class-imbalancing-mlp-on-cifar

May 27, 2024

1 Class Imbalancing in Multilayer perceptrons

This code will:

- 1.Load the CIFAR-10 dataset.
- 2. Create an imbalanced training set.
- 3.Apply SMOTE to balance the dataset.
- 4. Train a CNN on the CIFAR-10 dataset.
- 5.Extract features from the output layer of the trained CNN.
- 6. Train an MLP using these extracted features.
- 7. Test the MLP on the CIFAR-10 test dataset and print the accuracy.

```
[11]: import torch
import torch.nn as nn
import torch.optim as optim
import torch.nn.functional as F
from torchvision import datasets, transforms
from torch.utils.data import DataLoader, Subset
from imblearn.over_sampling import SMOTE
import numpy as np
```

1.0.1 Step 1: Load CIFAR 10 dataset

```
Downloading https://www.cs.toronto.edu/~kriz/cifar-10-python.tar.gz to data/cifar-10-python.tar.gz
```

```
100% | 170498071/170498071 [00:02<00:00, 84772974.95it/s]
```

Extracting data/cifar-10-python.tar.gz to data

1.0.2 Step 2: Apply imbalancing function for class imbalance

```
[13]: # Function to create an imbalanced dataset
      def get_imbalanced_data(dataset, num_sample_per_class, shuffle=False,_
       →random seed=0):
          11 11 11
          Return a list of imbalanced indices from a dataset.
          Input: A dataset (e.g., CIFAR-10), num_sample per class: list of integers
          Output: imbalanced_list
          11 11 11
          length = len(dataset)
          num_sample_per_class = list(num_sample_per_class)
          selected list = []
          indices = list(range(0, length))
          if shuffle:
              np.random.seed(random_seed)
              np.random.shuffle(indices)
          for i in range(0, length):
              index = indices[i]
              _, label = dataset[index]
              if num_sample_per_class[label] > 0:
                  selected_list.append(index)
                  num_sample_per_class[label] -= 1
          return selected_list
      # Create imbalance in the dataset
      num_samples = [5000, 3000, 2000, 1000, 500, 200, 100, 50, 20, 10]
      imbalanced indices = get imbalanced data(train dataset, num samples)
      train_dataset = Subset(train_dataset, imbalanced_indices)
```

1.0.3 Step 3: Apply SMOTE for balancing

```
[15]: # # Store flattened vectors for train data

# X_train = train_images_resampled.view(-1, 28 * 28)

# Y_train = train_labels_resampled
```

1.0.4 Step 4: Build CNN & Train

```
[16]: class CNN(nn.Module):
          def __init__(self):
              super(CNN, self).__init__()
              self.conv1 = nn.Conv2d(3, 32, kernel_size=3)
              self.conv2 = nn.Conv2d(32, 64, kernel_size=3)
              self.fc1 = nn.Linear(64 * 6 * 6, 128)
              self.fc2 = nn.Linear(128, 10)
          def forward(self, x):
              x = F.relu(F.max_pool2d(self.conv1(x), 2))
              x = F.relu(F.max_pool2d(self.conv2(x), 2))
              x = x.view(-1, 64 * 6 * 6)
              x = F.relu(self.fc1(x))
              logits = self.fc2(x)
              return logits, x # Return logits and features from the penultimate
       \hookrightarrow layer
      cnn = CNN()
      # Define optimizer and loss function
      optimizer cnn = optim.Adam(cnn.parameters(), lr=0.001)
      criterion = nn.CrossEntropyLoss()
      print("Training the CNN ... ")
      # Train the CNN
      def train_cnn(model, train_loader, optimizer, criterion, epochs=10):
          for epoch in range(epochs):
              model.train()
              running_loss = 0.0
              for data, target in train_loader:
                  optimizer.zero_grad()
                  logits, _ = model(data)
                  loss = criterion(logits, target)
                  loss.backward()
                  optimizer.step()
                  running_loss += loss.item() * data.size(0)
              print(f"Epoch {epoch+1}/{epochs}, Loss: {running_loss/len(train_loader.
       ⊸dataset)}")
      train_loader_cnn = DataLoader(list(zip(train_images_resampled,_
       strain_labels_resampled)), batch_size=64, shuffle=True)
```

```
train_cnn(cnn, train_loader_cnn, optimizer_cnn, criterion)

Training the CNN ...
    Epoch 1/10, Loss: 0.681249429860115
    Epoch 2/10, Loss: 0.25750763940811155
    Epoch 3/10, Loss: 0.14672491289377212
    Epoch 4/10, Loss: 0.09565989250063896
    Epoch 5/10, Loss: 0.06459150330781936
    Epoch 6/10, Loss: 0.04818558646805585
    Epoch 6/10, Loss: 0.03930638539776206
    Epoch 8/10, Loss: 0.03930638539776206
    Epoch 8/10, Loss: 0.03287420496612787
    Epoch 9/10, Loss: 0.029538248270601034
    Epoch 10/10, Loss: 0.017137879557819105

[17]: # # Store flattened vectors for test data
    # X_test = test_images.view(-1, 28 * 28)
    # Y_test = test_labels
```

