# Data Science UW Methods for Data Analysis

Bayesian models, Part 2 Steve Elston



#### Required packages

To run the code for today's lecture, make sure you have the following installed.

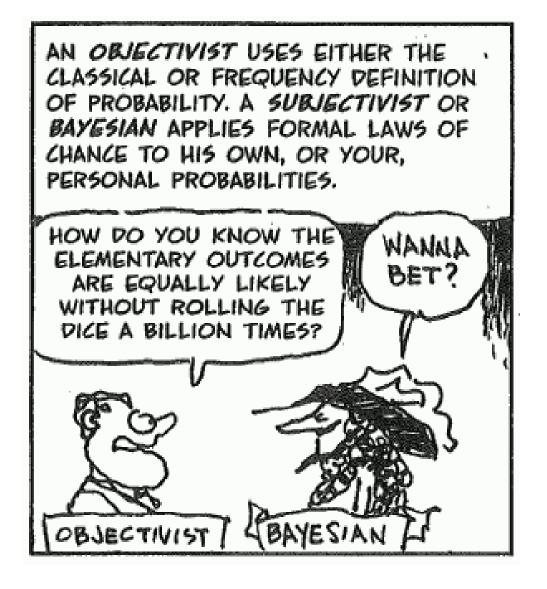
- > JAGS and the rjags Rbpackage. You must install the JAGS system from the downloads available at <a href="http://mcmc-jags.sourceforge.net/">http://mcmc-jags.sourceforge.net/</a> rjags is an R API for JAGS
- > LearnBayes
- > mlbench
- > ggplot2
- > e1071
- > coda



Deadline reminder!!!

All projects are due next Wednesday March 15. No exceptions can be granted!







#### **Bayesian Model Summary**

- > Bayesian view of the world includes updating/changing beliefs new observations
- > Bayesian view takes prior beliefs into account
- > Based on Bayes theorem

$$P(A|B) = P(B|A) \frac{P(A)}{P(B)}$$

> Can use simplified formulation with no P(B)

$$P(A|B) \propto P(B|A)P(A)$$
Posterior Distribution

Prior Distribution

The Likelihood



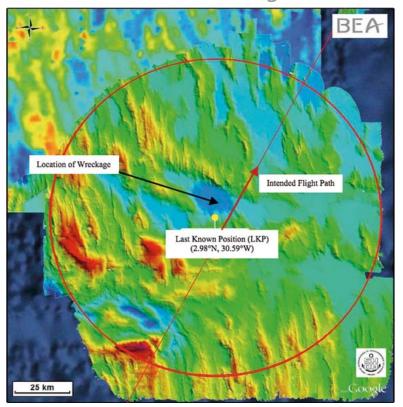
## **Bayes Model Summary**

- > Use MCMC models to scale Bayesian analysis
  - Metropolis-Hastings Algorithm
  - Gibbs sampling for better convergence

Frequentist	Bayesian
Goal is a point estimate and confidence interval	Goal is posterior distribution
Start from observations	Start from prior distribution
Re-compute model given new observations	Update belief (posterior) given new observations
Examples: Mean estimate, t-test, ANOVA	Examples: posterior distribution of mean, overlap in highest density interval (HDI)

# Reading assignment: Bayesian Inference Successes

- $P(parameters|data) \propto P(data|parameters)P(parameters)$
- > Bayesian inference used to successfully to find lost planes. E.g. Air France 447
- https://www.informs.org/ORMS-Today/Public-Articles/August-Volume-38-Number-4/In-Search-of-Air-France-Flight-447





#### **Topics**

- > Bayesian Statistics
  - Markov Chain Monte Carlo (MCMC)
  - Multi-level (Hierarchical ) models)
  - Bayes factor
  - Bayes hypothesis testing Time permitting
  - MCMC diagnostics
- > Naive Bayes



## Bayesian Estimation of a Coin Flip Probability

$$P(parameters|data) = P(data|parameters) \frac{P(parameters)}{P(data)}$$
  
$$f(x) = x^{a-1}(1-x)^{b-1} \cdot (normalizing \ constant)$$

> After we choose a prior, we compute the posterior:

$$Posterior = Likelihood \frac{Prior}{P(data)}$$

> Always a problem estimating the P(data):

$$Posterior = Likelihood \frac{Prior}{P(data|all\ parameters)}$$
 
$$Posterior = Likelihood \frac{Prior}{\sum P(data|theta)}$$



# **Bayesian Estimation of Multiple Parameters**

- > We only had one parameter to estimate for the coin flip example, p(H).
- > We created a grid to check (seq(0.01,0.99,length=100) and used this to calculate the p(data), by checking all the values.
- > What if we had several parameters? If we had 6 parameters with a length 100 grid... = 100^6 = 1,000,000,000,000 = 1 trillion points to check.
- > Maybe we don't have to sample everything, just enough points to understand and estimate the distribution of how p(data) behaves under the 6 parameters?

