

# An experimental study of the learnability of congestion control

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# Designing congestion-control protocols today

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- ▶ Formulate a mental model of the target network
- ▶ Decide on the protocol's goal
- ▶ Design a protocol to achieve this goal
- ▶ Can either be implicit or explicit

# But, the model is always wrong!

- ▶ Lost throughput due to stochastic loss
- ▶ Bufferbloat when queues are incorrectly sized
- ▶ Incast in datacenters

# Our work

- ▶ Can we formalize this design process ...



# Our work

- ▶ Can we formalize this design process ...
- ▶ and quantify the consequences of model mismatch?

# Contributions

- ▶ Formalize learnability in the context of congestion control
- ▶ Use it to answer:
  - ▶ Do we need to know the link speed exactly?
  - ▶ What is the cost of backwards compatibility?
  - ▶ Do we need to know the topology exactly?

# Approach

- ▶ Specify a *training scenario*.
  - ▶ Topology
  - ▶ Locations of senders and receiver
  - ▶ Application workload
  - ▶ Buffer size and queuing discipline
- ▶ Specify an *objective function*.
- ▶ Synthesize protocol automatically.
- ▶ Evaluate on a *testing scenario* inside ns-2

# Automated protocol synthesis

- ▶ Find best protocol, given an imperfect network model
- ▶ The problem is hard to solve in general
- ▶ Rely on Remy<sup>1</sup> to produce congestion-control protocols.

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<sup>1</sup>KW and Hari Balakrishnan, **TCP ex Machina: Computer-Generated Congestion Control**, *SIGCOMM 2013*

# Caveats and non-goals

- ▶ Very simple, controlled experiments
- ▶ Results could change with better protocol-design tools
- ▶ Not trying to understand Remy's internals

# Is using Remy reasonable?

- ▶ Training scenario:

Link speed	32 Mbits/sec
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Minimum RTT	150 ms
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Topology	Dumbbell
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Number of senders	2
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Workload	1 sec ON/OFF times
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Buffer size	5 BDP
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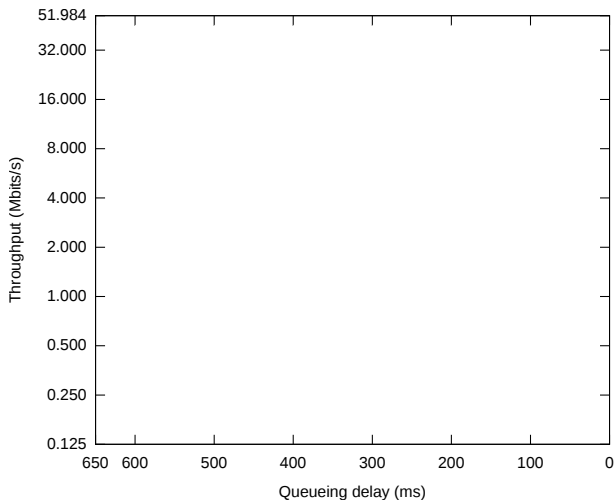
Objective function	$\sum \log(\text{throughput}) - \log(\text{delay})$
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- ▶ Testing scenario identical to training scenario

# Is using Remy reasonable?

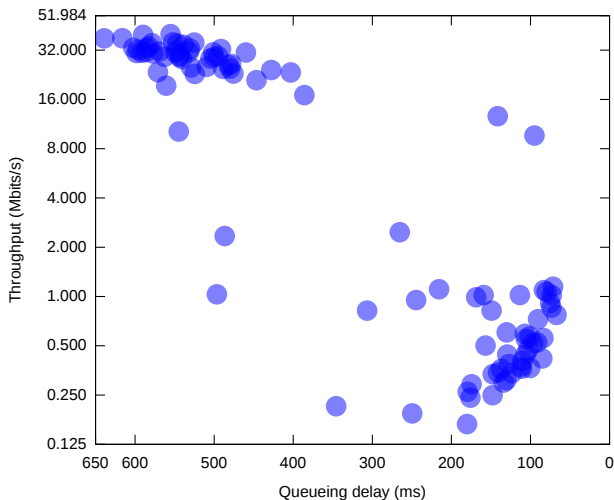
- ▶ A hypothetical centralized scheme (CEN)
  - ▶ Every time a sender turns ON/OFF, solve  $\sum \log(\text{throughput})$
  - ▶ Set each sender's rate using obtained solution
  - ▶ Zero queuing delay

