

In[*]:= **Rz = RotationMatrix[2 π / 3, {0, 0, 1}]**

Out[*]=

$$\left\{ \left\{ -\frac{1}{2}, -\frac{\sqrt{3}}{2}, 0 \right\}, \left\{ \frac{\sqrt{3}}{2}, -\frac{1}{2}, 0 \right\}, \{0, 0, 1\} \right\}$$

In[*]:= **data = {sp \rightarrow 76 * 10[^](-3), L \rightarrow 524 * 10[^](-3), l \rightarrow 1244 * 10[^](-3), wb \rightarrow 164 * 10[^](-3),
wp \rightarrow 22 * 10[^](-3), up \rightarrow 44 * 10[^](-3), sb \rightarrow 567 * (10[^](-3)), ub \rightarrow 327 * 10[^](-3)}**

Out[*]=

$$\left\{ \text{sp} \rightarrow \frac{19}{250}, \text{L} \rightarrow \frac{131}{250}, \text{l} \rightarrow \frac{311}{250}, \text{wb} \rightarrow \frac{41}{250}, \text{wp} \rightarrow \frac{11}{500}, \text{up} \rightarrow \frac{11}{250}, \text{sb} \rightarrow \frac{567}{1000}, \text{ub} \rightarrow \frac{327}{1000} \right\}$$

In[*]:= **b1 = {0, -wb, 0}**

Out[*]=

$$\{0, -\text{wb}, 0\}$$

In[*]:= **h = {x, y, z}**

Out[*]=

$$\{x, y, z\}$$

In[*]:= **b2 = Rz.b1**

Out[*]=

$$\left\{ \frac{\sqrt{3} \text{wb}}{2}, \frac{\text{wb}}{2}, 0 \right\}$$

In[*]:= **b3 = Rz.b2**

Out[*]=

$$\left\{ -\frac{\sqrt{3} \text{wb}}{2}, \frac{\text{wb}}{2}, 0 \right\}$$

In[*]:= **p1 = {0, -up, 0}**

Out[*]=

$$\{0, -\text{up}, 0\}$$

In[*]:= **p2 = {sp / 2, wp, 0}**

Out[*]=

$$\left\{ \frac{\text{sp}}{2}, \text{wp}, 0 \right\}$$

In[*]:= **p3 = {-sp / 2, wp, 0}**

Out[*]=

$$\left\{ -\frac{\text{sp}}{2}, \text{wp}, 0 \right\}$$

In[*]:= **Rx1 = RotationMatrix[(θ 1), {1, 0, 0}]**

Out[*]=

$$\{\{1, 0, 0\}, \{0, \text{Cos}[\theta 1], -\text{Sin}[\theta 1]\}, \{0, \text{Sin}[\theta 1], \text{Cos}[\theta 1]\}\}$$

In[*]:= **Rx2 = RotationMatrix[π / 2, {1, 0, 0}]**

Out[*]=

$$\{\{1, 0, 0\}, \{0, 0, -1\}, \{0, 1, 0\}\}$$

In[*]:= **L1 = Rx2.Rx1.{0, 0, L}**

Out[*]=

$$\{0, -L \text{Cos}[\theta 1], -L \text{Sin}[\theta 1]\}$$

In[*]:= Rx3 = RotationMatrix[θ2, {1, 0, 0}]

Out[*]=
 $\{\{1, 0, 0\}, \{0, \cos[\theta_2], -\sin[\theta_2]\}, \{0, \sin[\theta_2], \cos[\theta_2]\}\}$

In[*]:= L2 = Rz.Rx2.Rx3.{0, 0, L}

Out[*]=
 $\left\{\frac{1}{2}\sqrt{3}L\cos[\theta_2], \frac{1}{2}L\cos[\theta_2], -L\sin[\theta_2]\right\}$

In[*]:= Rx4 = RotationMatrix[θ3, {1, 0, 0}]

Out[*]=
 $\{\{1, 0, 0\}, \{0, \cos[\theta_3], -\sin[\theta_3]\}, \{0, \sin[\theta_3], \cos[\theta_3]\}\}$

In[*]:= L3 = Rz.Rz.Rx2.Rx4.{0, 0, L}

Out[*]=
 $\left\{-\frac{1}{2}\sqrt{3}L\cos[\theta_3], \frac{1}{2}L\cos[\theta_3], -L\sin[\theta_3]\right\}$

In[*]:= v1a = b1 + L1

Out[*]=
 $\{0, -wb - L\cos[\theta_1], -L\sin[\theta_1]\}$

In[*]:= v1b = p1 + h

Out[*]=
 $\{x, -up + y, z\}$

In[*]:= eq1 = Simplify[Expand[(v1b - v1a).(v1b - v1a)]] - 1^2

Out[*]=
 $-1^2 + L^2 + up^2 - 2upwb + wb^2 + x^2 - 2upy + 2wby + y^2 + z^2 - 2L(up - wb - y)\cos[\theta_1] + 2Lz\sin[\theta_1]$

In[*]:= v2a = b2 + L2

Out[*]=
 $\left\{\frac{\sqrt{3}wb}{2} + \frac{1}{2}\sqrt{3}L\cos[\theta_2], \frac{wb}{2} + \frac{1}{2}L\cos[\theta_2], -L\sin[\theta_2]\right\}$

In[*]:= v2b = p2 + h

Out[*]=
 $\left\{\frac{sp}{2} + x, wp + y, z\right\}$

In[*]:= eq2 = Simplify[Expand[(v2b - v2a).(v2b - v2a)]] - 1^2

Out[*]=
 $-1^2 + L^2 + \frac{sp^2}{4} - \frac{1}{2}\sqrt{3}spwb + wb^2 - wbwp + wp^2 + spx - \sqrt{3}wbx + x^2 - wby +$
 $2wpy + y^2 + z^2 - \frac{1}{2}L(\sqrt{3}sp + 2(-2wb + wp + \sqrt{3}x + y))\cos[\theta_2] + 2Lz\sin[\theta_2]$

In[*]:=

v3a = b3 + L3

Out[*]=
 $\left\{-\frac{\sqrt{3}wb}{2} - \frac{1}{2}\sqrt{3}L\cos[\theta_3], \frac{wb}{2} + \frac{1}{2}L\cos[\theta_3], -L\sin[\theta_3]\right\}$

