

Unit-4 Applications of Partial derivatives

Unit 4

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Objectives :- After studying this chapter, the learner will be able to :

- 1) know the concept of tangent plane and linearization.
- 2) Use the various properties of Jacobian transformation to evaluate required transformation.
- 3) Understand the different types of errors and find the required approximate error.
- 4) find the maximum and minimum values of the function of two variables.
- 5) Solve problems of Lagranges method of undetermined multipliers.

Defn: If u, v are functions of independent variables x, y , i.e. $u = f_1(x, y)$ $v = f_2(x, y)$ then the Jacobian J is defined as

$$J = \frac{\partial(u, v)}{\partial(x, y)} = \begin{vmatrix} \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{vmatrix} = \begin{vmatrix} u_x & u_y \\ v_x & v_y \end{vmatrix}$$

If u, v, w are functions of independent variables x, y, z then the Jacobian J is defined as

$$J = \frac{\partial(u, v, w)}{\partial(x, y, z)} = \begin{vmatrix} \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} & \frac{\partial u}{\partial z} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} & \frac{\partial v}{\partial z} \\ \frac{\partial w}{\partial x} & \frac{\partial w}{\partial y} & \frac{\partial w}{\partial z} \end{vmatrix}$$

* If $u = x^2 - y^2$ and $v = 2xy$ find $\frac{\partial(u, v)}{\partial(x, y)} \rightarrow \begin{vmatrix} u_x & u_y \\ v_x & v_y \end{vmatrix}$

$$\begin{vmatrix} 2x & -2y \\ 2y & 2x \end{vmatrix} \quad u_x + v_y = 4(x^2 + y^2)$$

Properties of determinants.

1) If a row or column of a determinant consist of all zeros then the value of determinant is zero.

2) If any two rows or columns of a determinant are identical, then its value is zero.

3) If any two rows and columns of a determinant are proportional then its value is zero.

$$4) \begin{vmatrix} a & b & c \\ kx & ky & kz \\ p & q & r \end{vmatrix} = K \begin{vmatrix} a & b & c \\ x & y & z \\ p & q & r \end{vmatrix}$$

$$5) \begin{vmatrix} 1 & 1 & 1 \\ x & y & z \\ x^2 & y^2 & z^2 \end{vmatrix} = (x-y)(y-z)(z-x)$$

Ex:- If $u = x(1-y)$ and $v = xy$ then find $\frac{\partial(u, v)}{\partial(x, y)}$.

Sol:- Given that $u = x(1-y)$ and $v = xy$

$$\therefore u = x - xy = x - v$$

$$\therefore x = u + v$$

$$\text{and } v = xy \Rightarrow v = (u+v)y$$

$$\Rightarrow y = \frac{v}{u+v}$$

$$\therefore x = u + v \longrightarrow (1)$$

$$\therefore y = \frac{v}{u+v} \longrightarrow (2)$$

$$\frac{\partial u}{\partial u} = 1, \quad \frac{\partial x}{\partial v} = 1, \quad \frac{\partial y}{\partial u} = v \left(\frac{-1}{(u+v)^2} \right) = \frac{-v}{(u+v)^2}$$

$$\frac{\partial y}{\partial v} = \frac{(u+v)(1) - v(1)}{(u+v)^2} = \frac{u}{(u+v)^2}$$

We have

$$J = \frac{\partial(x, y)}{\partial(u, v)} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix}$$

$$= \begin{vmatrix} 1 & 1 \\ \frac{-v}{(u+v)^2} & \frac{u}{(u+v)^2} \end{vmatrix} = \frac{u}{(u+v)^2} + \frac{v}{(u+v)^2} \\ = \frac{u+v}{(u+v)^2} = \frac{1}{u+v}$$

* Ex: If $uv = yz$ and $vy = zx$, $wz = xy$ find $\frac{\partial(u, v, w)}{\partial(x, y, z)}$ 2010

Sol:- We have

$$u = \frac{yz}{x}, \quad v = \frac{zx}{y}, \quad w = \frac{xy}{z}$$

$$\frac{\partial u}{\partial x} = -\frac{yz}{x^2}, \quad \frac{\partial u}{\partial y} = \frac{z}{x}, \quad \frac{\partial u}{\partial z} = \frac{y}{x},$$

$$\frac{\partial v}{\partial x} = \frac{z}{y}, \quad \frac{\partial v}{\partial y} = -\frac{zx}{y^2}, \quad \frac{\partial v}{\partial z} = \frac{x}{y},$$

$$\frac{\partial w}{\partial x} = \frac{y}{z}, \quad \frac{\partial w}{\partial y} = \frac{x}{z}, \quad \frac{\partial w}{\partial z} = -\frac{xy}{z^2}$$

Now,

$$J = \frac{\partial(u, v, w)}{\partial(x, y, z)} = \begin{vmatrix} \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} & \frac{\partial u}{\partial z} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} & \frac{\partial v}{\partial z} \\ \frac{\partial w}{\partial x} & \frac{\partial w}{\partial y} & \frac{\partial w}{\partial z} \end{vmatrix}$$

$$\begin{aligned}
 &= \begin{vmatrix} -yz & z & y \\ z & -zx & x \\ y & z & -xy \end{vmatrix} = -\frac{yz}{x^2} \left[\left(\frac{-zx}{y^2} \right) \left(\frac{-xy}{z^2} \right) - \left(\frac{x}{y} \right) \left(\frac{x}{z} \right) \right] \\
 &\quad - \frac{z}{x} \left[\frac{z}{y} \left(\frac{-xy}{z^2} \right) - \left(\frac{x}{y} \right) \left(\frac{y}{z} \right) \right] \\
 &\quad + \frac{y}{x} \left[\left(\frac{z}{y} \right) \left(\frac{x}{z} \right) - \left(-\frac{zx}{y^2} \right) \left(\frac{y}{z} \right) \right] \\
 &= -\frac{yz}{x^2} \left[\frac{-x^2y}{y^2z^2} - \frac{x^2}{yz^2} \right] - \frac{z}{x} \left[\frac{-xy^2}{yz^2} - \frac{xy}{y^2z} \right] + \frac{y}{x} \left[\frac{zx}{yz} + \frac{zx}{y^2z} \right] \\
 &= -\frac{yz}{x^2} \left[\frac{y^2}{y^2z^2} - \frac{x^2}{yz^2} \right] - \frac{z}{x} \left[-\frac{x}{z} - \frac{x}{z} \right] + \frac{y}{x} \left[\frac{x}{y} + \frac{x}{y} \right] \\
 &= 0 - \frac{z}{x} \left[-2 \frac{x}{z} \right] + \frac{y}{x} \left[2 \frac{x}{y} \right] = 2 + 2 = 4
 \end{aligned}$$

