Object extraction techniques and visual image search with Semantic web techniques

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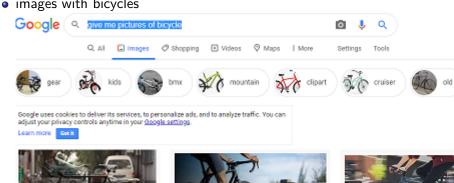
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Dennis Diefenbach

Cyber Physical and Social Systems University of Jean Monnet

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Introduction: Just Google

images with bicycles





Blovde - Wikipedia en.wikipedia.org



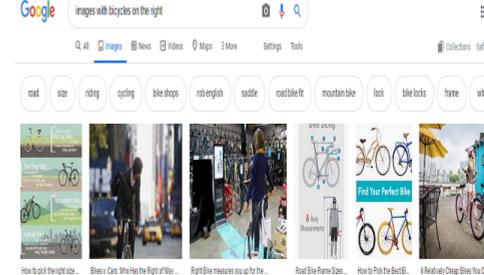
Orbea - Orbea orbea.com



Bikes: How to Choose | REI Co-op relicom



images with bicycles on the right



newsfas.com

loverguardiorenzy com

pirterest com

forbes com-

dall/burn.com

ginterest.com

Introduction:QAnswer

- QAnswer is knowledge based QA system.
- A knowledge base is a collection of facts that can be interpreted by a machine
- Such a fact can look like this: "bicycle" "in" "right".
- QAnswer translates from a natural language question to correct SPARQL queries.

Content

- Implementation of an Algorithm for object extraction.
- Design of a semantic web modelling for extracted data.
- Implementation of a visual image search engine through Qanswer.

Implementation of an Algorithm for object extraction.

YOLO-(You Only Look Once)

Implementation of an Algorithm for object extraction.

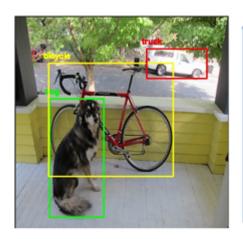


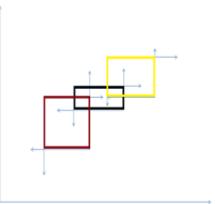
Class Number, Class Name, QID

```
person-Q215627
                           25.umbrella-Q41607
                                                      49.orange-Q39338
1.bicycle-Q11442
                           26.handbag-Q467505
                                                      50.broccoli-Q47722
2.car- Q1420
                           27.tie-044416
                                                      51.carrot-081
3.motorbike-034493
                           28.suitcase-0200814
                                                      52.hot dog-Q181055
4.aeroplane-Q197
                           29.frisbee-Q131689
                                                      53.pizza-Q177
5.bus-Q5638
                           30.skis-Q172226
                                                      54.donut-0192783
6.train-0870
                                                      55.cake-Q13276
                           31.snowboard-Q178131
7.truck-Q43193
                           32.sports ball-063347096
                                                      56.chair-015026
8.boat-035872
                           33.kite-0107061
                                                      57.sofa-Q131514
9.traffic light-Q8004
                           34.baseball bat-Q809910
                                                      58.pottedplant-Q203834
10.fire hydrant-Q634299
                           35.baseball glove-Q809894
                                                      59.bed-042177
11.stop sign-Q250429
                           36.skateboard-Q15783
                                                      60.diningtable-010578291
12.parking meter-0953960
                           37.surfboard-0457689
                                                      61.toilet-Q7857
13.bench-0204776
                           38.tennis racket-0153362
                                                      62.tvmonitor-Q289
14.bird-Q5113
                           39.bottle-080228
                                                      63.laptop-Q3962
15.cat-Q4167836
                           40.wine glass-01531435
                                                      64.mouse-Q7987
16.dog-0144
                                                      65.remote-0185091
                           41.cup-081727
17.horse-0726
                           42.fork-081881
                                                      66.keyboard-Q250
18.sheep-07368
                           43.knife-Q32489
                                                      67.cell phone-Q17517
19.cow-0830
                           44.spoon-081895
                                                      68.microwave-Q127956
20.elephant-Q7378
                           45.bowl-Q153988
                                                      69.oven-036539
21.bear-Q30090244
                           46.banana-0503
                                                      70.toaster-014890
22.zebra-Q32789
                                                      71.sink-Q140565
                           47.apple-Q89
23.giraffe-0862089
                           48.sandwich-028803
                                                      72.refrigerator-037828
24.backpack-05843
```

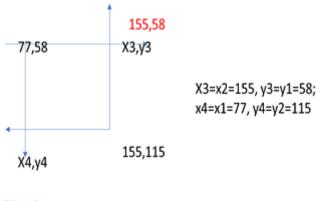
Class Number, Class Name, QID

Bounding Box





Co-ordinate representation of Bounding Box



77,115

Image-Object Relations

Image	relation	property value
	has on the left	
	has on the right	
	has on the top	
	has on the buttom	
	has in the center	

