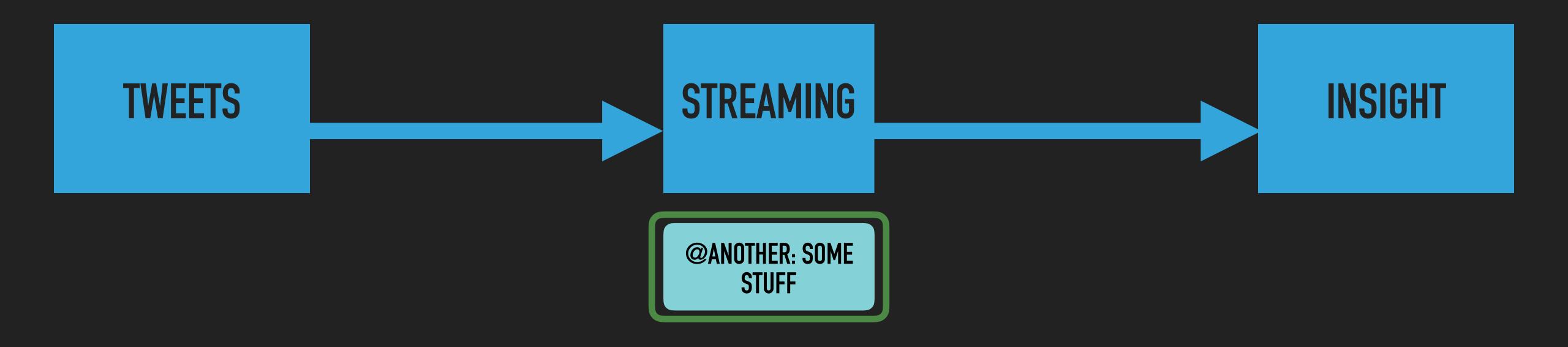
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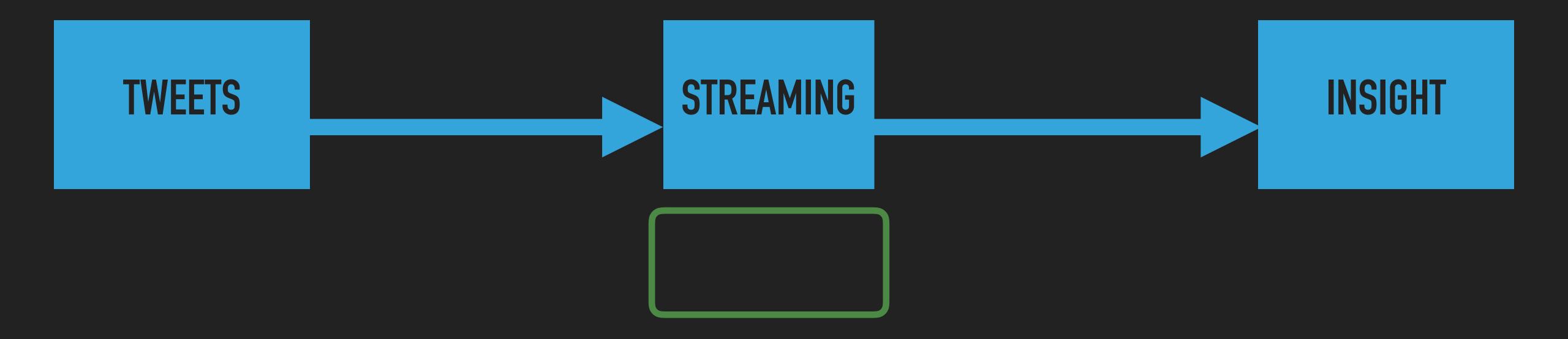
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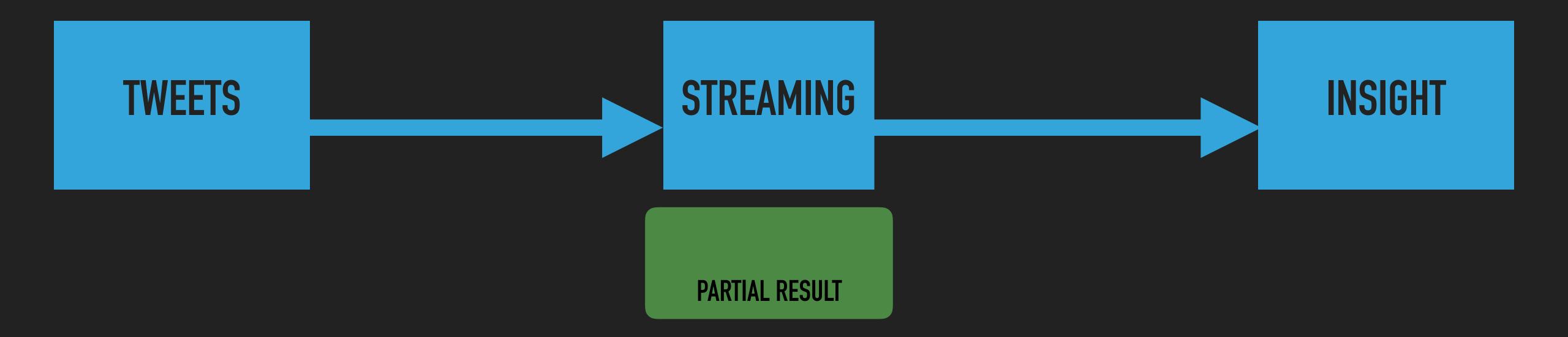
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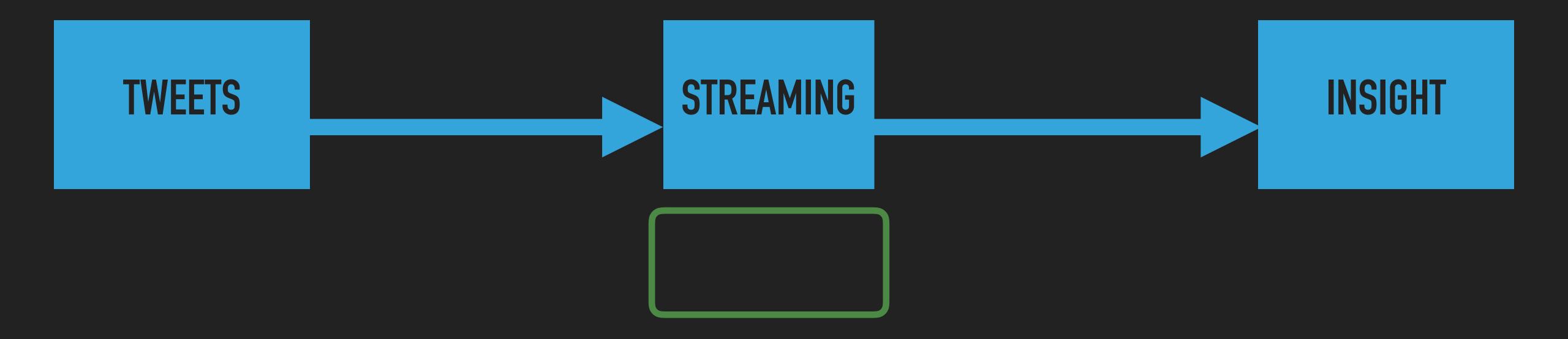




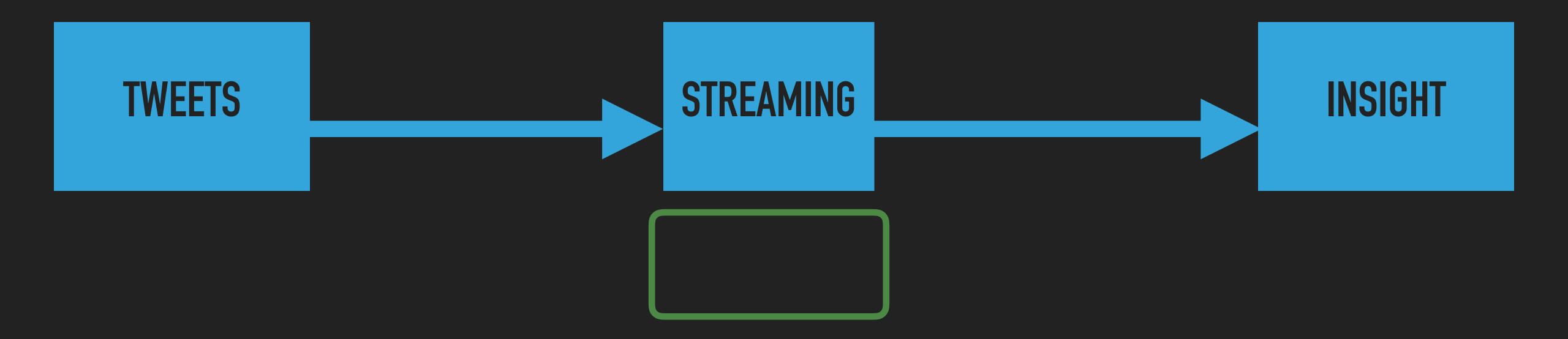




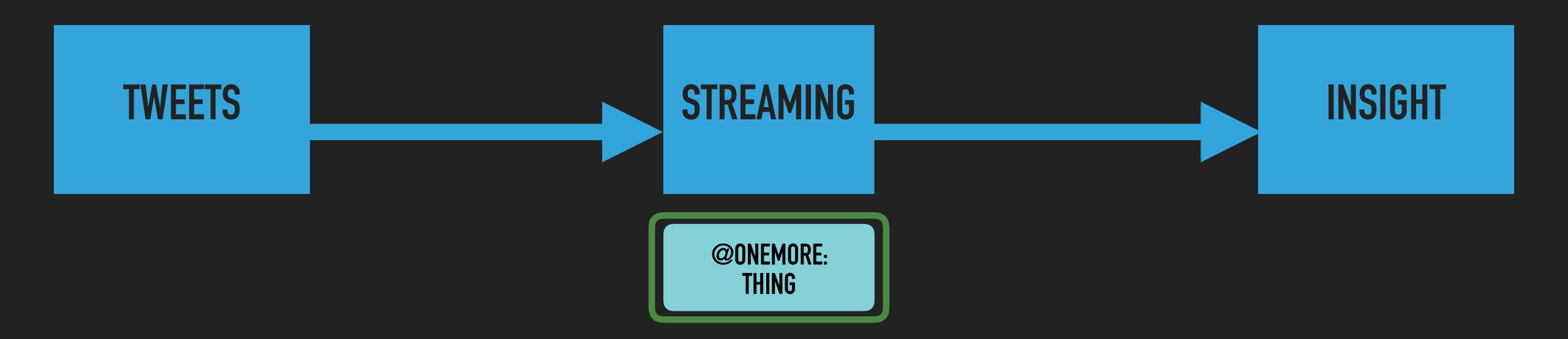


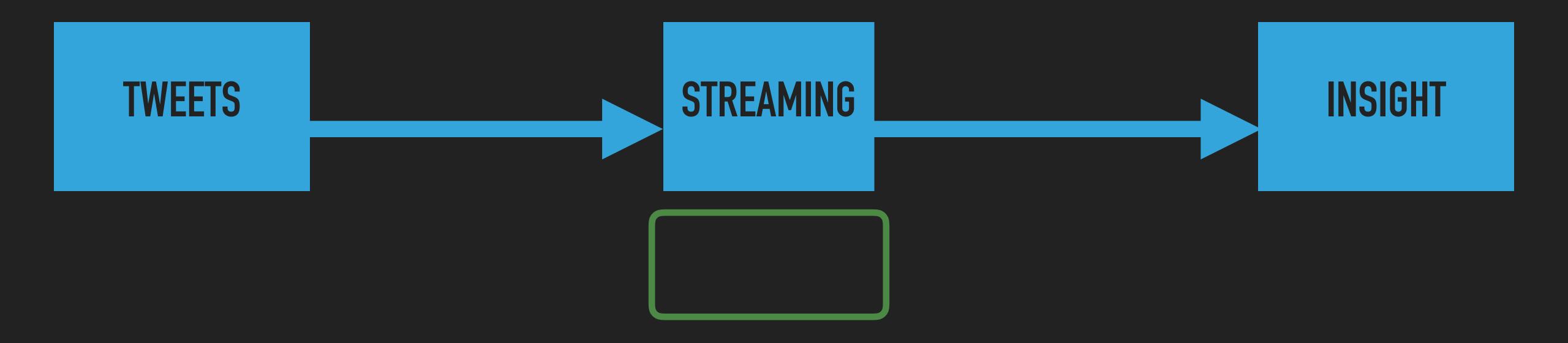


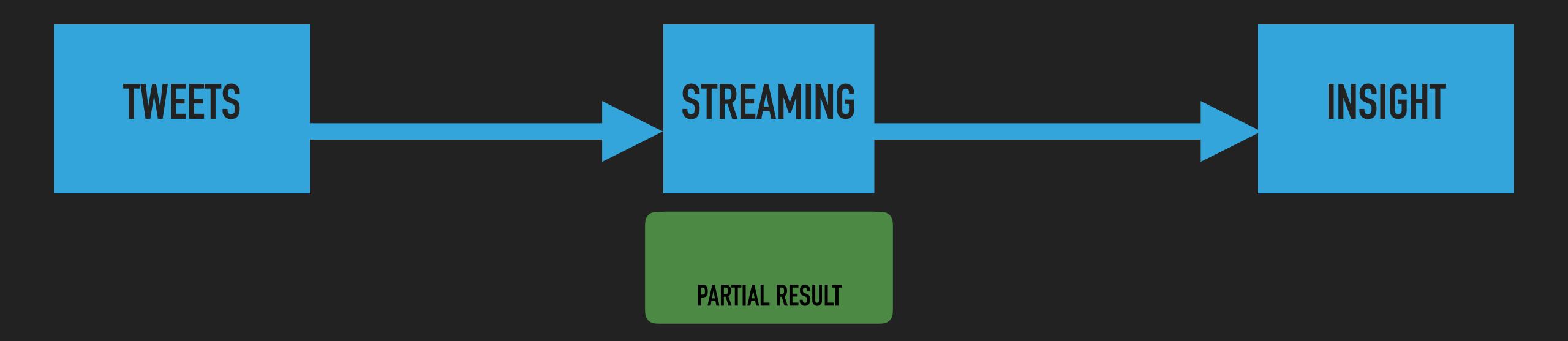


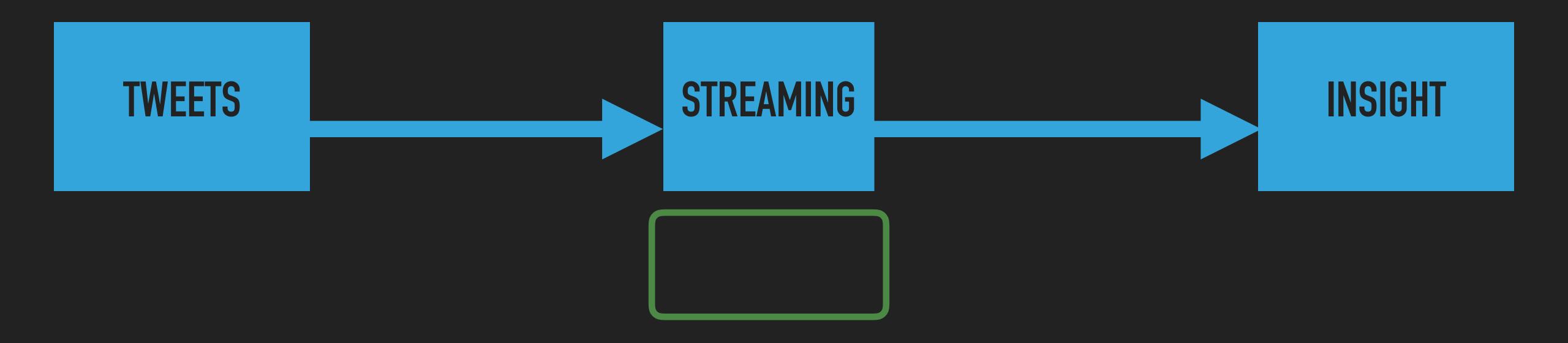




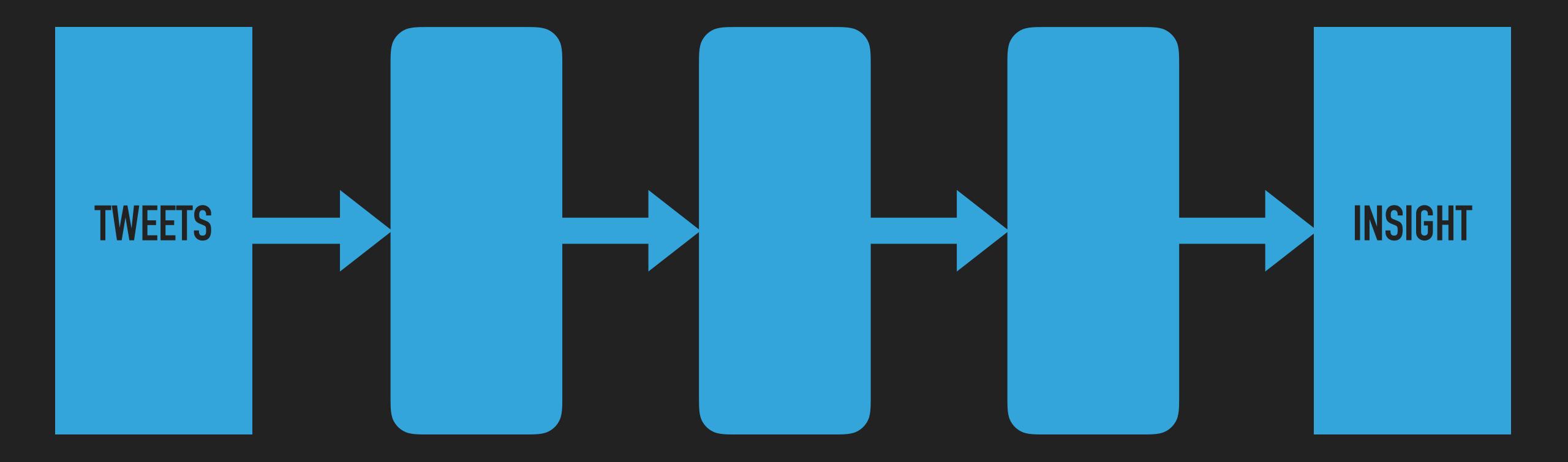


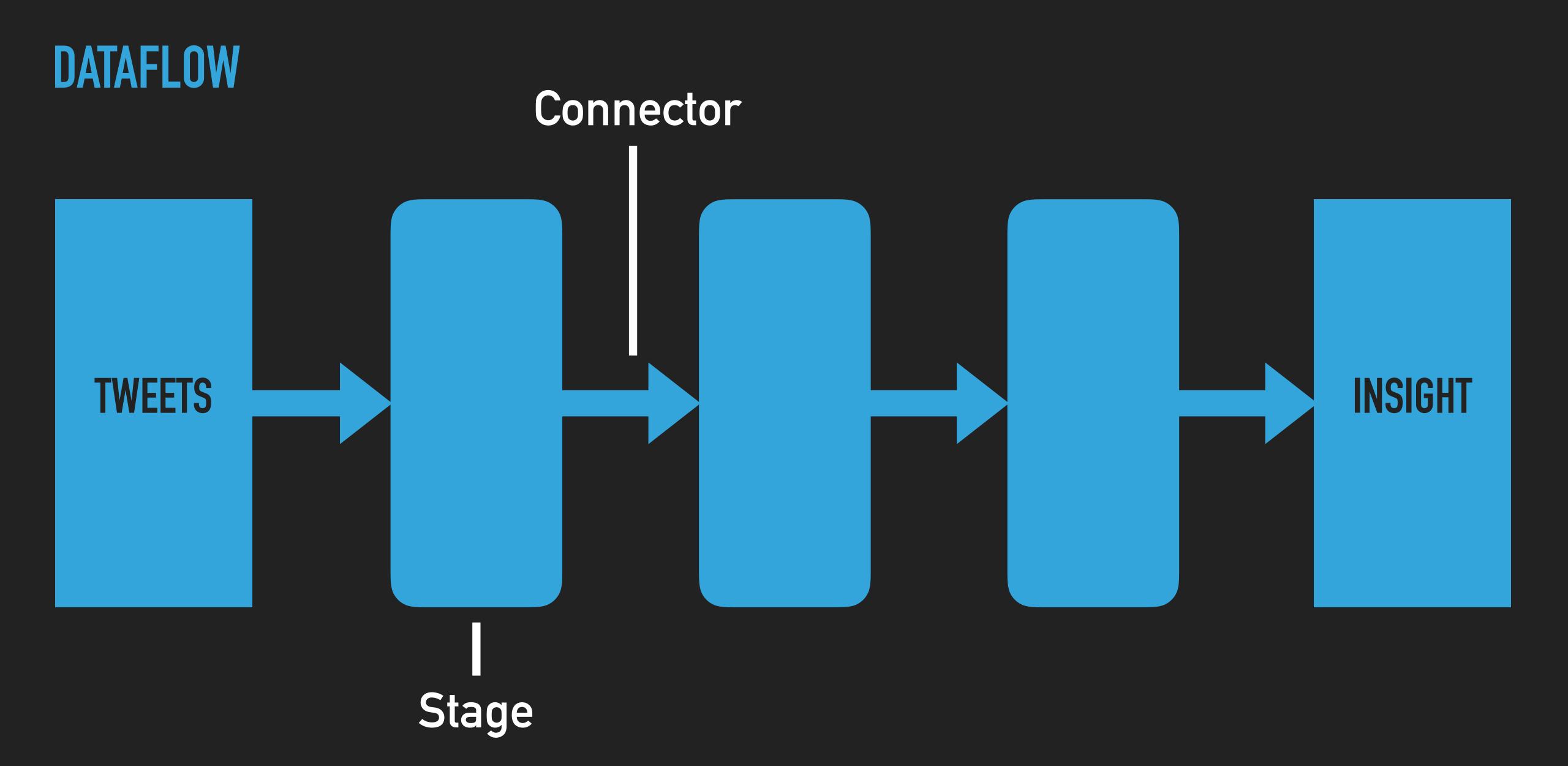




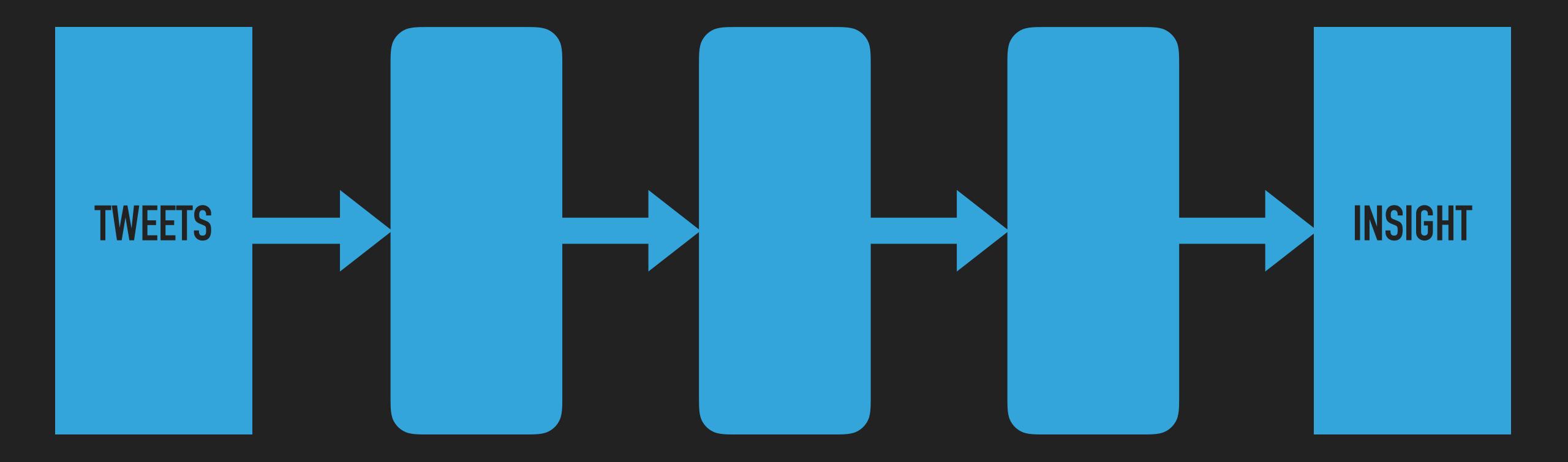


DATAFLOW

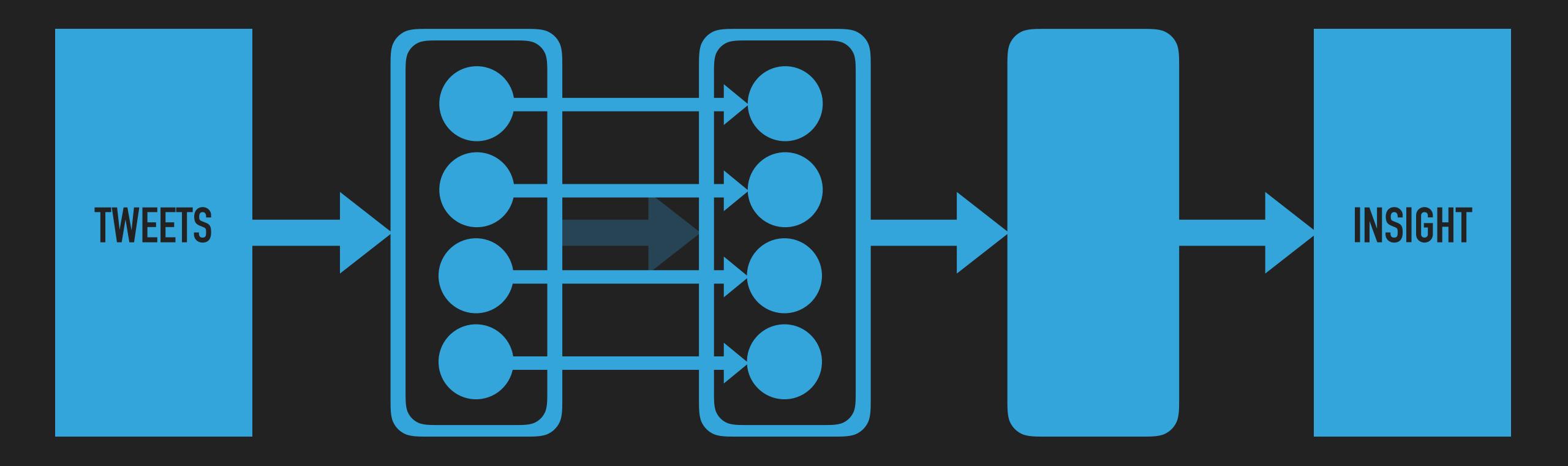




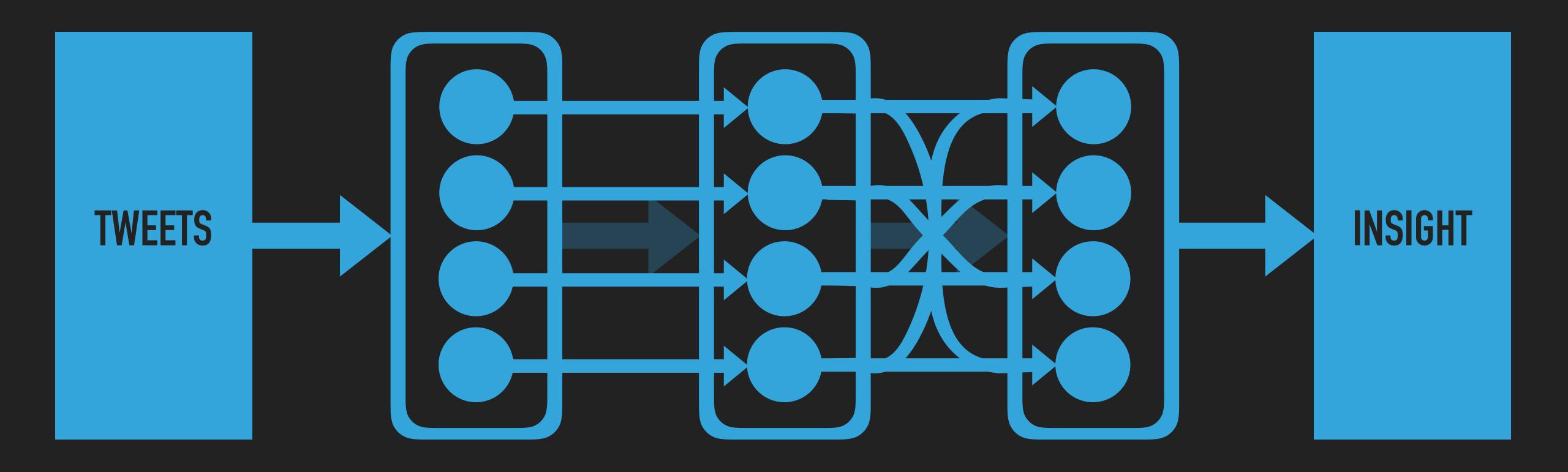
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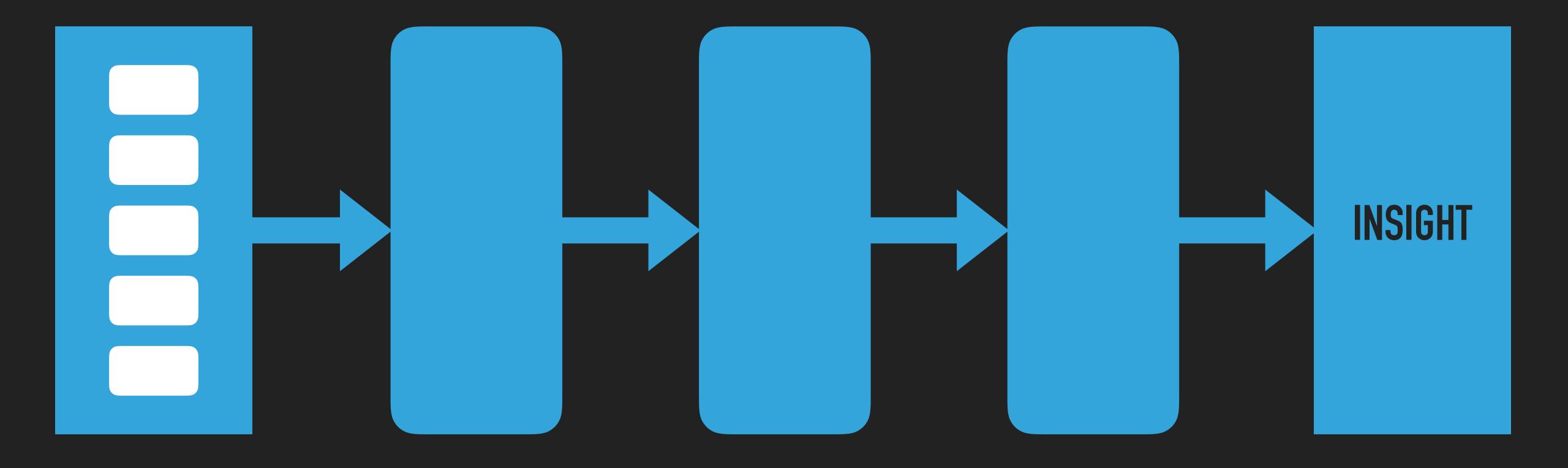


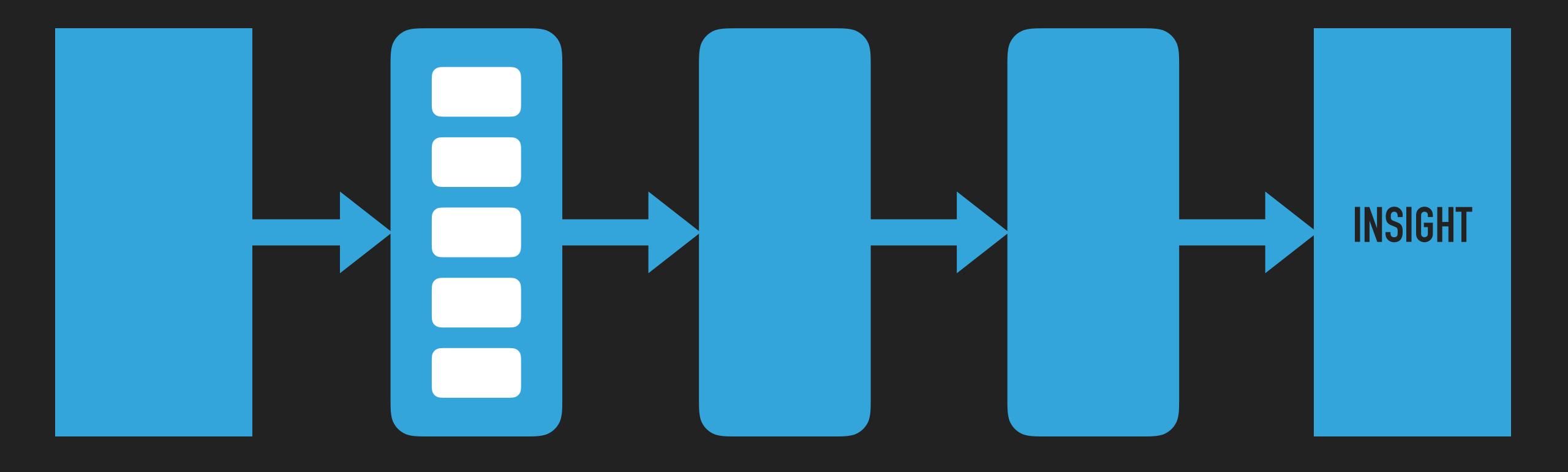
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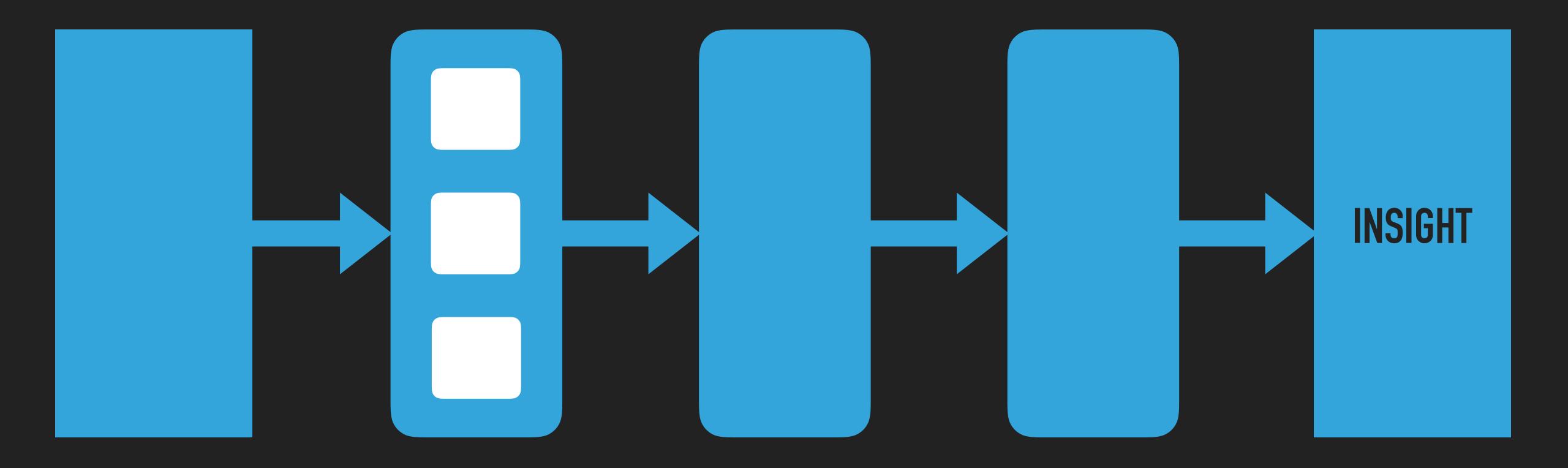


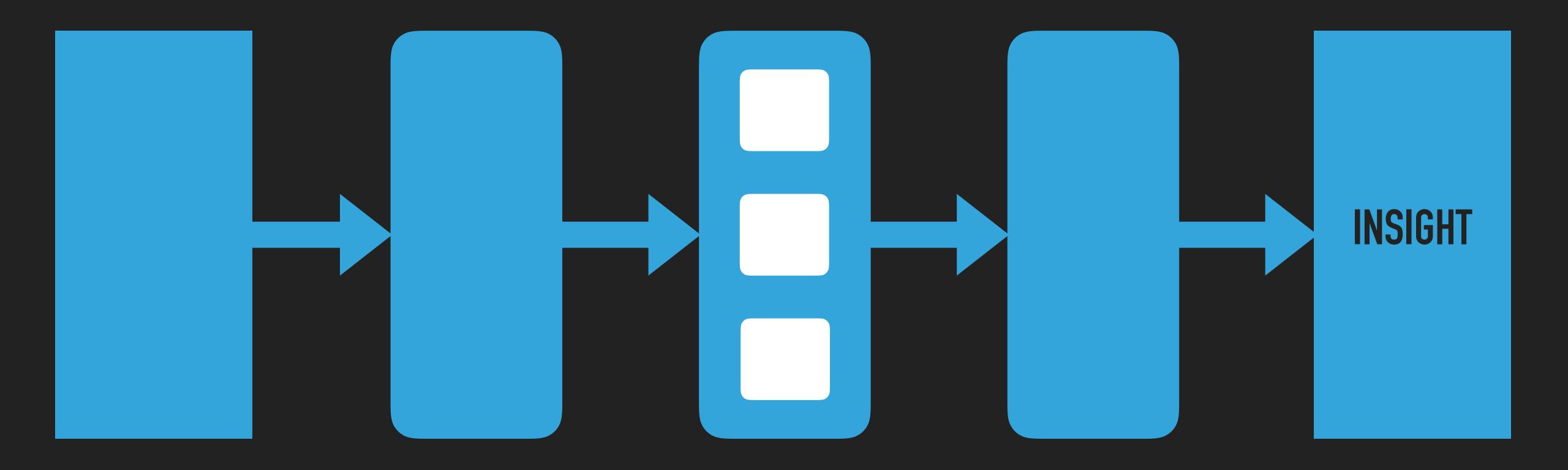
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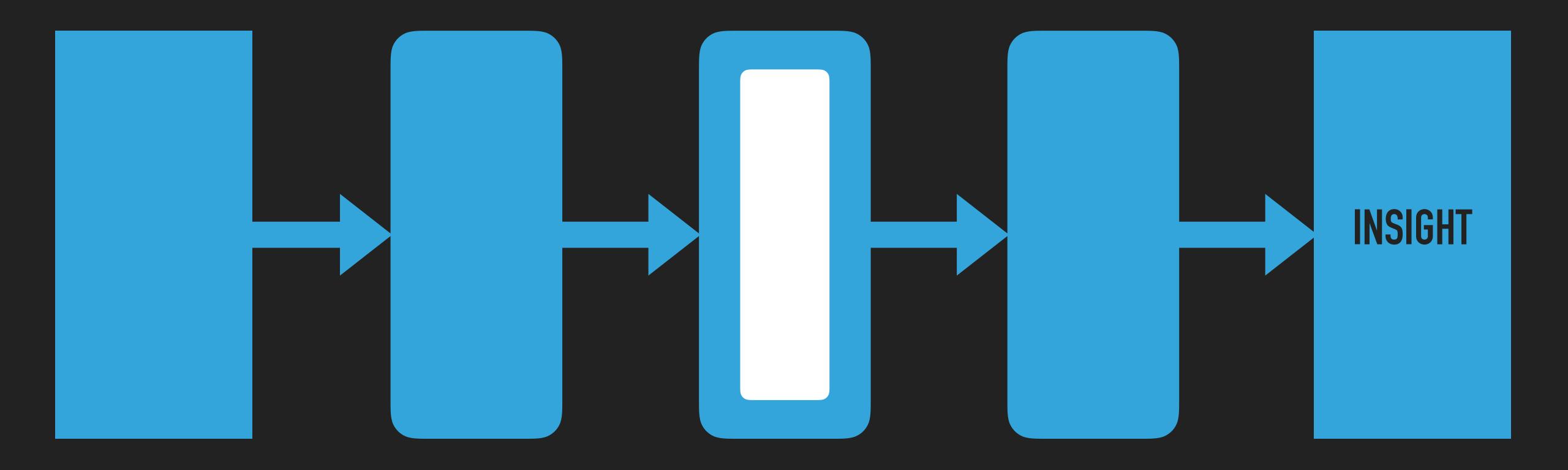