#### Markov Chain Monte Carlo

#### What is a Markov process?

- > A Markov process makes a transition from one state other states with probability  $\Pi$ 
  - $-\Pi$  only depends on the current state
  - Transition to one or more other states
  - Can 'transition' to current state
  - $\Pi$  is a matrix of dim N X N for N possible states
- > A Markov process is a random walk



#### Markov Chain Monte Carlo

Markov chain is a sequence of Markov transition processes:

$$P[X_{t+1} = x | X_t = x_t, ..., X_0 = x_0] = P[x_{t+1} = y | X_t = x_t]$$

'Memoryless' process

And

$$\Pi = \begin{bmatrix} P_{1,1} & P_{1,2} & ... & P_{1,N} \\ P_{2,1} & P_{2,2} & ... & ... \\ ... & ... & ... & ... & ... \\ P_{N,1} & & & P_{N,N} \end{bmatrix}$$



#### Introducing the Metropolis (Hastings) Algorithm

- > The Metropolis algorithm is a specific MCMC algorithm.
- > Algorithm:
  - 1. Pick a starting point in your parameter space and evaluate it according to your model. (find p(data)).
  - 2. Choose a nearby point randomly and evaluate this point.
    - > If the p(data) of the new point is greater than your previous points, accept new point and move there.
    - > If the p(data) of the new point is less than your previous point, only accept with probability according to the ratio: p(data new) / p(data old) .
  - 3. Repeat # 2 many times.



# Introducing the Metropolis (Hastings) Algorithm

- > M-H algorithm eventually converges to the underlying distribution.
- > We only have to visit N points, not 1 Trillion points.
- > There is high serial correlation in M-H chain, which slows convergence
- > Need to 'tune' the state selection probability distribution used to find the next point
  - E.g. if we use Normal distribution need to pick  $\sigma$ .
  - If  $\sigma$  is too small chain will only search the space slowly.
  - If  $\sigma$  is too big, get large jumps and slow converge

#### **Gibbs Sampling**

#### Improved version of M-H algorithm

- > Uses systematic sampling of the parameter space
- > Example: round-robin
  - With N dimensions
  - Sample 1, 2, ..., N and then start over again
  - Transition still based on p(data)
- > Reduces serial correlation and improves convergence



Remember Bayes Law:  $P(A|B) = P(B|A) \frac{P(A)}{P(B)}$ 

- > Tests are not the event. We have a disease test, which is different than the event of actually having the disease.
- > Tests are flawed. Tests have false positives and false negatives.
- > Tests return test probabilities, not the event probabilities.
- > False positives skew results.
  - E.g. If fraud is rare, then the likelihood of a positive result of fraud is probably due to a false positive



Simple Bayes models have all coefficients at same level

 $P(parameters|data) \propto P(data|parameters)P(parameters)$ 

> Example: Recall the Beta distribution used as prior for Bernoulli likelihood

$$P(\theta | a, b) = \kappa \theta^{(a-1)} (1 - \theta)^{(b-1)}$$

> But what if  $\theta$  is not from a single population?



How to model real-world hierarchies?

- > Sub-populations may behave differently
- > How to we partition the our model to account for subpopulations?
- > Multi-level or hierarchical models accommodate this structure



#### **Examples**

- > Distinguish effect of individual player vs. team
- > Performance of students vs. performance of school
- > Product sales vs. store sale effect
- > Species population vs. habitat



Can use multi-level models to apply adjustments

- > Individual player performance for team performance
- > Individual students performance for school performance
- > Sales for store effect
- > Species population for habitat changes



#### **Extending Bayesian model**

> Bayes rule becomes (chain rule for probabilities)