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Ex:- Given spherical polar co-ordinates,

$$\begin{aligned}
 x &= r \sin \theta \cos \phi \\
 y &= r \sin \theta \sin \phi \\
 z &= r \cos \theta
 \end{aligned} \quad \left. \right\} \quad (1)$$

Show that $\frac{\partial(x, y, z)}{\partial(r, \theta, \phi)} = r^2 \sin \theta$

$$\begin{aligned}
 \text{Ans' } & \text{ Given } x = r \sin \theta \cos \phi \\
 & y = r \sin \theta \sin \phi \\
 & z = r \cos \theta
 \end{aligned}$$

from eqn (1) we have

$$\begin{aligned}
 J &= \frac{\partial(x, y, z)}{\partial(r, \theta, \phi)} = \begin{vmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} & \frac{\partial x}{\partial \phi} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta} & \frac{\partial y}{\partial \phi} \\ \frac{\partial z}{\partial r} & \frac{\partial z}{\partial \theta} & \frac{\partial z}{\partial \phi} \end{vmatrix} \\
 &= \begin{vmatrix} \sin \theta \cos \phi & r \cos \theta \cos \phi & -r \sin \theta \sin \phi \\ \sin \theta \sin \phi & r \cos \theta \sin \phi & r \sin \theta \cos \phi \\ \cos \theta & -r \sin \theta & 0 \end{vmatrix} \\
 &= r^2 \sin \theta \begin{vmatrix} \sin \theta \cos \phi & \cos \theta \cos \phi & -\sin \phi \\ \sin \theta \sin \phi & \cos \theta \sin \phi & \cos \phi \\ \cos \theta & -\sin \theta & 0 \end{vmatrix} \\
 &= r^2 \sin \theta \left[\sin \theta \cos \phi \{0 + \sin \theta \cos \phi\} - \cos \theta \cos \phi \{0 - \cos \theta \cos \phi\} \right. \\
 &\quad \left. - \sin \phi \{-\sin^2 \theta \sin \phi - \cos^2 \theta \sin \phi\} \right] \\
 &= r^2 \sin \theta [\sin^2 \theta \cos^2 \phi + \cos^2 \theta \cos^2 \phi + \sin^2 \phi \{\sin^2 \theta + \cos^2 \phi\}] \\
 &= r^2 \sin \theta [\cos^2 \phi \{\sin^2 \theta + \cos^2 \theta\} + \sin^2 \phi] \\
 &= r^2 \sin \theta [\cos^2 \phi + \sin^2 \phi] = r^2 \sin \theta.
 \end{aligned}$$

Jacobian of Implicit functions

Divided into two types

① Explicit functions

② Implicit functions

① Explicit functions : An explicit function is a function in which one variable can be clearly (explicitly) expressed in terms of the other.

$$\text{Ex} \therefore x^2 + 3xy + 9x^2y^3 = 1$$

$$x^2(1 + 3y + 9y^3) = 1$$

$y = \frac{1}{1 + 3y + 9y^3}$, is an explicit function.

② Implicit functions : An implicit function is a function in which one variable can not be expressed in terms of the other.

$$\text{Ex} \quad x^2 + 2xy + y^2 = 9$$

To find Jacobian of implicit functions we will use method of functions as mentioned below.

① Let $f_1(x, y, u, v) = 0$ and $f_2(x, y, u, v) = 0$

$$\text{then } \frac{\partial(u, v)}{\partial(x, y)} = (-1)^2 \frac{\frac{\partial(f_1, f_2)}{\partial(x, y)}}{\frac{\partial(f_1, f_2)}{\partial(u, v)}}$$

Q If $f_1(x, y, z, u, v, \omega) = 0$
 $f_2(x, y, z, u, v, \omega) = 0$
 $f_3(x, y, z, u, v, \omega) = 0$ then
 $\frac{\partial(u, v, \omega)}{\partial(x, y, z)} = (-1)^3 \frac{\frac{\partial(f_1, f_2, f_3)}{\partial(x, y, z)}}{\frac{\partial(f_1, f_2, f_3)}{\partial(u, v, \omega)}}$

Ex: If $u^3 + v^3 = x + y$, $u^2 + v^2 = x^3 + y^3$, show that

$$\frac{\partial(u, v)}{\partial(x, y)} = \frac{1}{2} \frac{y^2 - x^2}{uv(u-v)}$$

Soln: Given, $u^3 + v^3 = x + y$
 $\therefore f_1 = u^3 + v^3 - x - y$

$$\therefore f_2 = u^2 + v^2 - x^3 - y^3$$

$$\frac{\partial(u, v)}{\partial(x, y)} = (-1)^2 \frac{\frac{\partial(f_1, f_2)}{\partial(x, y)}}{\frac{\partial(f_1, f_2)}{\partial(u, v)}} = \frac{N}{D} \rightarrow ①$$

where $N = \frac{\partial(f_1, f_2)}{\partial(x, y)} = \begin{vmatrix} \frac{\partial f_1}{\partial x} & \frac{\partial f_1}{\partial y} \\ \frac{\partial f_2}{\partial x} & \frac{\partial f_2}{\partial y} \end{vmatrix} = \begin{vmatrix} -1 & -1 \\ -3x^2 & -3y^2 \end{vmatrix}$

$$N = 3y^2 - (-3x^2)(-1) = 3y^2 - 3x^2$$

$$D = \frac{\partial(f_1, f_2)}{\partial(u, v)} = \begin{vmatrix} \frac{\partial f_1}{\partial u} & \frac{\partial f_1}{\partial v} \\ \frac{\partial f_2}{\partial u} & \frac{\partial f_2}{\partial v} \end{vmatrix} = \begin{vmatrix} 3u^2 & 3v^2 \\ 2u & 2v \end{vmatrix}$$

$$D_2 = 3(2)u.v \begin{vmatrix} u & v \\ 1 & 1 \end{vmatrix} = 6uv(v-u)$$

LHS. $\frac{\partial(u, v)}{\partial(x, y)} = \frac{N}{D} = \frac{3y^2 - 3x^2}{6uv(v-u)} = \frac{y^2 - x^2}{2uv(v-u)}$

$= \frac{1}{2} \frac{y^2 - x^2}{uv(v-u)}$ Hence proved.