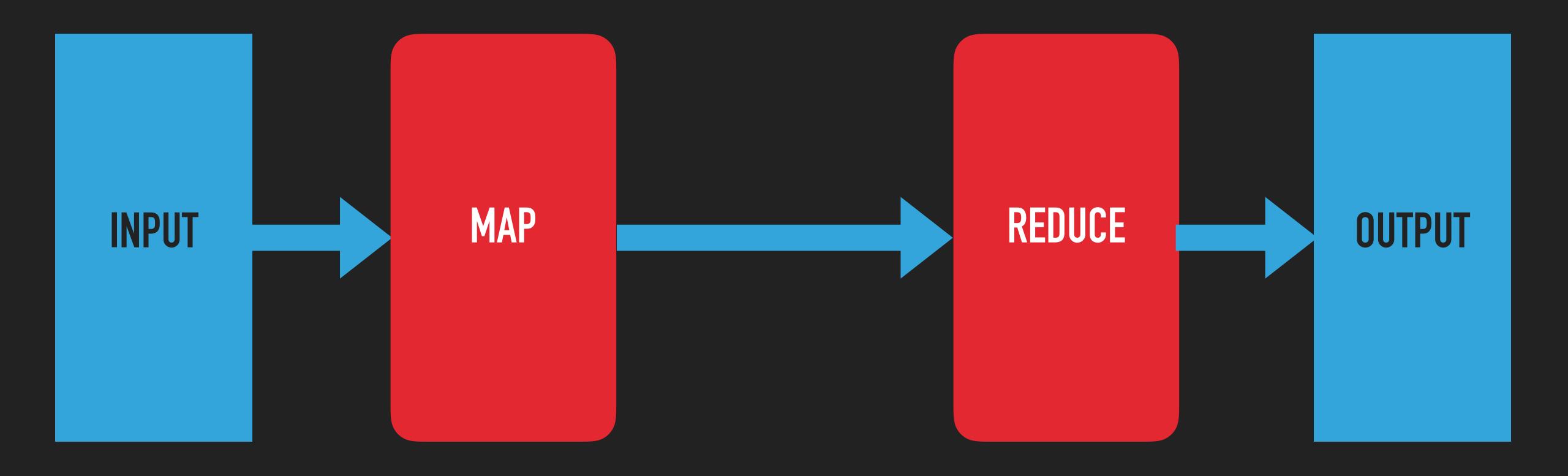


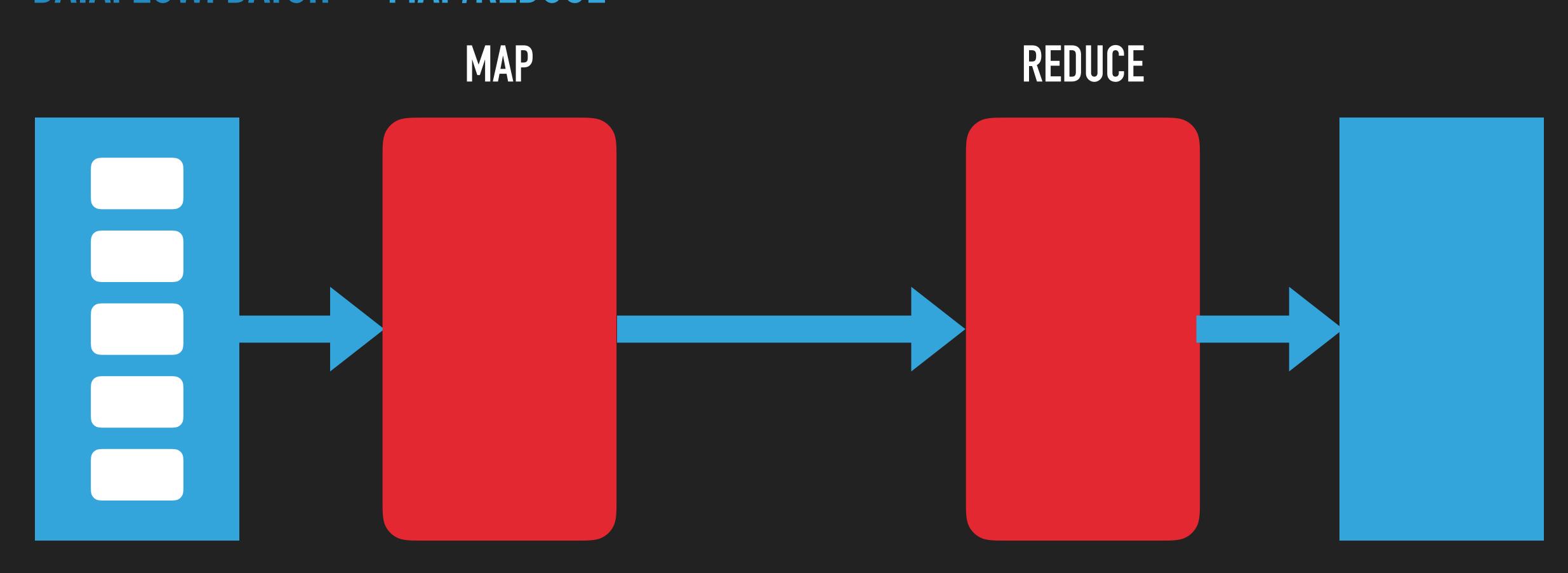


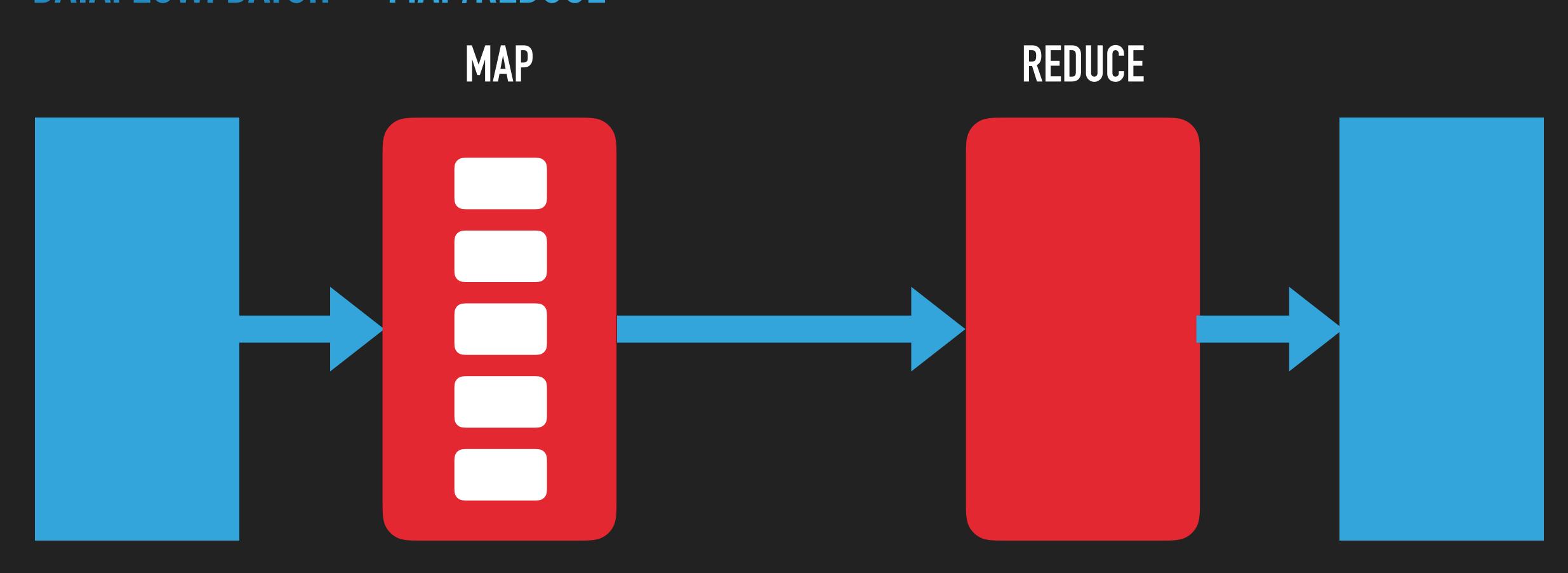


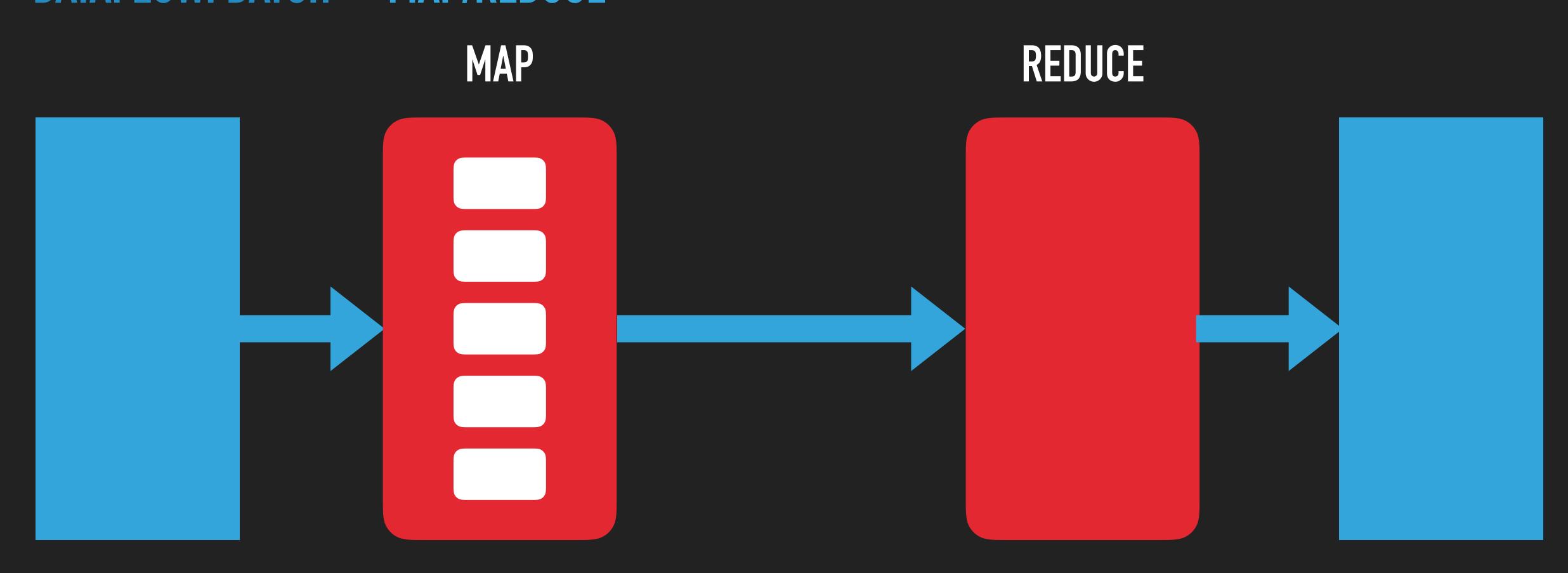


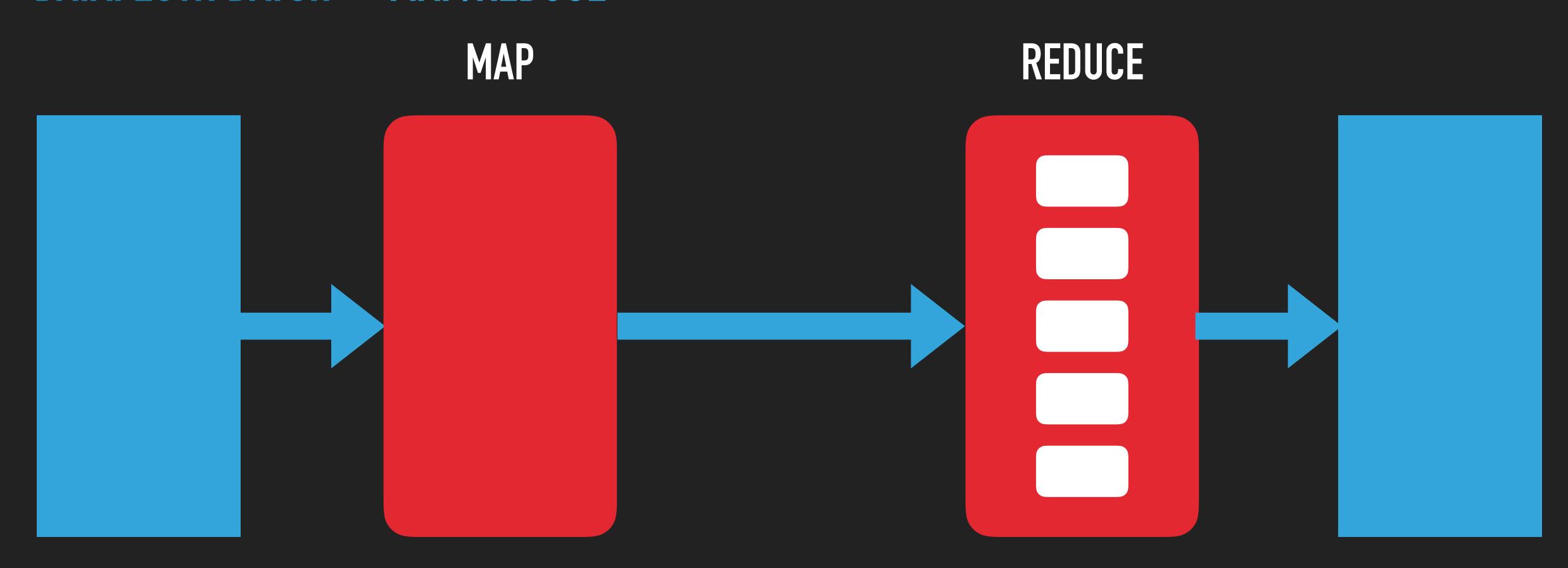


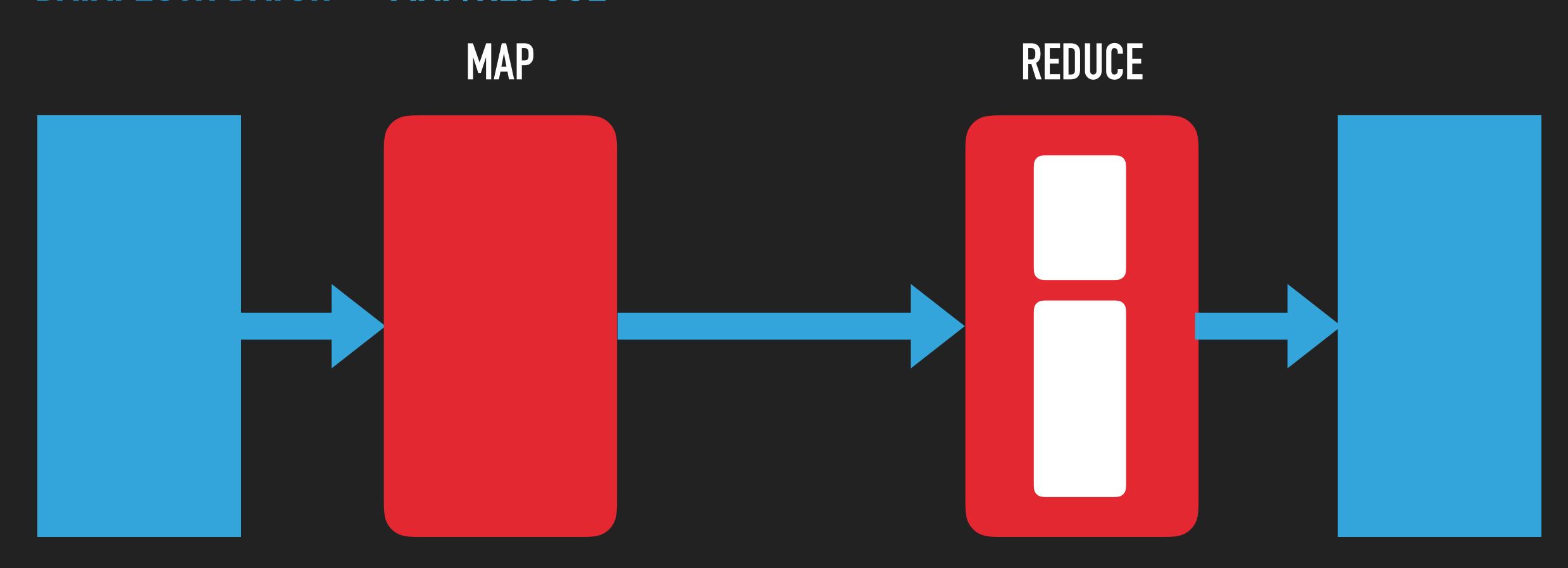


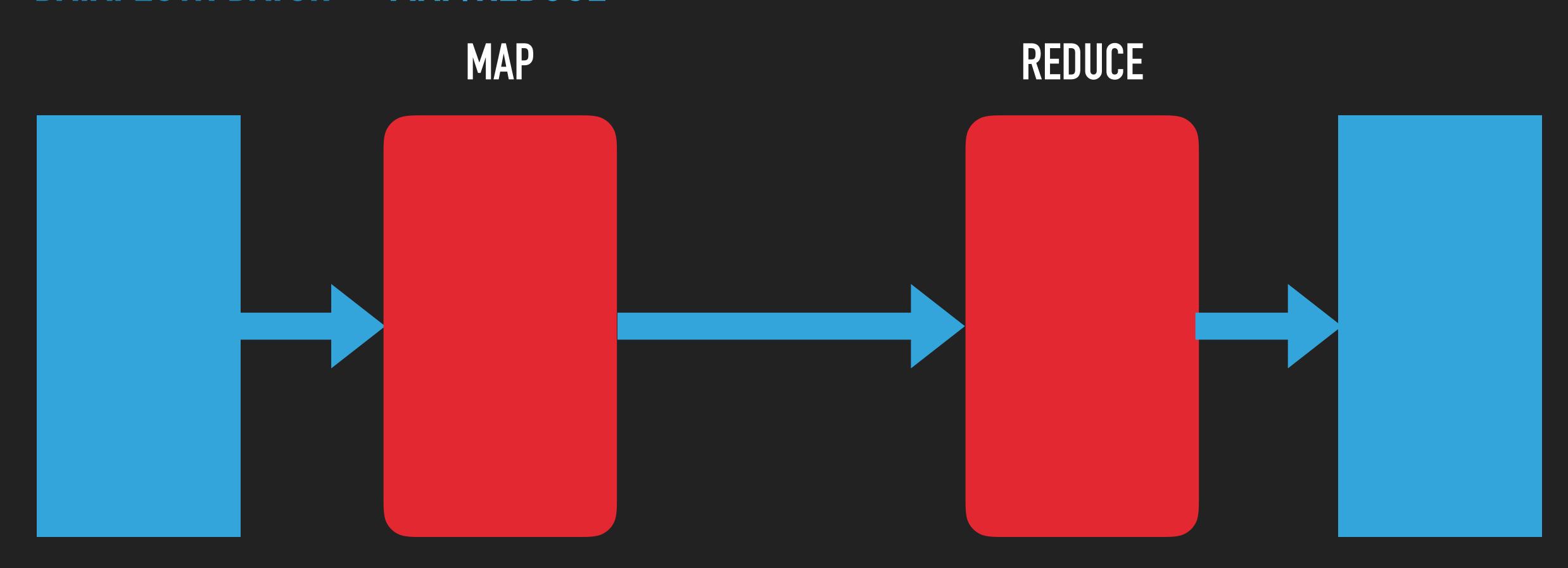


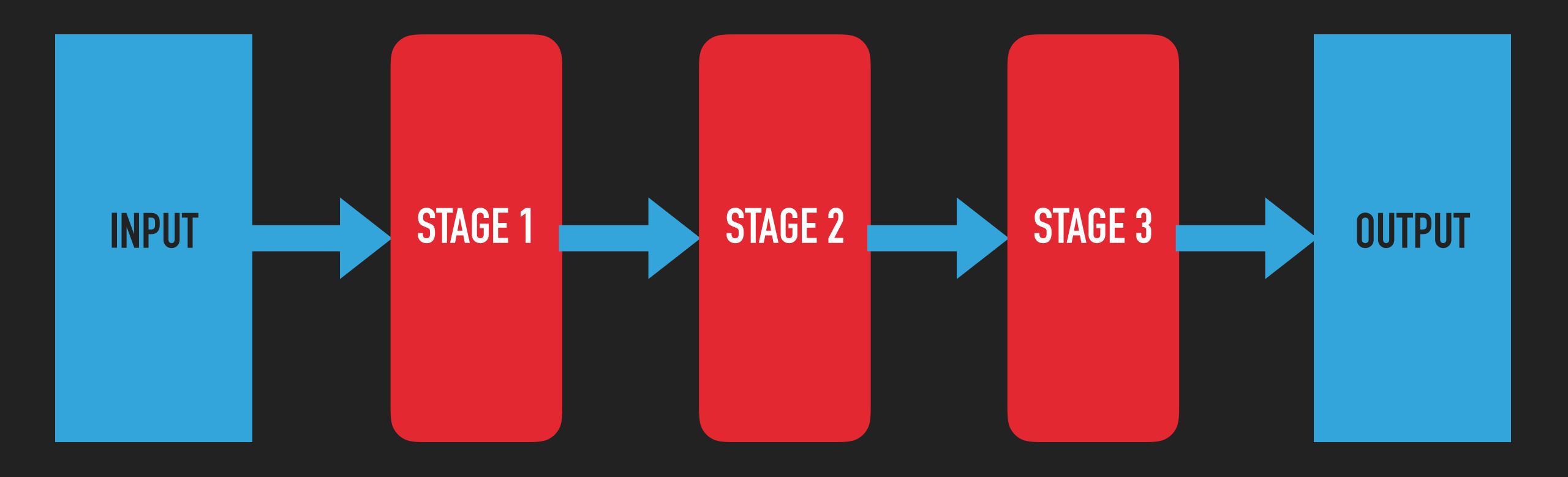


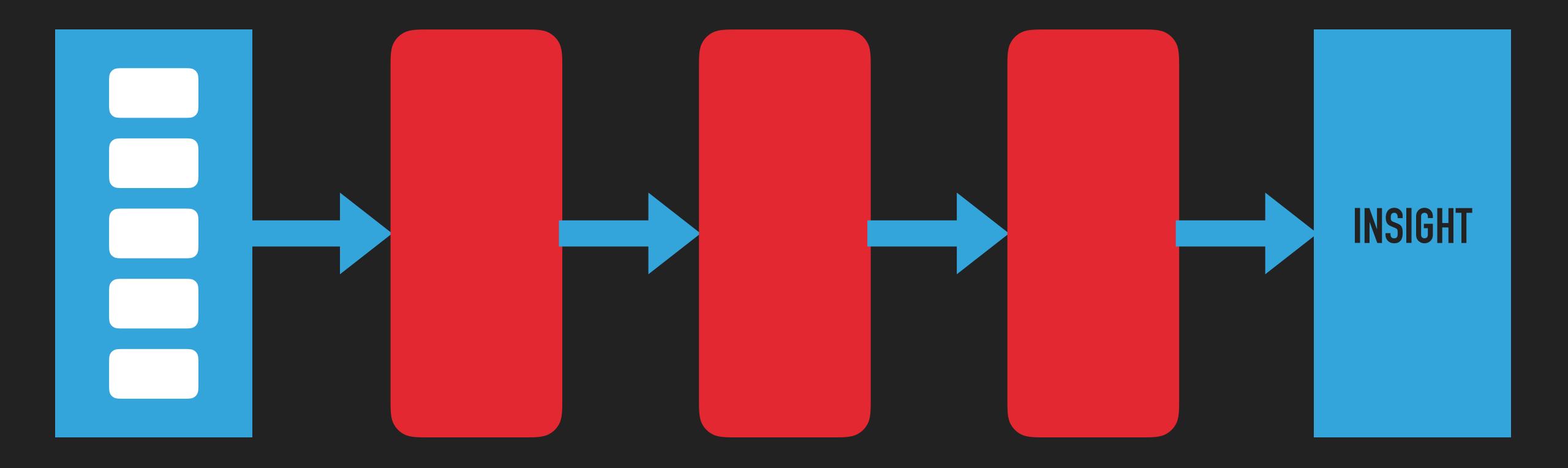


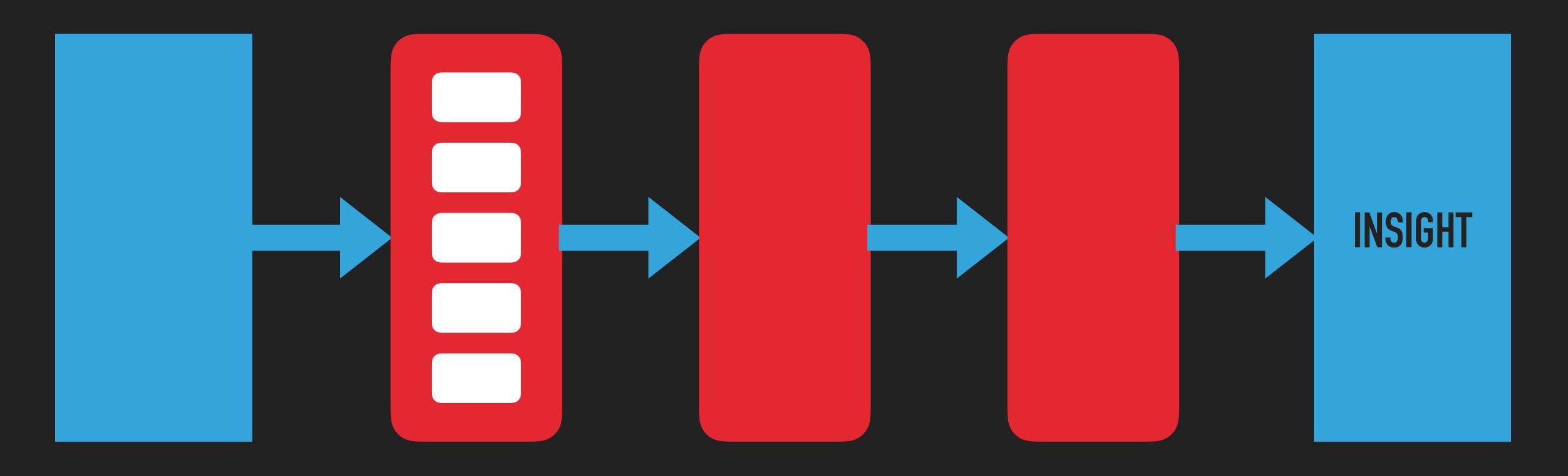


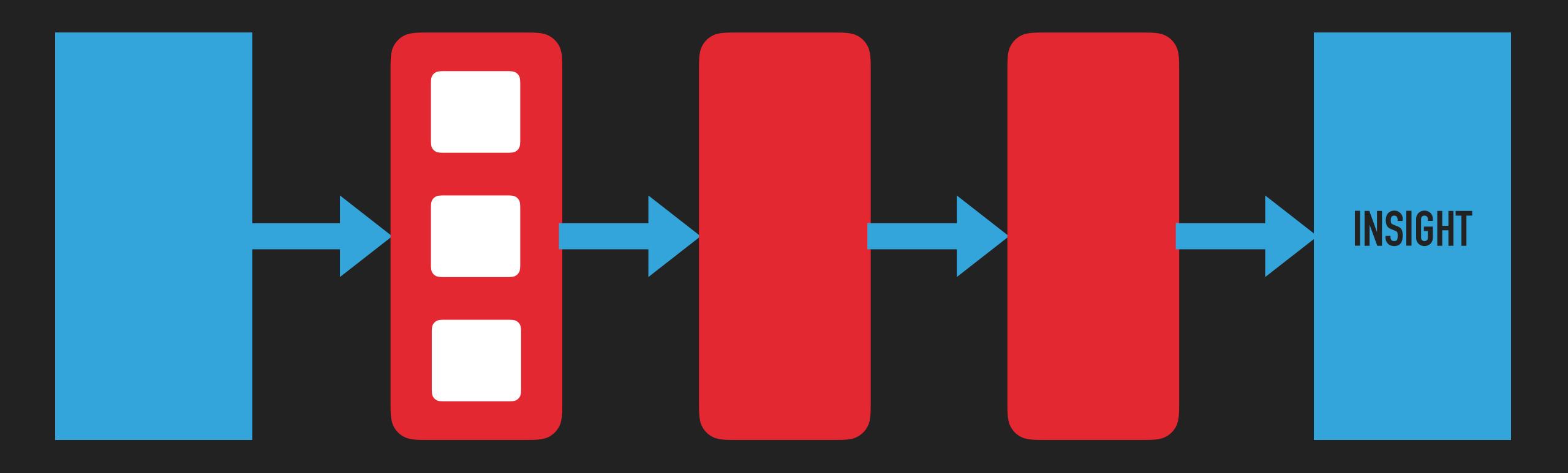


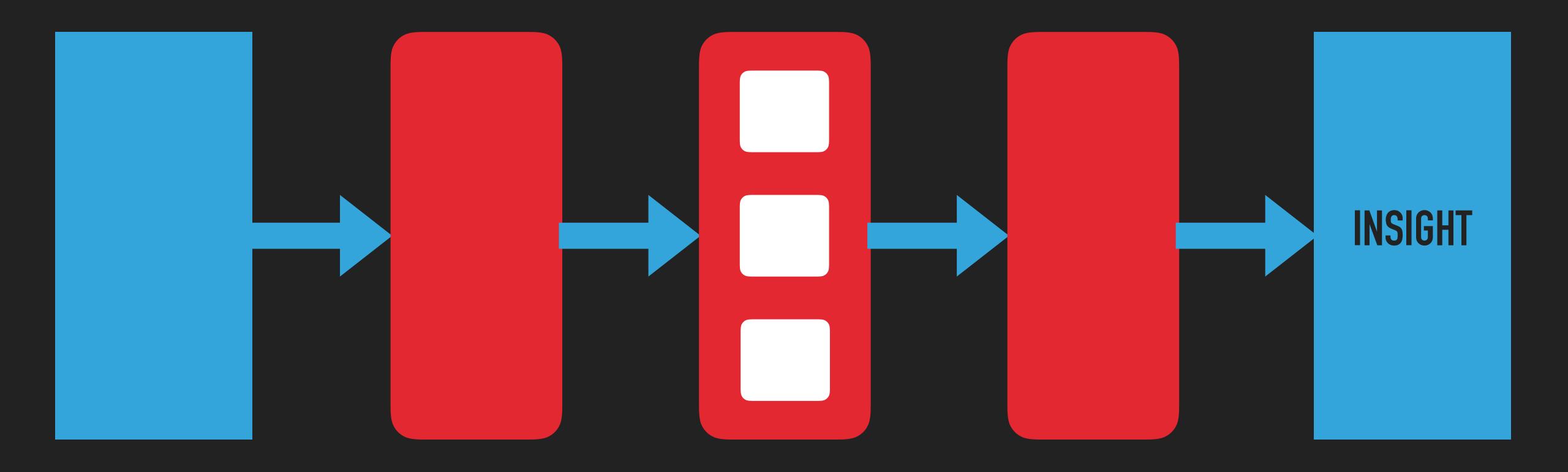


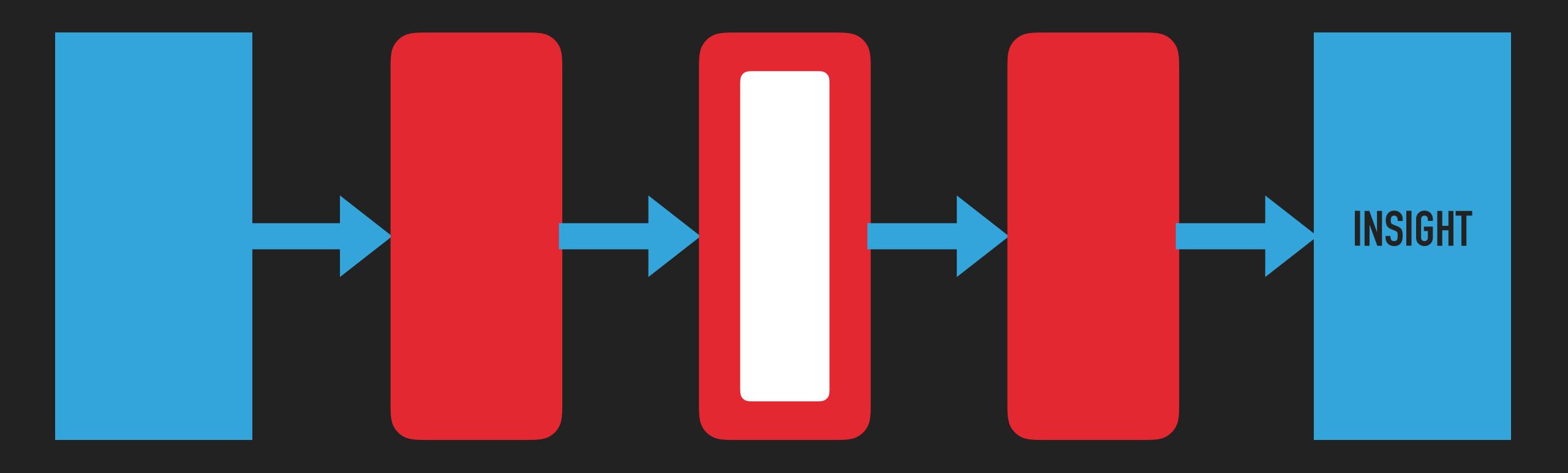


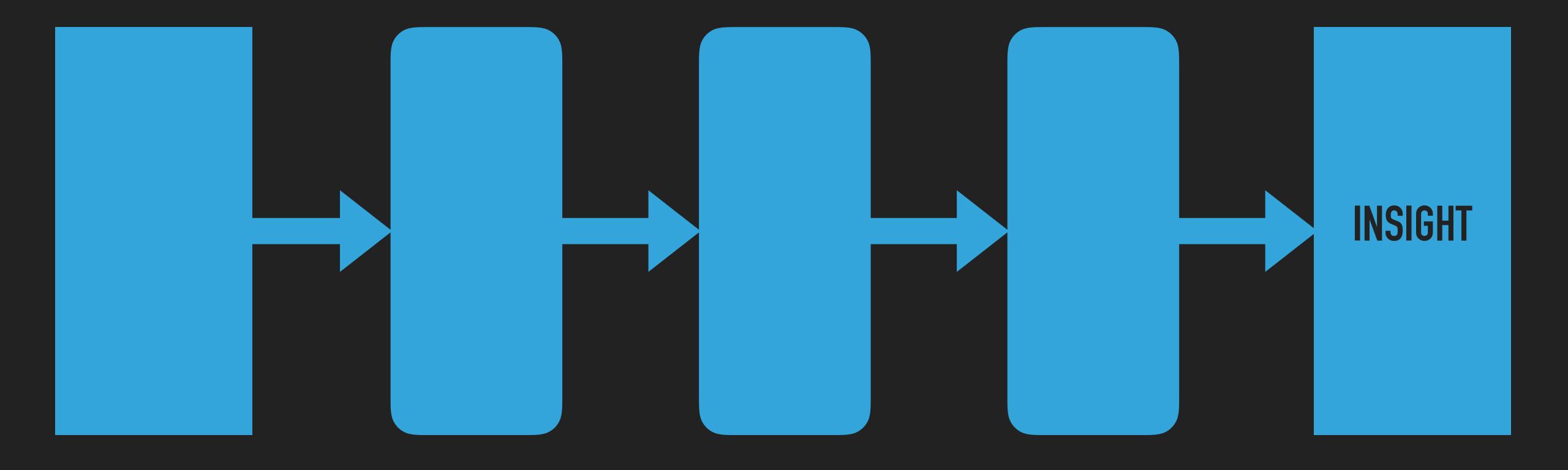


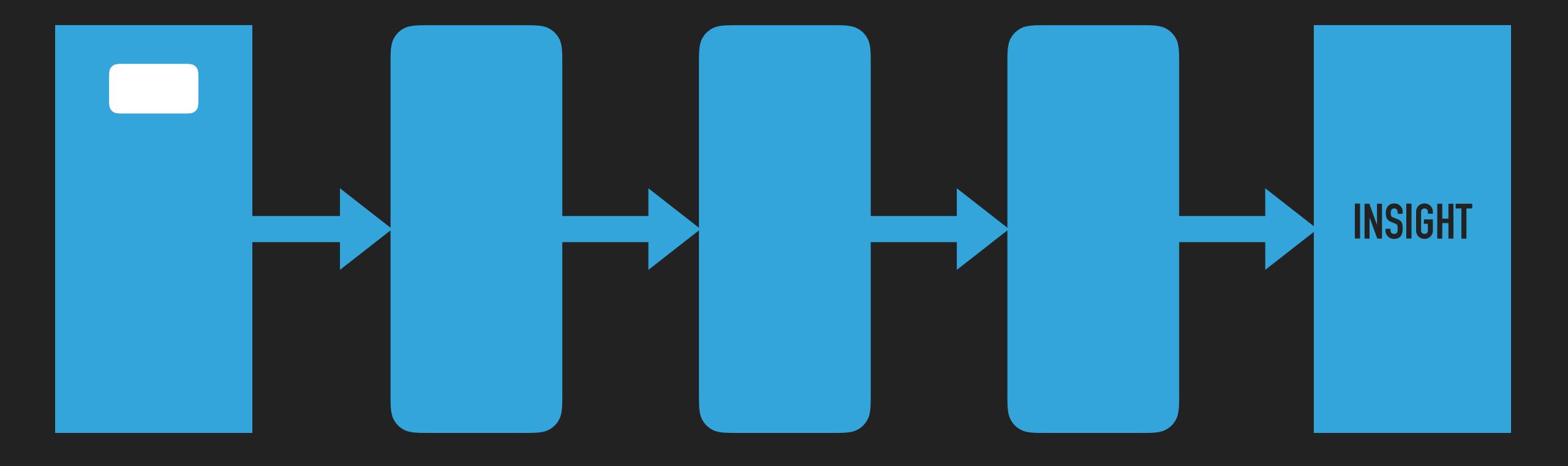


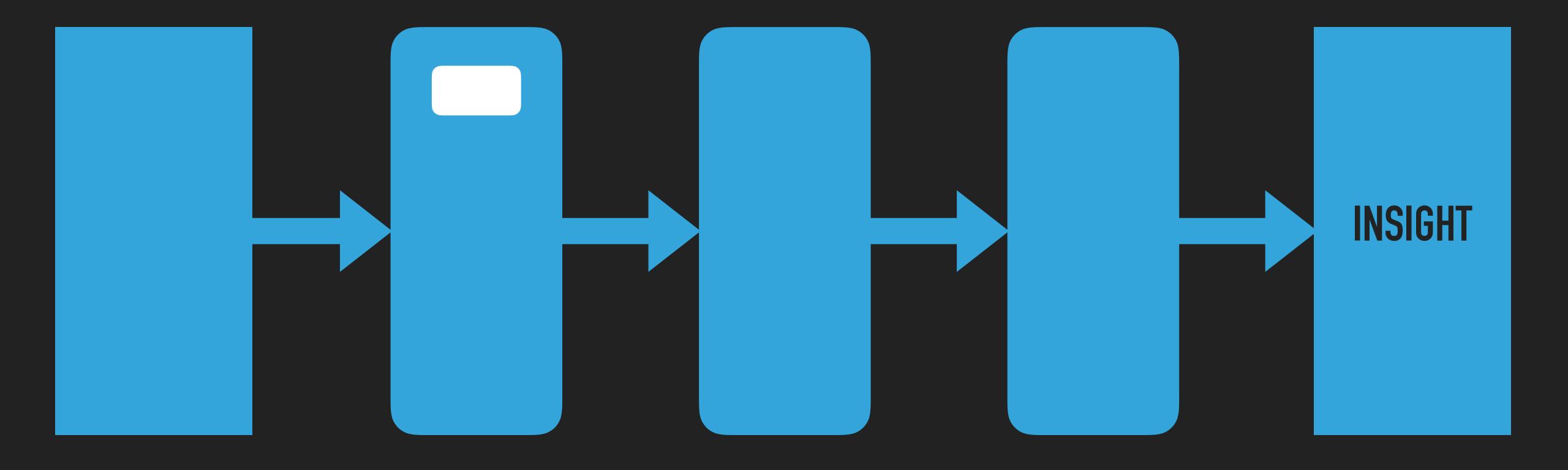


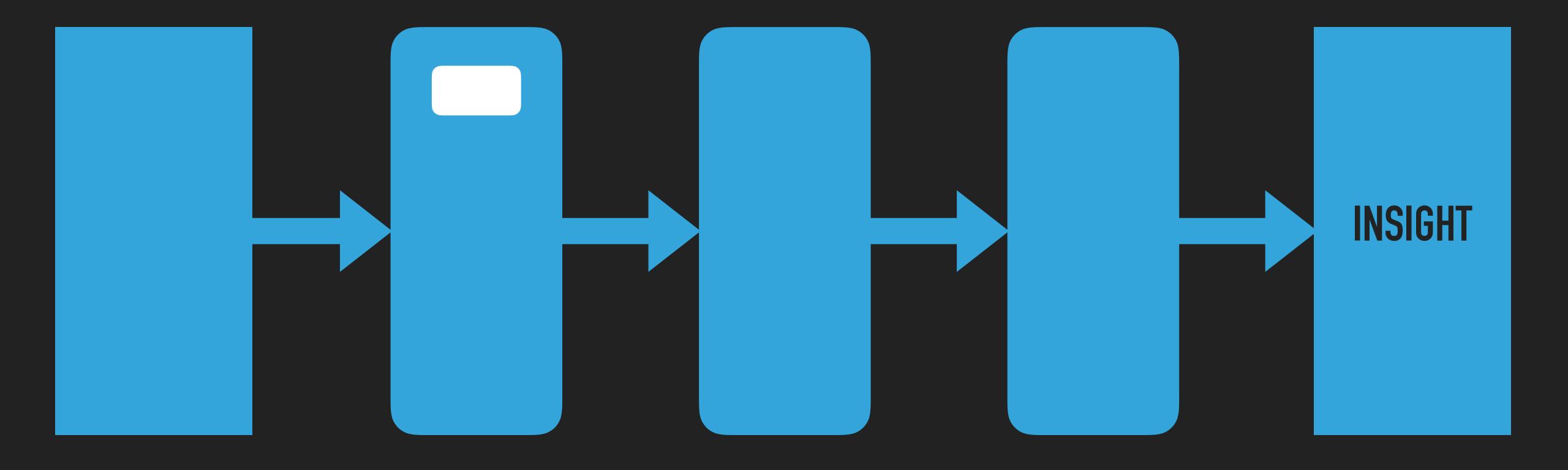


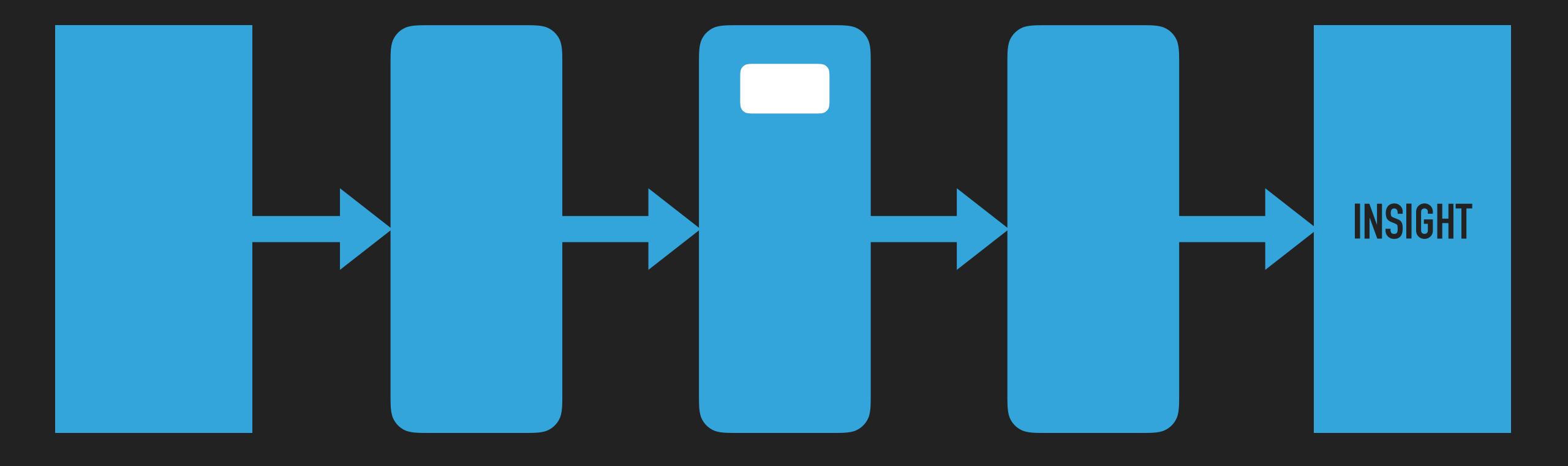


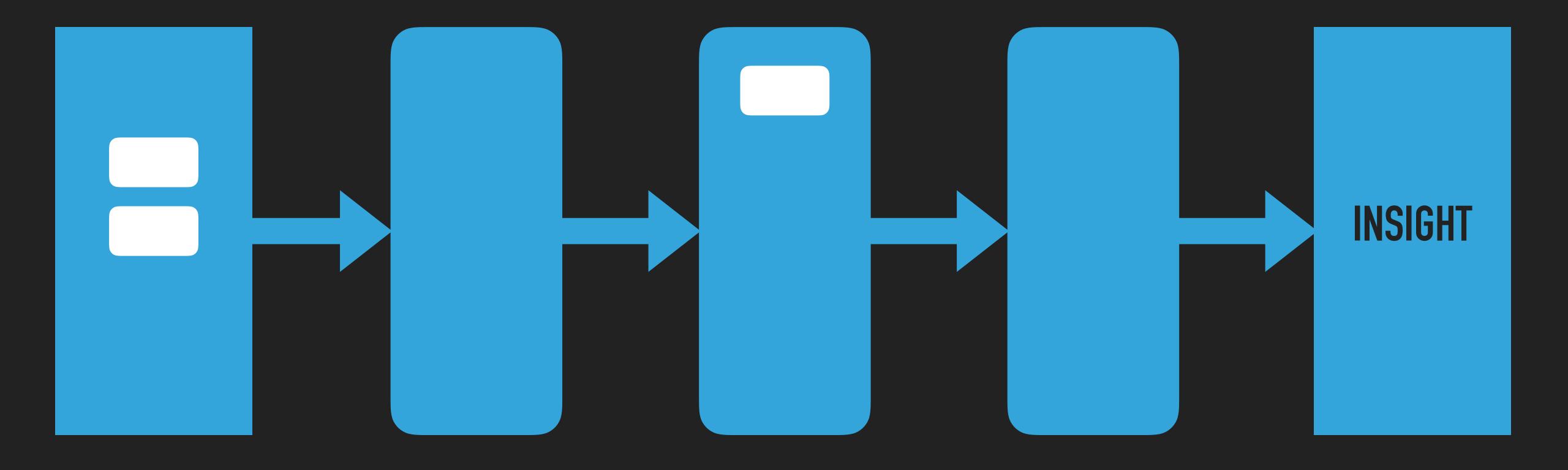


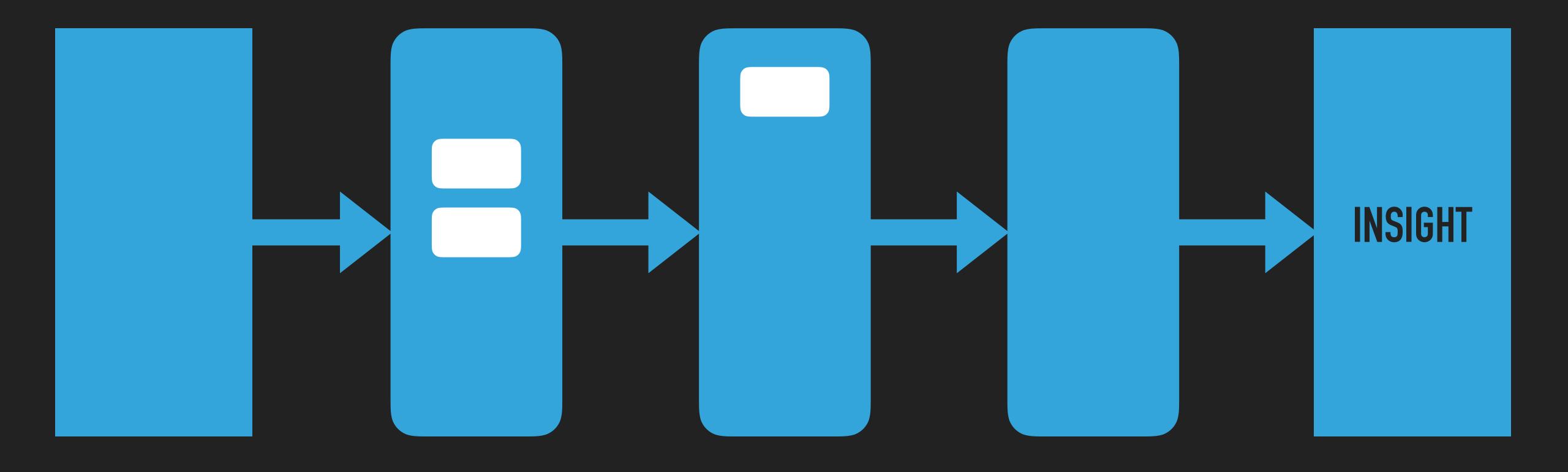


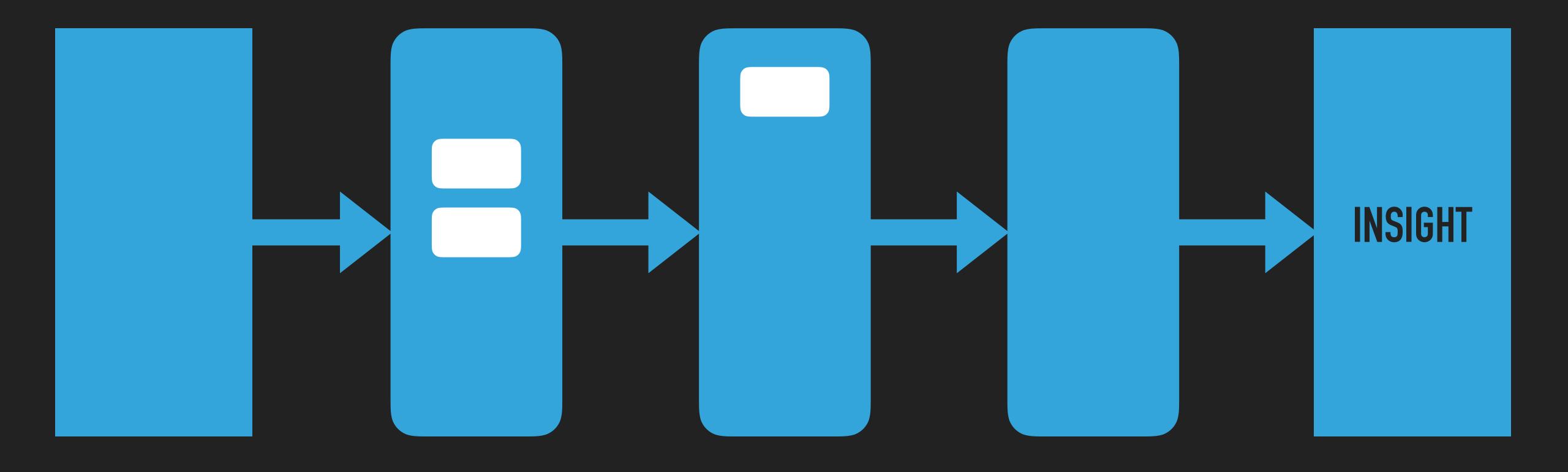


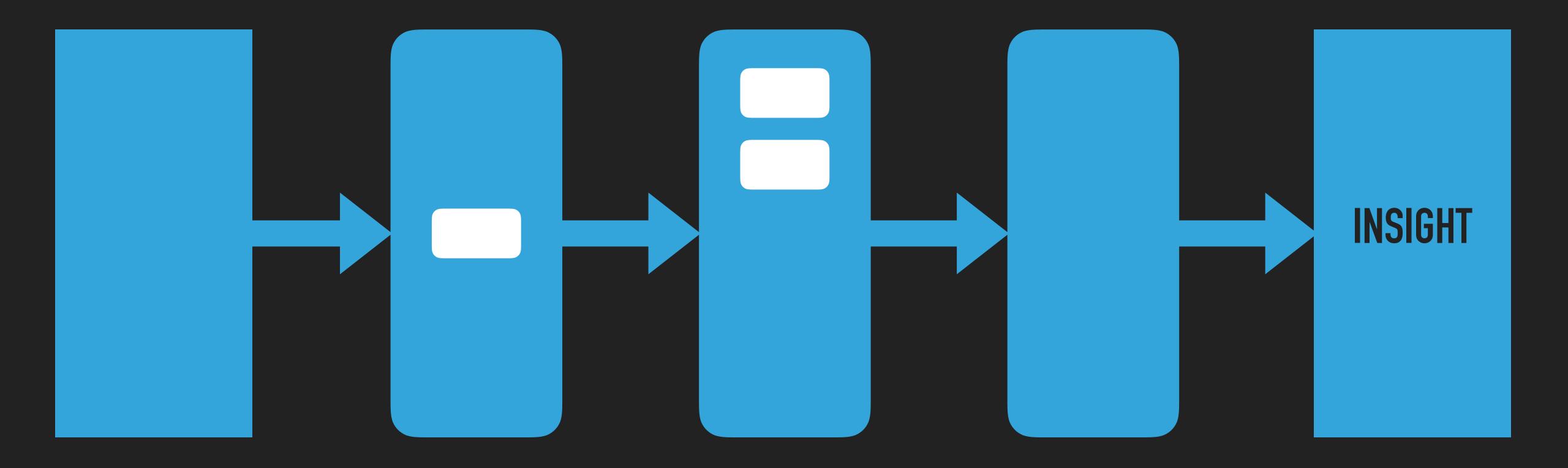