P(
$$\theta$$
,  $\omega$ | D)  $\propto$  P(D| $\theta$ ,  $\omega$ ) p( $\theta$ ,  $\omega$ )  $\propto$  P(D| $\theta$ ) p( $\theta$ | $\omega$ ) p( $\omega$ )

where

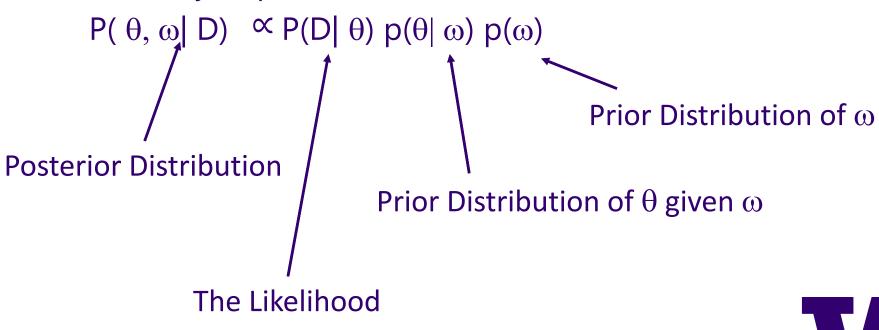
 $\theta$  = parameters for each sub-group

 $\omega$  = parameter for population



Bayes rule for multi-level models

> Hierarchy of priors



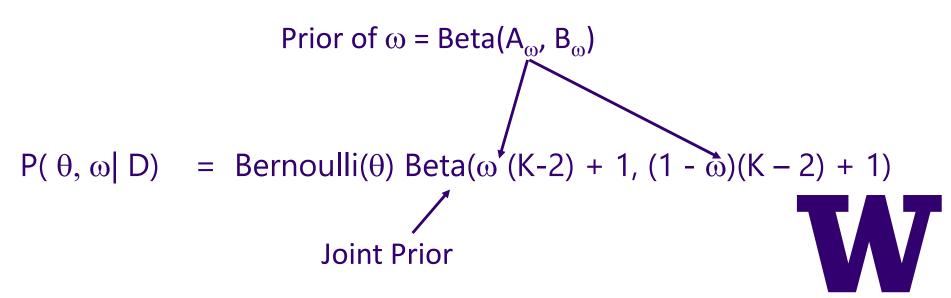


**Extending Bayesian model** 

> Bayes rule becomes

$$P(\theta, \omega | D) = P(D|\theta, \omega) p(\theta, \omega)$$
$$= P(D|\theta) p(\theta|\omega) p(\omega)$$

> Example: for beta prior and Bernoulli likelihood:



**Extending Bayesian model** 

> With Bayes rule:

$$P(\theta, \omega | D) = P(D|\theta) p(\theta|\omega) p(\omega)$$

> Example: for beta prior, the joint posterior probability is now:

$$p_j$$
 ~ Beta( $y_j$  + K $\eta$ ,  $n_j$  -  $y_j$  + K(1 -  $\eta$ )) where  $\eta$  = a / (a+b)  $K$  = a + b  $n_j$  = sample size  $y_j$  = number of hits for player  $j$ 



The posterior is proportional to the product of individual probabilities

$$P(\theta, \omega | D) \propto \prod_{j=1}^{N} p_j$$

To simplify computation in example we reparameterize

$$\theta_1 = \log[\eta / (1 - \eta)]$$

$$\theta_2 = \log(K)$$



#### **Bayesian Model Selection**

How do we find the best model?

- > Want model maximum apostiori probability
- > Different likelihood distributions
- > Different prior distributions
- > Compare hierarchies of models



# Compare Performance of Bayesian Models

Bayes Factor – identify the most likely model

> Hierarchy for models m:

$$P[\Theta_1, \Theta_2, ...m|D] \propto P[\Theta_1, \Theta_2, ...,m] P[D|\Theta_1, \Theta_2, ...m]$$

> Compare (hierarchy) of two models as a ratio:

$$\frac{p(m=1|D)}{p(m=2|D)} \propto \frac{p(D|m=1)}{p(D|m=2)} \frac{p(m=1)}{p(m=2)}$$

> Reduces to

$$\frac{p(m=1|D)}{p(m=2|D)} = \frac{p(D|m=1)}{p(D|m=2)} = Bayes Factor$$



## Hypothesis Testing with Bayes Models

Use HCI to perform hypothesis tests

- > Analogous to hypothesis tests on bootstrap resampled distributions
- > Test conditions for **posterior** distribution
  - If HDI overlap; accept Null Hypothesis
  - If no HDI overlap reject Null Hypothesis
- > HDI is different from Confidence Interval
  - HDI is for interval with greatest probability mass
  - Difference with CI is greatest for asymmetric prior
- > Tests can be one-sided or two-sided



#### Diagnostics for MCMC

#### Multiple ways to look at convergence

- > Summary statistics
  - Mean, median, se, time series se, quantiles
  - Plot cumulative mean and quantiles
  - Plot trace of each chain
  - Plot posterior distribution
- > Plots based on convergence of multiple chains
  - Gelman-Rudin plot of chain convergence
  - Compares shrinkage of between chain and within chain variance
  - Should converge to 1.0



