



IIT KHARAGPUR
IIT GANDHINAGAR



NPTEL ONLINE
CERTIFICATION COURSES

Scalable Data Science

Lecture 15b:QB decomposition

Anirban Dasgupta

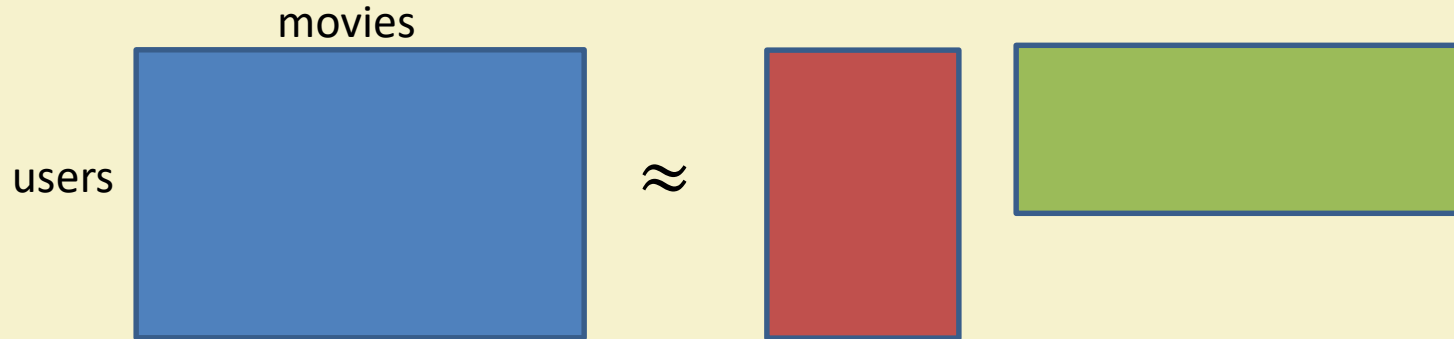
Computer Science and Engineering
IIT GANDHINAGAR



IIT Gandhinagar
Indian Institute of
Technology Gandhinagar

Application of dimension reduction

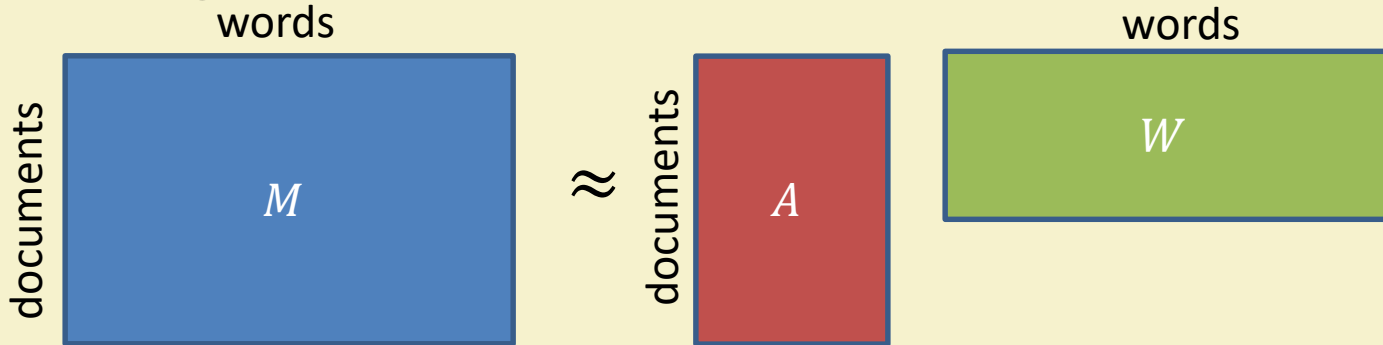
Recommendation system



Minimize some loss function, e.g. $\sum (A_{ij} - X_{i*}Y_{*j})^2$
Use $\sum_k X_{ik} Y_{kj}$ to predict missing entry (i, j)

Application of dimension reduction

Topic modelling



Constraints e.g. A and W non-negative

Singular Value Decomposition

- $A = U\Sigma V^t$
- Optimality properties e.g.

