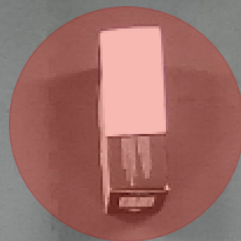


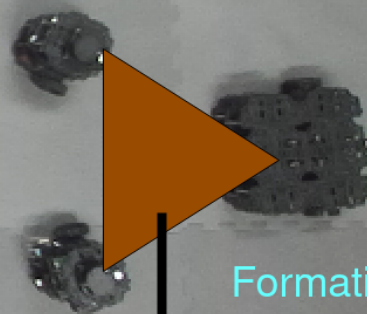
Obstacle



Obstacle

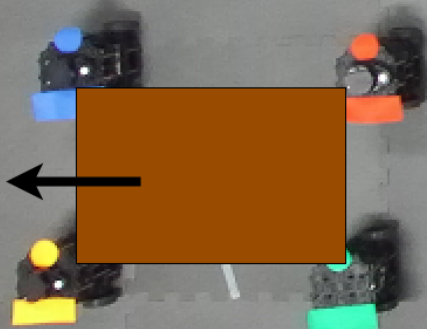
Goal F1

Goal F2

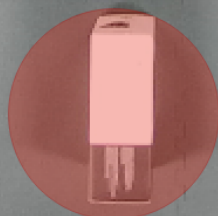


Formation F2

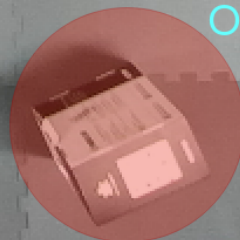
LOAD



Formation F1



Obstacle



Obstacle

LOAD