Ex: If $x+y+z=u$, $y+z=uv$, $x=uvw$, show that

$$\frac{\partial(x, y, z)}{\partial(u, v, w)} = u^2v$$

Soln: from the given relations, we have

$$f_1 = x+y+z-u$$

$$f_2 = y+z-uv$$

$$f_3 = z-uvw$$

$$\frac{\partial(x, y, z)}{\partial(u, v, w)} = (-1)^3 \frac{\frac{\partial(f_1, f_2, f_3)}{\partial(u, v, w)}}{\frac{\partial(f_1, f_2, f_3)}{\partial(x, y, z)}} = -\frac{N}{D} \rightarrow ①$$

where $N = \frac{\partial(f_1, f_2, f_3)}{\partial(u, v, w)}$

$$\therefore N = \begin{vmatrix} \frac{\partial f_1}{\partial u} & \frac{\partial f_1}{\partial v} & \frac{\partial f_1}{\partial w} \\ \frac{\partial f_2}{\partial u} & \frac{\partial f_2}{\partial v} & \frac{\partial f_2}{\partial w} \\ \frac{\partial f_3}{\partial u} & \frac{\partial f_3}{\partial v} & \frac{\partial f_3}{\partial w} \end{vmatrix} = \begin{vmatrix} -1 & 0 & 0 \\ -v & -u & 0 \\ -vw & -uw & -uv \end{vmatrix}$$

$$\therefore N = -1 [(-u)(-uv) - 0] = -u^2 v$$

Now, $D = \frac{\partial(f_1, f_2, f_3)}{\partial(x, y, z)} = \begin{vmatrix} \frac{\partial f_1}{\partial x} & \frac{\partial f_1}{\partial y} & \frac{\partial f_1}{\partial z} \\ \frac{\partial f_2}{\partial x} & \frac{\partial f_2}{\partial y} & \frac{\partial f_2}{\partial z} \\ \frac{\partial f_3}{\partial x} & \frac{\partial f_3}{\partial y} & \frac{\partial f_3}{\partial z} \end{vmatrix}$

$$\begin{matrix} 2, 3, 5, 5, 3, 3 \\ u, v, w \end{matrix} = \begin{vmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{vmatrix} = 1(1-0) - 1(0) + 1(0) = 1$$

$$LHS = \frac{\partial(x, y, z)}{\partial(u, v, w)} = \frac{-N}{D} = -\frac{(u^2 v)}{1} \quad R.H.S$$

Hence Proved.

Partial derivatives of Implicit functions using Jacobians.

Let $f_1(x, y, u, v) = 0$

$f_2(x, y, u, v) = 0$

then the formula to find partial derivatives by using Jacobian can be set up by following the steps.

$$\frac{\partial u}{\partial x} = - \frac{\frac{\partial(f_1, f_2)}{\partial(x, v)}}{\frac{\partial(f_1, f_2)}{\partial(u, v)}} \rightarrow \text{Numerator variable group}$$

$$\boxed{\frac{\partial u}{\partial x} = - \frac{\frac{\partial(f_1, f_2)}{\partial(x, v)}}{\frac{\partial(f_1, f_2)}{\partial(u, v)}}}$$

replace $u \rightarrow x$
in numerator only

$$\cancel{\frac{\partial y}{\partial x}} \quad \frac{\partial y}{\partial u} = - \frac{\frac{\partial(f_1, f_2)}{\partial(x, y)}}{\frac{\partial(f_1, f_2)}{\partial(u, y)}} \quad \text{replace } y \rightarrow u$$

$$\boxed{\frac{\partial y}{\partial u} = - \frac{\frac{\partial(f_1, f_2)}{\partial(x, u)}}{\frac{\partial(f_1, f_2)}{\partial(y, u)}}}$$

1
2, 4, 5, 8,
10, 22, 23, 25
24, 28, 30,
32, 38, 43
50, 53, 64,

a relation between them. If so,

$$\frac{\partial u}{\partial x} = - \frac{\frac{\partial(f_1, f_2, f_3)}{\partial(x, v, w)}}{\frac{\partial(f_1, f_2, f_3)}{\partial(u, v, w)}}$$

$$\frac{\partial y}{\partial w} = - \frac{\frac{\partial(f_1, f_2, f_3)}{\partial(x, w, z)}}{\frac{\partial(f_1, f_2, f_3)}{\partial(u, v, z)}}$$

Ex: If $u+v^2=x$, $v+w^2=y$, $w+u^2=z$, find $\frac{\partial u}{\partial x}$,

Solⁿ: $f_1 = u+v^2-x$.

$$f_2 = v+w^2-y$$

$$f_3 = w+u^2-z$$

$$\frac{\partial u}{\partial x} = - \frac{\frac{\partial(f_1, f_2, f_3)}{\partial(x, v, w)}}{\frac{\partial(f_1, f_2, f_3)}{\partial(u, v, w)}} = - \frac{N}{D} \rightarrow ①$$

$$N = \frac{\partial(f_1, f_2, f_3)}{\partial(x, v, w)} = \begin{vmatrix} \frac{\partial f_1}{\partial x} & \frac{\partial f_1}{\partial v} & \frac{\partial f_1}{\partial w} \\ \frac{\partial f_2}{\partial x} & \frac{\partial f_2}{\partial v} & \frac{\partial f_2}{\partial w} \\ \frac{\partial f_3}{\partial x} & \frac{\partial f_3}{\partial v} & \frac{\partial f_3}{\partial w} \end{vmatrix} = \begin{vmatrix} -1 & 2v & 0 \\ 0 & 1 & 2w \\ 0 & 0 & 1 \end{vmatrix}$$

$$N = -1(1-0) - 2v(0-0) + 0(0)$$

$$N = -1$$

$$D = \frac{\partial(f_1, f_2, f_3)}{\partial(u, v, w)}$$

$$D = \begin{vmatrix} \frac{\partial f_1}{\partial u} & \frac{\partial f_1}{\partial v} & \frac{\partial f_1}{\partial w} \\ \frac{\partial f_2}{\partial u} & \frac{\partial f_2}{\partial v} & \frac{\partial f_2}{\partial w} \\ \frac{\partial f_3}{\partial u} & \frac{\partial f_3}{\partial v} & \frac{\partial f_3}{\partial w} \end{vmatrix} = \begin{vmatrix} 1 & 2v & 0 \\ 0 & 1 & 2w \\ 2u & 0 & 1 \end{vmatrix}$$

$$D = 1[1] - 2v(0 - 4uw) + 0$$

$$= 1 + 8uvw$$

But the eqⁿ ①

$$\frac{\partial u}{\partial x} - \frac{-N}{D} = -\frac{(-1)}{1+8uvw} = \frac{1}{1+8uvw}$$