1.0.5 Step 5: Build a Multi-layer Perceptron

```
[18]: #Extract features from the CNN to feed into the MLP
      cnn.eval()
      with torch.no_grad():
          train_features = []
          for data, _ in train_loader_cnn:
              _, features = cnn(data)
              train_features.append(features)
          train_features = torch.cat(train_features)
      #Build a Multi-layer Perceptron
      class MLP(nn.Module):
          def __init__(self):
              super(MLP, self).__init__()
              self.fc1 = nn.Linear(128, 256)
              self.fc2 = nn.Linear(256, 128)
              self.fc3 = nn.Linear(128, 10)
          def forward(self, x):
              x = F.relu(self.fc1(x))
              x = F.relu(self.fc2(x))
              x = self.fc3(x)
              return x
      mlp = MLP()
      # Define optimizer and loss function
      optimizer_mlp = optim.Adam(mlp.parameters(), lr=0.001)
      criterion_mlp = nn.CrossEntropyLoss()
```

```
print("Training the MLP ... ")
```

Training the MLP \dots

1.0.6 Step 6: Apply cross-entropy loss for loss calculation

```
[19]: # Training the MLP
      def train_mlp(model, train_loader, optimizer, criterion, epochs=10):
          for epoch in range(epochs):
              model.train()
              running_loss = 0.0
              for data, target in train_loader:
                  optimizer.zero_grad()
                  output = model(data)
                  loss = criterion(output, target)
                  loss.backward()
                  optimizer.step()
                  running_loss += loss.item() * data.size(0)
              print(f"Epoch {epoch+1}/{epochs}, Loss: {running_loss/len(train_loader.
       →dataset)}")
      train_loader_mlp = DataLoader(list(zip(train_features,__
       →train_labels_resampled)), batch_size=64, shuffle=True)
      train_mlp(mlp, train_loader_mlp, optimizer_mlp, criterion_mlp)
```

```
Epoch 1/10, Loss: 2.308327042312622
Epoch 2/10, Loss: 2.302695669631958
Epoch 3/10, Loss: 2.302870717163086
Epoch 4/10, Loss: 2.301990905075073
Epoch 5/10, Loss: 2.301452420425415
Epoch 6/10, Loss: 2.3004353280639647
Epoch 7/10, Loss: 2.2984436138916013
Epoch 8/10, Loss: 2.2964931101226806
Epoch 9/10, Loss: 2.292941941986084
Epoch 10/10, Loss: 2.288054637680054
```

1.0.7 Step 8: Calculate final accuracy

```
[20]: def test(model, test_loader):
    model.eval()
    correct = 0
    total = 0
    with torch.no_grad():
        for data, target in test_loader:
            output = model(data)
            _, predicted = torch.max(output.data, 1)
```

```
total += target.size(0)
            correct += (predicted == target).sum().item()
    accuracy = correct / total
    return accuracy
test_loader_cnn = DataLoader(test_dataset, batch_size=64, shuffle=False)
test_features = []
test_labels = []
cnn.eval()
with torch.no_grad():
    for data, labels in test_loader_cnn:
        _, features = cnn(data)
        test_features.append(features)
        test_labels.append(labels)
test_features = torch.cat(test_features)
test_labels = torch.cat(test_labels)
test_loader_mlp = DataLoader(list(zip(test_features, test_labels)),__
⇔batch_size=64, shuffle=False)
accuracy = test(mlp, test_loader_mlp)
print(f"MLP Test Accuracy: {accuracy*100}")
```

MLP Test Accuracy: 9.2