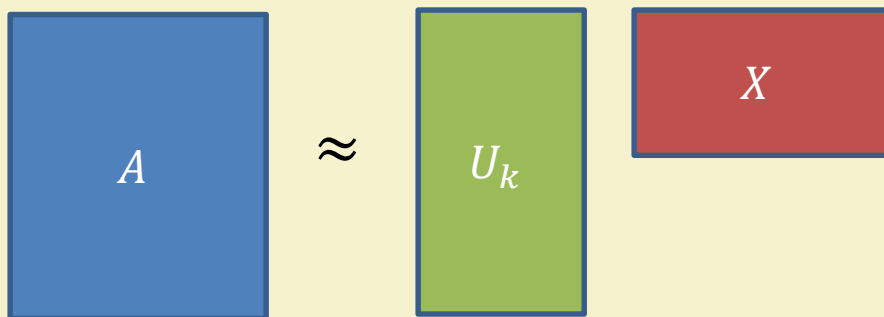
$$A_k = U_k \Sigma_k V_k^t = \operatorname{argmin}_{X: \operatorname{rank}(X) \leq k} \|A - X\|_F$$

$$A_k = U_k \Sigma_k V_k^t = \operatorname{argmin}_{X: \operatorname{rank}(X) \leq k} \|A - X\|_2$$

Issues: high complexity, negative U, V etc.

Yet often forms the initialization for other matrix factorizations

Alternate look at SVD



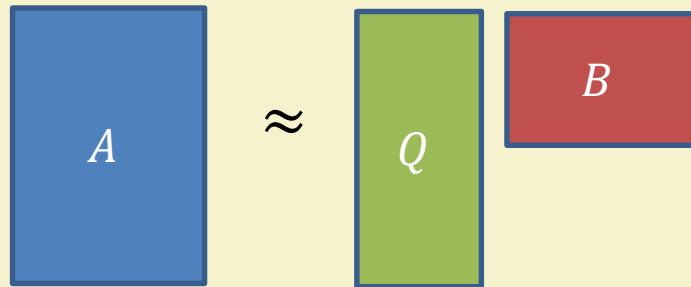
$$X = \Sigma_k V_k^t = U_k^t A$$

Can find a similar decomposition, but more efficiently?

Should retain (approximately) the optimality properties

$$\text{Optimal Frob error} = \|A - U_k(U_k^t A)\|_F^2 = \sum_{j>k} \sigma_j^2$$

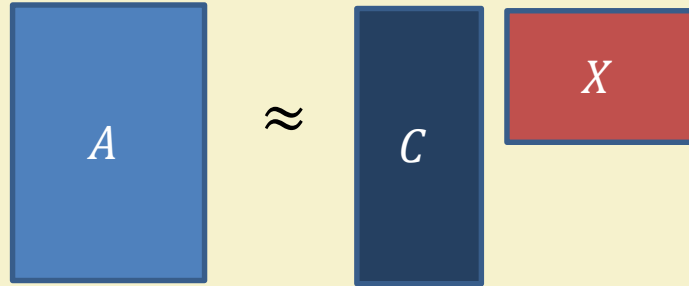
QB decomposition



Can we find orthogonal $Q \in \mathbb{R}^{n \times (k+p)}$ and B such that
 $|A - QB|_F \approx |A - A_k|_F$ and/or $|A - QB|_F \approx |A - A_k|_2$

Also want $k + p = O(k)$

CX decomposition

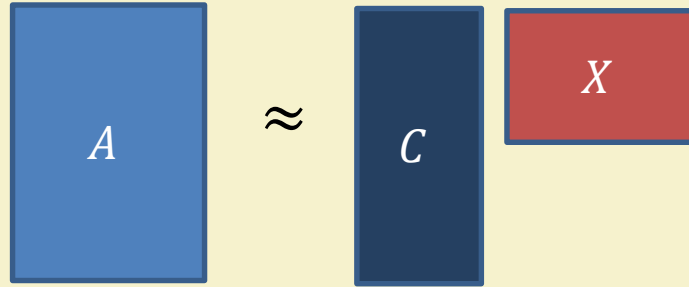


Can we find C , a subset of columns of A , such that

$$|A - CX|_F \approx |A - A_k|_F$$

and $|C| = O(k)$?

CX decomposition



Can we find C , a subset of columns of A , such that

$$\|A - CX\|_F \approx \|A - A_k\|_F$$

and $|C| = O(k)$? It is not clear that this even exists!! Useful in ML applications when actual columns, and not their linear combinations, are needed.

QB: prototype algorithm

Find $\Omega \in \Re^{d \times (k+p)}$ a random matrix

$$Y = A \Omega$$

Find Q = orthogonal basis for $\text{col}(Y)$

Return $(Q, Q^t A)$

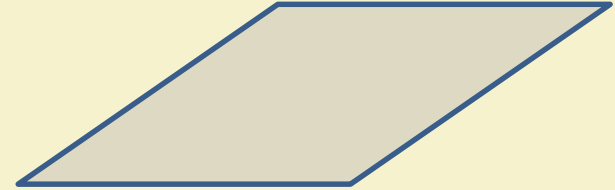


Intuition

Assume $\text{rank}(A) = k$

$\omega_1 \dots \omega_k \in \mathbb{R}^d$ be random vectors

$A\omega_1, A\omega_2, \dots, A\omega_k$ are in general position in column space of A