Ex: If $u+v=x^2+y^2$ and $u-v=x+2y$, find $\left(\frac{\partial u}{\partial x}\right)_y$

Soln: Given $f_1 = u+v-x^2-y^2$

$$f_2 = u-v-x-2y$$

and $\left(\frac{\partial u}{\partial x}\right)_y = -\frac{\frac{\partial(f_1, f_2)}{\partial(x, v)}}{\frac{\partial(f_1, f_2)}{\partial(u, v)}} = -\frac{N}{D} \rightarrow ①$

where $N = \frac{\partial(f_1, f_2)}{\partial(x, v)} = \begin{vmatrix} \frac{\partial f_1}{\partial x} & \frac{\partial f_1}{\partial v} \\ \frac{\partial f_2}{\partial x} & \frac{\partial f_2}{\partial v} \end{vmatrix} = \begin{vmatrix} -2x & 1 \\ -1 & -1 \end{vmatrix}$

$$N = 2x + 1$$

and $D = \frac{\partial(f_1, f_2)}{\partial(u, v)} \Rightarrow \begin{vmatrix} \frac{\partial f_1}{\partial u} & \frac{\partial f_1}{\partial v} \\ \frac{\partial f_2}{\partial u} & \frac{\partial f_2}{\partial v} \end{vmatrix} = \begin{vmatrix} 1 & 1 \\ 1 & -1 \end{vmatrix}$

$$D = -1 - 1 = -2$$

from eqⁿ ①.

$$\left(\frac{\partial u}{\partial x} \right)_y = -\frac{N}{D} = -\frac{(2x+1)}{-2} = \frac{2x+1}{2}$$

Ex: If $x = u+v$, $y = v^2+w^2$, $z = w^3+u^3$. Prove that

$$\frac{\partial u}{\partial x} = \frac{vw}{v^2w^2+u^2}$$

Solⁿ: Given $f_1: x = u+v$

$$f_2: y = v^2-w^2$$

$$f_3: z = w^3-u^3$$

$$\therefore \frac{\partial u}{\partial x} = \frac{-\frac{\partial(f_1, f_2, f_3)}{\partial(x, v, w)}}{\frac{\partial(f_1, f_2, f_3)}{\partial(u, v, w)}}$$

where. $N = \frac{\partial(f_1, f_2, f_3)}{\partial(x, v, w)} = \begin{vmatrix} \frac{\partial f_1}{\partial x} & \frac{\partial f_1}{\partial v} & \frac{\partial f_1}{\partial w} \\ \frac{\partial f_2}{\partial x} & \frac{\partial f_2}{\partial v} & \frac{\partial f_2}{\partial w} \\ \frac{\partial f_3}{\partial x} & \frac{\partial f_3}{\partial v} & \frac{\partial f_3}{\partial w} \end{vmatrix}$

$$N = \begin{vmatrix} 1 & -1 & 0 \\ 0 & -2v & -2w \\ 0 & 0 & -3w^2 \end{vmatrix}$$

$$= 1(6vw^2 - 0) + 1(0)$$

$$\text{and } D = \frac{\partial(f_1, f_2, f_3)}{\partial(u, v, w)} = \begin{vmatrix} \frac{\partial f_1}{\partial u} & \frac{\partial f_1}{\partial v} & \frac{\partial f_1}{\partial w} \\ \frac{\partial f_2}{\partial u} & \frac{\partial f_2}{\partial v} & \frac{\partial f_2}{\partial w} \\ \frac{\partial f_3}{\partial u} & \frac{\partial f_3}{\partial v} & \frac{\partial f_3}{\partial w} \end{vmatrix}$$

$$= \begin{vmatrix} -1 & -1 & 0 \\ 0 & -2v & -2w \\ -3u^2 & 0 & -3w^2 \end{vmatrix} = -1(6vw^2 - 0) + 1(0 + 6u^2w) \\ = -6vw^2 - 6wu^2 \\ = -6w(vw + u^2)$$

from eqⁿ ①.

$$\frac{\partial u}{\partial v} = -\frac{N}{D} = -\frac{6vw^2}{-6w(vw+u^2)} = \frac{vw}{vw+u^2}$$

Hence proved

Ex: If $ux+vy=a$, $\frac{u}{x}+\frac{v}{y}=1$, then by using Jacobians,

prove that $\left(\frac{\partial u}{\partial v}\right)_y - \left(\frac{\partial v}{\partial u}\right)_x = \frac{x+y^2}{y^2-x^2}$

Soln: $f_1 = ux+vy-a$

$$f_2 = \frac{u}{x} + \frac{v}{y} - 1$$

Part 1: To find $\left(\frac{\partial u}{\partial v}\right)_y$

$$\therefore \frac{\partial u}{\partial x} = - \frac{\frac{\partial(f_1, f_2)}{\partial(x, v)}}{\frac{\partial(f_1, f_2)}{\partial(u, v)}}$$

$$= - \frac{\begin{vmatrix} \frac{\partial f_1}{\partial x} & \frac{\partial f_1}{\partial v} \\ \frac{\partial f_2}{\partial x} & \frac{\partial f_2}{\partial v} \end{vmatrix}}{\begin{vmatrix} \frac{\partial f_1}{\partial u} & \frac{\partial f_1}{\partial v} \\ \frac{\partial f_2}{\partial u} & \frac{\partial f_2}{\partial v} \end{vmatrix}}$$

$$= - \frac{\begin{vmatrix} u & y \\ \frac{-u}{x^2} & \frac{1}{y} \end{vmatrix}}{\begin{vmatrix} x & y \\ \frac{1}{x} & \frac{1}{y} \end{vmatrix}} = \frac{-\frac{u}{y} + \frac{uy}{x^2}}{\frac{x}{y} - \frac{y}{x}}$$

$$= - \frac{u \left(\frac{1}{y} + \frac{y}{x^2} \right)}{\left(\frac{x^2 - y^2}{xy} \right)} = - \frac{u \left(\frac{x^2 + y^2}{xy} \right)}{\left(\frac{y^2 - x^2}{xy} \right)}$$

$$= - \frac{u (x^2 + y^2)}{xy} \times \frac{xy}{x^2 - y^2} = - \frac{u (x^2 + y^2)}{x (x^2 - y^2)}$$

→ ①

Divided
⑦

functional Dependence:

- 1) Let $u = f(x, y)$ and $v = g(x, y)$ be any two functions of x and y .
functions u and v are said to be functionally dependent if there exists a functional relation betⁿ u and v . otherwise functionally independent.

