

# **Team Contest Reference Team:** Romath

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$\overline{n}$	Runtime $100 \cdot 10^6$ in 3s
[10, 11]	$\mathcal{O}(n!)$
< 22	$\mathcal{O}(n2^n)$
$\leq 100$	$\mathcal{O}(n^4)$
$\leq 400$	$\mathcal{O}(n^3)$
$\leq 2.000$	$\mathcal{O}(n^2 \log n)$
$\leq 10.000$	$\mathcal{O}(n^2)$
$\leq 1.000.000$	$\mathcal{O}(n \log n)$
$\leq 100.000.000$	$\mathcal{O}(n)$

byte (8 Bit, signed): -128 ...127 short (16 Bit, signed): -32.768 ...23.767 integer (32 Bit, signed): -2.147.483.648 ...2.147.483.647 long (64 Bit, signed):  $-2^{63}$ ... $2^{63}$  - 1

MD5: cat <string>| tr -d [:space:] | md5sum

# 1 DP

## 1.1 LongestIncreasingSubsequence

Computes the length of the longest increasing subsequence and is easy to be adapted.

Input: array arr containig a sequence of length N

Output: lenght of the longest increasing subsequence in arr

```
// This has not been tested yet
// (adapted from tested C++ Murcia Code)
public static int LISeasy(int[] arr, int N) {
   int[] m = new int[N];
   for (int i = N - 1; i >= 0; i--) {
        m[i] = 1; //init table
   for (int j = i + 1; j < N; j++) {</pre>
```

```
// if arr[i] increases the length
         // of subsequence from array[j]
         if (arr[j] > arr[i])
           if (m[i] < m[j] + 1)
             // store lenght of new subseq
12
             m[i] = m[j] + 1;
13
14
    }
15
    // find max in array
    int longest = 0;
17
    for (int i = 0; i < N; i++) {</pre>
      if (m[i] > longest)
         longest = m[i];
20
21
    return longest;
22
23 }
```

**MD5:** 7561f576d50b1dc6262568c0fc6c42dd |  $\mathcal{O}(n^2)$ 

## 1.2 LongestIncreasingSubsequence

Computes the longest increasing subsequence using binary search. Input: array arr containing a sequence and empty array p of length arr.length for storing indices of the LIS (might be usefull to have)

Output: array p containing the longest increasing subsequence

```
public static int[] LISfast(int[] arr, int[] p) {
    // p[k] stores index of the predecessor of arr[k]
    // in the LIS ending at arr[k]
    // m[j] stores index k of smallest value arr[k]
     // so there is a LIS of length j ending at arr[k]
    int[] m = new int[arr.length+1];
     int l = 0;
     for(int i = 0; i < arr.length; i++) {</pre>
       // bin search for the largest positive j <= l</pre>
       // with arr[m[j]] < arr[i]</pre>
11
       int lo = 1;
12
       int hi = l;
       while(lo <= hi) {</pre>
13
        int mid = (int) (((lo + hi) / 2.0) + 0.6);
14
         if(arr[m[mid]] <= arr[i])</pre>
15
           lo = mid+1;
16
         else
17
           hi = mid-1;
18
       }
19
       // lo is 1 greater than length of the
20
       // longest prefix of arr[i]
21
       int newL = lo;
22
       p[i] = m[newL-1];
23
       m[newL] = i;
24
       // if LIS found is longer than the ones
25
       // found before, then update l
26
       if(newL > l)
27
         l = newL;
28
29
     // reconstruct the LIS
30
     int[] s = new int[l];
31
     int k = m[l];
32
     for(int i= l-1; i>= 0; i--) {
33
      s[i] = arr[k];
34
       k = p[k];
35
    }
36
    return s;
37
38 }
```

**MD5:**  $1d75905f78041d832632cb76af985b8e \mid \mathcal{O}(n \log n)$ 

## 2 DataStructures

#### 2.1 Fenwick-Tree

Can be used for computing prefix sums.

```
//note that 0 can not be used
  int[] fwktree = new int[m + n + 1];
  public static int read(int index, int[] fenwickTree) {
     int sum = 0;
     while (index > 0) {
        sum += fenwickTree[index];
        index -= (index & -index);
     }
     return sum;
  }
  public static int[] update(int index, int addValue,
11
      int[] fenwickTree) {
     while (index <= fenwickTree.length - 1) {</pre>
        fenwickTree[index] += addValue;
13
        index += (index & -index);
     }
     return fenwickTree;
```

**MD5:** 410185d657a3a5140bde465090ff6fb5 |  $\mathcal{O}(\log n)$ 

## 2.2 Range Maximum Query

process processes an array A of length N in  $O(N \log N)$  such that query can compute the maximum value of A in interval [i,j]. Therefore M[a,b] stores the maximum value of interval  $[a,a+2^b-1]$ .

*Input*: dynamic table M, array to search A, length N of A, start index i and end index j

 $\ensuremath{\textit{Output:}}$  filled dynamic table M or the maximum value of A in interval [i,j]

```
public static void process(int[][] M, int[] A, int N)
    for(int i = 0; i < N; i++)</pre>
      M[i][0] = i;
     // filling table M
     // M[i][j] = max(M[i][j-1], M[i+(1<<(j-1))][j-1]),
     // cause interval of length 2^j can be partitioned
     // into two intervals of length 2^(j-1)
    for(int j = 1; 1 << j <= N; j++) {</pre>
      for(int i = 0; i + (1 << j) - 1 < N; i++) {
         if(A[M[i][j-1]] >= A[M[i+(1 << (j-1))][j-1]])</pre>
           M[i][j] = M[i][j-1];
11
         else
12
           M[i][j] = M[i + (1 << (j-1))][j-1];
13
14
    }
15
  }
16
17
  public static int query(int[][] M, int[] A, int N,
                                         int i, int j) {
     // k = | log_2(j-i+1) |
    int k = (int) (Math.log(j - i + 1) / Math.log(2));
21
    if(A[M[i][k]] >= A[M[j-(1 << k) + 1][k]])
22
      return M[i][k];
23
    else
      return M[j - (1 << k) + 1][k];
25
26 }
```

MD5: db0999fa40037985ff27dd1a43c53b80  $\mid \mathcal{O}(N \log N, 1)$ 

# 2.3 Union-Find 2.4 Su

Union-Find is a data structure that keeps track of a set of elements partitioned into a number of disjoint subsets. UnionFind creates n disjoint sets each containing one element. union joins the sets x and y are contained in. find returns the representative of the set x is contained in.

Input: number of elements n, element x, element y

 $\it Output:$  the representative of element  $\it x$  or a boolean indicating whether sets got merged.

```
1 class UnionFind {
    private int[] p = null;
                                                                12
    private int[] r = null;
                                                                13
    private int count = 0;
                                                                14
                                                                15
    public int count() {
                                                                16
       return count;
                                                                17
    } // number of sets
                                                                18
                                                                19
    public UnionFind(int n) {
                                                                20
10
11
       count = n; // every node is its own set
                                                                21
       r = new int[n]; // every node is its own tree with 22
12
             height 0
       p = new int[n];
                                                                24
13
       for (int i = 0; i < n; i++)</pre>
                                                                25
14
         p[i] = -1; // no parent = -1
                                                                26
15
                                                                27
16
    public int find(int x) {
19
       int root = x;
       while (p[root] >= 0) { // find root
21
         root = p[root];
22
       while (p[x] \ge 0) \{ // \text{ path compression } 
23
         int tmp = p[x];
25
         p[x] = root;
26
         x = tmp;
                                                                37
27
                                                                38
28
       return root;
29
30
    // return true, if sets merged and false, if already 42
31
          from same set
    public boolean union(int x, int y) {
32
                                                                44
       int px = find(x);
33
       int py = find(y);
34
                                                                45
       if (px == py)
35
                                                                46
         return false; // same set -> reject edge
36
       if (r[px] < r[py]) { // swap so that always h[px</pre>
37
                                                                48
           ]>=h[py]
                                                                49
         int tmp = px;
38
         px = py;
39
                                                                51
         py = tmp;
40
                                                                52
41
                                                                53
       p[py] = px; // hang flatter tree as child of
42
                                                                54
           higher tree
       r[px] = Math.max(r[px], r[py] + 1); // update (
43
           worst-case) height
                                                                57
       count--;
       return true;
45
46
```

```
MD5: 5c507168e1ffd9ead25babf7b3769cfd \mid \mathcal{O}(\alpha(n)) \mid
```

## 2.4 Suffix array

```
#include<vector>
#include<string>
#include<algorithm>
using namespace std;
vector<int> sa, pos, tmp, lcp;
string s;
int N, gap;
bool sufCmp(int i, int j) {
  if(pos[i] != pos[i])
    return pos[i] < pos[j];</pre>
  i += gap;
  j += gap;
  return (i < N && j < N) ? pos[i] < pos[j] : i > j;
void buildSA()
  N = s.size();
  for(int i = 0; i < N; ++i) {</pre>
    sa.push_back(i);
    pos.push_back(s[i]);
  tmp.resize(N);
  for(gap = 1;;gap *= 2) {
    sort(sa.begin(), sa.end(), sufCmp);
    for(int i = 0; i < N - 1; ++i) {</pre>
      tmp[i+1] = tmp[i] + sufCmp(sa[i], sa[i+1]);
    for(int i = 0; i < N; ++i) {</pre>
      pos[sa[i]] = tmp[i];
    if(tmp[N-1] == N-1) break;
}
void buildLCP()
  lcp.resize(N);
  for(int i = 0, k = 0; i < N; ++i) {</pre>
    if(pos[i] != N - 1) {
      for(int j = sa[pos[i] + 1]; s[i + k] == s[j + k
           ];) {
         ++k;
      }
      lcp[pos[i]] = k;
      if (k) --k;
  }
}
int main()
  string r, t;
  cin >> r >> t;
  s = r + "§" + t;
  buildSA();
  buildLCP();
  for(int i = 0; i < N; ++i) {</pre>
```

```
cout << sa[i] << "" << lcp[i] << endl;
62
    }
     int mx = 0, mxi = -1;
63
     for(int i = 0; i+1 < s.size(); ++i) {</pre>
64
       bool a_in_s = sa[i] < r.size(), b_in_s = sa[i+1] < 17
65
             r.size();
       if(a_in_s != b_in_s) {
                                                                19
         int l = lcp[i];
         if(l > mx) {
           mx = l;
                                                                22
           mxi = sa[i];
      }
72
    }
73
     cout << mx << endl;</pre>
74
     cout << s.substr(mxi, mx) << endl;</pre>
75
```