In[*]:= v3b = p3 + h

Out[*]=

$$\left\{-\frac{sp}{2} + x, wp + y, z\right\}$$

In[*]:= eq3 = Simplify[Expand[(v3b - v3a) . (v3b - v3a)]] - 1^2

Out[*]=

$$-1^2 + L^2 + \frac{sp^2}{4} - \frac{1}{2} \sqrt{3} sp wb + wb^2 - wb wp + wp^2 - sp x + \sqrt{3} wb x + x^2 - wb y + 2 wp y + y^2 + z^2 - \frac{1}{2} L \left(\sqrt{3} sp + 2 (-2 wb + wp - \sqrt{3} x + y) \right) \cos[\theta 3] + 2 L z \sin[\theta 3]$$

In[*]:= sub3 = {Cos[θ3] → (1 - t3^2) / (1 + t3^2), Sin[θ3] → 2 * t3 / (1 + t3^2)}

Out[*]=

$$\left\{\cos[\theta 3] \rightarrow \frac{1 - t3^2}{1 + t3^2}, \sin[\theta 3] \rightarrow \frac{2 t3}{1 + t3^2}\right\}$$

In[*]:= eq3a = eq3 /. sub3

Out[*]=

$$-1^2 + L^2 + \frac{sp^2}{4} - \frac{1}{2} \sqrt{3} sp wb + wb^2 - wb wp + wp^2 - sp x + \sqrt{3} wb x + x^2 - wb y + 2 wp y + y^2 - \frac{L (1 - t3^2) (\sqrt{3} sp + 2 (-2 wb + wp - \sqrt{3} x + y))}{2 (1 + t3^2)} + \frac{4 L t3 z}{1 + t3^2} + z^2$$

In[*]:= sub2 = {Cos[θ2] → (1 - t2^2) / (1 + t2^2), Sin[θ2] → 2 * t2 / (1 + t2^2)}

Out[*]=

$$\left\{\cos[\theta 2] \rightarrow \frac{1 - t2^2}{1 + t2^2}, \sin[\theta 2] \rightarrow \frac{2 t2}{1 + t2^2}\right\}$$

In[*]:= eq2a = eq2 /. sub2

Out[*]=

$$-1^2 + L^2 + \frac{sp^2}{4} - \frac{1}{2} \sqrt{3} sp wb + wb^2 - wb wp + wp^2 + sp x - \sqrt{3} wb x + x^2 - wb y + 2 wp y + y^2 - \frac{L (1 - t2^2) (\sqrt{3} sp + 2 (-2 wb + wp + \sqrt{3} x + y))}{2 (1 + t2^2)} + \frac{4 L t2 z}{1 + t2^2} + z^2$$

In[*]:= sub1 = {Cos[θ1] → (1 - t1^2) / (1 + t1^2), Sin[θ1] → 2 * t1 / (1 + t1^2)}

Out[*]=

$$\left\{\cos[\theta 1] \rightarrow \frac{1 - t1^2}{1 + t1^2}, \sin[\theta 1] \rightarrow \frac{2 t1}{1 + t1^2}\right\}$$

In[*]:= eq1a = eq1 /. sub1

Out[*]=

$$-1^2 + L^2 + up^2 - 2 up wb + wb^2 + x^2 - \frac{2 L (1 - t1^2) (up - wb - y)}{1 + t1^2} - 2 up y + 2 wb y + y^2 + \frac{4 L t1 z}{1 + t1^2} + z^2$$

In[*]:= eq1b = Collect[Numerator[Together[eq1a]], t1]

Out[*]=

$$-1^2 + L^2 - 2 L up + up^2 + 2 L wb - 2 up wb + wb^2 + x^2 + 2 L y - 2 up y + 2 wb y + y^2 + 4 L t1 z + z^2 + t1^2 (-1^2 + L^2 + 2 L up + up^2 - 2 L wb - 2 up wb + wb^2 + x^2 - 2 L y - 2 up y + 2 wb y + y^2 + z^2)$$

In[*]:= Sol1 = Solve[eq1b == 0, t1]

Out[*]=

$$\left\{ \left\{ t1 \rightarrow \left(-4 L z - \sqrt{16 L^2 z^2 - 4 \left(-1^2 + L^2 + 2 L up + up^2 - 2 L wb - 2 up wb + wb^2 + x^2 - 2 L y - 2 up y + 2 wb y + y^2 + z^2 \right) \left(-1^2 + L^2 - 2 L up + up^2 + 2 L wb - 2 up wb + wb^2 + x^2 + 2 L y - 2 up y + 2 wb y + y^2 + z^2 \right)} \right) \right\} / \left(2 \left(-1^2 + L^2 + 2 L up + up^2 - 2 L wb - 2 up wb + wb^2 + x^2 - 2 L y - 2 up y + 2 wb y + y^2 + z^2 \right) \right) \right\}, \\ \left\{ t1 \rightarrow \left(-4 L z + \sqrt{16 L^2 z^2 - 4 \left(-1^2 + L^2 + 2 L up + up^2 - 2 L wb - 2 up wb + wb^2 + x^2 - 2 L y - 2 up y + 2 wb y + y^2 + z^2 \right) \left(-1^2 + L^2 - 2 L up + up^2 + 2 L wb - 2 up wb + wb^2 + x^2 + 2 L y - 2 up y + 2 wb y + y^2 + z^2 \right)} \right) \right\} / \left(2 \left(-1^2 + L^2 + 2 L up + up^2 - 2 L wb - 2 up wb + wb^2 + x^2 - 2 L y - 2 up y + 2 wb y + y^2 + z^2 \right) \right) \right\}$$

In[*]:= eq2a = eq2 /. sub2

Out[*]=

$$-1^2 + L^2 + \frac{sp^2}{4} - \frac{1}{2} \sqrt{3} sp wb + wb^2 - wb wp + wp^2 + sp x - \sqrt{3} wb x + x^2 - wb y + 2 wp y + y^2 - \frac{L (1 - t2^2) (\sqrt{3} sp + 2 (-2 wb + wp + \sqrt{3} x + y))}{2 (1 + t2^2)} + \frac{4 L t2 z}{1 + t2^2} + z^2$$

In[*]:= eq2b = Collect[Numerator[Together[eq2a]], t2]