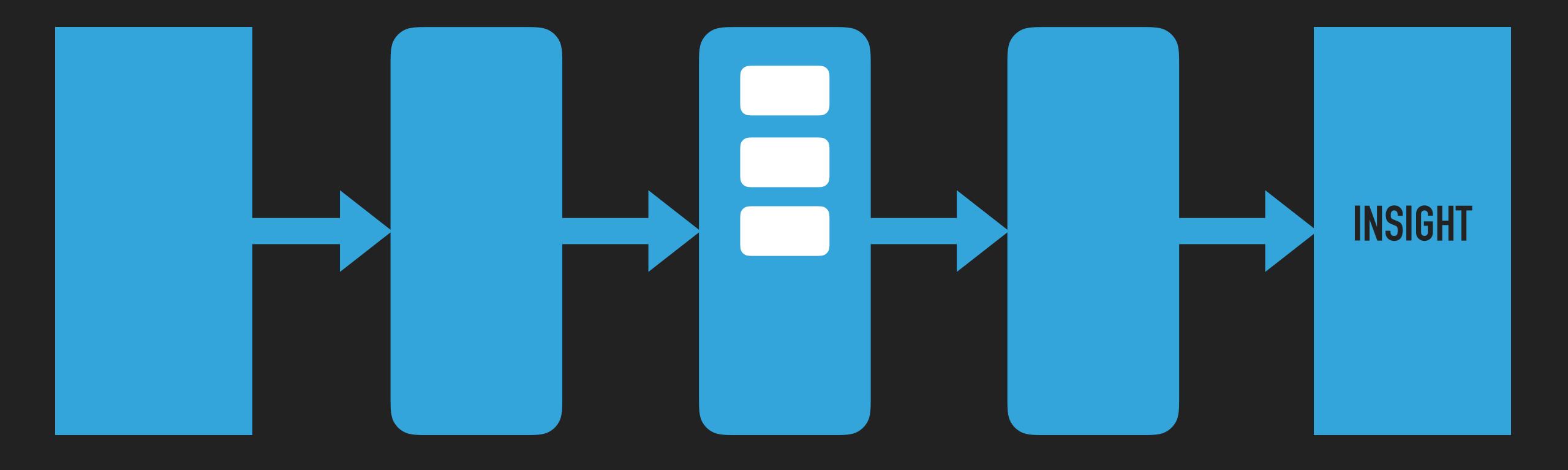


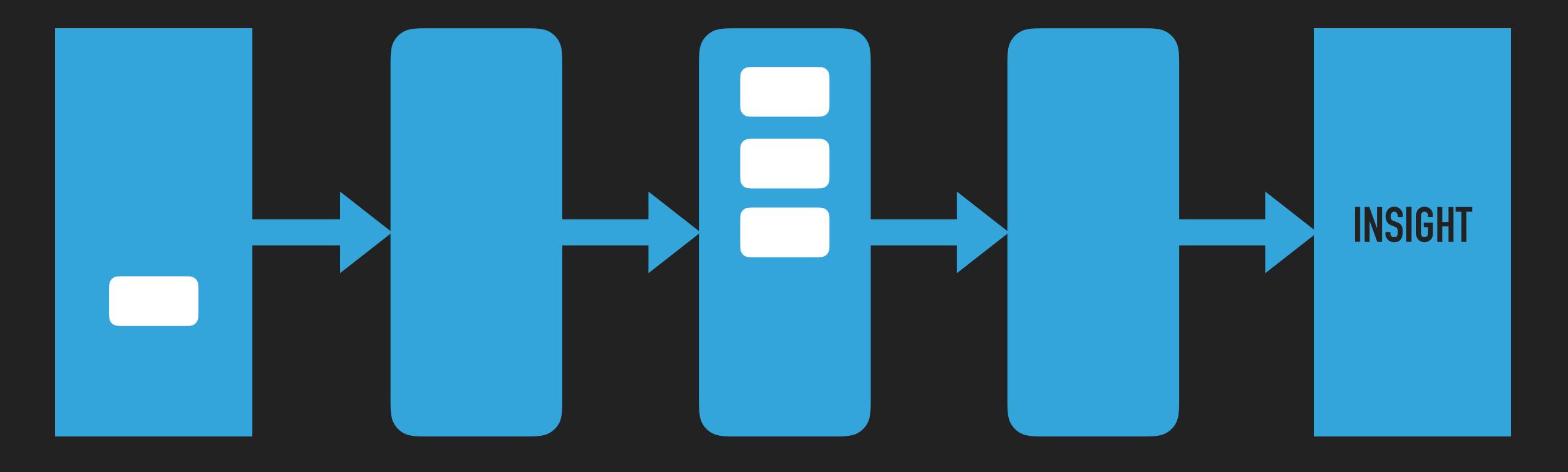


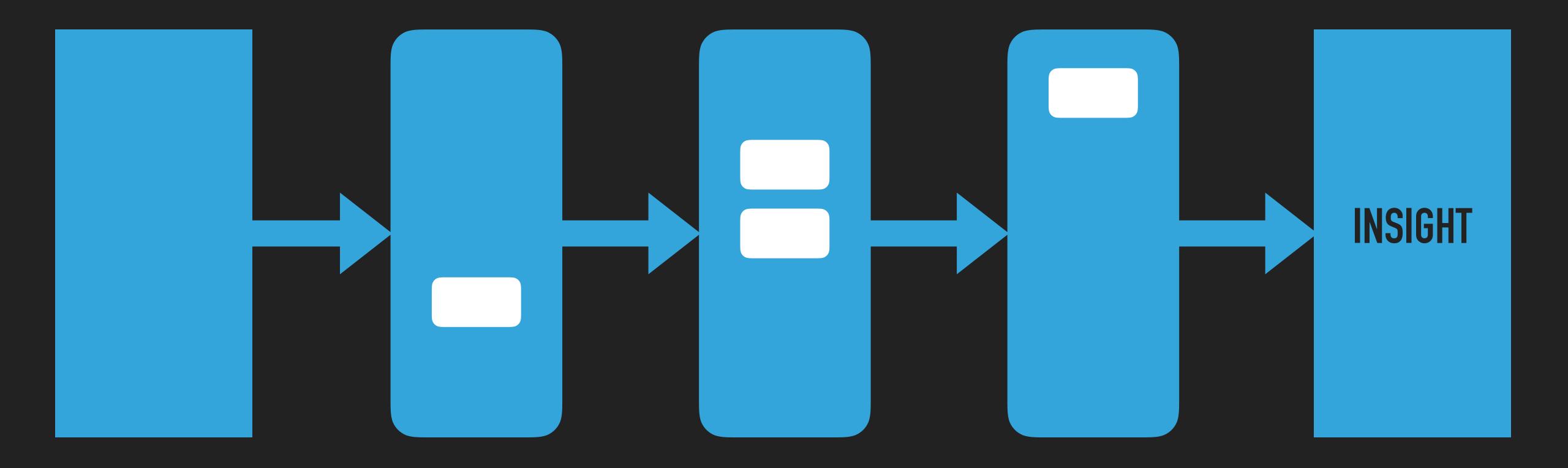


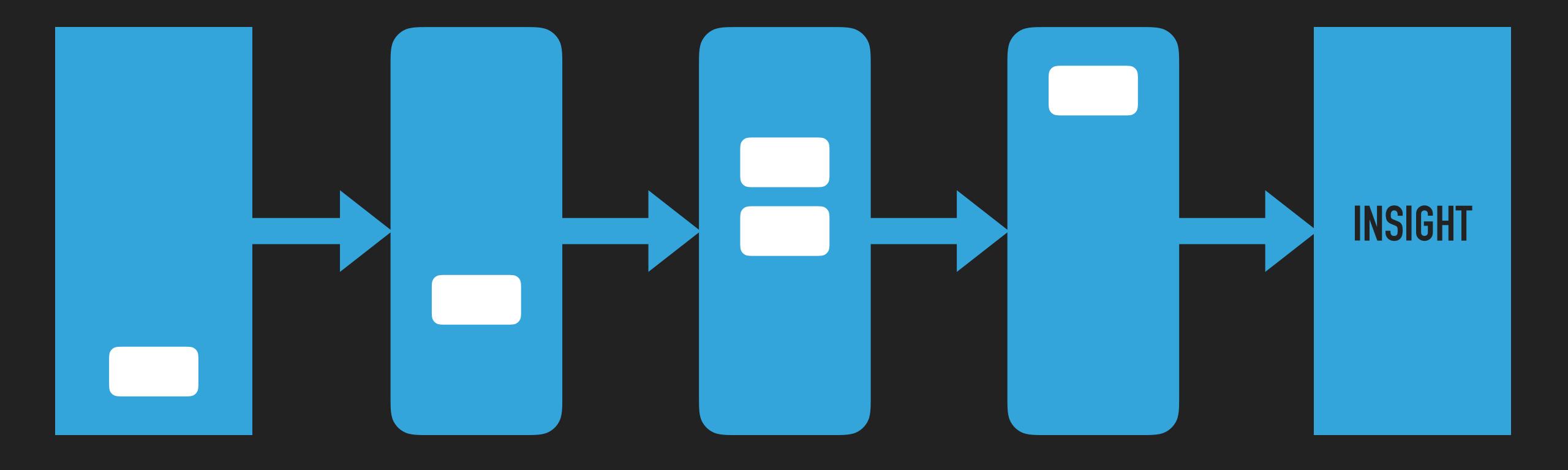






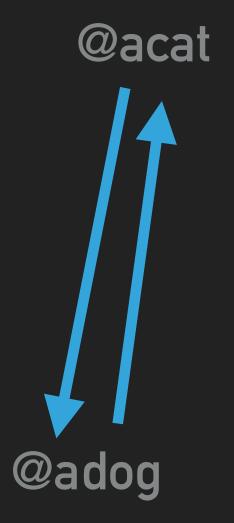






GRAPH





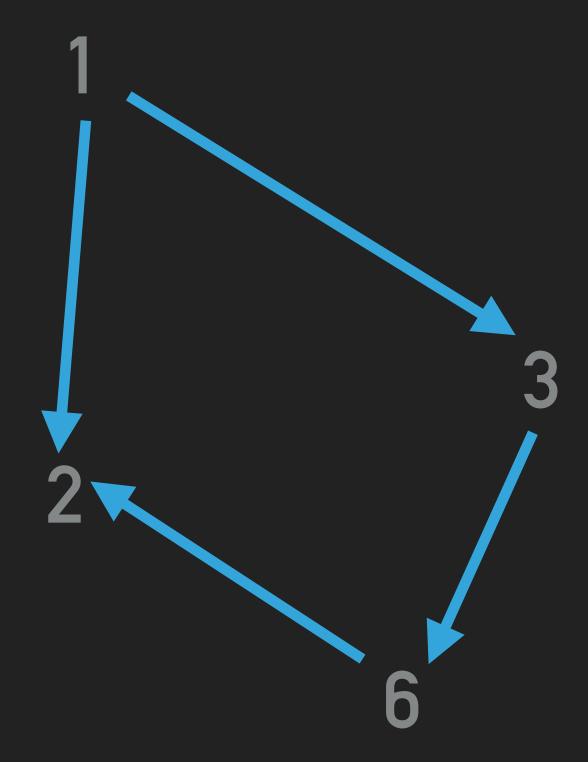
GRAPH





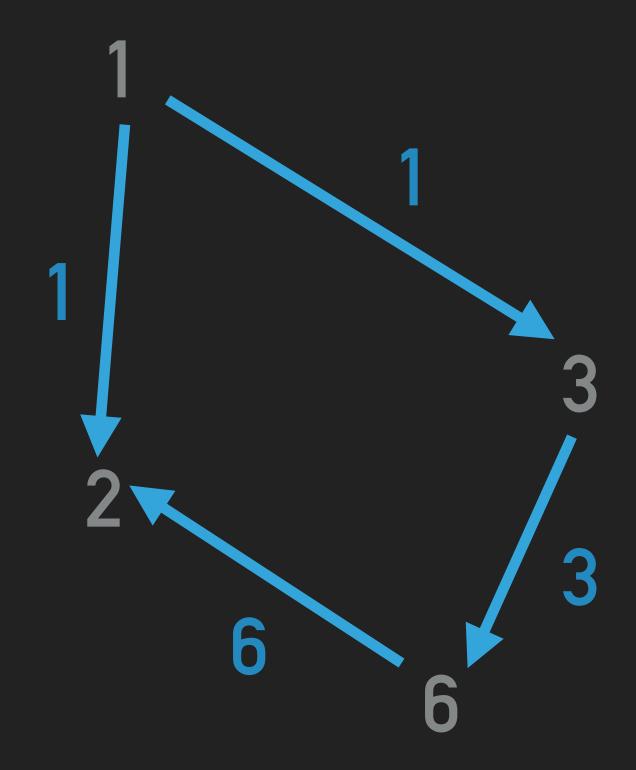
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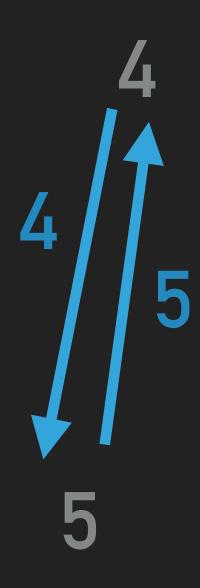
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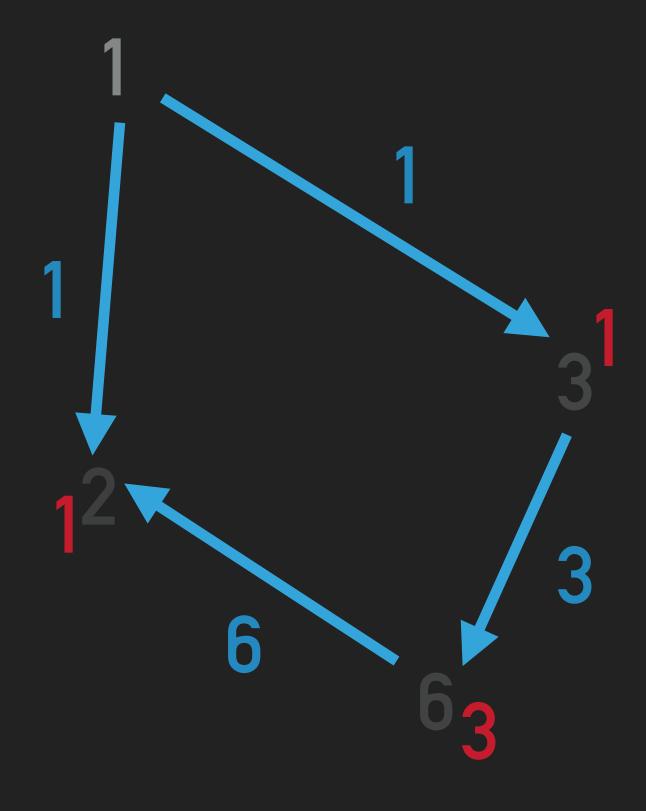


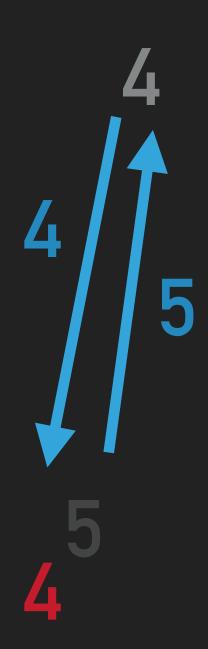
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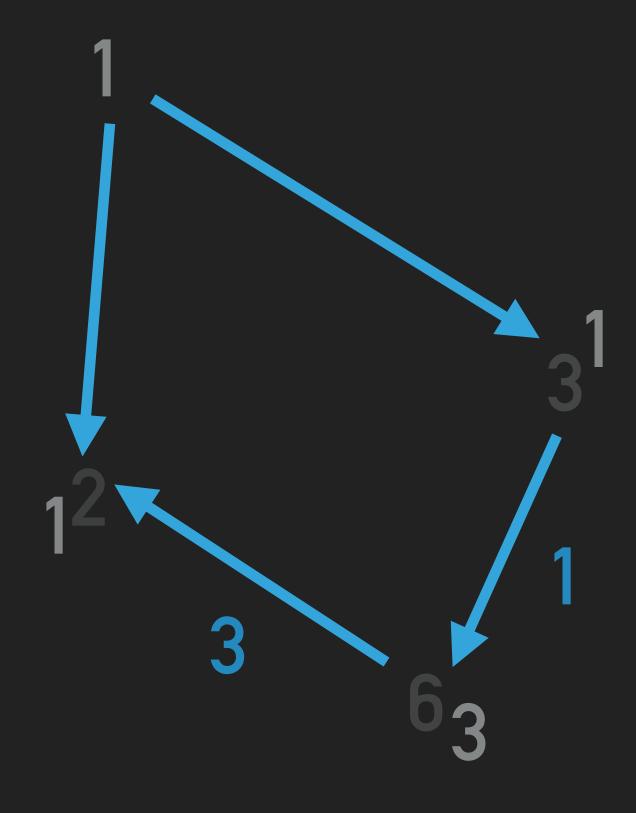


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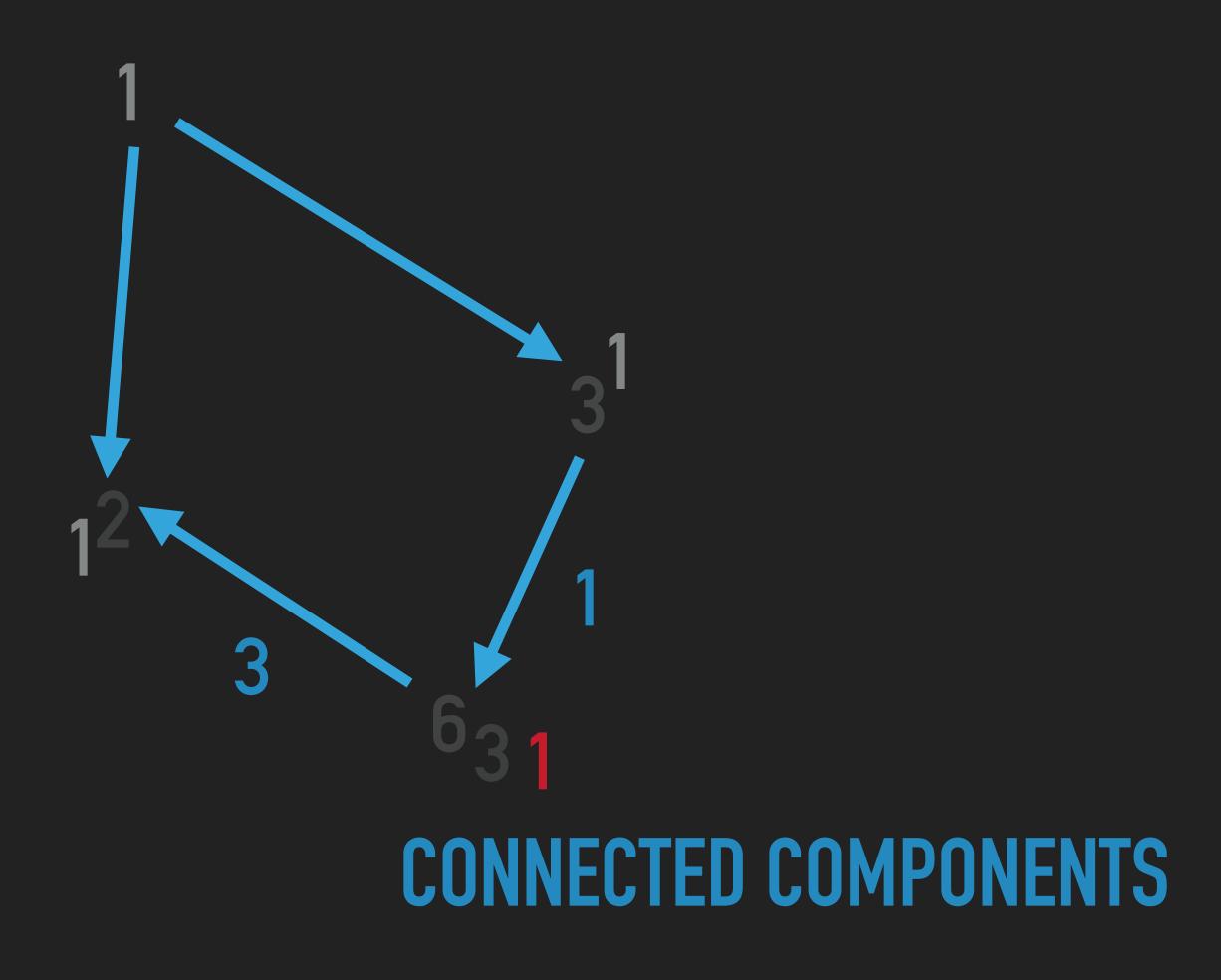


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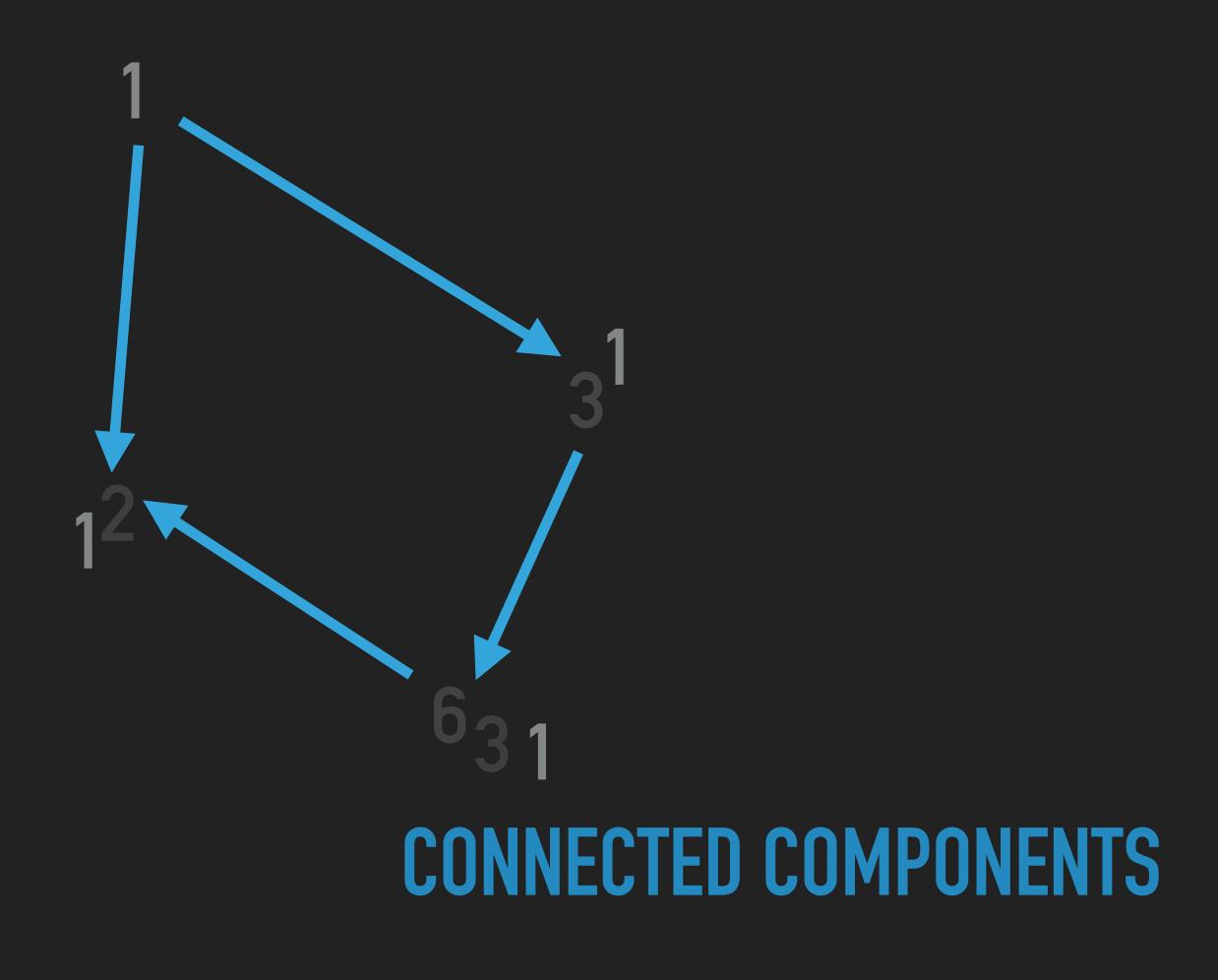




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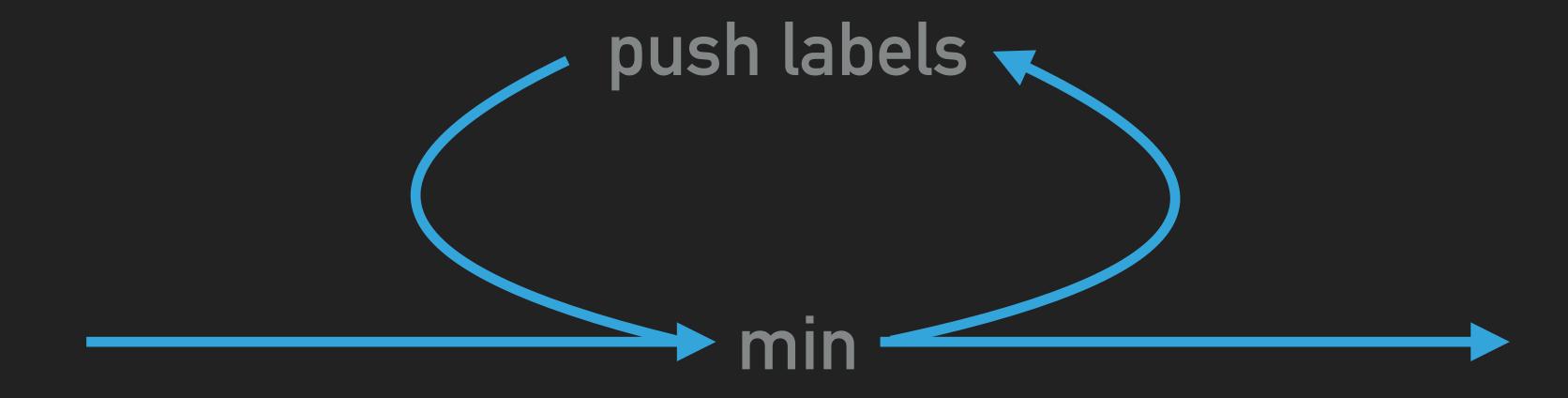








GRAPH PROCESSING IN DATAFLOW: CYCLES!

