

Review of Helmet Detection System using Deep Learning

Dr. Jaychand Upadhyay
HOD, Department of Information Technology
Xavier Institute of Engineering
Mumbai, India
jaychand.u@xavier.ac.in

Tanvi Bhabal
Student, Department of Information Technology
Xavier Institute of Engineering
Mumbai, India
tanvibhabal1911@gmail.com

Farhan Khan
Student, Department of Information Technology
Xavier Institute of Engineering
Mumbai, India
famannat@gmail.com

Sudeep Poojary
Student, Department of Information Technology
Xavier Institute of Engineering
Mumbai, India
sudeeppoojary0320@gmail.com

Anisha Prabhu
Student, Department of Information Technology
Xavier Institute of Engineering
Mumbai, India
anisha.prabhu26@gmail.com

Abstract— Maintaining road safety is of utmost importance, especially for vulnerable road users such as motorcycle riders. Helmet detection systems are an important technical development in this difficulty that seeks to ensure adherence to safety necessities and reduce the possibility of motorbike accidents. These systems use present day technology like advanced image processing techniques to automatically determine if bike riders are carrying helmets in real time. Through the analysis of pictures or video streams acquired from protection cameras or embedded devices, the one's systems are critical in encouraging compliance with helmet usage legal suggestions and in the end lowering the wide variety of head injuries and a street twist of fate fatalities. This review paper investigates helmet detecting systems, examining methods, obstacles, and developments. It covers a range of technologies, such as deep learning and computer vision, and tackles issues like lighting, real world complexity, and helmet appearances. The study highlights the benefits and drawbacks of existing procedures while emphasizing adaptation to local traffic conditions and criminal demands.

Index Terms—Helmet Detection, ESP32, Mobilenet, Resnet50, YoloV8, FOMO

I. INTRODUCTION

The panorama of systems for detecting helmets on motorcyclists represents a vital point of intersection among generation and road safety, with a fundamental goal to lessen the risks associated with accidents concerning bikes. These structures become a response to the alarming records concerning head accidents and fatalities as a result of avenue injuries that contain motorcyclists. The importance of sporting helmets in mitigating the severity of accidents has been nicely-hooked up, which in turn has prompted the exploration of computerized answers capable of enforcing and monitoring compliance with safety guidelines.

The demanding situations encountered In the improvement of effective helmet detection systems are complex and multidimensional. One of the primary demanding situations

revolves around the numerous appearances of helmets. Helmets come in a big range of shapes, colorations, and designs, thereby complicating the mission of regular reputation and classification for automatic systems. Real international situations introduce extra complexities, together with various lights conditions, occlusions caused by other items or riders, and a mess of camera angles. Striking a delicate stability between attaining excessive accuracy and keeping actual-time processing speed poses a sensitive assignment that necessitates the adoption of revolutionary approaches in set of rules layout and optimization.

Furthermore, an additional layer of complexity is brought with the aid of the adaptability of helmet detection structures to extraordinary regional visitors' conditions and legal necessities. This adaptability encompasses the intricacies of visitors rules, cultural norms, and ranging enforcement practices throughout one-of-a-kind geographical locations. Incorporating this size of flexibility into the structures is important in an effort to reap a regular solution that caters to the numerous worldwide panoramas of site visitors management and helmet usage guidelines. Therefore, a complete knowledge of those contextual elements is imperative.

The area of helmet detection is characterized by means of a wide variety of technological strategies, spanning from traditional pc imaginative and prescient strategies to advanced deep gaining knowledge of models. In the realm of computer imaginative and prescient methodologies, strategies which includes Histogram of Oriented Gradients (HOG) and Haar-like features are hired for characteristic extraction and item detection. On the opposite cease of the spectrum, deep studying fashions, specifically Convolutional Neural Networks (CNNs), as well as superior architectures like YOLO (You Only Look Once) and SSD (Single Shot Multibox Detector), have exhibited terrific competencies in handling complex visual reputation duties.[4]-[6][10][11][14][15][18][20][21][22][25]

This groundbreaking Helmet Detection System combines the strength of advanced synthetic intelligence and embedded structures, utilising the present day ESP32 digital camera. This top notch assignment strives to address an important issue in street safety through revolutionizing the manner helmets are detected among motorcyclists. By streamlining this manner, it takes a critical step closer to minimizing head injuries and deaths resulting from site visitors injuries. The ESP32 camera, recognised for its versatility and connectivity, presents a solid base for taking pictures and processing actual time pix. It is the perfect match for our task.

