

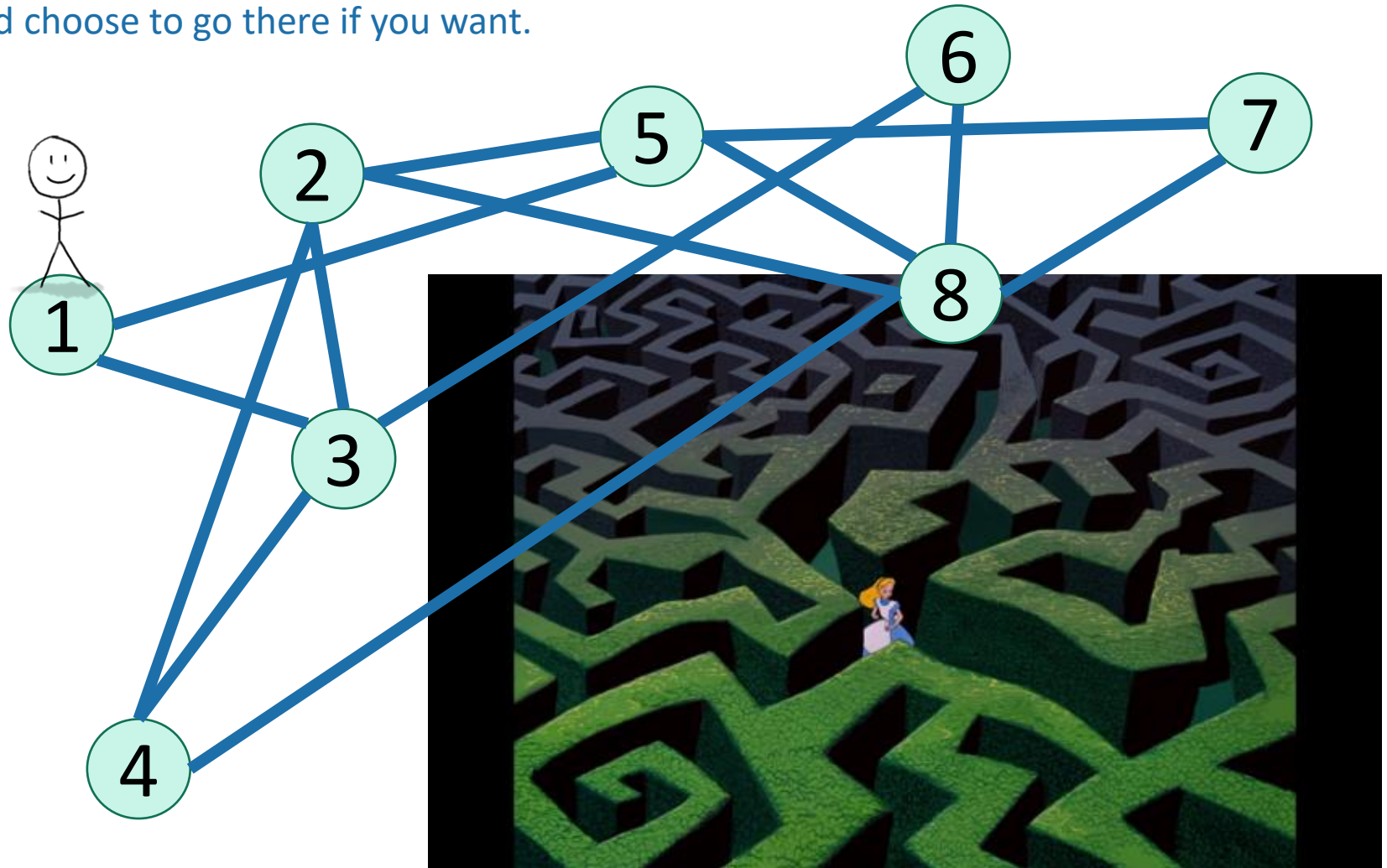
Advanced Data Structures and Algorithms

Depth First Search (DFS)

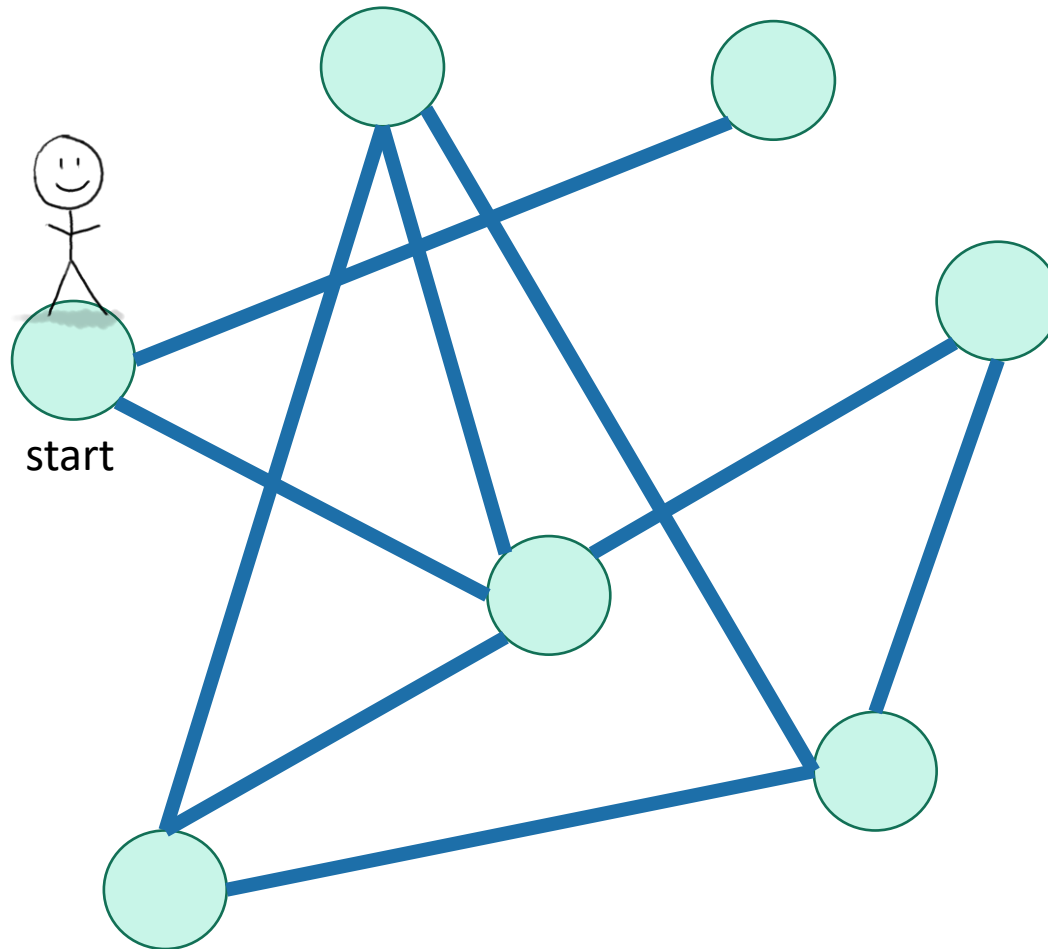
Depth-first search




How do we explore a graph?