Assume that u and v are functionally dependent and the relation i.e. $\phi \rightarrow u, v \rightarrow v, y$. betⁿ u and v is $\phi(u, v) = 0$.

→ (1)

Thus u and v are said to be functionally dependent.

$$J = \frac{\partial(u, v)}{\partial(x, y)} = 0, \text{ If } J = \frac{\partial(u, v)}{\partial(x, y)} \neq 0$$

then u and v are functionally independent.

- 2) If u, v are functions of x, y and z then u and v are functionally dependent if

$$\frac{\partial(u, v)}{\partial(x, y)} = \frac{\partial(u, v)}{\partial(x, z)} = \frac{\partial(u, v)}{\partial(y, z)} = 0$$

- 3) If u, v, w are functions of x, y, z then u, v, w are functionally dependent if $\frac{\partial(u, v, w)}{\partial(x, y, z)} = 0$.

Ex: Examine whether u, v, w are functionally dependent or not. If dependent find relation among them.

$$a) u = y+z, v = x+2z^2, w = x-4yz-2y^2$$

$$b) u = x+y+z, v = x^2+y^2+z^2, w = xy+yz+zx$$

$$c) u = x+y+z, v = x^2+y^2+z^2, w = x^3+y^3+z^3-3xyz$$

$$d) u = \frac{x}{y-z}, v = \frac{y}{z-x}, w = \frac{z}{x-y}$$

Solⁿ(a) Given that :

$$u = y+z, v = x+2z^2, w = x-4yz-2y^2$$

Consider :

$$J = \frac{\partial(u, v, w)}{\partial(x, y, z)} = \begin{vmatrix} u_x & u_y & u_z \\ v_x & v_y & v_z \\ w_x & w_y & w_z \end{vmatrix} = \begin{vmatrix} 0 & 1 & 1 \\ 1 & 0 & 4z \\ 1 & -4z-4y & -4y \end{vmatrix}$$

$$= 0 - 1(-4y - 4z) + 1(-4z - 4y) = 0$$

$$= 4y + 4z - 4z - 4y = 0.$$

Hence u, v, w are functionally dependent.

To find Relation:

$$\text{We have } u^2 = (y+z)^2 = y^2 + z^2 + 2yz.$$

$$2u^2 = 2y^2 + 4yz + 2z^2$$

$$v - 2u^2 = (x+2z^2) - (2y^2 + 4yz + 2z^2)$$

$$= x - 4yz - 2y^2 = w$$

$$v - 2u^2 = w$$

(b)

Given that

$$u = x+y+z, v = x^2+y^2+z^2, w = xy+yz+zx$$

$$u_x = 1, u_y = 1, u_z = 1, v_x = 2x, v_y = 2y, v_z = 2z$$

$$w_x = y+z, w_y = x+z, w_z = x+y.$$

Consider.

$$J = \frac{\partial(u, v, w)}{\partial(x, y, z)} = \begin{vmatrix} u_x & u_y & u_z \\ v_x & v_y & v_z \\ w_x & w_y & w_z \end{vmatrix} = \begin{vmatrix} 1 & 1 & 1 \\ 2x & 2y & 2z \\ y+z & x+z & x+y \end{vmatrix}$$

$$= 2 \begin{vmatrix} 1 & 1 & 1 \\ x & y & z \\ y+z & x+z & x+y \end{vmatrix}$$

Apply $R_3 + R_2$

$$\frac{1}{2} \begin{vmatrix} 1 & 1 & 1 \\ x & y & z \\ x+y+z & x+y+z & x+y+z \end{vmatrix} = 2(x+y+z) \begin{vmatrix} 1 & 1 & 1 \\ x & y & z \\ 1 & 1 & 1 \end{vmatrix}$$

$$= 2(x+y+z) [1(y-z) - 1(x-z) + 1(x-y)]$$

$$= 2(x+y+z) [y-x - x+z + x-y] = 0$$

Hence u, v, w are functionally dependent.

To find relation:

$$u^2 = (x+y+z)^2$$

$$= (x^2+y^2+z^2) + 2xy + 2yz + 2xz.$$

$$u^2 = v + 2w$$

$$\boxed{u^2 = v + 2w}$$

~~Ex-~~ Are the following functions functionally dependent? If so, find a relation betⁿ them.

$$u = \frac{x-y}{x+z}; \quad v = \frac{x+z}{y+z}$$

soln:

$$u, v \rightarrow x, y, z$$

$$\frac{\partial(u, v)}{\partial(x, y)} = \frac{\partial(u, v)}{\partial(y, z)} = \frac{\partial(u, v)}{\partial(z, x)} = 0$$

Now,

$$u = \frac{x-y}{x+z}$$

$$\frac{\partial u}{\partial x} = \frac{(x+2)(1) - (x-y)(1+0)}{(x+2)^2} = \frac{x+2 - x+y}{(x+2)^2} = \frac{z+y}{(x+2)^2}$$

$$\frac{\partial u}{\partial y} = \frac{-1}{x+z}$$

$$\frac{\partial u}{\partial z} = \frac{-(x-y)}{(x+2)^2} \cdot (0+1) = \frac{y-x}{(x+2)^2}$$

Now

$$v = \frac{x+z}{y+z}$$

$$\frac{\partial v}{\partial x} = \frac{1}{y+z}$$

$$\frac{\partial v}{\partial y} = \frac{-(x+2)}{(y+z)^2} (1+0) = \frac{-(x+2)}{(y+z)^2}$$

$$\frac{\partial v}{\partial z} = \frac{(y+z)(0+1) - (x+2)(0+1)}{(y+z)^2} = \frac{y+z - x - z}{(y+z)^2} = \frac{y-x}{(y+z)^2}$$

$$\frac{\partial(u, v)}{\partial(x, y)} = \begin{vmatrix} u_x & u_y \\ v_x & v_y \end{vmatrix} = \begin{vmatrix} \frac{z+y}{(x+2)^2} & \frac{-1}{(x+2)} \\ \frac{1}{(y+z)} & \frac{-(x+2)}{(y+z)^2} \end{vmatrix}$$

$$= \frac{-(z+y)}{(x+2)^2} \cdot \frac{(x+2)}{(y+z)^2} + \frac{1}{(x+2)} \cdot \frac{1}{(y+z)} = \frac{-1}{(x+2)(y+z)} + \frac{1}{(x+2)(y+z)} = 0$$

$$\text{If } \frac{\partial(u, v)}{\partial(y, z)} = 0$$

$$\text{and } \frac{\partial(u, v)}{\partial(z, x)} = 0$$

$\therefore u$ and v are functionally dependent.