# Is using Remy reasonable?

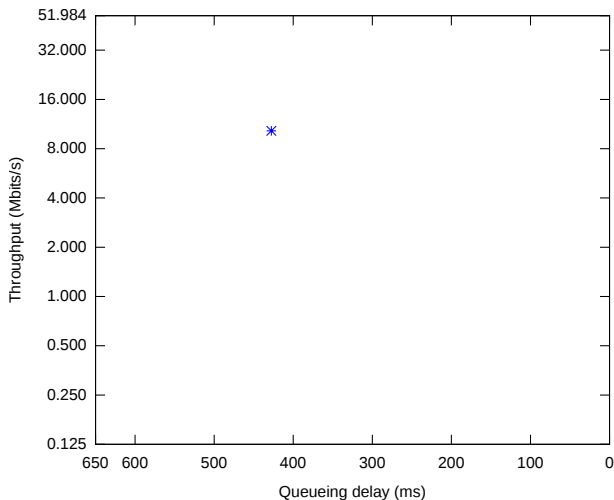




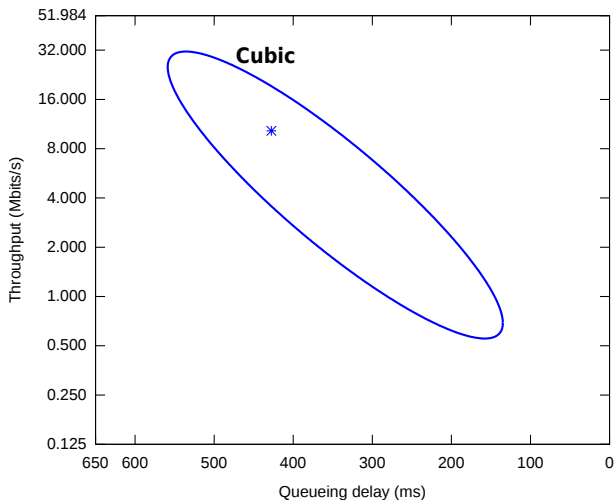
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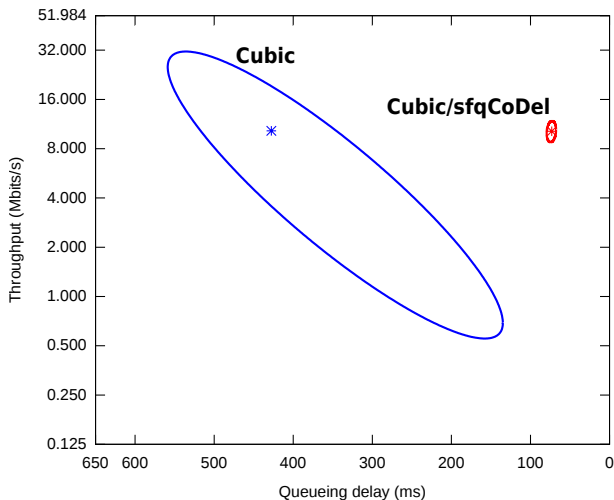
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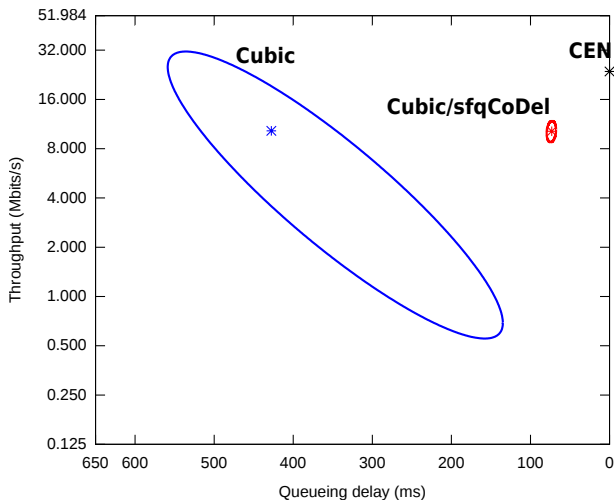
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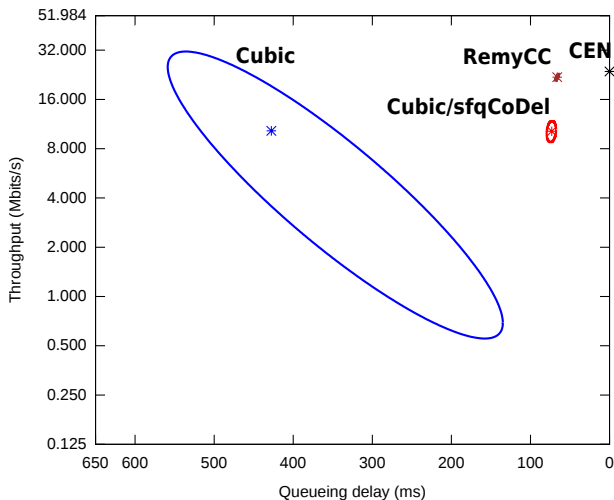
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# The cost of generality, or forwards-compatibility