Out[*]=

$$-4 L^2 + 4 L^2 - 2 \sqrt{3} L sp + sp^2 + 8 L wb - 2 \sqrt{3} sp wb + 4 wb^2 - 4 L wp - 4 wb wp + 4 wp^2 - 4 \sqrt{3} L x + 4 sp x - 4 \sqrt{3} wb x + 4 x^2 - 4 L y - 4 wb y + 8 wp y + 4 y^2 + 16 L t2 z + 4 z^2 + t2^2 (-4 L^2 + 4 L^2 + 2 \sqrt{3} L sp + sp^2 - 8 L wb - 2 \sqrt{3} sp wb + 4 wb^2 + 4 L wp - 4 wb wp + 4 wp^2 + 4 \sqrt{3} L x + 4 sp x - 4 \sqrt{3} wb x + 4 x^2 + 4 L y - 4 wb y + 8 wp y + 4 y^2 + 4 z^2)$$

In[*]:= Sol2 = Solve[eq2b == 0, t2]

Out[*]=

$$\left\{ \left\{ t2 \rightarrow \left(-16 L z - \sqrt{256 L^2 z^2 - 4 \left(-4 L^2 + 4 L^2 - 2 \sqrt{3} L sp + sp^2 + 8 L wb - 2 \sqrt{3} sp wb + 4 wb^2 - 4 L wp - 4 wb wp + 4 wp^2 - 4 \sqrt{3} L x + 4 sp x - 4 \sqrt{3} wb x + 4 x^2 - 4 L y - 4 wb y + 8 wp y + 4 y^2 + 4 z^2 \right) \left(-4 L^2 + 4 L^2 + 2 \sqrt{3} L sp + sp^2 - 8 L wb - 2 \sqrt{3} sp wb + 4 wb^2 + 4 L wp - 4 wb wp + 4 wp^2 + 4 \sqrt{3} L x + 4 sp x - 4 \sqrt{3} wb x + 4 x^2 + 4 L y - 4 wb y + 8 wp y + 4 y^2 + 4 z^2 \right)} \right) \right\} / \left(2 \left(-4 L^2 + 4 L^2 + 2 \sqrt{3} L sp + sp^2 - 8 L wb - 2 \sqrt{3} sp wb + 4 wb^2 + 4 L wp - 4 wb wp + 4 wp^2 + 4 \sqrt{3} L x + 4 sp x - 4 \sqrt{3} wb x + 4 x^2 + 4 L y - 4 wb y + 8 wp y + 4 y^2 + 4 z^2 \right) \right) \right\}, \\ \left\{ t2 \rightarrow \left(-16 L z + \sqrt{256 L^2 z^2 - 4 \left(-4 L^2 + 4 L^2 - 2 \sqrt{3} L sp + sp^2 + 8 L wb - 2 \sqrt{3} sp wb + 4 wb^2 - 4 L wp - 4 wb wp + 4 wp^2 - 4 \sqrt{3} L x + 4 sp x - 4 \sqrt{3} wb x + 4 x^2 - 4 L y - 4 wb y + 8 wp y + 4 y^2 + 4 z^2 \right) \left(-4 L^2 + 4 L^2 + 2 \sqrt{3} L sp + sp^2 - 8 L wb - 2 \sqrt{3} sp wb + 4 wb^2 + 4 L wp - 4 wb wp + 4 wp^2 + 4 \sqrt{3} L x + 4 sp x - 4 \sqrt{3} wb x + 4 x^2 + 4 L y - 4 wb y + 8 wp y + 4 y^2 + 4 z^2 \right)} \right) \right\} / \left(2 \left(-4 L^2 + 4 L^2 + 2 \sqrt{3} L sp + sp^2 - 8 L wb - 2 \sqrt{3} sp wb + 4 wb^2 + 4 L wp - 4 wb wp + 4 wp^2 + 4 \sqrt{3} L x + 4 sp x - 4 \sqrt{3} wb x + 4 x^2 + 4 L y - 4 wb y + 8 wp y + 4 y^2 + 4 z^2 \right) \right) \right\}$$

```
In[*]:= eq3a = eq3 /. sub3
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Out[*]=
```

$$-1^2 + L^2 + \frac{sp^2}{4} - \frac{1}{2} \sqrt{3} sp wb + wb^2 - wb wp + wp^2 - sp x + \sqrt{3} wb x + x^2 - wb y + 2 wp y + y^2 - \frac{L (1 - t^3) (\sqrt{3} sp + 2 (-2 wb + wp - \sqrt{3} x + y))}{2 (1 + t^3)} + \frac{4 L t^3 z}{1 + t^3} + z^2$$

```
In[*]:= eq3b = Collect[Numerator[Together[eq3a]], t3]
```

```
Out[*]=
```

$$-4 L^2 + 4 L^2 - 2 \sqrt{3} L sp + sp^2 + 8 L wb - 2 \sqrt{3} sp wb + 4 wb^2 - 4 L wp - 4 wb wp + 4 wp^2 + 4 \sqrt{3} L x - 4 sp x + 4 \sqrt{3} wb x + 4 x^2 - 4 L y - 4 wb y + 8 wp y + 4 y^2 + 16 L t^3 z + 4 z^2 + t^3 (-4 L^2 + 4 L^2 + 2 \sqrt{3} L sp + sp^2 - 8 L wb - 2 \sqrt{3} sp wb + 4 wb^2 + 4 L wp - 4 wb wp + 4 wp^2 - 4 \sqrt{3} L x - 4 sp x + 4 \sqrt{3} wb x + 4 x^2 + 4 L y - 4 wb y + 8 wp y + 4 y^2 + 4 z^2)$$

```
In[*]:= Sol3 = Solve[eq3b == 0, t3]
```

```
Out[*]=
```

