

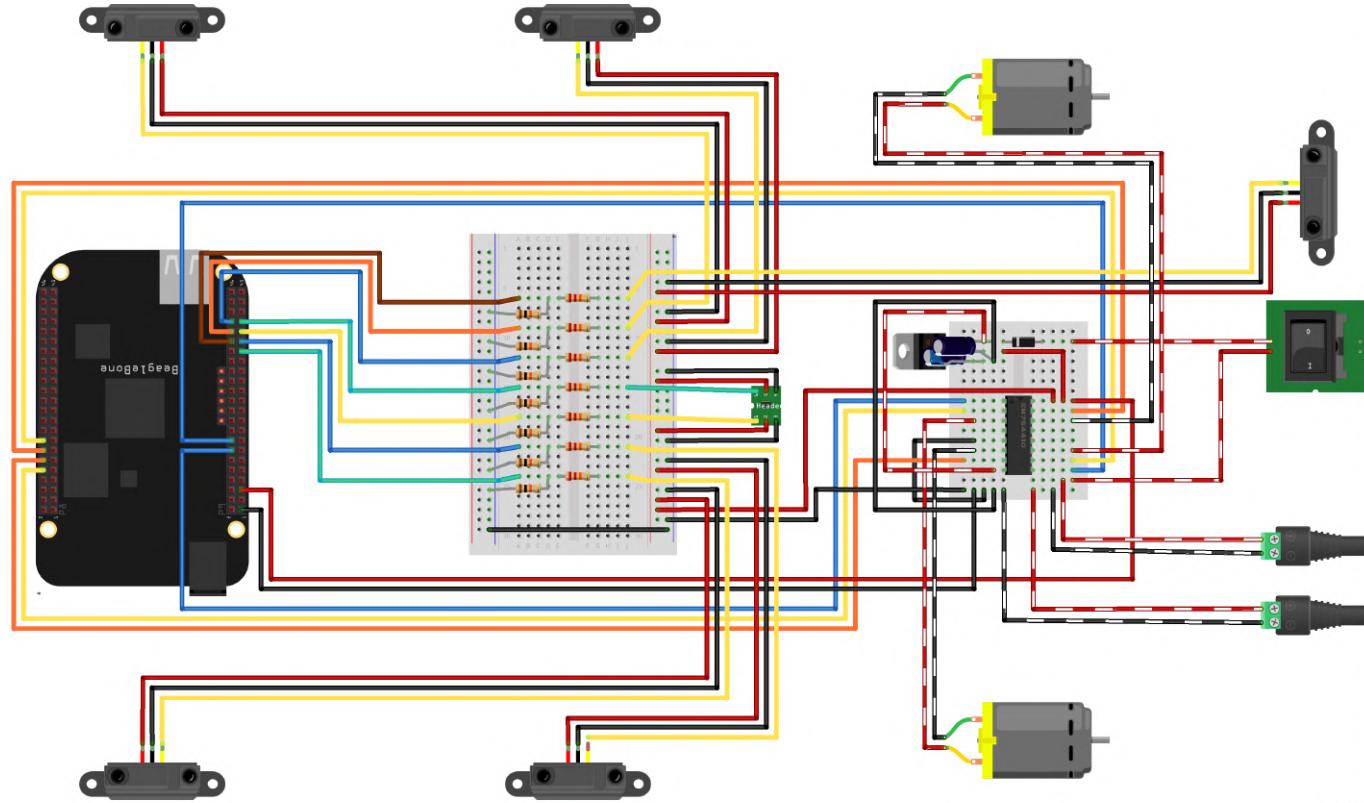
Wiring the QuickBot

Control of Mobile Robots: Hardware Lecture #3



Rowland O'Flaherty
Robotics Ph.D. Candidate
Georgia Tech

QuickBot Wiring



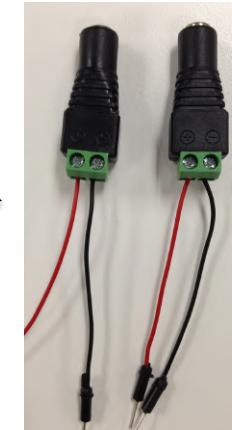
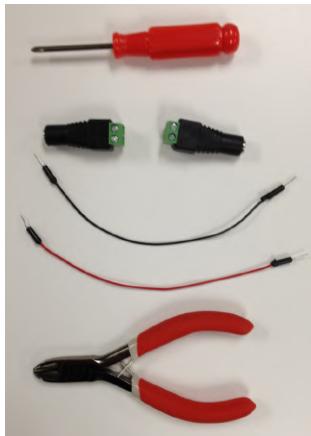
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QuickBot Parts



Build DC Barrel Plug Connectors

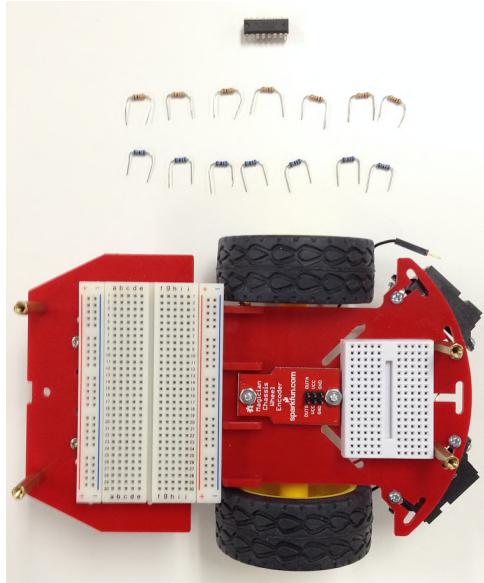
- Cut 2 M-M jumper wires and strip ends



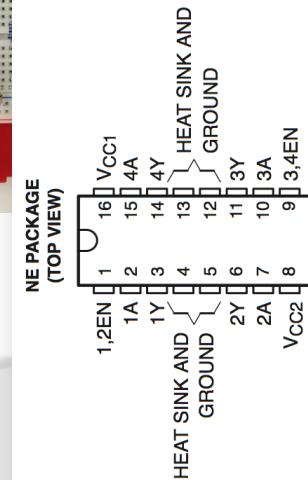
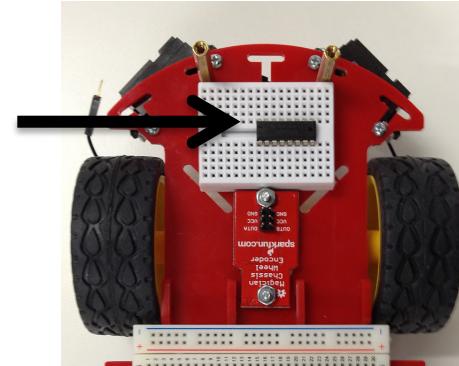
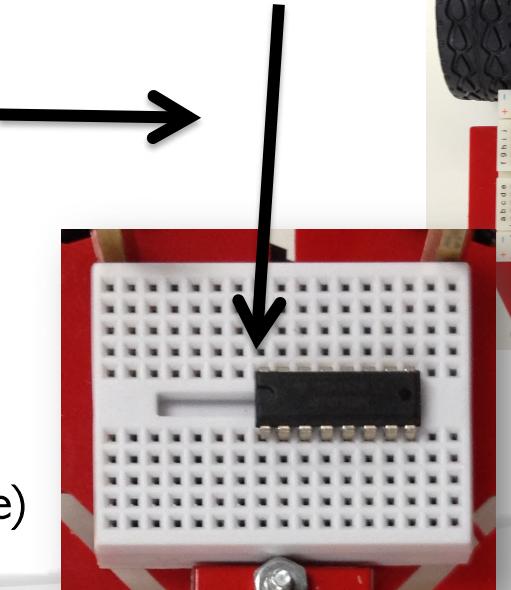
Red wire into "+" pole
Black wire into "-" pole

- Two DC Barrel Jacks
- One Black M/M Wire
- One Read M/M Wire

Add H-Bridge and Voltage Divider Resistors

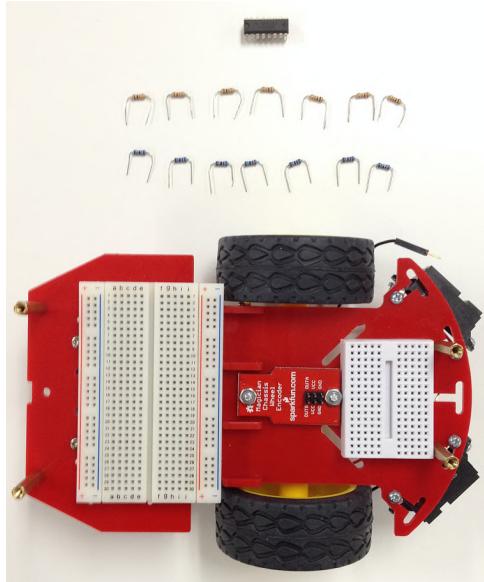


Place notch on IC to the left



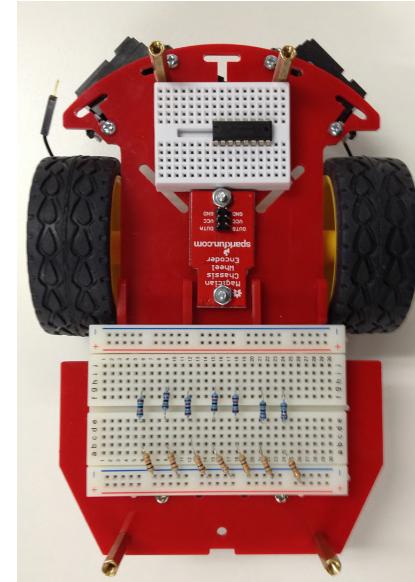
- H-Bridge IC
- Seven 20K Resistors (Red, Black, Orange)
- Seven 10K Resistors (Brown, Black, Orange)

Add H-Bridge and Voltage Divider Resistors



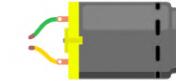
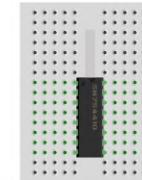
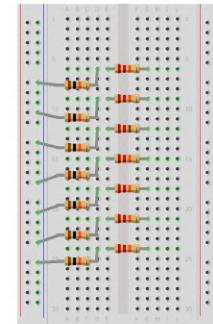
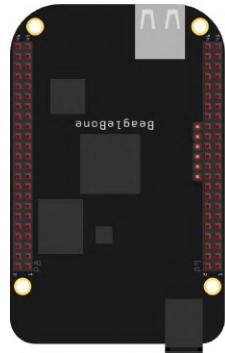
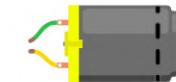
For the voltage divider
use breadboard rows:

1. Row 6
2. Row 9
3. Row 12
4. Row 15
5. Row 18
6. Row 21
7. Row 24



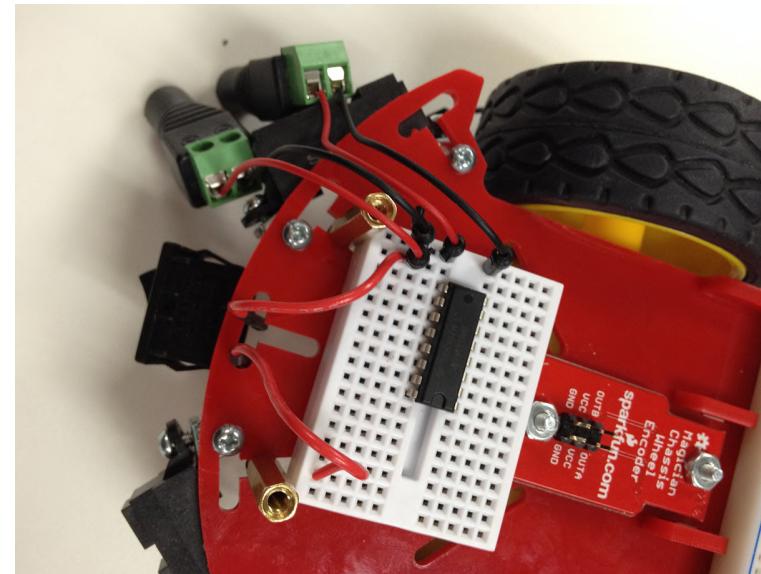
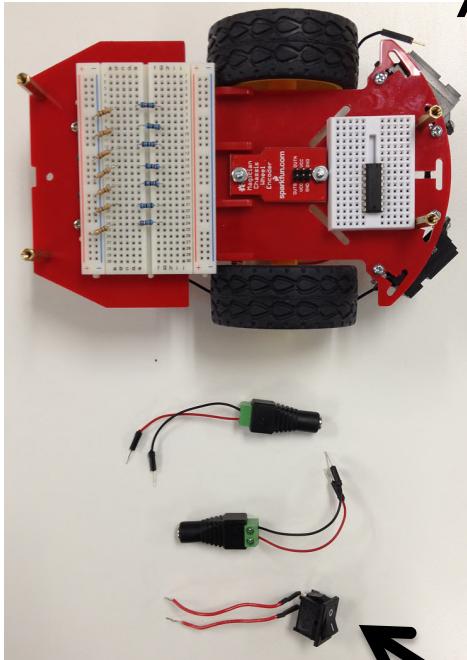
- H-Bridge IC
- Seven 20K Resistors (Red, Black, Orange)
- Seven 10K Resistors (Brown, Black, Orange)

Add H-Bridge and Voltage Divider Resistors



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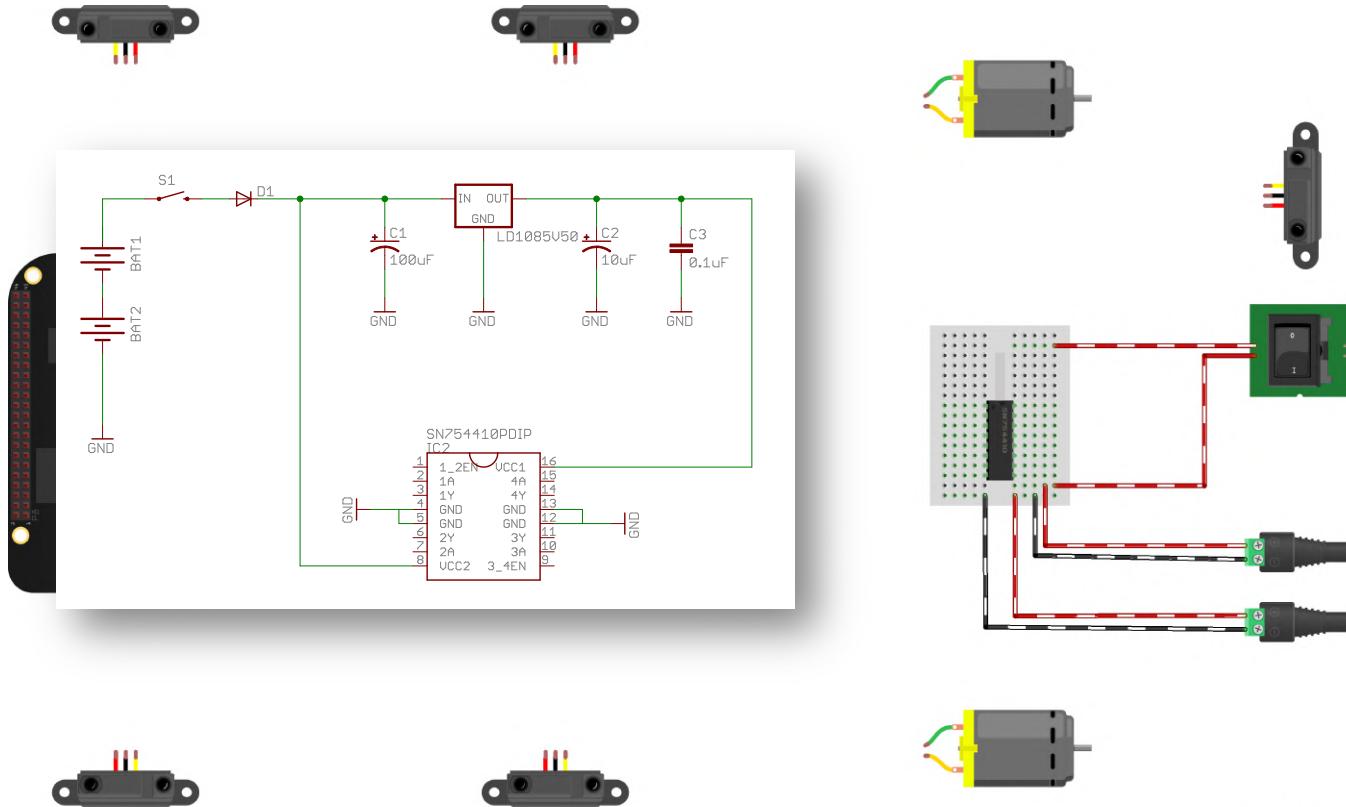
Add DC Jacks & Switch