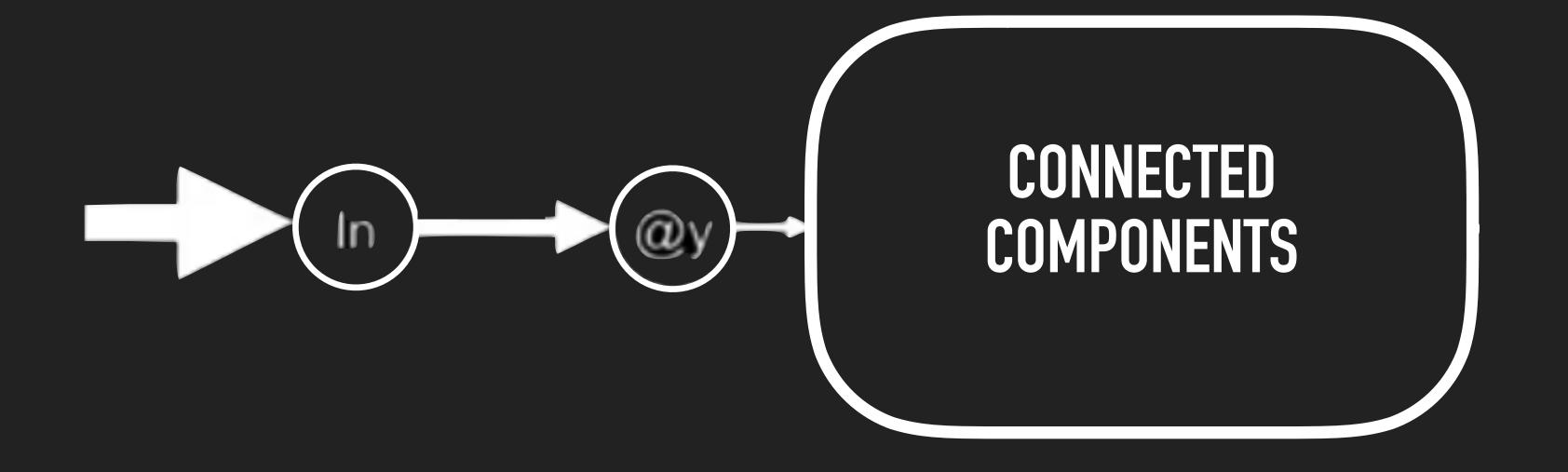


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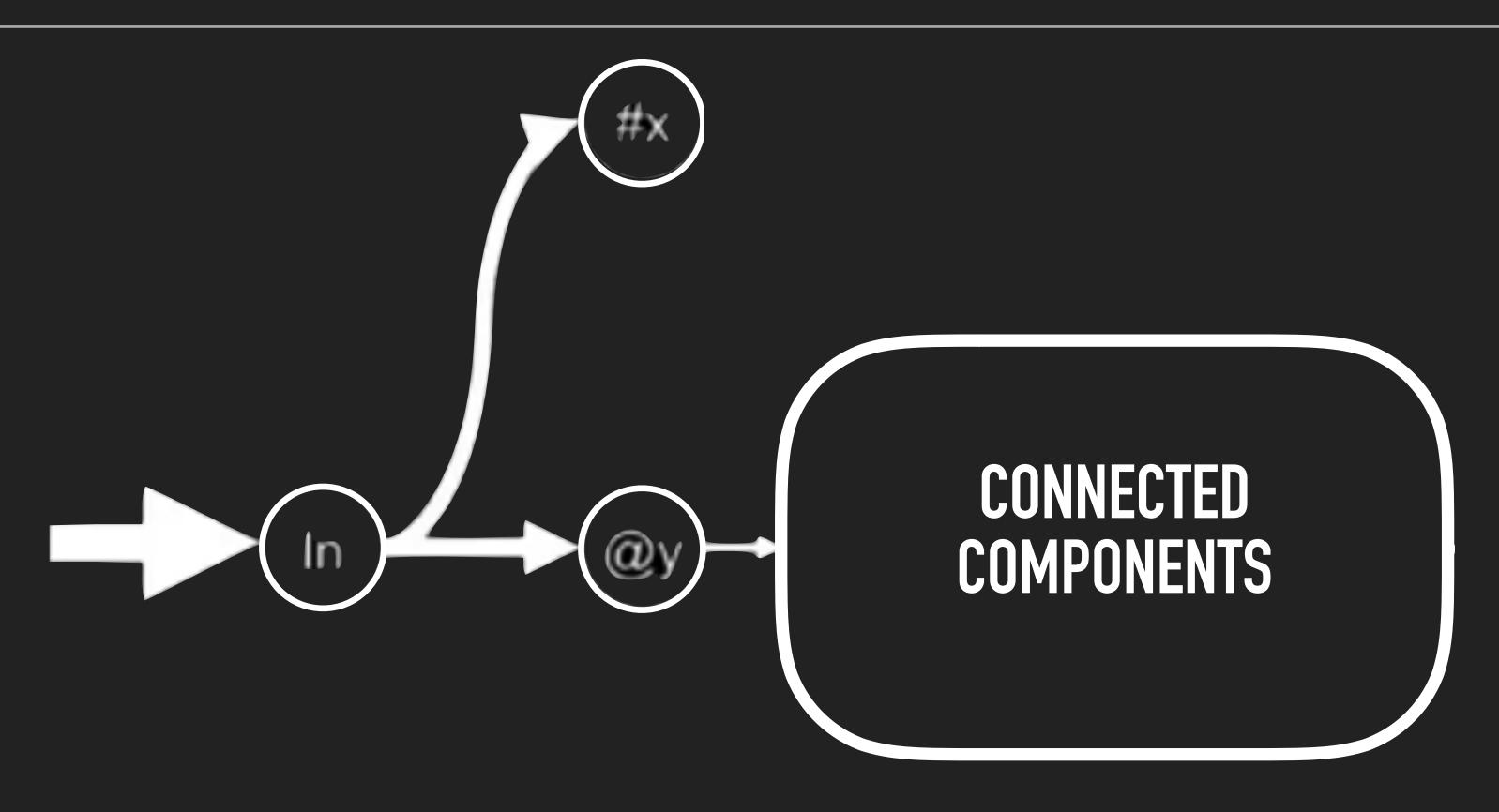
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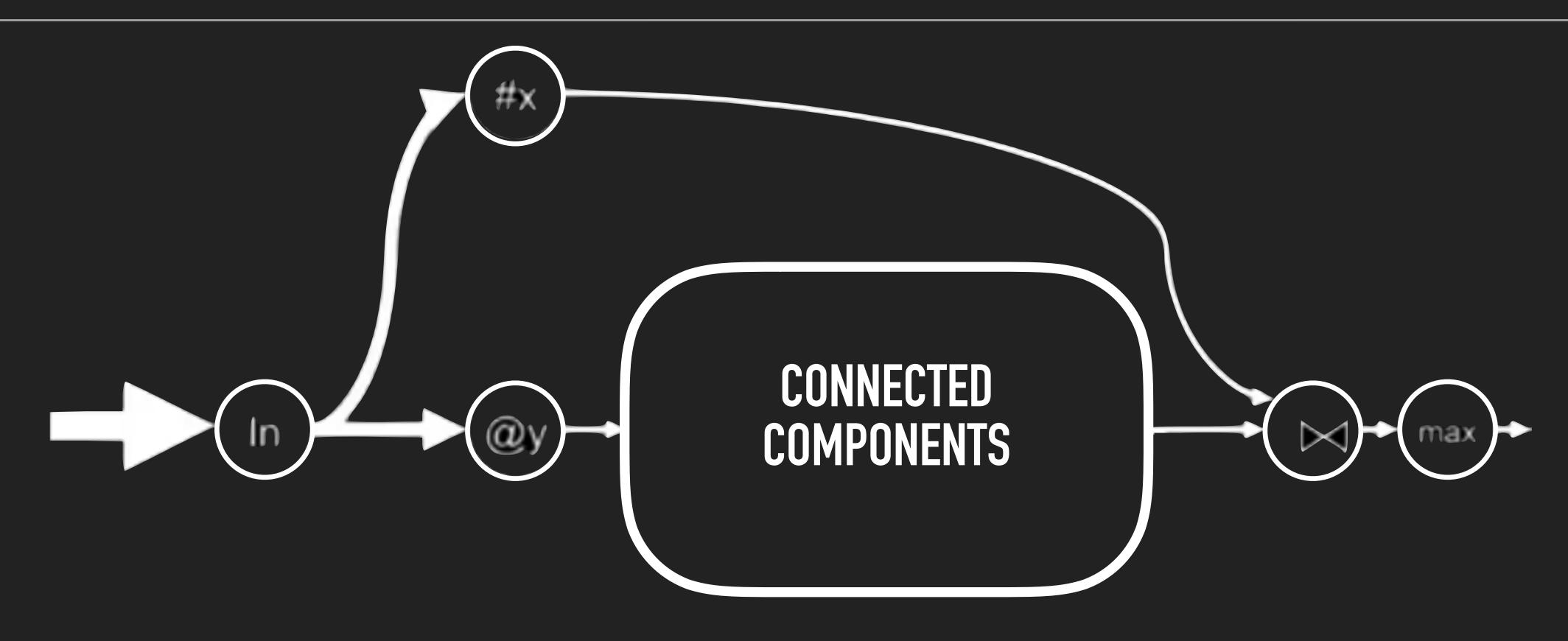
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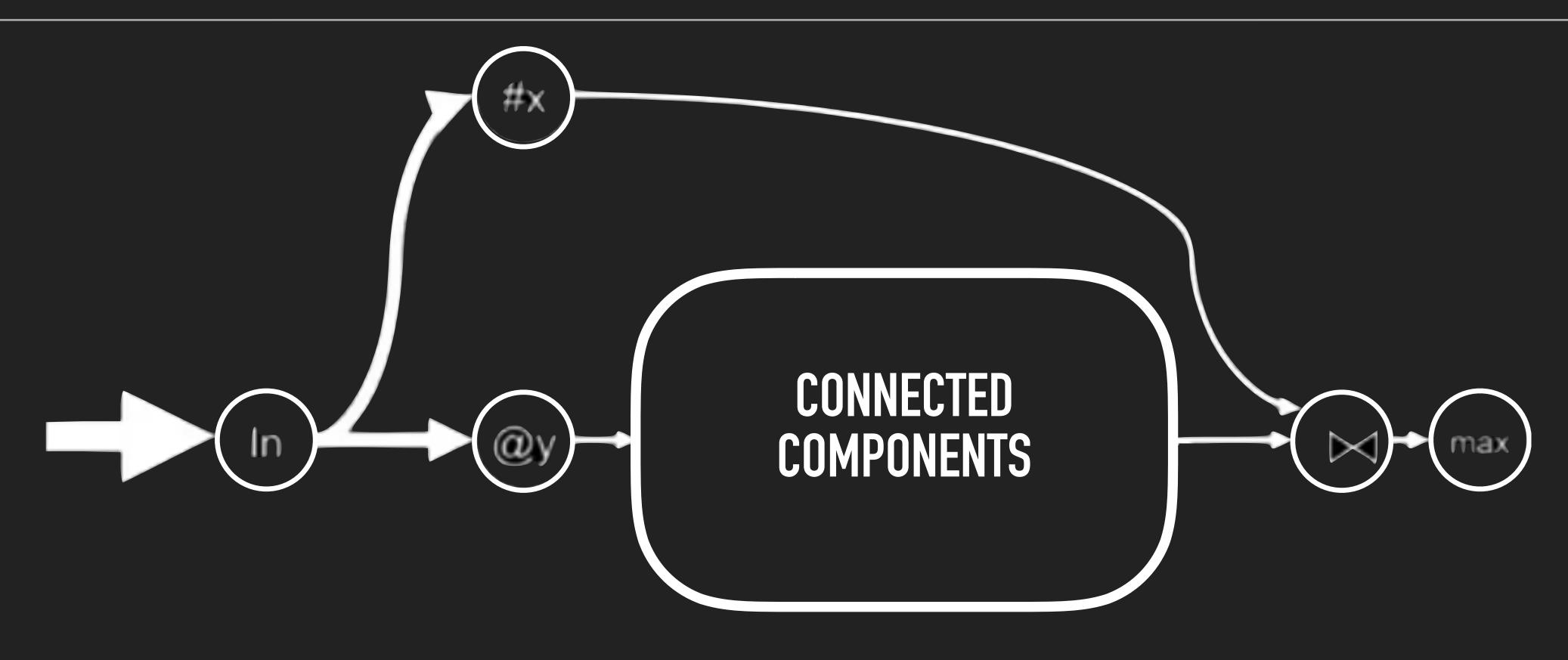
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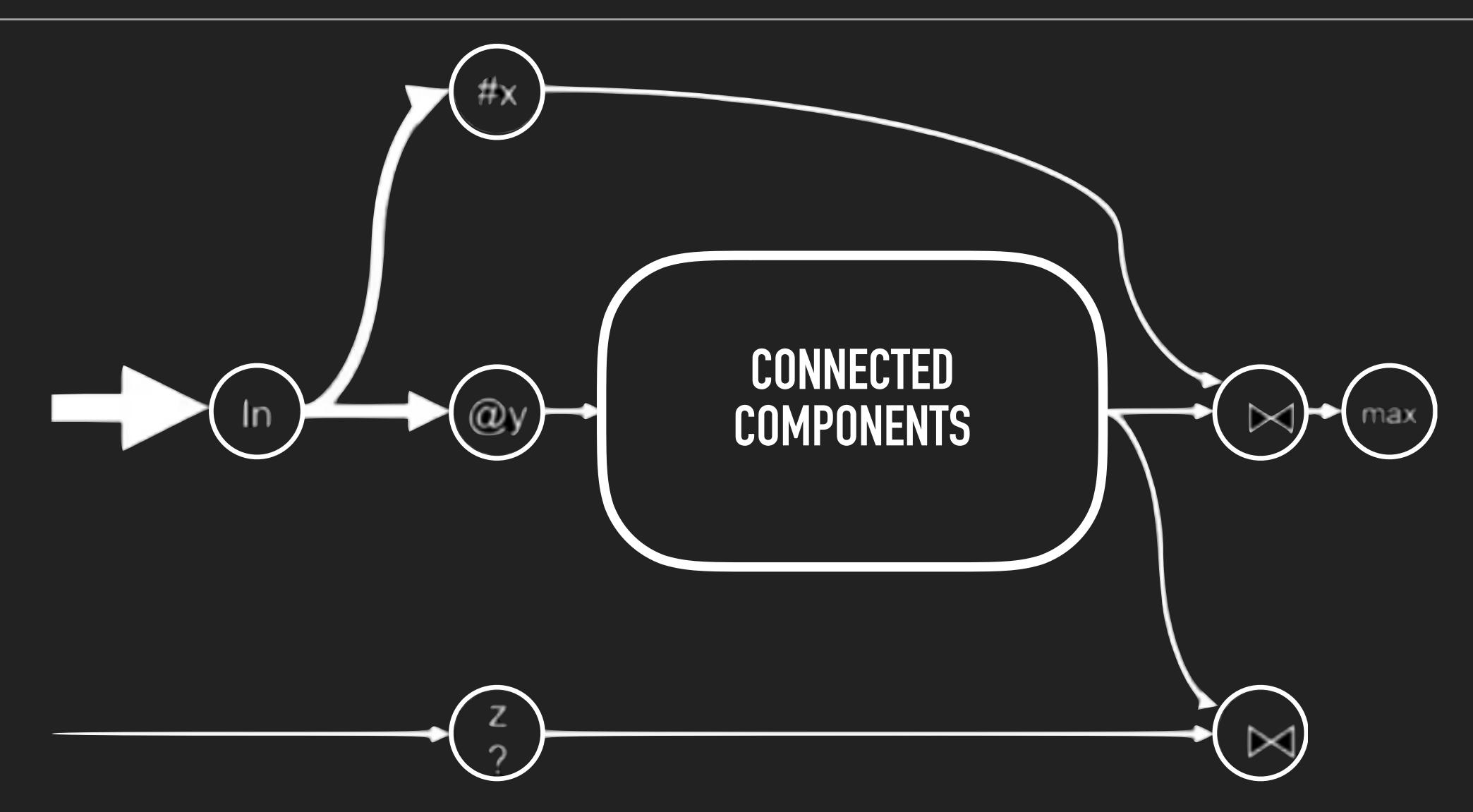
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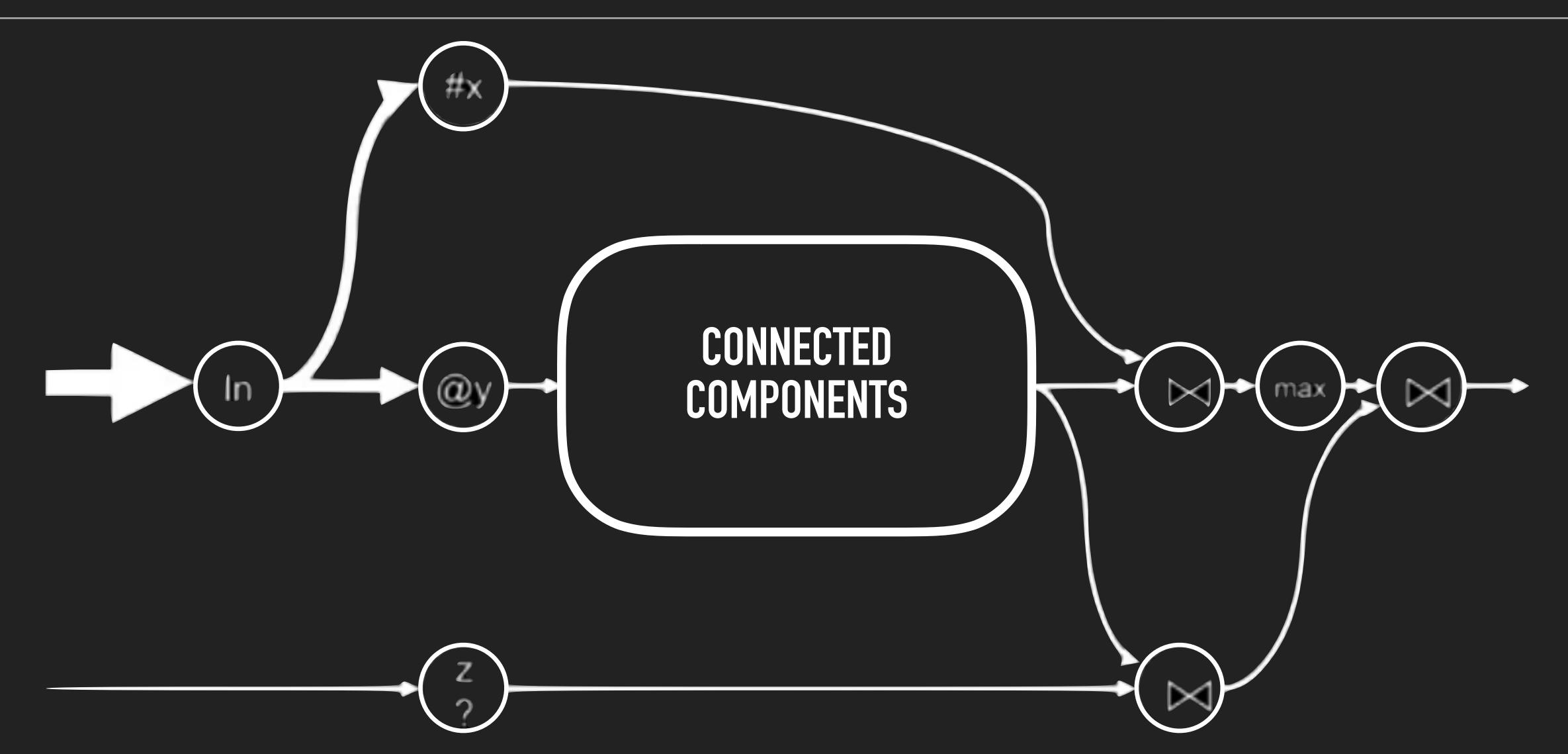
BATCH



BATCH

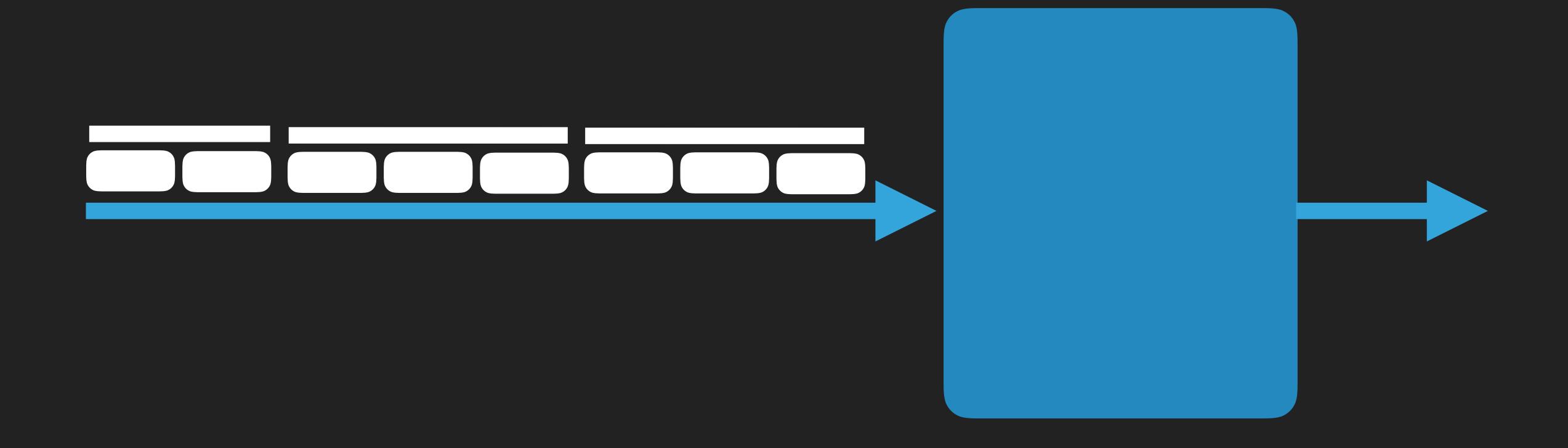


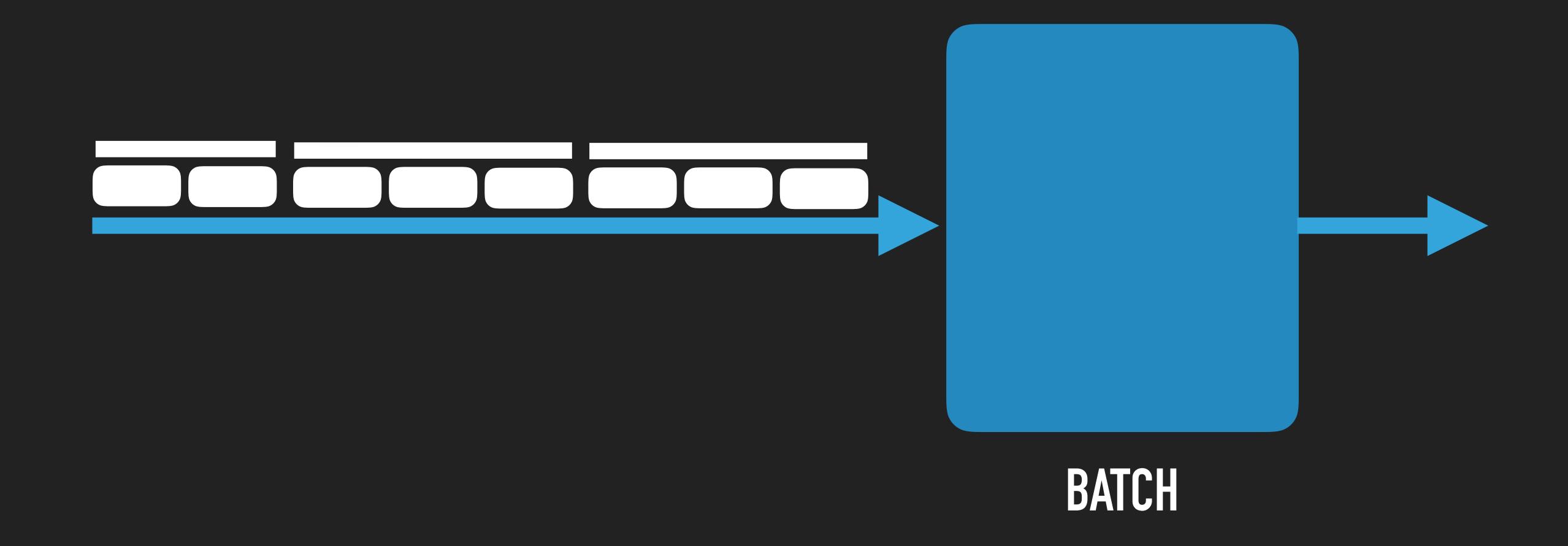
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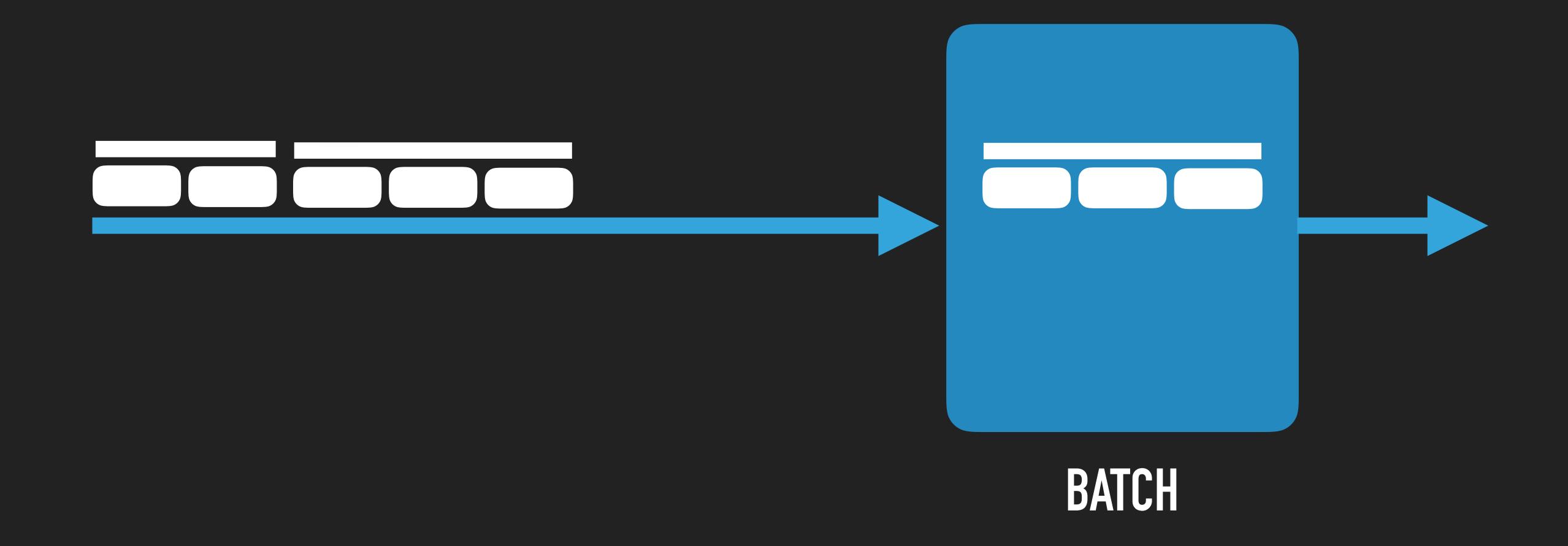


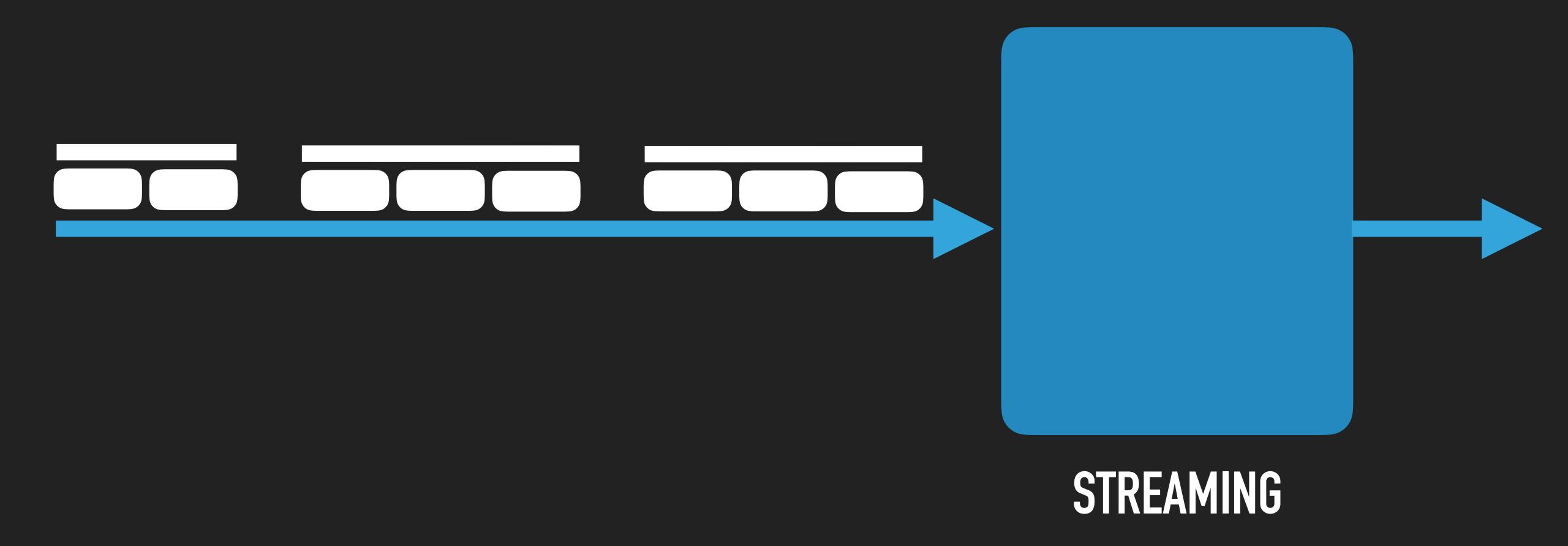
ACHIEVE THE PERFORMANCE OF SPECIALIZED FRAMEWORK, PROVIDE THE FLEXIBILITY OF A GENERIC FRAMEWORK.