At each node, you can get a list of neighbors,
and choose to go there if you want.

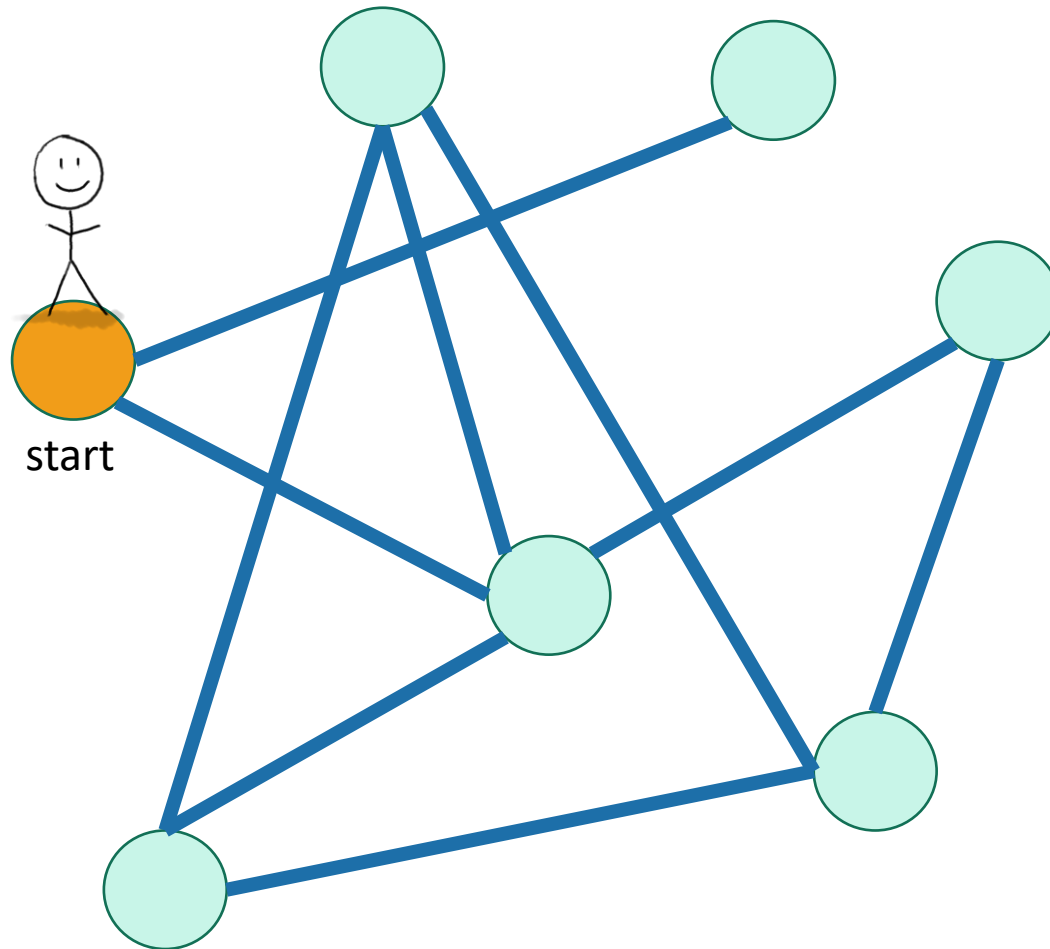





Depth First Search



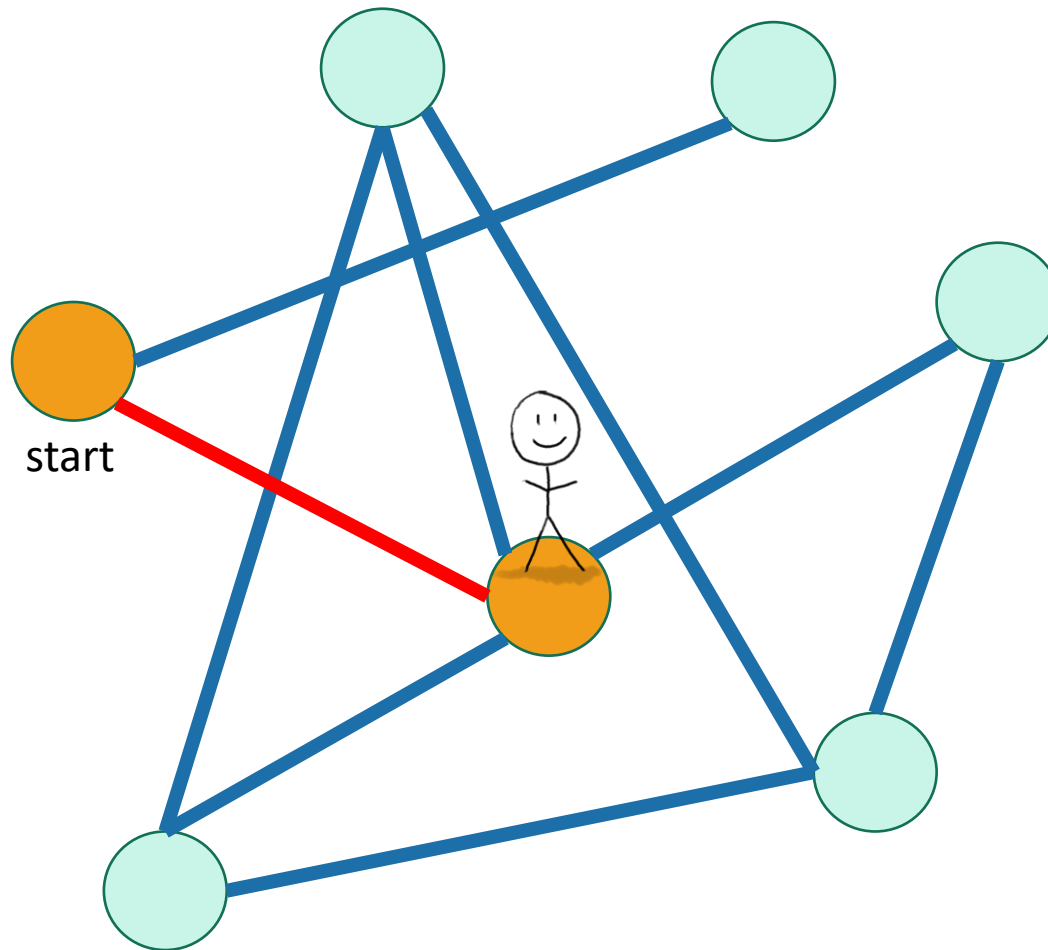
-  Not been there yet
-  Been there, haven't explored all the paths out.
-  Been there, have explored all the paths out.