Algorithms for Image-Object Relations

Algorithm 1 has on the left and right

```
1: if X - centre \le 0.3 * X - ImageDimentions then

2: hasontheleft \leftarrow object

3: else

4: if X - centre \ge 0.6 * X - ImageDimentions then

5: hasontheright \leftarrow object

6: end if
```

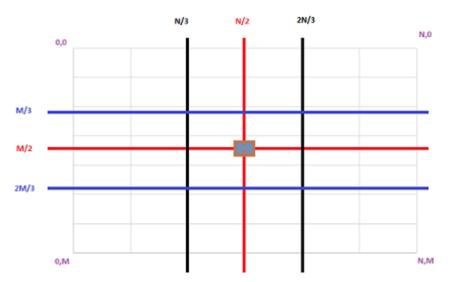
Algorithm 2 has on the top and bottom

```
1: if Y − centre ≤ 0.3 * Y − ImageDimentions then
2: hasonthetop ← object
3: else
4: if Y − centre ≥ 0.6 * Y − ImageDimentions then
5: hasonthebottom ← object
6: end if
7: end if
```

Algorithm 3 has in the center

```
    if X − centre ≥ 0.3 + X − Image Dimentions,
    X − centre ≤ 0.66 * X − Image Dimentions,
    Y − centre ≥ 0.3 * Y − Image Dimentions,
    Y − centre ≤ 0.66 * Y − Image Dimentions then
    2: has in the center ← object
```

An attempt to show a graphical representation of top, bottom, left, right, and central position



Algorithms for Image-Object Relations

Algorithm 1 has on the left and right

```
 \begin{array}{ll} \text{1: if } X-centre \leq 0.3*X-ImageDimentions \ \textbf{then} \\ 2: & has on the left \leftarrow object \\ 3: & \textbf{else} \\ 4: & \textbf{if } X-centre \geq 0.6*X-ImageDimentions \ \textbf{then} \\ 5: & has on the right \leftarrow object \\ 6: & \textbf{end if} \\ 7: & \textbf{end if} \\ \end{array}
```

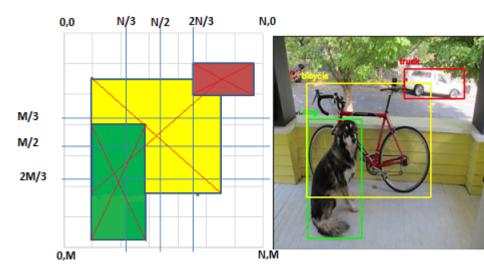
Algorithm 2 has on the top and bottom

```
1: if Y = centre ≤ 0.3 * Y = ImageDimentions then
hasonthetop ← object
3: else
4: if Y = centre ≥ 0.6 * Y = ImageDimentions then
5: hasonthebottom ← object
6: end if
7: end if
```

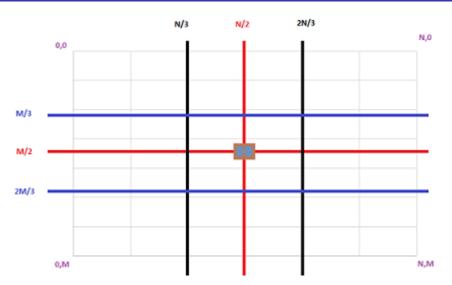
Algorithm 3 has in the center

```
1: if X − centre ≥ 0.3 + X − ImageDimentions,
X − centre ≤ 0.66 + X − ImageDimentions,
Y − centre ≥ 0.3 * Y − ImageDimentions,
Y − centre ≤ 0.66 * Y − ImageDimentions then
2: hasinthecenter ← object
```

An attempt to show a graphical representation of Image-Object relation in comparison to an incoming photo



An attempt to show a graphical representation of Image-Object relation



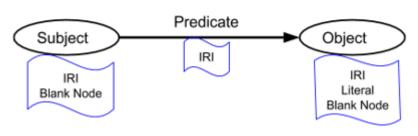
Using Image-Object relation we create a csv file

