IIB Project Proposal

I wish to explore network generation and associated metrics, with a particular focus on 2-D networks and then extend analysis to N-D networks. I have conducted some basic background studies and analysis on the same, existing studies usually explore topological representations of urban networks or 3-D lattices and explore how to build reinforcement learning systems that allow vehicles to navigate networks that minimize global congestion. I wish to see how to generate networks given a distribution of source and destination nodes – maximizing the path efficiency while minimizing global congestion.

A small network testing application I built using python helped me explore this. Networks can be built - for them to be able to tessellate a rectangular grid certain rules must be fulfilled that I won't enumerate here - but they allow one to travel between any point on the grid to any other point through the network. The network is built by the user and converted into a dictionary in the form: {(source node): ((dest node 1, w1), (dest node 2, w2)),}

This is then converted into a full network by tessellating the network horizontally and vertically.

The network is then re-weighted - we inflate weights of nodes that are connected to many nodes (intersection weighting) which is tuned by a parameter W. For a given parameter W - we will multiply each node's outgoing weight by a term β_n where –

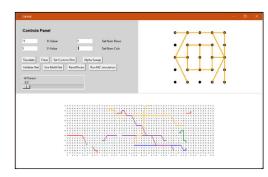


Figure 1: Network Testing Application

 $\beta_n = W * \max\left(\frac{len(node)}{2}, 1\right)$. This will ensure that networks with too many intersections and junctions are penalized.

Random routes can be plotted using Dijkstra's algorithm. Their efficiency is then calculated as the ratio of the Euclidean distance between source and destination nodes over the total weighting. With intersection weighting a route efficiency metric won't make intuitive sense as we are artificially re-weighting path weights. We will now refer to the efficiency metric as a *relative efficiency*

metric - as it can no longer truly equal 1. Networks with higher average *relative efficiencies* will be better with our fixed path capacity model - they offer an average route that doesn't involve many intersections.

Some examples are given below in figure 2, for *relative path efficiencies* for networks with a fixed aspect ratio of the grid being 3:1 - note this is for a W value of 1 - so intersections of 3 paths increase the node weight by 50%, intersections of 4 increase the node weight by 100% etc. We also note source and destination points are chosen from a uniform distribution.

Several things interest me regarding this project, while the analysis before is basic, I want to use it as a starting point to explore some ideas about graph networks:

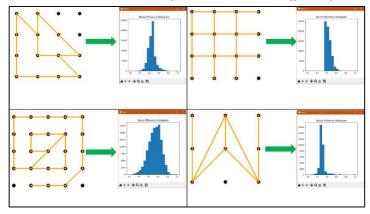


Figure 2: Comparison of relative efficiency histogram (Monte Carlo Simulations) for different networks with aspect ratio 3:1.

- 1. With the uniform distribution of points, and a fixed aspect ratio what would be the theoretical highest average relative efficiency possible.
- 2. We can now expand this to an arbitrary probability distribution over space we can use a mixture of Gaussians model to indicate 'popular' source and destination nodes. How would a theoretical best network look if one was varying the parameters of the MoG model could one use reinforcement learning techniques to draw relationships between parameters of the population distribution and the network tessellation required?
- 3. Abstracting this further, removing the need for a 'tessellation'; given a population distribution what would a deep learning network draw to maximize distance efficiency whilst minimizing intersectional weighting (ensuring the network is planar with no discontinuities)
- 4. We can then extend this into N-D space. For 3-D space we can generate a probability distribution; for N >> 3 (e.g. for vectorized images with some dimensionality reduction) we can use an image dataset to generate our p-distribution. How will a neural network with the same motivations build a graph in N-D space that will maximize N-D distance efficiency and minimize number of intersections. And could the properties of this network be used to build semantic relationships between image classes?