$$\left\{ \left\{ t_3 \rightarrow \frac{\left(-16 L z - \sqrt{256 L^2 z^2 - 4 (-4 L^2 + 4 L^2 - 2 \sqrt{3} L sp + sp^2 + 8 L wb - 2 \sqrt{3} sp wb + 4 wb^2 - 4 L wp - 4 wb wp + 4 wp^2 + 4 \sqrt{3} L x - 4 sp x + 4 \sqrt{3} wb x + 4 x^2 - 4 L y - 4 wb y + 8 wp y + 4 y^2 + 4 z^2) (-4 L^2 + 4 L^2 + 2 \sqrt{3} L sp + sp^2 - 8 L wb - 2 \sqrt{3} sp wb + 4 wb^2 + 4 L wp - 4 wb wp + 4 wp^2 - 4 \sqrt{3} L x - 4 sp x + 4 \sqrt{3} wb x + 4 x^2 + 4 L y - 4 wb y + 8 wp y + 4 y^2 + 4 z^2) \right)}{2 (-4 L^2 + 4 L^2 + 2 \sqrt{3} L sp + sp^2 - 8 L wb - 2 \sqrt{3} sp wb + 4 wb^2 + 4 L wp - 4 wb wp + 4 wp^2 - 4 \sqrt{3} L x - 4 sp x + 4 \sqrt{3} wb x + 4 x^2 + 4 L y - 4 wb y + 8 wp y + 4 y^2 + 4 z^2)} \right\}, \left\{ t_3 \rightarrow \frac{\left(-16 L z + \sqrt{256 L^2 z^2 - 4 (-4 L^2 + 4 L^2 - 2 \sqrt{3} L sp + sp^2 + 8 L wb - 2 \sqrt{3} sp wb + 4 wb^2 - 4 L wp - 4 wb wp + 4 wp^2 + 4 \sqrt{3} L x - 4 sp x + 4 \sqrt{3} wb x + 4 x^2 - 4 L y - 4 wb y + 8 wp y + 4 y^2 + 4 z^2) (-4 L^2 + 4 L^2 + 2 \sqrt{3} L sp + sp^2 - 8 L wb - 2 \sqrt{3} sp wb + 4 wb^2 + 4 L wp - 4 wb wp + 4 wp^2 - 4 \sqrt{3} L x - 4 sp x + 4 \sqrt{3} wb x + 4 x^2 + 4 L y - 4 wb y + 8 wp y + 4 y^2 + 4 z^2) \right)}{2 (-4 L^2 + 4 L^2 + 2 \sqrt{3} L sp + sp^2 - 8 L wb - 2 \sqrt{3} sp wb + 4 wb^2 + 4 L wp - 4 wb wp + 4 wp^2 - 4 \sqrt{3} L x - 4 sp x + 4 \sqrt{3} wb x + 4 x^2 + 4 L y - 4 wb y + 8 wp y + 4 y^2 + 4 z^2)} \right\} \right\}$$

```
In[*]:= solu3 = Flatten[Sol3 /. data /. {x -> 0} /. {y -> 0} /. {z -> -0.9}]
```

```
Out[*]=
```

$$\{t_3 \rightarrow -0.181037, t_3 \rightarrow -3.10312\}$$

```
In[*]:= solu2 = Flatten[Sol2 /. data /. {x -> 0} /. {y -> 0} /. {z -> -0.9}]
```

```
Out[*]=
```

$$\{t_2 \rightarrow -0.181037, t_2 \rightarrow -3.10312\}$$

```
In[*]:= solu1 = Flatten[Sol1 /. data /. {x -> 0} /. {y -> 0} /. {z -> -0.9}]
```

```
Out[*]=
```

$$\{t_1 \rightarrow -0.181105, t_1 \rightarrow -3.10347\}$$

```
In[*]:= val03 = {03 -> 2 * ArcTan[t3 /. solu3[[1]], 03 -> 2 * ArcTan[t3 /. solu3[[2]]]}
```

```
Out[*]=
```

$$\{03 \rightarrow -0.358194, 03 \rightarrow -2.5181\}$$

```
In[*]:= val02 = {02 → 2 * ArcTan[t2 /. solu2[[1]]], 02 → 2 * ArcTan[t2 /. solu2[[2]]]}
```

```
Out[*]=  
{02 → -0.358194, 02 → -2.5181}
```

```
In[*]:= val01 = {01 → 2 * ArcTan[t1 /. solu1[[1]]], 01 → 2 * ArcTan[t1 /. solu1[[2]]]}
```

```
Out[*]=  
{01 → -0.358327, 01 → -2.51816}
```

```
In[*]:= i1 = {0, 0}
```

```
Out[*]=  
{0, 0}
```

```
In[*]:= i2 = p1 + {x, y, z} /. data /. {x → 0} /. {y → 0} /. {z → -0.9}
```

```
Out[*]=  
 $\left\{0, -\frac{11}{250}, -0.9\right\}$ 
```

```
In[*]:= i3 = p2 + {x, y, z} /. data /. {x → 0} /. {y → 0} /. {z → -0.9}
```

```
Out[*]=  
 $\left\{\frac{19}{500}, \frac{11}{500}, -0.9\right\}$ 
```

```
In[*]:= i4 = p3 + {x, y, z} /. data /. {x → 0} /. {y → 0} /. {z → -0.9}
```

```
Out[*]=  
 $\left\{-\frac{19}{500}, \frac{11}{500}, -0.9\right\}$ 
```

```
In[*]:= B1 = {sb / 2, -wb, 0} /. data;
```

```
B2 = {0, ub, 0} /. data;
```

```
B3 = {-sb / 2, -wb, 0} /. data;
```

```
bb1 = b1 /. data;
```

```
bb2 = b2 /. data;
```

```
bb3 = b3 /. data;
```

```
l11 = L1 /. data /. val01[[1]];
```

```
l12 = L2 /. data /. val02[[1]];
```

```
l13 = L3 /. data /. val03[[1]];
```

```

In[ ]:= line1 = Graphics3D[{Thickness[0.005], Line[{i2, i3}]}];
line2 = Graphics3D[{Thickness[0.005], Line[{i3, i4}]}];
line3 = Graphics3D[{Thickness[0.005], Line[{i4, i2}]}];

line4 = Graphics3D[{Thickness[0.01], Line[{B1, B2}]}];
line5 = Graphics3D[{Thickness[0.01], Line[{B2, B3}]}];
line6 = Graphics3D[{Thickness[0.01], Line[{B3, B1}]}];

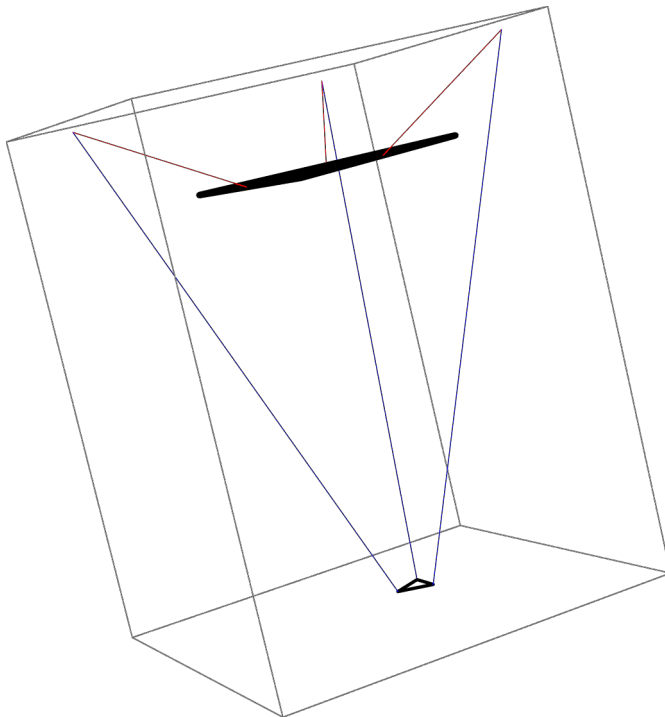
line7 = Graphics3D[{Red, Line[{bb1, ll1}]}];
line8 = Graphics3D[{Red, Line[{bb2, ll2}]}];
line9 = Graphics3D[{Red, Line[{bb3, ll3}]}];

line10 = Graphics3D[{Blue, Line[{ll1, i2}]}];
line11 = Graphics3D[{Blue, Line[{ll2, i3}]}];
line12 = Graphics3D[{Blue, Line[{ll3, i4}]}];

In[ ]:= Show[{line1, line2, line3, line4, line5,
              line6, line7, line8, line9, line10, line11, line12}]