**MD5:** 96e0269748dc2834567a075768eb871a |  $\mathcal{O}(?)$ 

# 3 Graph

## 3.1 2SAT

```
1 //We assume that ind(not a) = ind(a) + N, with N being
        the number of variables
2 //could however be changed easily
g public static boolean 2SAT(Vertex[] G) {
    //call SCC
    double DFS(G);
    //check for contradiction
    boolean poss = true;
    for(int i = 0; i < S+A; i++) {</pre>
      if(G[i].comp == G[i + (S+A)].comp) {
        poss = false;
10
                                                             15
      }
11
                                                             16
    }
12
    return poss;
                                                             17
13
14
  }
```

**MD5:** 6c06a2b59fd3a7df3c31b06c58fdaaf5 |  $\mathcal{O}(V+E)$ 

## 3.2 Breadth First Search

Iterative BFS. Uses ref Vertex class, no Edge class needed. In this<sup>25</sup> version we look for a shortest path from s to t though we could also<sup>26</sup> find the BFS-tree by leaving out t. *Input*: IDs of start and goal vertex and graph as AdjList *Output*: true if there is a connection between s and g, false otherwise

```
public static boolean BFS(Vertex[] G, int s, int t) {
    //make sure that Vertices vis values are false etc
    Queue<Vertex> q = new LinkedList<Vertex>();
    G[s].vis = true;
    G[s].dist = 0;
    G[s].pre = -1;
    q.add(G[s]);
    //expand frontier between undiscovered and
        discovered vertices
    while(!q.isEmpty()) {
      Vertex u = q.poll();
10
      //when reaching the goal, return true
11
      //if we want to construct a BFS-tree delete this
12
          line
```

```
if(u.id = t) return true;
//else add adj vertices if not visited
for(Vertex v : u.adj) {
    if(!v.vis) {
       v.vis = true;
       v.dist = u.dist + 1;
       v.pre = u.id;
       q.add(v);
    }
    }
}
//did not find target
return false;
}
```

**MD5:** 71f3fa48b4f1b2abdff3557a27a9a136  $|\mathcal{O}(|V| + |E|)$ 

#### 3.3 BellmanFord

Finds shortest pathes from a single source. Negative edge weights are allowed. Can be used for finding negative cycles.

```
public static boolean bellmanFord(Vertex[] G) {
  //source is 0
  G[0].dist = 0;
  //calc distances
  //the path has max length |V|-1
  for(int i = 0; i < G.length-1; i++) {</pre>
    //each iteration relax all edges
    for(int j = 0; j < G.length; j++) {</pre>
      for(Edge e : G[j].adj) {
        if(G[j].dist != Integer.MAX_VALUE
        && e.t.dist > G[j].dist + e.w) {
          e.t.dist = G[j].dist + e.w;
      }
    }
  //check for negative-length cycle
  for(int i = 0; i < G.length; i++) {</pre>
    for(Edge e : G[i].adj) {
      if(G[i].dist != Integer.MAX_VALUE
          && e.t.dist > G[i].dist + e.w) {
        return true;
    }
  }
  return false;
```

**MD5:** d101e6b6915f012b3f0c02dc79e1fc6f |  $\mathcal{O}(|V| \cdot |E|)$ 

### 3.4 Bipartite Graph Check

Checks a graph represented as adjList for being bipartite. Needs a little adaption, if the graph is not connected.

*Input:* graph as adjList, amount of nodes N as int Output: true if graph is bipartite, false otherwise

```
public static boolean bipartiteGraphCheck(Vertex[] G){
   // use bfs for coloring each node
   G[0].color = 1;
   Queue<Vertex> q = new LinkedList<Vertex>();
   q.add(G[0]);
   while(!q.isEmpty()) {
```

```
Vertex u = q.poll();
       for(Vertex v : u.adj) {
        // if node i not yet visited,
        // give opposite color of parent node u
        if(v.color == -1) {
11
          v.color = 1-u.color;
12
          q.add(v);
13
        // if node i has same color as parent node u
        // the graph is not bipartite
15
        } else if(u.color == v.color)
           return false;
17
         // if node i has different color
         // than parent node u keep going
19
20
    }
21
    return true;
22
```

**MD5:** e93d242522e5b4085494c86f0d218dd4  $|\mathcal{O}(|V| + |E|)$ 

# 3.5 Maximum Bipartite Matching

Finds the maximum bipartite matching in an unweighted graph using DFS.

*Input:* An unweighted adjacency matrix boolean[M][N] with M anodes being matched to N nodes.

*Output:* The maximum matching. (For getting the actual matching, little changes have to be made.)

```
// A DFS based recursive function that returns true
2 // if a matching for vertex u is possible
  boolean bpm(boolean bpGraph[][], int u,
               boolean seen[], int matchR[]) {
    // Try every job one by one
    for (int v = 0; v < N; v++) {
      // If applicant u is interested in job v and v
       // is not visited
                                                           17
      if (bpGraph[u][v] && !seen[v]) {
                                                           18
        seen[v] = true; // Mark v as visited
10
                                                           19
11
         // If job v is not assigned to an applicant OR
12
         // previously assigned applicant for job v
13
        // (which is matchR[v]) has an alternate job
14
         // available. Since v is marked as visited in
15
        // the above line, matchR[v] in the following
16
         // recursive call will not get job v again
17
        if (matchR[v] < 0 ||
18
        bpm(bpGraph, matchR[v], seen, matchR)) {
19
          matchR[v] = u;
20
           return true;
21
22
        }
      }
23
    }
24
    return false;
25
  }
26
27
28 // Returns maximum number of matching from M to N
int maxBPM(boolean bpGraph[][]) {
    // An array to keep track of the applicants assigned
    // to jobs. The value of matchR[i] is the applicant
31
    // number assigned to job i, the value -1 indicates 10
32
    // nobody is assigned.
33
                                                           11
    int matchR[] = new int[N];
                                                           12
34
    // Initially all jobs are available
                                                           13
35
    for(int i = 0; i < N; ++i)</pre>
36
                                                           14
  matchR[i] = -1;
37
```

```
// Count of jobs assigned to applicants
int result = 0;
for (int u = 0; u < M; u++) {
    // Mark all jobs as not seen for next applicant.
    boolean seen[] = new boolean[N];
    for(int i = 0; i < N; ++i)
        seen[i] = false;
    // Find if the applicant u can get a job
    if (bpm(bpGraph, u, seen, matchR))
        result++;
}
return result;
}</pre>
```

**MD5:** a4cc90bf91c41309ad7aaa0c2514ff06 |  $\mathcal{O}(M \cdot N)$ 

### 3.6 Bitonic TSP

Input: Distance matrix d with vertices sorted in x-axis direction. Output: Shortest bitonic tour length

```
public static double bitonic(double[][] d) {
 int N = d.length;
  double[][] B = new double[N][N];
  for (int j = 0; j < N; j++) {
    for (int i = 0; i <= j; i++) {</pre>
      if (i < j - 1)
        B[i][j] = B[i][j - 1] + d[j - 1][j];
      else {
        double min = 0;
        for (int k = 0; k < j; k++) {
          double r = B[k][i] + d[k][j];
          if (min > r || k == 0)
            min = r;
        }
        B[i][j] = min;
      }
   }
 }
 return B[N-1][N-1];
```

**MD5:** 49fca508fb184da171e4c8e18b6ca4c7  $\mid \mathcal{O}(?)$ 

## 3.7 Single-source shortest paths in dag

Not tested but should be working fine Similar approach can be used for longest paths. Simply go through ts and add 1 to the largest longest path value of the incoming neighbors

```
public static void dagSSP(Vertex[] G, int s) {
    //calls topological sort method
    LinkedList<Integer> sorting = TS(G);
    G[s].dist = 0;
    //go through vertices in ts order
    for(int u : sorting) {
        for(Edge e : G[u].adj) {
            Vertex v = e.t;
            if(v.dist > u.dist + e.w) {
                 v.dist = u.dist + e.w;
                 v.pre = u.id;
            }
        }
    }
}
```

**MD5:** 552172db2968f746c4ac0bd322c665f9 |  $\mathcal{O}(|V| + |E|)$ 

## 3.8 Dijkstra

Finds the shortest paths from one vertex to every other vertex  $in_{26}$  the graph (SSSP).

For negative weights, add |min|+1 to each edge, later subtract from<sup>28</sup> result.

To get a different shortest path when edges are ints, add an  $\varepsilon = \frac{1}{k+1}$  on each edge of the shortest path of length k, run again.

*Input:* A source vertex s and an adjacency list G.