- Two DC Jacks
- Switch

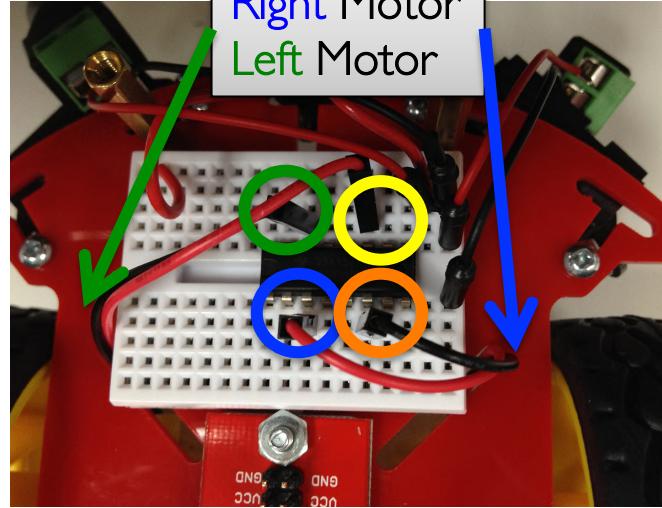
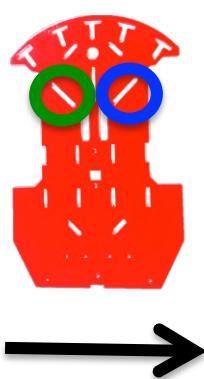
Requires soldering

Add DC Jacks & Switch



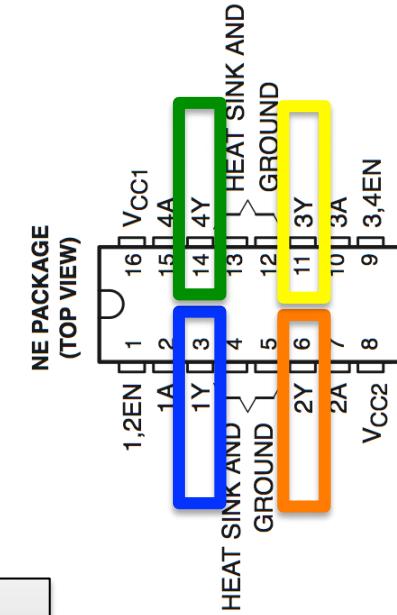
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Plug In Motor Wires

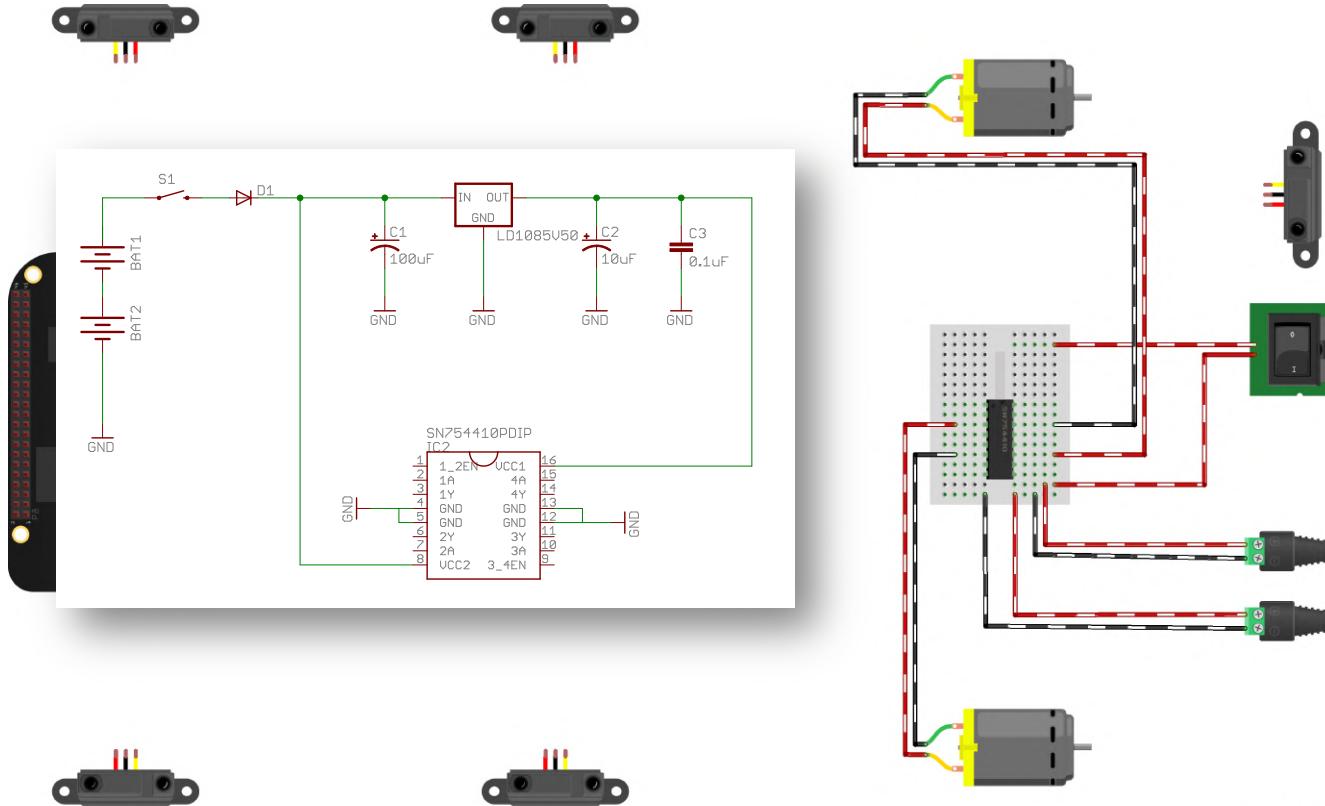


Tape wires

- Connect Right Motor Red Wire to H-Bridge 1Y (Pin 3)
- Connect Right Motor Black Wire to H-Bridge 2Y (Pin 6)
- Connect Left Motor Red Wire to H-Bridge 3Y (Pin 11)
- Connect Left Motor Black Wire to H-Bridge 4Y (Pin 14)

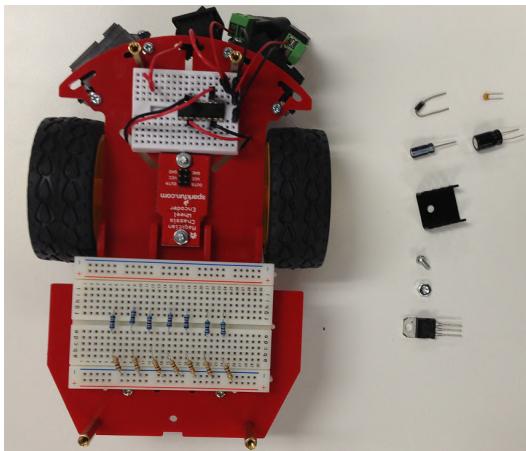


Plug In Motor Wires



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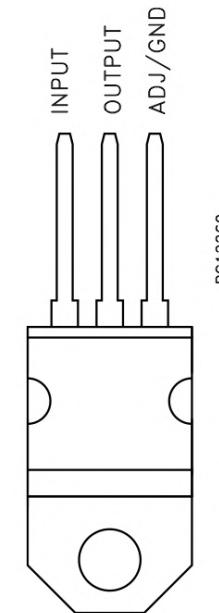
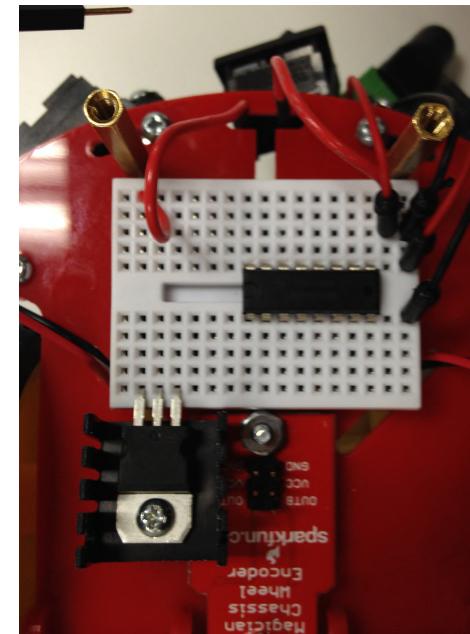
Assemble Power Supply – Voltage Regulator



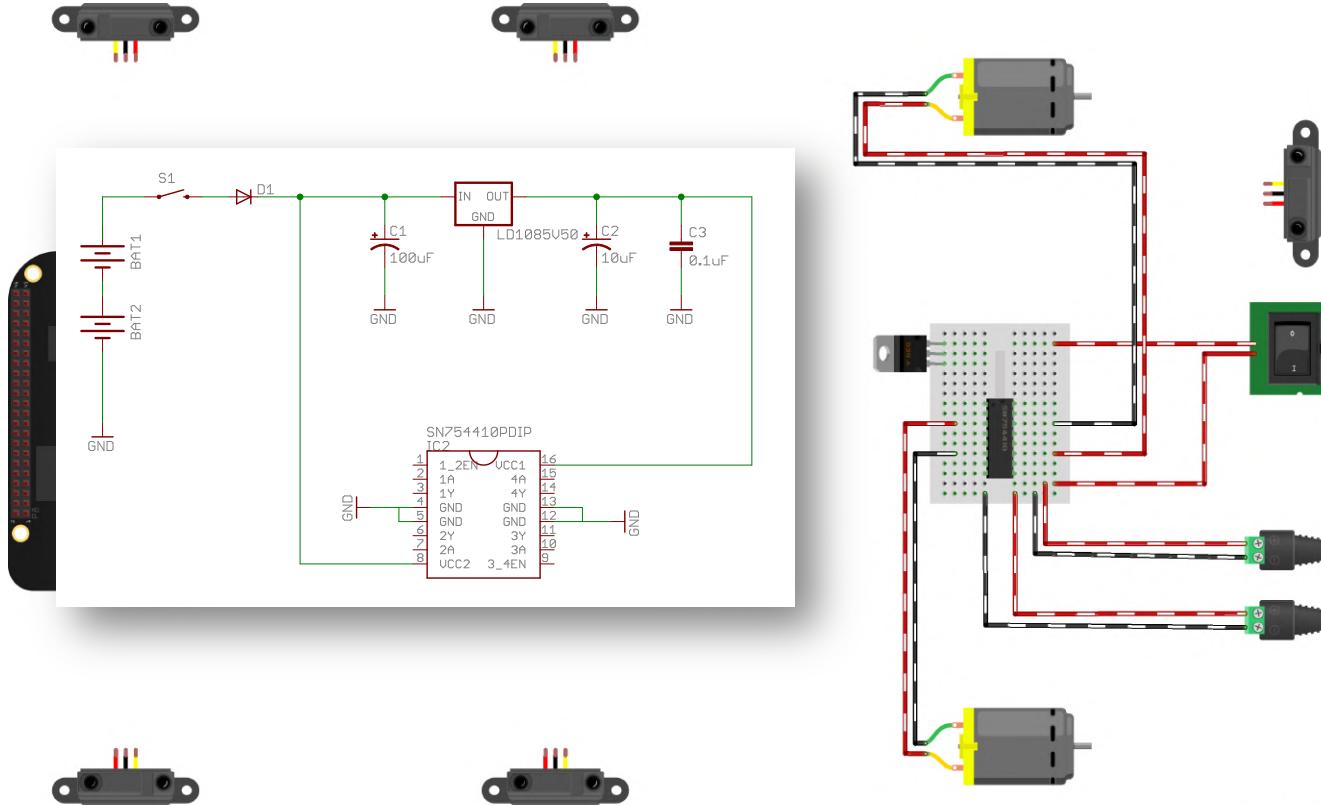
Start with
voltage regulator



- One Voltage Regulator
- One $\frac{1}{4}$ " 4-40 Screws
- One 4-40 Angle Bracket
- One Heat Sink
- One 100uF Capacitor
- One 10uF Capacitor
- One 0.1uF Capacitor
- One Diode

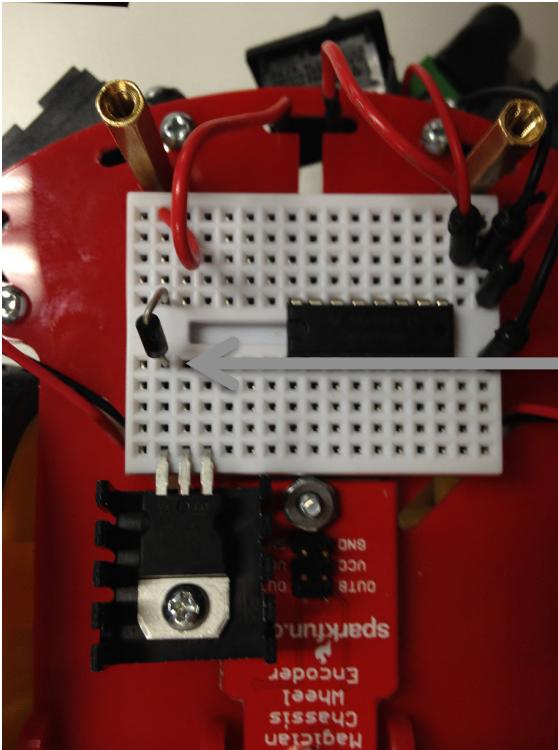


Assemble Power Supply – Voltage Regulator

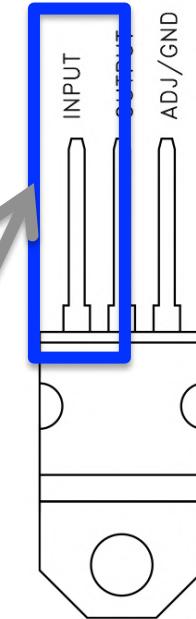


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Assemble Power Supply – Diode

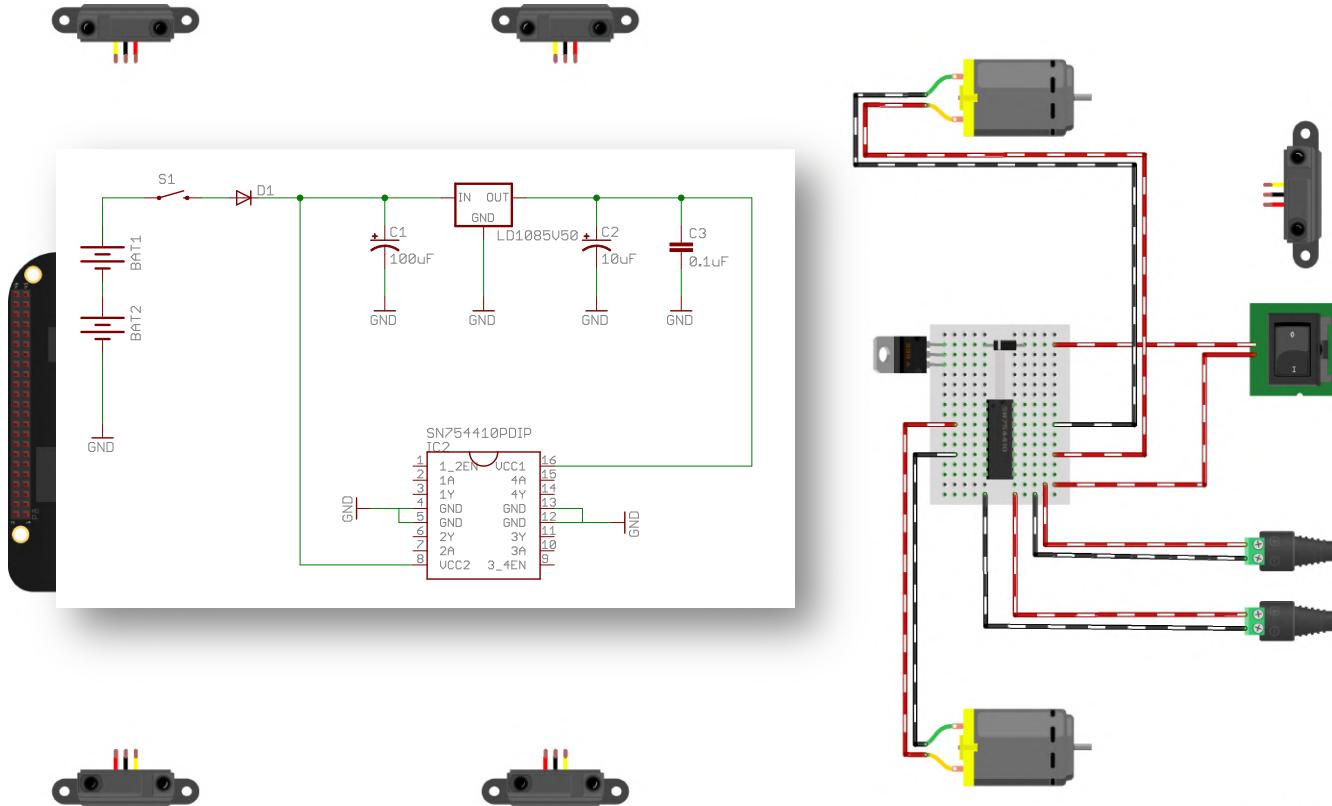


- Diode lead with LINE connect to voltage regulator INPUT pin
- Diode lead without LINE connect switch