Relation:

$$\begin{aligned} \text{Let } u + \frac{1}{v} &= \frac{x-y}{x+z} + \frac{1}{\frac{x+z}{y+z}} = \frac{x-y}{x+z} + \frac{y+z}{x+z} \\ &= \frac{x-y+y+z}{x+z} \\ &= \frac{x+z}{x+z} = 1 \end{aligned}$$

$$\boxed{u + \frac{1}{v} = 1}$$

Ex: Determine whether the following functions are functionally dependent, if so, find the relation betⁿ items.

$$u = \frac{x+y}{1-xy} \text{ and } v = \tan^{-1}x + \tan^{-1}y$$

Soln: u & v are functionally dependent if $J=0$

$$\text{Now } J = \frac{\partial(u, v)}{\partial(x, y)} = \begin{vmatrix} \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{vmatrix} \rightarrow ①$$

$$\text{Let } u = \frac{x+y}{1-xy}$$

$$\left[\frac{\partial u}{\partial x} = \frac{v}{1-y^2} - u \frac{\partial v}{\partial x} \right]$$

$$\frac{\partial u}{\partial x} = \frac{(1-ny)(1+0) - (-y)(x+y)}{(1-xy)^2} = \frac{1-ny+x+y^2}{(1-xy)^2} = \frac{1+y^2}{(1-xy)^2}$$

$$u = \frac{x+y}{1-xy}$$

$$\frac{\partial u}{\partial y} = \frac{(1-xy)(1) - (-x)(1+y)}{(1-xy)^2} = \frac{1-xy+x^2+xy}{(1-xy)^2} = \frac{1+x^2}{(1-xy)^2}$$

$$\text{Now } v = \tan^{-1}x + \tan^{-1}y.$$

$$\frac{\partial v}{\partial x} = \frac{1}{1+y^2}$$

$$\frac{\partial v}{\partial y} = \frac{1}{1+x^2}$$

$$J = \begin{vmatrix} \frac{1+y^2}{(1-xy)^2} & \frac{1+x^2}{(1-xy)^2} \\ \frac{1}{1+y^2} & \frac{1}{1+x^2} \end{vmatrix} = \frac{1}{(1-xy)^2} \begin{vmatrix} 1+y^2 & 1+x^2 \\ \frac{1}{1+y^2} & \frac{1}{1+x^2} \end{vmatrix}$$

$$= \frac{1}{(1-xy)^2} \left[\frac{1+y^2}{1+y^2} - \frac{1+x^2}{1+x^2} \right] = 0$$

$\therefore u$ and v are functionally dependent.

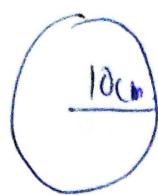
Relation: $v = \tan^{-1}x + \tan^{-1}y$.

$$v = \tan^{-1} \left[\frac{x+y}{1-xy} \right] = \tan^{-1} u$$

$$\therefore \boxed{v = \tan^{-1} u}$$

Errors and Approximations.

Consider a circle of radius 10 cm as shown in fig.



$$\text{Area of circle} = A = \pi r^2$$

$$= \pi (10)^2$$

$$= 100\pi \text{ cm}^2$$

Now, there can be a human error while calculating the radius of circle, it can be positive or negative. Let's say, radius calculated is 10.1 cm instead of 10 cm.

$$A = \pi r^2 = \pi (10.1)^2$$

$$= 102.01\pi \text{ cm}^2$$

∴ for $(10.1 - 10)$ cm = 0.1 cm error in radius, there will corresponding $(102.01\pi - 100\pi) = 2.01\pi \text{ cm}^2$ error in area.
And this is called as error.

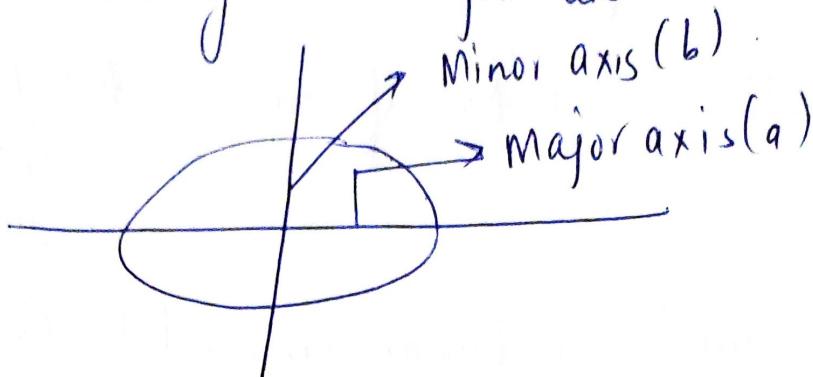
Note:- ①. If dr is the actual error made in measurement of radius ' r ', then the dA is the approximate error introduced in area ' A '.

$\frac{100dr}{r}$ and $\frac{100dA}{A}$ are known as % errors in radius and area respectively.

- (i) dr, dy, dz are known as actual errors in x, y, z , resp.
- (ii) $\frac{dx}{x}, \frac{dy}{y}, \frac{dz}{z}$ are known as relative error in x, y, z , respectively.
- (iii) $\frac{100dx}{x}, \frac{100dy}{y}, \frac{100dz}{z}$ are known as Percentage errors in x, y, z , resp.

Ex: find the percentage error in the area of an ellipse when an error of 2% and 3% is made in measuring its major and minor axis

Soln



Given

$$\frac{100da}{a} = 2, \quad \frac{100db}{b} = 3$$

Area of the ellipse is given by,

$$A = \pi ab$$

Taking log on both sides

$$\log A = \log(\pi ab) = \log \pi + \log a + \log b$$

[$\because \log(abc) = \log a + \log b + \log c$]

Differentiation

$$\frac{1}{A} dA = 0 + \frac{1}{a} da + \frac{1}{b} db$$

Multiplying by 100

$$\frac{100 dA}{A} = \frac{100da}{a} + \frac{100db}{b} = 2 + 3 = 5$$

% error in area $A = 5\%$

Ex: In calculating the volume of a right circular cone, errors of 2% and 1% are made in measuring the height and radius of base resp.

Find the error in calculated volume.