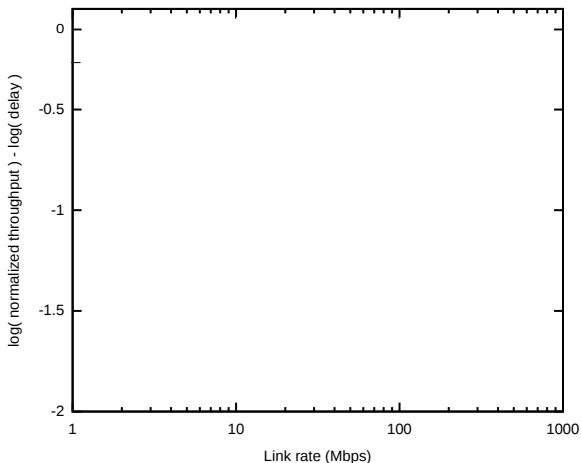
<b>RemyCC</b>	<b>Link rates</b>	<b>RTT</b>	<b>Senders</b>	<b>ON/OFF time</b>	<b>Topology</b>
1000x	1–1000 Mbps	150 ms	2	1 sec	Dumbbell
100x	3.2–320 Mbps	150 ms	2	1 sec	Dumbbell
10x	10–100 Mbps	150 ms	2	1 sec	Dumbbell
2x	22–44 Mbps	150 ms	2	1 sec	Dumbbell

**Table :** Training scenarios for forwards-compatibility experiment

<b>Link rates</b>	<b>RTT</b>	<b>Senders</b>	<b>ON/OFF time</b>	<b>Topology</b>
1–1000 Mbps	150 ms	2	1 sec	Dumbbell

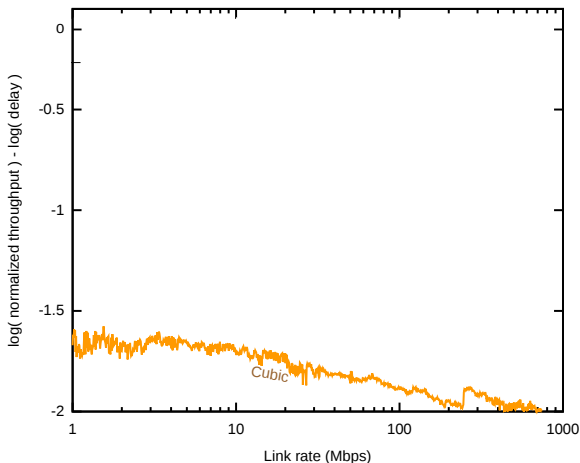
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# The cost of generality, or forwards-compatibility