X1	Y1	X2	Y2	object nar	lmage nar	has on the left	has on the right	has on the	has on the bottom	has in the center
190	813	3897	1932	airplane	Antonov_	na	airplane	us.	airplane	airplane
220	596	5021	1673	airplane	EBACE_20	na	airplane	us.	airplane	airplane
742	1303	3933	2099	airplane	Embraer_	na	airplane	us.	airplane	airplane
889	1035	1378	1374	airplane	Kirchturm	na	airplane	N8	airplane	airplane
172	278	4018	1722	airplane	Lufthansa	na	airplane	N3	airplane	airplane
331	532	2362	1245	airplane	North_An	na	airplane	N3	airplane	airplane
1355	704	1444	813	person	North_An	na	person	N3	person	person
833	251	2202	1761	airplane	Paris_Air	na	airplane	n 3	airplane	airplane
1460	1207	1579	1738	person	Playing_ir	na	person	na na	person	na
224	1063	466	1813	person	Playing_ir	person	na	na na	person	na
756	1286	845	1562	person	Playing_ir	person	na	na na	person	na
2374	990	2486	1359	person	Playing_ir	na	person	us.	person	na
468	1194	546	1264	frisbee	Playing_ir	frisbee	na	us.	frisbee	na
264	273	2284	1571	airplane	RUAG_Av	ina	airplane	na	airplane	airplane
										-

Design of a semantic web modelling for extracted data. Image-Object

Design of a semantic web modelling based on the csv file.

Image	relation	property value
	has on the left	
	has on the right	
	has on the top	
	has on the buttom	
	has in the center	



Object-Object Relation

Object	relation	property value
	left of	object
	right of	object
	top of	object
	buttom of	object
	close to	object
	far from	object
0	verlaping wit	object
	greater than	object
	smaler than	object
	%of image	value

OORelation algos ready to be used

Algorithm 4 is on the left and right of

- if X − centreOfObject₁ ≤ X − centreOfObject₂ then
 Object₁IsOnTheLeft ← Object₂
- Object₁1sOnTheLeft ← Object₂
- 3: else
- if X − centreOfObject₁ ≥ X − centreOfObject₂ then
- 5: Object₁IsOnTheRight \leftarrow Object₂
- 6: end if
- 7: end if

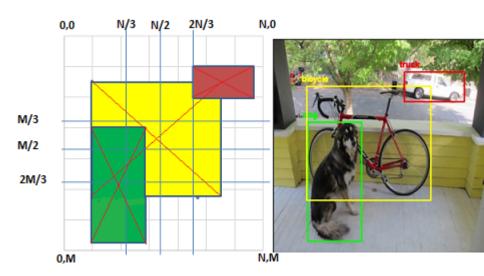
Algorithm 5 is on the top and bottom of

- if Y − centreOfObject₁ ≤ Y − centreOfObject₂ then
- Object₁IsOnTheTop ← Object₂
- 3: else
- if Y − centreOfObject₁ ≥ Y − centreOfObject₂ then
- 5: $Object_1IsOnTheBottom \leftarrow Object_2$
- 6: end if
- 7: end if

Algorithm 6 close and far from

- if distance(Center1, Center2) ≤ means of diagonal of the 2 objects then
- Object₁IsCloseTo ← Object₂
- 3: else
- if distance(Center1, Center2) ≥ means of diagonal of the 2 objects then
- Object₁IsFarFrom ← Object₂
- 6: end if

An attempt to show a graphical representation of O-O Relations in comparison to an incoming photo



OORelation algos ready to be used, contd...

Greater and Smaller Than

Algorithm 7 greater and smaller than

```
    if AreaOfObject<sub>1</sub> ≤ AreaOfObject<sub>2</sub> then
```

Object₁IsSmallerThan ← Object₂

3: else

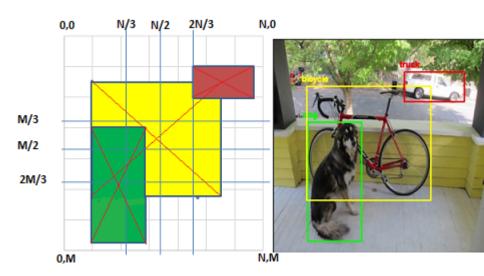
: if $AreaOfObject_1 \ge AreaOfObject_2$ then

5: $Object_1IsGreaterThan \leftarrow Object_2$

6: end if

7: end if

An attempt to show a graphical representation of O-O Relations in comparison to an incoming photo



OORelation algos ready to be used, contd...

Overlapping With

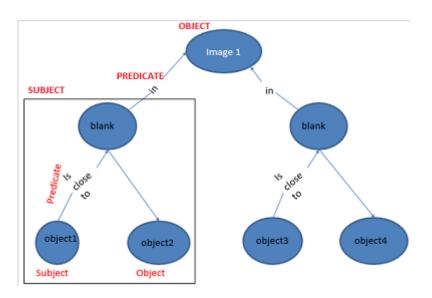
```
from shapely.geometry import Polygon p1 = Polygon([(0,0), (1,1), (1,0)]) p2 = Polygon([(0,1), (1,0), (1,1)]) print(p1.intersects(p2))
```