Soln: Let h = height

Given r = radius of base

$$\frac{100 dh}{h} = 2; \quad \frac{100 dr}{r} = 1$$

Volume V of right circular cone is given by,

$$V = \frac{1}{3} \pi r^2 h$$

Taking log on both sides,

$$\log V = \log \left[\frac{1}{3} \pi r^2 h \right]$$

$$\log V = \log \frac{1}{3} + \log \pi + \log r^2 + \log h$$

$$[\text{By } \log m^n = n \log m]$$

$$\log V = \log \frac{1}{3} + \log \pi + 2 \log r + \log h$$

Differentiating,

$$\frac{1}{V} dV = 0 + 0 + 2 \frac{1}{r} dr + \frac{1}{h} dh$$

Multiplying by 100

$$\frac{100 dV}{V} = 2 \frac{100 dr}{r} + \frac{100 dh}{h}$$

$$\therefore \frac{100 dV}{V} = 2(1) + 2 = 4$$

$\therefore \%$ error in volume (V) = 40%

Ex: find the possible percentage error in calculating parallel resistance 'x' of the three resistances r_1, r_2, r_3 from the formula $\frac{1}{x} = \frac{1}{r_1} + \frac{1}{r_2} + \frac{1}{r_3}$ if r_1, r_2, r_3 are each in error by $\pm 1\%$.

Soln:- Given:

$$\frac{100dr_1}{r_1} = 1.2, \quad \frac{100dr_2}{r_2} = 1.2, \quad \frac{100dr_3}{r_3} = 1.2.$$

$$\text{and } \frac{1}{x} = \frac{1}{r_1} + \frac{1}{r_2} + \frac{1}{r_3} \quad \dots \quad (1)$$

Differentiating,

$$-\frac{1}{x^2} dx = -\frac{1}{r_1^2} dr_1 - \frac{1}{r_2^2} dr_2 - \frac{1}{r_3^2} dr_3 \quad \left(\because \frac{d}{dx} \frac{1}{x} = -\frac{1}{x^2} \right)$$

$$-\frac{1}{x} \cdot \frac{dx}{x} = \left[\frac{1}{r_1} \frac{dr_1}{r_1} + \frac{1}{r_2} \frac{dr_2}{r_2} + \frac{1}{r_3} \frac{dr_3}{r_3} \right]$$

Multiplying by 100 on both sides.

$$\frac{1}{x} \frac{100dx}{x} = \frac{1}{r_1} \frac{100dr_1}{r_1} + \frac{1}{r_2} \frac{100dr_2}{r_2} + \frac{1}{r_3} \frac{100dr_3}{r_3}$$

~~Now~~

$$\therefore \frac{1}{x} \frac{100dx}{x} = \frac{1}{r_1} (1.2) + \frac{1}{r_2} (1.2) + \frac{1}{r_3} (1.2)$$

$$\therefore \frac{1}{x} \frac{100dx}{x} = \left[\frac{1}{r_1} + \frac{1}{r_2} + \frac{1}{r_3} \right] (1.2)$$

$$\text{But from eqn } (1). \quad \frac{1}{x} = \frac{1}{r_1} + \frac{1}{r_2} + \frac{1}{r_3}$$

$$\therefore \text{So, } \frac{1}{f} \cdot \frac{100\delta s}{s} = \frac{1}{f}(1.2) = 1.2$$

\therefore % Error in f is 1.2%

Ex: The focal length of a mirror is found from the formula $\frac{1}{v} - \frac{1}{u} = \frac{2}{f}$. find the percentage error if if u and v are both in error by $p\%$ each.

$$\text{Soln: } \frac{100 du}{u} = p \text{ and } \frac{100 dv}{v} = p \quad (\text{Given})$$

$$\text{and } \frac{1}{v} - \frac{1}{u} = \frac{2}{f} \quad \rightarrow \textcircled{1}$$

Differentiating

$$-\frac{1}{v^2} dv + \frac{1}{u^2} du = -\frac{2}{f^2} df$$

$$f \left(\frac{1}{v} \frac{dv}{v} - \frac{1}{u} \frac{du}{u} \right) = f \frac{2}{f} \cdot \frac{df}{F}$$

Multiplying by 100

$$\frac{1}{v} \frac{100 dv}{v} - \frac{1}{u} \frac{100 du}{u} = \frac{2}{f} \cdot 100 \frac{df}{F}$$

$$\frac{1}{v} (p) - \frac{1}{u} (p) = \frac{2}{f} \cdot \frac{100 df}{F} \quad \dots \text{ (Given)}$$

$$P \left(\frac{1}{v} - \frac{1}{u} \right) = \frac{2}{f} \cdot 100 \frac{df}{F}$$

$$\text{But from eqn } \textcircled{1} \cdot P \left(\frac{2}{f} \right) = \frac{2}{f} \cdot \frac{100 df}{F} \Rightarrow P = \frac{100 df}{F}$$

% error in f is $P\%$

Ex:- If $x = u(1-v)$ and $y = uv$, then Prove that $JJ' = 1$.

Soln: Given $x = u(1-v)$ and $y = uv$

Part 1: To find J

$$J = \frac{\partial(x, y)}{\partial(u, v)} = \begin{vmatrix} x_u & x_v \\ y_u & y_v \end{vmatrix} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix}$$

$$= \begin{vmatrix} 1-v & -u \\ v & u \end{vmatrix} = (1-v)u + uv \\ = u - uv + uv = u = J$$

Part 2: To find J' (Reciprocal of J)

Given $x = u(1/v)$ and $y = uv$

$$\frac{1}{J} = J' = \frac{\partial(y, v)}{\partial(x, y)} = \begin{vmatrix} y_v & y_y \\ v_x & v_y \end{vmatrix} = \frac{1}{u},$$

$$JJ' = 1 = u \cdot \frac{1}{u} = 1 \text{ Hence Proved!}$$

Note: For J' , we will always follow the method of functions as explained in this example.