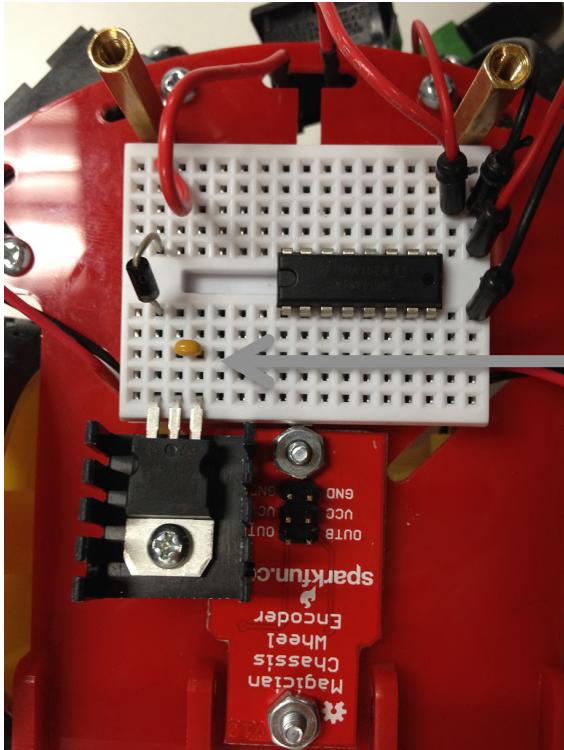
PC12260

Assemble Power Supply – Diode

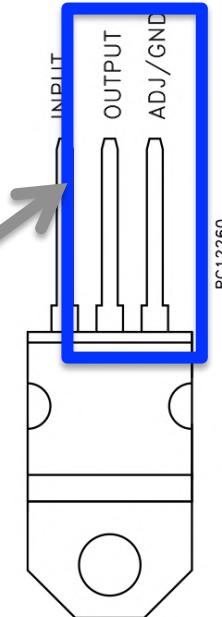


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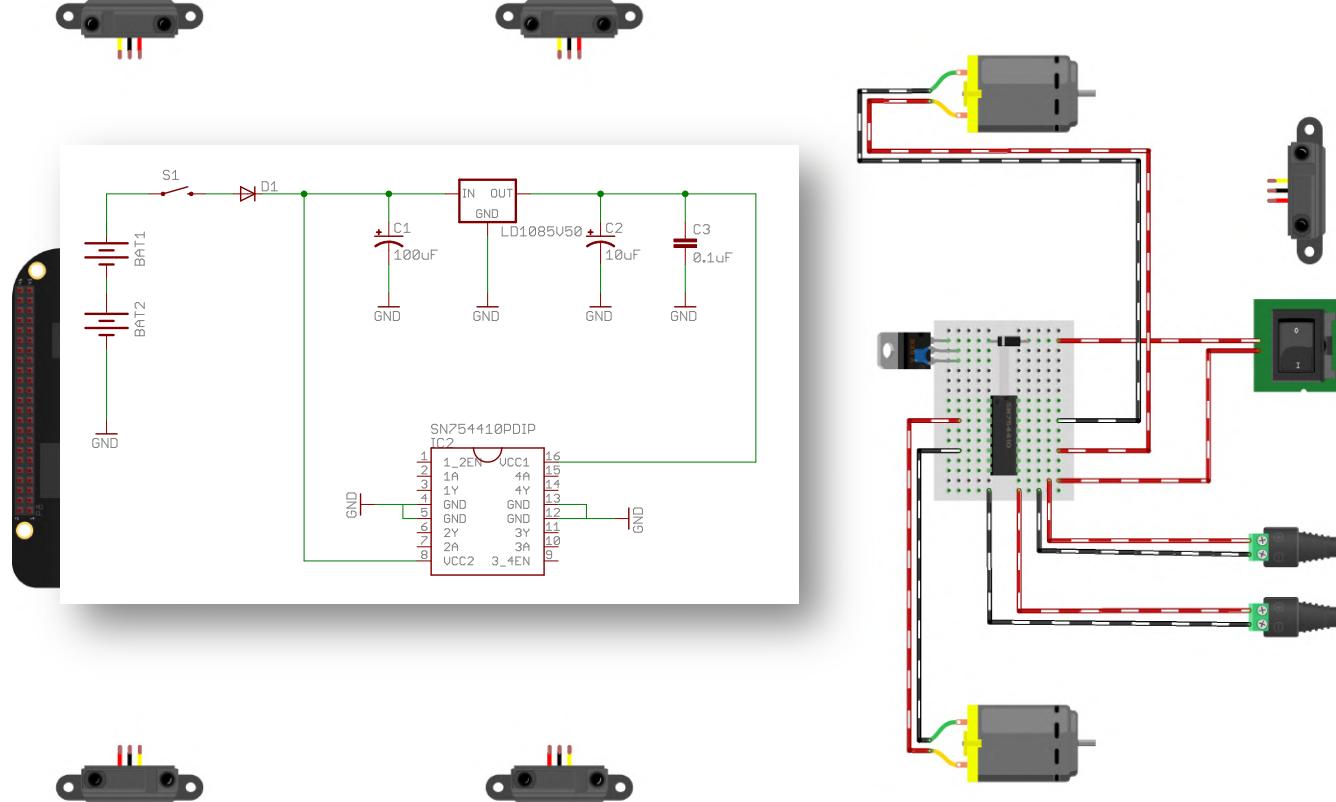
Assemble Power Supply – 0.1 uF Cap



0.1uF Cap connect to
voltage regulator **OUTPUT**
and **GND**

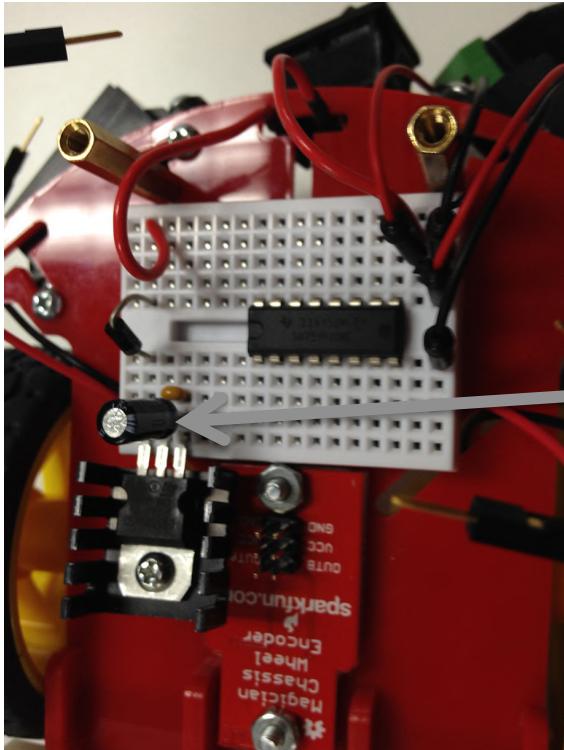


Assemble Power Supply – 0.1 uF Cap

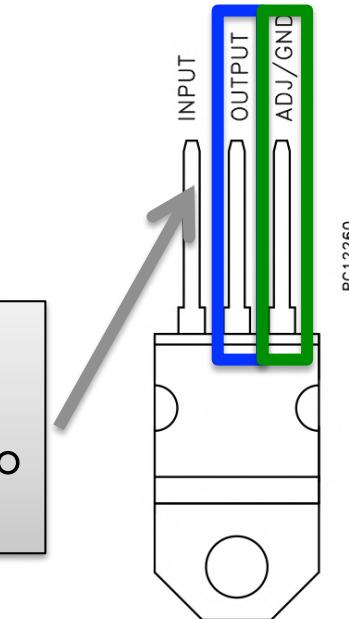


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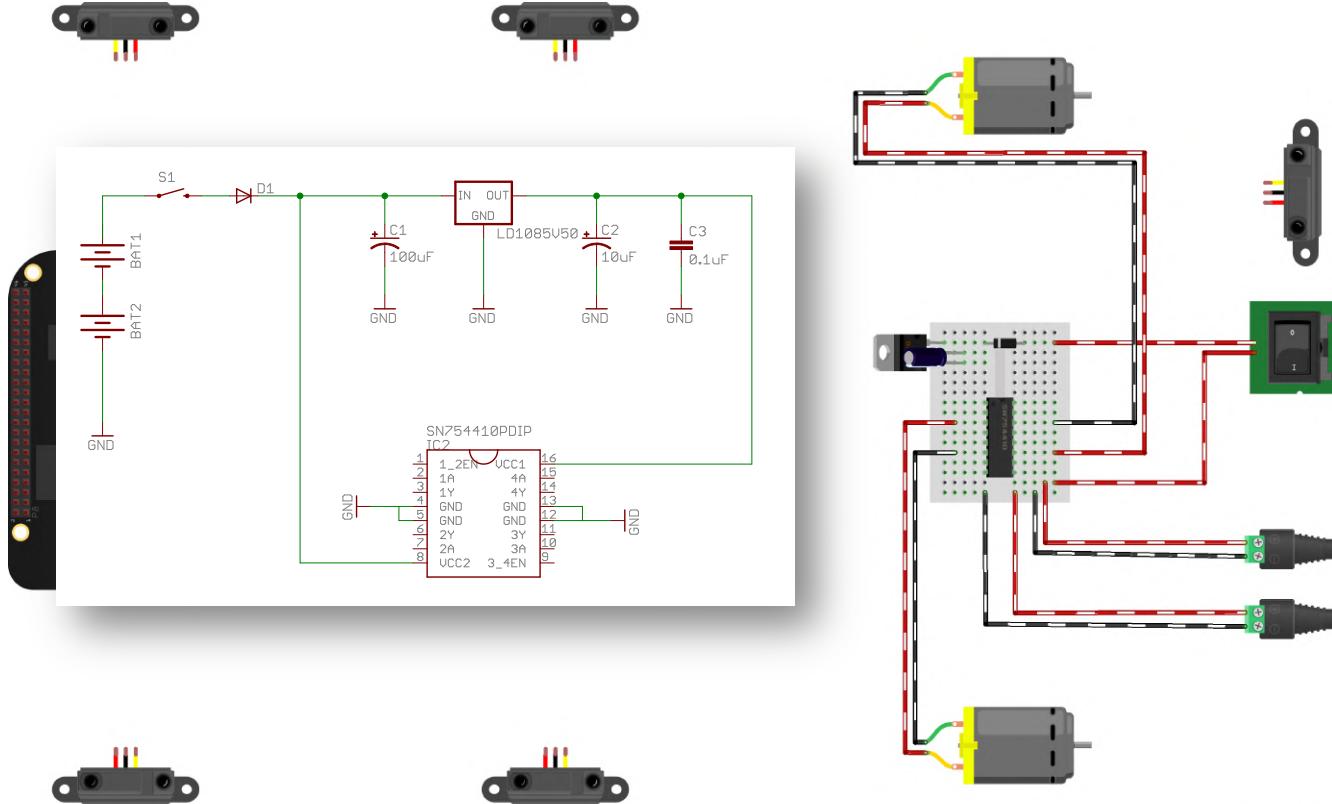
Assemble Power Supply – 10uF Cap



- 10uF Cap positive lead connect to **voltage regulator OUTPUT pin**
- 10uF Cap negative lead ("−") connect to **voltage regulator GND pin**

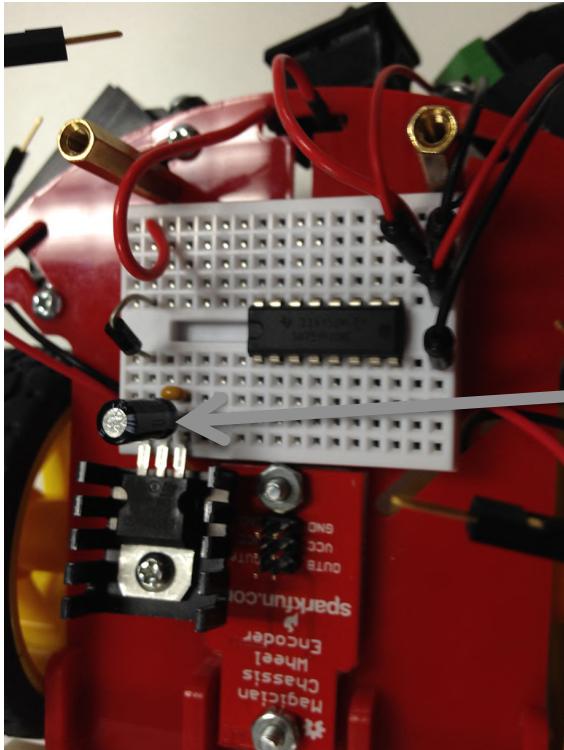


Assemble Power Supply – 100uF Cap

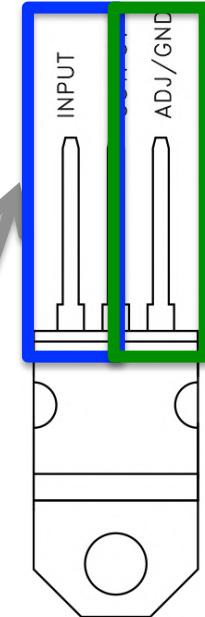


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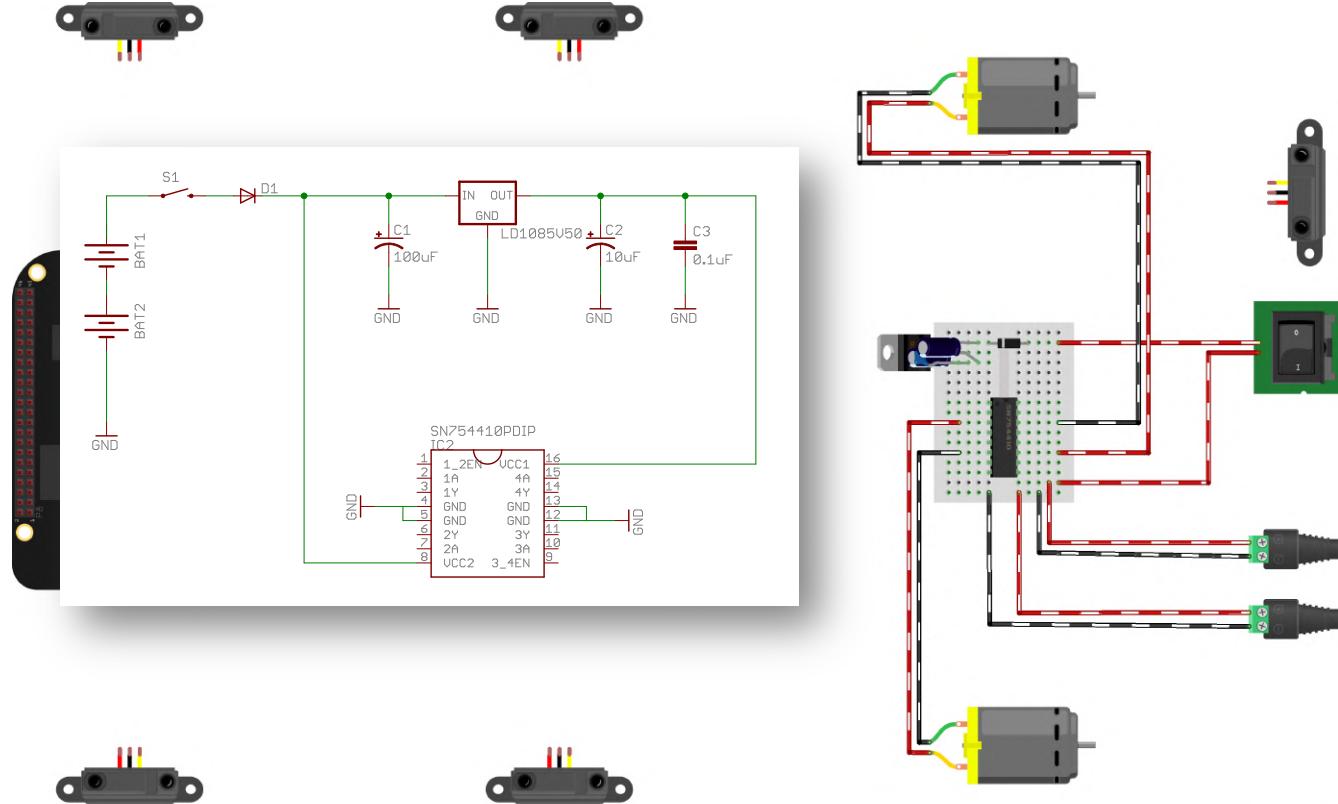
Assemble Power Supply – 100uF Cap



- 100uF Cap positive lead connect to **voltage regulator INPUT pin**
- 100uF Cap negative lead ("−") connect to **voltage regulator GND pin**

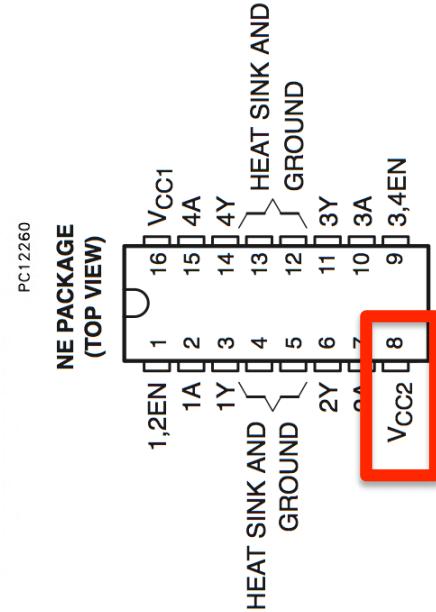
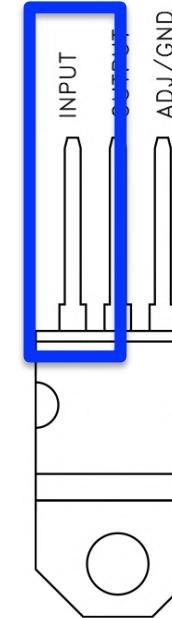
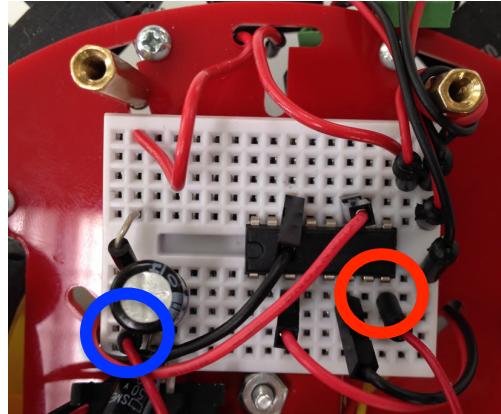
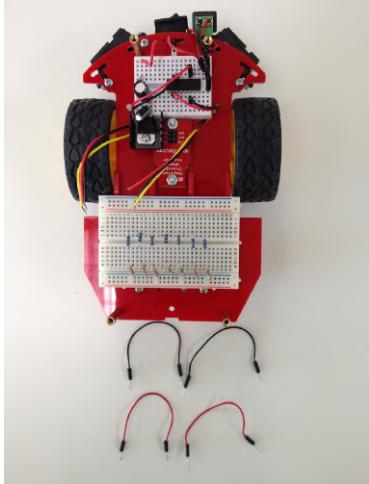