Depth First Search



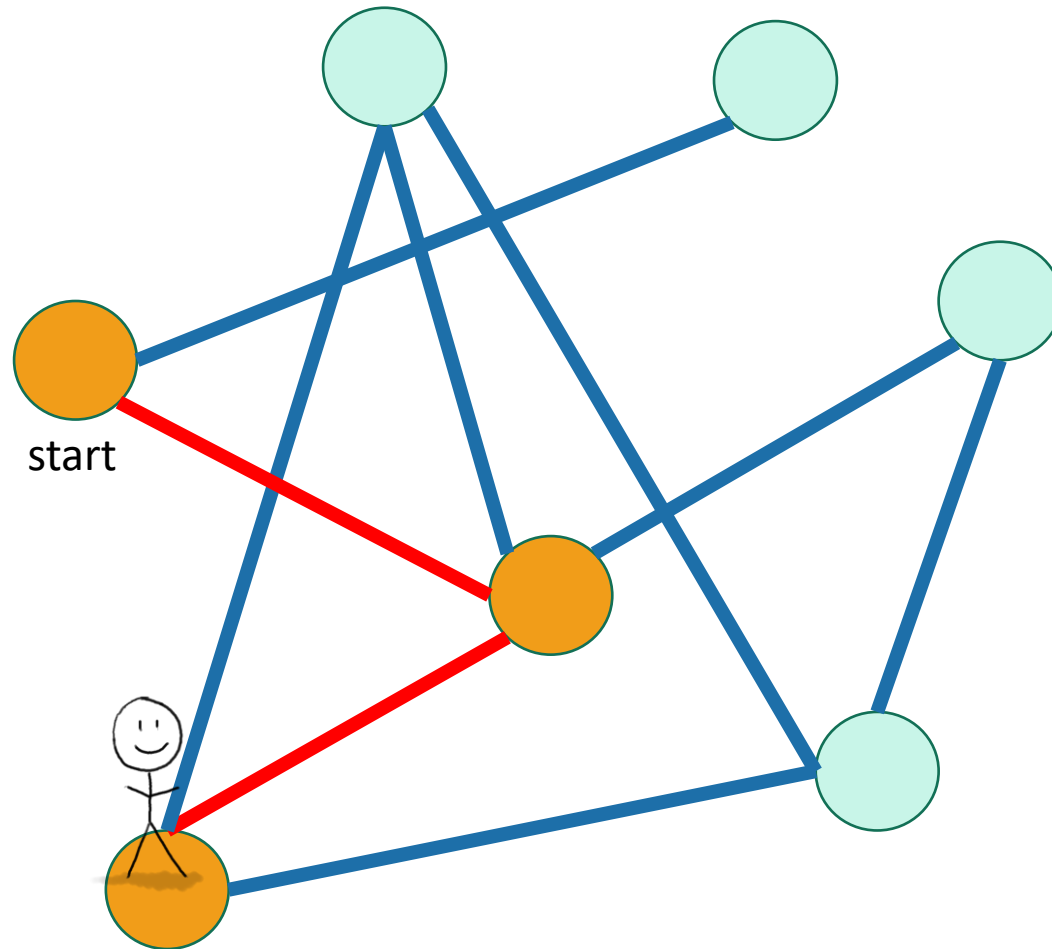
-  Not been there yet
-  Been there, haven't explored all the paths out.
-  Been there, have explored all the paths out.




Depth First Search



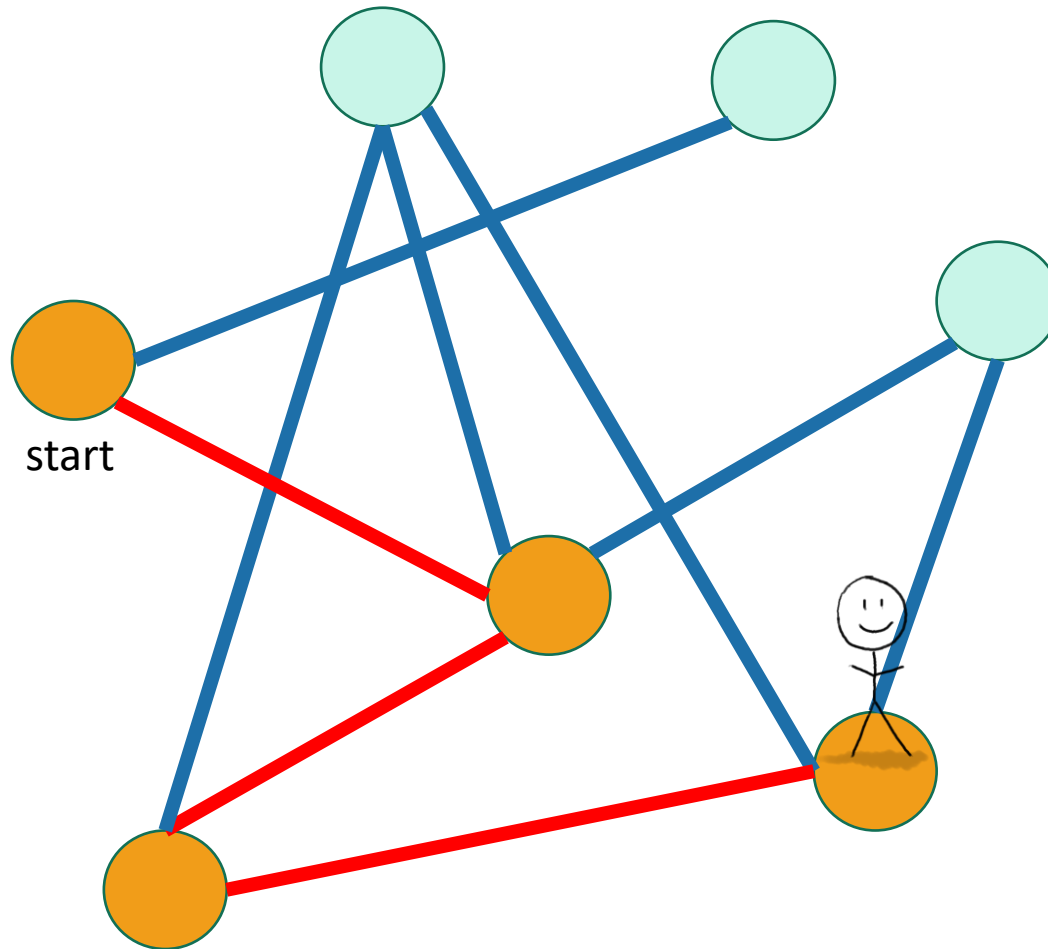
-  Not been there yet
-  Been there, haven't explored all the paths out.
-  Been there, have explored all the paths out.