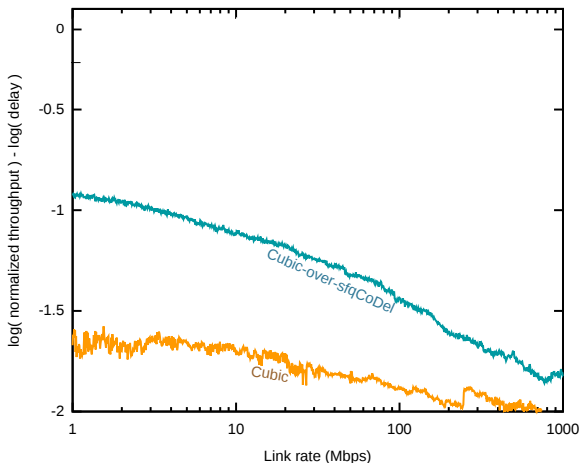




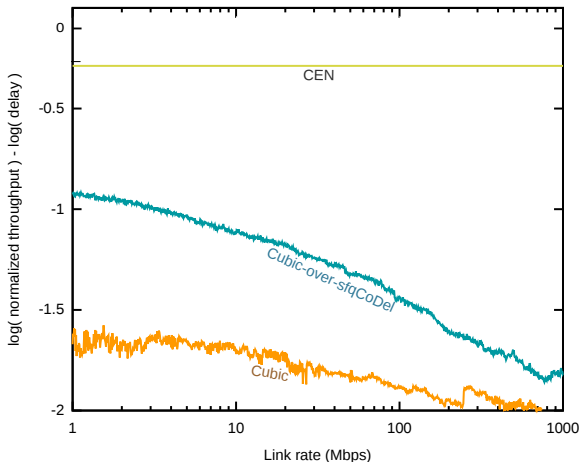
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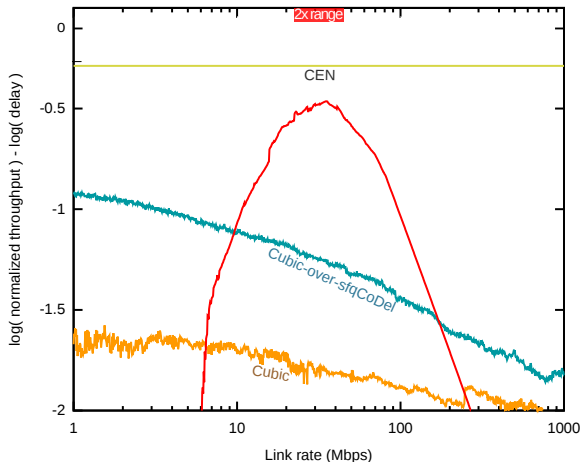
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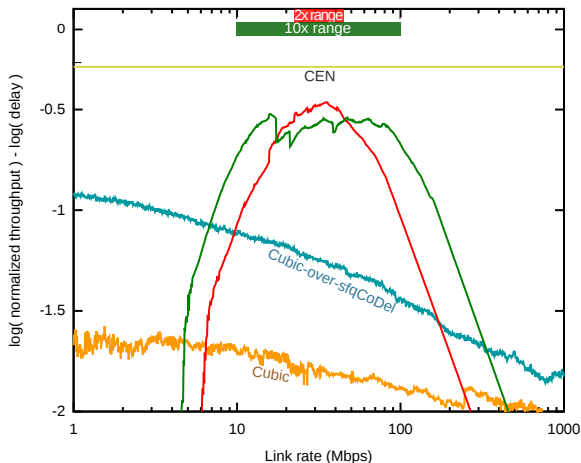
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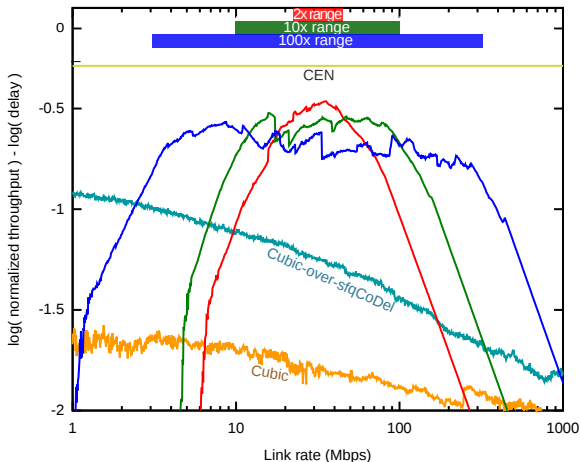
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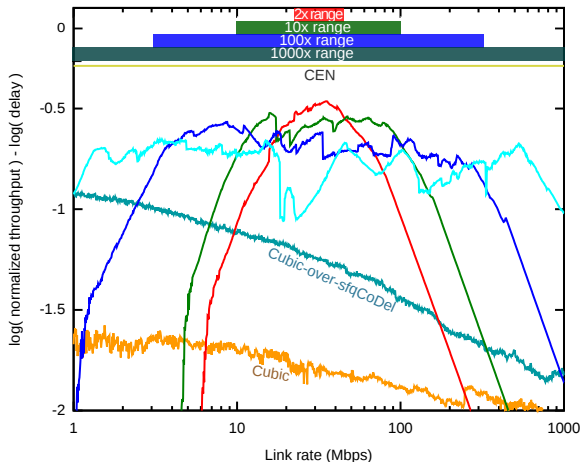
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# The cost of generality, or forwards-compatibility



# Can we design a RemyCC that is TCP aware?

RemyCC	Link rates	RTT	Senders	ON/OFF time	Topology
TCP-aware	9–11 Mbps	100 ms	2 Remy 1 Remy, 1 AIMD	5 sec ON/OFF 5 sec ON, 10 ms OFF	Dumbbell
TCP-naive	9–11 Mbps	100 ms	2 Remy	5 sec ON/OFF 5 sec ON, 10 ms OFF	Dumbbell

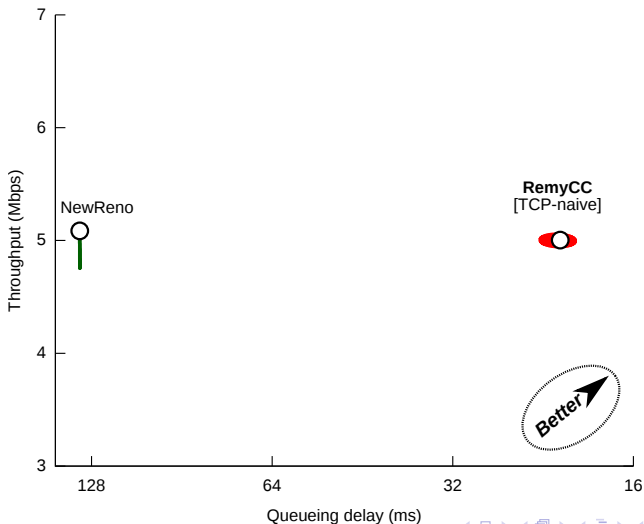
Table : Training scenarios

Link rates	RTT	Senders	ON/OFF time	Topology
10 Mbps	100 ms	2 TCP-aware	5 sec ON, 10 ms OFF	Dumbbell
10 Mbps	100 ms	2 TCP-naive	5 sec ON, 10 ms OFF	Dumbbell
10 Mbps	100 ms	TCP-aware, AIMD	5 sec ON, 10 ms OFF	Dumbbell
10 Mbps	100 ms	TCP-naive, AIMD	5 sec ON, 10 ms OFF	Dumbbell
10 Mbps	100 ms	2 AIMD	5 sec ON, 10 ms OFF	Dumbbell