Output: Modified adj. list with distances from s and predcessor, vertices set.

```
public static void dijkstra(Vertex[] G, int s) {
    G[s].dist = 0:
    Tuple st = new Tuple(s, 0);
    PriorityQueue<Tuple> q = new PriorityQueue<Tuple>();
    q.add(st);
                                                            43
    while(!q.isEmpty()) {
      Tuple sm = q.poll();
      Vertex u = G[sm.id];
      //this checks if the Tuple is still useful, both
          checks should be equivalent
      if(u.vis || sm.dist > u.dist) continue;
      u.vis = true;
12
      for(Edge e : u.adj) {
13
        Vertex v = e.t;
14
        if(!v.vis && v.dist > u.dist + e.w) {
15
          v.pre = u.id;
          v.dist = u.dist + e.w;
17
          Tuple nt = new Tuple(v.id, v.dist);
18
          q.add(nt);
19
20
21
      }
    }
22
23 }
```

**MD5:** e46eb1b919179dab6a42800376f04d7a  $|\mathcal{O}(|E|\log|V|)$ 

## 3.9 EdmondsKarp

Finds the greatest flow in a graph. Capacities must be positive.

```
public static boolean BFS(Vertex[] G, int s, int t) {
    int N = G.length;
                                                              15
    for(int i = 0; i < N; i++) {</pre>
                                                              16
      G[i].vis = false;
                                                              17
    }
                                                              18
                                                              19
    Queue<Vertex> q = new LinkedList<Vertex>();
                                                              20
    G[s].vis = true;
                                                              21
    G[s].pre = -1;
                                                              22
    q.add(G[s]);
10
11
    while(!q.isEmpty()) {
12
      Vertex u = q.poll();
13
       if(u.id == t) return true;
14
       for(int i : u.adj.keySet()) {
15
         Edge e = u.adj.get(i);
16
         Vertex v = e.t;
17
        if(!v.vis && e.rw > 0) {
18
```

```
v.vis = true;
        v.pre = u.id;
        q.add(v);
    }
  }
  return (G[t].vis);
//We store the edges in the graph in a hashmap
public static int edKarp(Vertex[] G, int s, int t) {
  int maxflow = 0;
  while(BFS(G, s, t)) {
    int pflow = Integer.MAX_VALUE;
    for(int v = t; v!= s; v = G[v].pre) {
      int u = G[v].pre;
      pflow = Math.min(pflow, G[u].adj.get(v).rw);
    for(int v = t; v != s; v = G[v].pre) {
      int u = G[v].pre;
      G[u].adj.get(v).rw -= pflow;
      G[v].adj.get(u).rw += pflow;
    }
    maxflow += pflow;
  }
  return maxflow;
}
```

**MD5:** 6067fa877ff237d82294e7511c79d4bc |  $\mathcal{O}(|V|^2 \cdot |E|)$ 

## 3.10 Reference for Edge classes

Used for example in Dijkstra algorithm, implements edges with weight. Needs testing.

```
//for Kruskal we need to sort edges, use: java.lang.
    Comparable
class Edge implements Comparable<Edge> {}
class Edge {
  //for Kruskal it is helpful to store the start as
  //well, moreover we might not need the vertex class
  int s;
 int t;
  //for EdKarp we also want to store residual weights
  int rw;
  Vertex t;
  int w:
  public Edge(Vertex t, int w) {
    this.t = t;
    this.w = w;
    this.rw = w;
 public Edge(int s, int t, int w) {...}
 public int compareTo(Edge other) {
    return Integer.compare(this.w, other.w);
```

MD5: aae80ac4bfbfcc0b9ac4c65085f6f123 |  $\mathcal{O}(1)$ 

## 3.11 FloydWarshall

Finds all shortest paths. Paths in array next, distances in ans.

```
public static void floydWarshall(int[][] graph,
                         int[][] next, int[][] ans) {
    for(int i = 0; i < ans.length; i++)</pre>
       for(int j = 0; j < ans.length; j++)</pre>
         ans[i][j] = graph[i][j];
    for (int k = 0; k < ans.length; k++)</pre>
       for (int i = 0; i < ans.length; i++)</pre>
         for (int j = 0; j < ans.length; j++)</pre>
           if (ans[i][k] + ans[k][j] < ans[i][j]</pre>
                     && ans[i][k] < Integer.MAX_VALUE
                     && ans[k][j] < Integer.MAX_VALUE) {
12
             ans[i][j] = ans[i][k] + ans[k][j];
13
             next[i][j] = next[i][k];
14
           }
15
16
```

**MD5:** a98bbda7e53be8ee0df72dbd8721b306 |  $\mathcal{O}(|V|^3)$ 

## 3.12 Held Karp

Algorithm for TSP

```
public static int[] tsp(int[][] graph) {
     int n = graph.length;
     if(n == 1) return new int[]{0};
     //C stores the shortest distance to node of the
         second dimension, first dimension is the
         bitstring of included nodes on the way
     int[][] C = new int[1<<n][n];</pre>
     int[][] p = new int[1<<n][n];</pre>
     //initialize
     for(int k = 1; k < n; k++) {
       C[1<< k][k] = graph[0][k];
10
11
     for(int s = 2; s < n; s++) {
       for(int S = 1; S < (1<<n); S++) {</pre>
12
13
         if(Integer.bitCount(S)!=s || (S&1) == 1)
              continue;
         for(int k = 1; k < n; k++) {</pre>
14
           if((S & (1 << k)) == 0) continue;
15
           //Smk is the set of nodes without k
17
           int Smk = S ^ (1 << k);
19
           int min = Integer.MAX_VALUE;
20
           int minprev = 0;
21
           for(int m=1; m<n; m++) {</pre>
22
             if((Smk & (1<<m)) == 0) continue;</pre>
23
             //distance to m with the nodes in Smk +
24
                  connection from m to k
             int tmp = C[Smk][m] +graph[m][k];
25
             if(tmp < min) {</pre>
26
               min = tmp;
27
               minprev = m;
28
             }
29
           }
30
           C[S][k] = min;
31
           p[S][k] = minprev;
32
33
       }
34
    }
35
   //find shortest tour length
```

```
int min = Integer.MAX_VALUE;
  int minprev = -1;
  for(int k = 1; k < n; k++) {</pre>
    //Set of all nodes except for the first + cost
        from 0 to k
    int tmp = C[(1 << n) - 2][k] + graph[0][k];
    if(tmp < min) {</pre>
      min = tmp;
      minprev = k;
 }
  //Note that the tour has not been tested yet, only
      the correctness of the min-tour-value backtrack
      tour
 int[] tour = new int[n+1];
  tour[n] = 0;
  tour[n-1] = minprev;
 int bits = (1<<n)-2;
  for(int k = n-2; k>0; k--) {
    tour[k] = p[bits][tour[k+1]];
    bits = bits ^ (1<<tour[k+1]);
 }
 tour[0] = 0;
 return tour;
}
```

**MD5:** f3e9730287dcbf2695bf7372fc4bafe0 |  $\mathcal{O}(2^n n^2)$ 

#### 3.13 Iterative DFS

57

60

Simple iterative DFS, the recursive variant is a bit fancier. Not tested.

```
//if we want to start the DFS for different connected
      components, there is such a method in the
      recursive variant of DFS
  public static boolean ItDFS(Vertex[] G, int s, int t){
    //take care that all the nodes are not visited at
        the beginning
    Stack<Integer> S = new Stack<Integer>();
    s.push(s);
    while(!S.isEmpty()) {
      int u = S.pop();
      if(u.id == t) return true;
      if(!G[u].vis) {
        G[u].vis = true;
        for(Vertex v : G[u].adj) {
          if(!v.vis)
            S.push(v.id);
      }
    }
    return false;
17
```

**MD5:** 80f28ea9b2a04af19b48277e3c6bce9e |  $\mathcal{O}(|V| + |E|)$ 

## 3.14 Johnsons Algorithm

```
public static int[][] johnson(Vertex[] G) {
   Vertex[] Gd = new Vertex[G.length+1];
   int s = G.length;
   for(int i = 0; i < G.length; i++)
     Gd[i] = G[i];</pre>
```

```
//init new vertex with zero-weight-edges to each
         vertex
    Vertex S = new Vertex(G.length);
    for(int i = 0; i < G.length; i++)</pre>
       S.adj.add(new Edge(Gd[i], 0));
    Gd[G.length] = S;
10
11
    //bellman-ford to check for neg-weight-cycles and to
          adapt edges to enable running dijkstra
    if(bellmanFord(Gd, s)) {
13
       System.out.println("False");
       //this should not happen and will cause troubles
       return null;
17
    //change weights
18
    for(int i = 0; i < G.length; i++)</pre>
19
       for(Edge e : Gd[i].adj)
         e.w = e.w + Gd[i].dist - e.t.dist;
21
    //store distances to invert this step later
22
    int[] h = new int[G.length];
23
    for(int i = 0; i < G.length; i++)</pre>
24
25
       h[i] = G[i].dist;
26
27
    //create shortest path matrix
28
    int[][] apsp = new int[G.length][G.length];
29
    //now use original graph G
30
    //start a dijkstra for each vertex
31
    for(int i = 0; i < G.length; i++) {</pre>
32
       //reset weights
33
       for(int j = 0; j < G.length; j++) {</pre>
34
         G[j].vis = false;
35
         G[j].dist = Integer.MAX_VALUE;
36
37
       dijkstra(G, i);
38
       for(int j = 0; j < G.length; j++)</pre>
39
         apsp[i][j] = G[j].dist + h[j] - h[i];
40
41
    return apsp;
42
43 }
```

**MD5:** 0a5c741be64b65c5211fe6056ffc1e02 |  $\mathcal{O}(|V|^2 \log V + VE)$ 

#### 3.15 Kruskal

Computes a minimum spanning tree for a weighted undirected graph

```
public static int kruskal(Edge[] edges, int n) {
    Arrays.sort(edges);
    //n is the number of vertices
    UnionFind uf = new UnionFind(n);
    //we will only compute the sum of the MST, one could
         of course also store the edges
    int sum = 0;
    int cnt = 0;
    for(int i = 0; i < edges.length; i++) {</pre>
      if(cnt == n-1) break;
      if(uf.union(edges[i].s, edges[i].t)) {
10
        sum += edges[i].w;
11
        cnt++;
12
13
14
    return sum;
15
16 }
```

**MD5:** 91a1657706750a76d384d3130d98e5fb |  $\mathcal{O}(|E| + \log |V|)$ 

#### **3.16** Min Cut

Calculates the min cut using Edmonds Karp algorithm.