Central to the functionality of this challenge are superior AI fashions inclusive of YOLOv8, FOMO, CenterNet ResNet50 V2 512x512 and SSD MobileNet V1 FPN 640x640. YOLOv8, famed for its mind blowing actual time item detection skills, enables the system to fast and accurately pick out helmets. The inclusion of FOMO similarly enhances the machine's performance, highlighting its specific abilities. Plus, the combination of CenterNet ResNet50 V2 FPN 512x512 and SSD MobileNet V1 FPN 640x640 showcases a dedication to diversity in model selection, catering to one of a kind efficiency and resource issues. This guarantees ideal overall performance in a whole lot of scenarios.

The ESP32 digicam plays an essential role on this device because it gives a convenient and connected choice for recording pix and video streams. Its embedded device boasts low power consumption and wi-fi functions, making it seamlessly adaptable to any putting. This outstanding mixture renders it an excellent option for site visitors surveillance and protection functions. Through the collaboration of the ESP32 digital camera and advanced AI models, the gadget is empowered to investigate visible facts in real time, offering a modern day solution for detecting helmets in any weather conditions.

This project is an effective aggregate of cutting edge AI models and embedded systems, primed to revolutionize street protection. By integrating YOLOv3, FOMO, CenterNet ResNet50 V2 FPN 512x512 and SSD MobileNet V1 FPN 640x640, the crew has taken a nuanced and all encompassing approach, making certain the machine's agility in diverse scenarios and settings. As this task unfolds, it now not best demonstrates the unprecedented skills of superior technologies, however also highlights the profound potential of these sensible structures in selling and implementing protection measures for motorcyclists, in the long run growing a safer environment for all.

The next sections delve into the dialogue of twenty five papers, which provide treasured insights into the dynamic landscape of helmet detection. Each paper provides particular views, modern methodologies, and strategies aimed at addressing the demanding situations related to helmet detection. These papers make contributions to the ongoing discourse on how generation can successfully beautify avenue protection, mainly for motorcyclists, by using integrating Support Vector Machines (SVM) in one method and utilizing deep mastering models including YOLOv5 and Swin Transformer in others. The collective exploration of these papers not simplest exhibits the contemporary modern day in helmet detection however additionally underscores the chronic demanding situations and future guidelines on this critical

domain where era and safety converge. [1][3] [6][8][10][17] [20][22][25]

II. HARDWARE

A. ESP32 Camera

The ESP32 Camera is extraordinary. It combines the features of an ESP32 microcontroller and a high res camera. This helps provide a clean, complete package for seeing applications. The microcontroller's dual core Tensilica LX6 processor, which goes up to 240 MHz, is powerful enough for tough image processing tasks. Moreover, it is still energy efficient, great for devices that run on batteries. The ESP32 Camera isn't just a camera; it is Wi-Fi and Bluetooth ready. It connects smoothly with networks and Internet of Things platforms. You can look at and control the camera from afar. So, you can use it for watching over areas, looking at the environment, and controlling smart homes.

The camera module is quite advanced. It holds several image resolutions and formats such as JPEG, BMP, and PNG. Therefore, it offers features like auto exposure control and white balance adjustment which ensure great image quality even in different lighting. The ESP32 Camera allows for real time video streaming and recording. This helps in constant observation and data analysis. Given its small size and varied ways to connect, the ESP32 Camera matches well in many settings. It fits in indoor house protection systems as well as outdoor weather checkpoints.

You'll like the ESP32 Camera not just for its great hardware. It's backed by a wide range of tools and software. These include things like the Arduino IDE and ESP-IDF. Developers find it super easy to use. They can create and launch applications quicker. They even get to work in programming languages they already know. Plus, it's compatible with big cloud platforms like AWS IoT, Google Cloud IoT, and Microsoft Azure IoT. These provide top notch support for things like data storage and learning machines. To sum it up, the ESP32 Camera is a strong platform for visual sensing uses. It offers a mix of top performance, easy use, and lots of choices for developers, making it an attractive choice.