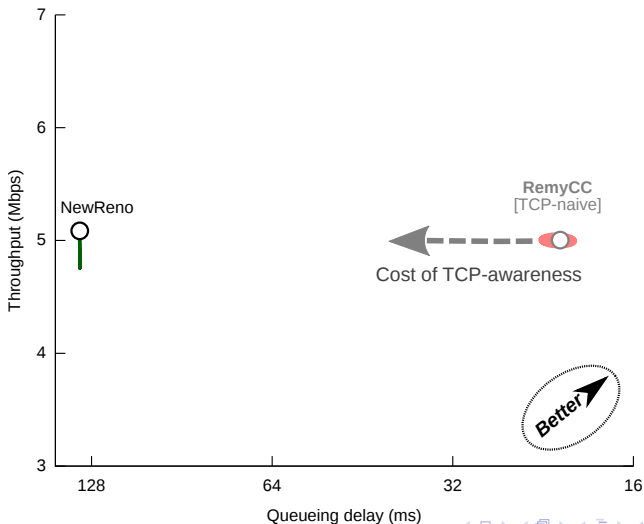
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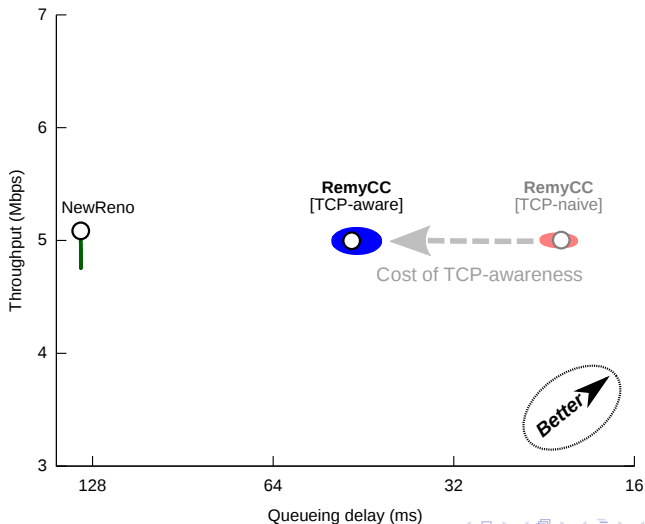
# RemyCC competing against itself



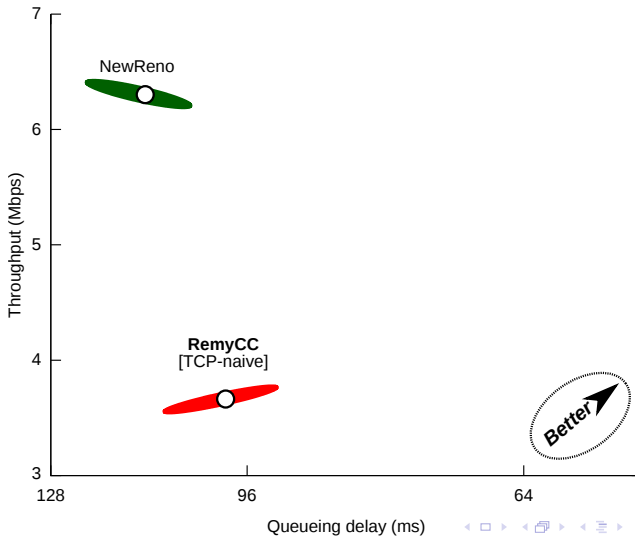
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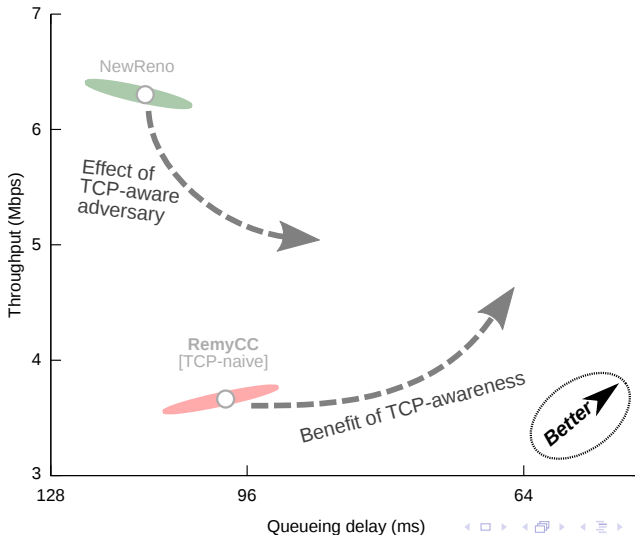
# RemyCC competing against itself