```

Out[]=



```
In[*]:= eq1
eq2
eq3
```

```
Out[*]=
```

$$-l^2 + L^2 + up^2 - 2 up wb + wb^2 + x^2 - 2 up y + 2 wb y + y^2 + z^2 - 2 L (up - wb - y) \cos[\theta 1] + 2 L z \sin[\theta 1]$$

```
Out[*]=
```

$$-l^2 + L^2 + \frac{sp^2}{4} - \frac{1}{2} \sqrt{3} sp wb + wb^2 - wb wp + wp^2 + sp x - \sqrt{3} wb x + x^2 - wb y +$$

$$2 wp y + y^2 + z^2 - \frac{1}{2} L (\sqrt{3} sp + 2 (-2 wb + wp + \sqrt{3} x + y)) \cos[\theta 2] + 2 L z \sin[\theta 2]$$

```
Out[*]=
```

$$-l^2 + L^2 + \frac{sp^2}{4} - \frac{1}{2} \sqrt{3} sp wb + wb^2 - wb wp + wp^2 - sp x + \sqrt{3} wb x + x^2 - wb y +$$

$$2 wp y + y^2 + z^2 - \frac{1}{2} L (\sqrt{3} sp + 2 (-2 wb + wp - \sqrt{3} x + y)) \cos[\theta 3] + 2 L z \sin[\theta 3]$$

```
In[*]:= eqa = Simplify[eq1 - eq2]
```

```
Out[*]=
```

$$-\frac{sp^2}{4} + up^2 + \frac{1}{2} \sqrt{3} sp wb - 2 up wb + wb wp - wp^2 -$$

$$sp x + \sqrt{3} wb x - 2 up y + 3 wb y - 2 wp y - 2 L (up - wb - y) \cos[\theta 1] +$$

$$\frac{1}{2} L (\sqrt{3} sp + 2 (-2 wb + wp + \sqrt{3} x + y)) \cos[\theta 2] + 2 L z \sin[\theta 1] - 2 L z \sin[\theta 2]$$

```
In[*]:= eqb = Simplify[eq2 - eq3]
```

```
Out[*]=
```

$$\frac{1}{2} (4 sp x - 4 \sqrt{3} wb x - L (\sqrt{3} sp + 2 (-2 wb + wp + \sqrt{3} x + y)) \cos[\theta 2] +$$

$$L (\sqrt{3} sp + 2 (-2 wb + wp - \sqrt{3} x + y)) \cos[\theta 3] + 4 L z \sin[\theta 2] - 4 L z \sin[\theta 3])$$

```
In[*]:= eqc = Simplify[eq1 - eq3]
```

```
Out[*]=
```

$$-\frac{sp^2}{4} + up^2 + \frac{1}{2} \sqrt{3} sp wb - 2 up wb + wb wp - wp^2 +$$

$$sp x - \sqrt{3} wb x - 2 up y + 3 wb y - 2 wp y - 2 L (up - wb - y) \cos[\theta 1] +$$

$$\frac{1}{2} L (\sqrt{3} sp + 2 (-2 wb + wp - \sqrt{3} x + y)) \cos[\theta 3] + 2 L z \sin[\theta 1] - 2 L z \sin[\theta 3]$$

In[*]:= sol = Numerator[Solve[{eqb, eqc} == 0, {x, y}]] [[1]]

Out[*]=

$$\left\{ x \rightarrow \frac{\left(\left((-L \cos[\theta_2] + L \cos[\theta_3]) \left(-\frac{sp^2}{4} + up^2 + \frac{1}{2} \sqrt{3} sp wb - 2 up wb + wb wp - wp^2 - 2 L up \cos[\theta_1] + 2 L wb \cos[\theta_1] + \frac{1}{2} \sqrt{3} L sp \cos[\theta_3] - 2 L wb \cos[\theta_3] + L wp \cos[\theta_3] + 2 L z \sin[\theta_1] - 2 L z \sin[\theta_3] \right) - (-2 up + 3 wb - 2 wp + 2 L \cos[\theta_1] + L \cos[\theta_3]) \right) \left(-\frac{1}{2} \sqrt{3} L sp \cos[\theta_2] + 2 L wb \cos[\theta_2] - L wp \cos[\theta_2] + \frac{1}{2} \sqrt{3} L sp \cos[\theta_3] - 2 L wb \cos[\theta_3] + L wp \cos[\theta_3] + 2 L z \sin[\theta_2] - 2 L z \sin[\theta_3] \right) \right)}{\left((-L \cos[\theta_2] + L \cos[\theta_3]) (sp - \sqrt{3} wb - \sqrt{3} L \cos[\theta_3]) - (-2 up + 3 wb - 2 wp + 2 L \cos[\theta_1] + L \cos[\theta_3]) (2 sp - 2 \sqrt{3} wb - \sqrt{3} L \cos[\theta_2] - \sqrt{3} L \cos[\theta_3]) \right)},$$