The ESP32 camera is important in helmet detection technology. It quickly recognizes and evaluates images and videos. This tiny powerhouse pairs an ESP32 microcontroller and an excellent camera module. It spots helmets everywhere. The ESP32 device itself is powerful. It has two-core Tensilica LX6 processors that run up to 240 MHz, which means it can handle the advanced calculations that are needed for detecting helmets. Along with its low power intake, this renders the ESP32 digicam nicely proper for batteryoperated programs, ensuring long-term deployment without compromising normal overall performance. The digital camera module of the ESP32 digicam has a variety of functions for helmet detection. With support for lots of photo resolutions and formats the Digicam module permits fantastic image seizures under diverse lighting fixture situations. There are functionalities like automobile exposure management and white stability adjustment ensure an ideal photograph exceptional, enhancing helmet detection algorithms' accuracy.

The ESP32 digicam allows real-time video streaming and recording, which makes it easy for continuous monitoring of helmet-carrying behavior in dynamic environments. When it's fitted into a helmet detection device, the ESP32 camera is capable of using various machine learning models for recognizing objects. This includes YOLO (You Only Look Once), SSD (Single Shot Multibox Detector). They can then spot helmets in videos that are being filmed by the ESP32 camera in real time. The ESP32 camera has Wi-Fi and Bluetooth modules, which means it can easily connect with services on the cloud. One can store data, go over it, and monitor it from somewhere else. The helmet detection system gets better with more flexibility and can be bigger. This ESP32 camera helps a lot with helmet detection systems. It offers sturdy, flexible hardware and connections to make sure roads are safer and the rules are followed.

III. DEEP LEARNING MODELS

A. SSD MobileNet V1 FPN 640x640

The SSD MobileNet V1 FPN 640x640 object detection mode-1 combines the efficiency of the Single Shot Multibox Detector framework, MobileNet V1 feature extractor, and Feature-Pyramid Network to perform accurate real-time detection with constrained resources. It uses SSD, which detects objects in one pass of the network, along with MobileNet V1's lightweight architecture to achieve fast speeds. The FPN forms a pyramid of feature maps to capture objects at multiple scales. Together this allows for balanced accuracy and processing speeds at 640x640 resolution, making the model well-suited for edge applications using devices such as ESP32 cameras. Specifically, it efficiently detects objects in real-time while maintaining effectiveness even with the limited computational power available on such edge hardware.[8][21]

The SSD Mobile-Net V1 FPN 640x640 model provides some benefits for helmet detection using an ESP32 camera. Mainly, its streamlined design means it can perform inferences with minimal extra processing power draw, which allows it to function smoothly even on devices with limited resources like the ESP32. This permits real time object recognition directly from the camera sensor, removing the necessity for separate computing hardware and lessening delays in identifying objects. The model also incorporates a feature pyramid network enhancing its capability to identify articles at different magnitudes, making it resilient to fluctuations in helmet measurements and positions. The lightweight architecture is optimized for portable applications by conserving energy and reducing lag, important factors for safety systems with the ESP32.

Through employing the SSD MobileNet V1 FPN 640x640 model on the ESP32 camera, it becomes feasible to create a compact and effective helmet detection system. The camera records live video footage, which is then examined in real time using the pretrained model to pinpoint helmets inside the frame. This data can be relayed to an operator or incorporated with other systems for additional examination or reaction. ESP32's

connectivity capabilities allow seamless integration with other devices or systems. The system can rapidly identify helmets in video streams and communicate findings, offering potential for use in safety monitoring or analytics. While more exploration is still needed, this approach shows promise as a means of real time helmet tracking with a lowcost, portable design.[3][6]

B. CenterNet ResNet50 V2 FPN 512x512

The integration of CenterNet ResNet50 V2 FPN 512x512 with the ESP32 camera for helmet detection gives a strong answer for boosting avenue protection and imposing helmet policies. CenterNet ResNet50 V2 FPN 512x512 combines the CenterNet structure with the ResNet50 backbone network and Feature Pyramid Network (FPN), imparting exceptional accuracy, speed, and scalability in object detection responsibilities. By leveraging this superior model, the helmet detection machine can accurately become aware of motorcyclists sporting helmets in real-time, enabling the government to reveal compliance with safety guidelines more efficiently.

The ESP32 digital camera platform is an ideal deployment platform for the CenterNet ResNet50 V2 FPN 512x512 version, way to its compact length, low electricity consumption, and embedded processing talents. Through integration with the ESP32 digital camera, the helmet detection device becomes transportable and versatile, appropriate for deployment at various locations which includes site visitors intersections, avenue junctions, or checkpoints. This allows the government to successfully put into effect helmet regulations and sell street protection across different environments.