# RemyCC competing against TCP NewReno



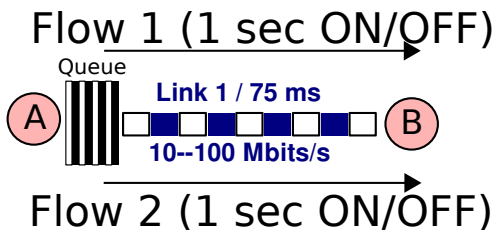
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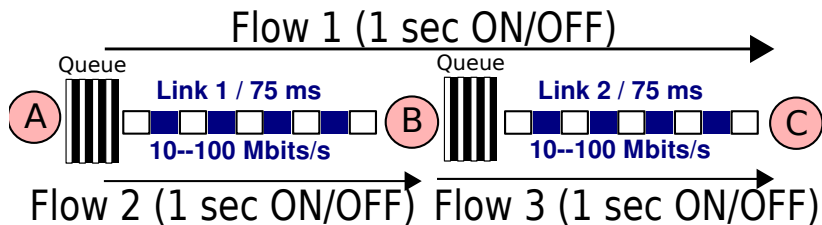
# When the model is wrong about the topology

One bottleneck



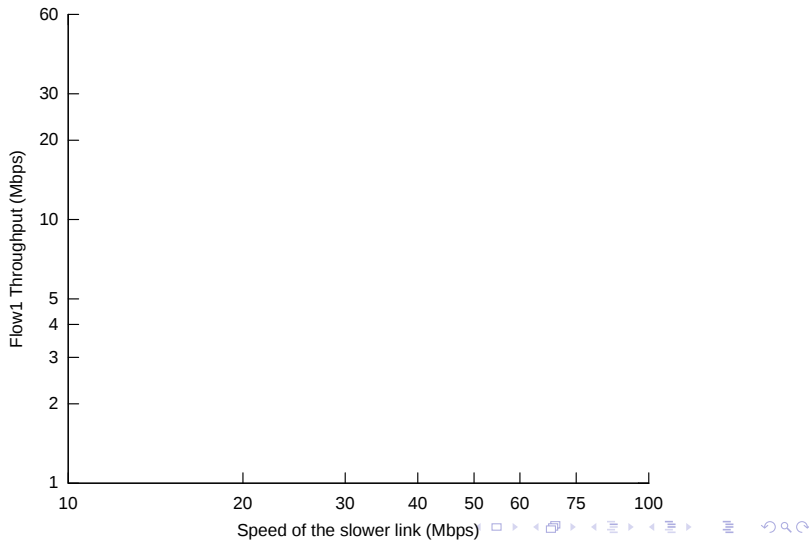
## When the model is wrong about the topology