Assemble Power Supply – 100uF Cap



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Connect H-Bridge Power – 1st Red Wire

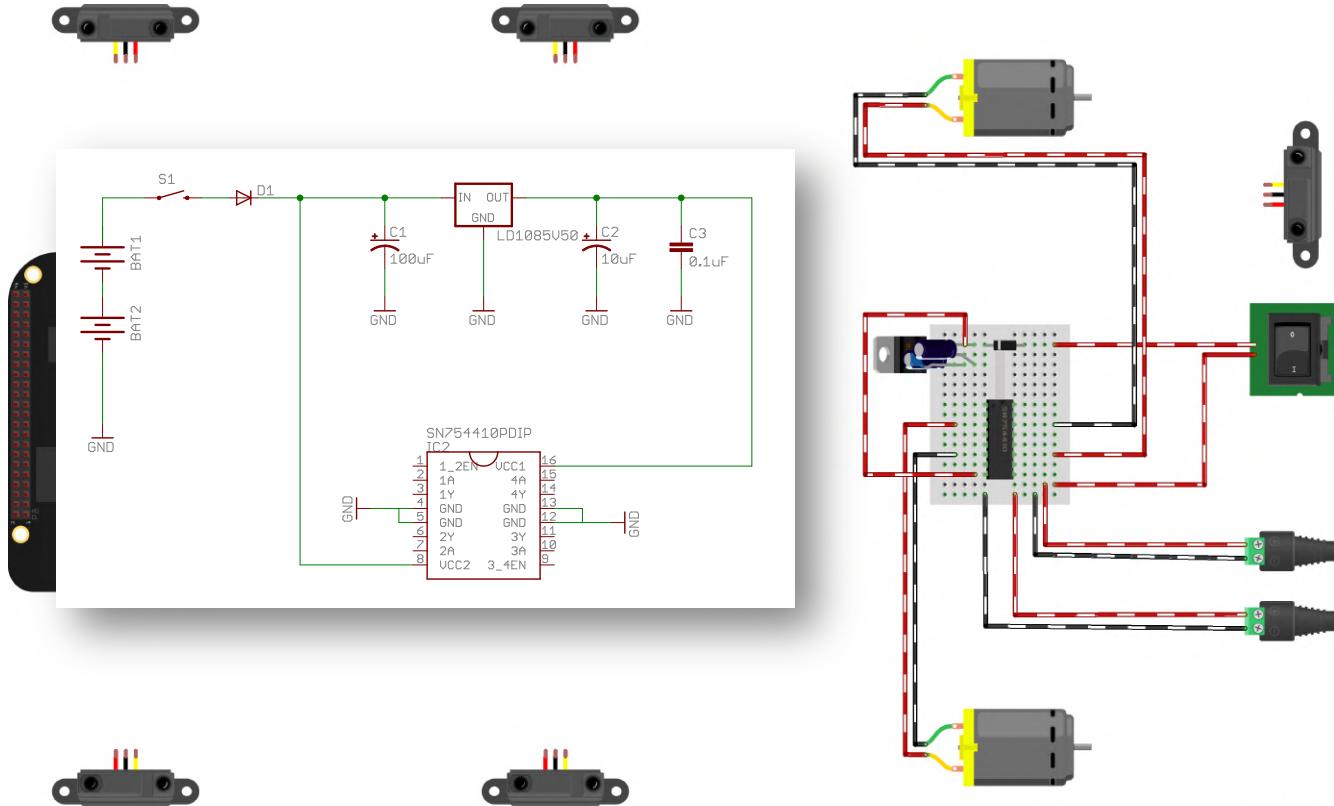


- Two Black M/M Wires
- Two Red M/M Wires

Connect **voltage regulator INPUT** pin to **H-Bridge Vcc2 (Pin 8)**

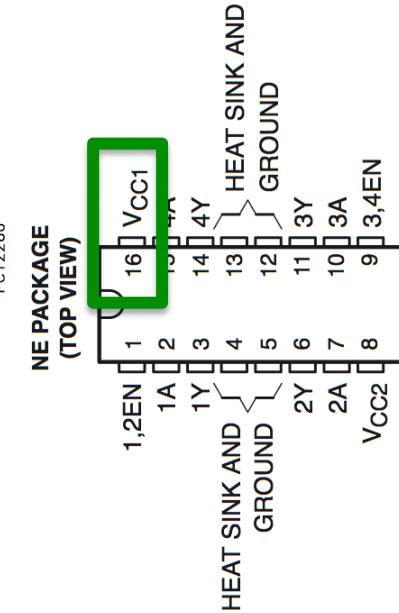
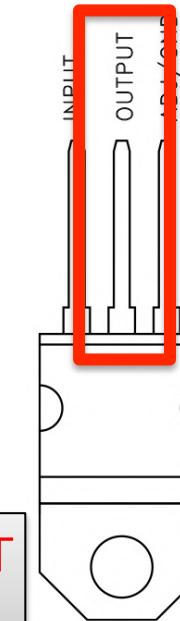
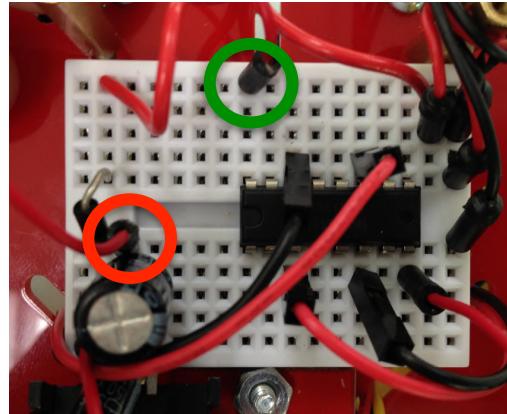
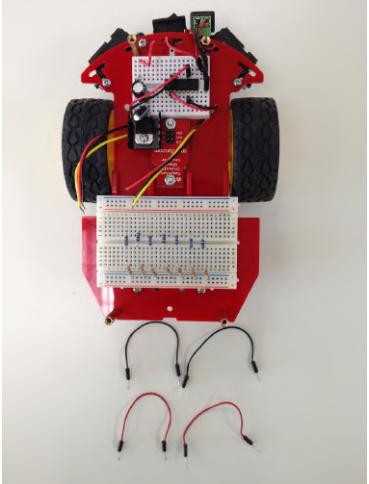
Caution: Triple check that you have wired this connection correctly.
If this is wired incorrectly there is a good chance you will burn out your BeagleBone Black!

Connect H-Bridge Power – 1st Red Wire



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Connect H-Bridge Power – 2nd Red Wire

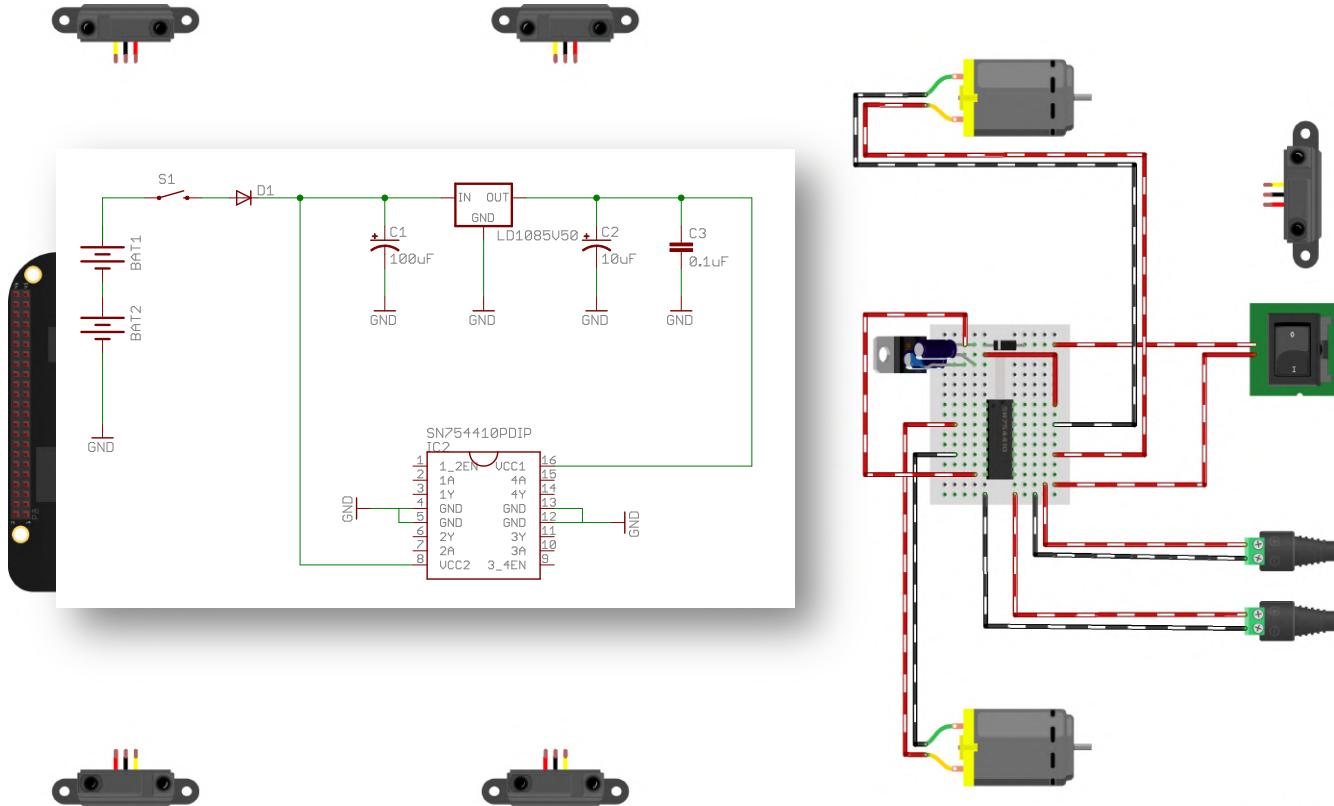


- Two Black M/M Wires
- Two Red M/M Wires

Connect **voltage regulator OUTPUT pin** to H-Bridge Vcc1 (Pin 16)

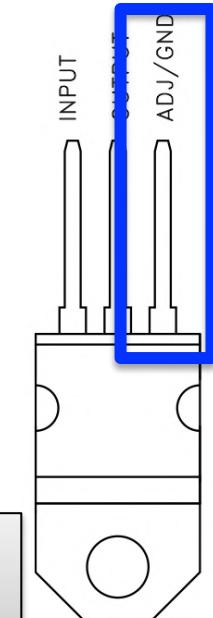
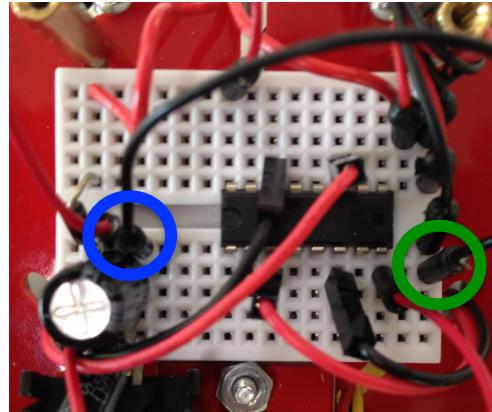
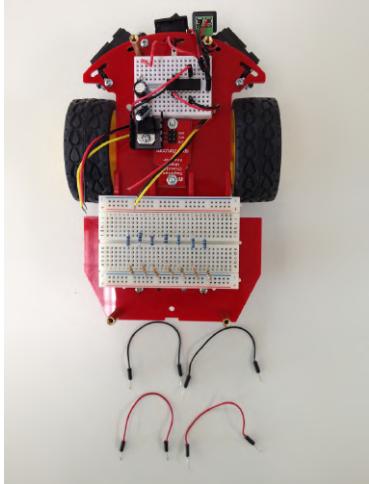
Caution: Triple check that you have wired this connection correctly.
If this is wired incorrectly there is a good chance you will burn out your BeagleBone Black!

Connect H-Bridge Power – 2nd Red Wire



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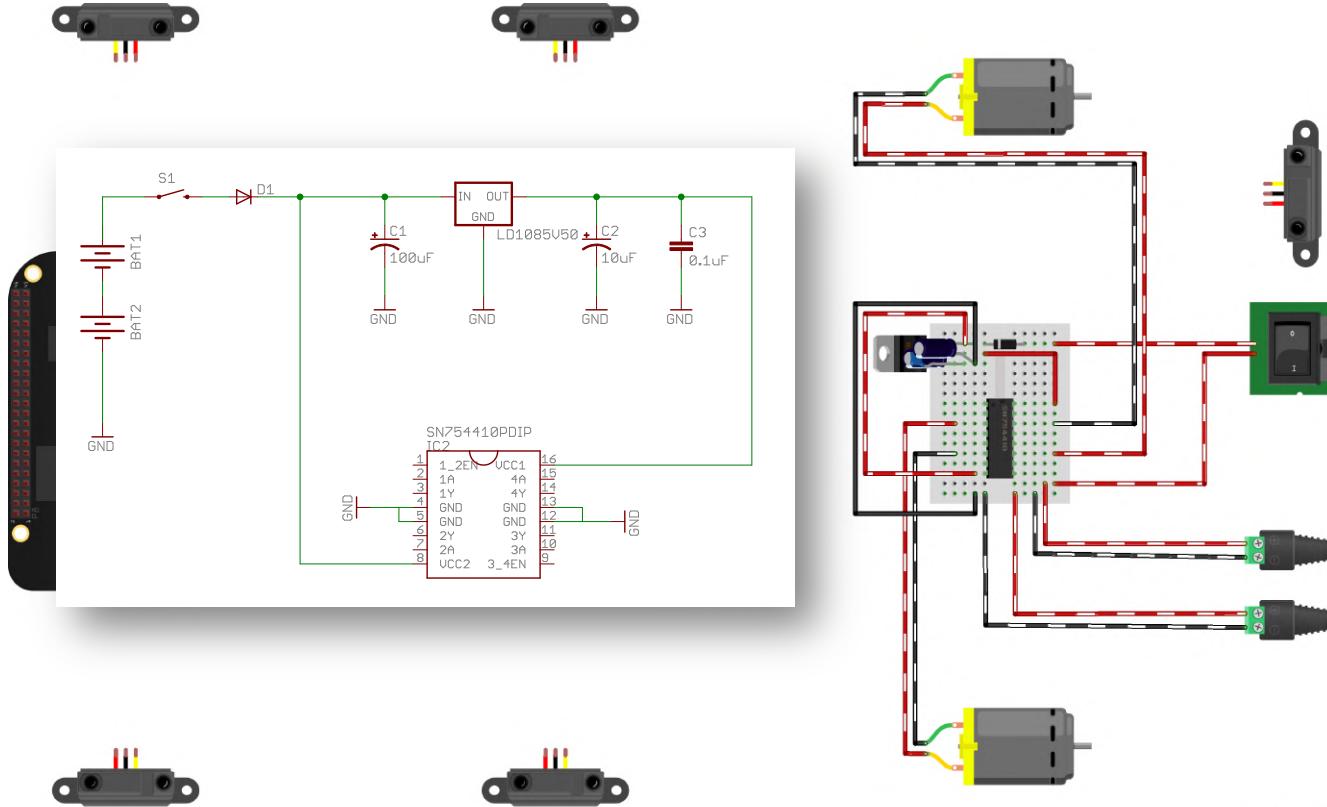
Connect H-Bridge Power – 1st Black Wire



- Two Black M/M Wires
- Two Red M/M Wires

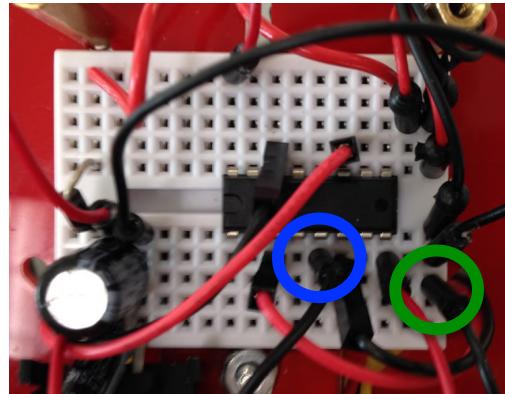
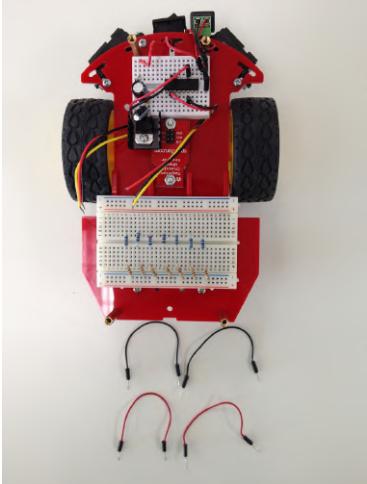
Connect **voltage regulator GND**
to **battery GND**