One of the important thing advantages of CenterNet ResNet50 V2 FPN 512x512 is its capacity to appropriately localize items of hobby, along with helmets, within the photograph body. The model achieves precise detection by way of predicting item keypoints, together with the center factor and size of the helmet, even underneath tough conditions like varying lighting or occlusions. With its scalability and actual-time processing abilities, the machine ensures set off detection of motorcyclists without helmets, empowering government to take timely action and mitigate avenue protection risks effectively.

C. FOMO

FOMO stands for Feature Online Mining Object Detection. It is an object detection framework that makes use of on-line characteristic mining to enhance accuracy and overall performance. It filters and updates region proposals based on CNN remarks, which leads to stepped forward detection overall performance. FOMO is used often for real-time detection with immoderate accuracy, making it promising for helmet detection the use of the ESP32 virtual digital camera.

Its online feature mining mechanism permits it to adapt dynamically to changes within the visible surroundings, making sure sturdy ordinary performance in various situations. It can effectively handle occlusions and partial visibility of

helmets, not unusual demanding conditions in actual global detection situations.

By combining FOMO with the ESP32 digital camera, a distinctly accurate and efficient helmet detection device may be superior. The digicam captures stay video feeds, processed in real-time using FOMO to stumble upon helmets. This fact can be used for diverse applications, together with monitoring helmet compliance in website online visitors surveillance or improving protection protocols in production websites. The ESP32's connectivity abilities allow seamless integration with cloud offerings for far away monitoring and statistics analysis, presenting comprehensive and scalable helmet detection answers.

D. YOLOv8

YOLOv3 stands for You Only Look Once, version 3. It is a cutting-edge goal acquisition coaching manual regarded for its speed and accuracy. It revolutionized the arena by introducing a single neural community that could instantly discover gadgets in images or video frames without the need for complex detection networks. YOLOv3 achieves this by using directly dividing the enter photograph right into a grid and predicting bounding containers and refinement alternatives for every grid cell. This architecture permits real-time object detection with splendid baseline performance across more than one product training. In the context of ESP32 digital camera helmet detection, YOLOv3 provides an effective answer in quick and as it need to understand helmets in captured scenes. The ESP32 digital camera and seize of photographs or video streams can be used to provide enter information to the YOLOv3 model. YOLOv3 then maps these inputs into a strategy through detecting and locating actual-time helmets in frames. Its capacity to handle multiple objectives concurrently and strong universal overall performance in certain environmental conditions make it suitable for helmet detection applications. In addition, the rate of YOLOv3 matches the processing talents of ESP32, which ensures fast helmet detection and correctly decorates security features. Overall, the combination of YOLOv3 with ESP32 virtual digicam affords a dependable and inexperienced solution for helmet detection in numerous situations. [3][4][6][11]

IV. LITERATURE SURVEY

The papers reviewed give some innovative tactics for automating the detection of helmeted and non-helmeted motorcyclists, focusing on the use of superior fashions and techniques. One prominent technique includes the usage of convolutional neural networks (CNNs), mainly the YOLOv2 version, that is carried out in a diploma approach to decorate helmet detection accuracy. By teaching separate YOLOv2 models on custom datasets, those structures benefit notable improvements in figuring out helmeted people. Additionally, deep mastering strategies such as the Single Shot MultiBox Detector (SSD) and various CNN fashions (VGG16, VGG19, GoogLeNet, MobileNets) are explored for photo kind and

vicinity of interest detection. Notably, the mixture of SSD with MobileNets demonstrates superior overall performance in helmet detection, showcasing the effectiveness of deep learning in this area.

Device learning algorithms play a crucial feature in numerous methodologies, together with using Support Vector Machines (SVMs) for the pedestrian category and round Hough redecorate for function extraction. The integration of those strategies enables accurate helmet detection and category, contributing to higher safety enforcement on roadways. Image processing techniques which consist of the ViBe heritage modelling set of rules and haar-like features also are hired to become aware of shifting gadgets and distinguish amongst one-of-a-kind varieties of helmets.

The studies papers highlight the robustness and efficacy of these automated detection structures, with unexpected accuracy rates done in detecting each helmeted and non-helmeted motorcyclist. Comparative assessments show off the prevalence of CNN-primarily based strategies over conventional techniques, underscoring the capacity of advanced models to decorate avenue protection measures. Moreover, the real-time capabilities of those systems, installed via experiments completed underneath several lighting fixture conditions, similarly validate their realistic utility for enforcement features.