**MD5:** d41d8cd98f00b204e9800998ecf8427e |  $\mathcal{O}(?)$ 

## 3.17 Prim

```
//s is the startpoint of the algorithm, in general not
     too important; we assume that graph is connected
public static int prim(Vertex[] G, int s) {
  //make sure dists are maxint
  G[s].dist = 0;
 Tuple st = new Tuple(s, 0);
 PriorityQueue<Tuple> q = new PriorityQueue<Tuple>();
 q.add(st);
  //we will store the sum and each nodes predecessor
  int sum = 0;
 while(!q.isEmpty()) {
    Tuple sm = q.poll();
    Vertex u = G[sm.id];
    //u has been visited already
    if(u.vis) continue;
    //this is not the latest version of u
    if(sm.dist > u.dist) continue;
    u.vis = true;
    //u is part of the new tree and u.dist the cost of
         adding it
    sum += u.dist;
    for(Edge e : u.adj) {
     Vertex v = e.t;
     if(!v.vis && v.dist > e.w) {
        v.pre = u.id;
        v.dist = e.w;
        Tuple nt = new Tuple(v.id, e.w);
        q.add(nt);
   }
 }
 return sum:
```

**MD5:** c82f0bcc19cb735b4ef35dfc7ccfe197 |  $\mathcal{O}(?)$ 

### 3.18 Recursive Depth First Search

Recursive DFS with different options (storing times, connected/unconnected graph). Needs testing.

Input: A source vertex s, a target vertex t, and adjlist G and the time (0 at the start)

Output: Indicates if there is connection between s and t.

```
//if we want to visit the whole graph, even if it is
   not connected we might use this
public static void DFS(Vertex[] G) {
   //make sure all vertices vis value is false etc
   int time = 0;
   for(int i = 0; i < G.length; i++) {
      if(!G[i].vis) {
        //note that we leave out t so this does not work
        with the below function
      //adaption will not be too difficult though</pre>
```

```
//time should not always start at zero, change
             if needed
         recDFS(i, G, 0);
12
    }
13 }
  //first call with time = 0
  public static boolean recDFS(int s, int t, Vertex[] G,
    //it might be necessary to store the time of
         discovery
    time = time + 1;
18
    G[s].dtime = time;
19
    G[s].vis = true; //new vertex has been discovered
21
22
    //when reaching the target return true
23
    //not necessary when calculating the DFS-tree
24
    if(s == t) return true;
    for(Vertex v : G[s].adj) {
25
      //exploring a new edge
26
27
      if(!v.vis) {
28
         v.pre = u.id;
29
         if(recDFS(v.id, t, G)) return true;
30
31
    }
    //storing finishing time
32
    time = time + 1;
33
    G[s].ftime = time;
34
    return false;
35
36 }
                                                             13
```

**MD5:** 3cef44fd916e1aecfb0e3eacc355e2e3  $| \mathcal{O}(|V| + |E|)$ 

## **3.19 Strongly Connected Components**

```
public static void fDFS(Vertex u, LinkedList<Integer>
       sorting) {
     //compare with TS
     u.vis = true;
                                                              21
     for(Vertex v : u.out)
                                                              22
       if(!v.vis)
                                                              23
         fDFS(v, sorting);
     sorting.addFirst(u.id);
     return sorting;
9
11
  public static void sDFS(Vertex u, int cnt) {
     //basic DFS, all visited vertices get cnt
13
     u.vis = true;
                                                              31
14
     u.comp = cnt;
                                                              32
15
     for(Vertex v : u.in)
16
       if(!v.vis)
17
         sDFS(v, cnt);
18
  }
19
20
public static void doubleDFS(Vertex[] G) {
     //first calc a topological sort by first DFS
22
     LinkedList<Integer> sorting = new LinkedList<Integer 40
23
         >();
     for(int i = 0; i < G.length; i++)</pre>
24
                                                              42
       if(!G[i].vis)
25
                                                              43
         fDFS(G[i], sorting);
26
     for(int i = 0; i < G.length; i++)</pre>
27
       G[i].vis = false;
28
     //then go through the sort and do another DFS on G^T<sub>47</sub>
   //each tree is a component and gets a unique number 48
```

```
int cnt = 0;
for(int i : sorting)
  if(!G[i].vis)
    sDFS(G[i], cnt++);
}
```

**MD5:** 1e023258a9249a1bc0d6898b670139ea |  $\mathcal{O}(|V| + |E|)$ 

#### 3.20 Suurballe

Finds the min cost of two edge disjoint paths in a graph. If vertex disjoint needed, split vertices.

Input: Graph G, Source s, Target t

Output: Min cost as int

14

15

```
public static int suurballe(Vertex[] G, int s, int t){
  //this uses the usual dijkstra implementation with
      stored predecessors
  dijkstra(G, s);
  //Modifying weights
  for(int i = 0; i < G.length; i++)</pre>
    for(Edge e : G[i].adj)
      e.dist = e.dist - e.t.dist + G[i].dist;
  //reversing path and storing used edges
  int old = t;
  int pre = G[t].pre;
  HashMap<Integer, Integer> hm = new HashMap<Integer,
      Integer>();
  while(pre != -1) {
    for(int i = 0; i < G[pre].adj.size(); i++) {</pre>
      if(G[pre].adj.get(i).t.id == old) {
        hm.put(pre * G.length + old, G[pre].adj.get(i)
             .tdist);
        G[pre].adj.remove(i);
        break;
    boolean found = false;
    for(int i = 0; i < G[old].adj.size(); i++) {</pre>
      if(G[old].adj.get(i).t.id == pre) {
        G[old].adj.get(i).dist = 0;
        found = true;
        break;
      }
    if(!found)
      G[old].adj.add(new Edge(G[pre], 0));
    old = pre;
    pre = G[pre].pre;
  }
  //reset graph
  for(int i = 0; i < G.length; i++) {</pre>
    G[i].pre = -1;
    G[i].dist = Integer.MAX_VALUE;
    G[i].vis = false;
  }
  dijkstra(G, s);
  //store edges of second path
  old = t;
  pre = G[t].pre;
  while(pre != -1) {
    //store edges and remove if reverse
    for(int i = 0; i < G[pre].adj.size(); i++) {</pre>
      if(G[pre].adj.get(i).t.id == old) {
        if(!hm.containsKey(pre + old * G.length))
```

```
hm.put(pre * G.length + old, G[pre].adj.get(
                  i).tdist);
           else
             hm.remove(pre + old * G.length);
52
           break:
        }
53
54
      }
      old = pre;
55
      pre = G[pre].pre;
57
    //sum up weights
    int sum = 0;
    for(int i : hm.keySet())
      sum += hm.get(i);
    return sum;
62
                                                              18
63 }
```

**MD5:** 222dac2a859273efbbdd0ec0d6285dd7 |  $\mathcal{O}(VlogV + E)$ 

## 3.21 Kahns Algorithm for TS

Gives the specific TS where Vertices first in G are first in the sorting

```
public static LinkedList<Integer> TS(Vertex[] G) {
    LinkedList<Integer> sorting = new LinkedList<Integer</pre>
         >():
    PriorityQueue<Vertex> p = new PriorityQueue<Vertex</pre>
         >();
    //inc counts the number of incoming edges, if they
         are zero put the vertex in the queue
    for(int i = 0; i < G.length; i++) {</pre>
5
      if(G[i].inc == 0) {
        p.add(G[i]);
         G[i].vis = true;
      }
10
    while(!p.isEmpty()) {
11
      Vertex u = p.poll();
12
                                                              13
      sorting.add(u.id);
13
                                                              14
      //update inc
14
15
      for(Vertex v : u.out) {
16
         if(v.vis) continue;
17
         v.inc--;
18
         if(v.inc == 0) {
           p.add(v);
19
           v.vis = true;
20
21
      }
22
23
    return sorting;
24
25
```

**MD5:** e53d13c7467873d1c5d210681f4450d8 |  $\mathcal{O}(V+E)$ 

## 3.22 Topological Sort

```
//maybe checking if there are too many values in
           sorting is easier?!
      return sorting;
  }
  public static LinkedList<Integer> recTS(Vertex u,
      LinkedList<Integer> sorting) {
    u.vis = true;
    for(Vertex v : u.adj)
      if(v.vis)
        //the -1 indicates that it will not be possible
             to find an TS
        //there might be a much faster and elegant way (
             flag?!)
        sorting.addFirst(-1);
      else
        recTS(v, sorting);
    sorting.addFirst(u.id);
20
21
    return sorting;
22
  }
```

**MD5:** f6459575bf0d53344ddd9e5daf1dfbb8 |  $\mathcal{O}(|V| + |E|)$ 

## **3.23** Tuple

Simple tuple class used for priority queue in Dijkstra and Prim

```
class Tuple implements Comparable<Tuple> {
  int id;
  int dist;

public Tuple(int id, int dist) {
    this.id = id;
    this.dist = dist;
}

public int compareTo(Tuple other) {
    return Integer.compare(this.dist, other.dist);
}

4
}
```

**MD5:** fb1aa32dc32b9a2bac6f44a84e7f82c7 |  $\mathcal{O}(1)$ 

#### 3.24 Reference for Vertex classes

Used in many graph algorithms, implements a vertex with its edges. Needs testing.

```
class Vertex {
  int id;
  boolean vis = false;
  int pre = -1;

  //for dijkstra and prim
  int dist = Integer.MAX_VALUE;

  //for SCC store number indicating the dedicated
      component
  int comp = -1;

  //for DFS we could store the start and finishing
      times
  int dtime = -1;
  int ftime = -1;
```

```
//use an ArrayList of Edges if those information are
17
    ArrayList<Edge> adj = new ArrayList<Edge>();
18
    //use an ArrayList of Vertices else
    ArrayList<Vertex> adj = new ArrayList<Vertex>();
    //use two ArrayLists for SCC
21
    ArrayList<Vertex> in = new ArrayList<Vertex>();
    ArrayList<Vertex> out = new ArrayList<Vertex>();
    //for EdmondsKarp we need a HashMap to store Edges,
        Integer is target
    HashMap<Integer, Edge> adj = new HashMap<Integer,
        Edge>();
                                                            12
27
                                                            13
    //for bipartite graph check
28
                                                            14
29
    int color = -1;
                                                           15
30
                                                           16
31
    //we store as key the target
                                                           17
32
    public Vertex(int id) {
                                                            18
33
      this.id = id;
34
35 }
```