Given $x = u(1-v)$ and $y = uv$

$$\therefore f_1 = x - u(1-v) = x - u + uv$$

$$f_2 = y - uv = y - uv$$

$$\therefore J' = \frac{\partial(u, y)}{\partial(x, y)} = (-1)^2 \frac{\partial(f_1, f_2)}{\partial(x, y)} = \frac{\frac{\partial(f_1, f_2)}{\partial(f_1, f_1)}}{\frac{\partial(f_1, f_2)}{\partial(u, v)}} = \frac{N}{D}$$

$$\therefore J^{-1} = \frac{N}{D} \quad \rightarrow ①$$

$$N = \begin{vmatrix} \frac{\partial f_1}{\partial x} & \frac{\partial f_1}{\partial y} \\ \frac{\partial f_2}{\partial x} & \frac{\partial f_2}{\partial y} \end{vmatrix} = \begin{vmatrix} 1 & 0 \\ 0 & 1 \end{vmatrix} = 1$$

and

$$D = \frac{\partial(f_1, f_2)}{\partial(u, v)} = \begin{vmatrix} \frac{\partial f_1}{\partial u} & \frac{\partial f_1}{\partial v} \\ \frac{\partial f_2}{\partial u} & \frac{\partial f_2}{\partial v} \end{vmatrix} = \begin{vmatrix} -1+v & u \\ -v & -u \end{vmatrix}$$

$$\begin{aligned} &= -(1+v)(-u) - u(-v) \\ &= u + uv + uv = u \end{aligned}$$

$$\text{from eqn } ① \quad J^{-1} = \frac{N}{D} = \frac{1}{u} =$$

$$\text{Now LHS: } JJ^{-1} = u \cdot \frac{1}{u} = 1 \quad \text{R.H.S}$$

hence proved

Ex: If $x=uv$ and $y=\frac{u+v}{u-v}$, prove that, $\frac{\partial(u,v)}{\partial(x,y)} = \frac{(u-v)^2}{4uv}$

Soln: Given $x=uv$ and $y=\frac{u+v}{u-v}$

$$f_1: x=uv$$

$$y(u-v)=u+v$$

$$yu-yv=u+v$$

$$f_2: yu-yv=u-v$$

$$\text{Now } \frac{\partial(u, v)}{\partial(x, y)} = (-1)^1 \cdot \frac{\frac{\partial(f_1, f_2)}{\partial(x, y)}}{\frac{\partial(f_1, f_2)}{\partial(u, v)}}$$

$$\frac{\partial(u, v)}{\partial(x, y)} = \frac{N}{D}$$

where $N = \frac{\partial(f_1, f_2)}{\partial(x, y)} = \begin{vmatrix} \frac{\partial f_1}{\partial x} & \frac{\partial f_1}{\partial y} \\ \frac{\partial f_2}{\partial x} & \frac{\partial f_2}{\partial y} \end{vmatrix} = \begin{vmatrix} 1 & 0 \\ 0 & u-v \end{vmatrix}$

$$N = u - v$$

and $D = \frac{\partial(f_1, f_2)}{\partial(u, v)} = \begin{vmatrix} \frac{\partial f_1}{\partial u} & \frac{\partial f_1}{\partial v} \\ \frac{\partial f_2}{\partial u} & \frac{\partial f_2}{\partial v} \end{vmatrix} = \begin{vmatrix} -v & -u \\ y-1 & -y-1 \end{vmatrix}$

$$D = (-v)(-y-1) - (-u)(y-1)$$

$$D = vy + v + uy - u$$

$$\text{Now: LHS} = \frac{\partial(u, v)}{\partial(x, y)} = \frac{N}{D} = \frac{u-v}{vy+v+uy-u}$$

$$\text{But } y = \frac{u+v}{u-v} \quad (\text{Given})$$

$$= \frac{u-v}{v\left(\frac{u+v}{u-v}\right) + v + u\left(\frac{u+v}{u-v}\right) - u}$$

$$= \frac{u-v}{v(u+v) + v(u-v) + u(u+v) - u(u-v)}$$

$$= \frac{(u-v)^2}{uv + v^2 + uv - v^2 + u^2 + uv - u^2 + uv}$$

$$= \frac{(u-v)^2}{4uv} = R.H.S \text{ Hence proved}$$

→ If $x = v^2 + w^2$; $y = w^2 + u^2$, $z = u^2 + v^2$, then Prove
that $J J' = 1$

Soln: To find J

Given : $x = v^2 + w^2$, $y = w^2 + u^2$, $z = u^2 + v^2$

$$\therefore J = \frac{\partial(x, y, z)}{\partial(u, v, w)} = \begin{vmatrix} x_u & x_v & x_w \\ y_u & y_v & y_w \\ z_u & z_v & z_w \end{vmatrix}$$

$$= \begin{vmatrix} 0 & 2v & 2w \\ 2u & 0 & 2w \\ 2u & 2v & 0 \end{vmatrix}$$

Taking common, $2u$ from 1st column
 $2v$ from 2nd column
 $2w$ from 3rd column

$$\therefore J = (2u)(2v)(2w) \begin{vmatrix} 0 & 1 & 1 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{vmatrix}$$

$$J = \frac{8uvw}{16uvw} \left(0 - 1(a-1) + 1(1) \right) = 8uvw(2)$$

To find J'

$$\text{Given } x = v^2 + w^2, y = w^2 + u^2, z = u^2 + v^2$$

$$f_1 = x - v^2 - w^2$$

$$f_2 = y - w^2 - u^2$$

$$f_3 = z - u^2 - v^2$$

$$\therefore J' = \frac{\partial(u, v, w)}{\partial(x, y, z)} = (-1)^3 \frac{\partial(f_1, f_2, f_3)}{\partial(x, y, z)} \frac{\partial(x, y, z)}{\partial(f_1, f_2, f_3)} \frac{\partial(f_1, f_2, f_3)}{\partial(u, v, w)}$$

$$J' = \frac{-N}{D}$$

$$\text{where } N = \frac{\partial(f_1, f_2, f_3)}{\partial(x, y, z)}$$

$$N = \begin{vmatrix} f_{1x} & f_{1y} & f_{1z} \\ f_{2x} & f_{2y} & f_{2z} \\ f_{3x} & f_{3y} & f_{3z} \end{vmatrix} = \begin{vmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{vmatrix}$$

$$D = \frac{\partial(f_1, f_2, f_3)}{\partial(u, v, w)} = \begin{vmatrix} f_{1u} & f_{1v} & f_{1w} \\ f_{2u} & f_{2v} & f_{2w} \\ f_{3u} & f_{3v} & f_{3w} \end{vmatrix} \quad N = 1$$

$$\begin{aligned}
 &= \begin{vmatrix} 0 & -2v & -2w \\ -2u & 0 & -2w \\ -2v & -2w & 0 \end{vmatrix} = (-2u)(-2v)(-2w) \begin{vmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{vmatrix} \\
 &= -8uvw(0 - 1(0 - 1) + 1(1)) \\
 &= -8uvw(2) = -16uvw
 \end{aligned}$$

But from eqⁿ ①.

$$J = -\frac{N}{D} = \frac{-1}{-16uvw} = \frac{1}{16uvw}$$

$$\text{LHS } JJ' = 16uvw \times \frac{1}{16uvw} = 1 \text{ Henie Proved.}$$