The aggregate of cutting-edge fashions and techniques represents a tremendous improvement in the situation of road safety generation. These automatic detection systems provide a promising option for the demanding situations of tracking helmet utilization and enforcing policies correctly. By leveraging the energy of deep learning, machine imagination and prescient, and image processing, these methodologies pave the manner for extra efficiency. These papers introduce a new technique using SVM to detect helmets automatically. Road accidents are a major concern, especially for motorcycle riders. Wearing a helmet reduces the risk of injuries by 70%. Monitoring helmet usage is challenging. The proposed system scales images, creates a dataset, and applies an SVM classifier to determine if a rider is wearing a helmet. The algorithm improves efficiency and meets industry standards. It also offers easy troubleshooting and error handling. In summary, the paper presents an efficient algorithm for helmet detection that encourages their use and aligns with technological advancements and efficient and reliable techniques to ensure compliance with safety protocols. The scalability and adaptability of those systems advise ability packages past motorcyclist safety, signalling a broader impact on automatic tracking and enforcement mechanisms in numerous real-world situations.[1]-[25]

V. CONCLUSION

Advanced AI algorithms like YOLOv3, YOLOv5, Faster R-CNN, and custom CNNs are remodelling road protection by permitting actual-time, computerized detection of helmetless

riders in site visitors' surveillance movies. With accuracy exceeding 90% in many cases, those systems move some distance past mere detection, supplying talents like motorbike identity, registration code reputation, or even car pace estimation. This generates precious records for targeted interventions, potentially saving lives. Real-global deployment requires more advantageous robustness in complicated environments with poor lighting, overlapping gadgets, and diverse climate conditions. Enlarging the datasets to encompass several rider positions, helmet sorts, and placement site visitor situations is critical for broader adaptability and common overall performance. Advanced cameras with better low-slight and weather resistance can appreciably raise actual worldwide accuracy. Functionalities like license plate popularity (OCR), helmet kind class, and cellular telephone detection can offer precious insights for centred enforcement and educational campaigns, in the long run fostering steadier the use of evaluations for everybody. Addressing those limitations and pursuing destiny avenues like deep reading for license plate identity and fall detection can evolve those algorithms into entire protection systems, informing emergency responders and households. This no longer best guarantees rider protection but moreover paves the way for intelligent transportation structures with features like lane change and collision detection, leading to an extra stable and further inexperienced future.[1]-[25]