Depth First Search



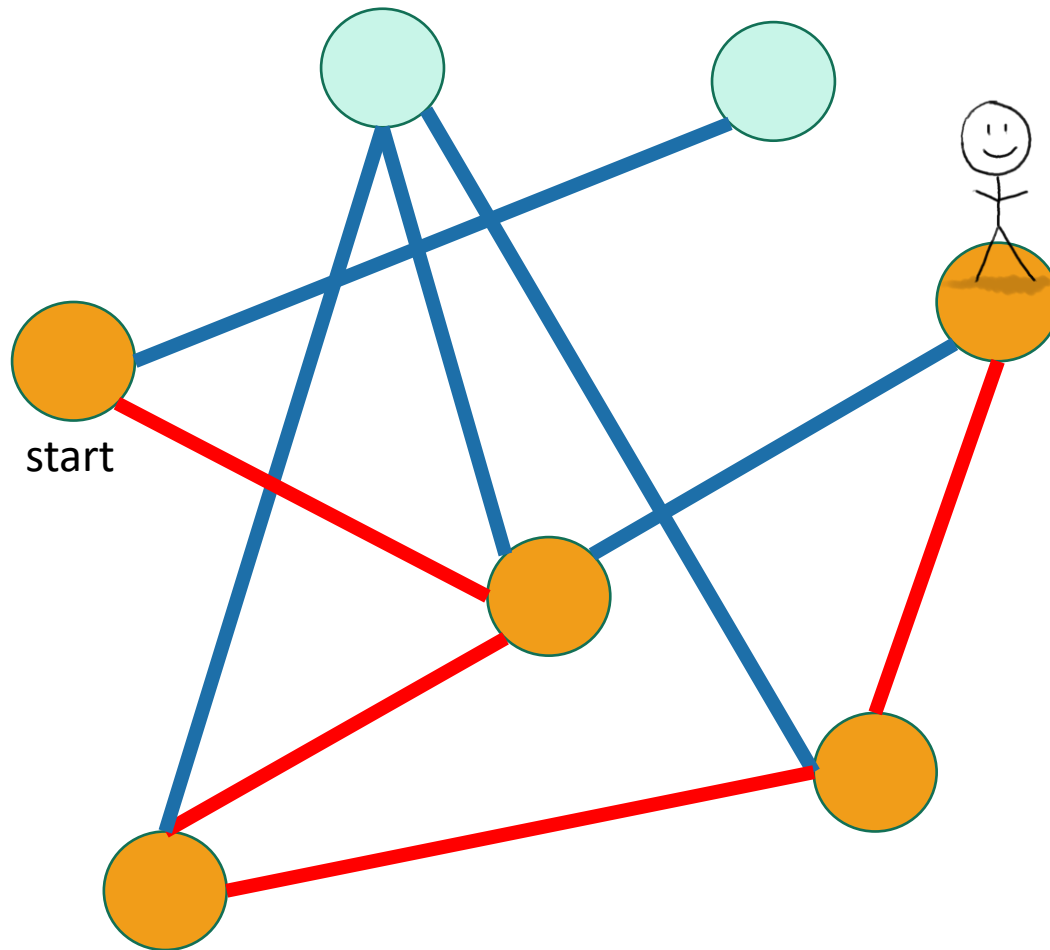
-  Not been there yet
-  Been there, haven't explored all the paths out.
-  Been there, have explored all the paths out.




Depth First Search



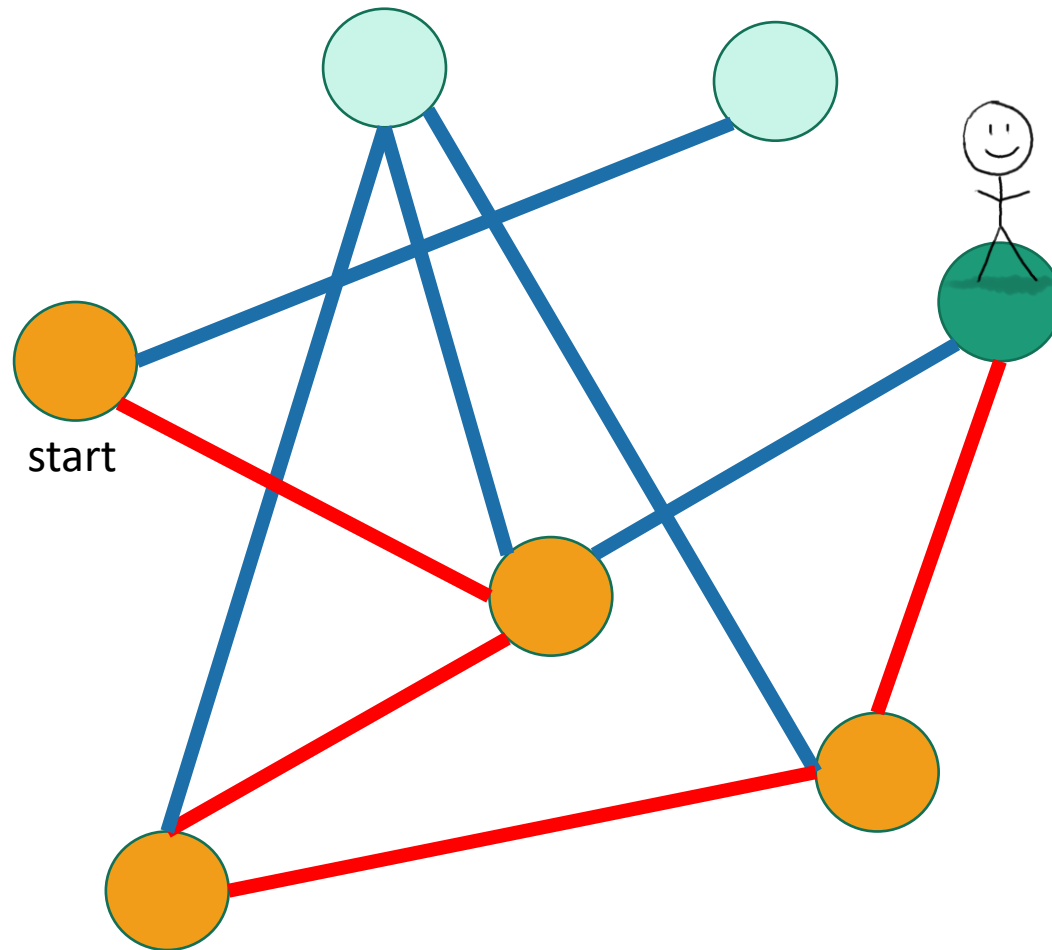
-  Not been there yet
-  Been there, haven't explored all the paths out.
-  Been there, have explored all the paths out.




Depth First Search



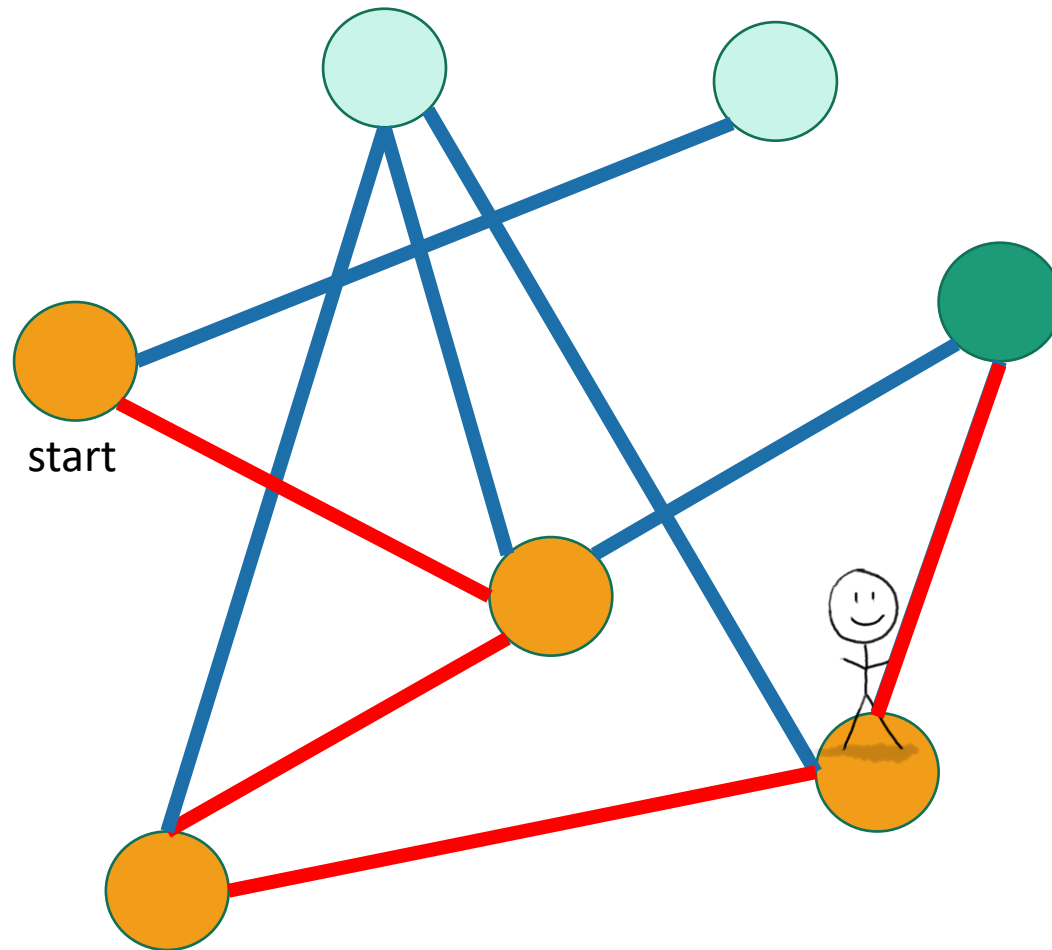
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Depth First Search