Two bottlenecks

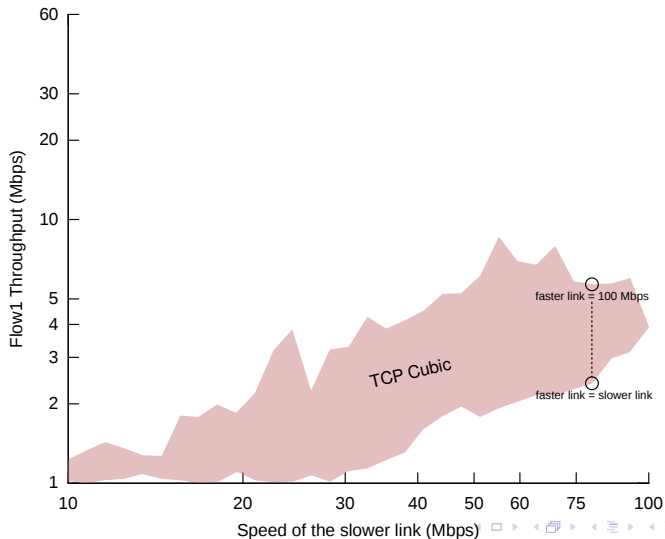




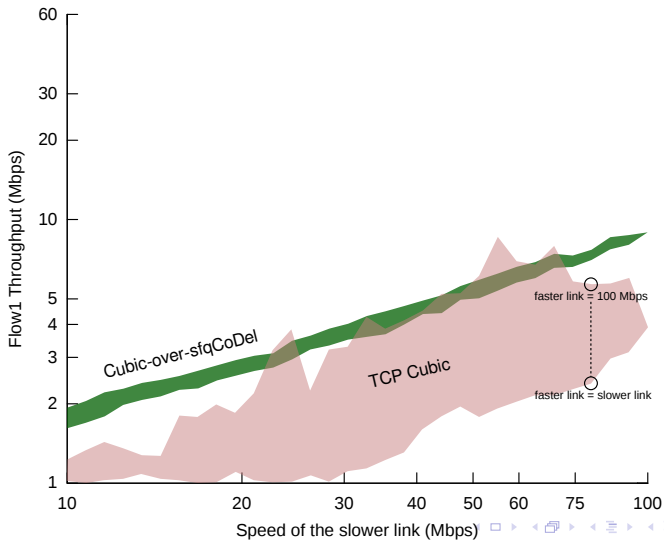
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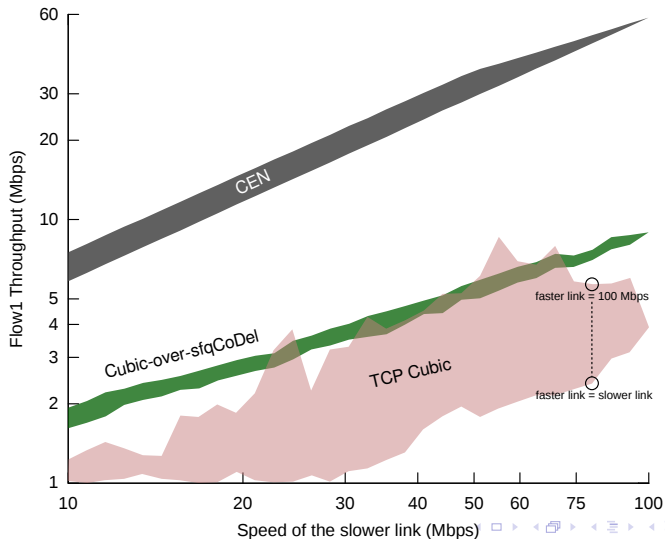
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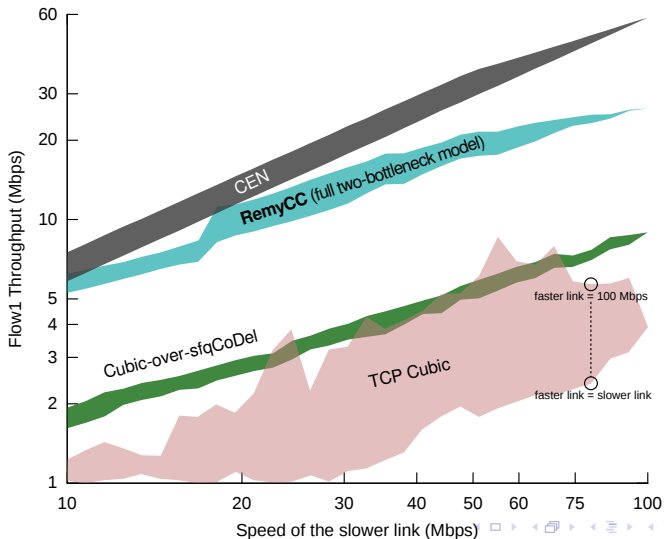
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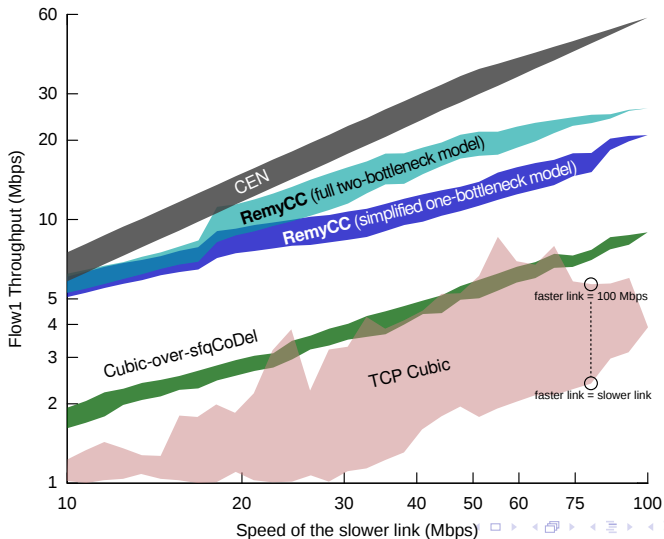
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# When the model is wrong about the topology



# When the model is wrong about the topology



# Related Work

- ▶ Probably approximately correct learning
- ▶ Transfer learning
- ▶ Machine-generated congestion control

# Limitations and future work

- ▶ Generalizability to more complex topologies?
- ▶ Better characterization of gap from optimal
- ▶ Do results change if we learn in-network behavior as well?
- ▶ Model mismatches between simulation and the real world