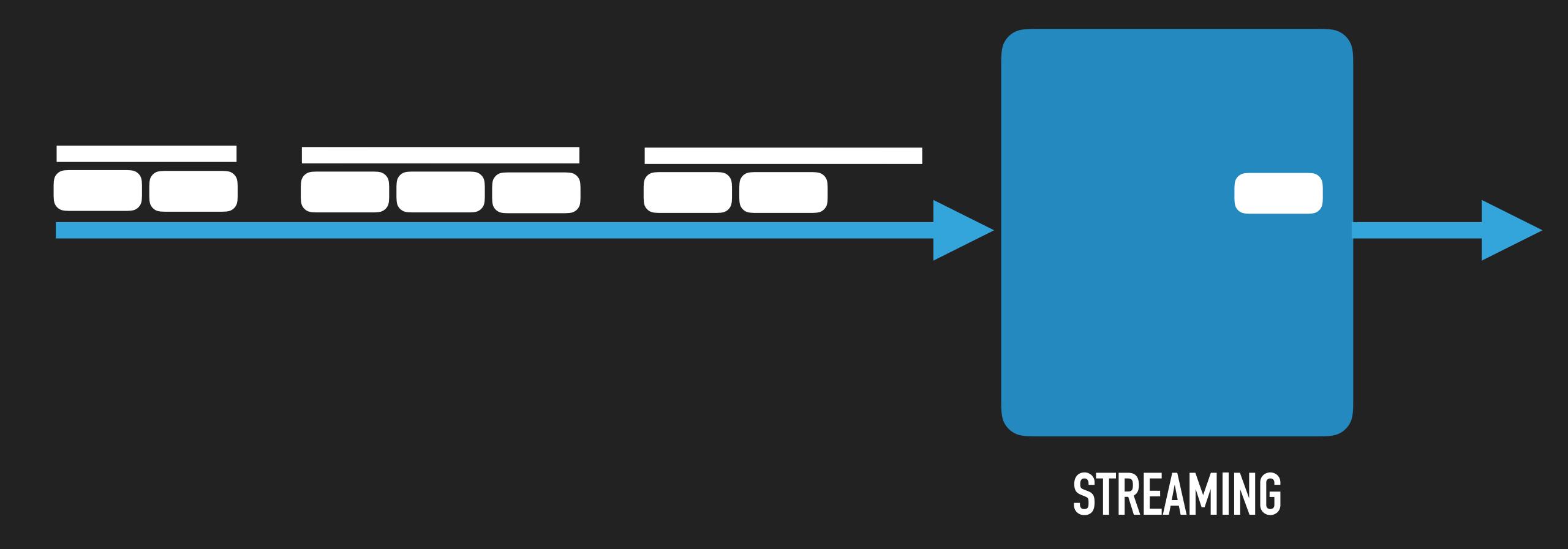
Derek Murray

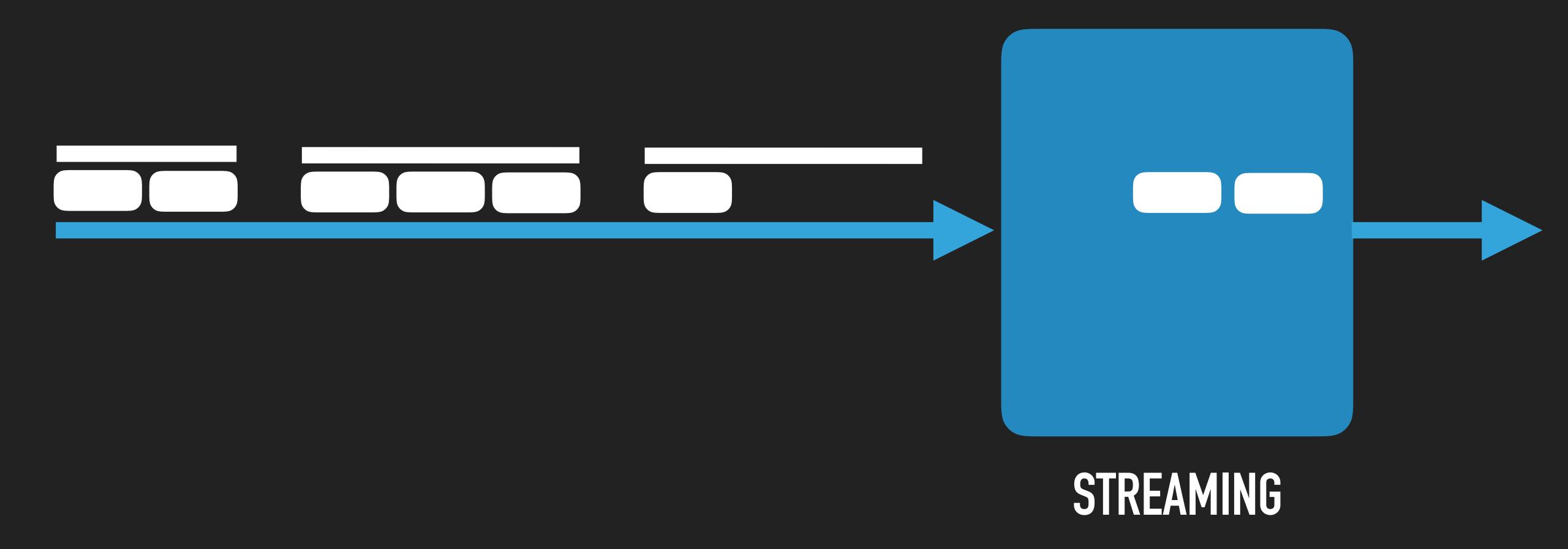


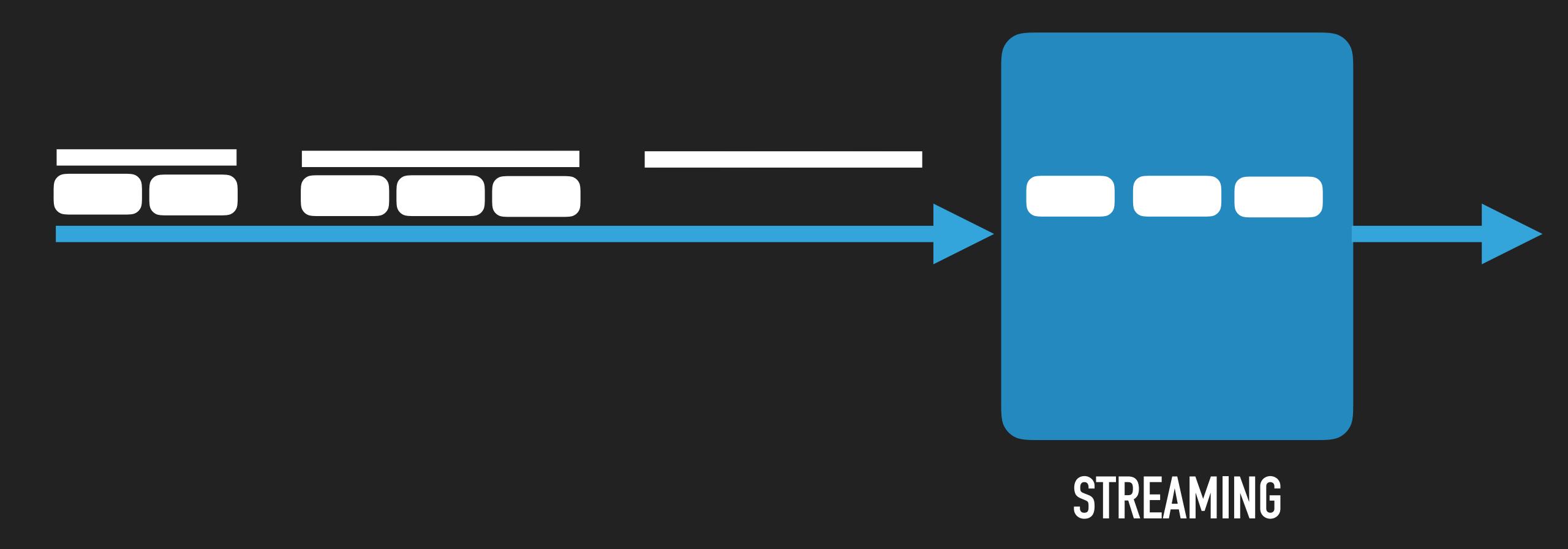


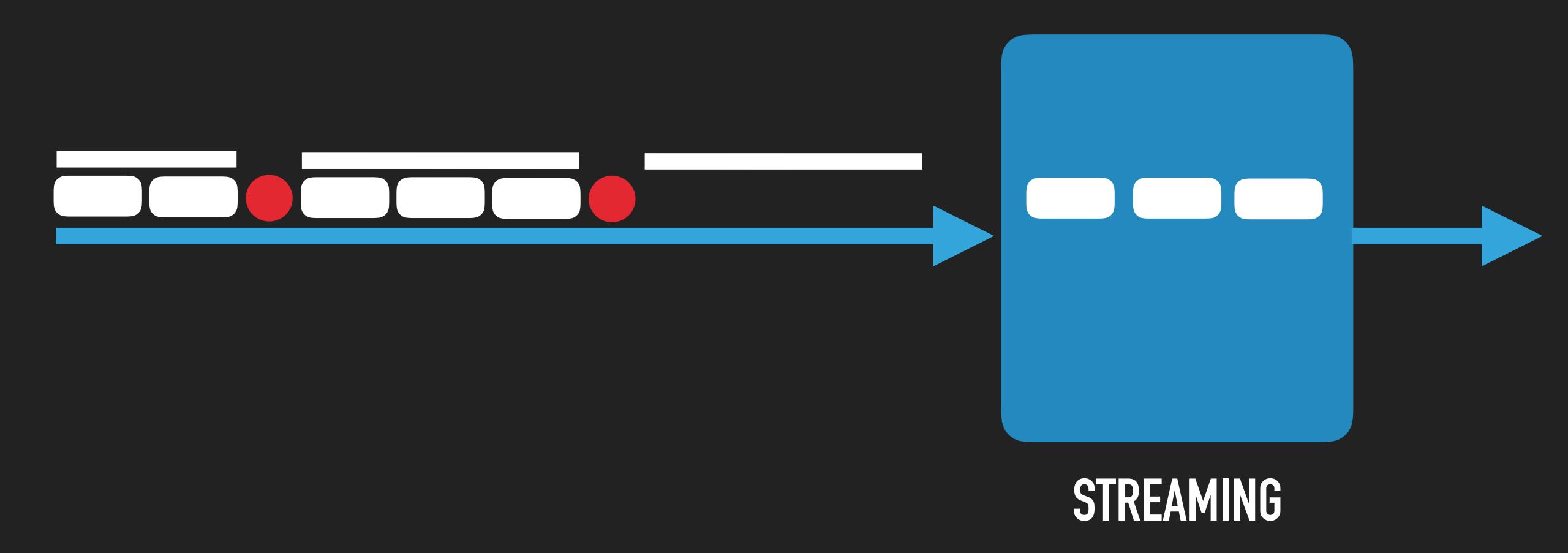


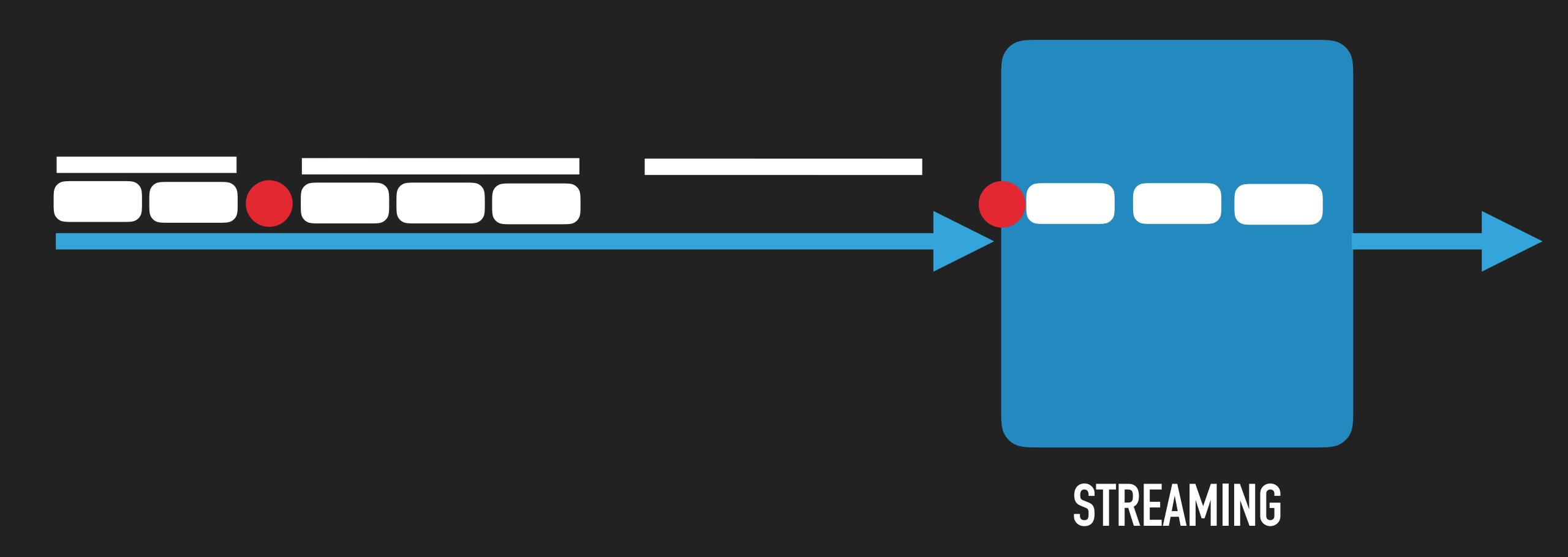


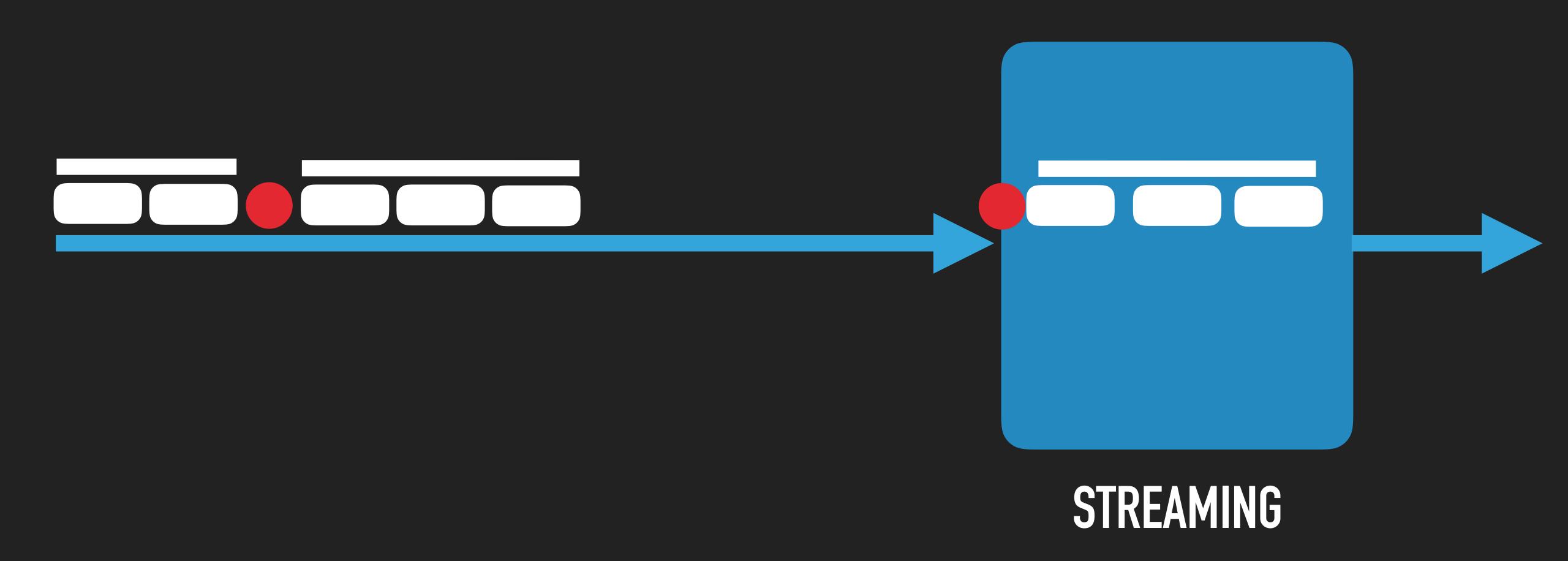


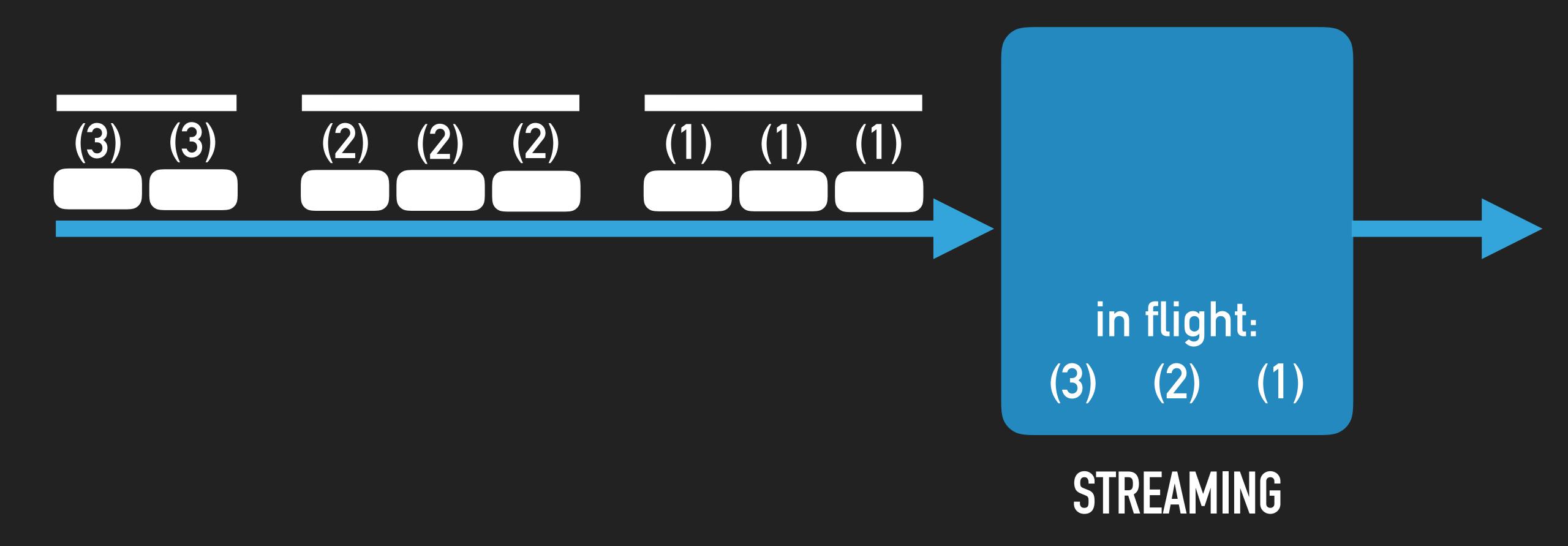


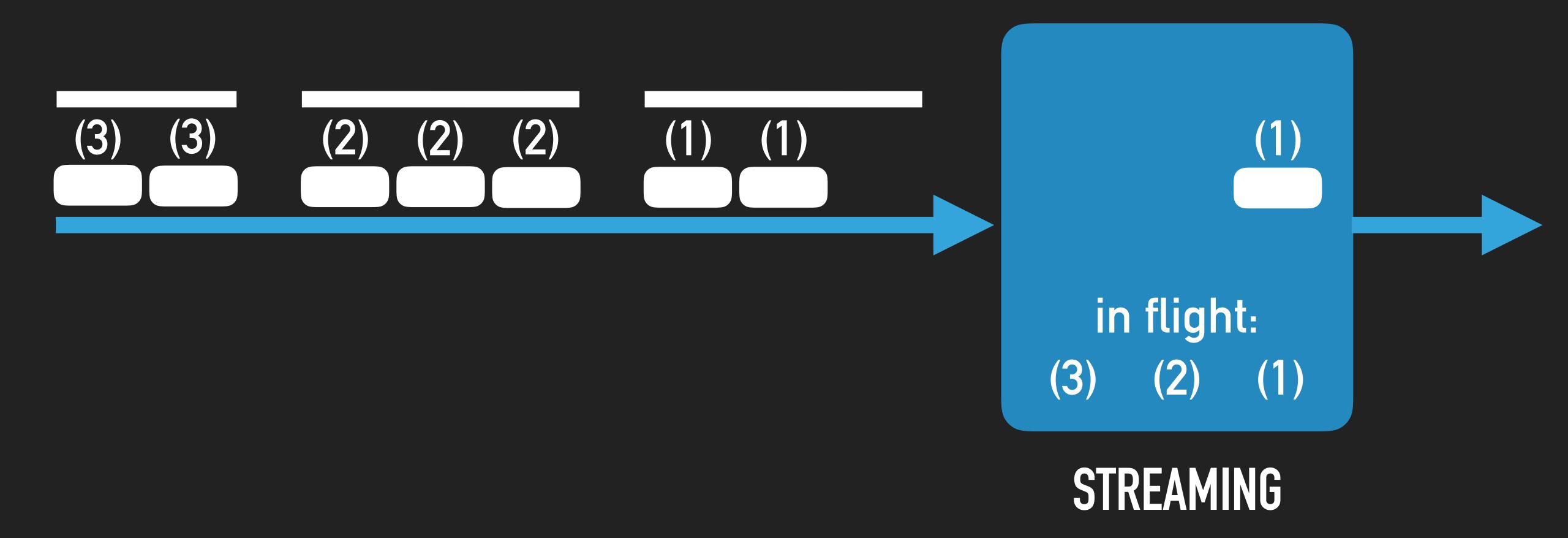


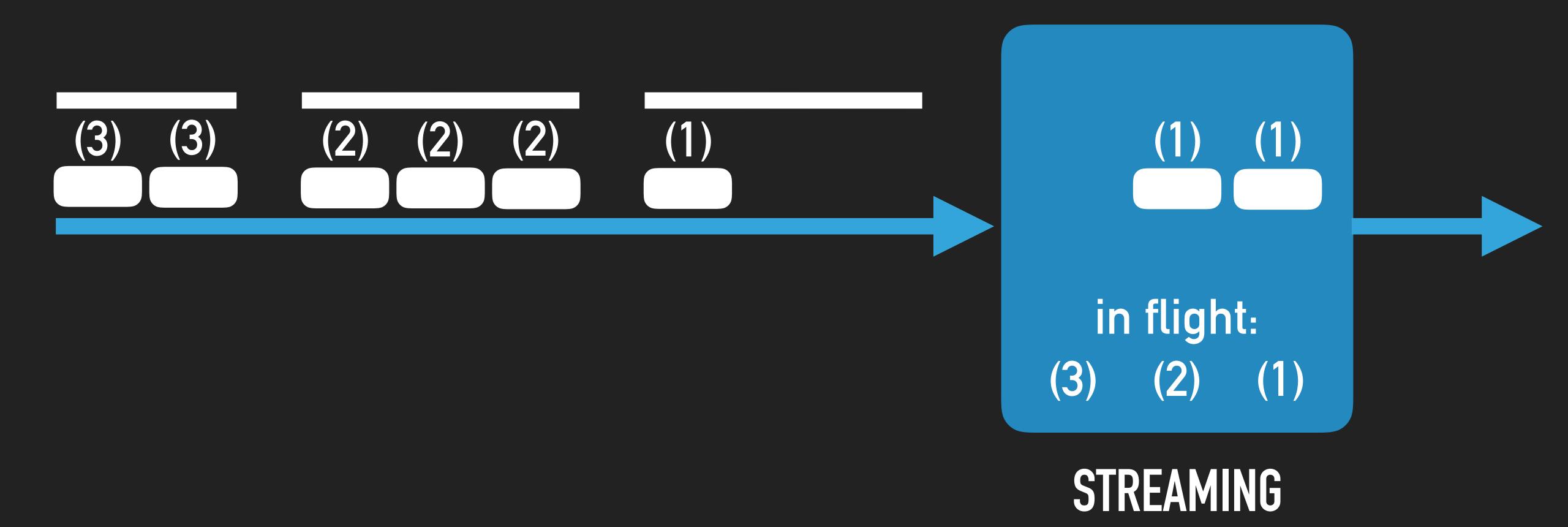


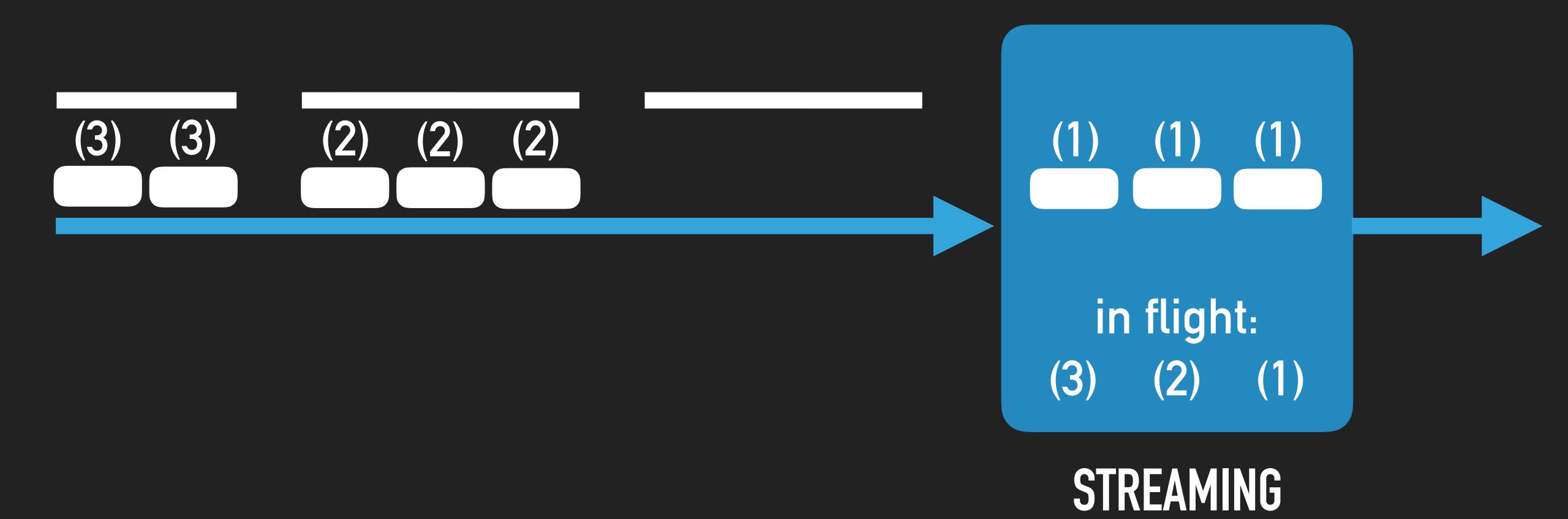


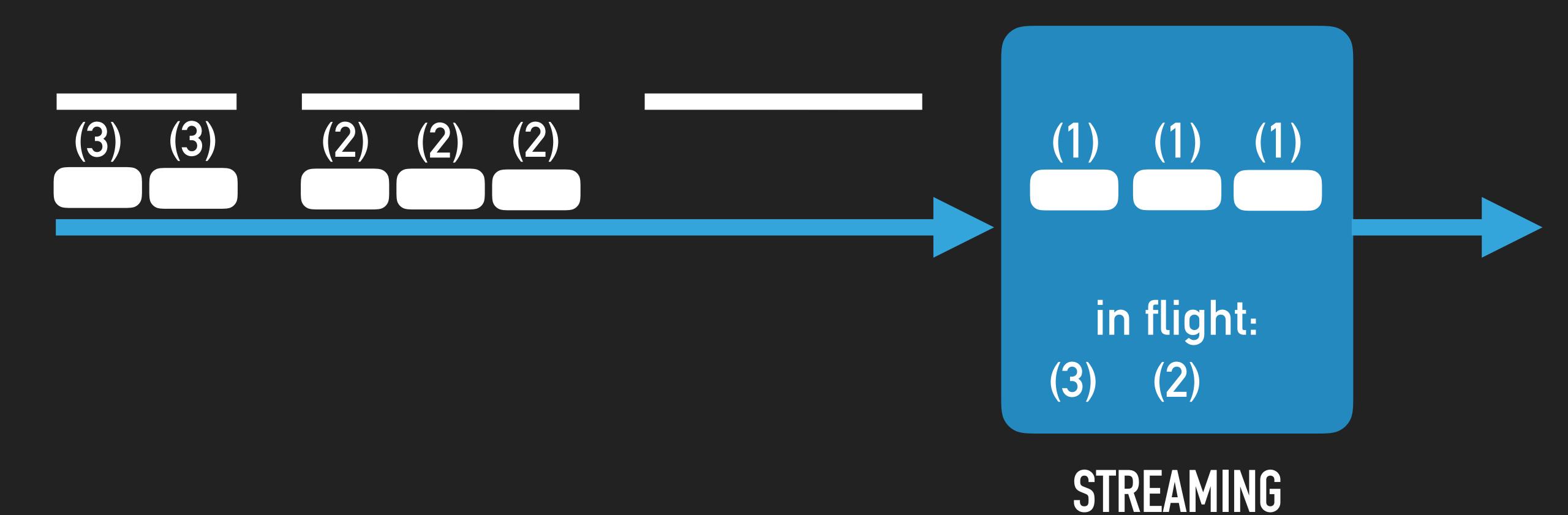


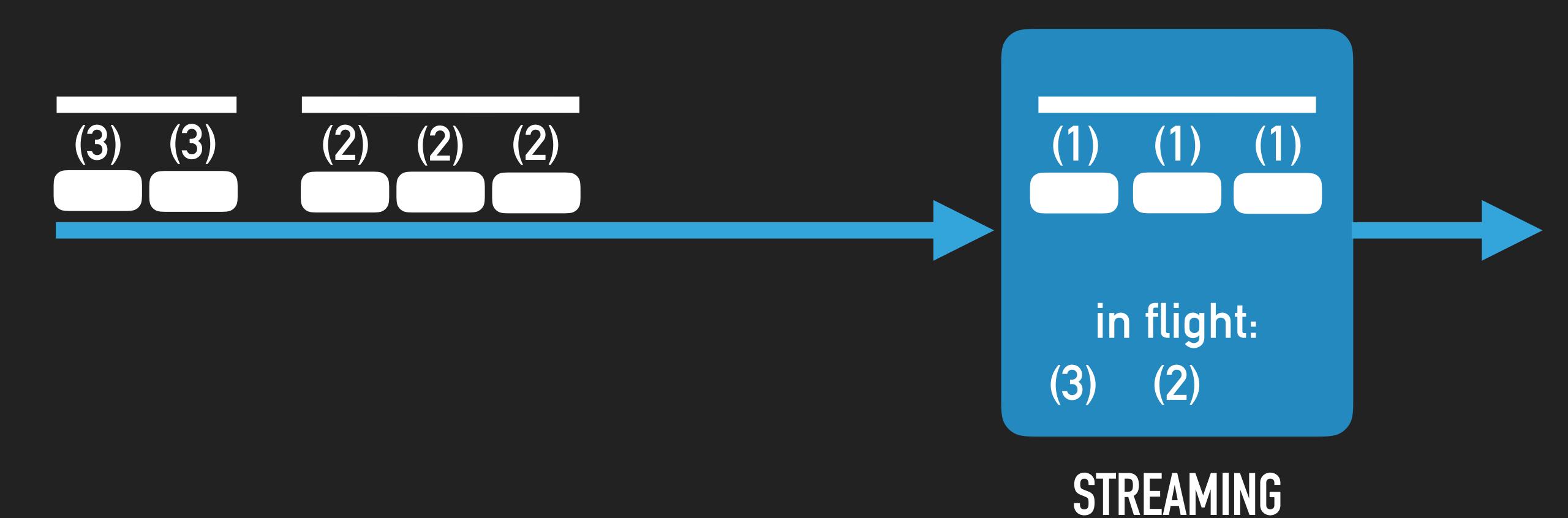


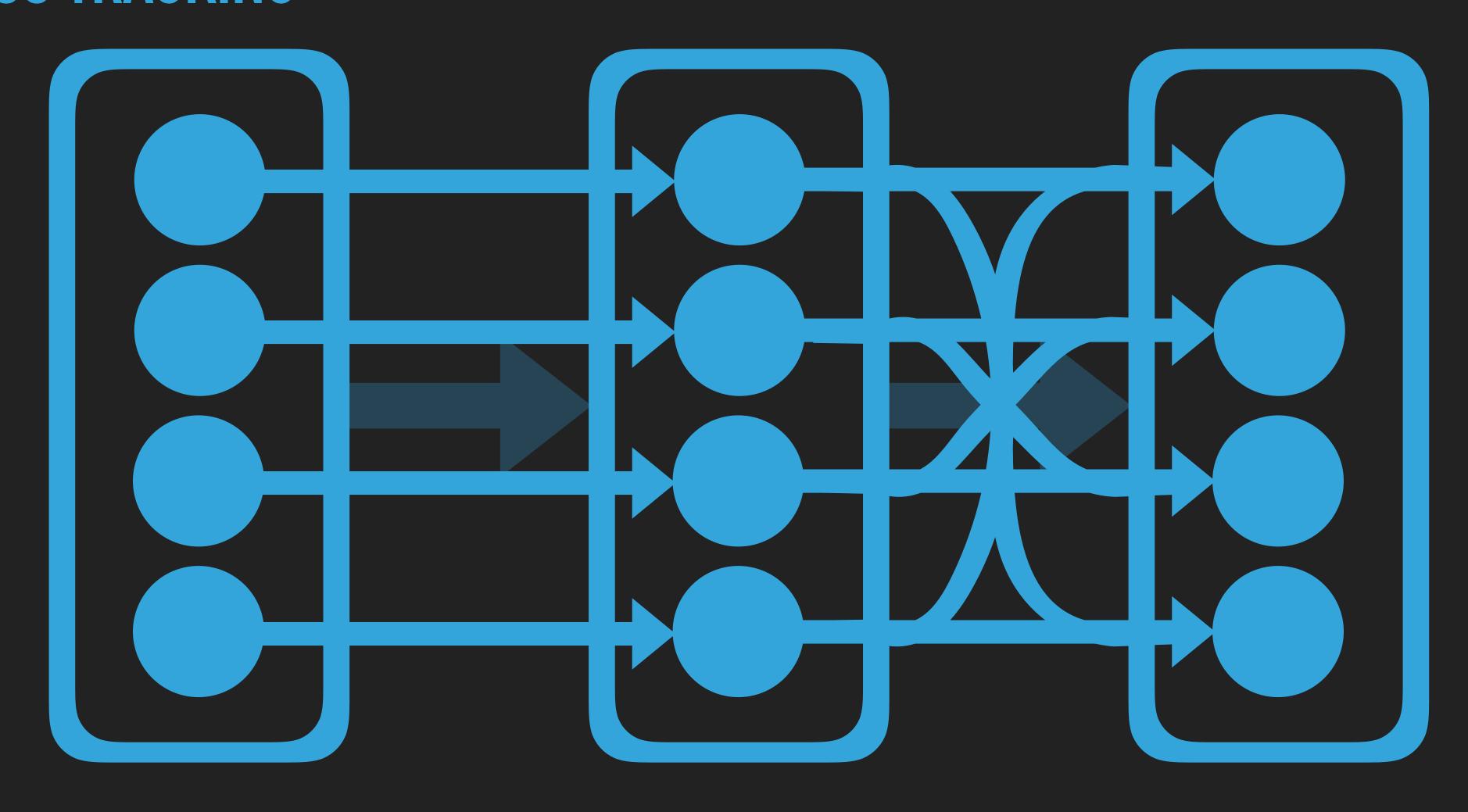


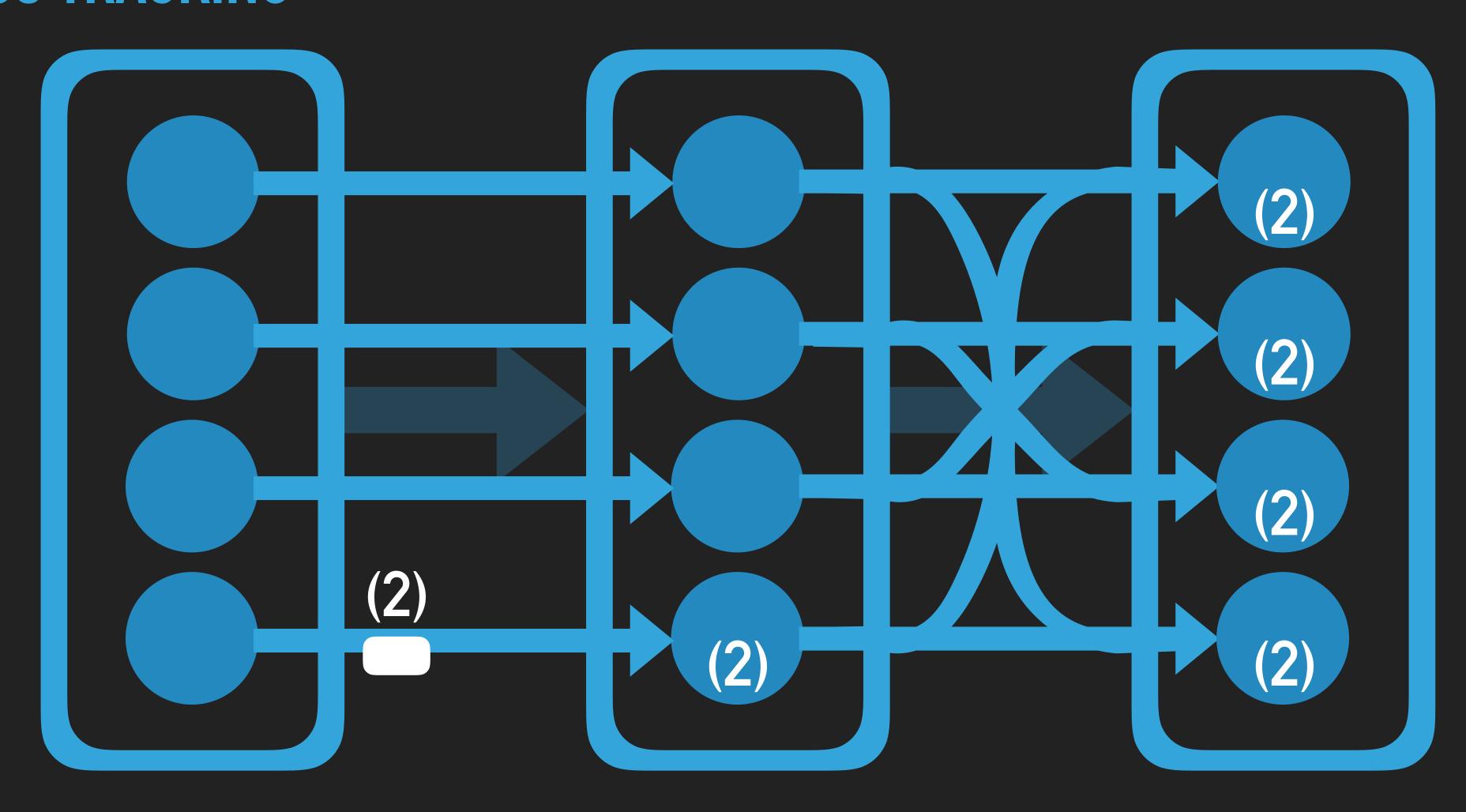


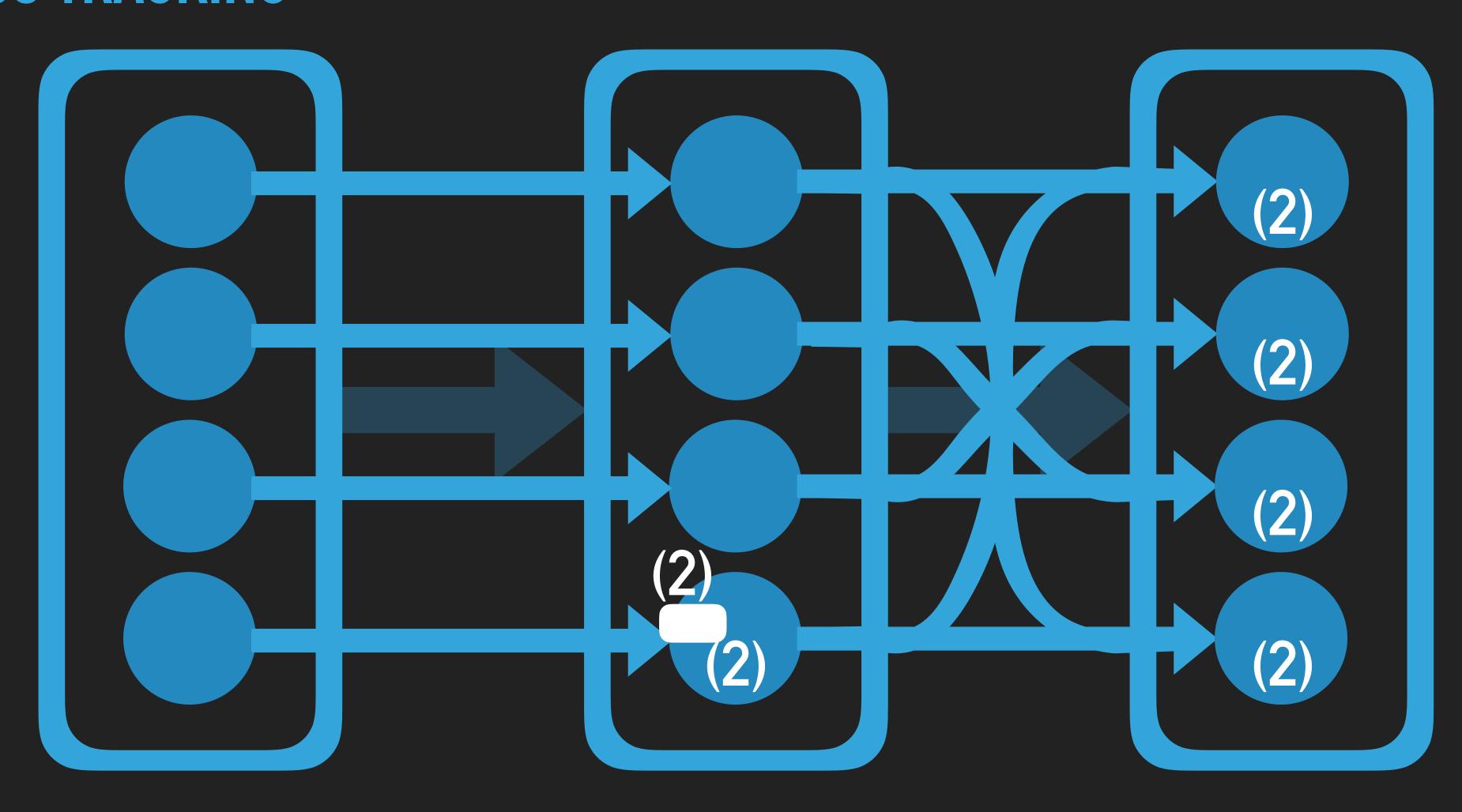


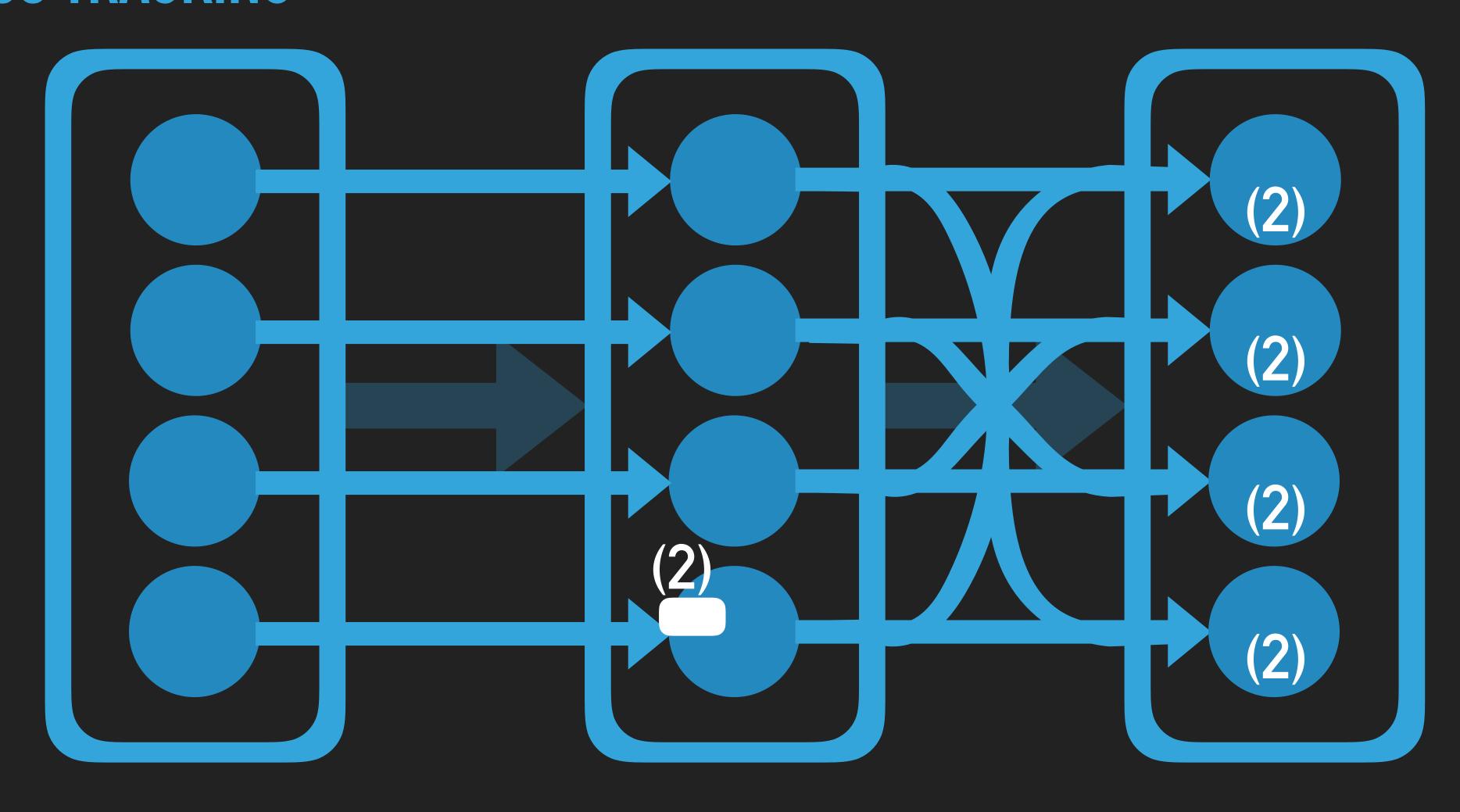


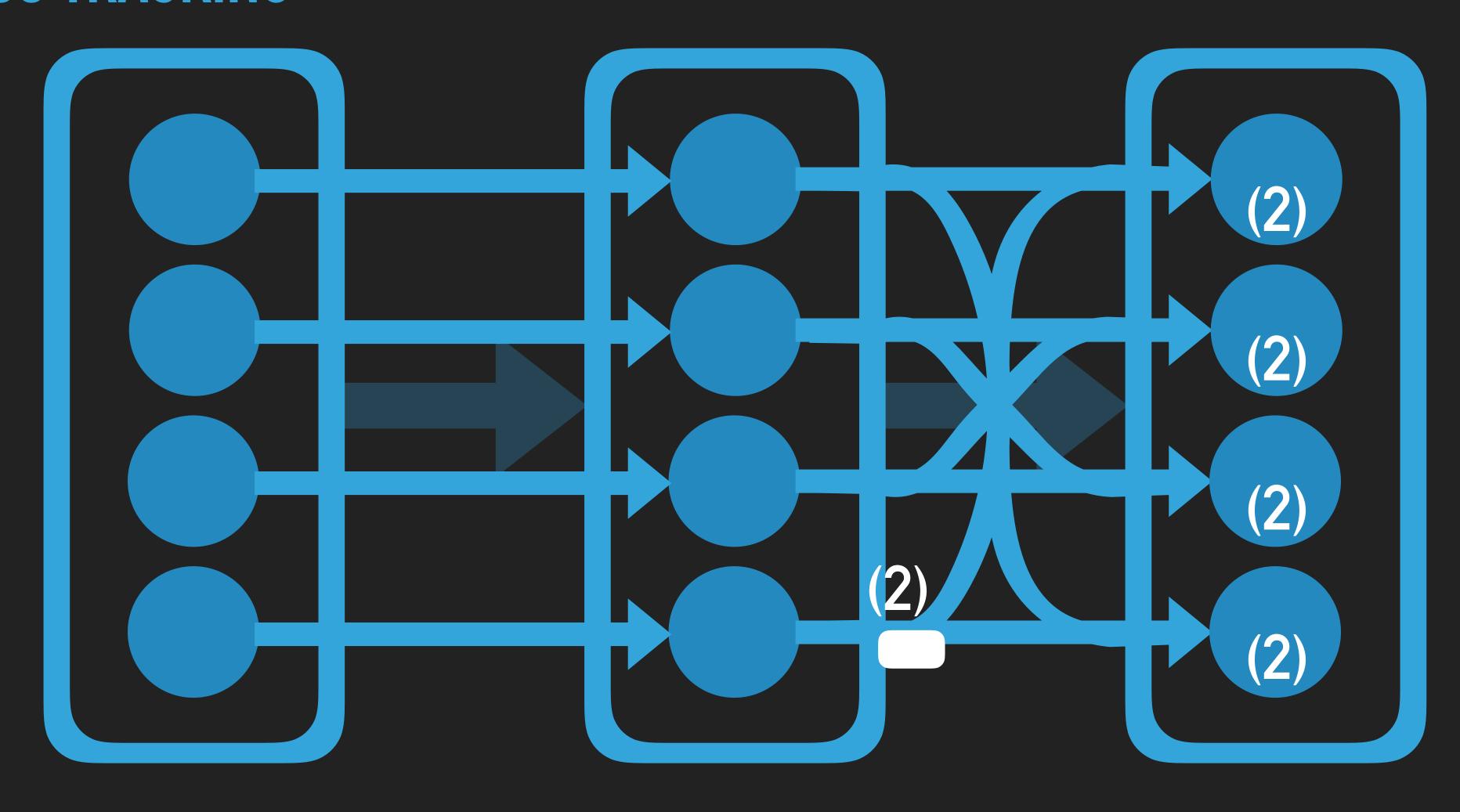




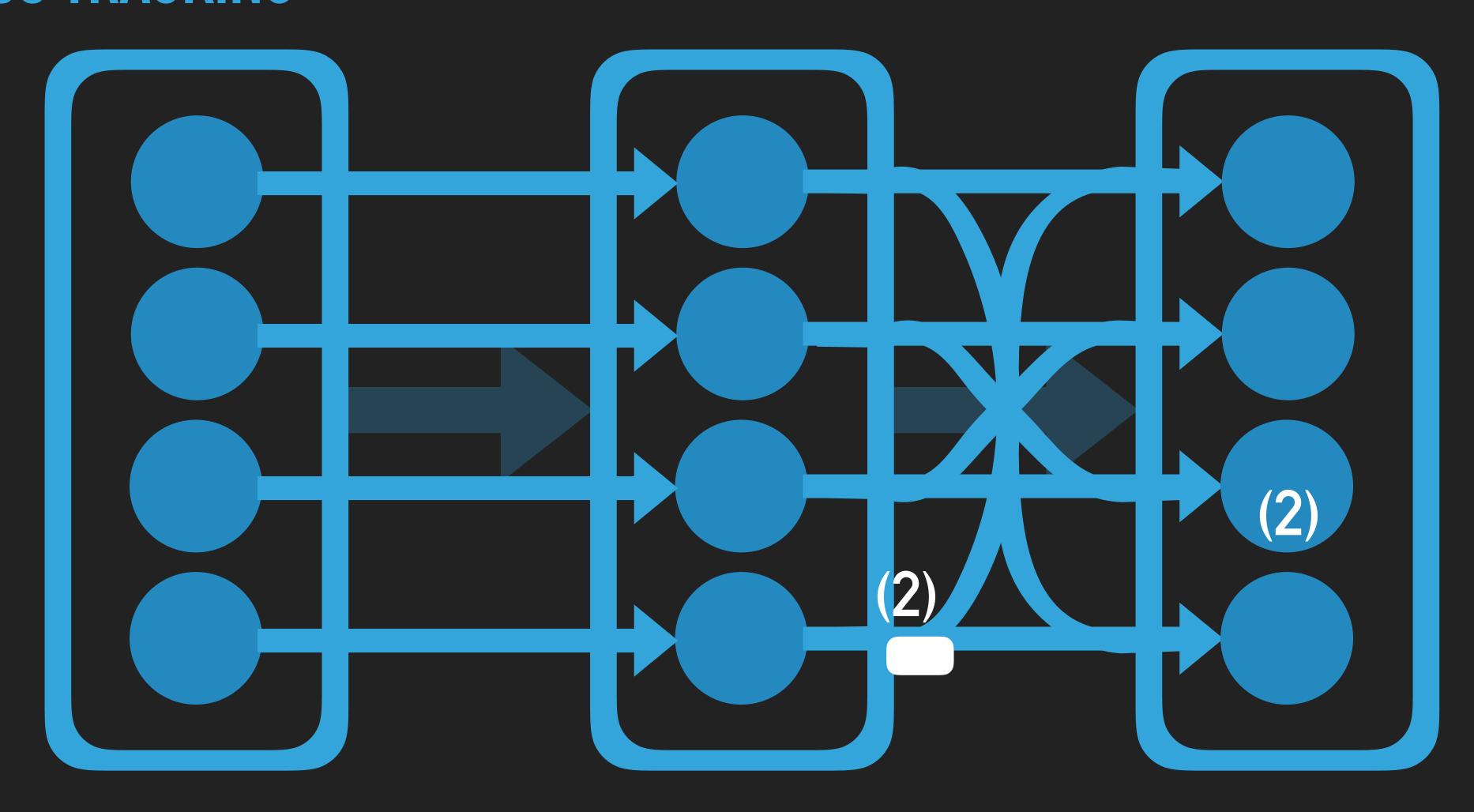


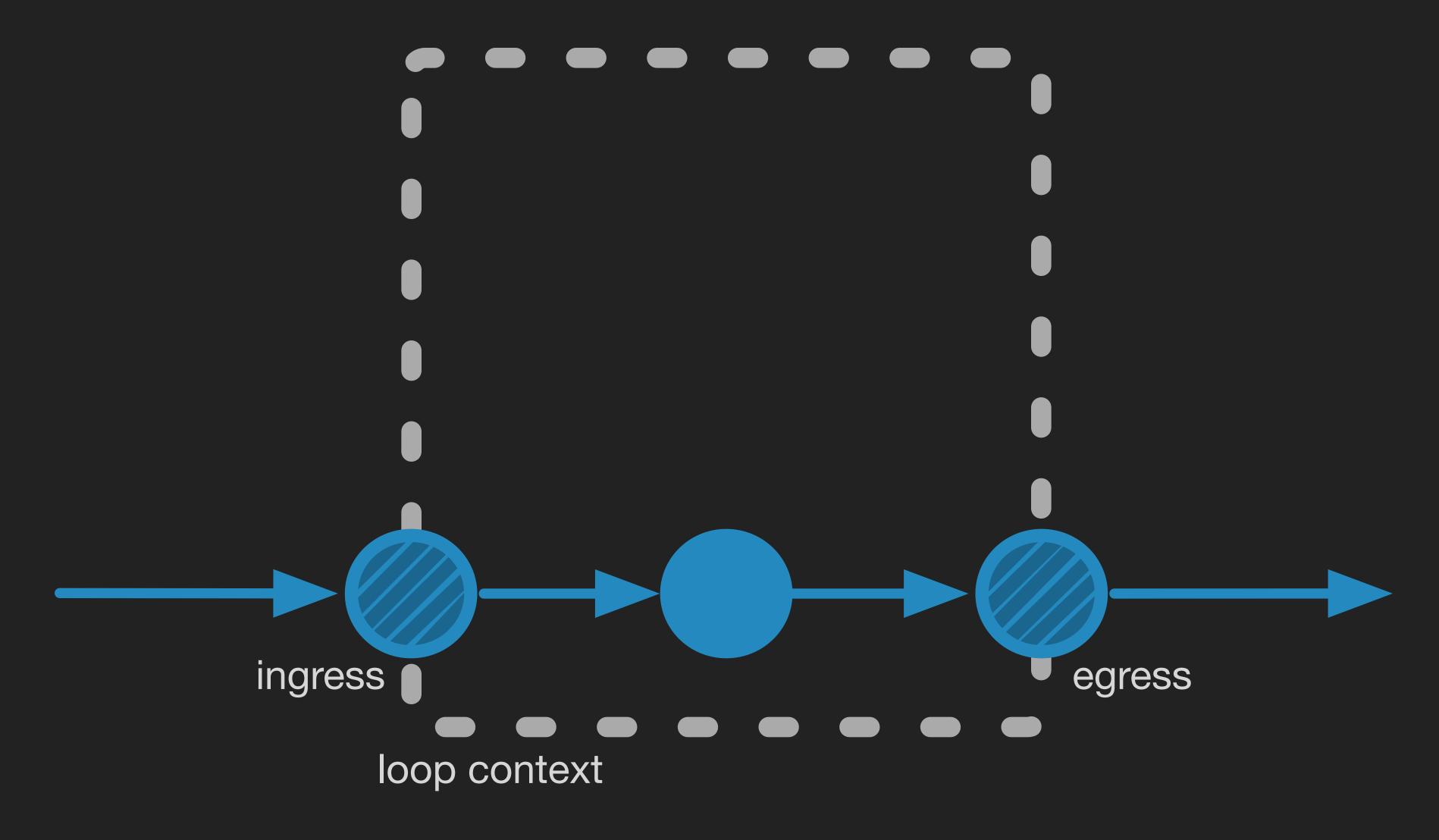


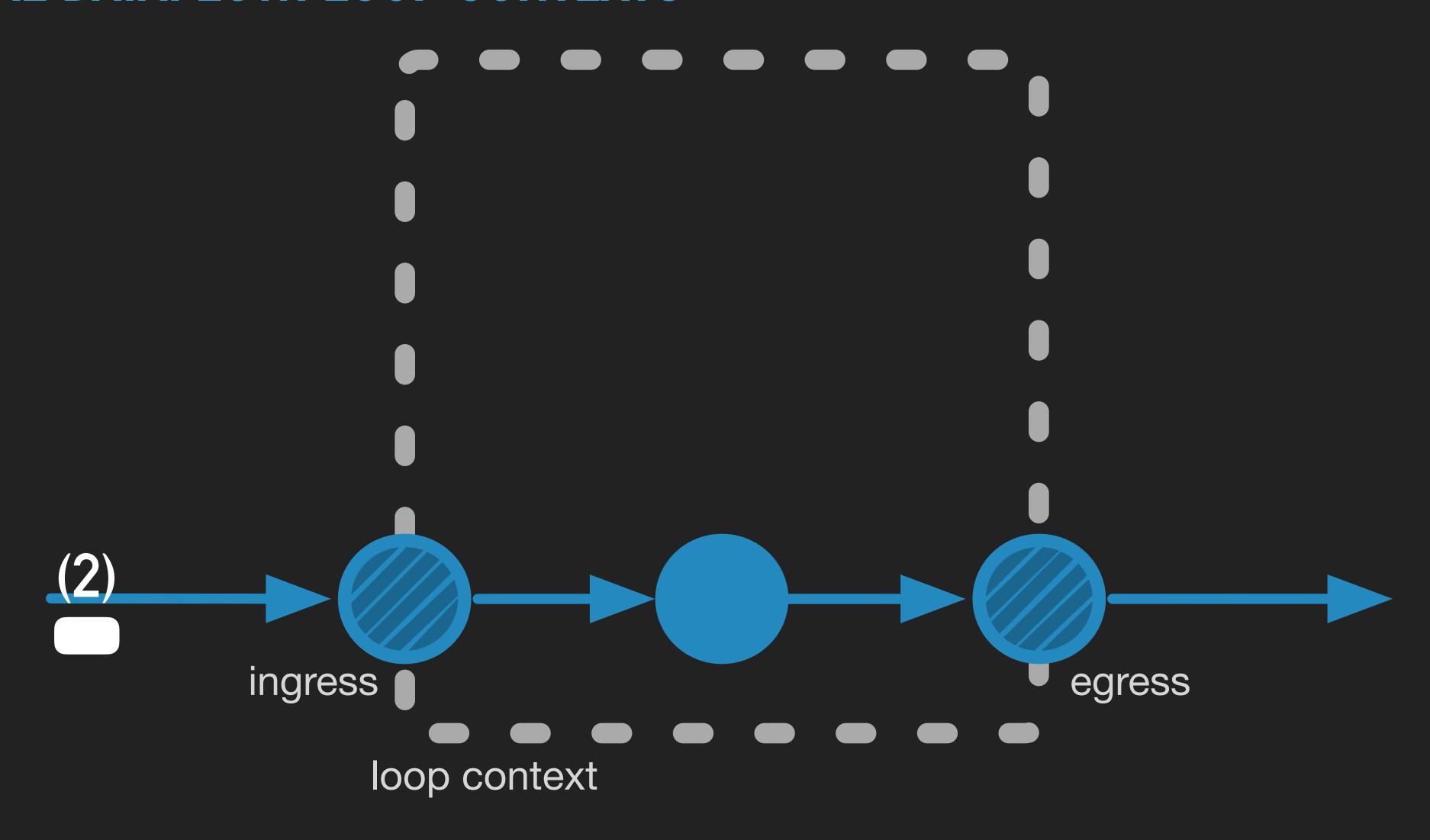