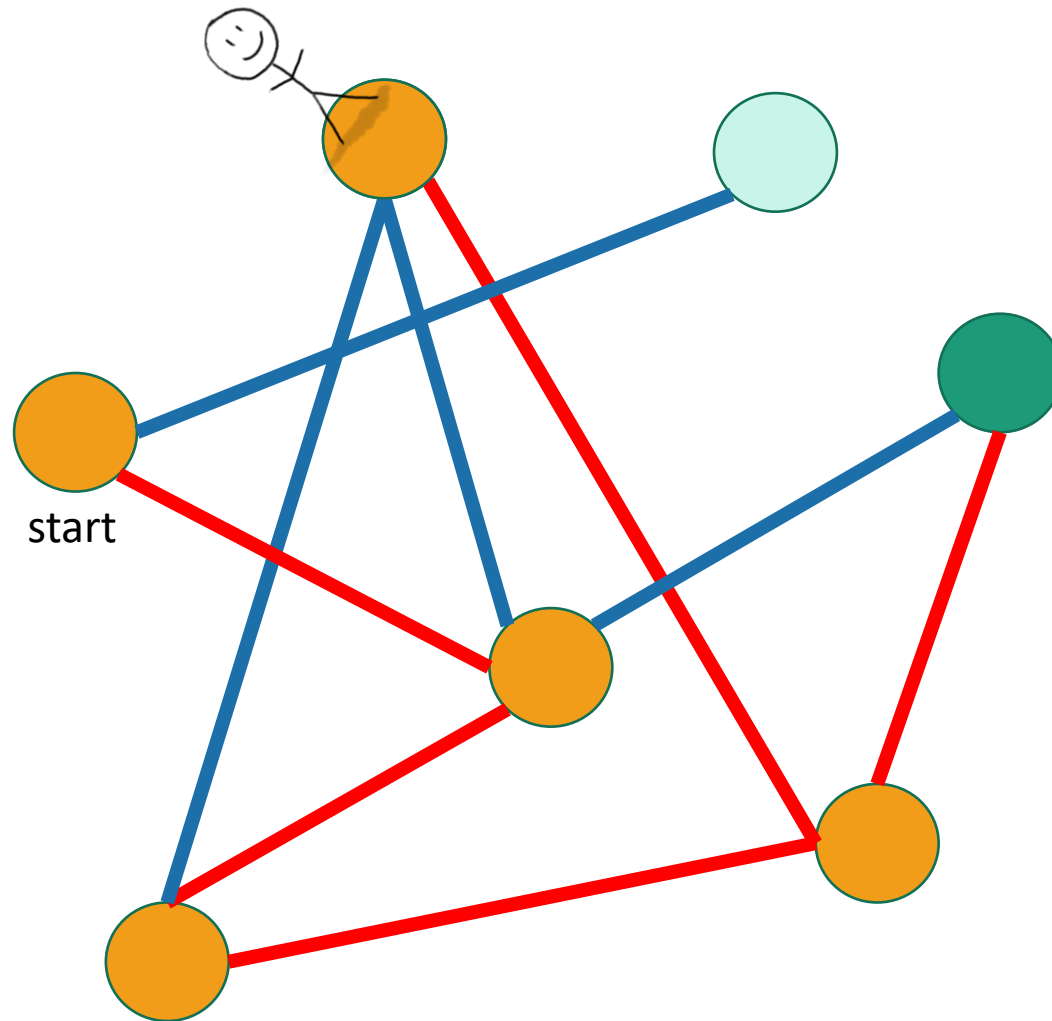
-  Not been there yet
-  Been there, haven't explored all the paths out.
-  Been there, have explored all the paths out.




Depth First Search



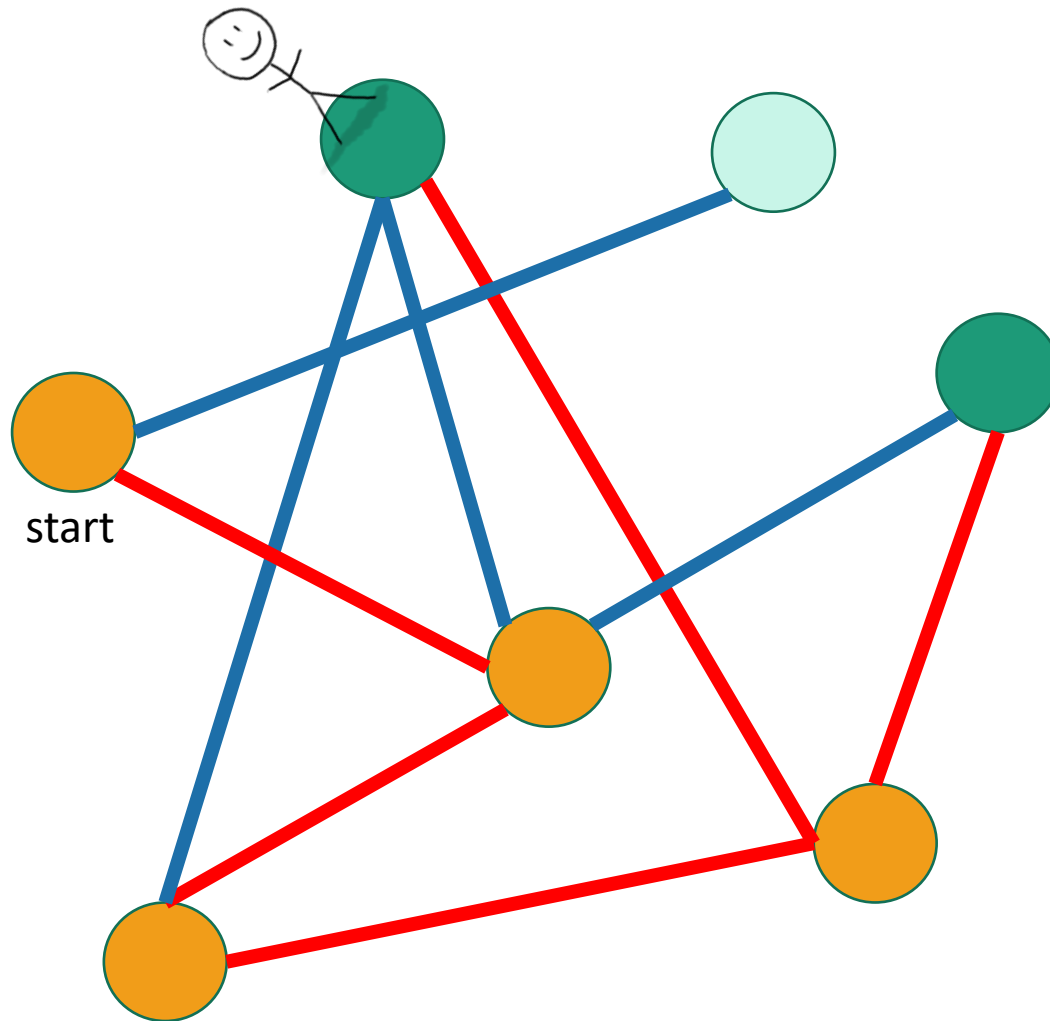
-  Not been there yet
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Depth First Search