**MD5:** 90e8120ce9f665b07d4388e30395dd36 |  $\mathcal{O}(1)$ 

## 4 Math

#### 4.1 Binomial Coefficient

Gives binomial coefficient (n choose k)

```
public static long bin(int n, int k) {
   if (k == 0)
     return 1;
   else if (k > n/2)
     return bin(n, n-k);
   else
   return n*bin(n-1, k-1)/k;
   }
```

**MD5:** 32414ba5a444038b9184103d28fa1756 |  $\mathcal{O}(k)$ 

## 4.2 Binomial Matrix

Gives binomial coefficients for all  $K \le N$ .

```
public static long[][] binomial_matrix(int N, int K) {
19
long[][] B = new long[N+1][K+1];
20
for (int k = 1; k <= K; k++)

    B[0][k] = 0;
5 for (int m = 0; m <= N; m++)
    B[m][0] = 1;
7 for (int m = 1; m <= N; m++)
8 for (int k = 1; k <= K; k++)
9    B[m][k] = B[m-1][k-1] + B[m-1][k];
10 return B;
11</pre>
```

 $\textbf{MD5:} \ \texttt{e6f103bd9852173c02a1ec64264f4448} \mid \mathcal{O}(N \cdot K)$ 

## 4.3 Divisability

Calculates (alternating) k-digitSum for integer number given by<sub>32</sub>

```
public static long digit_sum(String M, int k, boolean
    alt) {
  long dig_sum = 0;
  int vz = 1;
  while (M.length() > k) {
    if (alt) vz *= −1;
    dig_sum += vz*Integer.parseInt(M.substring(M.
        length()-k));
    M = M.substring(0, M.length()-k);
  }
  if (alt)
    vz \star = -1;
  dig_sum += vz*Integer.parseInt(M);
  return dig_sum;
}
// example: divisibility of M by 13
public static boolean divisible13(String M) {
  return digit_sum(M, 3, true)%13 == 0;
}
```

**MD5:** 33b3094ebf431e1e71cd8e8db3c9cdd6 |  $\mathcal{O}(|M|)$ 

#### 4.4 Graham Scan

Multiple unresolved issues: multiple points as well as collinearity. N denotes the number of points

```
public static Point[] grahamScan(Point[] points) {
  //find leftmost point with lowest y-coordinate
  int xmin = Integer.MAX_VALUE;
  int ymin = Integer.MAX_VALUE;
  int index = -1;
  for(int i = 0; i < points.length; i++) {</pre>
    if(points[i].y < ymin || (points[i].y == ymin &&</pre>
        points[i].x < xmin)) {</pre>
      xmin = points[i].x;
      ymin = points[i].y;
      index = i;
   }
 }
  //get that point to the start of the array
 Point tmp = new Point(points[index].x, points[index
      ].y);
  points[index] = points[0];
 points[0] = tmp;
  for(int i = 1; i < points.length; i++)</pre>
    points[i].src = points[0];
  Arrays.sort(points, 1, points.length);
  //for collinear points eliminate all but the
      farthest
  boolean[] isElem = new boolean[points.length];
  for(int i = 1; i < points.length-1; i++) {</pre>
    Point a = new Point(points[i].x - points[i].src.x,
         points[i].y - points[i].src.y);
    Point b = new Point(points[i+1].x - points[i+1].
        src.x, points[i+1].y - points[i+1].src.y);
    if(Calc.crossProd(a, b) == 0)
      isElem[i] = true;
  //works only if there are more than three non-
      collinear points
 Stack<Point> s = new Stack<Point>();
  int i = 0;
  for(; i < 3; i++) {</pre>
    while(isElem[i++]);
    s.push(points[i]);
```

```
for(; i < points.length; i++) {</pre>
35
       if(isElem[i]) continue;
       while(true) {
37
         Point first = s.pop();
         Point second = s.pop();
39
         s.push(second);
         Point a = new Point(first.x - second.x, first.y
             - second.y);
         Point b = new Point(points[i].x - second.x,
             points[i].y - second.y);
         //use >= if straight angles are needed
         if(Calc.crossProd(a, b) > 0) {
44
           s.push(first);
45
           s.push(points[i]);
           break;
47
48
         }
49
      }
50
    }
51
    Point[] convexHull = new Point[s.size()];
    for(int j = s.size()-1; j >= 0; j--)
52
      convexHull[j] = s.pop();
53
54
    return convexHull;
55
    /*Sometimes it might be necessary to also add points
          to the convex hull that form a straight angle.
         The following lines of code achieve this. Only
         at the first and last diagonal we have to add
         those. Of course the previous return-statement
         has to be deleted as well as allowing straight
         angles in the above implementation. */
                                                            15
56 }
                                                            16
57 class Point implements Comparable<Point> {
                                                            17
    Point src; //set seperately in GrahamScan method
58
                                                            18
    int x;
59
                                                            19
60
    int y;
61
    public Point(int x, int y) {
62
      this.x = x;
63
      this.y = y;
64
65
66
    //might crash if one point equals src
67
    //major issues with multiple points on same location
68
        -1
    public int compareTo(Point cmp) {
69
    Point a = new Point(this.x - src.x, this.y - src.y);
70
    Point b = new Point(cmp.x - src.x, cmp.y - src.y);
71
    //checks if points are identical
72
    if(a.x == b.x && a.y == b.y) return 0;
73
    //if same angle, sort by dist
74
    if(Calc.crossProd(a, b) == 0 && Calc.dotProd(a, b) >
75
          0)
       return Integer.compare(Calc.dotProd(a, a), Calc.
76
           dotProd(b, b));
    //angle of a is 0, thus b>a
77
                                                            12
    if(a.y == 0 && a.x > 0) return -1;
78
                                                            13
    //angle of b is 0, thus a>b
                                                            14
    if(b.y == 0 \&\& b.x > 0) return 1;
                                                            15
    //a ist between 0 and 180, b between 180 and 360
                                                            16
    if(a.y > 0 && b.y < 0) return -1;
                                                            17
    if(a.y < 0 && b.y > 0) return 1;
    //return negative value if cp larger than zero
    return Integer.compare(0, Calc.crossProd(a, b));
85
                                                            19
86
87 }
                                                            21
                                                            22
89 class Calc {
    public static int crossProd(Point p1, Point p2) {
```

```
return p1.x * p2.y - p2.x * p1.y;
}
public static int dotProd(Point p1, Point p2) {
   return p1.x * p2.x + p1.y * p2.y;
}
```

**MD5:** 2555d858fadcfe8cb404a9c52420545d  $| \mathcal{O}(N \log N) |$ 

### 4.5 Iterative EEA

Berechnet den ggT zweier Zahlen a und b und deren modulare Inverse  $x=a^{-1} \mod b$  und  $y=b^{-1} \mod a$ .

```
// Extended Euclidean Algorithm - iterativ
public static long[] eea(long a, long b) {
  if (b > a) {
   long tmp = a;
    a = b:
    b = tmp:
 long x = 0, y = 1, u = 1, v = 0;
 while (a != 0) {
   long q = b / a, r = b % a;
    long m = x - u * q, n = y - v * q;
    b = a; a = r; x = u; y = v; u = m; v = n;
 long gcd = b;
  // x = a^{-1} \% b, y = b^{-1} \% a
  // ax + by = gcd
 long[] erg = { gcd, x, y };
  return erg;
```

**MD5:** 81fe8cd4adab21329dcbe1ce0499ee75  $| \mathcal{O}(\log a + \log b) |$ 

## 4.6 Polynomial Interpolation

```
public class interpol {
  // divided differences for points given by vectors x
       and y
  public static rat[] divDiff(rat[] x, rat[] y) {
    rat[] temp = y.clone();
    int n = x.length;
    rat[] res = new rat[n];
    res[0] = temp[0];
    for (int i=1; i < n; i++) {</pre>
      for (int j = 0; j < n-i; j++) {</pre>
        temp[j] = (temp[j+1].sub(temp[j])).div(x[j+i].
            sub(x[j]));
      res[i] = temp[0];
   }
    return res;
  // evaluates interpolating polynomial p at t for
  // x-coordinates and divided differences
 public static rat p(rat t, rat[] x, rat[] dD) {
    int n = x.length;
    rat p = new rat(0);
    for (int i = n-1; i > 0; i--) {
      p = (p.add(dD[i])).mult(t.sub(x[i-1]));
```

```
p = p.add(dD[0]);
       return p;
28
29 }
31 // implementation of rational numbers
32 class rat {
                                                                100
     public long c;
34
                                                                101
     public long d;
35
                                                                102
     public rat (long c, long d) {
                                                               104
37
       this.c = c;
38
       this.d = d;
39
       this.shorten();
40
41
42
     public rat (long c) {
43
44
      this.c = c;
45
       this.d = 1;
46
47
48
     public static long ggT(long a, long b) {
49
       while (b != 0) {
         long h = a%b;
50
         a = b;
51
         b = h:
52
53
       }
54
       return a;
55
56
     public static long kgV(long a, long b) {
57
       return a*b/ggT(a,b);
58
59
60
     public static rat[] commonDenominator(rat[] c) {
61
       long kgV = 1;
62
       for (int i = 0; i < c.length; i++) {</pre>
63
         kgV = kgV(kgV, c[i].d);
64
65
       for (int i = 0; i < c.length; i++) {</pre>
66
         c[i].c *= kgV/c[i].d;
67
         c[i].d *= kgV/c[i].d;
68
69
       return c;
70
71
72
73
     public void shorten() {
74
       long ggT = ggT(this.c, this.d);
75
       this.c = this.c / ggT;
       this.d = this.d / ggT;
76
       if (d < 0) {
77
         this.d *= -1;
78
         this.c *= -1;
79
80
81
     public String toString() {
83
       if (this.d == 1) return ""+c;
84
       return ""+c+"/"+d;
85
87
88
     public rat mult(rat b) {
89
       return new rat(this.c*b.c, this.d*b.d);
90
91
     public rat div(rat b) {
92
```

```
return new rat(this.c*b.d, this.d*b.c);
    }
    public rat add(rat b) {
      long new_d = kgV(this.d, b.d);
      long new_c = this.c*(new_d/this.d) + b.c*(new_d/b.
      return new rat(new_c, new_d);
    public rat sub(rat b) {
      return this.add(new rat(-b.c, b.d));
105
  }
```