Connect H-Bridge Power – 1st Black Wire

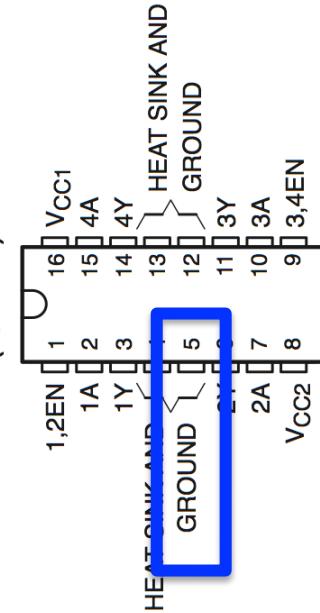


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Connect H-Bridge Power – 2nd Black Wire



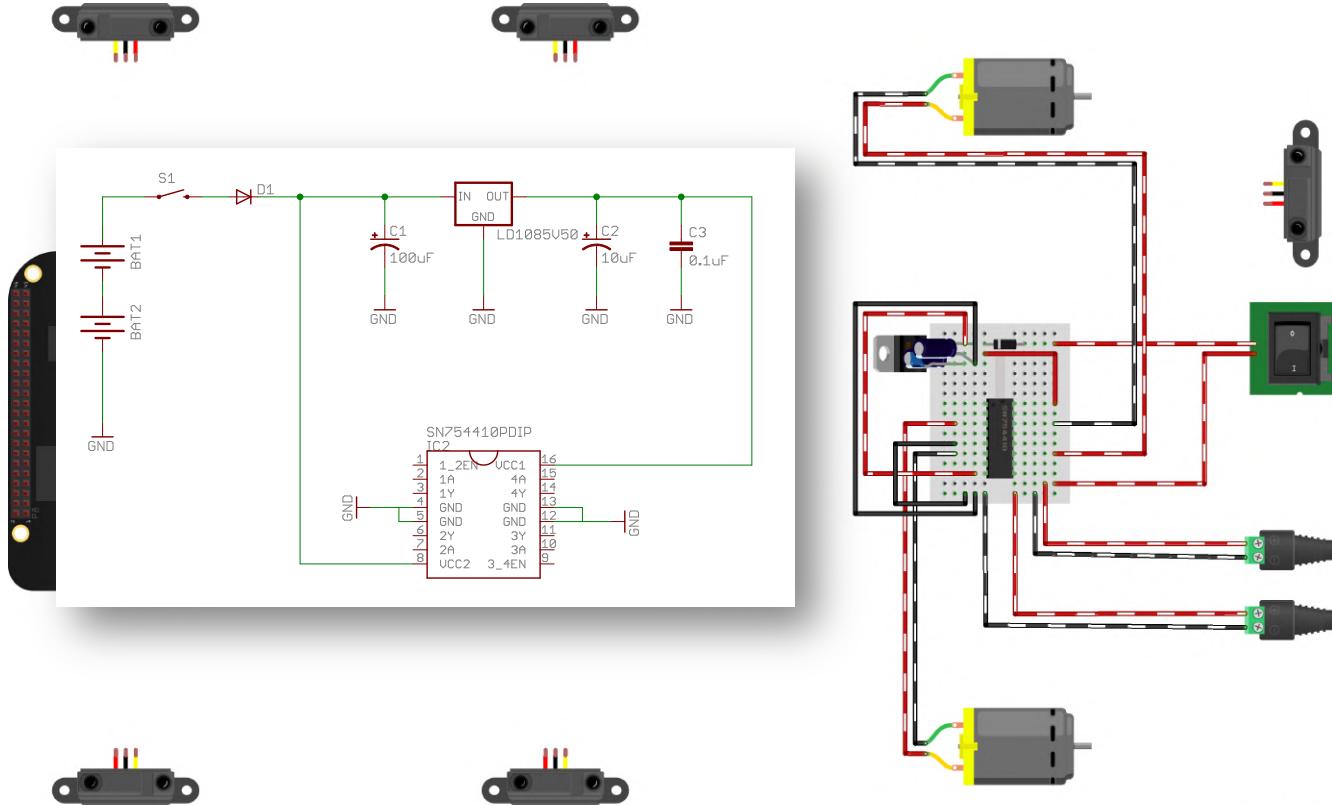
NE PACKAGE
(TOP VIEW)



- Two Black M/M Wires
- Two Red M/M Wires

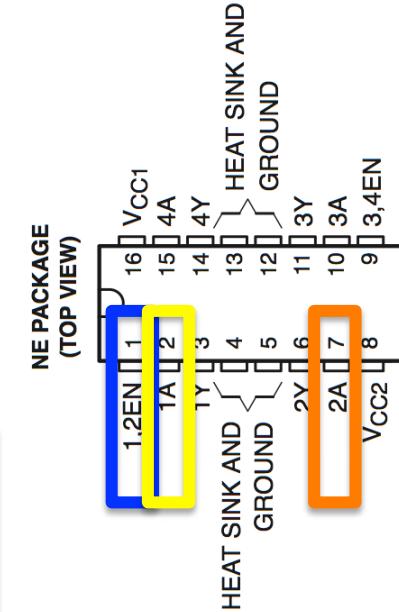
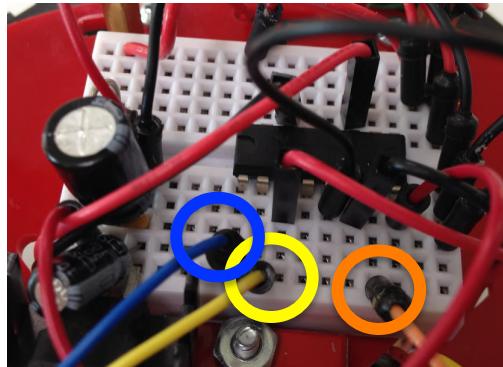
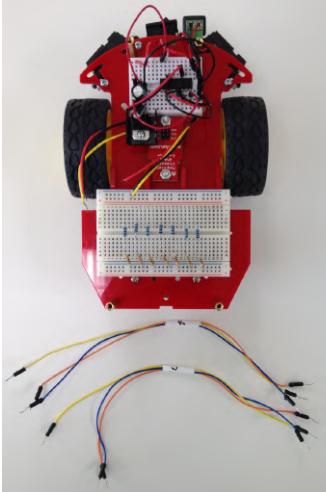
Connect H-Bridge GND (Pin 5) to battery GND

Connect H-Bridge Power – 2nd Black Wire



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Connect Motor Control Wires – Right Motor



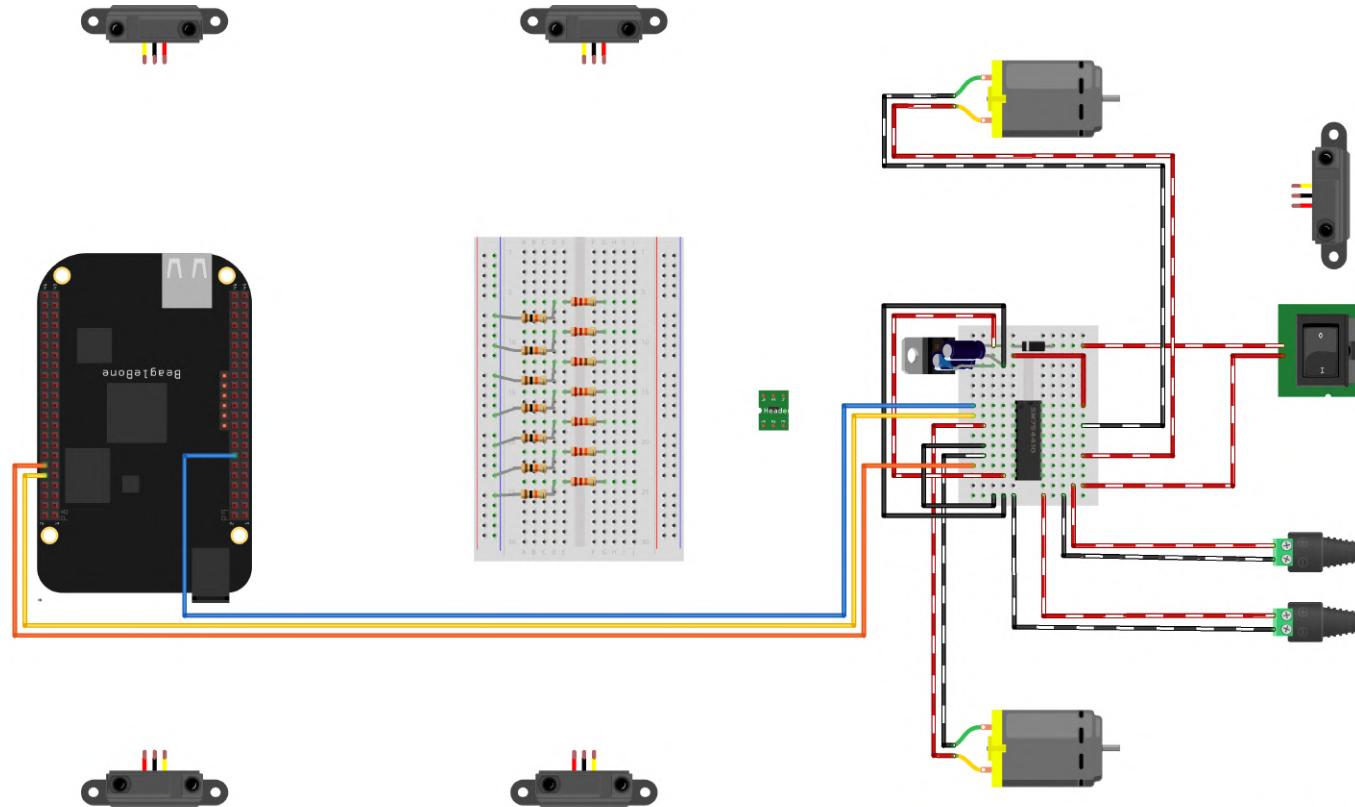
- Connect Blue Wire to H-Bridge 1,2EN (Pin 1)
- Connect Yellow Wire to H-Bridge 1A (Pin 2)
- Connect Orange Wire to H-Bridge 2A (Pin 7)

- Two Groups of Blue, Yellow, & Orange M/M Wires

Caution: Triple check that you have wired this connection correctly.

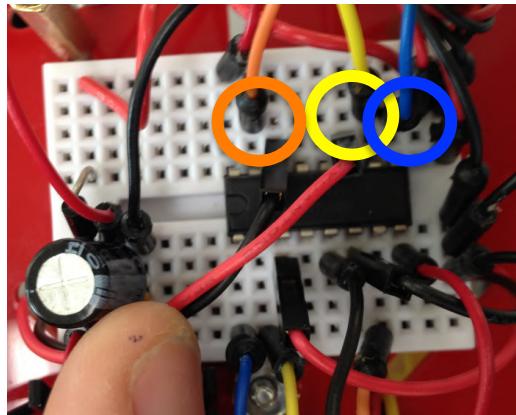
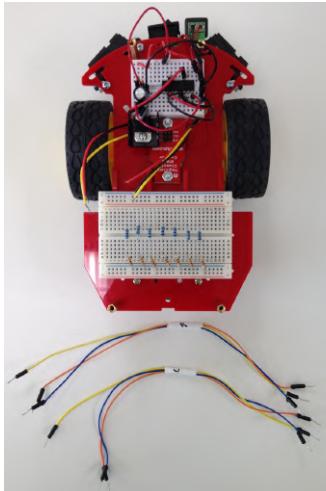
If this is wired incorrectly there is a good chance you will burn out your BeagleBone Black!

Connect Motor Control Wires – Right Motor



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Connect Motor Control Wires – Left Motor



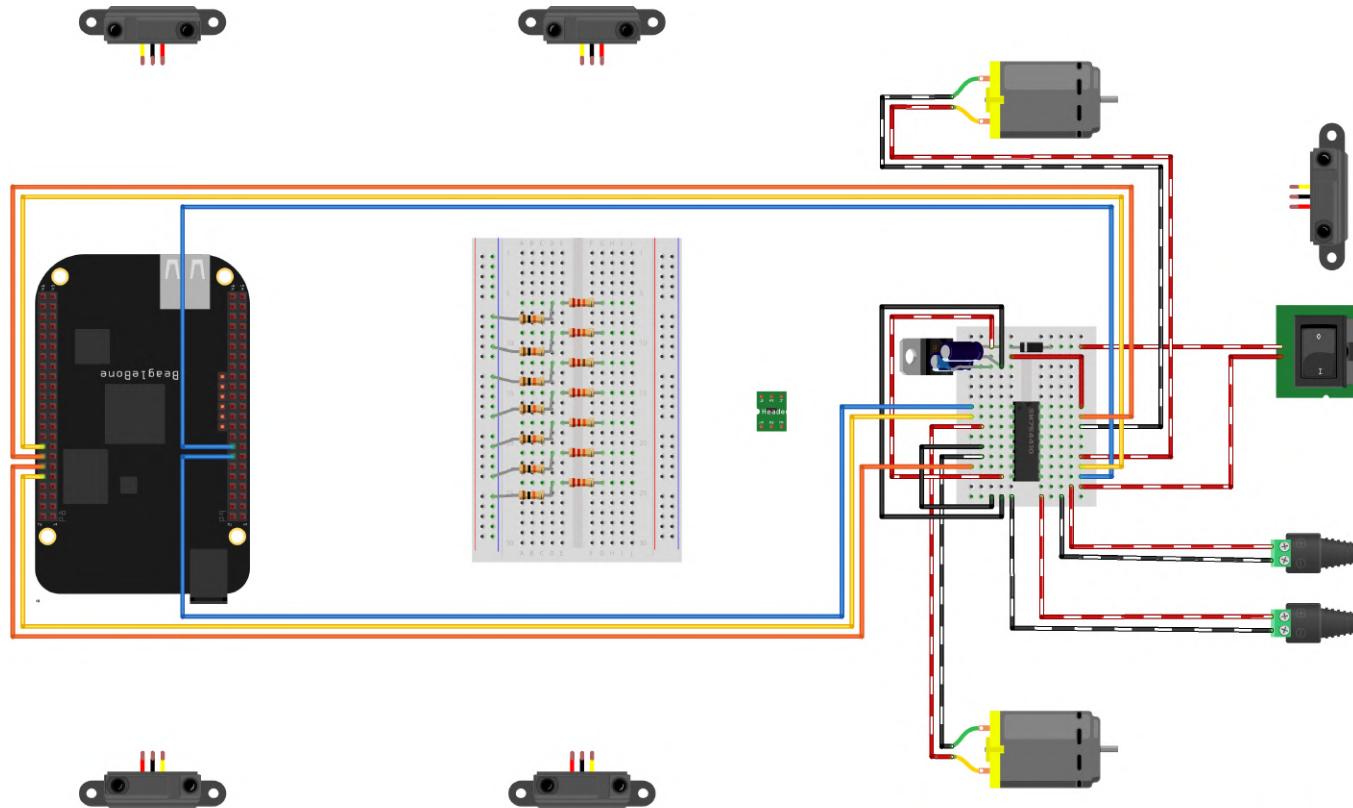
- Connect Blue Wire to H-Bridge 3,4EN (Pin 9)
- Connect Yellow Wire to H-Bridge 3A (Pin 10)
- Connect Orange Wire to H-Bridge 4A (Pin 15)

- Two Groups of Blue, Yellow, & Orange M/M Wires

Caution: Triple check that you have wired this connection correctly.

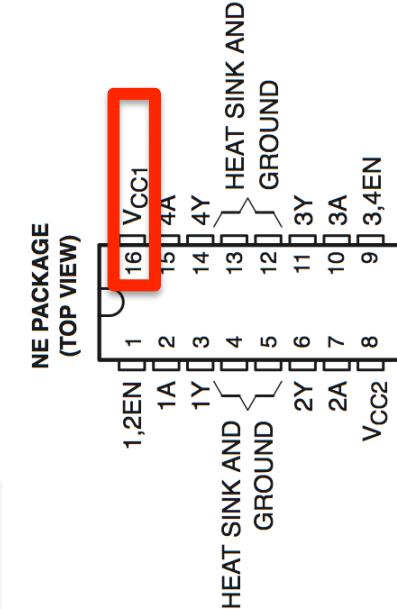
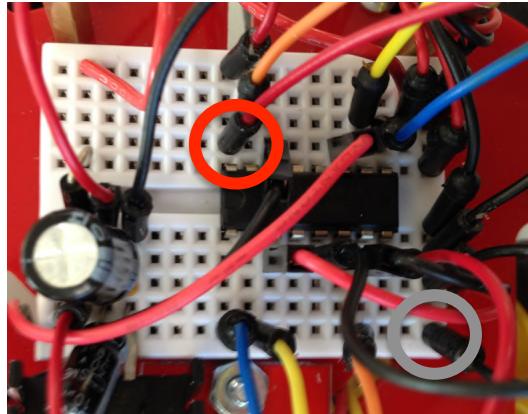
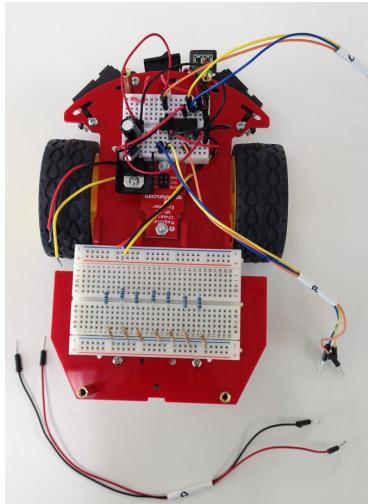
If this is wired incorrectly there is a good chance you will burn out your BeagleBone Black!