## Diagnostics for MCMC

#### Detect convergence issues

- > High rejection rate inhibits convergence
- > High autocorrelation inhibits convergence
- > Use ACF
- > Effective Sample Size

$$ESS = N / (1 + 2 \sum_{k} ACF(k))$$



#### Introduction to Naïve Bayes

Naïve Bayes is a remarkably good and flexible classifier

- > Widely used classifier
  - Document classification
  - SPAM detection
  - Image classification
- > Scales well
  - Does not require a prior
  - Computation linear in number of parameter/features
  - Requires minimal data
  - Simple regularization



# Introduction to Naïve Bayes

Simplify the conditional probability calculation

- > Start with Bayes Theorem:  $P(A|B) = P(B|A) \frac{P(A)}{P(B)}$
- > The probability of class  $C_k$  is the joint distribution:

= 
$$p(x_1|x_2, ..., x_n, C_k) p(x_2|x_{3_i}, ..., x_n, C_k) ... p(C_k)$$

> But if {x<sub>1</sub>, x<sub>2</sub>, ...., x<sub>n</sub>} are independent:

$$p(x_i|x_{i+1}, ..., x_n, C_k) = p(x_i, |C_k)$$



# Introduction to Naïve Bayes

Simplify the conditional probability calculation

> With {x<sub>1</sub>, x<sub>2</sub>, ...., x<sub>n</sub>} independent:

$$p(x_i | x_{i+1}, ..., x_n, C_k) = p(x_i, | C_k)$$

> The probability of class  $C_k$  is the joint distribution:

$$p(C_k | x_1, x_2, ..., x_n) \propto p(C_k) \prod_{j=1}^{N} p(x_j | C_k)$$

> And the most likely class y<sub>hat</sub> is:

$$y_{hat} = argmax_k [p(C_k) \prod_{j=1}^{N} p(x_j | C_k)]$$
No Prior



# Naïve Bayes Classifiers

Different distributions lead to different classifiers

- > Different Naïve Bayes models are not the same!
- > Normal naïve Bayes classifier
- > Multinomial naïve Bayes classifier

$$\begin{split} Log(p(C_k \mid x)) &\propto log[\ p(C_k)\ \Pi^{\ N}_{\ j \ = \ 1}\ p_{kj}^{\ Xi}\ ] \\ &= log(\ p(C_k)\ ) \ + \ \sum^{\ N}_{\ j \ = \ 1} xi\ log(\ p_{kj}) \end{split}$$

> Bernoulli naïve Bayes classifier

$$p(x \mid C_k) = \prod_{j=1}^{N} p_{kj}^{Xi} (1 - p_{kj})^{(1-Xi)}$$



# Naïve Bayes Document Classification

Use 'bag of words' model

> Want the probability of topic C in document D given set of words in topic  $\{w_1, w_2, ..., w_n\}$ :

$$p(C \mid D) = \prod_{j=1}^{N} p(w_j \mid C)$$

> Spam classification:

$$p(S+\mid D) \propto p(S+) \prod_{j=1}^{N} p(w_j\mid S+)$$

> Test the hypothesis text is spam:

$$ln(p(S+|D)/p(S-|D)) =$$

$$ln(p(S) / p(S-)) + \sum_{j=1}^{N} ln(p(w_j | S+) / p(w_j | S-)) > 0$$



#### Naïve Bayes Pitfalls

#### A few words of caution

- > Multiplication of small probabilities leads to floating point underflow
  - Compute with In(p)
- > If no samples/data get probability = 0
  - Product of probabilities = 0
  - Use Laplace smoother to ensure all p > 0
- > Collinear features can be a problem
  - Do not exhibit independence
- > Regularization is minor issue
  - Uninformative feature tends to uniform distribution



## **Final Projects**

#### Only one week to go!

- > This project gives you a chance to demonstrate your knowledge of the topics covered in the course
- > You must create your report independently
  - Collaboration with others on the analysis is okay
- > Report must contain:
  - Introduction and summary with clearly stated conclusions
  - Support your conclusions based on exploration of data and model results
  - See Florence Nightingale report for example



#### Final Projects, Continued

- > Steps which you must show
  - Exploration of data from several views using graphics and summary statistics as appropriate
    - > Demonstrate your understanding of the data relationships and properties
  - Comparison of several models
    - > Compare difference classes of models and/or features as required
- > R Code must in a professional style
  - Well structured
  - Clean comments
- > Due Monday August 29
- > NO EXTENSIONS! University policy