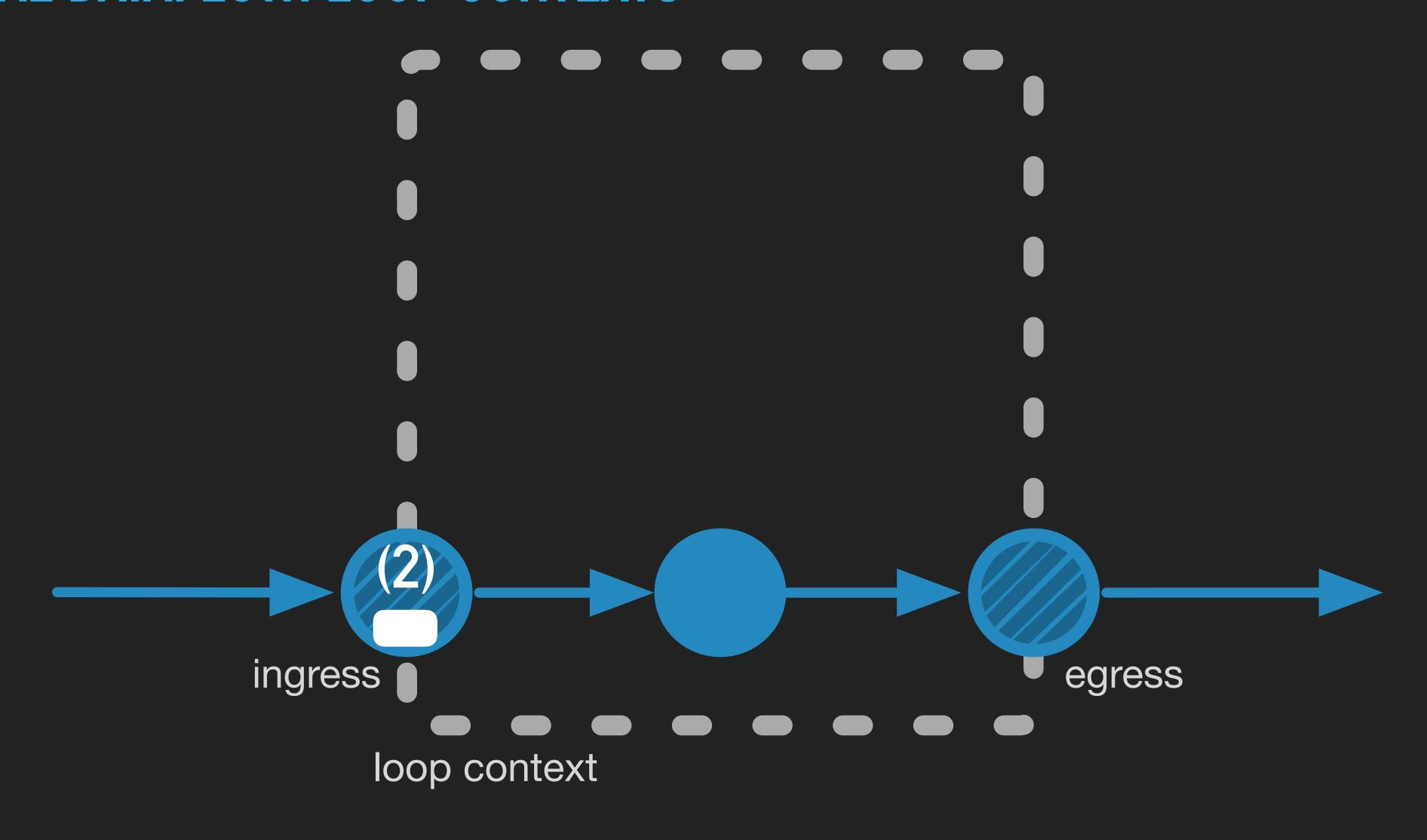


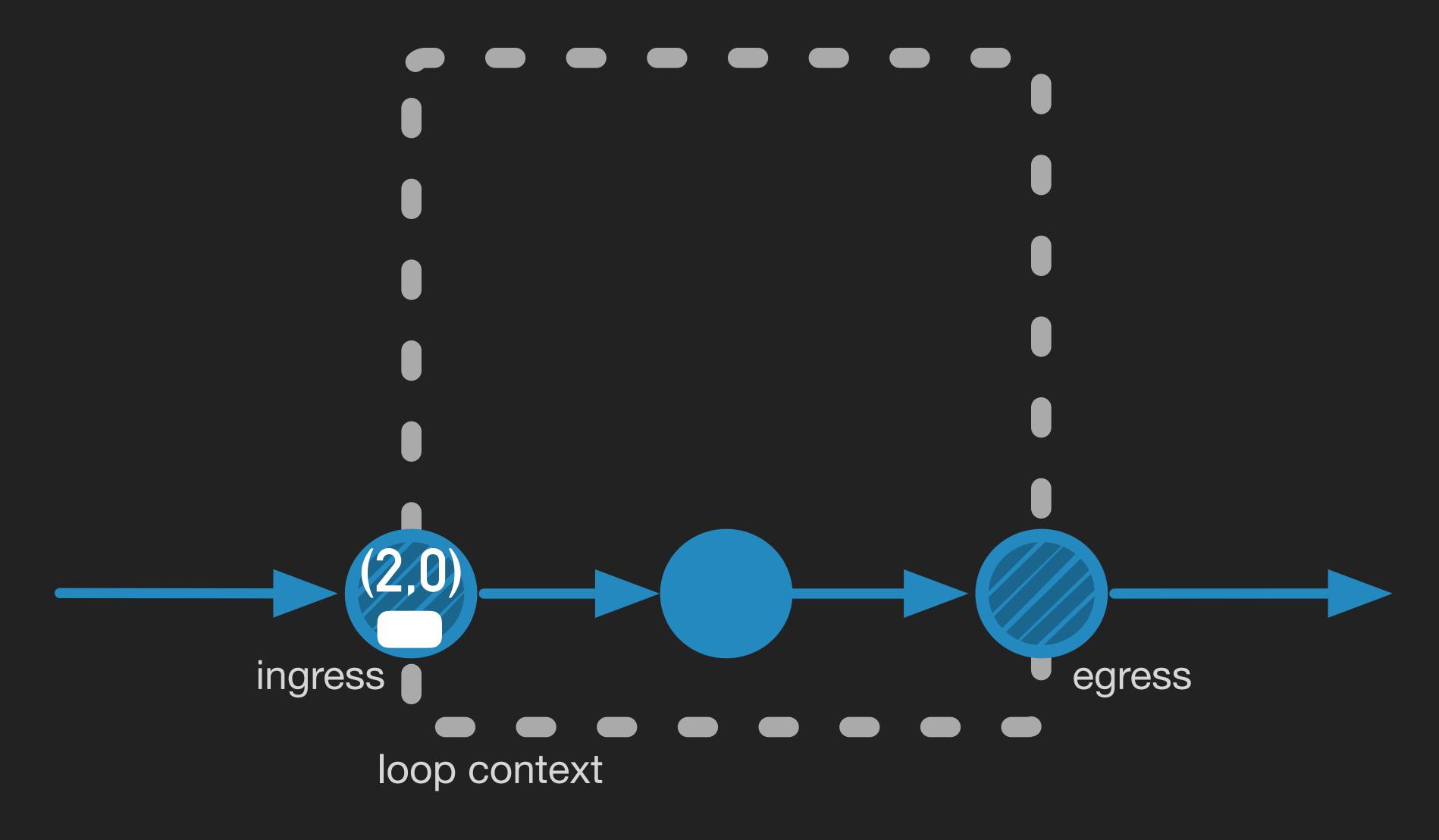
PROGRESS TRACKING

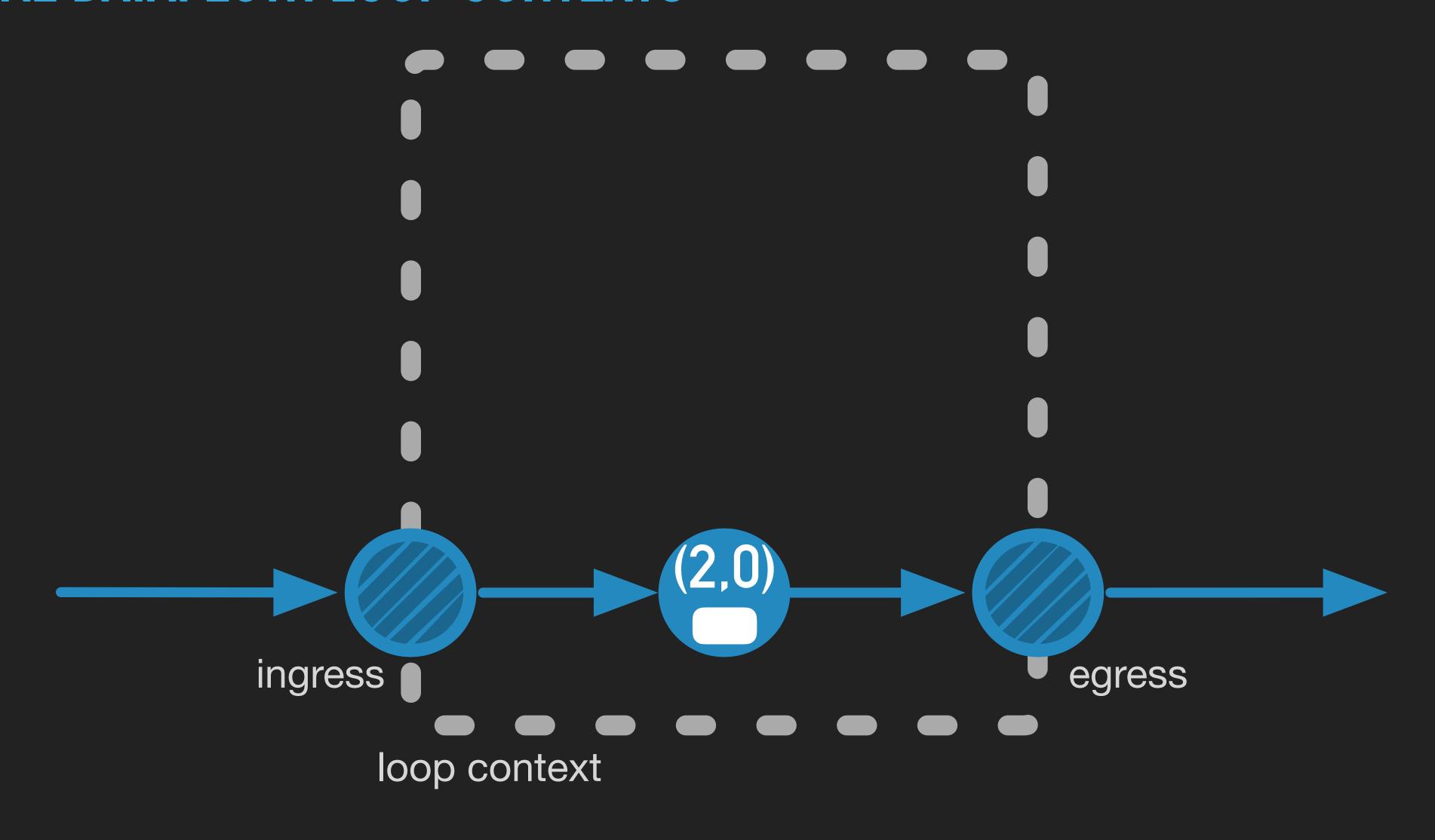


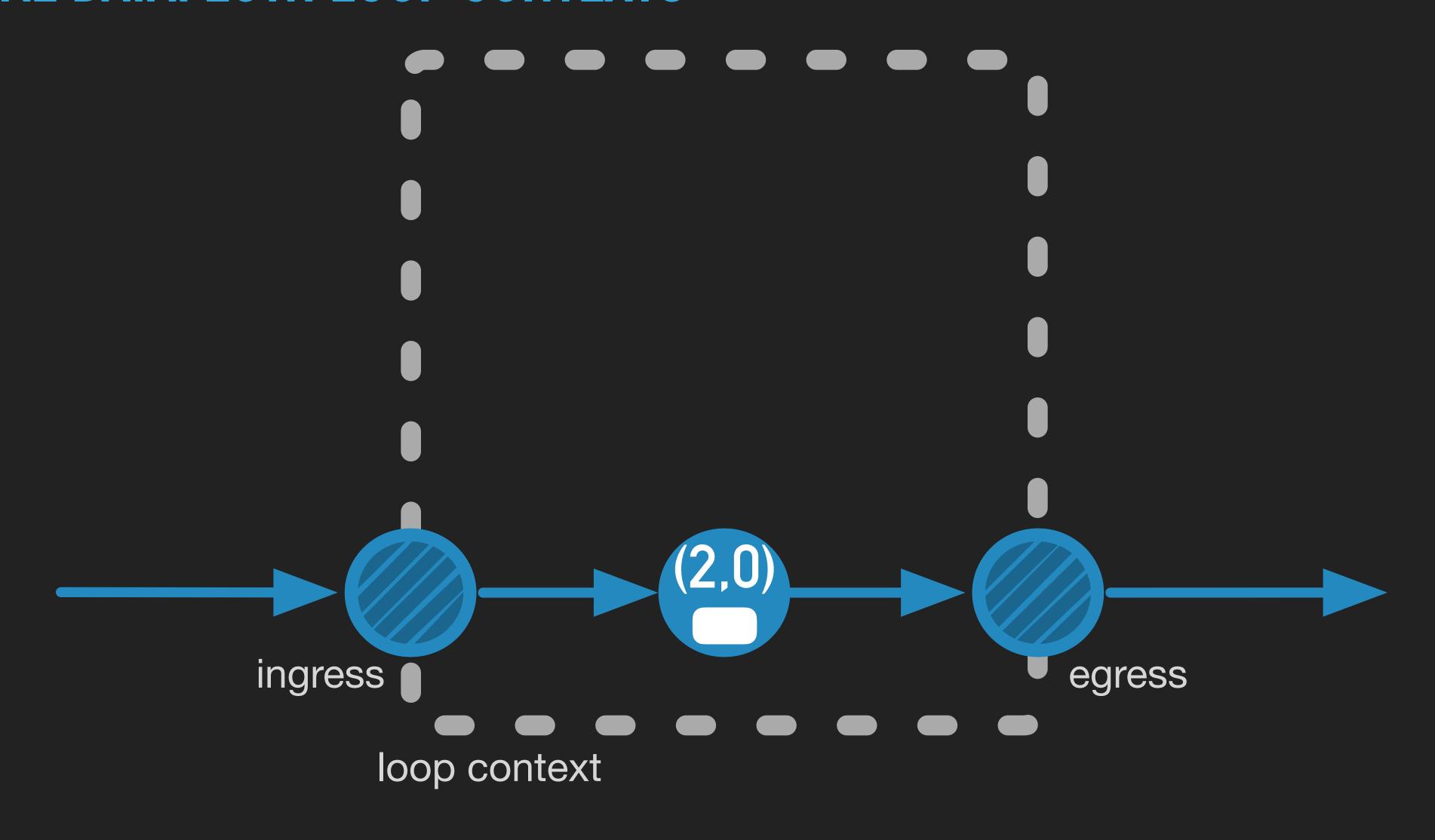


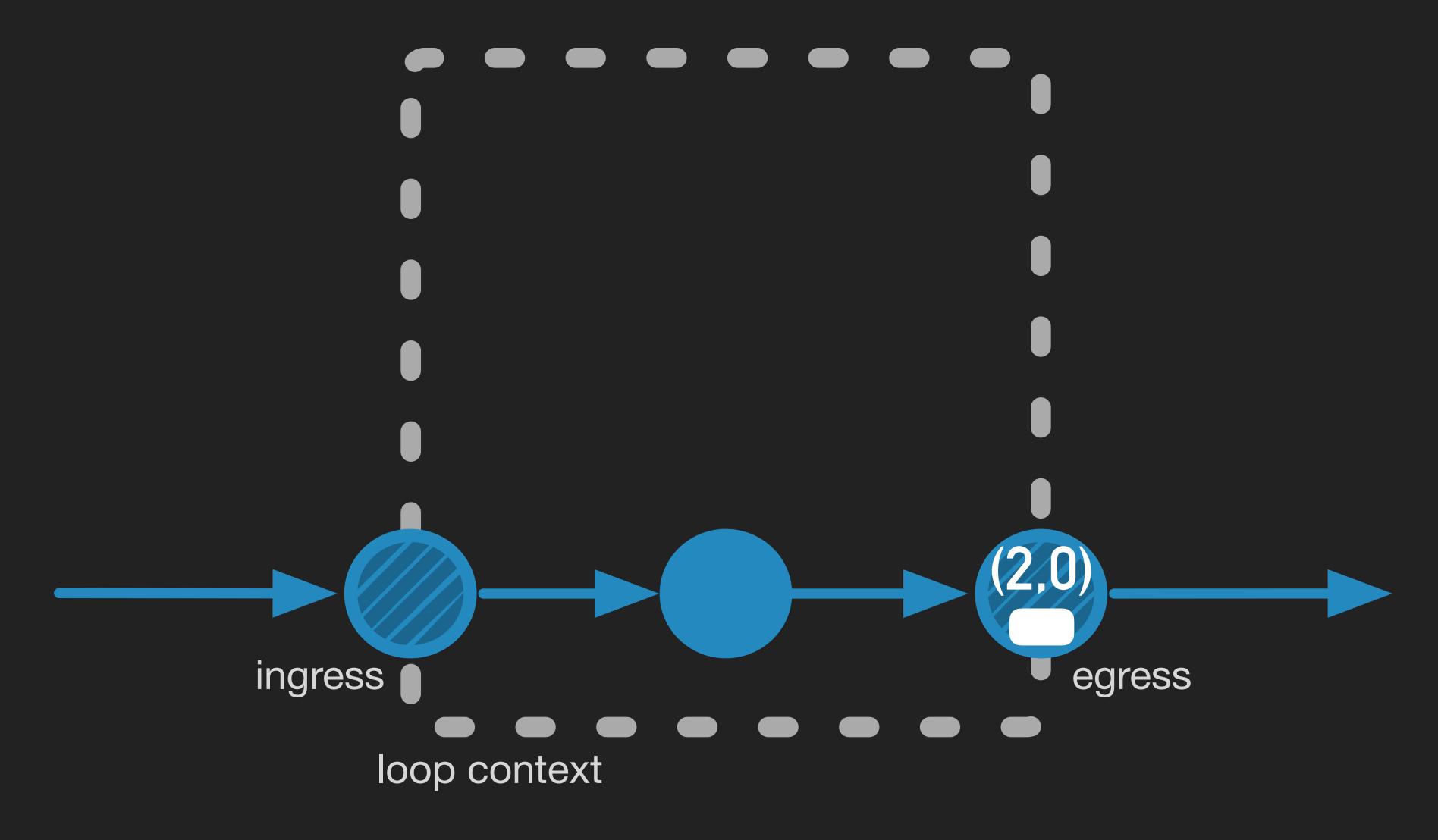


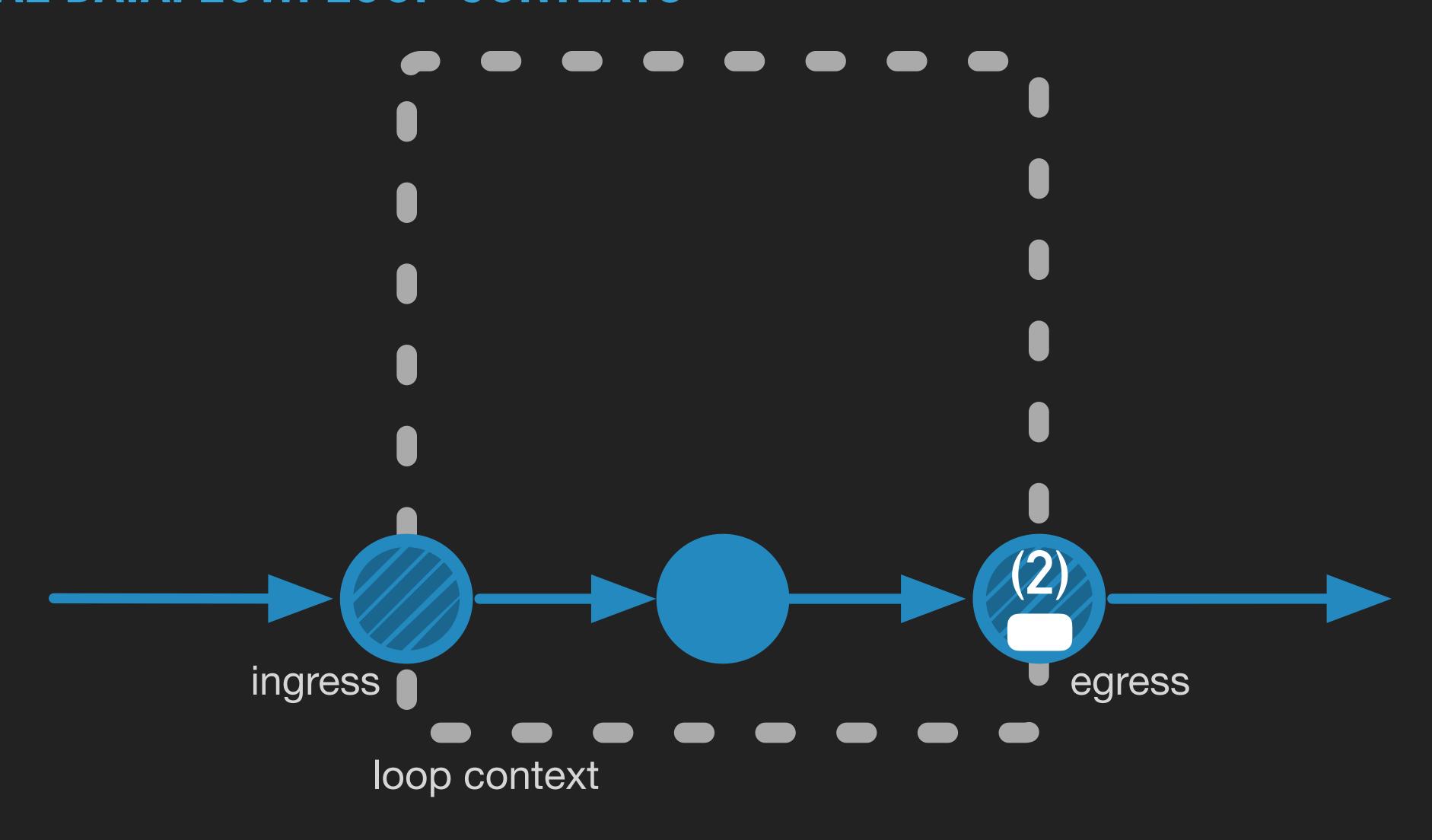


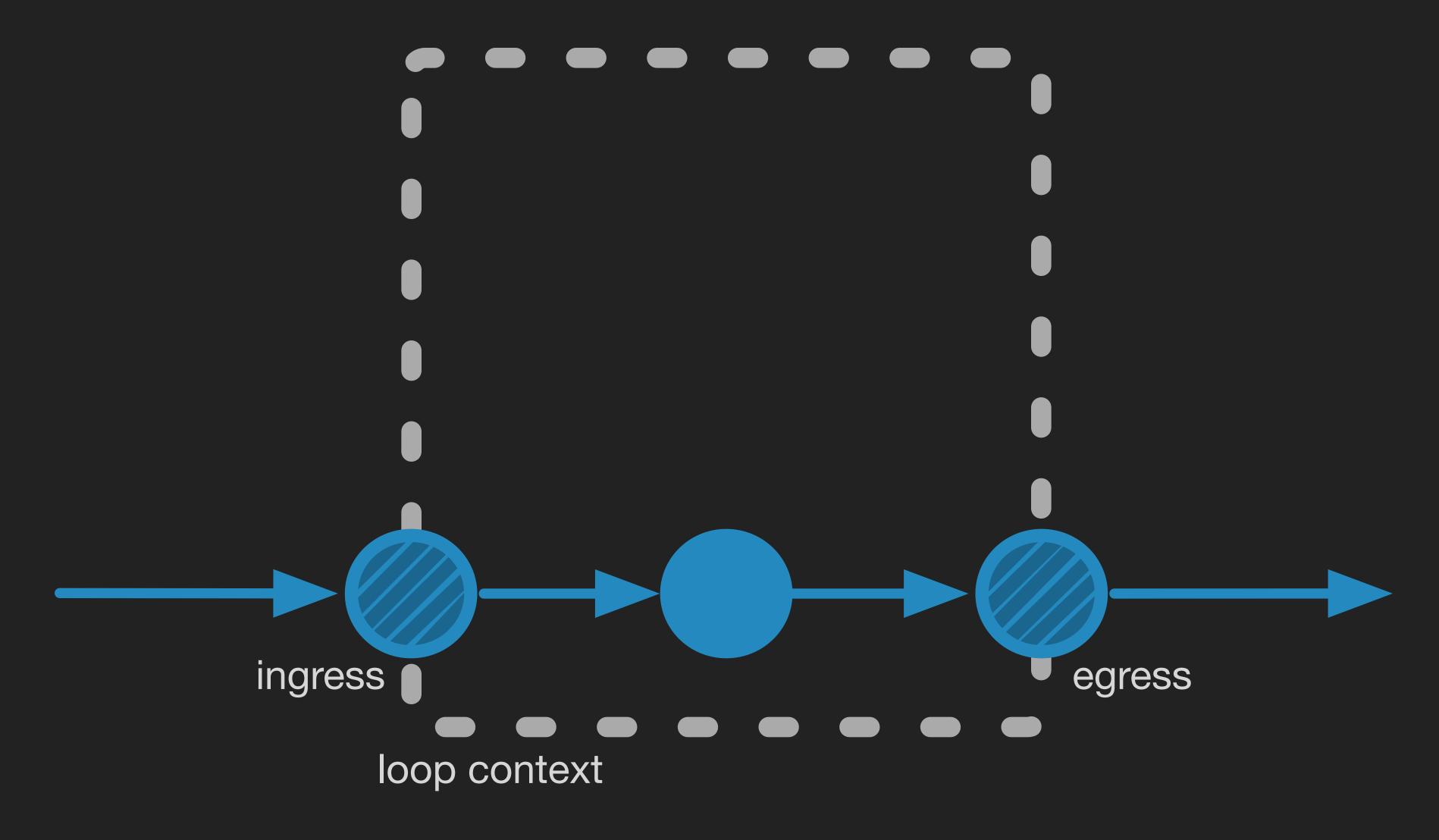


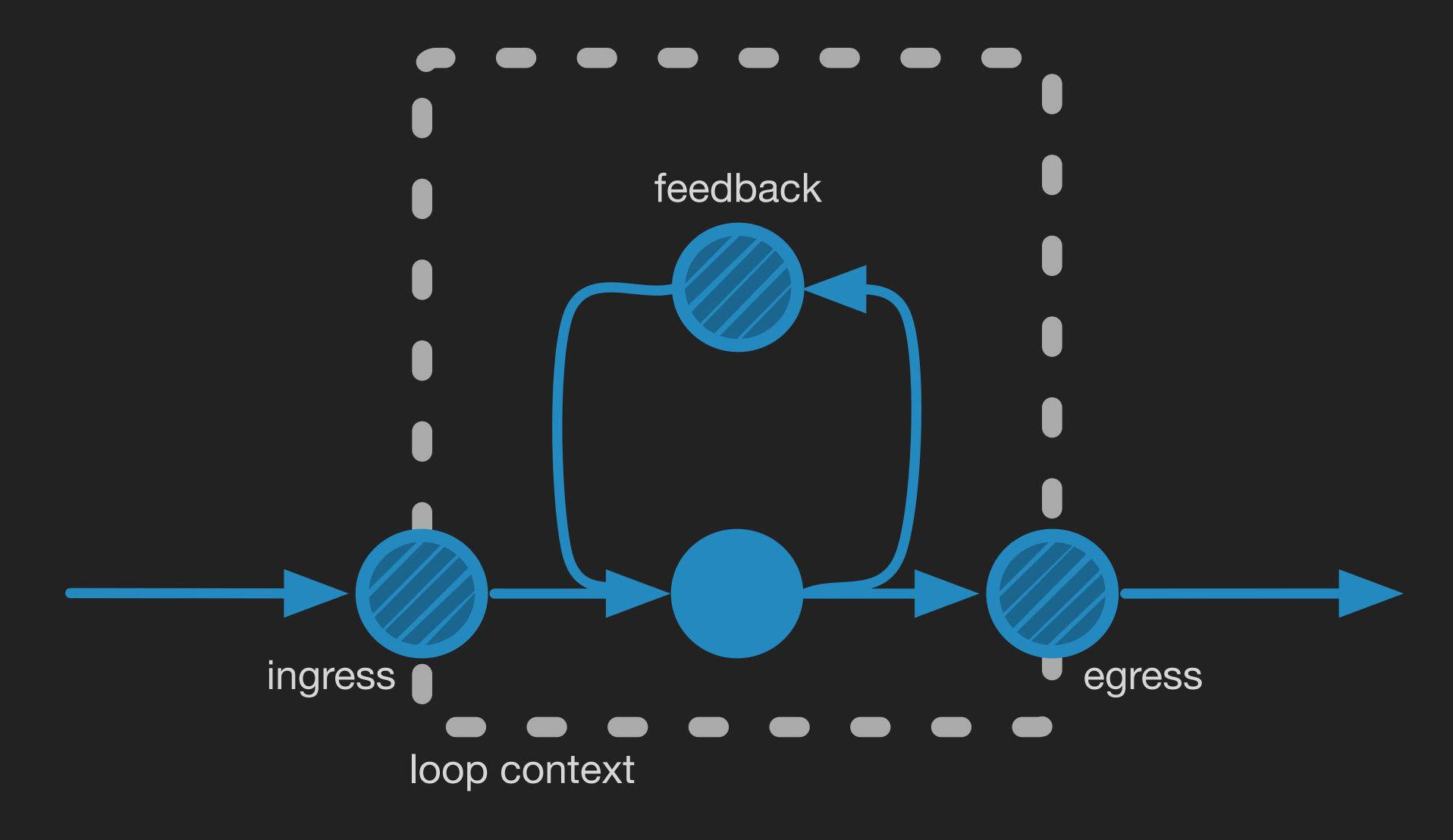


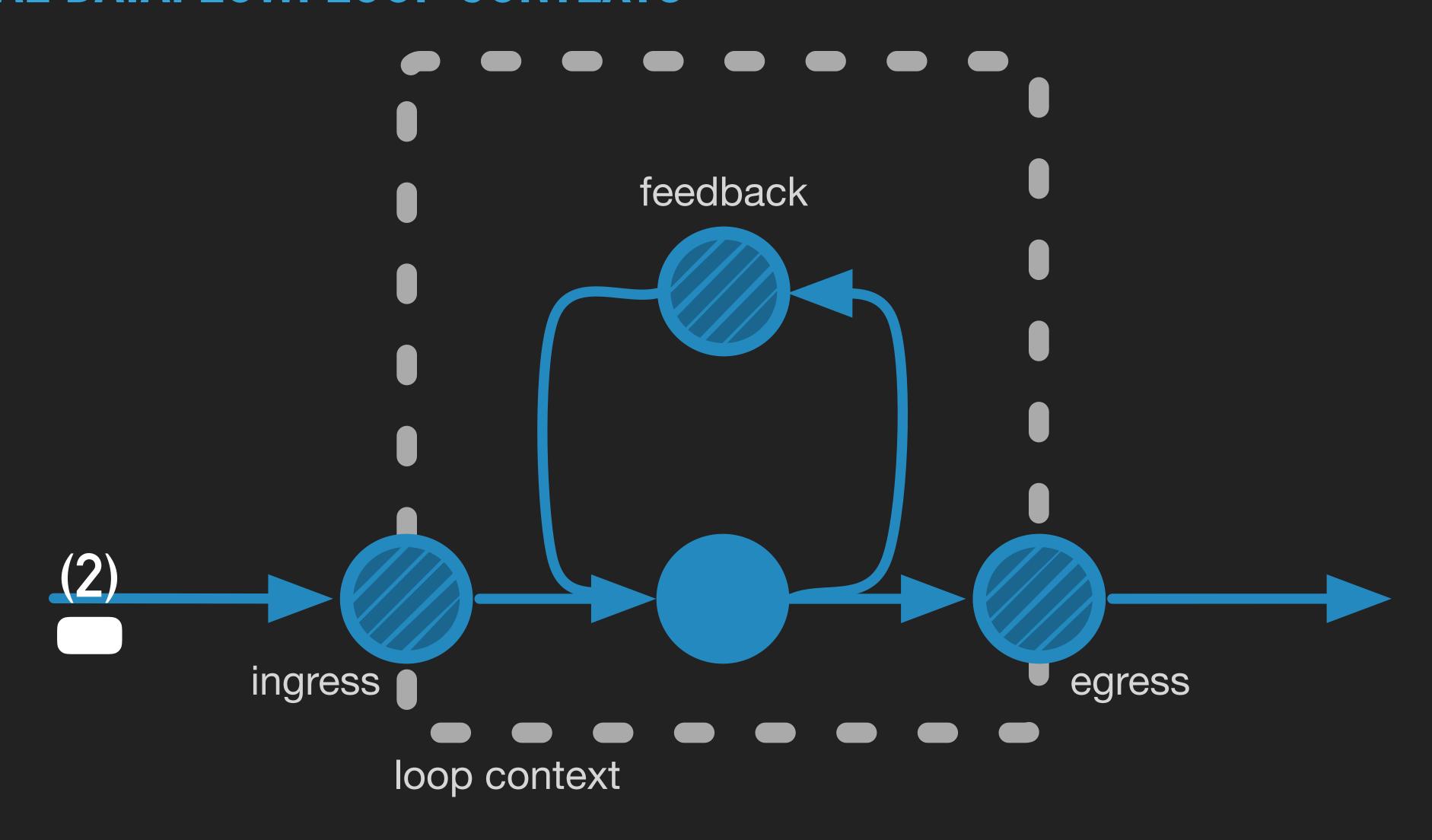


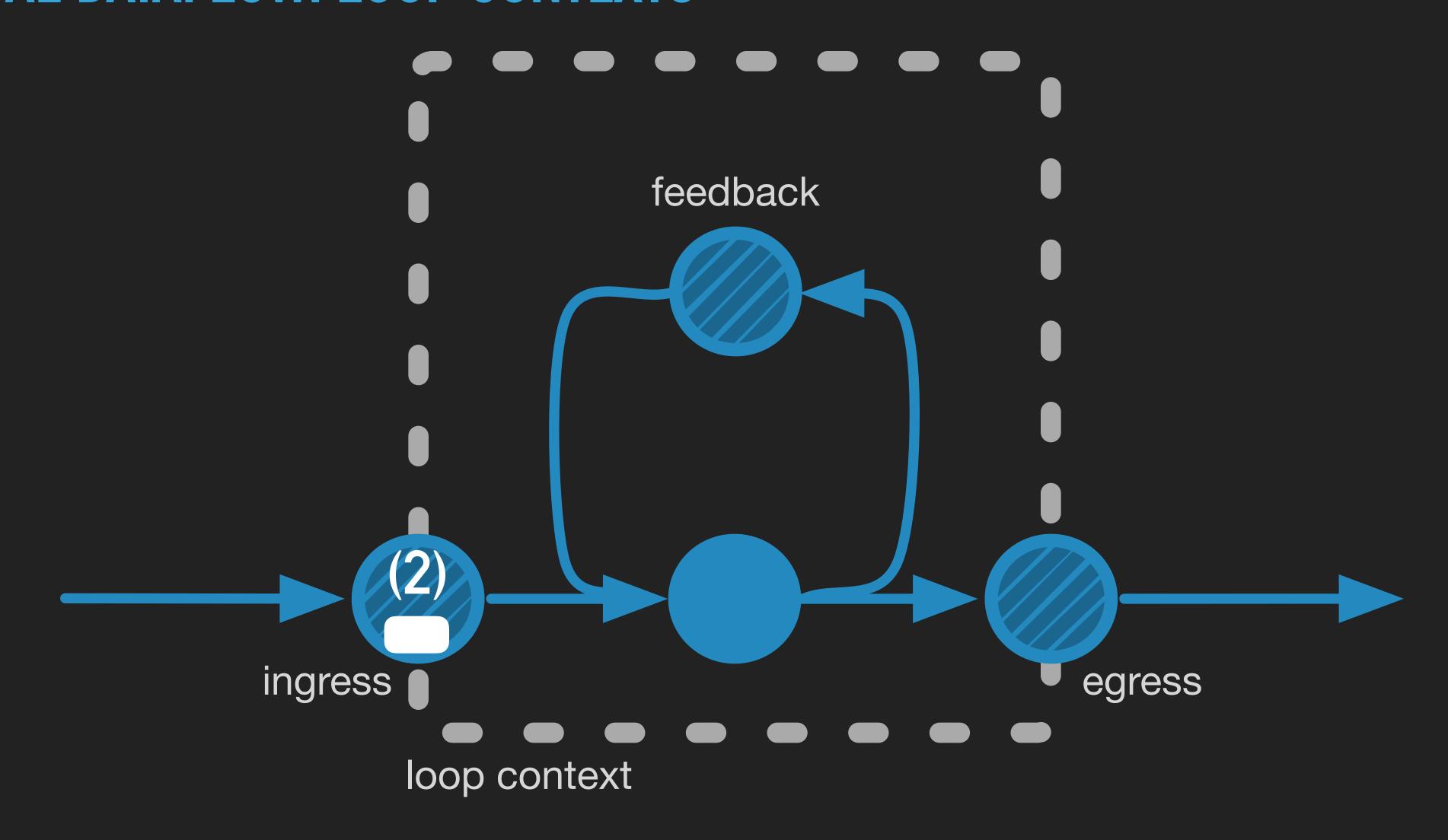


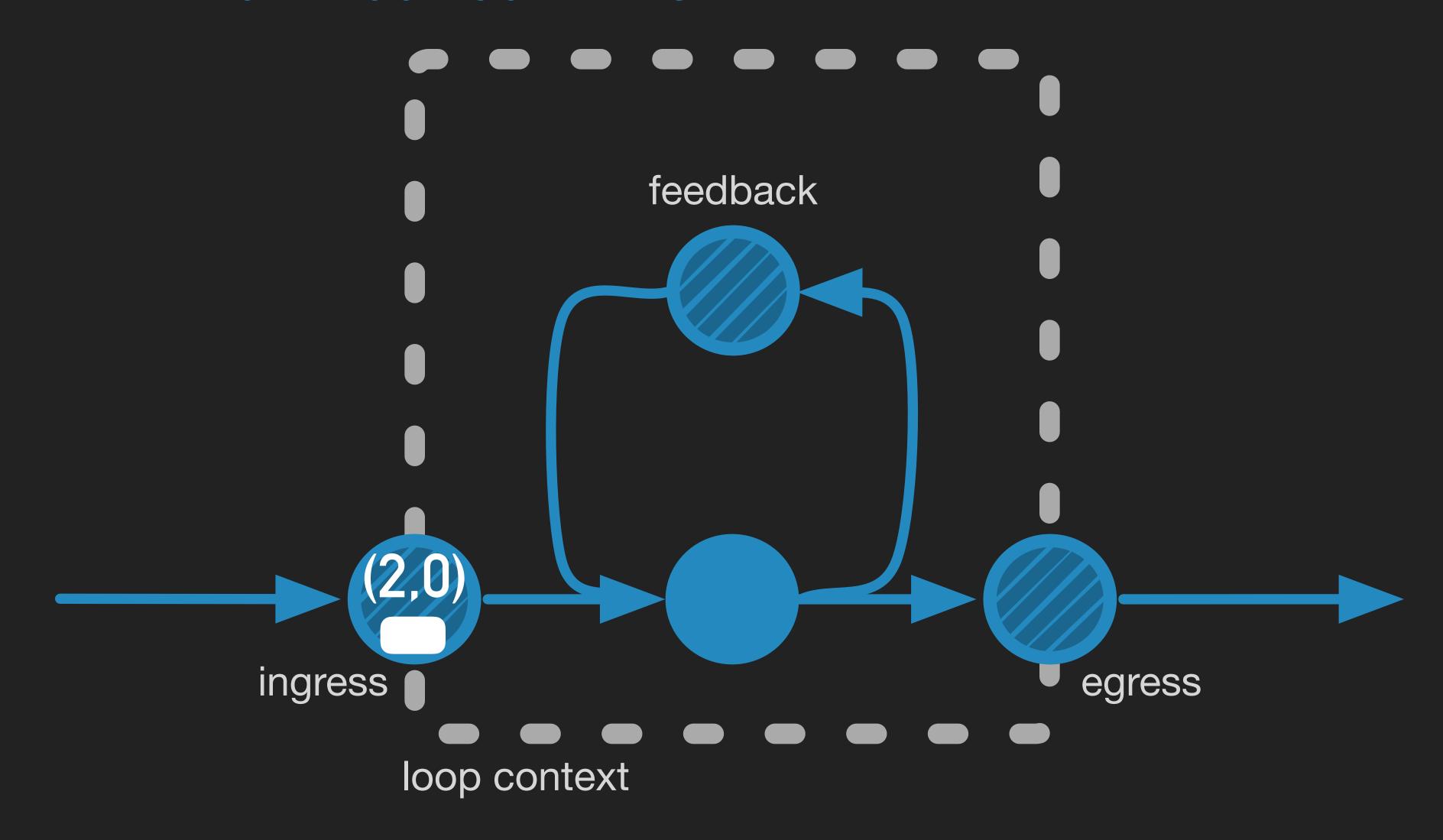


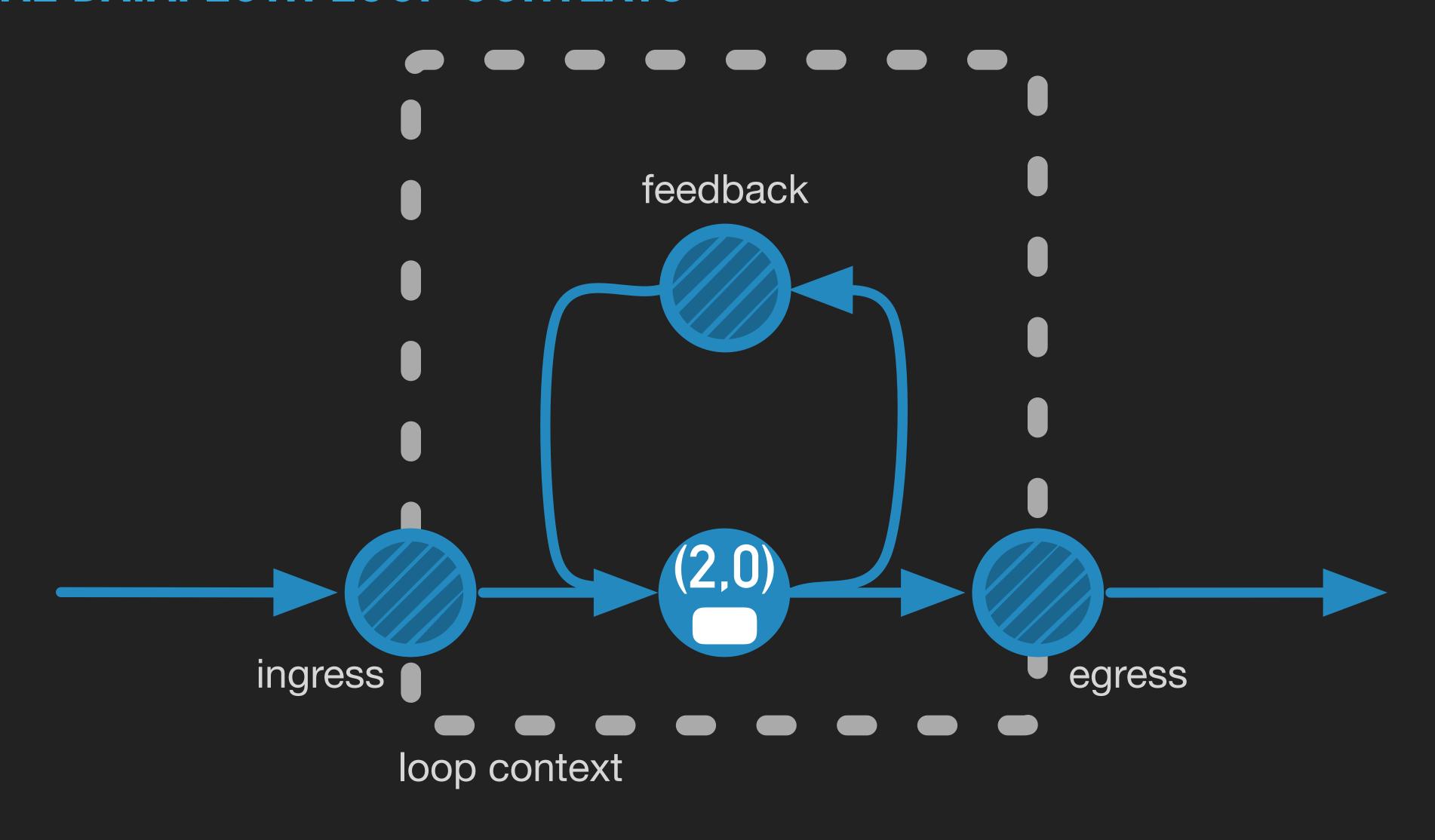


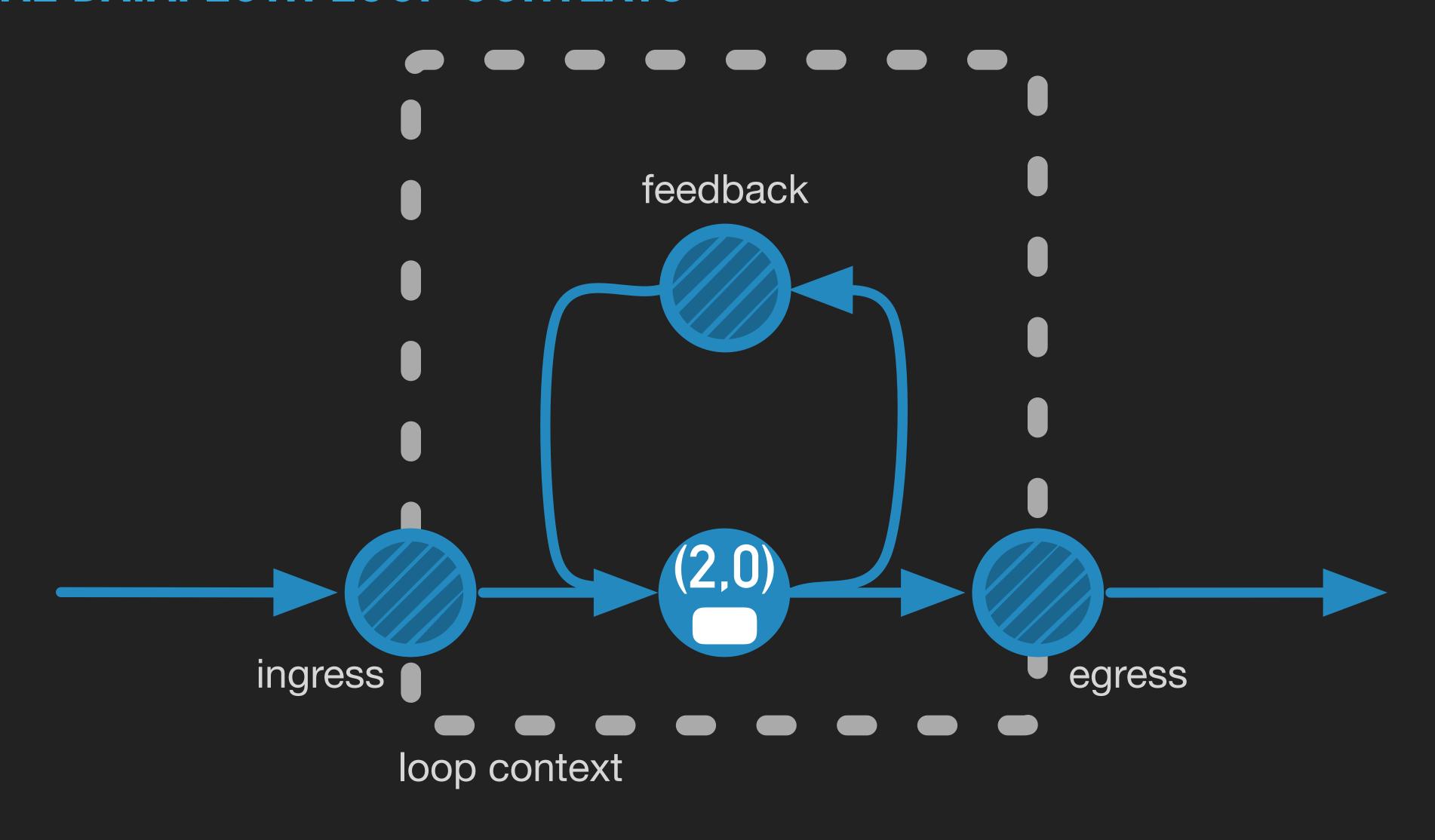


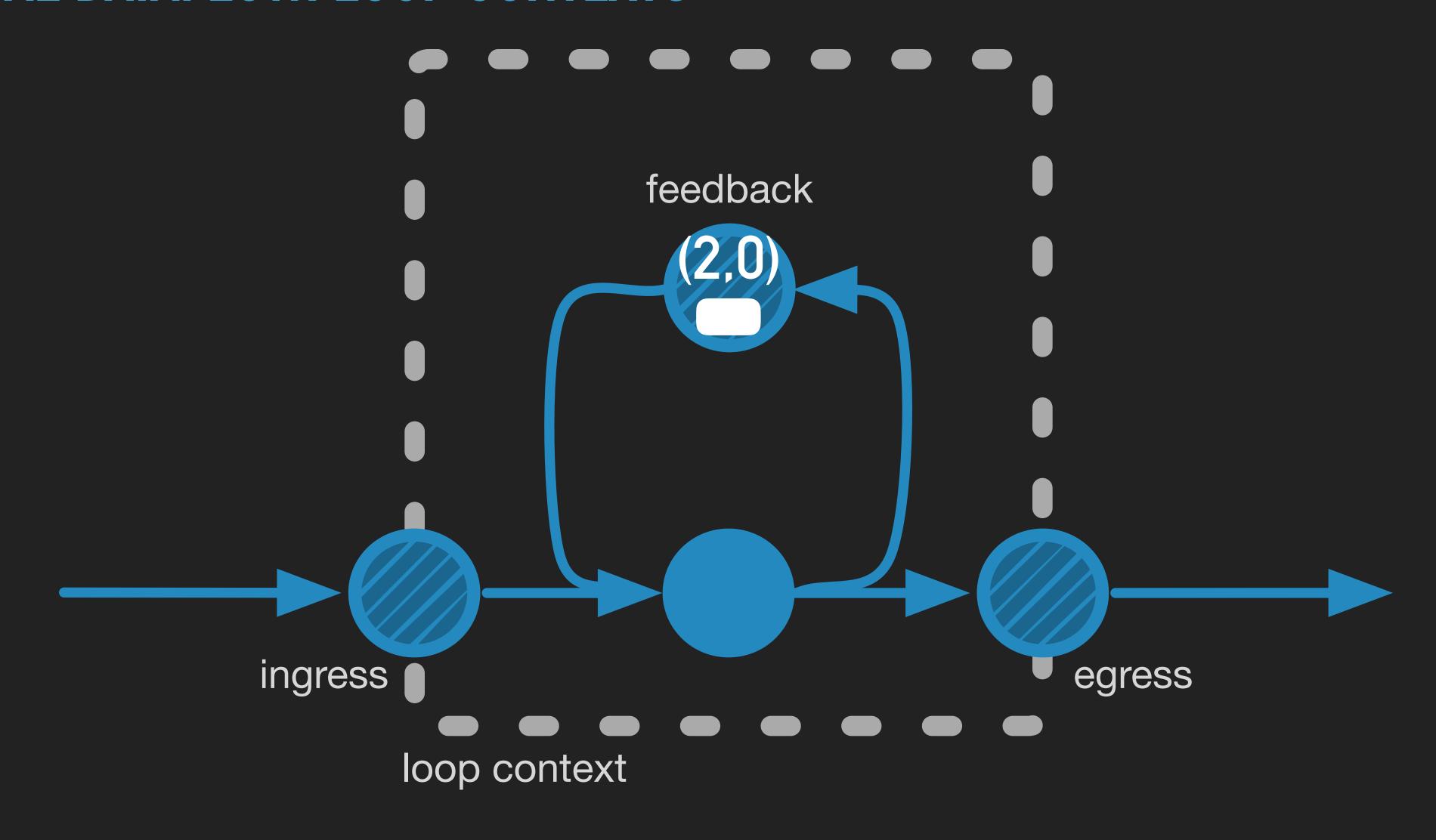


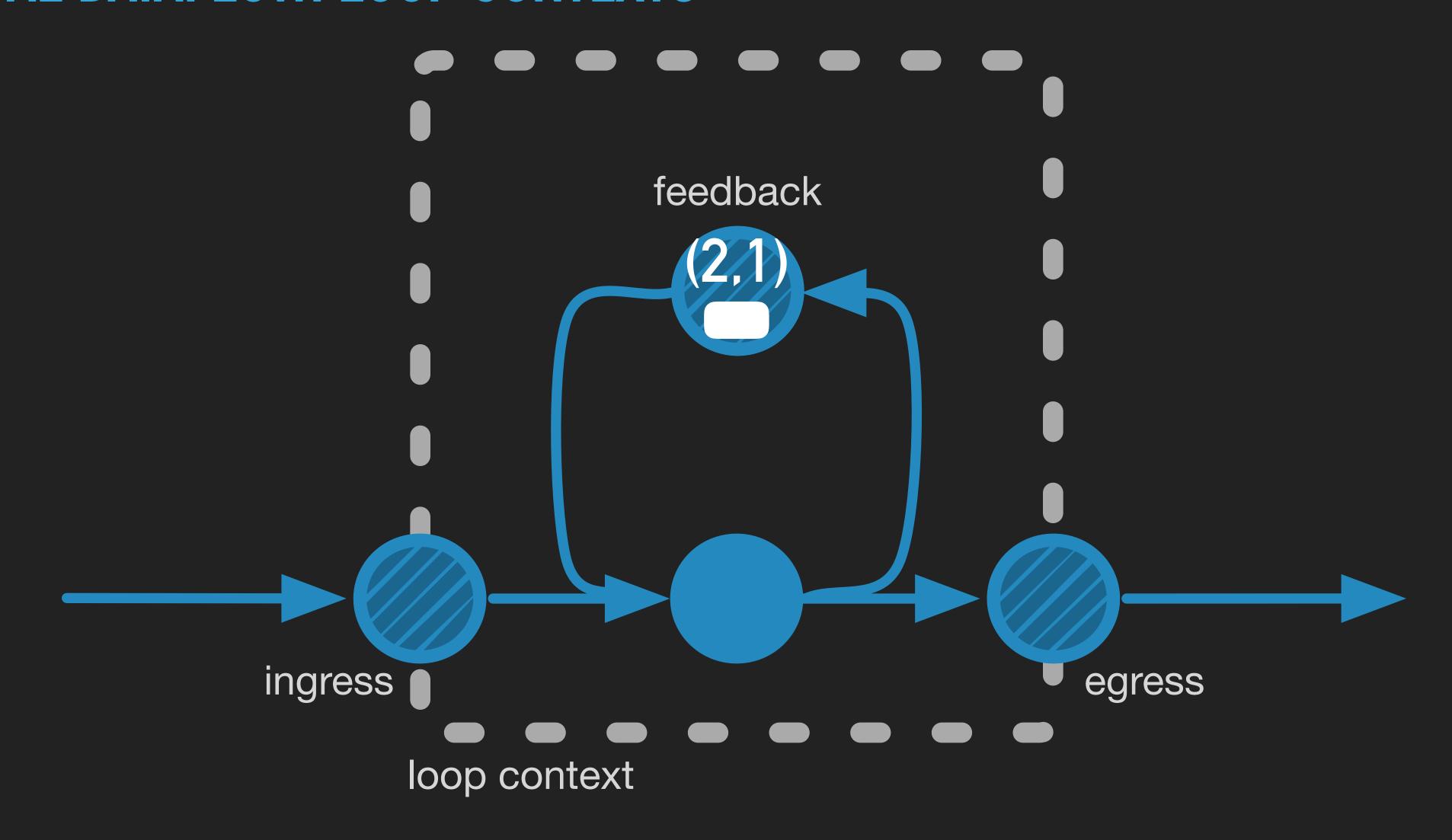


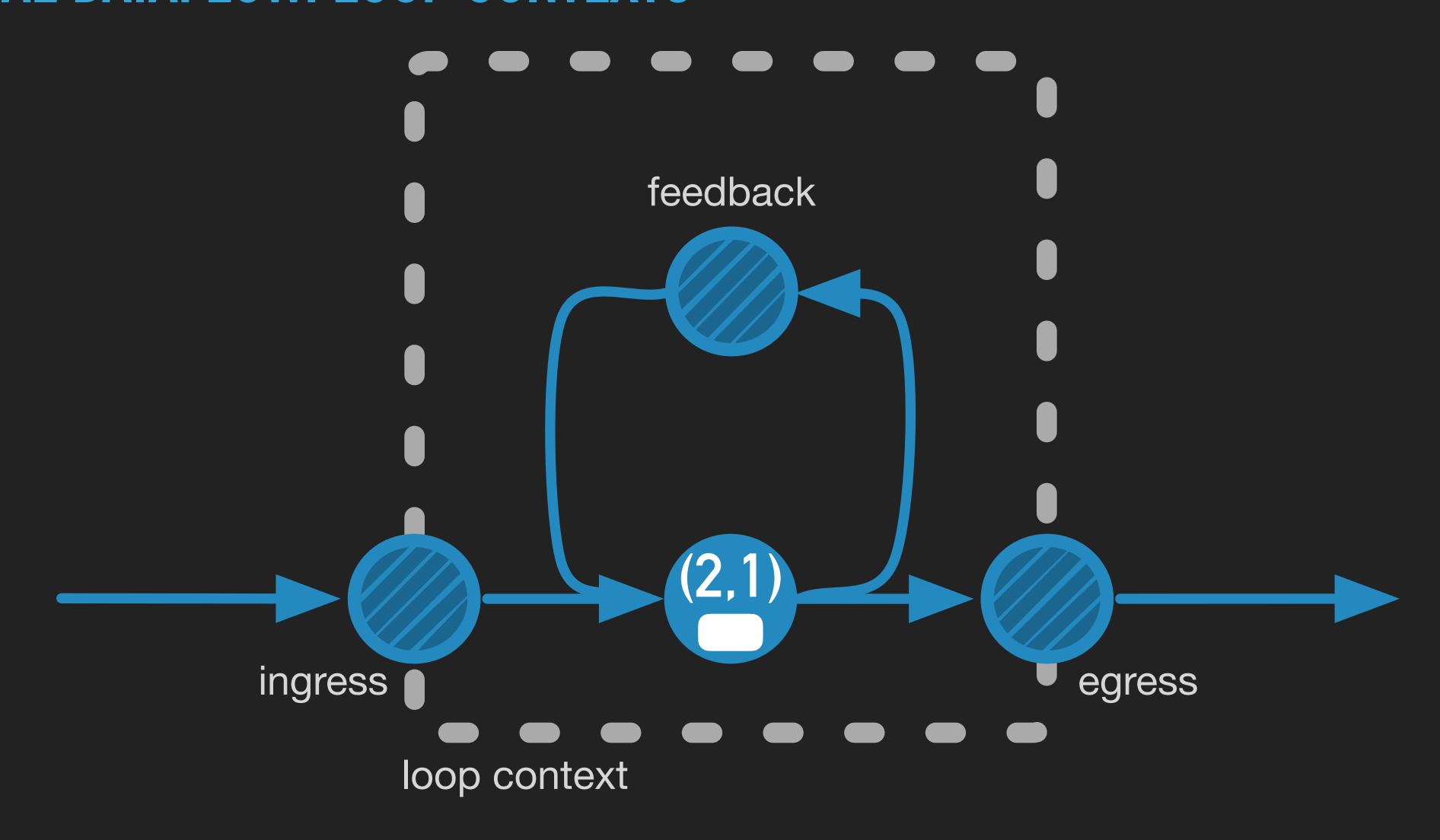


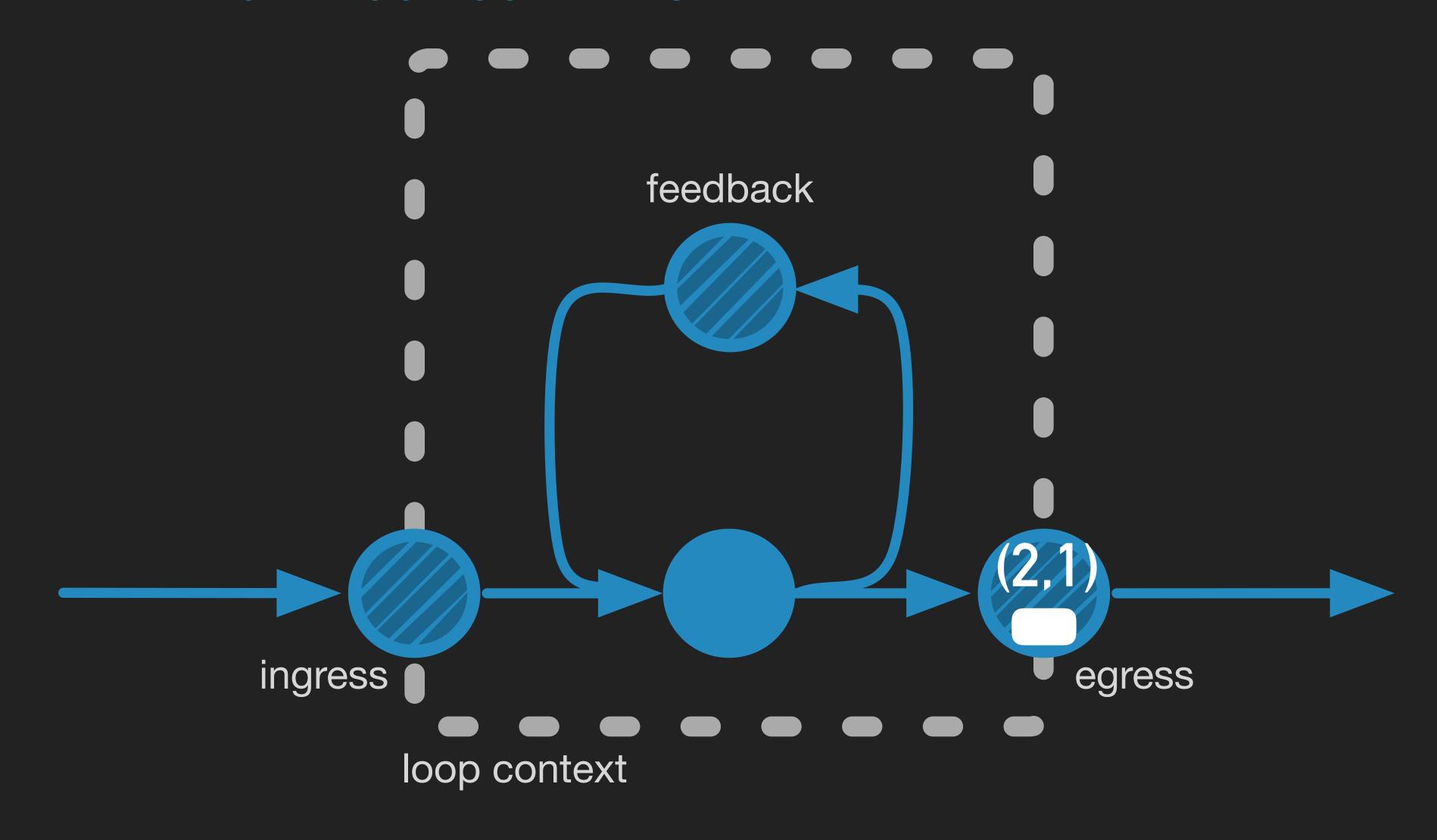


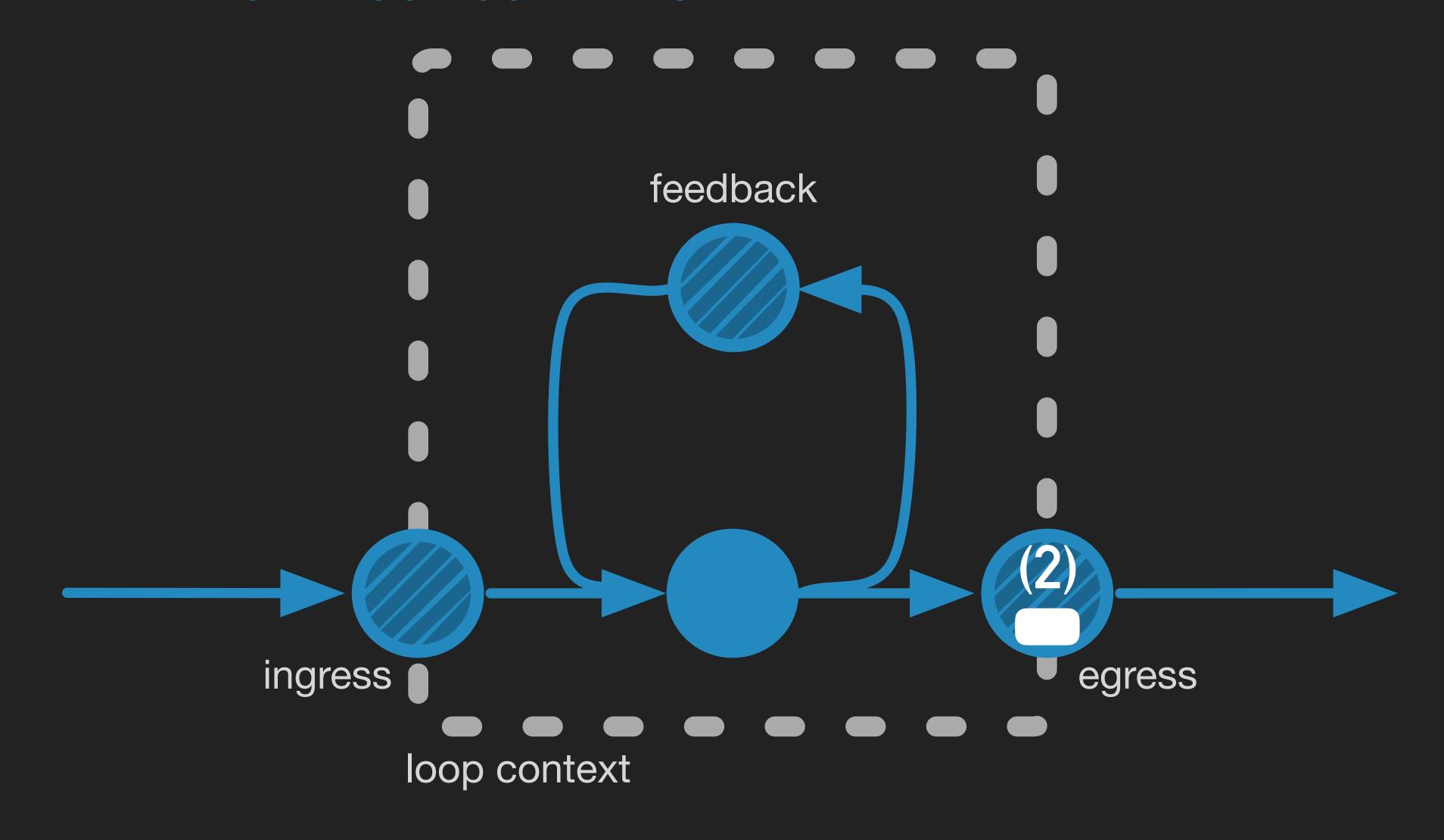


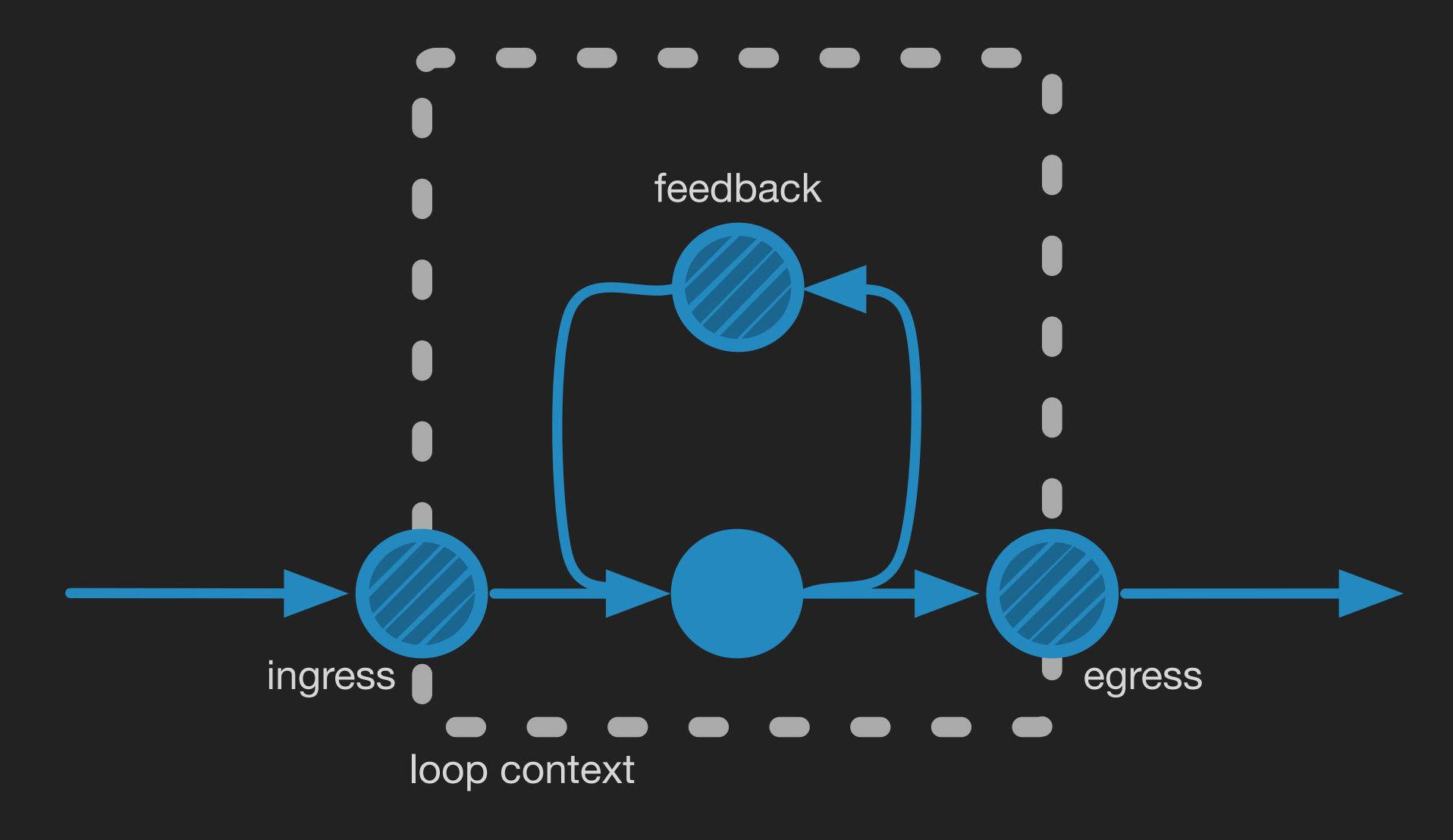


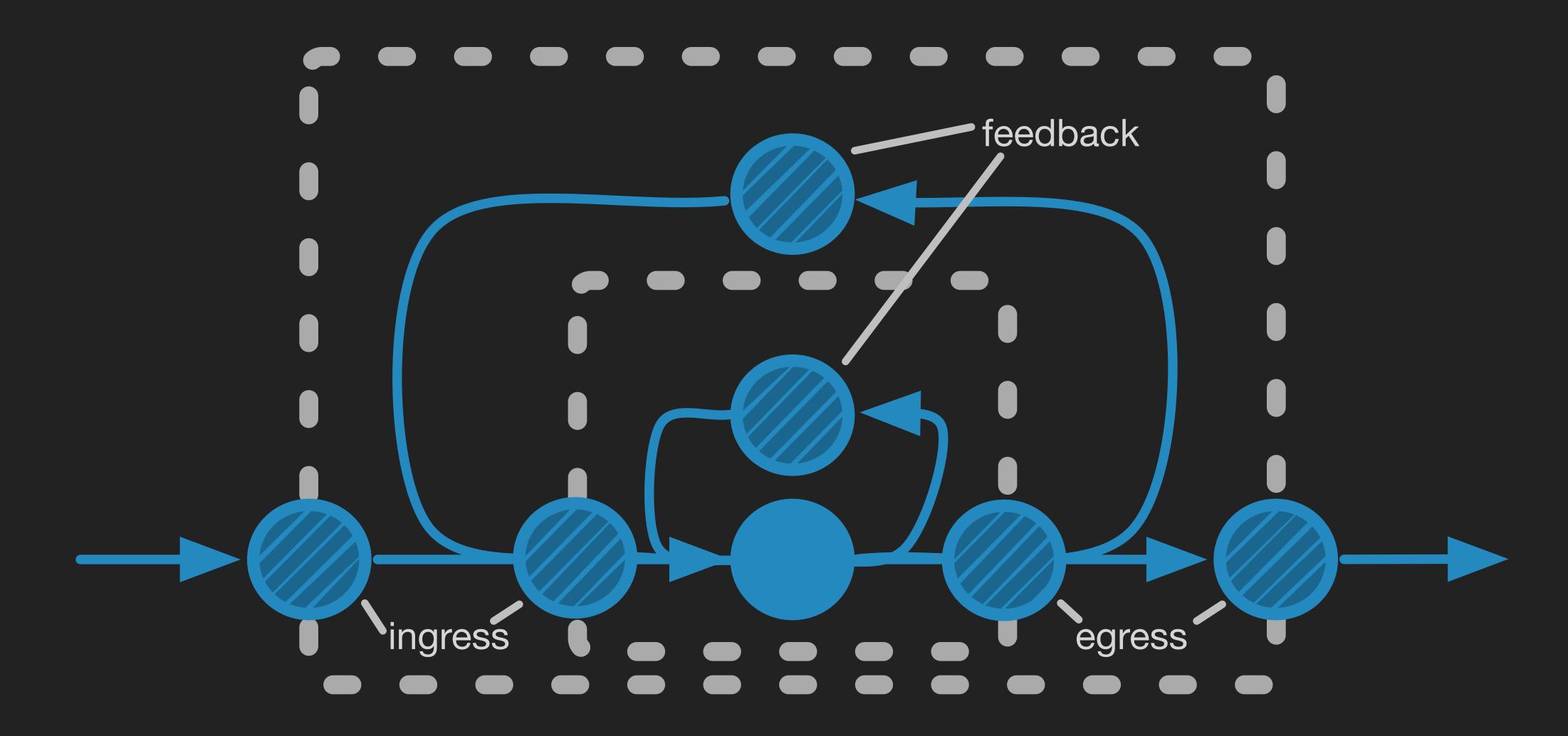


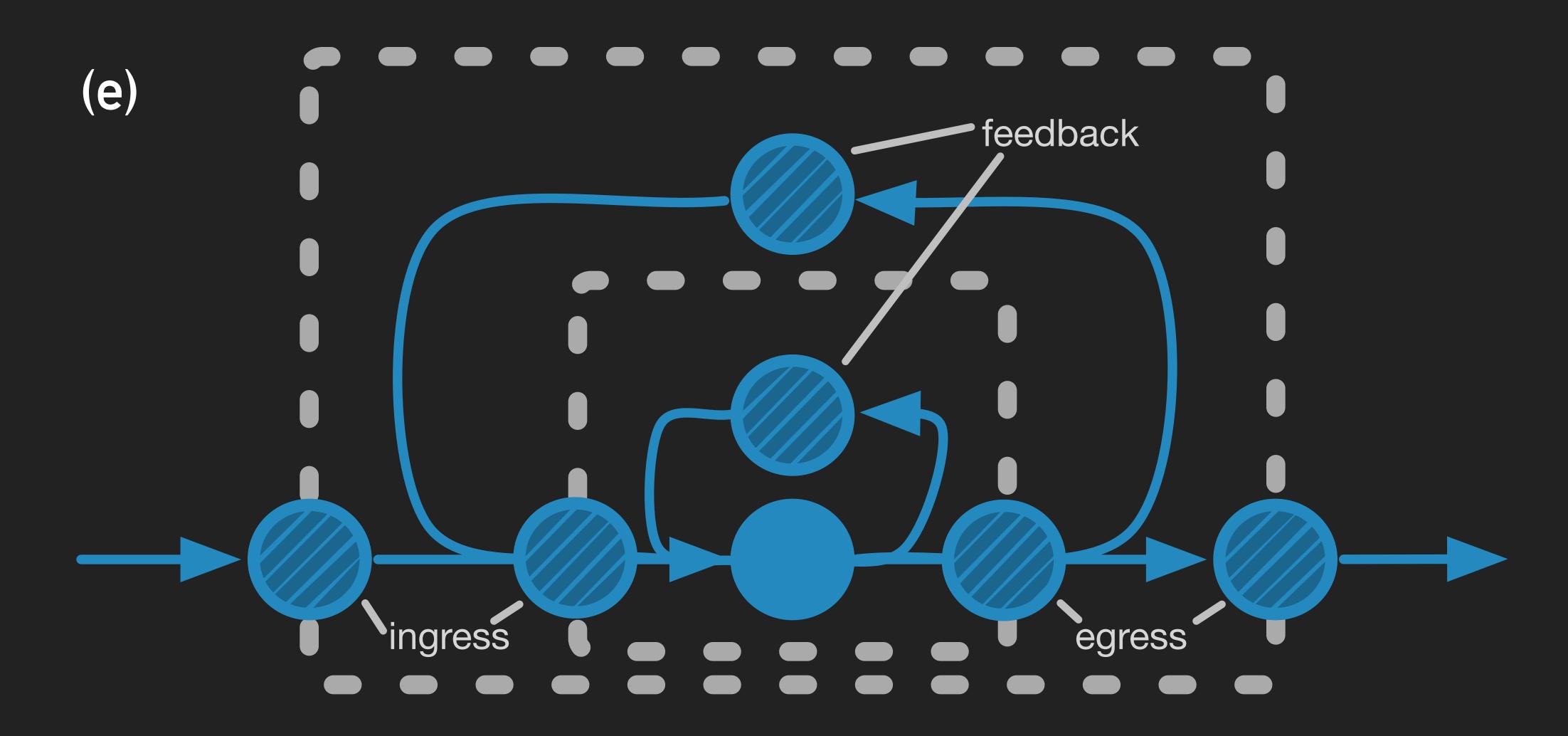