Connect Motor Control Wires – Left Motor



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Connect BBB Power

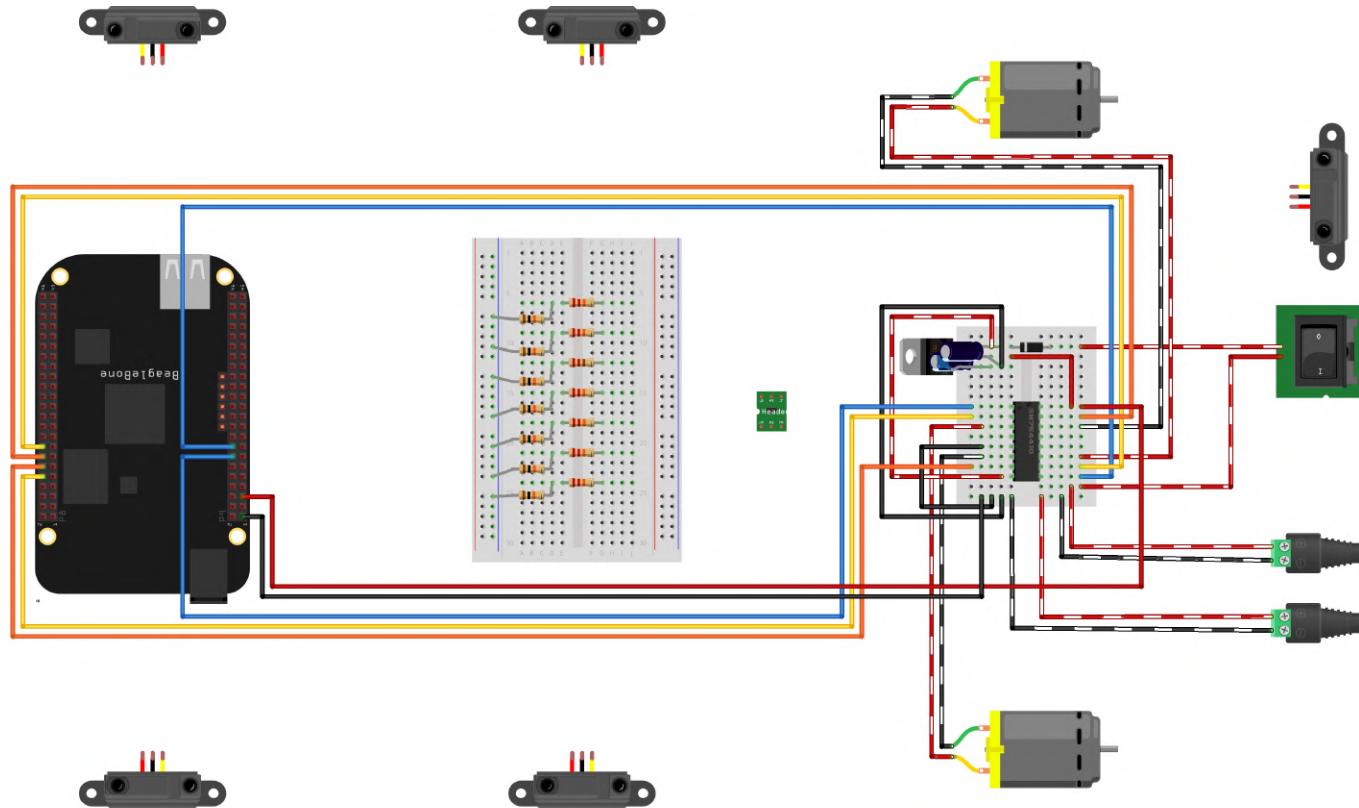


- One Group of Red & Black M/M Wires

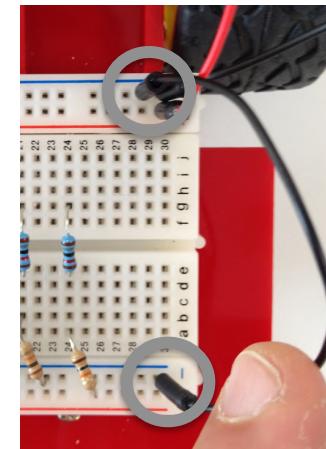
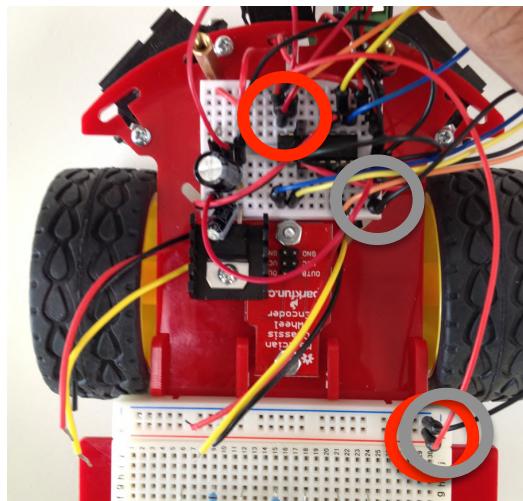
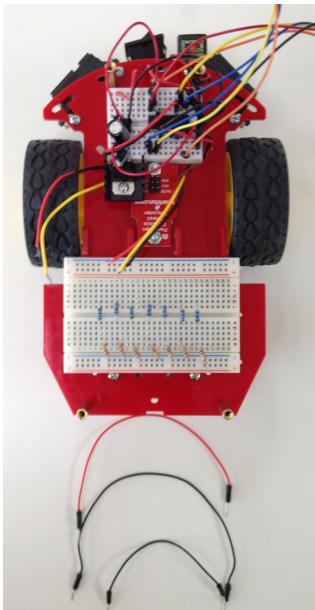
- Connect Red Wire to H-Bridge Vcc1 (Pin 16)
- Connect Black Wire to battery GND

Caution: Triple check that you have wired this connection correctly.
If this is wired incorrectly there is a good chance you will burn out your BeagleBone Black!

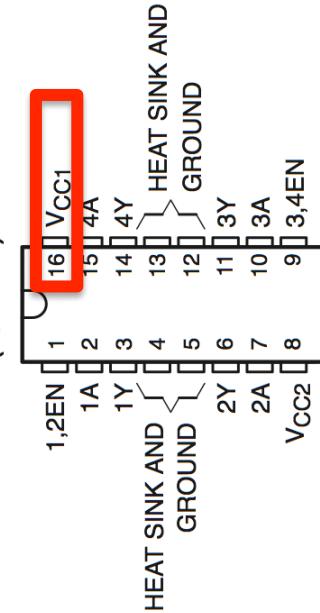
Connect BBB Power



Connect Big Breadboard Power

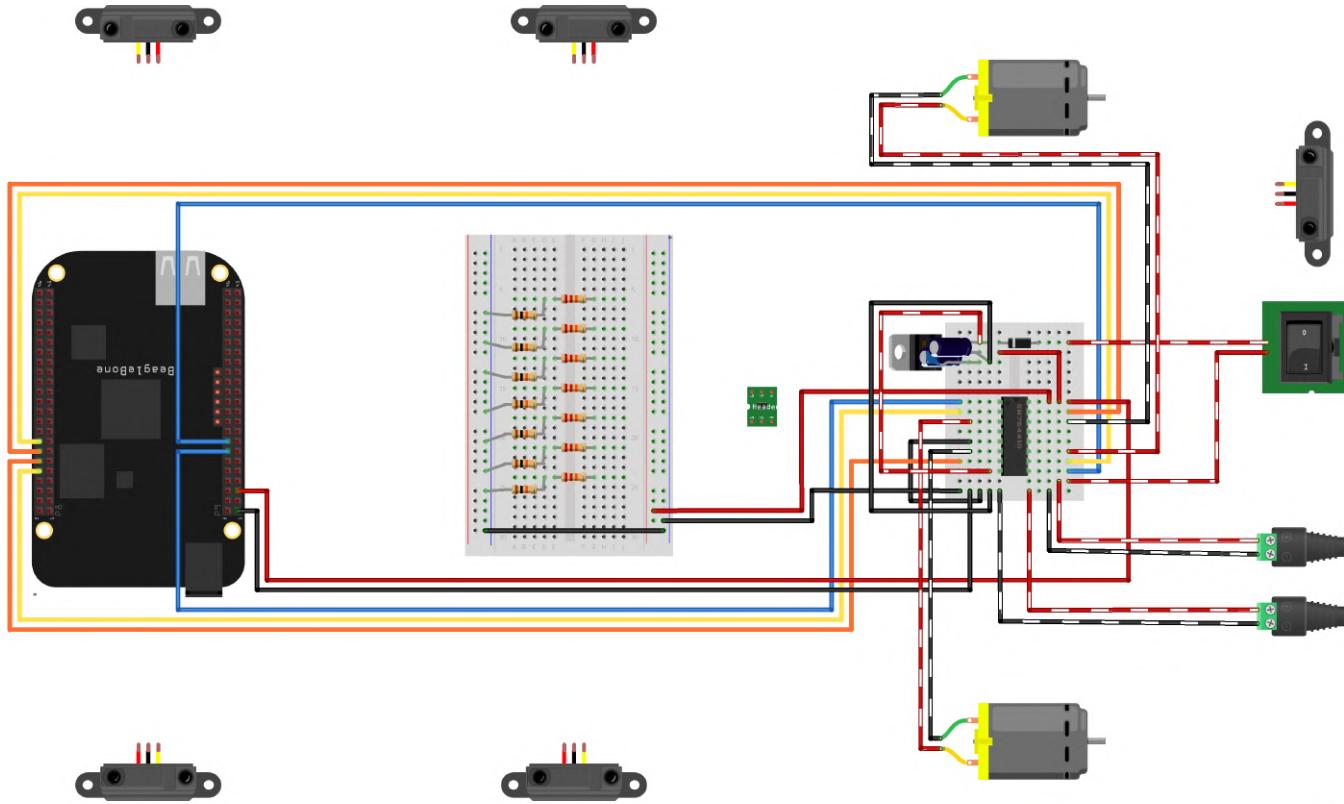


NE PACKAGE
(TOP VIEW)



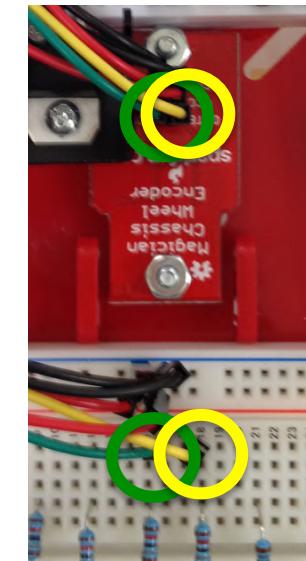
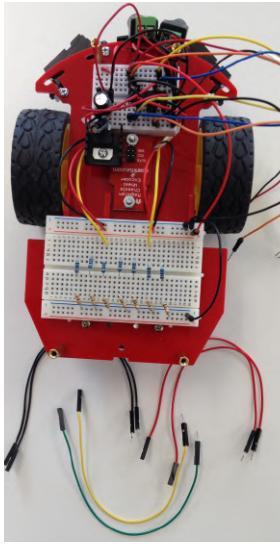
- One Red M/M Wires
- Two Black M/M Wires
- Connect Red Wire to H-Bridge Vcc1 (Pin 16)
- Connect Black Wire to battery GND
- Connect Black Wire to GND rails on breadboard

Connect Big Breadboard Power



fritzing

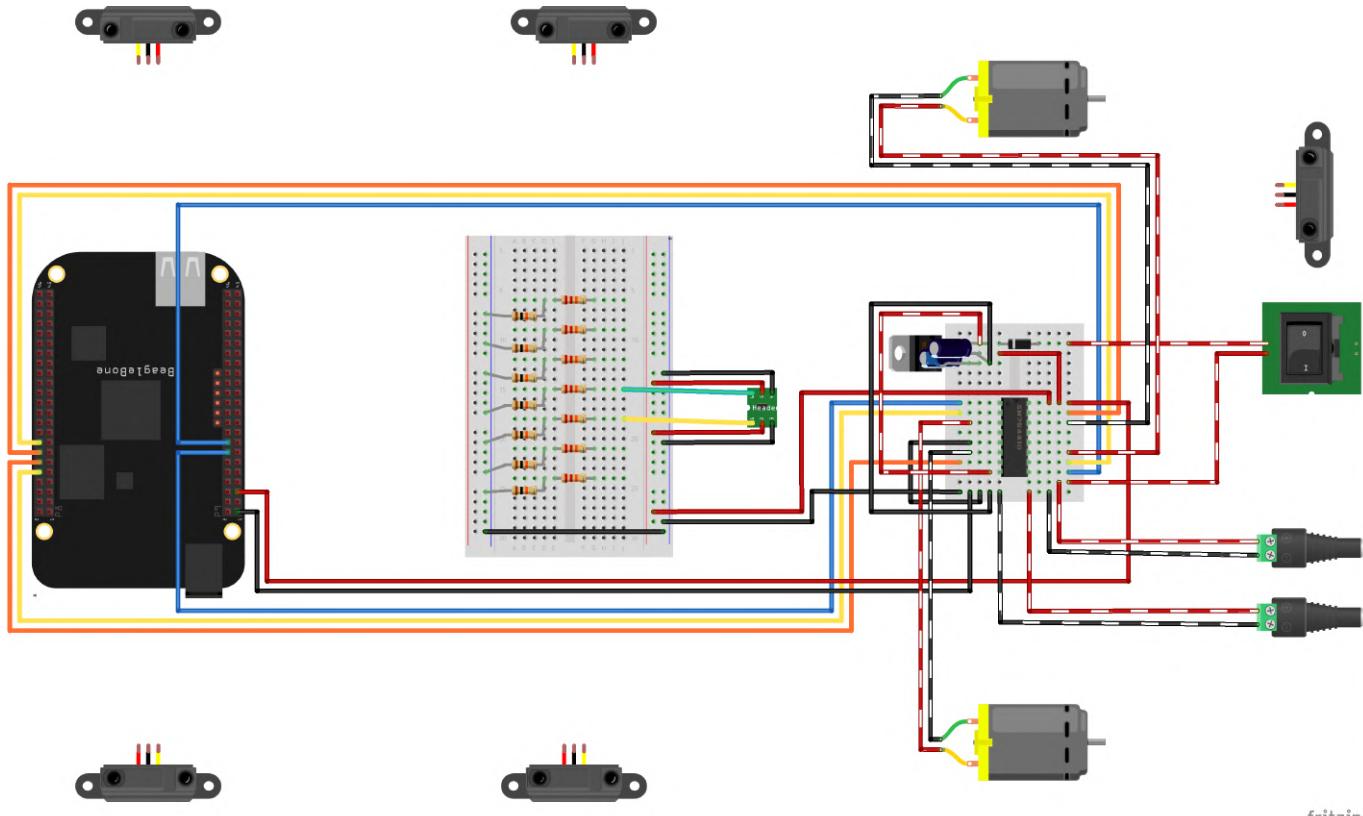
Connect Encoder



- Two Black M/M Wires
- Two Red M/F Wires
- One Green M/F Wire
- One Yellow M/F Wire

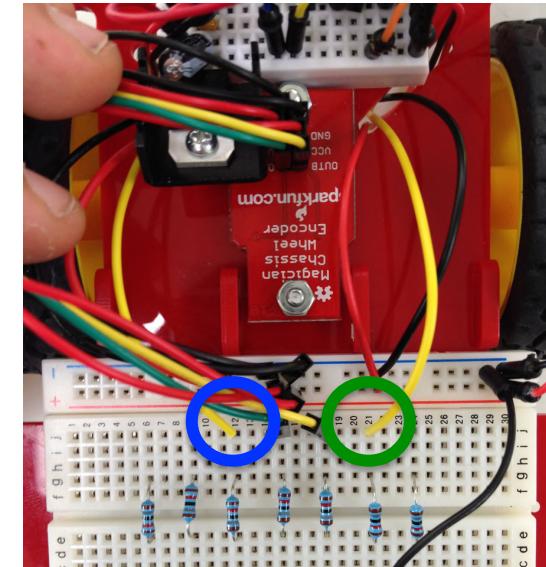
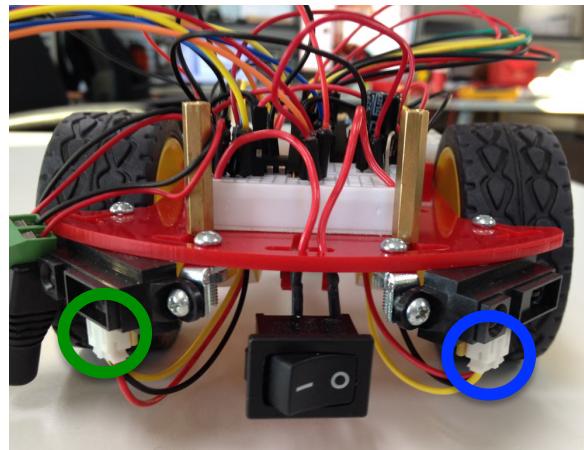
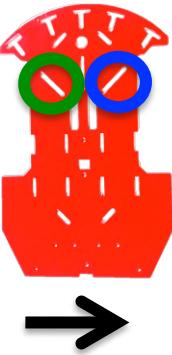
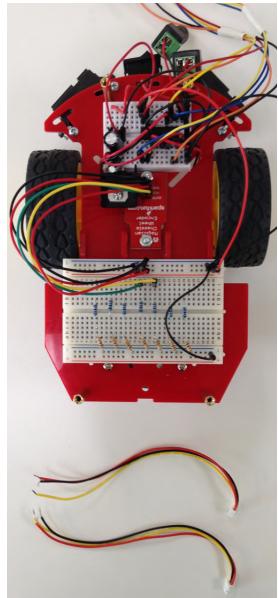
- Connect Black Wires to Encoder GND and GND rail
- Connect Red Wires to EncoderVCC and VCC rail
- Connect Green Wire to Left Encoder OUT and breadboard row 15
- Connect Yellow Wire to Right Encoder OUT and breadboard row 18