**MD5:** e7b408030f7e051e93a8c55056ba930b |  $\mathcal{O}(?)$ 

#### 4.7 **Root of permutation**

94

16

17

18

20

21

22

23

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25

26

27

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29

31

35

36

37

41

42

Calculates the K'th root of permutation of size N. Number at place i indicates where this dancer ended. needs commenting

```
public static int[] rop(int[] perm, int N, int K) {
  boolean[] incyc = new boolean[N];
  int[] cntcyc = new int[N+1];
  int[] g = new int[N+1];
  int[] needed = new int[N+1];
  for(int i = 1; i < N+1; i++) {</pre>
    int j = i;
    int k = K;
    int div;
    while(k > 1 && (div = gcd(k, i)) > 1) {
      k /= div;
      j *= div;
    needed[i] = j;
    g[i] = gcd(K, j);
  }
  HashMap<Integer, ArrayList<Integer>> hm = new
      HashMap<Integer, ArrayList<Integer>>();
  for(int i = 0; i < N; i++) {</pre>
    if(incyc[i]) continue;
    ArrayList<Integer> cyc = new ArrayList<Integer>();
    cyc.add(i);
    incyc[i] = true;
    int newelem = perm[i];
    while(newelem != i) {
      cyc.add(newelem);
      incyc[newelem] = true;
      newelem = perm[newelem];
    int len = cyc.size();
    cntcyc[len]++;
    if(hm.containsKey(len)) {
      hm.get(len).addAll(cyc);
    } else {
      hm.put(len, cyc);
  }
  boolean end = false;
  for(int i = 1; i < N+1; i++) {</pre>
    if(cntcyc[i] % g[i] != 0) end = true;
  if(end) {
    //not possible
    return null;
```

```
} else {
       int[] out = new int[N];
46
       for(int length = 0; length < N; length++) {</pre>
         if(!hm.containsKey(length)) continue;
         ArrayList<Integer> p = hm.get(length);
         int totalsize = p.size();
50
         int diffcyc = totalsize / needed[length];
51
         for(int i = 0; i < diffcyc; i++) {</pre>
52
           int[] c = new int[needed[length]];
53
           for(int it = 0; it < needed[length]; it++) {</pre>
             c[it] = p.get(it + i * needed[length]);
           int move = K / (needed[length]/length);
57
           int[] rewind = new int[needed[length]];
                                                              11
           for(int set = 0; set < needed[length]/length;</pre>
                set++) {
             int pos = set * length;
             for(int it = 0; it < length; it++) {</pre>
61
                                                              15
               rewind[pos] = c[it + set * length];
62
               pos = ((pos - set * length + move) %
63
                    length)+ set * length;
             }
64
           }
65
           int[] merge = new int[needed[length]];
66
           for(int it = 0; it < needed[length]/length; it</pre>
67
                ++) {
             for(int set = 0; set < length; set++) {</pre>
68
               merge[set * needed[length] / length + it]
69
                    = rewind[it * length + set];
70
             }
71
           for(int it = 0; it < needed[length]; it++) {</pre>
72
             out[merge[it]] = merge[(it+1) % needed[
73
                  length]];
74
           }
75
76
77
       return out;
78
    }
79
  }
```

**MD5:** b446a7c21eddf7d14dbdc71174e8d498 |  $\mathcal{O}(?)$ 

#### 4.8 Sieve of Eratosthenes

Calculates Sieve of Eratosthenes.

Input: A integer N indicating the size of the sieve.

Output: A boolean array, which is true at an index i iff i is prime.

**MD5:** 95704ae7c1fe03e91adeb8d695b2f5bb  $\mid \mathcal{O}(n) \mid$ 

#### 4.9 Greatest Common Devisor

Calculates the gcd of two numbers a and b or of an array of numbers a and b array a and b array a and a array a and a array a and a array a and a array a

*Input:* Numbers a and b or array of numbers input Output: Greatest common devisor of the input

```
private static long gcd(long a, long b) {
    while (b > 0) {
        long temp = b;
        b = a % b; // % is remainder
        a = temp;
    }
    return a;
}

private static long gcd(long[] input) {
    long result = input[0];
    for(int i = 1; i < input.length; i++)
    result = gcd(result, input[i]);
    return result;
}</pre>
```

**MD5:** 48058e358a971c3ed33621e3118818c2  $|\mathcal{O}(\log a + \log b)|$ 

## 4.10 Least Common Multiple

Calculates the lcm of two numbers a and b or of an array of numbers input.

*Input:* Numbers a and b or array of numbers input Output: Least common multiple of the input

```
private static long lcm(long a, long b) {
    return a * (b / gcd(a, b));
}

private static long lcm(long[] input) {
    long result = input[0];
    for(int i = 1; i < input.length; i++)
        result = lcm(result, input[i]);
    return result;
}</pre>
```

**MD5:** 3cfaab4559ea05c8434d6cf364a24546  $| \mathcal{O}(\log a + \log b) |$ 

#### 4.11 Fourier transform

```
#include<complex>
#include<vector>
#include<algorithm>
#include<cmath>
using namespace std;
void iterativefft(const vector<long long> &pol, vector
    <complex<double>> &fft, int n, bool inv)
    //copy pol into fft
    if(!inv) {
        for(int i = 0; i < n; ++i) {</pre>
            complex<double> cp (pol[i], 0);
            fft[i] = cp;
        }
    //swap positions accordingly
    for(int i = 0, j = 0; i < n; ++i) {
        if(i < j) swap(fft[i], fft[j]);</pre>
        int m = n >> 1;
        while(1 <= m && m <= j) j -= m, m >>= 1;
```

```
j += m;
23
       for(int m = 1; m <= n; m <<= 1) { //<= or <
24
           double theta = (inv ? -1 : 1) * 2 * M_PI / m;
25
           complex<double> wm(cos(theta), sin(theta));
           for(int k = 0; k < n; k += m) {</pre>
27
               complex<double> w = 1;
               for(int j = 0; j < m/2; ++j) {
                    complex<double> t = w * fft[k + j + m
                        /2];
                    complex<double> u = fft[k + j];
                    fft[k + j] = u + t;
                    fft[k + j + m/2] = u - t;
                    w = w*wm;
               }
           }
37
       if(inv) {
38
           for(int i = 0; i < n; ++i) {</pre>
39
40
               fft[i] /= complex<double> (n);
41
42
43 }
44
                                                             15
45 int main()
                                                             16
46
  {
                                                             17
       int N:
47
                                                             18
       cin >> N:
48
                                                             19
       vector<long long> pol (262144);
49
       int min = 60000;
50
       int max = -60000;
51
       for(int i = 0; i < N; ++i) {</pre>
52
           int ind;
53
           cin >> ind;
54
           if(ind < min) min = ind;</pre>
55
           if(ind > max) max = ind;
56
           ++pol[ind+65536];
57
58
       vector<complex<double>> fft (262144);
59
       iterativefft(pol, fft, 262144, false);
60
       for(int i = 0; i < 262144; ++i) {
61
           fft[i] *= fft[i];
62
63
       iterativefft(pol, fft, 262144, true);
64
       long long sum = 0;
65
       for(int i = 81072; i <= 181072; ++i) {
66
           int ind = i - 131072;
67
           if(ind < min) continue;</pre>
68
           if(ind > max) break;
69
           long long resi = round(fft[i].real());
70
           if(ind % 2 == 0 && ind != 0) {
71
               resi -= pol[ind/2 + 65536] * pol[ind/2 +
72
               resi += pol[ind/2 + 65536]*(pol[ind/2 +
73
                    65536]-1);
           resi *= pol[ind + 65536];
           if(ind != 0) {
               resi -= 2*pol[65536] * pol[ind + 65536] *
                    pol[ind + 65536];
               resi += 2*pol[65536] * pol[ind + 65536] *
                    (pol[ind + 65536]-1);
           }
           sum += resi;
       sum -= pol[65536] * pol[65536];
82
       sum += pol[65536] * (pol[65536] - 1) * (pol[65536]
83
            - 2);
```

```
cout << sum << endl;
}</pre>
```

**MD5:** fd9669c4967b6f26c13f464f98bdfb2a |  $\mathcal{O}(?)$ 

## 4.12 Matrix exponentiation

```
void mult(int a[][nos], int b[][nos], int N)
    int res[nos][nos] = {0};
    for(int i = 0; i < N; i++) {</pre>
        for(int j = 0; j < N; j++) {</pre>
             for(int k = 0; k < N; k++) {
                 res[i][j] = (res[i][j] + a[i][k]*b[k][
                     j]) % 10000;
            }
        }
    for(int i = 0; i < N; i++) {</pre>
        for(int j = 0; j < N; j++) {</pre>
            a[i][j] = res[i][j];
        }
    }
        //start with g^L by succ squaring
        int res[nos][nos] = {0};
        for(int i = 0; i < N; i++) {</pre>
             for(int j = 0; j < N; j++) {
                 if(i == j) res[i][j] = 1;
        for(int i = 0; (1 << i) <= L; i++) {
            if(((1 << i) & L) == (1 << i)) {
                 mult(res, g, N);
            mult(g, g, N);
        }
```