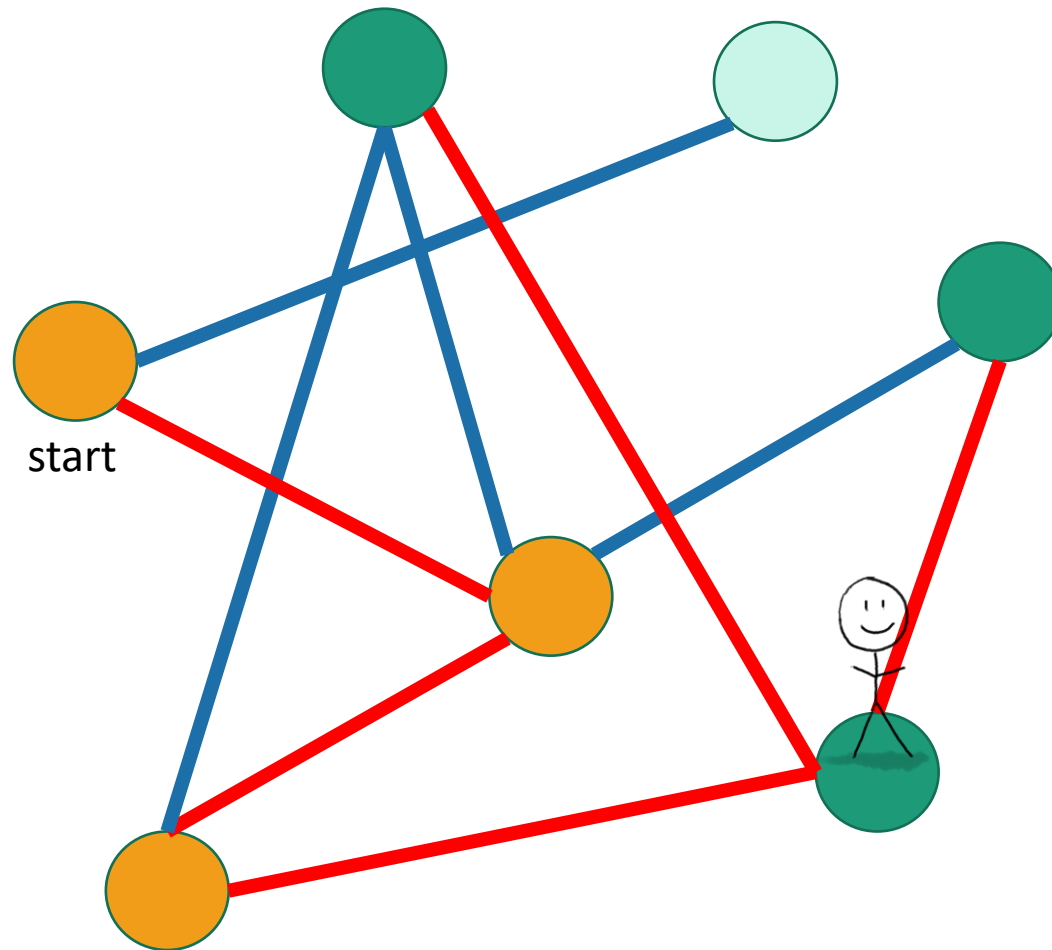
-  Not been there yet
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Depth First Search



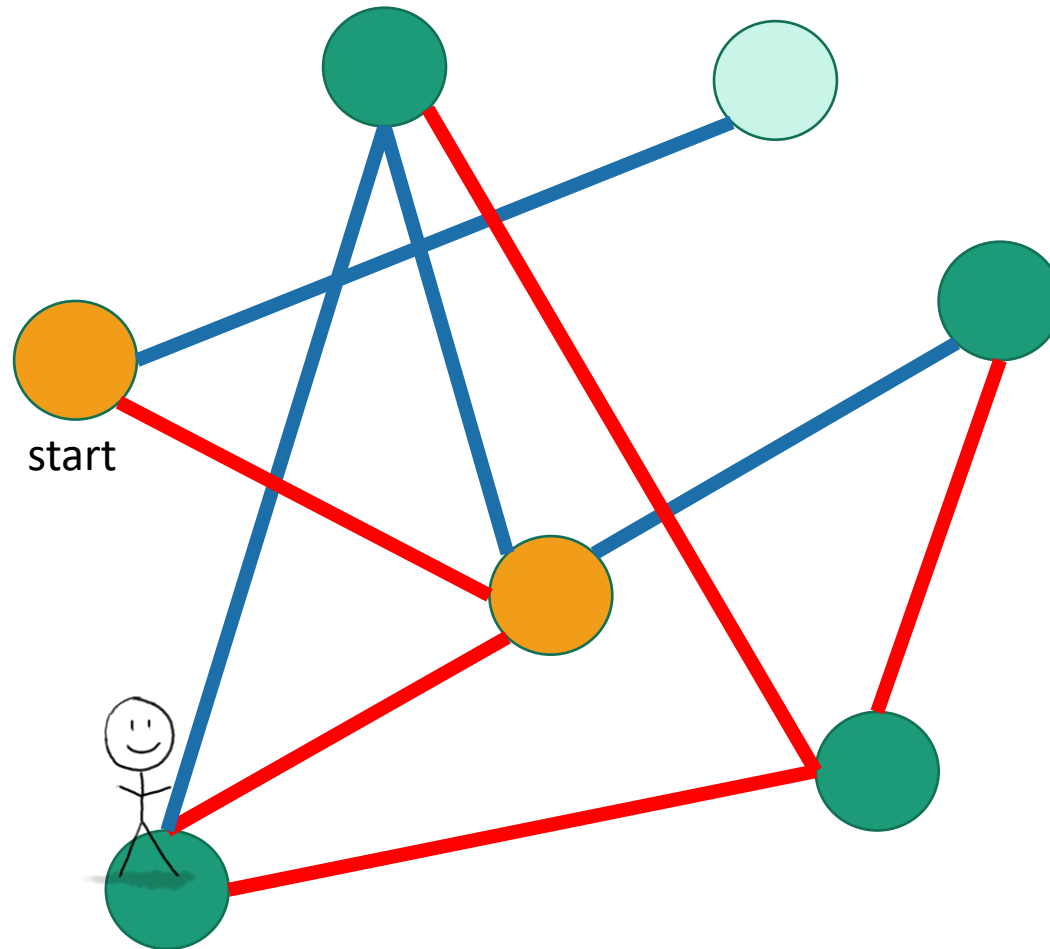
-  Not been there yet
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Depth First Search