Connect Encoder



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Connect Front Lower IR Sensors

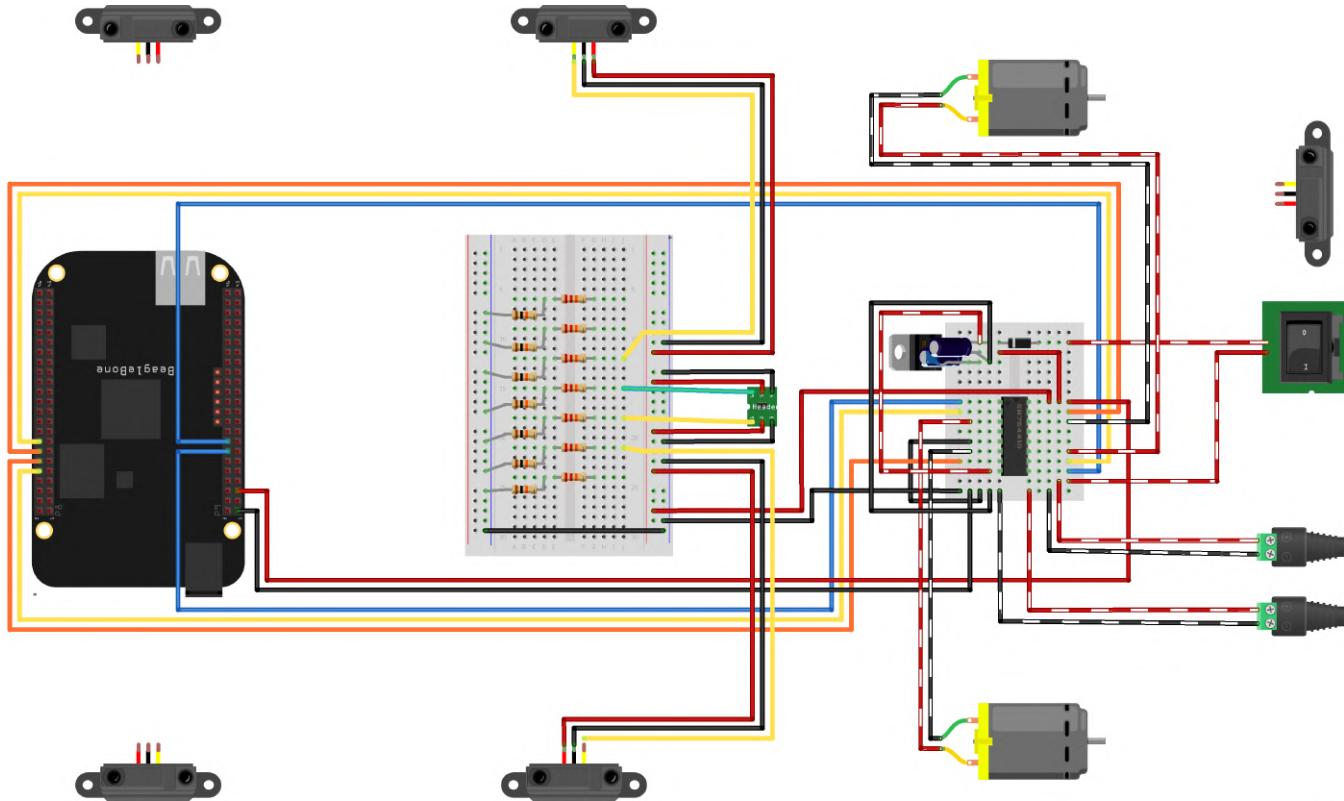


Route wires up through chassis

- Two JST 3-Wire Jumper

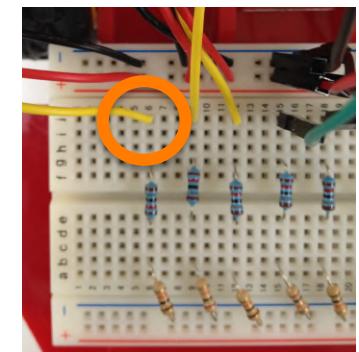
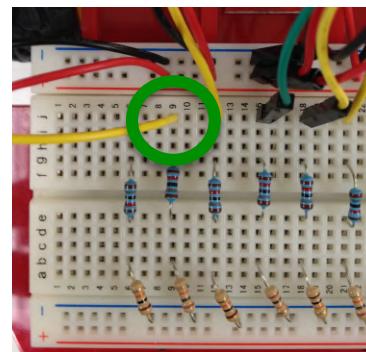
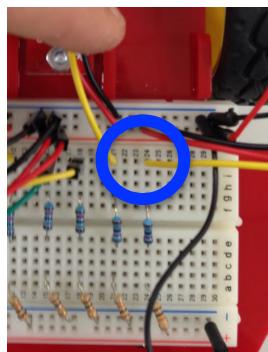
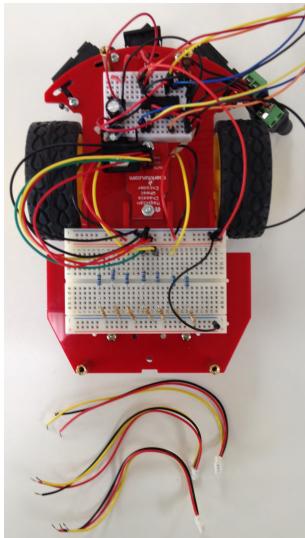
- Connect Black Wires to GND rail
- Connect Red Wires to VCC rail
- Connect Left IR Signal Wire to breadboard row 12
- Connect Right IR Signal Wire and breadboard row 21

Connect Front Lower IR Sensors



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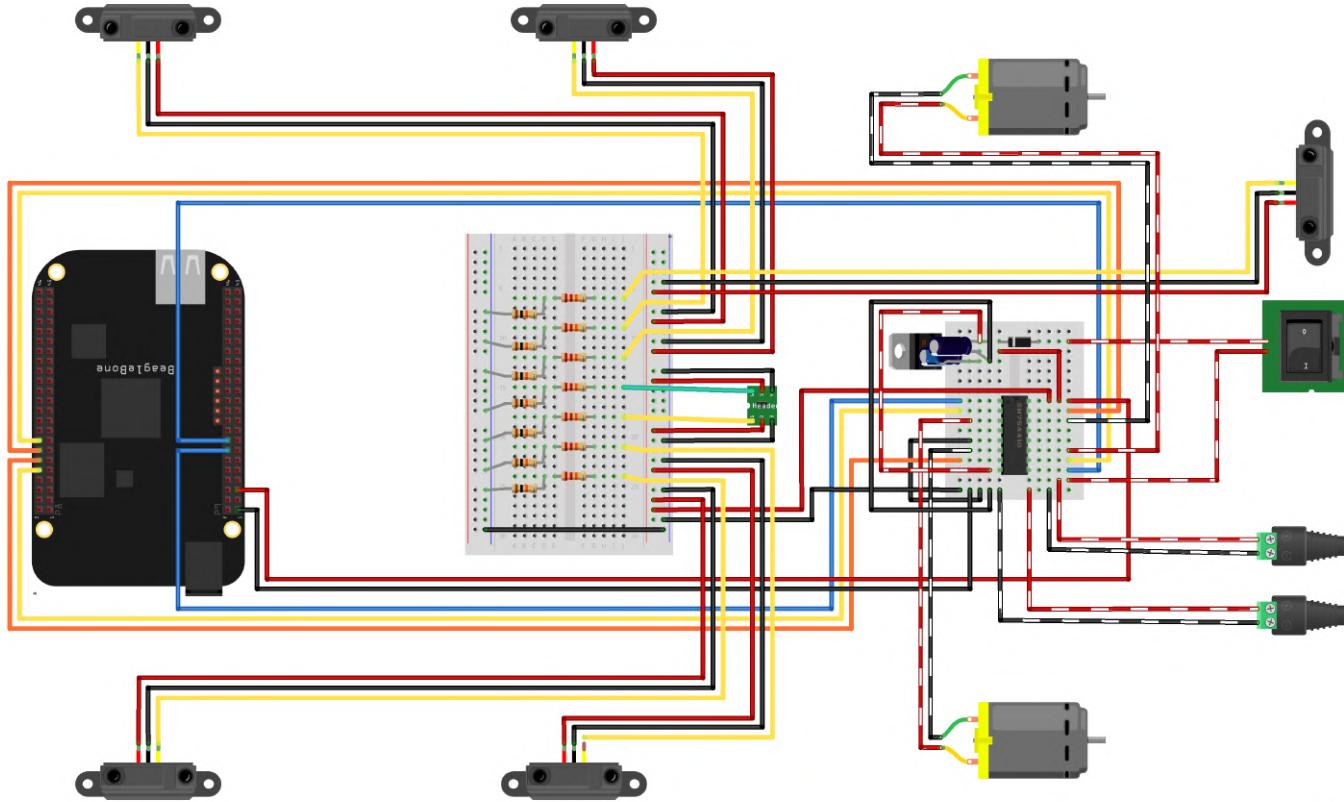
Connect Upper IR Sensors



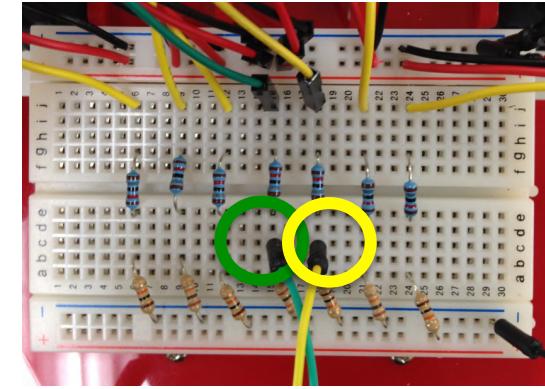
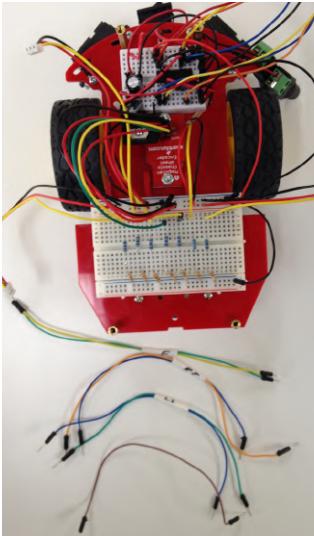
- Three JST 3-Wire Jumper

- Connect Black & Red Wires to rails
- Connect Signal Wire to breadboard row 24
- Connect Signal Wire to breadboard row 9
- Connect Signal Wire to breadboard row 6

Connect Upper IR Sensors



Connect ADC to BBB - Encoders

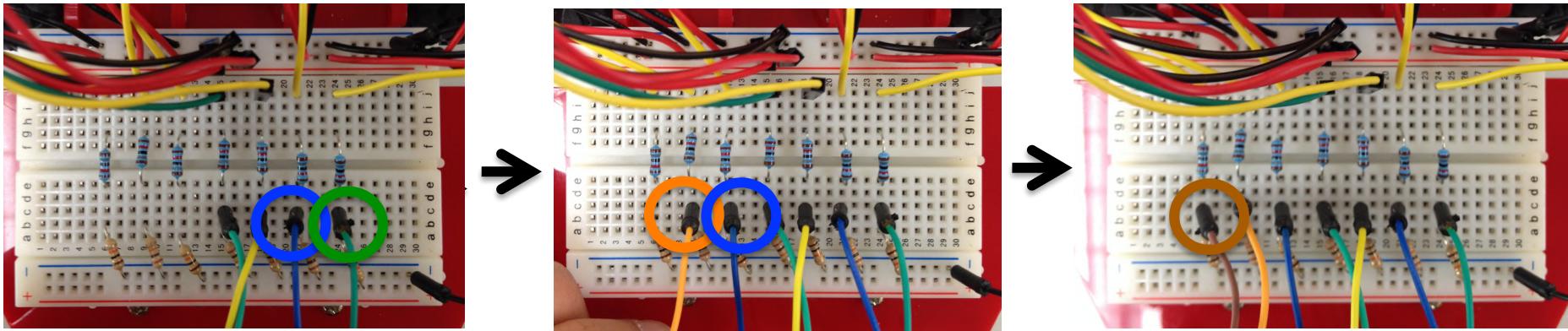


- One Group of **Green & Yellow** M/M Wires
- One Group of **Blue & Green** M/M Wires
- One Group of **Orange & Blue** M/M Wires
- One **Brown** M/M Wire

From Green & Yellow Group:

- Connect **Green** Wire to **breadboard row 15**
- Connect **Yellow** Wire to **breadboard row 18**

Connect ADC to BBB – Infrared Sensors



From Blue & Green Group:

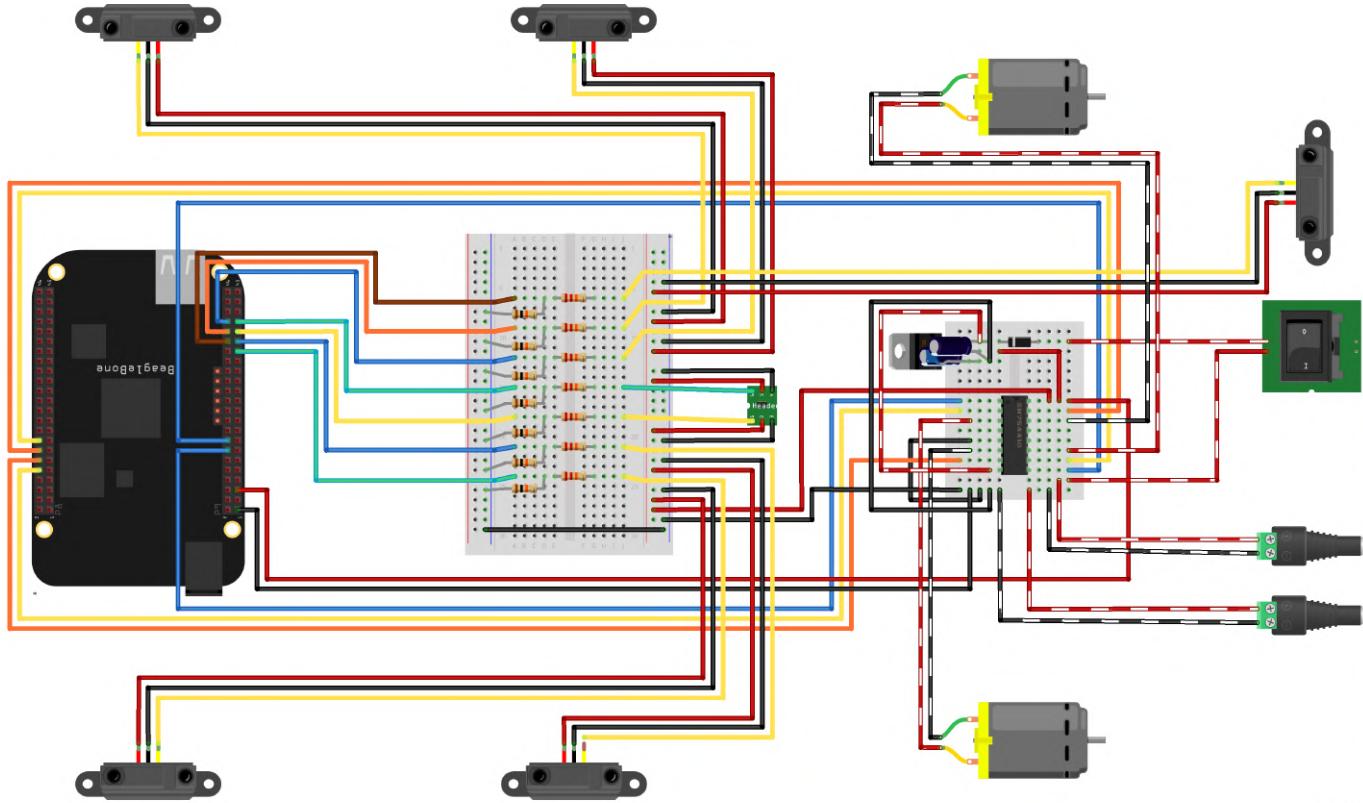
- Connect **Blue Wire** to **breadboard row 21**
- Connect **Green Wire** to **breadboard row 24**

- Connect **Brown Wire** to **breadboard row 6**

From Orange & Blue Group:

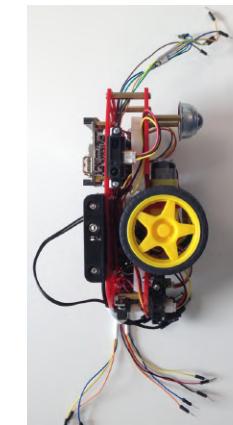
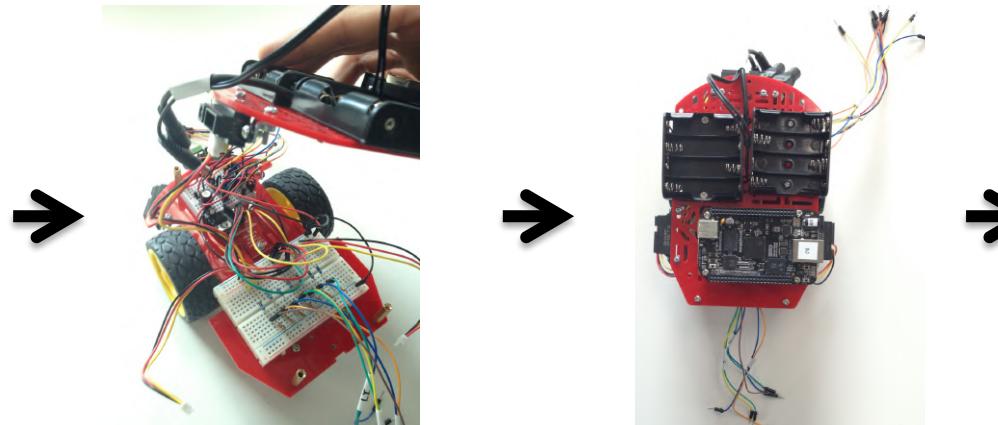
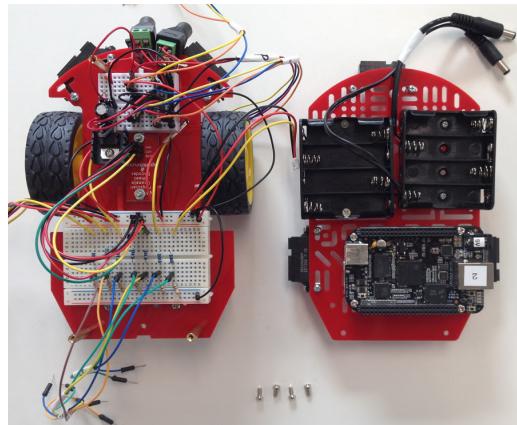
- Connect **Orange Wire** to **breadboard row 9**
- Connect **Blue Wire** to **breadboard row 12**

QuickBot Wiring



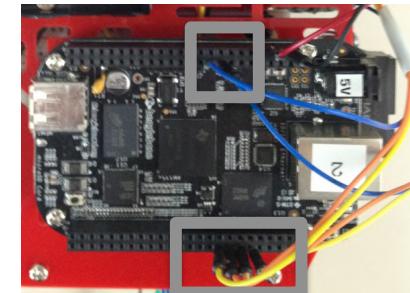
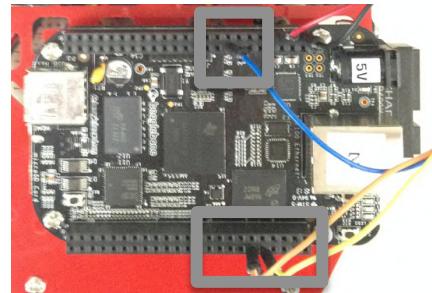
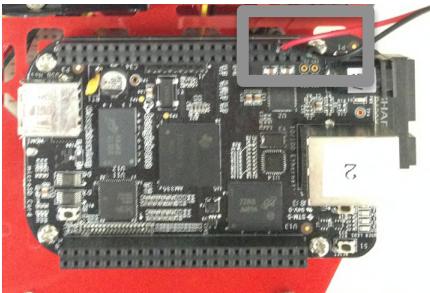
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Add Top Plate



- Four M3*6 Screws
 - 1. Attach JST wire to front IR sensor
 - 2. Attach top plate
 - 3. Attach JST wires to side IR sensors

Wire BBB

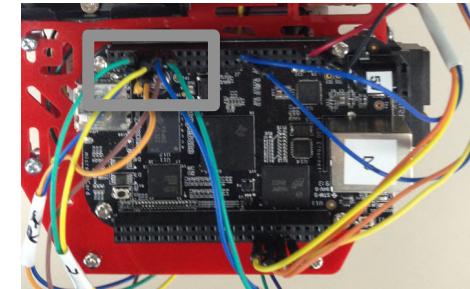
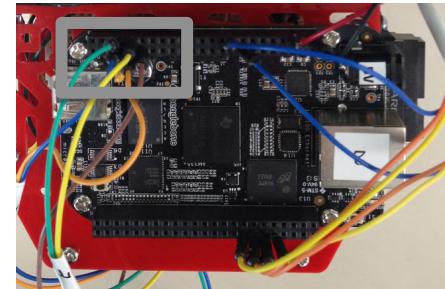
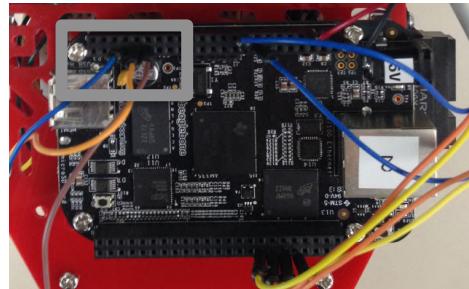
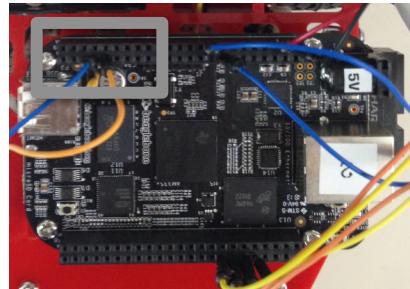


- Connect 5V to BBB 5V_Raw (Pin P9_05)
- Connect GND to BBB GND (Pin P9_01)

- Connect Right Motor Blue to BBB GPIO_51(Pin P9_14)
- Connect Right Motor Yellow to BBB GPIO_68 (Pin P8_10)
- Connect Right Motor Orange to BBB GPIO_44 (Pin P8_12)

- Connect Left Motor Blue to BBB GPIO_05(Pin P9_16)
- Connect Left Motor Yellow to BBB GPIO_46 (Pin P8_16)
- Connect Left Motor Orange to BBB GPIO_26 (Pin P8_14)

Wire BBB



- Connect Left IR Blue to BBB Ain_1 (Pin P9_40)
- Connect Left IR Orange to BBB Ain_3 (Pin P9_38)



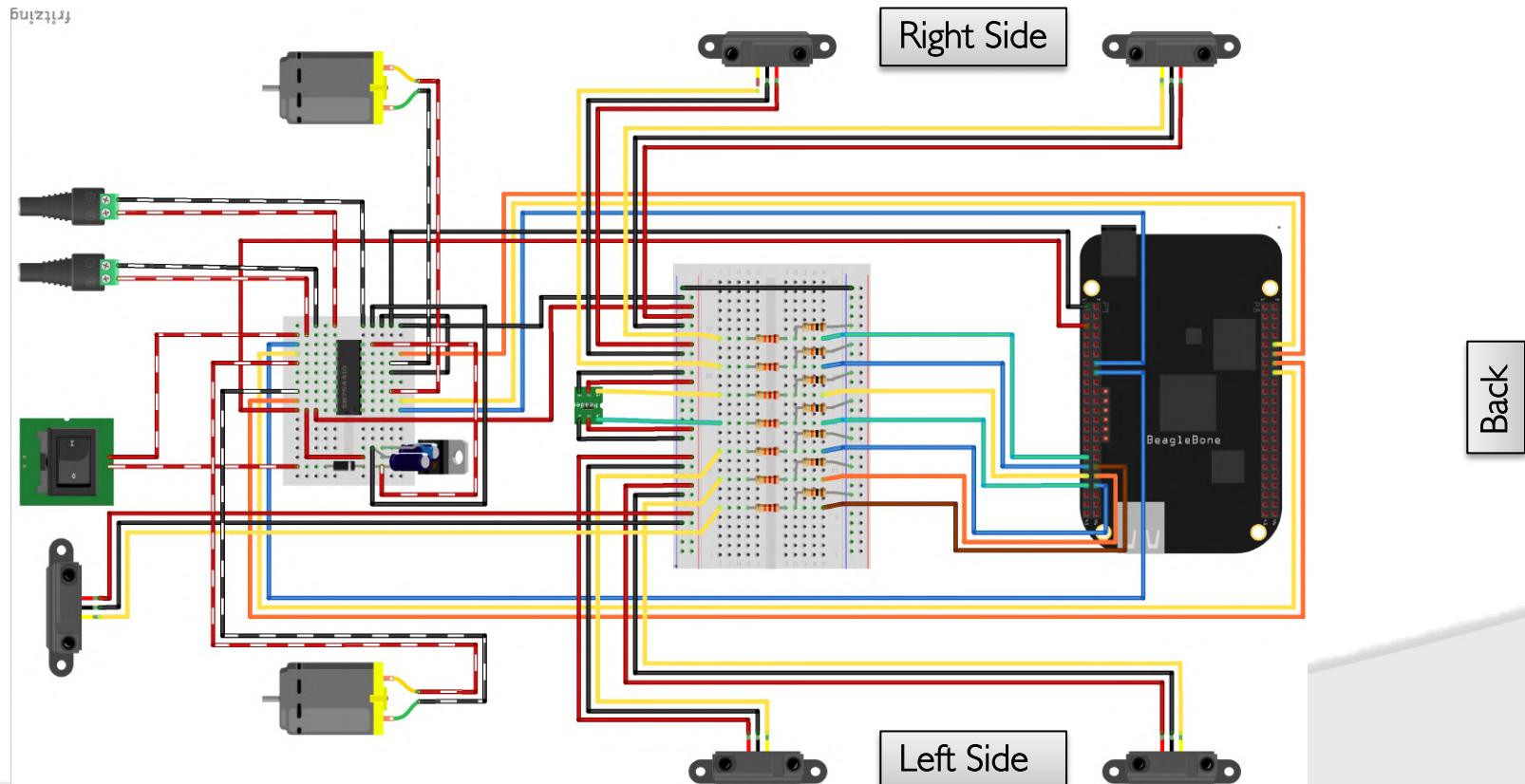
- Connect Encoder Green to BBB Ain_0 (Pin P9_39)
- Connect Encoder Yellow to BBB Ain_2 (Pin P9_37)

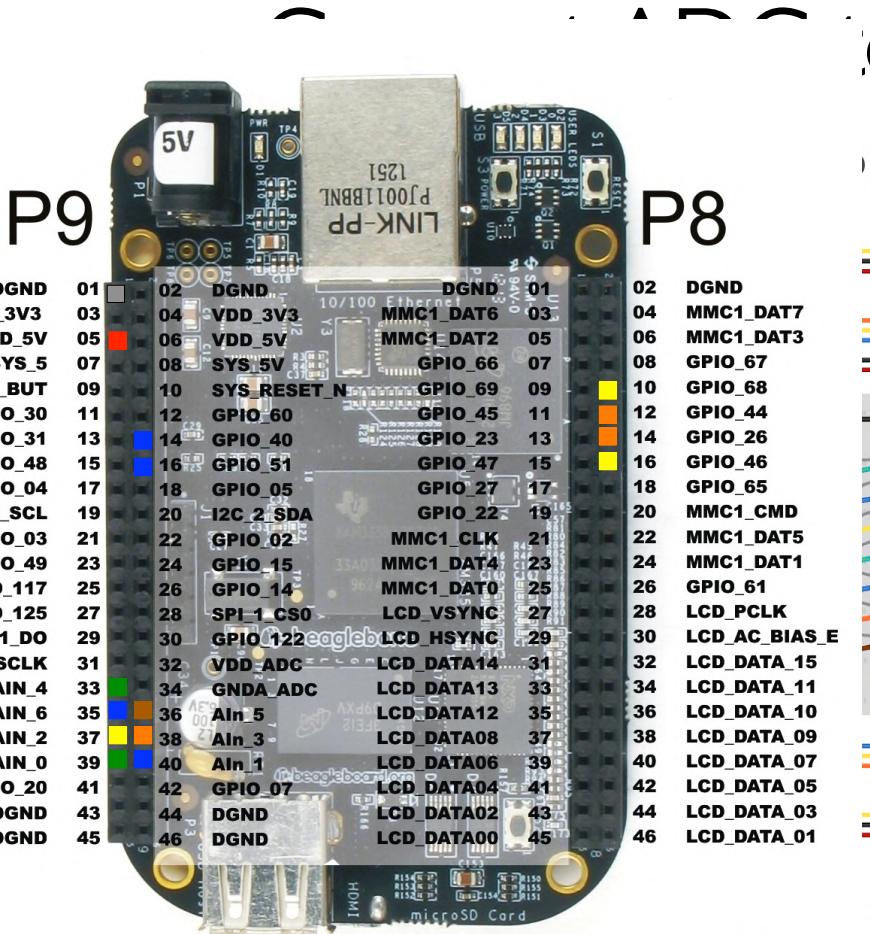
- Connect Front IR Brown to BBB Ain_5 (Pin P9_36)



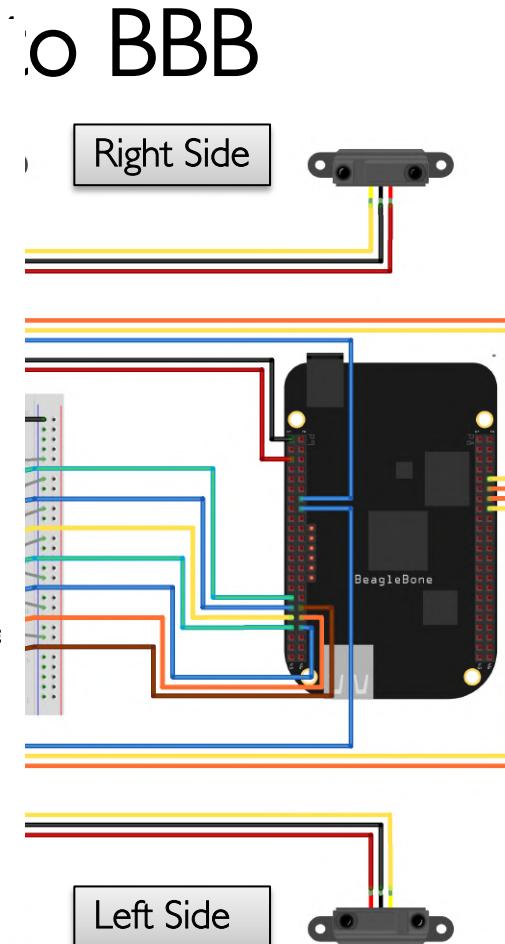
- Connect Right IR Blue to BBB Ain_6 (Pin P9_35)
- Connect Right IR Green to BBB Ain_4 (Pin P9_33)

Connect ADC to BBB

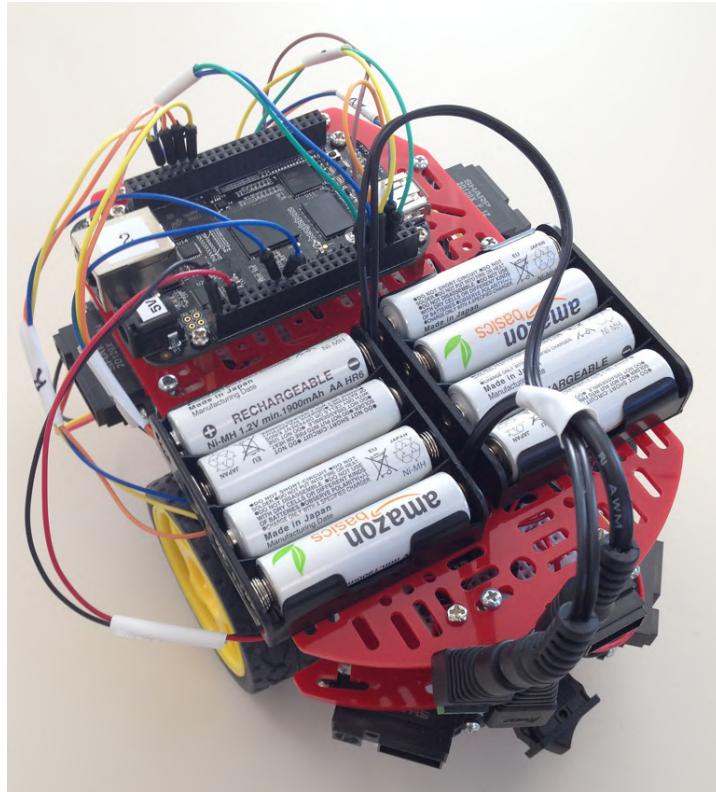




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Install Batteries & Connect DC Plugs



Optionally: Power QuickBot From Wall

- 1st DC Barrel Plug Connector: Cut barrel plug and connect ends
- 2nd DC Barrel Plug Connector: Use DC Power Supply with output 9-12V, \geq 1Amp



CAUTION: DON'T USE WITH BATTERIES INSTALLED!!!

Learn From My Mistakes

Ways I killed some BeagleBone Blacks:

1. Mixed up 5V and battery voltage wiring
2. Plugged BBB GPIO wire into motor breadboard hole
3. Set BBB down on a screw while it was powered on
4. Loosened brass standoff and the BBB touched it while it was powered on