MD5: dcabdd3a0beceb4221f4c41071ac9b6d |  $\mathcal{O}(?)$ 

## 4.13 phi function calculator

takes sqrt(n) time

```
int phi(int n)
{
    double result = n;
    for(int p = 2; p * p <= n; ++p) {
        if(n % p == 0) {
            while(n % p == 0) n /= p;
            result *= (1.0 - (1.0 / (double) p));
        }
    }
    if(n > 1) result *= (1.0 - (1.0 / (double) n));
    return round(result);
}
```

**MD5:**  $2ec930cc10935f1638700bb74e3439d9 | \mathcal{O}(?)$ 

## 4.14 prints farey seq

```
def farey( n, asc=True ):
    """Python function to print the nth Farey sequence
    , either ascending or descending."""
```

```
if asc:
    a, b, c, d = 0, 1, 1 , n # (*)

else:
    a, b, c, d = 1, 1, n-1, n # (*)

print "%d/%d" % (a,b)

while (asc and c <= n) or (not asc and a > 0):
    k = int((n + b)/d)
    a, b, c, d = c, d, k*c - a, k*d - b

print "%d/%d" % (a,b)
```

**MD5:** 5fe50f5717cb7d4e3eb91c8c8f6a1e85 |  $\mathcal{O}(?)$ 

## 5 Misc

## 5.1 Binary Search

Binary searchs for an element in a sorted array.

Input: sorted array to search in, amount N of elements in array, element to search for a

*Output:* returns the index of a in array or -1 if array does not so contain a

```
12
  public static int BinarySearch(int[] array,
                                                               13
                                         int N, int a) {
    int lo = 0;
                                                               14
    int hi = N-1;
                                                               15
    // a might be in interval [lo,hi] while lo <= hi
                                                               16
                                                               17
    while(lo <= hi) {</pre>
                                                               18
       int mid = (lo + hi) / 2;
                                                               19
       // if a > elem in mid of interval,
                                                               20
       // search the right subinterval
                                                               21
       if(array[mid] < a)</pre>
                                                               22
         lo = mid+1;
11
       // else if a < elem in mid of interval,
12
       // search the left subinterval
13
       else if(array[mid] > a)
        hi = mid-1;
15
       // else a is found
16
       else
17
         return mid;
18
19
    // array does not contain a
20
    return -1;
21
22 }
```

**MD5:** 203da61f7a381564ce3515f674fa82a4  $\mid \mathcal{O}(\log n)$ 

## 5.2 Next number with n bits set

From x the smallest number greater than x with the same amount of bits set is computed. Little changes have to be made, if the calculated number has to have length less than 32 bits.

*Input*: number x with n bits set (x = (1 << n) - 1)

Output: the smallest number greater than x with n bits set

```
public static int nextNumber(int x) {
    //break when larger than limit here
    if(x == 0) return 0;
    int smallest = x & -x;
    int ripple = x + smallest;
    int new_smallest = ripple & -ripple;
    int ones = ((new_smallest/smallest) >> 1) - 1;
    return ripple | ones;
```

```
MD5: 2d8a79cb551648e67fc3f2f611a4f63c | O(1)
```

#### 5.3 Next Permutation

Returns true if there is another permutation. Can also be used to compute the nextPermutation of an array.

*Input:* String a as char array

*Output:* true, if there is a next permutation of a, false otherwise

```
public static boolean nextPermutation(char[] a) {
  int i = a.length - 1;
  while(i > 0 && a[i-1] >= a[i])
    i--;
  if(i <= 0)
    return false;
  int j = a.length - 1;
  while (a[j] <= a[i-1])
    j--;
  char tmp = a[i - 1];
  a[i - 1] = a[j];
  a[j] = tmp;
  j = a.length - 1;
  while(i < j) {</pre>
    tmp = a[i];
    a[i] = a[j];
    a[j] = tmp;
    i++;
    j--;
  }
  return true;
```

**MD5:** 7d1fe65d3e77616dd2986ce6f2af089b |  $\mathcal{O}(n)$ 

## 5.4 Mo's algorithm

Works for queries on intervals. Sort queries and add, remove on borders in O(1). Thus only usable when this is possible for the task.

```
#include<vector>
#include<utilitv>
#include<algorithm>
using namespace std;
int BLOCK_SIZE;
int cur_answer;
vector<int> lmen;
vector<int> lwomen;
vector<int> cmen:
vector<int> cwomen;
bool cmp(const pair<pair<int, int>, int> &i, const
    pair<pair<int, int>, int> &j) {
    if(i.first.first / BLOCK_SIZE != j.first.first /
        BLOCK_SIZE) {
        return i.first.first < j.first.first;</pre>
    return i.first.second < j.first.second;</pre>
```

```
void add(int i, int j) {
       //adds values i, j to function
22
       cur_answer -= min(cmen[i], cwomen[i]);
23
       cur_answer -= min(cmen[j], cwomen[j]);
24
       if(i == j) cur_answer += min(cmen[j], cwomen[j]); 92
25
       ++cmen[i];
26
       ++cwomen[j];
27
       cur_answer += min(cmen[i], cwomen[i]);
       cur_answer += min(cmen[j], cwomen[j]);
       if(i == j) cur_answer -= min(cmen[j], cwomen[j]);
31
32
  void remove(int i, int j) {
       //removes values i, j from function
34
       cur_answer -= min(cmen[i], cwomen[i]);
35
       cur_answer -= min(cmen[j], cwomen[j]);
       if(i == j) cur_answer += min(cmen[j], cwomen[j]);
37
38
       --cmen[i];
       --cwomen[j];
39
       cur_answer += min(cmen[i], cwomen[i]);
40
       cur_answer += min(cmen[j], cwomen[j]);
41
42
       if(i == j) cur_answer -= min(cmen[j], cwomen[j]);
43
  }
44
45 int main()
46
  {
       int N, M, K;
47
       cin >> N >> M >> K;
48
       lmen.resize(N);
49
       lwomen.resize(N);
50
       cmen.resize(K);
51
       cwomen.resize(K);
52
       BLOCK_SIZE = static_cast<int>(sqrt(N));
53
       vector<pair<int, int>, int>> queries(M);
54
       vector<int> answers(M);
55
       for(int i = 0; i < N; ++i) {</pre>
56
           cin >> lmen[i];
57
58
       for(int i = 0; i < N; ++i) {</pre>
59
           cin >> lwomen[i];
60
61
       for(int i = 0; i < M; ++i) {</pre>
62
           cin >>queries[i].first.first >> queries[i].
63
                first.second;
           queries[i].second = i;
64
65
       //sort the queries into buckets
66
       sort(queries.begin(), queries.end(), cmp);
67
       int mo_left = 0, mo_right = -1;
68
       for(int i = 0; i < M; ++i) {</pre>
69
           int left = queries[i].first.first;
70
           int right = queries[i].first.second;
71
           while(mo_right < right) {</pre>
72
               ++mo right;
73
               add(lmen[mo_right], lwomen[mo_right]);
           while(mo_right > right) {
               remove(lmen[mo_right], lwomen[mo_right]);
               --mo_right;
           while(mo_left < left) {</pre>
               remove(lmen[mo_left], lwomen[mo_left]);
               ++mo_left;
           while(mo_left > left) {
               --mo_left;
85
               add(lmen[mo_left], lwomen[mo_left]);
```

```
}
    answers[queries[i].second] = cur_answer;
}
for(int i = 0; i < M; ++i) {
    cout << answers[i] << endl;
}
</pre>
```

**MD5:** a7af72b67f95a76818d1dabadf4f9e5c |  $\mathcal{O}(?)$ 

# 6 String

#### 6.1 Knuth-Morris-Pratt

*Input:* String s to be searched, String w to search for. *Output:* Array with all starting positions of matches

```
public static ArrayList<Integer> kmp(String s, String
    w) {
 ArrayList<Integer> ret = new ArrayList<>();
  //Build prefix table
  int[] N = new int[w.length()+1];
  int i=0; int j =-1; N[0]=-1;
 while (i<w.length()) {</pre>
    while (j>=0 && w.charAt(j) != w.charAt(i))
      j = N[j];
    i++; j++; N[i]=j;
  //Search string
  i=0; j=0;
  while (i<s.length()) {</pre>
    while (j>=0 && s.charAt(i) != w.charAt(j))
      j = N[j];
      i++; j++;
      if (j==w.length()) { //match found
      ret.add(i-w.length()); //add its start index
      j = N[j];
  return ret;
```

**MD5:**  $3cb03964744db3b14b9bff265751c84b \mid \mathcal{O}(n+m)$ 

### **6.2** Levenshtein Distance

Calculates the Levenshtein distance for two strings (minimum number of insertions, deletions, or substitutions).

*Input:* A string a and a string b.

Output: An integer holding the distance.

**MD5:** 79186003b792bc7fd5c1ffbbcfc2b1c6 |  $\mathcal{O}(|a| \cdot |b|)$ 

## **6.3** Longest Common Subsequence

Finds the longest common subsequence of two strings.

*Input:* Two strings string1 and string2.