$$y \rightarrow \frac{\left(2 sp^3 - 8 sp up^2 - 6 \sqrt{3} sp^2 wb + 16 sp up wb + 8 \sqrt{3} up^2 wb + 12 sp wb^2 - 16 \sqrt{3} up wb^2 - 8 sp wb wp + 8 \sqrt{3} wb^2 wp + 8 sp wp^2 - 8 \sqrt{3} wb wp^2 + 16 L sp up \cos[\theta_1] - 16 L sp wb \cos[\theta_1] - 16 \sqrt{3} L up wb \cos[\theta_1] + 16 \sqrt{3} L wb^2 \cos[\theta_1] - 3 \sqrt{3} L sp^2 \cos[\theta_2] + 4 \sqrt{3} L up^2 \cos[\theta_2] + 20 L sp wb \cos[\theta_2] - 8 \sqrt{3} L up wb \cos[\theta_2] - 8 \sqrt{3} L wb^2 \cos[\theta_2] - 4 L sp wp \cos[\theta_2] + 8 \sqrt{3} L wb wp \cos[\theta_2] - 4 \sqrt{3} L wp^2 \cos[\theta_2] - 8 \sqrt{3} L^2 up \cos[\theta_1] \cos[\theta_2] + 8 \sqrt{3} L^2 wb \cos[\theta_1] \cos[\theta_2] - 3 \sqrt{3} L sp^2 \cos[\theta_3] + 4 \sqrt{3} L up^2 \cos[\theta_3] + 20 L sp wb \cos[\theta_3] - 8 \sqrt{3} L up wb \cos[\theta_3] - 8 \sqrt{3} L wb^2 \cos[\theta_3] - 4 L sp wp \cos[\theta_3] + 8 \sqrt{3} L wb wp \cos[\theta_3] - 4 \sqrt{3} L wp^2 \cos[\theta_3] - 8 \sqrt{3} L^2 up \cos[\theta_1] \cos[\theta_3] + 8 \sqrt{3} L^2 wb \cos[\theta_1] \cos[\theta_3] + 12 L^2 sp \cos[\theta_2] \cos[\theta_3] - 16 \sqrt{3} L^2 wb \cos[\theta_2] \cos[\theta_3] + 8 \sqrt{3} L^2 wp \cos[\theta_2] \cos[\theta_3] - 16 L sp z \sin[\theta_1] + 16 \sqrt{3} L wb z \sin[\theta_1] + 8 \sqrt{3} L^2 z \cos[\theta_2] \sin[\theta_1] + 8 \sqrt{3} L^2 z \cos[\theta_3] \sin[\theta_1] + 8 L sp z \sin[\theta_2] - 8 \sqrt{3} L wb z \sin[\theta_2] - 8 \sqrt{3} L^2 z \cos[\theta_3] \sin[\theta_2] + 8 L sp z \sin[\theta_3] - 8 \sqrt{3} L wb z \sin[\theta_3] - 8 \sqrt{3} L^2 z \cos[\theta_2] \sin[\theta_3] \right)}{\left(4 \left(-4 sp up + 6 sp wb + 4 \sqrt{3} up wb - 6 \sqrt{3} wb^2 - 4 sp wp + 4 \sqrt{3} wb wp + 4 L sp \cos[\theta_1] - 4 \sqrt{3} L wb \cos[\theta_1] + L sp \cos[\theta_2] + 2 \sqrt{3} L up \cos[\theta_2] - 4 \sqrt{3} L wb \cos[\theta_2] + 2 \sqrt{3} L wp \cos[\theta_2] - 2 \sqrt{3} L^2 \cos[\theta_1] \cos[\theta_2] + L sp \cos[\theta_3] + 2 \sqrt{3} L up \cos[\theta_3] - 4 \sqrt{3} L wb \cos[\theta_3] + 2 \sqrt{3} L wp \cos[\theta_3] - 2 \sqrt{3} L^2 \cos[\theta_1] \cos[\theta_3] - 2 \sqrt{3} L^2 \cos[\theta_2] \cos[\theta_3] \right) \right)}$$

In[*]:= fkin = {val01[[1]], val02[[1]], val03[[1]]}

Out[*]=

$$\{\theta_1 \rightarrow -0.358327, \theta_2 \rightarrow -0.358194, \theta_3 \rightarrow -0.358194\}$$

```
In[*]:= fineq = Numerator[Together[eq1 /. sol]]
```

```
Out[*]=
```

$$\begin{aligned} & sp^6 - 64 L^2 sp^2 up^2 + 64 L^2 sp^2 up^2 + 8 sp^4 up^2 + 16 sp^2 up^4 - 6 \sqrt{3} sp^5 wb + 192 L^2 sp^2 up wb - \\ & 192 L^2 sp^2 up wb - 24 sp^4 up wb + 128 \sqrt{3} L^2 sp up^2 wb - 128 \sqrt{3} L^2 sp up^2 wb - 32 \sqrt{3} sp^3 up^2 wb - \\ & 96 sp^2 up^3 wb - 32 \sqrt{3} sp up^4 wb - 144 L^2 sp^2 wb^2 + 144 L^2 sp^2 wb^2 + 63 sp^4 wb^2 - 384 \sqrt{3} L^2 sp up wb^2 + \\ & 384 \sqrt{3} L^2 sp up wb^2 + \dots 2124 \dots + 64 L^4 z^2 \cos[\theta_2] \cos[\theta_3] \sin[\theta_2] \sin[\theta_3] + 16 L^2 sp^2 z^2 \sin[\theta_3]^2 + \\ & 64 L^2 up^2 z^2 \sin[\theta_3]^2 - 32 \sqrt{3} L^2 sp wb z^2 \sin[\theta_3]^2 - 192 L^2 up wb z^2 \sin[\theta_3]^2 + 192 L^2 wb^2 z^2 \sin[\theta_3]^2 + \\ & 128 L^2 up wp z^2 \sin[\theta_3]^2 - 192 L^2 wb wp z^2 \sin[\theta_3]^2 + 64 L^2 wp^2 z^2 \sin[\theta_3]^2 - 128 L^3 up z^2 \cos[\theta_1] \sin[\theta_3]^2 + \\ & 192 L^3 wb z^2 \cos[\theta_1] \sin[\theta_3]^2 - 128 L^3 wp z^2 \cos[\theta_1] \sin[\theta_3]^2 + 64 L^4 z^2 \cos[\theta_1]^2 \sin[\theta_3]^2 - \\ & 32 \sqrt{3} L^3 sp z^2 \cos[\theta_2] \sin[\theta_3]^2 - 64 L^3 up z^2 \cos[\theta_2] \sin[\theta_3]^2 + 192 L^3 wb z^2 \cos[\theta_2] \sin[\theta_3]^2 - \\ & 64 L^3 wp z^2 \cos[\theta_2] \sin[\theta_3]^2 + 64 L^4 z^2 \cos[\theta_1] \cos[\theta_2] \sin[\theta_3]^2 + 64 L^4 z^2 \cos[\theta_2]^2 \sin[\theta_3]^2 \end{aligned}$$