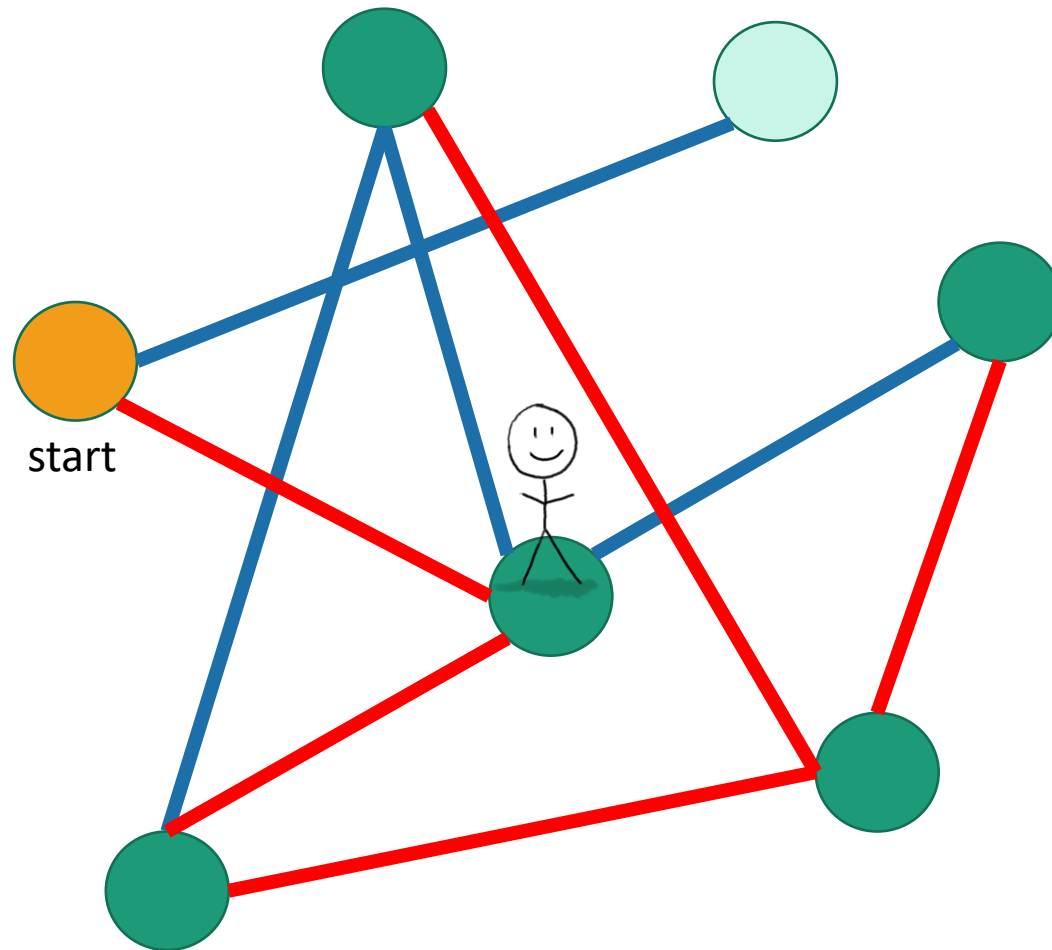
-  Not been there yet
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Depth First Search



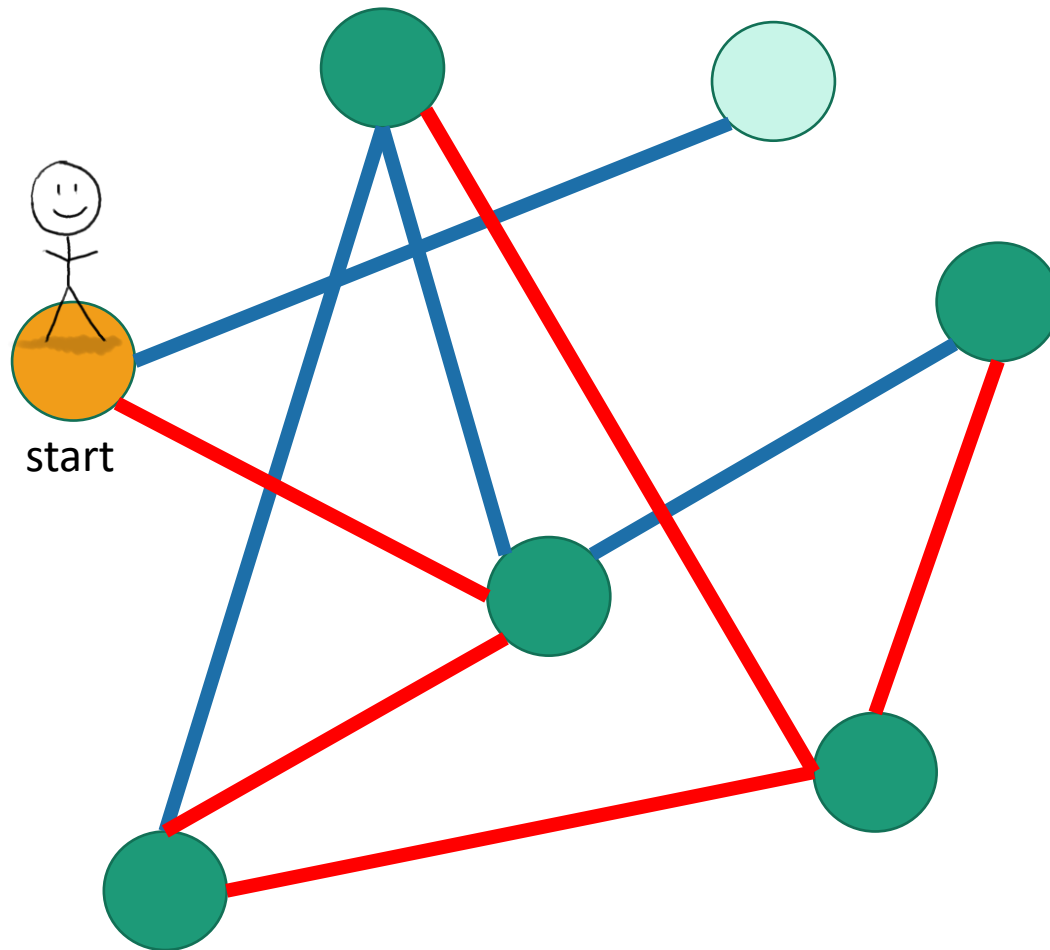
- Not been there yet
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Depth First Search