Output: The LCS as a string.

```
public static String longestCommonSubsequence(String
      string1, String string2) {
    char[] s1 = string1.toCharArray();
    char[] s2 = string2.toCharArray();
    int[][] num = new int[s1.length + 1][s2.length + 1];
    // Actual algorithm
    for (int i = 1; i <= s1.length; i++)</pre>
      for (int j = 1; j <= s2.length; j++)</pre>
        if (s1[i - 1] == s2[j - 1])
          num[i][j] = 1 + num[i - 1][j - 1];
10
          num[i][j] = Math.max(num[i - 1][j], num[i][j -
11
                1]);
    // System.out.println("length of LCS = " + num[s1.
12
         length][s2.length]);
    int s1position = s1.length, s2position = s2.length;
13
    List<Character> result = new LinkedList<Character>()
14
    while (s1position != 0 && s2position != 0) {
15
      if (s1[s1position - 1] == s2[s2position - 1]) {
16
        result.add(s1[s1position - 1]);
17
        s1position--;
18
19
        s2position--;
20
      } else if (num[s1position][s2position - 1] >= num[
           s1position][s2position])
21
        s2position--;
      else
22
        s1position--;
23
24
    Collections.reverse(result);
25
    char[] resultString = new char[result.size()];
    int i = 0;
    for (Character c : result) {
      resultString[i] = c;
      i++;
31
    return new String(resultString);
32
33 }
```

MD5: 4dc4ee3af14306bea5724ba8a859d5d4  $\mid \mathcal{O}(n \cdot m)$ 

## 6.4 Longest common substring

gets two String and finds all LCSs and returns them in a set

```
public static TreeSet<String> LCS(String a, String b)
{
```

```
int[][] t = new int[a.length()+1][b.length()+1];
  for(int i = 0; i <= b.length(); i++)</pre>
    t[0][i] = 0;
  for(int i = 0; i <= a.length(); i++)</pre>
    t[i][0] = 0;
  for(int i = 1; i <= a.length(); i++)</pre>
    for(int j = 1; j <= b.length(); j++)</pre>
      if(a.charAt(i-1) == b.charAt(j-1))
         t[i][j] = t[i-1][j-1] + 1;
      else
         t[i][j] = 0;
  int max = -1;
  for(int i = 0; i <= a.length(); i++)</pre>
    for(int j = 0; j <= b.length(); j++)</pre>
      if(max < t[i][j])
         max = t[i][j];
  if(max == 0 || max == −1)
    return new TreeSet<String>();
  TreeSet<String> res = new TreeSet<String>();
  for(int i = 0; i <= a.length(); i++)</pre>
    for(int j = 0; j <= b.length(); j++)</pre>
      if(max == t[i][j])
         res.add(a.substring(i-max, i));
  return res;
}
```

MD5: 9de393461e1faebe99af3ff8db380bde |  $\mathcal{O}(|a|*|b|)$ 

## 7 Math Roland

## 7.1 Divisability Explanation

 $D \mid M \Leftrightarrow D \mid \text{digit\_sum}(M, k, \text{alt})$ , refer to table for values of D, k, alt.

### 7.2 Combinatorics

- Variations (ordered): k out of n objects (permutations for k = n)
  - without repetition:  $M = \{(x_1, \dots, x_k) : 1 \le x_i \le n, x_i \le n \}$

```
M = \{(x_1, \dots, x_k) : 1 \le x_i \le n, \ x_i \ne x_j \text{ if } i \ne j\},\ |M| = \frac{n!}{(n-k)!}
```

- with repetition:

```
M = \{(x_1, \dots, x_k) : 1 \le x_i \le n\}, |M| = n^k
```

- Combinations (unordered): k out of n objects
  - without repetition:  $M = \{(x_1, \ldots, x_n) : x_i \in \{0,1\}, x_1 + \ldots + x_n = k\}, |M| = \binom{n}{k}$
  - with repetition:  $M = \{(x_1, \dots, x_n) : x_i \in \{0, 1, \dots, k\}, x_1 + \dots + x_n = k\}, |M| = \binom{n+k-1}{k}$
- Ordered partition of numbers:  $x_1 + ... + x_k = n$  (i.e. 1+3 = 3+1 = 4 are counted as 2 solutions)
  - #Solutions for  $x_i \in \mathbb{N}_0$ :  $\binom{n+k-1}{k-1}$
  - #Solutions for  $x_i \in \mathbb{N}$ :  $\binom{n-1}{k-1}$
- Unordered partition of numbers:  $x_1 + ... + x_k = n$  (i.e. 1+3 = 3+1 = 4 are counted as 1 solution)

- #Solutions for  $x_i \in \mathbb{N}$ :  $P_{n,k} = P_{n-k,k} + P_{n-1,k-1}$ where  $P_{n,1} = P_{n,n} = 1$
- Derangements (permutations without fixed points): !n $n! \sum_{k=0}^{n} \frac{(-1)^k}{k!} = \lfloor \frac{n!}{e} + \frac{1}{2} \rfloor$

## **Polynomial Interpolation**

#### 7.3.1 Theory

Problem: for  $\{(x_0, y_0), \dots, (x_n, y_n)\}\$  find  $p \in \Pi_n$  with  $p(x_i) =$  $y_i$  for all  $i = 0, \ldots, n$ .

Solution:  $p(x) = \sum\limits_{i=0}^n \gamma_{0,i} \prod\limits_{j=0}^{i-1} (x-x_i)$  where  $\gamma_{j,k} = y_j$  for k=0 and  $\gamma_{j,k} = \frac{\gamma_{j+1,k-1}-\gamma_{j,k-1}}{x_{j+k}-x_j}$  otherwise. Efficient evaluation of p(x):  $b_n = \gamma_{0,n}$ ,  $b_i = b_{i+1}(x-x_i) + \gamma_{0,i}$ 

for  $i = n - 1, \dots, 0$  with  $b_0 = p(x)$ .

## Fibonacci Sequence

#### 7.4.1 Binet's formula

$$\begin{pmatrix} f_n \\ f_{n+1} \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 1 & 1 \end{pmatrix}^n \begin{pmatrix} 0 \\ 1 \end{pmatrix} \Rightarrow f_n = \frac{1}{\sqrt{5}} (\phi^n - \tilde{\phi}^n) \text{ where } \phi = \frac{1+\sqrt{5}}{2} \text{ and } \tilde{\phi} = \frac{1-\sqrt{5}}{2}.$$

#### 7.4.2 Generalization

$$g_n = \frac{1}{\sqrt{5}} (g_0(\phi^{n-1} - \tilde{\phi}^{n-1}) + g_1(\phi^n - \tilde{\phi}^n)) = g_0 f_{n-1} + g_1 f_n$$
 for all  $g_0, g_1 \in \mathbb{N}_0$ 

## 7.4.3 Pisano Period

Both  $(f_n \mod k)_{n \in \mathbb{N}_0}$  and  $(g_n \mod k)_{n \in \mathbb{N}_0}$  are periodic.

#### 7.5 Reihen

$$\begin{split} \sum_{i=1}^n i &= \frac{n(n+1)}{2}, \sum_{i=1}^n i^2 = \frac{n(n+1)(2n+1)}{6}, \sum_{i=1}^n i^3 = \frac{n^2(n+1)^2}{4} \\ \sum_{i=0}^n c^i &= \frac{c^{n+1}-1}{c-1}, c \neq 1, \sum_{i=0}^\infty c^i = \frac{1}{1-c}, \sum_{i=1}^n c^i = \frac{c}{1-c}, |c| < 1 \\ \sum_{i=0}^n ic^i &= \frac{nc^{n+2}-(n+1)c^{n+1}+c}{(c-1)^2}, c \neq 1, \sum_{i=0}^\infty ic^i = \frac{c}{(1-c)^2}, |c| < 1 \end{split}$$

#### Binomialkoeffizienten

#### 7.7 Catalanzahlen

$$C_n = \frac{1}{n+1} {2n \choose n} = \frac{(2n)!}{(n+1)!n!}$$

$$C_0 = 1, C_{n+1} = \sum_{k=0}^{n} C_k C_{n-k}, C_{n+1} = \frac{4n+2}{n+2} C_n$$

#### **7.8** Geometrie

**Polygonfläche:** 
$$A = \frac{1}{2}(x_1y_2 - x_2y_1 + x_2y_3 - x_3y_2 + \cdots + x_{n-1}y_n - x_ny_{n-1} + x_ny_1 - x_1y_n)$$

#### 7.9 Zahlentheorie

**Chinese Remainder Theorem:** Es existiert eine Zahl C, sodass:  $C \equiv a_1 \mod n_1, \cdots, C \equiv a_k \mod n_k, \operatorname{ggt}(n_i, n_j) = 1, i \neq j$ Fall k=2:  $m_1n_1+m_2n_2=1$  mit EEA finden.

Lösung ist  $x = a_1 m_2 n_2 + a_2 m_1 n_1$ .

Allgemeiner Fall: iterative Anwendung von k=2

**Eulersche**  $\varphi$ -Funktion:  $\varphi(n) = n \prod_{p|n} (1 - \frac{1}{p}), p$  prim

 $\varphi(p) = p - 1, \varphi(pq) = \varphi(p)\varphi(q), p, q \text{ prim}$ 

 $\varphi(p^k) = p^k - p^{k-1}, p, q \text{ prim}, k \ge 1$ 

**Eulers Theorem:**  $a^{\varphi(n)} \equiv 1 \mod n$ 

**Fermats Theorem:**  $a^p \equiv a \mod p, p$  prim

## 7.10 Faltung

$$(f * g)(n) = \sum_{m=-\infty}^{\infty} f(m)g(n-m) = \sum_{m=-\infty}^{\infty} f(n-m)g(m)$$

# Java Knowhow

# System.out.printf() und String.format()

Syntax: %[flags][width][.precision][conv] flags:

left-justify (default: right)

+ always output number sign

zero-pad numbers

space instead of minus for pos. numbers (space)

group triplets of digits with,

width specifies output width

precision is for floating point precision

#### conv:

byte, short, int, long d

f float, double

char (use C for uppercase)

String (use S for all uppercase)

#### 8.2 **Modulo: Avoiding negative Integers**

#### 8.3 Speed up IO

Use

BufferedReader br = new BufferedReader(new InputStreamReader(System.in));

Use

Double.parseDouble(Scanner.next());