# Backup slides

# Can applications with different objectives coexist?

- ▶ Tpt. Sender: A throughput-intensive sender

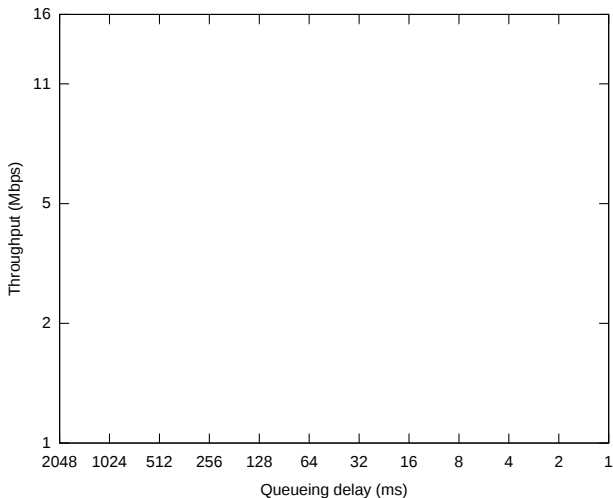
$$\log(\text{throughput}) - 0.1 * \log(\text{delay}) \quad (1)$$

- ▶ Lat. Sender: A latency-sensitive sender

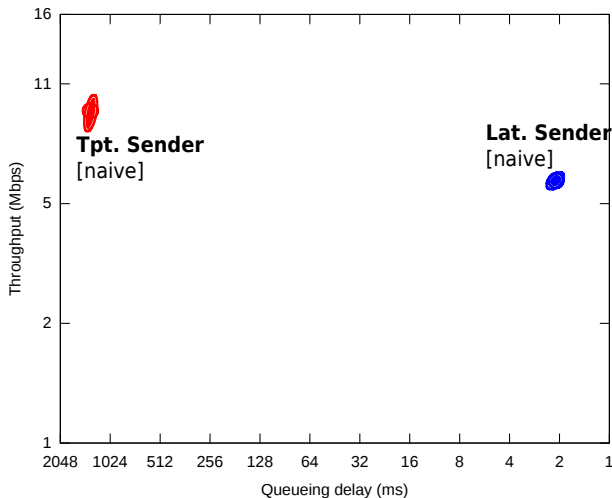
$$\log(\text{throughput}) - 10.0 * \log(\text{delay}) \quad (2)$$

- ▶ Running over a FIFO queue

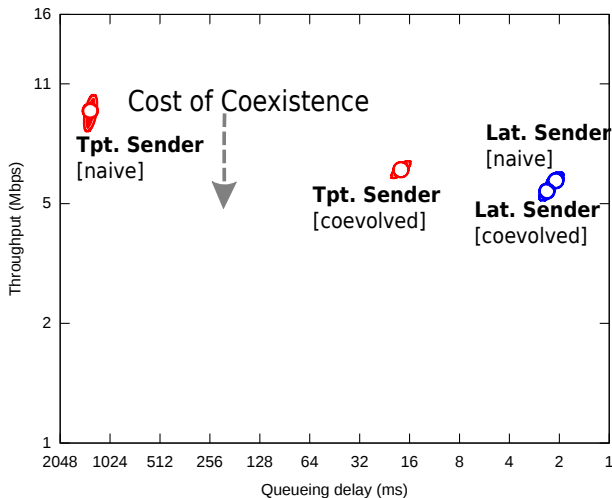
# Training for diversity has a cost ...



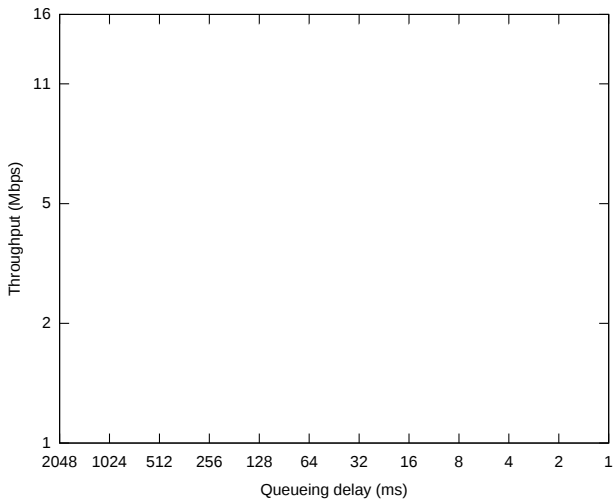
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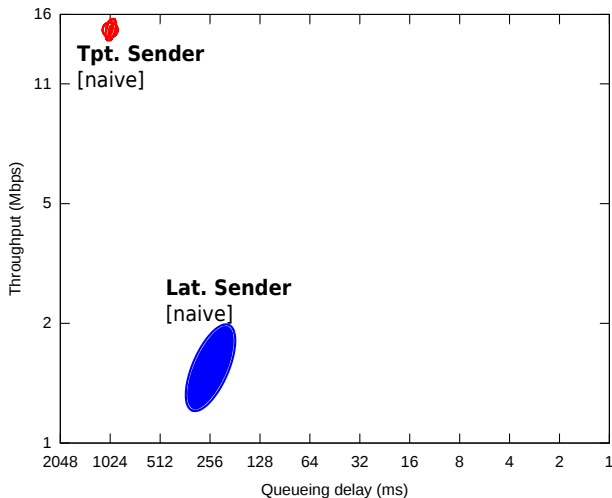
# Training for diversity has a cost ...



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