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from random import seed
from random import random
from math import exp
import matplotlib.pyplot as plt
import numpy as np

def initialize_network(n_inputs, n_hidden, n_outputs):
    network = list()
    hidden_layer = [{'weights':[0.1, 0.2, 0.3]}, {'weights':[0.1, 0.2, 0.3]}]
    network.append(hidden_layer)
    output_layer = [{'weights':[0.2, 0.1, 0.5]}, {'weights':[0.2, 0.1, 0.4]}]
    network.append(output_layer)
    return network

def activate(weights, inputs):
    activation = weights[-1]
    for i in range(len(weights)-1):
        activation += weights[i] * inputs[i]
    return activation

def transfer(activation):
    return (exp(activation) - exp(-activation)) / (exp(activation) + exp(-activation))

def forward_propagate(network, row):
    inputs = row
    for layer in network:
        new_inputs = []
        for neuron in layer:
            activation = activate(neuron['weights'], inputs)
            neuron['output'] = transfer(activation)
            new_inputs.append(neuron['output'])
        inputs = new_inputs
    return inputs

def transfer_derivative(output):
    return (1.0 - output ** 2)

def backward_propagate_error(network, expected):
    for i in reversed(range(len(network))):
        layer = network[i]
        errors = list()
        if i != len(network)-1:
            for j in range(len(layer)):
                error = 0.0
                for neuron in network[i + 1]:
                    error += (neuron['weights'][j] * neuron['delta'])
                errors.append(error)
        else:
            for j in range(len(layer)):
                neuron = layer[j]
                errors.append(neuron['output'] - expected)
            for j in range(len(layer)):
                neuron = layer[j]
                neuron['delta'] = errors[j]
            for j in range(len(layer)):
                neuron = layer[j]
                for i in range(len(neuron['weights'])):
                    neuron['weights'][i] += neuron['output'] * neuron['delta'] * neuron['weights'][i]

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        neuron = layer[j]
        errors.append(expected[j] - neuron['output'])
    for j in range(len(layer)):
        neuron = layer[j]
        neuron['delta'] = errors[j] * transfer_derivative(neuron['output'])

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def update_weights(network, row, l_rate):
    for i in range(len(network)):
        inputs = row[:-1]
        if i != 0:
            inputs = [neuron['output'] for neuron in network[i - 1]]
        for neuron in network[i]:
            for j in range(len(inputs)):
                neuron['weights'][j] += l_rate * neuron['delta'] * inputs[j]
            neuron['weights'][-1] += l_rate * neuron['delta']

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def train_network(network, train, l_rate, n_epoch, n_outputs):
    for epoch in range(n_epoch):
        sum_error = 0
        if(epoch > 50000):
            l_rate = 1/epoch * 100
        for row in train:
            outputs = forward_propagate(network, row)
            expected = [0 for i in range(n_outputs)]
            expected[int(row[-1])] = 1
            sum_error += sum([(expected[i]-outputs[i])**2 for i in range(len(expected))])
            backward_propagate_error(network, expected)
            update_weights(network, row, l_rate)
        if(epoch % 100 == 0):
            print('>epoch=%d, lrate=%.3f, error=%.3f' % (epoch, l_rate, sum_error))

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def predict(network, row):
    outputs = forward_propagate(network, row)
    return outputs.index(max(outputs))

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#As no dataset was given, I took a data set from previous assignment and trained the nuera

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w1 = np.array([[2, 2, 0], [-1, 2, 0], [1, 3, 0], [-1, -1, 0], [0.5, 0.5, 0]])
w2 = np.array([[1, -3, 1], [0, -1, 1], [1, -2, 1], [-1, -2, 1], [0, -2, 1]])
dataset = np.concatenate([w1, w2], axis = 0)
w1 = np.array([[2, 2], [-1, 2], [1, 3], [-1, -1], [0.5, 0.5]])
w2 = np.array([[1, -3], [0, -1], [1, -2], [-1, -2], [0, -2]])
f, ax = plt.subplots(figsize=(7, 7))
c1, c2, c3 = 'b', 'r', 'm'

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ax.scatter(*w1.T, c=c1, s = 10, label = "w1")
ax.legend()
ax.scatter(*w2.T, c=c2, s = 10, label = "w2")
ax.legend()

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n_inputs = len(dataset[0]) - 1
n_outputs = len(set([row[-1] for row in dataset]))
network = initialize_network(n_inputs, 1, n_outputs)

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print(network)
train_network(network, dataset, 0.1, 1000, n_outputs)
print(network)
x = np.arange(-3.5, 3.5, 0.1)
y = np.arange(-3.5, 3.5, 0.1)
print(predict(network, [0.1, 0.2]))
for layer in network:
    print(layer)

for i in range(len(x)):
    for j in range(len(y)):
        pt = [x[i], y[j]]
        if(predict(network, pt) == 0):
            c = 'r'
        else:
            c = 'b'
        ax.scatter(x[i], y[j], c = c, s = 1)
```

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plt.show()
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[[{'weights': [0.1, 0.2, 0.3]}, {'weights': [0.1, 0.2, 0.3]}], [{'weights': [0.2, 0.1
>epoch=0, lrate=0.100, error=4.949
>epoch=100, lrate=0.100, error=0.322
>epoch=200, lrate=0.100, error=0.087
>epoch=300, lrate=0.100, error=0.050
>epoch=400, lrate=0.100, error=0.035
>epoch=500, lrate=0.100, error=0.022
>epoch=600, lrate=0.100, error=0.018
>epoch=700, lrate=0.100, error=0.015
>epoch=800, lrate=0.100, error=0.015
>epoch=900, lrate=0.100, error=0.013
[[{'weights': [-1.417457417419993, 1.6584789785868526, -0.1934273486840623], 'output'
0
[{'weights': [-1.417457417419993, 1.6584789785868526, -0.1934273486840623], 'output'
[{'weights': [0.48886806504695524, 1.0513478494222745, 1.517199509445146], 'output':

```