True

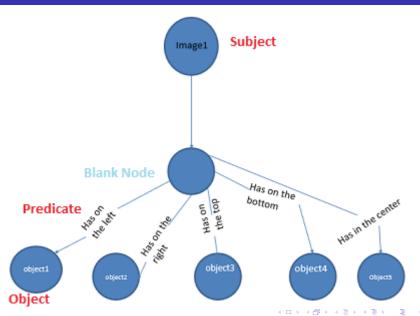
Object-Object Relation

Object	relation	property value
	left of	object
	right of	object
	top of	object
	buttom of	object
	close to	object
	far from	object
0	verlaping wit	object
	greater than	object
	smaler than	object
	%of image	value

Reified Triple



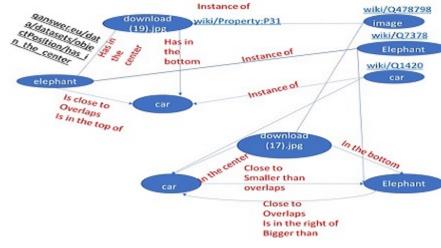
Regular Triple



Knowledge Graph

Image-Object Relation with a hint of Object-Object Relation

Design of a semantic web modelling for extracted data.

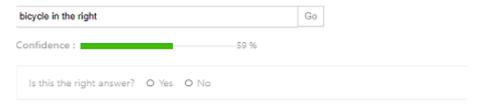


After Semantic Web Modelling

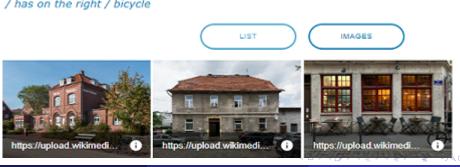
- We convert the CSV file created for Image-Object Relations into
 - a RDF file
 - with the help of a Java Program
- and upload the RDF file into QAnswer

Results

QAnswer: images with bicycle in the right



/ has on the right / bicycle



images in the center

• QAnswer: airplane in the center

Confidence: -55.96

Is this the right answer? O Yes O No

/ has in the center / airplane

LIST IMAGES







images in the left

train in the left

https://qanswer-frontend.univ-st-etienne.fr/user/query?kb=onto&user=anindamaulik

Qanswer: Image-Object Relation-contains

person and chair



https://upload.wikimedia.org/wikipedia/commons/e/eb/CEE_Spi





special Wikimediacommons api give images and human hand-annotated structured data

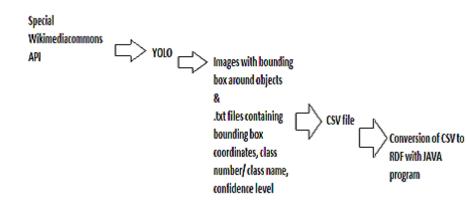
The Api

https://commons.wikimedia.org/w/api.php?action=query&list=search&srsearch=haswbstatement:

 ${\tt P180=Q7378\&srnamespace=6\&format=json}$

- give images in form of json data
- and human hand-annotated structured data for some images
- Examples
 - what are the items portrayed in the image
 - 2 who is the creator of the file
 - what is the source of the file
 - inception date of the file
 - copyright status
 - The url showing structured data https://commons.wikimedia.org/wiki/File: African_elephants,_Lake_St_Lucia_06.jpg

Automation pipeline



Limitations and Future Work

Query for images on the top

Issue with confidence of detection by YOLO

/ has on the top / clock

https://upload.wikimedia.org/wikipedia/commons/e/e7/Taipei_i Rheinland-Office-Building-02.jpg

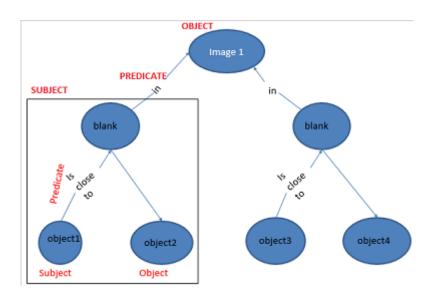




YOLO got overconfident



Reified Triple



Reified Triple not being interpreted by QAnswer



special Wikimediacommons api give images and human hand annotated structured data Our time constraints

 $\label{limits} https://commons.wikimedia.org/w/api.php?action=query\&list=search\&srsearch=haswbstatement:$

P180=Q7378&srnamespace=6&format=json

- We are yet to handle the incoming RDF data from the api
- and merge with our RDF file,
- in order to be able to query
- "Give me pictures of bicycles from February 2019"

Conclusion

- We have worked on improving image search engines
- Omputer Vision techniques is able to identify objects in images.
- Semantic Web techniques give a semantic representation of the images that can be queried QAnswer.
- This work can be easily used by any search or query engine to give results
- We do not have a bench mark as of yet

END

- Thank you for your attention, time and patience
- Please ask me any question that you have.
- Please provide your suggestion which can be used to make my work better