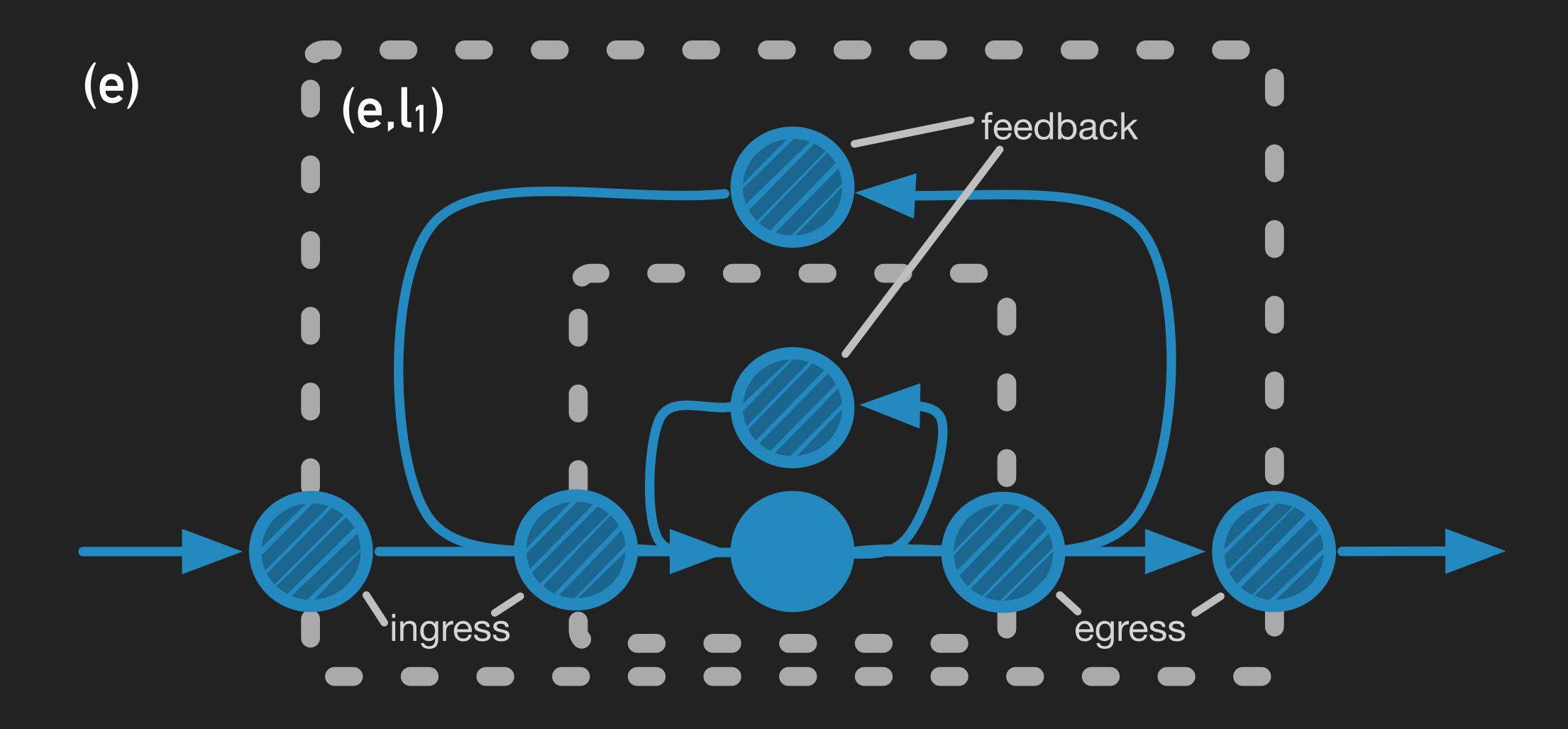


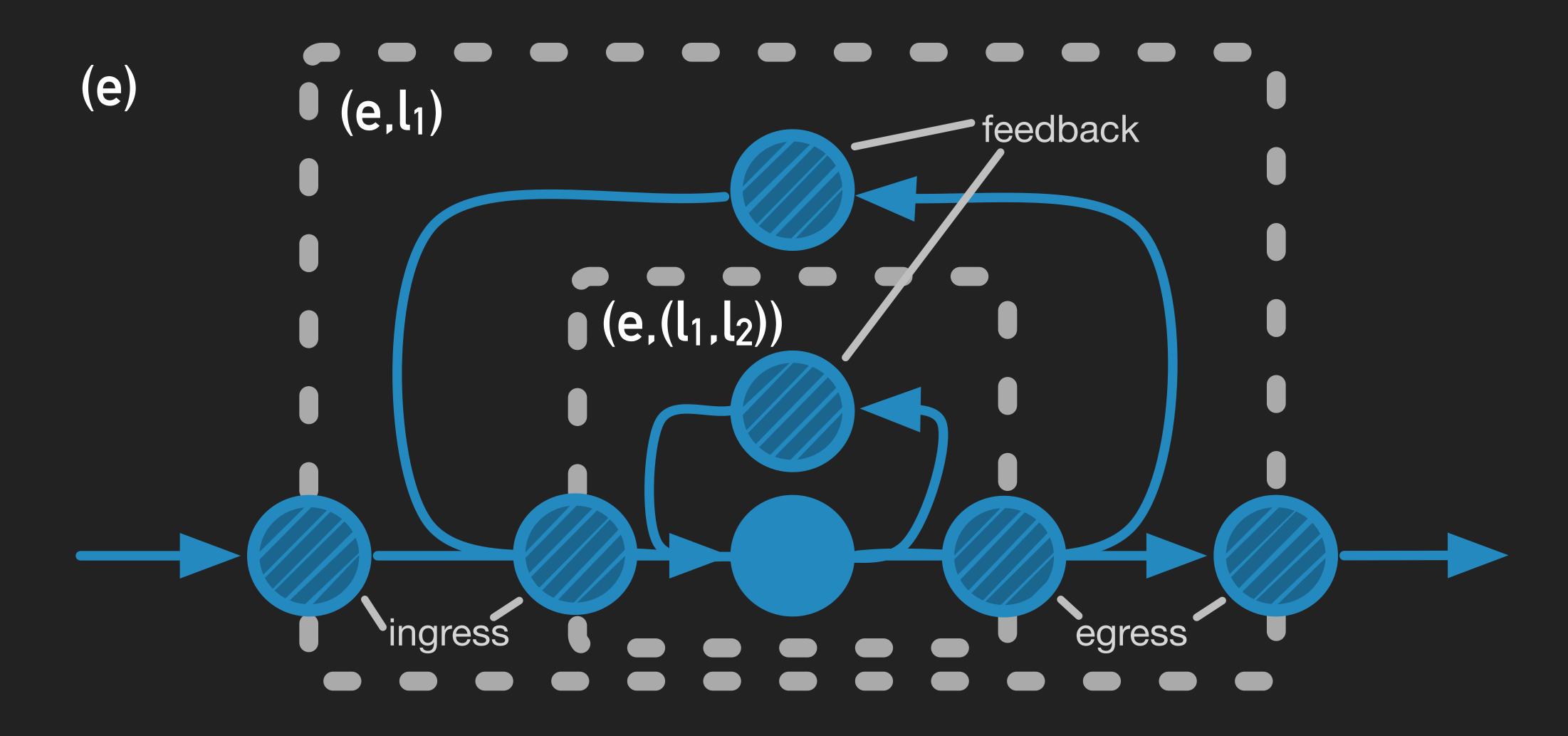












CYCLICAL DATAFLOW: TIMESTAMPS IN LOOP CONTEXTS

Input timestamp Vertex

Ingress

Egress

Feedback

 $(e,\langle c_1,\ldots,c_k\rangle)$

 $(e, \langle c_1, \ldots, c_k, c_{k+1} \rangle)$

 $(e,\langle c_1,\ldots,c_k\rangle)$

Output timestamp

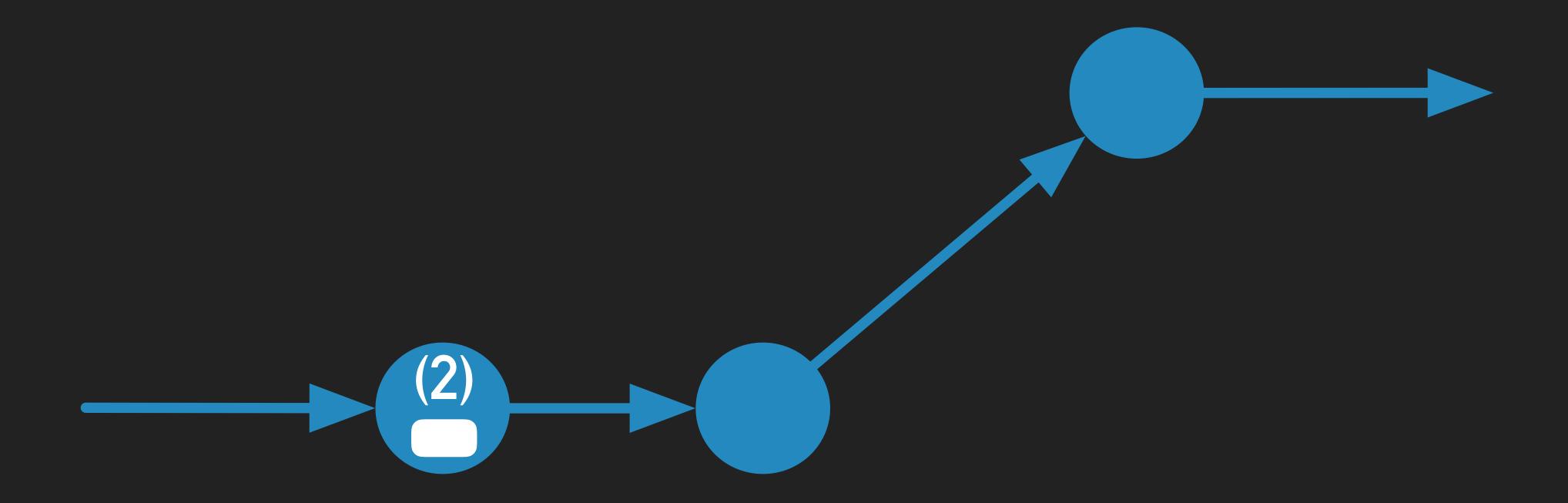
 $(e,\langle c_1,\ldots,c_k,0\rangle)$

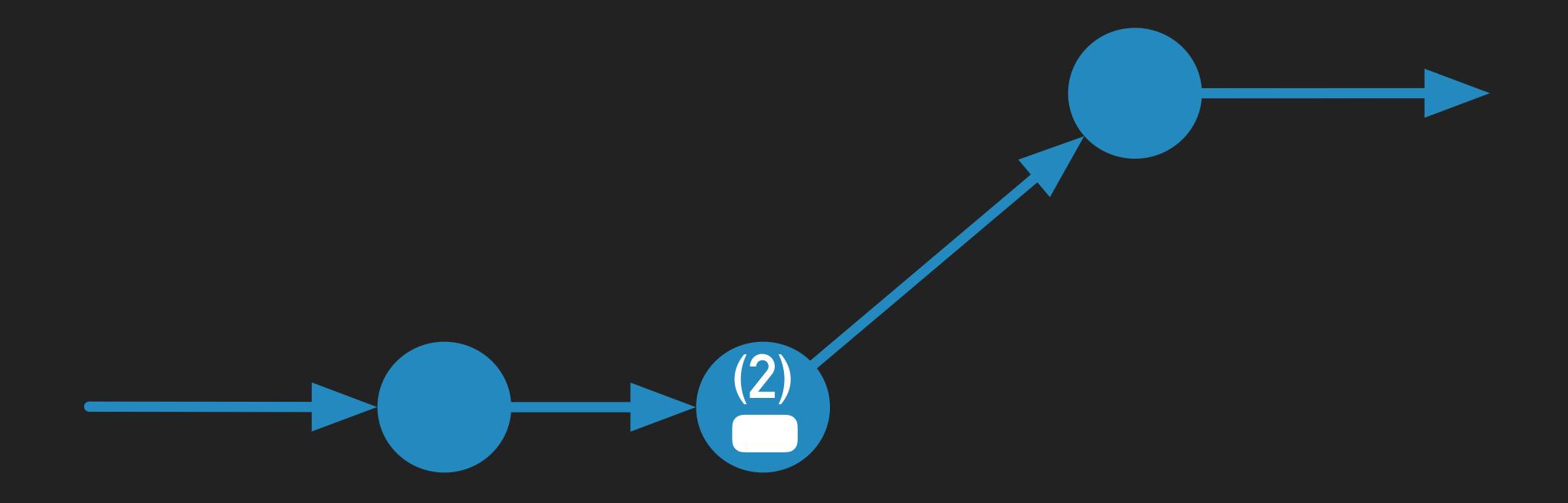
 $(e,\langle c_1,\ldots,c_k\rangle)$

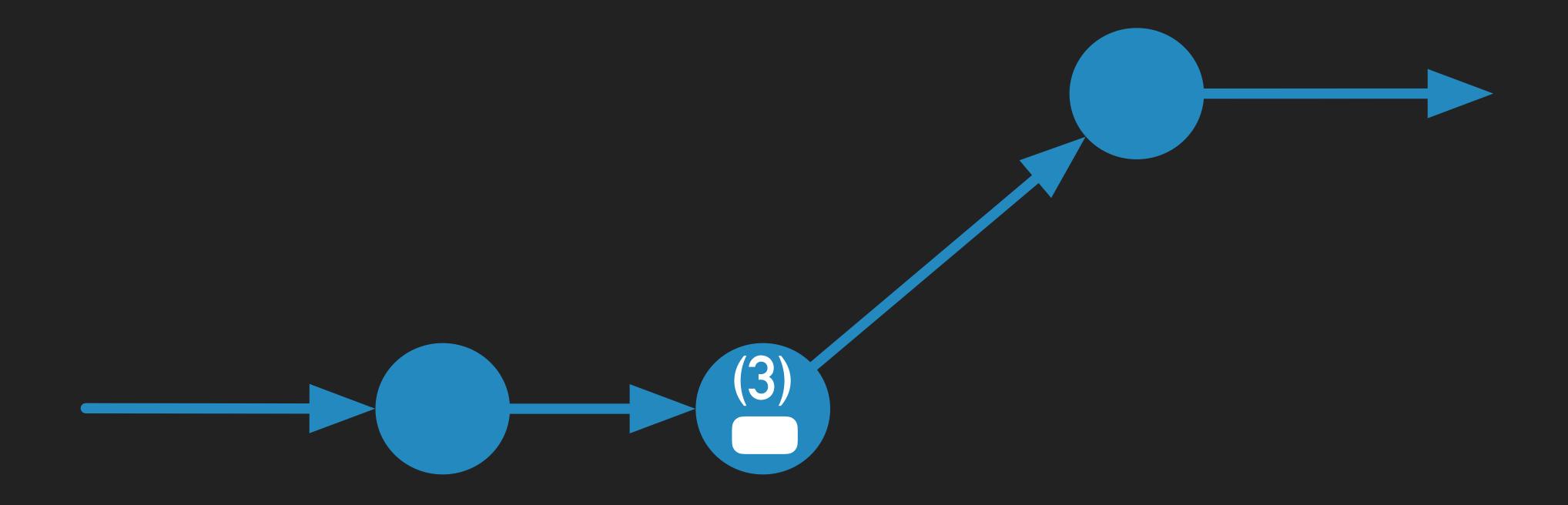
 $(e,\langle c_1,\ldots,c_k+1\rangle)$

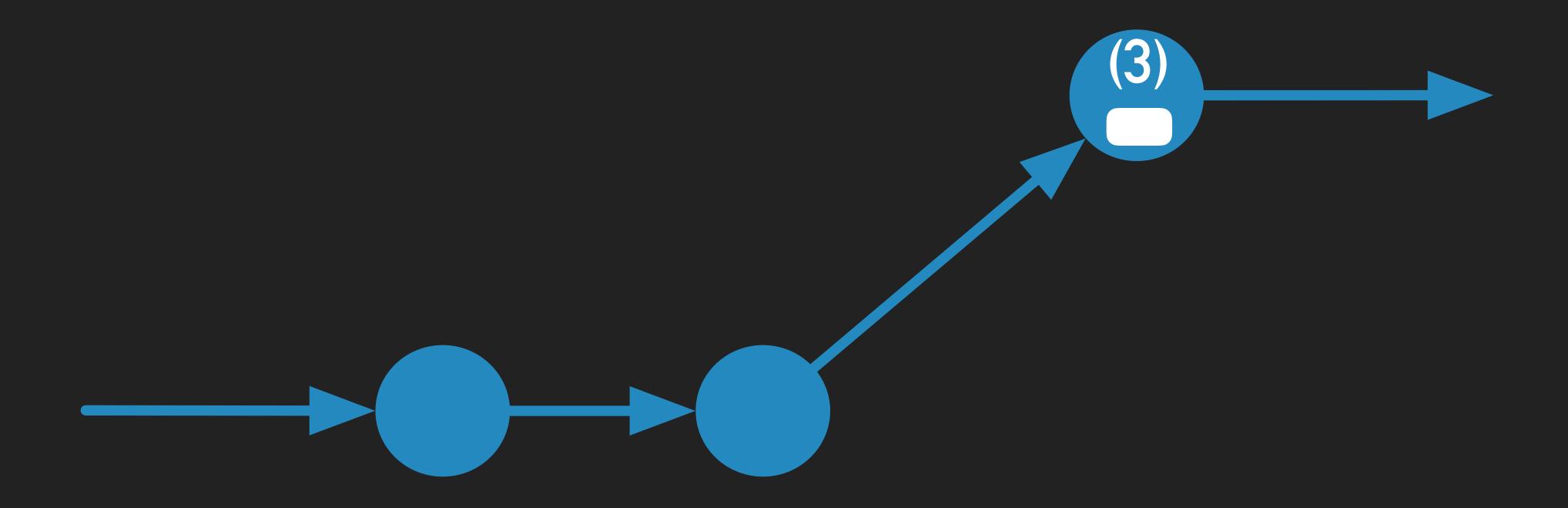
For two timestamps $t_1 = (e_1, c_1)$ and $t_2 = (e_2, c_2)$

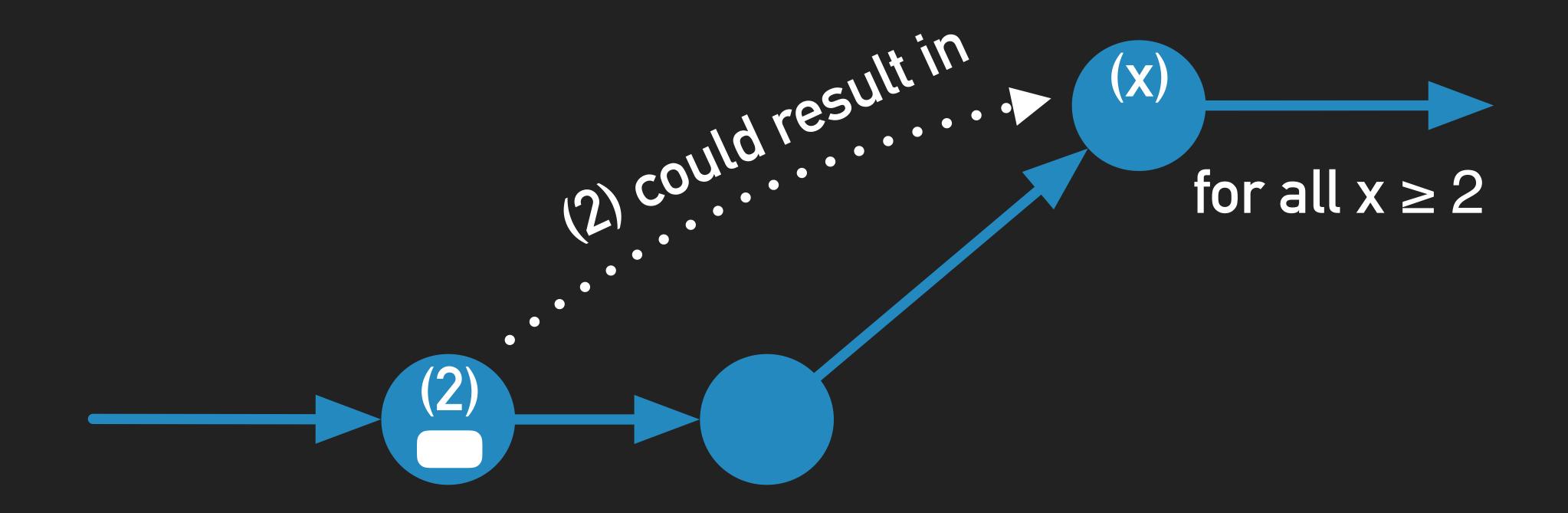
 $t_1 \le t_2$ iff. $e_1 \le e_2$ and $c_1 \le c_2$

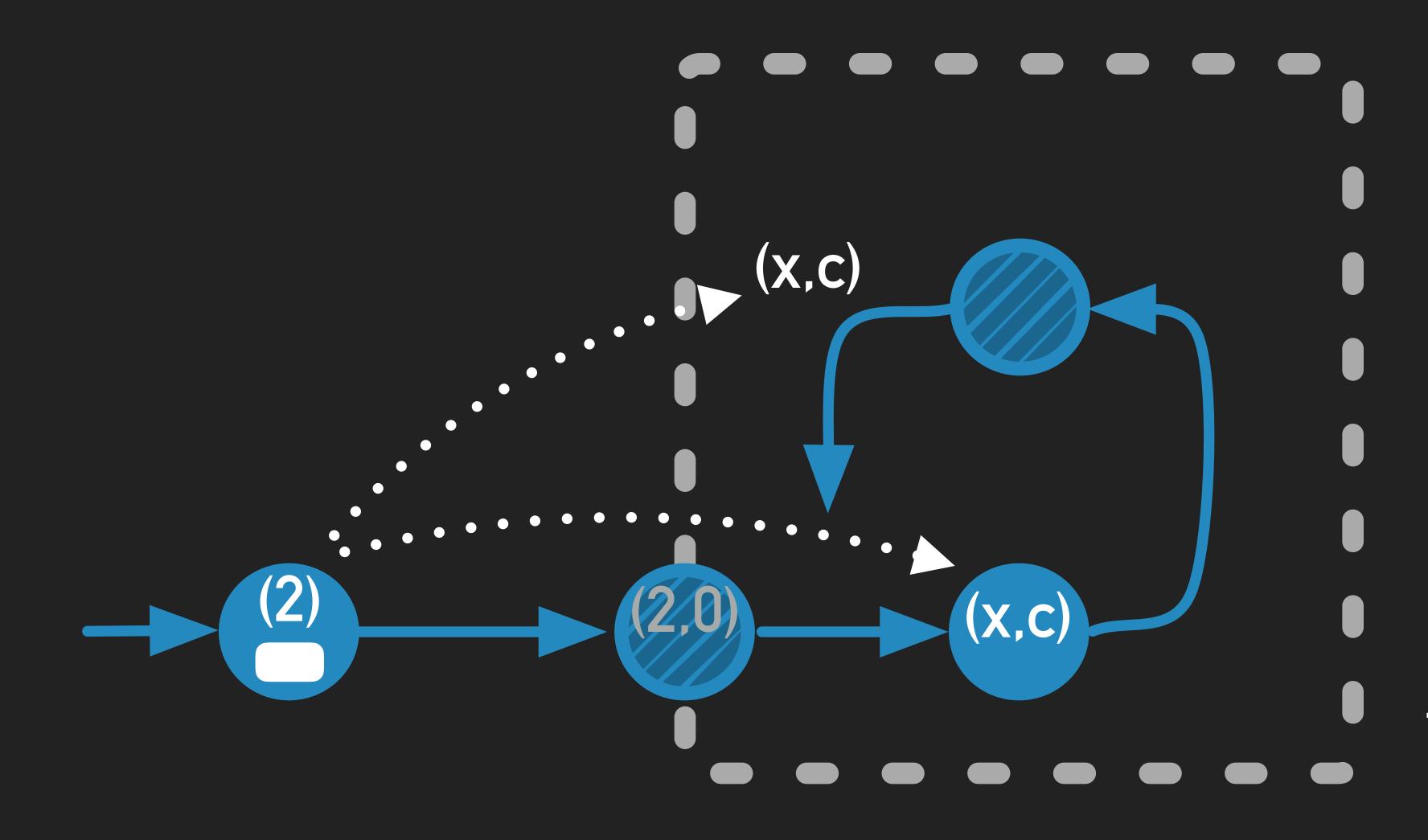






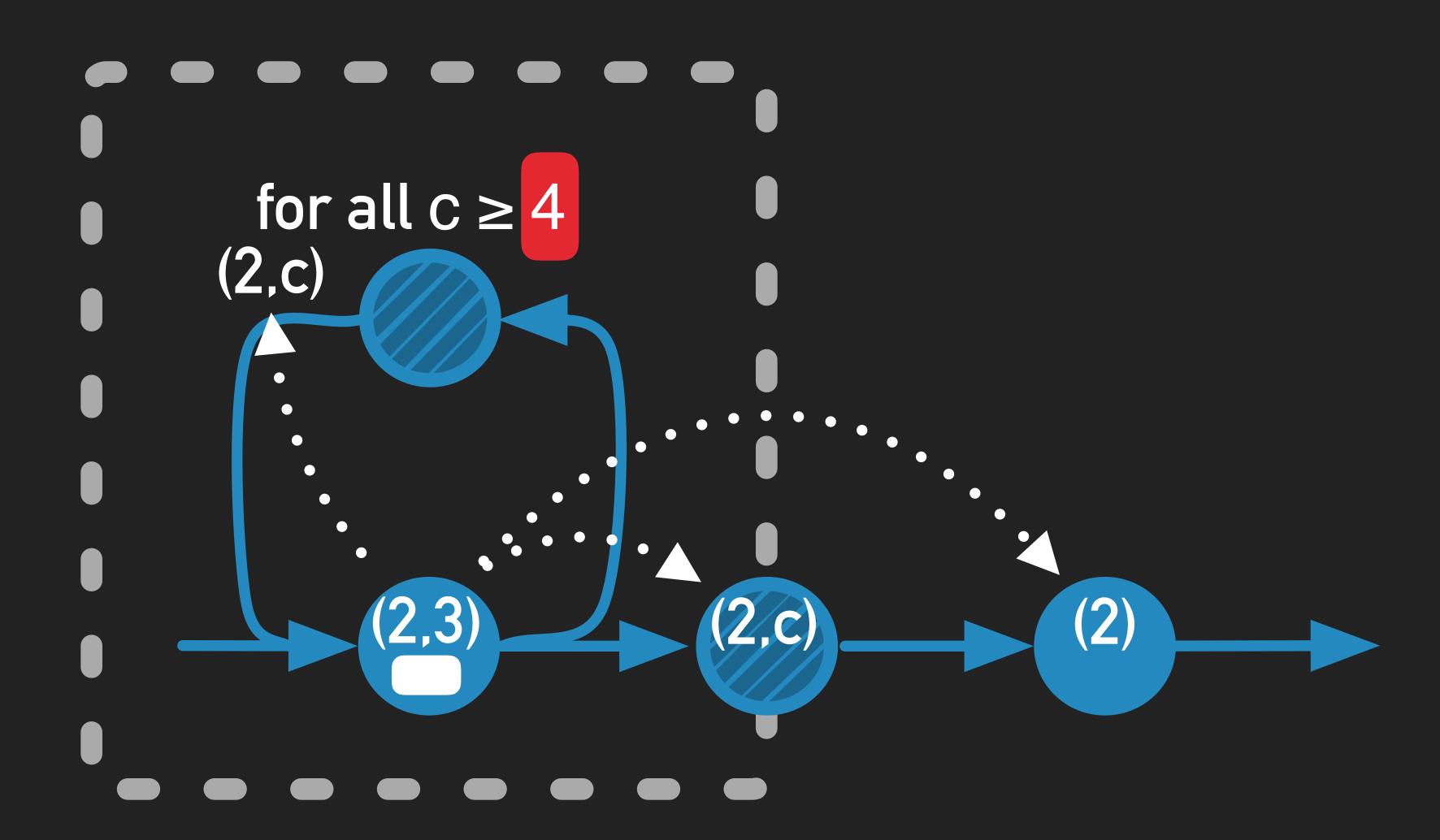