Full expression not available (original memory size: 0.6 MB)



```
In[*]:= solz = Solve[fineq == 0, z]
```

```
Out[*]=
```

$$\begin{aligned} & \left\{ \left\{ z \rightarrow \frac{\dots 1 \dots}{2 \left(64 sp^2 up^2 - 192 sp^2 up wb - 128 \sqrt{3} sp up^2 wb + 144 sp^2 wb^2 + 384 \sqrt{3} sp up wb^2 + 192 up^2 wb^2 - 288 \sqrt{3} sp wb^3 - \right. \right.} \right. \\ & \quad 576 up wb^3 + 432 wb^4 + \dots 311 \dots + 192 L^3 wb \cos[\theta_1] \sin[\theta_3]^2 - 128 L^3 wp \cos[\theta_1] \sin[\theta_3]^2 + \\ & \quad 64 L^4 \cos[\theta_1]^2 \sin[\theta_3]^2 - 32 \sqrt{3} L^3 sp \cos[\theta_2] \sin[\theta_3]^2 - 64 L^3 up \cos[\theta_2] \sin[\theta_3]^2 + 192 L^3 wb \cos[\theta_2] \\ & \quad \left. \left. \sin[\theta_3]^2 - 64 L^3 wp \cos[\theta_2] \sin[\theta_3]^2 + 64 L^4 \cos[\theta_1] \cos[\theta_2] \sin[\theta_3]^2 + 64 L^4 \cos[\theta_2]^2 \sin[\theta_3]^2 \right) \right\}, \\ & \left\{ z \rightarrow \left(\frac{\dots 585 \dots + \sqrt{\left((-16 L sp^4 \sin[\theta_1] + \dots 567 \dots + 96 L^5 \cos[\theta_1] \dots 1 \dots^2 \cos[\theta_3] \sin[\theta_3])^2 - \right.}}{4 \left(\dots 1 \dots \right) \left(\dots 335 \dots + 64 \dots 3 \dots \dots 1 \dots^2 + 64 L^4 \cos[\theta_2]^2 \sin[\theta_3]^2 \right)} \right) \right\} \\ & \left. \left(2 \left(64 sp^2 up^2 - 192 sp^2 up wb - 128 \sqrt{3} sp up^2 wb + 144 sp^2 wb^2 + 384 \sqrt{3} sp up wb^2 + \dots 325 \dots + 192 L^3 wb \cos[\theta_2] \right. \right. \right. \\ & \quad \left. \left. \left. \sin[\theta_3]^2 - 64 L^3 wp \cos[\theta_2] \sin[\theta_3]^2 + 64 L^4 \cos[\theta_1] \cos[\theta_2] \sin[\theta_3]^2 + 64 L^4 \cos[\theta_2]^2 \sin[\theta_3]^2 \right) \right) \right\} \end{aligned}$$

Full expression not available (original memory size: 1.6 MB)



```
In[*]:= solz /. fkin /. data
```

```
Out[*]=
```

```
{ {z -> -0.9}, {z -> 1.26746} }
```

```
In[*]:= ceq = fineq /. fkin /. data
```

```
Out[*]=
```

```
-68.5868 - 22.0938 z + 60.1265 z^2
```

```
In[*]:= invz = NSolve[ceq == 0, z]
```

```
Out[*]=
```

```
{ {z -> -0.9}, {z -> 1.26746} }
```

```
In[*]:= {invx, invy} = sol /. fkin /. data /. invz[[1]]
```

```
Out[*]=
```

```
{x -> 0., y -> -1.02182 x 10^-16}
```

```
In[*]:= num1 = N[Numerator[t1 /. Sol1[[1]] /. data]]
```

```
Out[*]=
```

```
-2.096 z -
1. Sqrt[4.39322 z^2 - 4. (-1.38432 + x^2 - 0.808 y + y^2 + z^2) (-1.1328 + x^2 + 1.288 y + y^2 + z^2)]
```

```
In[ ]:= num2 = Numerator[t2 /. Sol2[[1]] /. data]
```

```
Out[ ]:=
```

$$-\frac{1048 z}{125} - \sqrt{\left(\frac{1098304 z^2}{15625} - 4 \left(-\frac{5437}{1250} - \frac{1634 \sqrt{3}}{15625} + \frac{38 x}{125} - \frac{344 \sqrt{3} x}{125} + 4 x^2 - \frac{322 y}{125} + 4 y^2 + 4 z^2 \right) \right.}$$

$$\left. \left(-\frac{176011}{31250} + \frac{171 \sqrt{3}}{3125} + \frac{38 x}{125} + \frac{36 \sqrt{3} x}{25} + 4 x^2 + \frac{202 y}{125} + 4 y^2 + 4 z^2 \right) \right)$$

```
In[ ]:= num3 = Numerator[t3 /. Sol3[[1]] /. data]
```

```
Out[ ]:=
```

$$-\frac{1048 z}{125} - \sqrt{\left(\frac{1098304 z^2}{15625} - 4 \left(-\frac{5437}{1250} - \frac{1634 \sqrt{3}}{15625} - \frac{38 x}{125} + \frac{344 \sqrt{3} x}{125} + 4 x^2 - \frac{322 y}{125} + 4 y^2 + 4 z^2 \right) \right.}$$

$$\left. \left(-\frac{176011}{31250} + \frac{171 \sqrt{3}}{3125} - \frac{38 x}{125} - \frac{36 \sqrt{3} x}{25} + 4 x^2 + \frac{202 y}{125} + 4 y^2 + 4 z^2 \right) \right)$$