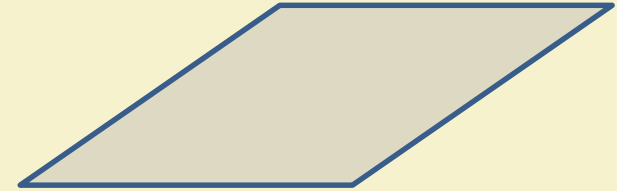
$$\text{colspace}(A) = \text{span}(\{A_{*i}\})$$



Intuition

Assume $\text{rank}(A) = k$

$\omega_1 \dots \omega_k \in \mathbb{R}^d$ be random vectors



$$\text{colspace}(A) = \text{span}(\{A_{*i}\})$$

$A\omega_1, A\omega_2, \dots, A\omega_k$ are in general position in column space of A

$Q = \text{orthogonal basis of } [A\omega_1, \dots, A\omega_k] = A\Omega$ is also basis for $\text{colspace}(A)$

Intuition

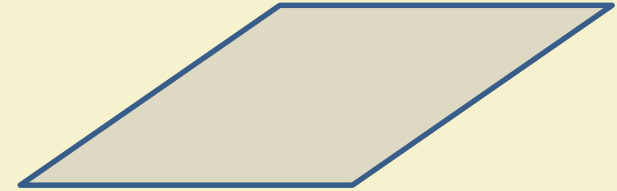
$$A = A_k + E, |E| \text{ small}$$

$\omega_1 \dots \omega_k \in \mathbb{R}^d$ be random vectors

$$A\omega_i = A_k\omega_i + E\omega_i$$

The perturbation E can take a vector out of the column-space A

But, if we take $k + p$ vectors, the chance that $\{A\omega_i\}$ does not span $\{A_{*i}\}$ is small



$$\text{colspace}(A) = \text{span}(\{A_{*i}\})$$

Random matrix

Ω = any JL matrix e.g. $N(0,1)$ or ± 1 or FJLT or Sparse JL

Theoretical bounds are the same, however these differ in numerical stability issues

Most practical implementations use $N(0,1)$

Theoretical Guarantee

Claim: $E[|A - QB|_F] \leq \left(1 + \frac{k}{p-1}\right) |A - A_k|_F$

Bounds can also be obtained on the L2 norm error, few different variants of the bound

Qualitative take-away: Need to choose p to be a small constant, in practice ≈ 5

Modified Algorithm

In reality, the bound $|A - QB|_F$ depends on the singular values $\{\sigma_{k+1}, \dots, \}$

Bound improves if $\sum_{i \leq k} \sigma_i^2 \gg \sum_{i > k} \sigma_i^2$

Power scheme

In reality, the bound $|A - QB|_F$ depends on the singular values $\{\sigma_{k+1}, \dots, \}$

Bound improves if $\sum_{i \leq k} \sigma_i^2 \gg \sum_{i > k} \sigma_i^2$

To achieve this, we use $(AA^t)^P A = U \Sigma^{2P+1} V^t$

Modified Algorithm [HMK10]

```
function  $[\mathbf{Q}, \mathbf{B}] = \text{randQB\_p}(\mathbf{A}, \ell, P)$ 
```

```
 $\mathbf{\Omega} = \text{randn}(n, \ell).$ 
```

```
 $\mathbf{Q} = \text{orth}(\mathbf{A}\mathbf{\Omega}).$ 
```

```
for  $j = 1 : P$ 
```

```
     $\mathbf{Q} = \text{orth}(\mathbf{A}^* \mathbf{Q}).$ 
```

```
     $\mathbf{Q} = \text{orth}(\mathbf{A} \mathbf{Q}).$ 
```

```
end for
```

```
 $\mathbf{B} = \mathbf{Q}^* \mathbf{A}$ 
```

Total runtime = $O(nd\ell + n\ell^2)$

$\ell = k + p \approx k + 5$

$P = 1$ or 2 is sufficient

References:

- Primary reference
 - Lecture notes on Randomized Numerical Linear Algebra by Petros Drineas and Michael Mahoney, <https://arxiv.org/abs/1712.08880>
 - Finding Structure with Randomness, Halko, Martinsson and Tropp, <https://arxiv.org/pdf/0909.4061.pdf>
 - A Practical Guide to Randomized Matrix Computations with MATLAB Implementations, Shushen Wang, <https://arxiv.org/pdf/1505.07570.pdf>

Thank You!!



IIT Gandhinagar
Indian Institute of
Technology Gandhinagar



NPTEL ONLINE
CERTIFICATION COURSES

Anirban Dasgupta
Computer Science and Engg.