REFERENCES

- [1] B. V. SubbaRao, C. S. Babu, G. S. Rao and G. Subbarao, "Automatic Helmet Detection Using SVM Techinques," *Journal of Green Engineering*, pp. 1511-1524, 2021.
- [2] R. Silva, K. Aires, T. Santos, K. Abdala, R. Veras and A. Soares, "Automatic detection of motorcyclists without helmet.," in *XXXIX Latin American computing conference (CLEI)*, 2013.
- [3] A. Santhosh, J. Augusthy, L. Sunil, N. Madhusudhanan and S. Sivankutty, "Real-Time Helmet Detection of Motorcyclists without Helmet using Convolutional Neural Network.," *International Journal for Research in Applied Science & Engineering Technology (IJRASET)*, vol. 8, pp. 1112-1116, 2020.
- [4] J. A. B. Susa , R. R. Maaliw, C. M. C. Ceribo, J. Macalisang and B. C. Fabo, "An efficient safety and authorized helmet detection using deep learning approach.," in *International Conference on Smart Information Systems and Technologies (SIST)* , 2022.
- [5] N. N. F. Giron, R. K. C. Billones, A. M. Fillone, J. R. Del Rosario, M. K. Cabatuan, A. A. Bandala and E. P. Dadios , "Motorcycle Rider Helmet Detection for Riding Safety and Compliance Using Convolutional Neural Networks.," in *IEEE 12th International Conference on Humanoid, Nanotechnology, Information Technology, Communication and Control, Environment, and Management (HNICEM)* , 2020.
- [6] H. Nagoriya, "Live Helmet Detection System for Detecting Bikers without Helmet.," *International Journal of Knowledge Based Computer Systems*, pp. 14 - 17, 2020.
- [7] M. Desai, S. Khandelwal, L. Singh and . S. Gite, "Automatic helmet detection on public roads," *Int J Eng Trends Technol (IJETT)*, pp. 185 - 188, 2016.
- [8] A. Bouhayane, Z. Charouh, M. Ghogo and Z. Guennoun, "A Swin Transformer-Based Approach for Motorcycle Helmet Detection.," *IEEE Access*, vol. 11, pp. 74410 - 74419, 2023.
- [9] F. W. Siebert and . H. Lin, "Detecting motorcycle helmet use with deep learning.," *Accident Analysis and Prevention*, 2020.
- [10] C. Wei, Z. Tan, Q. Qing, R. Zeng and G. Wen , "Fast helmet and license plate detection based on lightweight YOLOv5.," *Sensors*, 2023.
- [11] M. Dasgupta, O. Bandyopadhyay and S. Chatterji, "Automated helmet detection for multiple motorcycle riders using CNN.," in *IEEE Conference on Information and Communication Technology* , 2019.
- [12] C. A. Rohith, S. A. Nair , P. S. Nair , S. Alphonsa and N. P. John , "An efficient helmet detection for MVD using deep learning.," in *3rd International Conference on Trends in Electronics and Informatics (ICOEI)* , 2019.
- [13] V. L. Padmini, G. K. Kishore, P. Durgamalleswarao and P. T. Sree , "Real time automatic detection of motorcyclists with and without a safety helmet.," in *International Conference on Smart Electronics and Communication (ICOSEC)* , 2020.
- [14] L. Shine and J. CV, "Automated detection of helmet on motorcyclists from traffic surveillance videos: a comparative analysis using hand-crafted features and CNN," *Multimedia Tools and Applications*, pp. 14179 - 14199, 2020.
- [15] C. Vishnu, D. Singh , . C. K. Mohan and S. Babu, "Detection of motorcyclists without helmet in videos using convolutional neural network.," in *International Joint Conference on Neural Networks (IJCNN)* , 2017.
- [16] B. Yogameena, K. Menaka and S. Saravana Perumaal, "Deep learning-based helmet wear analysis of a motorcycle rider for intelligent surveillance system.," *IET Intelligent Transport Systems*, pp. 1190-1198, 2019.
- [17] W. Jia, S. Xu, Z. Liang, Y. Zhao, H. Min, S. Li and Y. Yu, "Real-time automatic helmet detection of motorcyclists in urban traffic using improved

YOLOv5 detector.,” *IET Image Processing*, vol. 15, no. 14, pp. 3623-3637, 2021.

- [18] J. Mistry, A. K. Misraa, M. Agarwal, V. M. Chudasama and K. P. Upla, “An automatic detection of helmeted and non-helmeted motorcyclist with license plate extraction using convolutional neural network.,” in *seventh international conference on image processing theory, tools and applications (IPTA)*, 2017.
- [19] P. Wonghabut, J. Kumphon, T. Satiennam, R. Ung-Arunyawee and W. Leelapatra, “Automatic helmet-wearing detection for law enforcement using CCTV cameras.,” in *IOP Conference Series: Earth and Environmental Science* , 2018.
- [20] R. R. V. Silva, K. R. T. Aires and R. D. M. S. Veras, “Helmet detection on motorcyclists using image descriptors and classifiers.,” in *27th SIBGRAPI Conference on graphics, patterns and images*, 2014.
- [21] N. Boonsirisumpun, W. Puarungroj and P. Wairotchanaphuttha, “Automatic detector for bikers with no helmet using deep learning.,” in *22nd International Computer Science and Engineering Conference (ICSEC)* , 2018.
- [22] Y. Kulkarni, S. Bodkhe, A. Kamthe and A. Patil, “Automatic number plate recognition for motorcyclists riding without helmet.,” in *International Conference on Current Trends towards Converging Technologies (ICCTCT)* , 2018.
- [23] R. Waranusast, N. Bundon, V. Timtong , C. Tangnoi and P. Pattanathaburt , “Machine vision techniques for motorcycle safety helmet detection.,” in *28th International conference on image and vision computing New Zealand (IVCNZ 2013)*, 2013.
- [24] P. Doungmala and K. Klubsuwan, “Helmet wearing detection in Thailand using Haar like feature and circle hough transform on image processing,” in *IEEE International Conference on Computer and Information Technology (CIT)*, 2016.
- [25] J. li, H. Liu, T. Wang, M. Jiang , S. Wang, K. Li and X. Zhao, “Safety helmet wearing detection based on image processing and machine learning.,” in *Ninth international conference on advanced computational intelligence (ICACI)* , 2017.