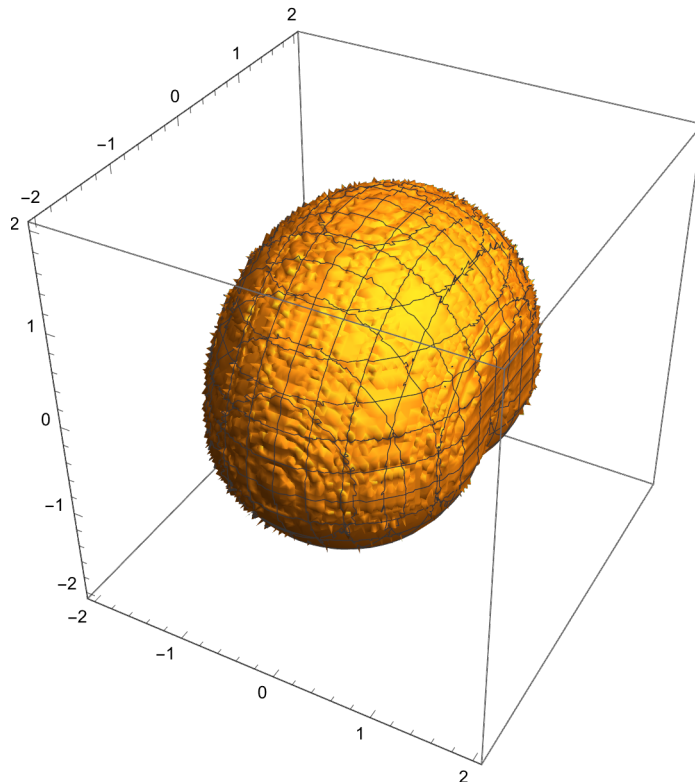
```
In[ ]:= lim = 2;
```

```
ContourPlot3D[num1 == 0, {x, -lim, lim}, {y, -lim, lim}, {z, -lim, lim}, Mesh -> Full]
```

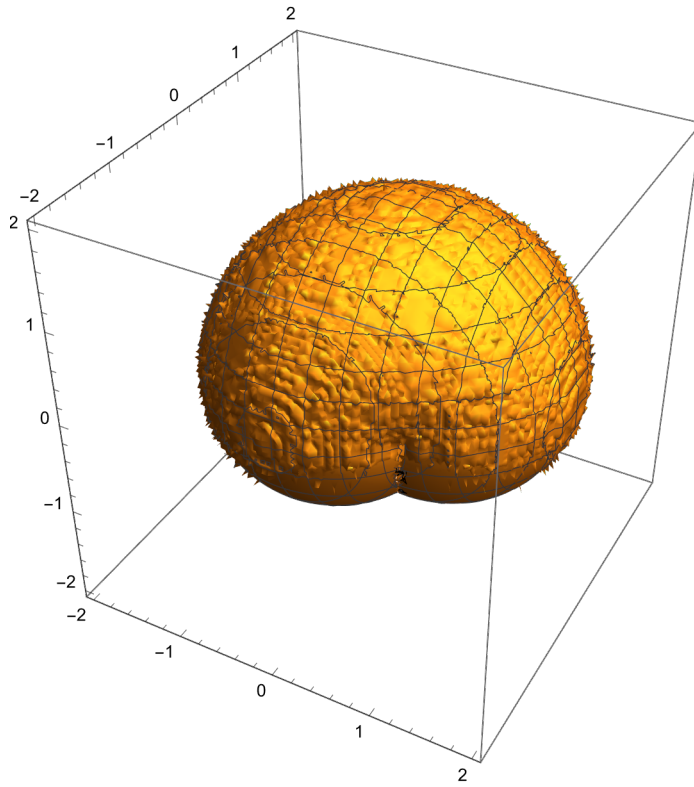
```
ContourPlot3D[num2 == 0, {x, -lim, lim}, {y, -lim, lim}, {z, -lim, lim}, Mesh -> Full]
```

```
ContourPlot3D[num3 == 0, {x, -lim, lim}, {y, -lim, lim}, {z, -lim, lim}, Mesh -> Full]
```

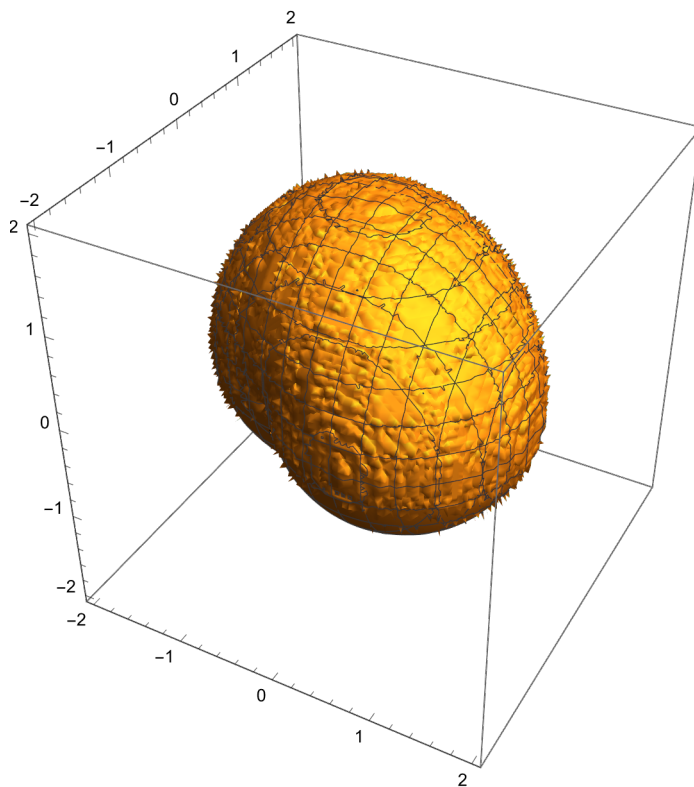
```
Out[ ]:=
```



Out[*n*]=



Out[*n*]=



```

In[ ]:= ContourPlot3D[{num1 == 0, num2 == 0, num3 == 0},
  {x, -lim, lim}, {y, -lim, lim}, {z, -lim, lim},
  ContourStyle → {Directive[Red, Opacity[0.5]], Directive[Green, Opacity[0.5]],
    Directive[Blue, Opacity[0.5]]}, Mesh → Full, AxesLabel → {"x", "y", "z"},
  PlotLabel → "Intersection of Three Surfaces", PlotPoints → 30]

```

Out[]=