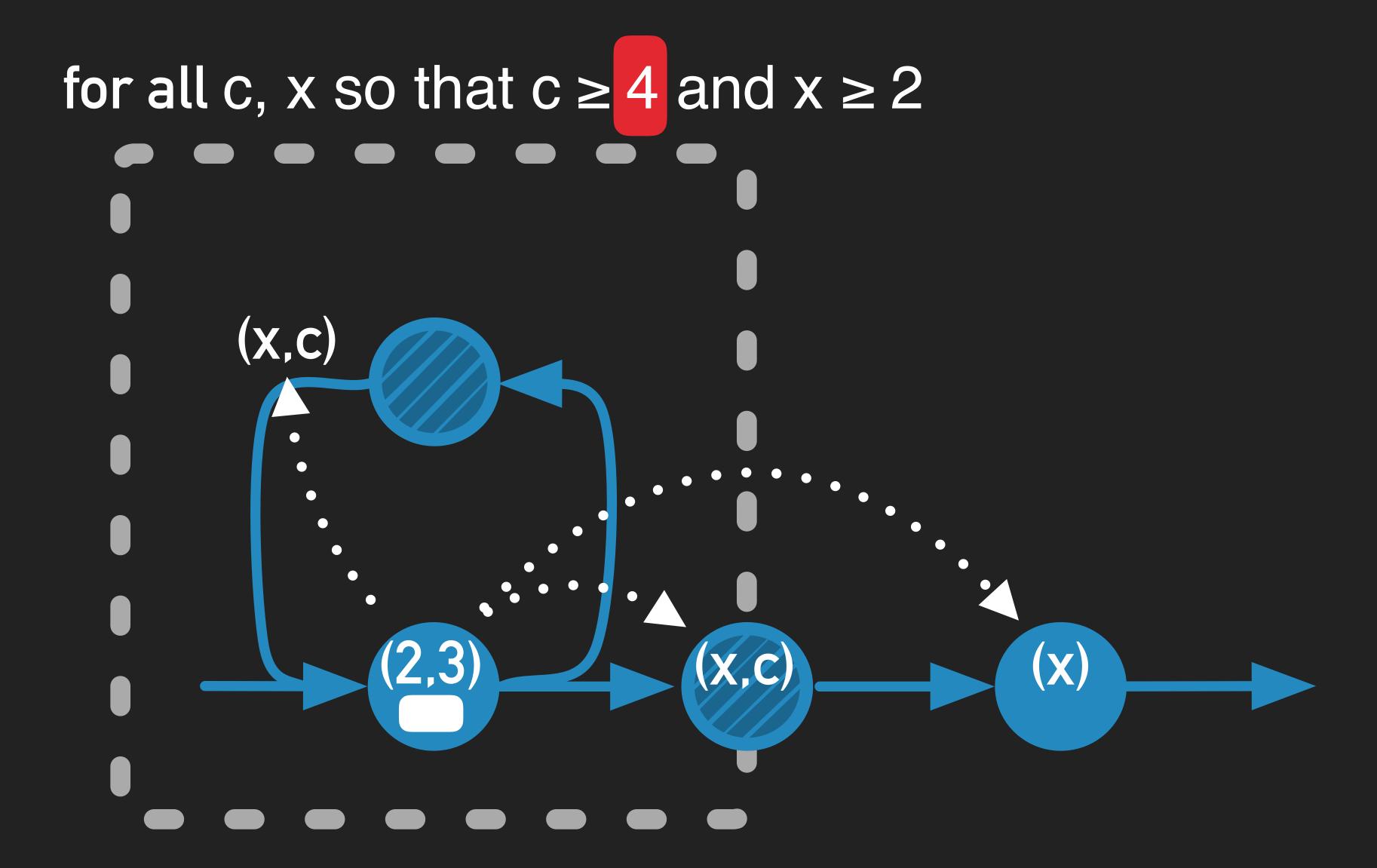




for all $x \ge 2$, $c \ge 0$

$$(e = 2, c)$$



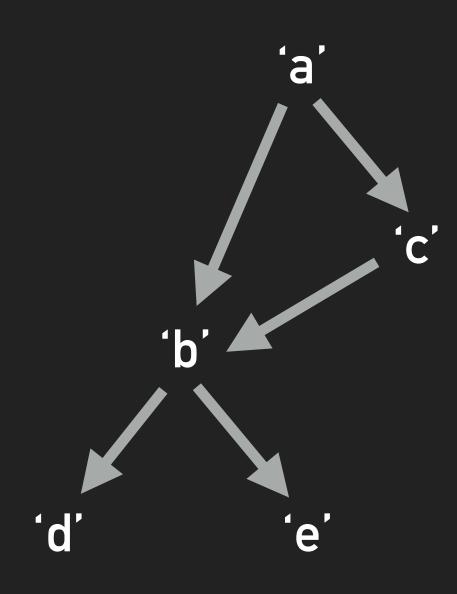


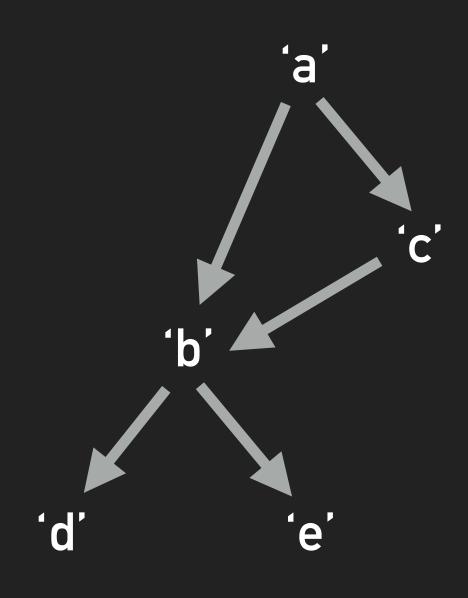
NOT IN THIS TALK

- details about the distributed implementation,
- progress tracking optimization,
- how to prevent micro-stragglers,
- frameworks on top of Naiad / Timely Dataflow,
- performance evaluation.

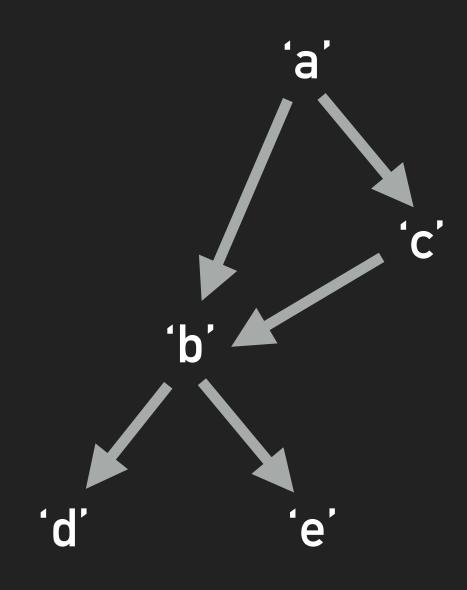
github.com/frankmcsherry/timely-dataflow

TIMELY DATAFLOW IN RUST (**).



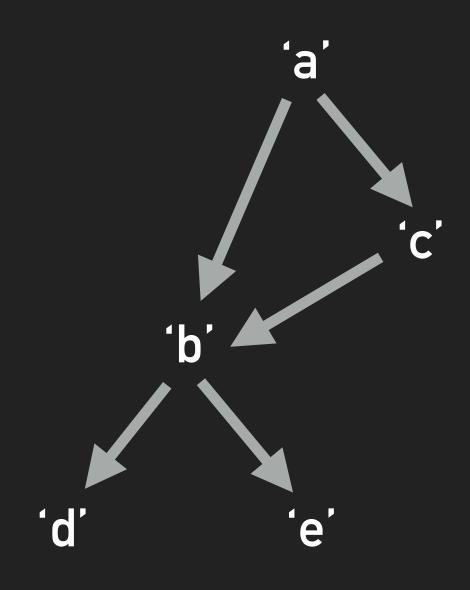


('a', 'b')

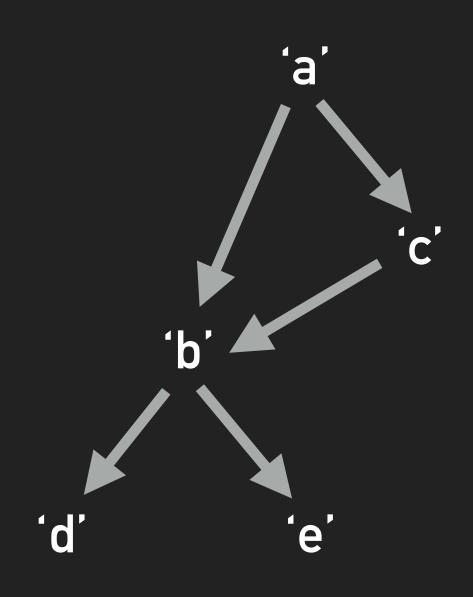


('a', 'b')

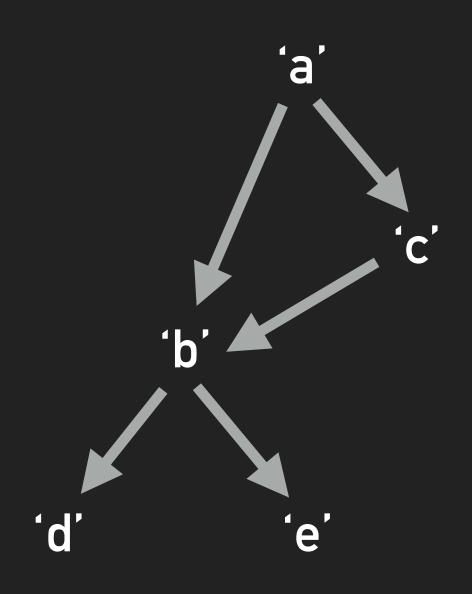
('b', 'd')

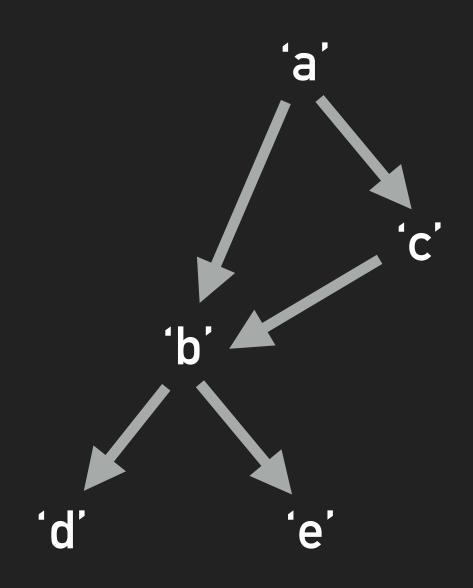


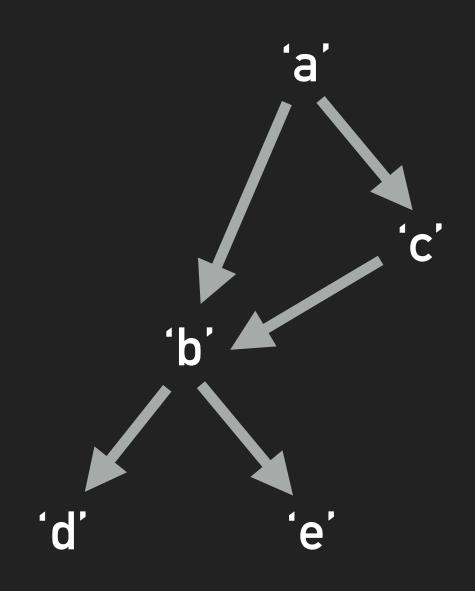
- ('a', 'b')
- ('b', 'd')
- ('b', 'e')



- ('a', 'b') ('a', 'c')
- ('b', 'd')
- ('b', 'e')







('a', 'b') ('a', 'c') ('c', 'b') ('b', 'd') ('b', 'e')