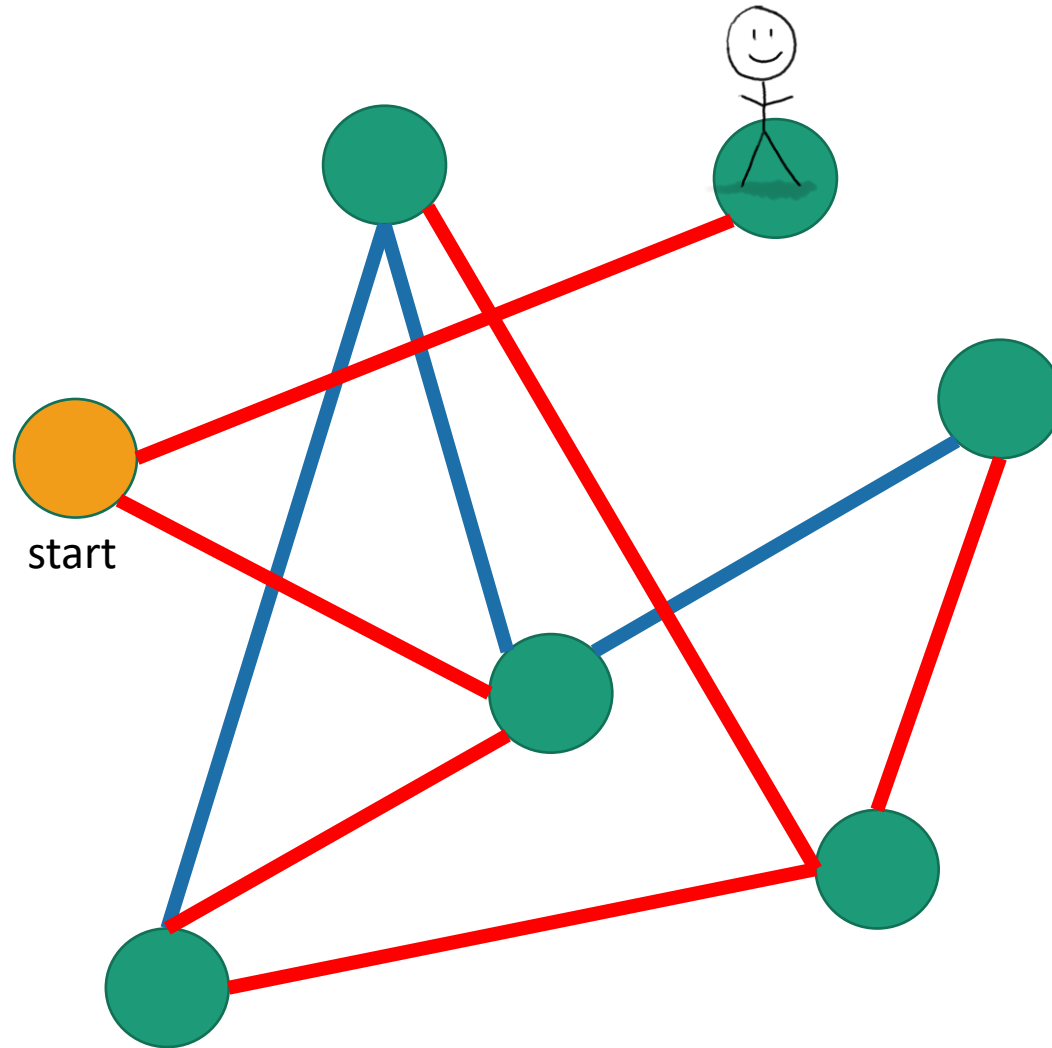
-  Not been there yet
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Depth First Search



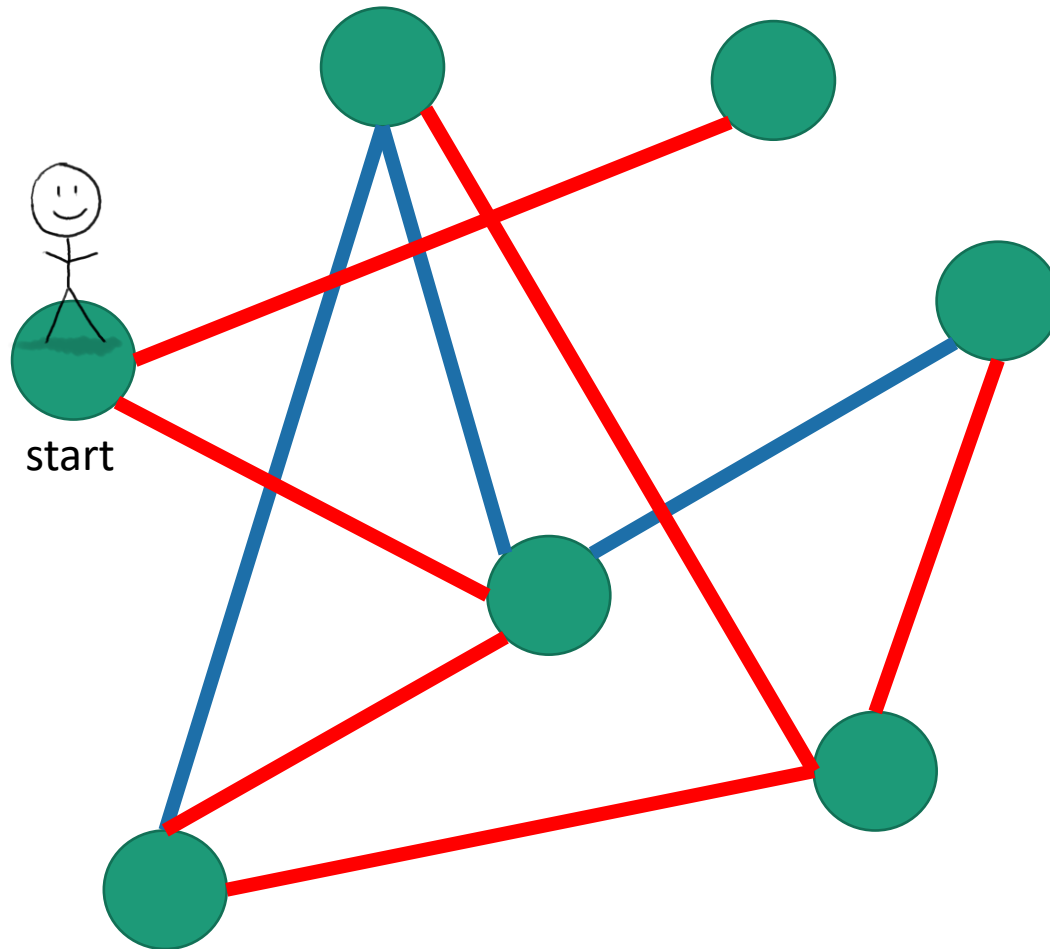
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Depth First Search



- Not been there yet
- Been there, haven't explored all the paths out.
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Depth First Search



- Not been there yet
- Been there, haven't explored all the paths out.
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Depth First Search

Pseudocode

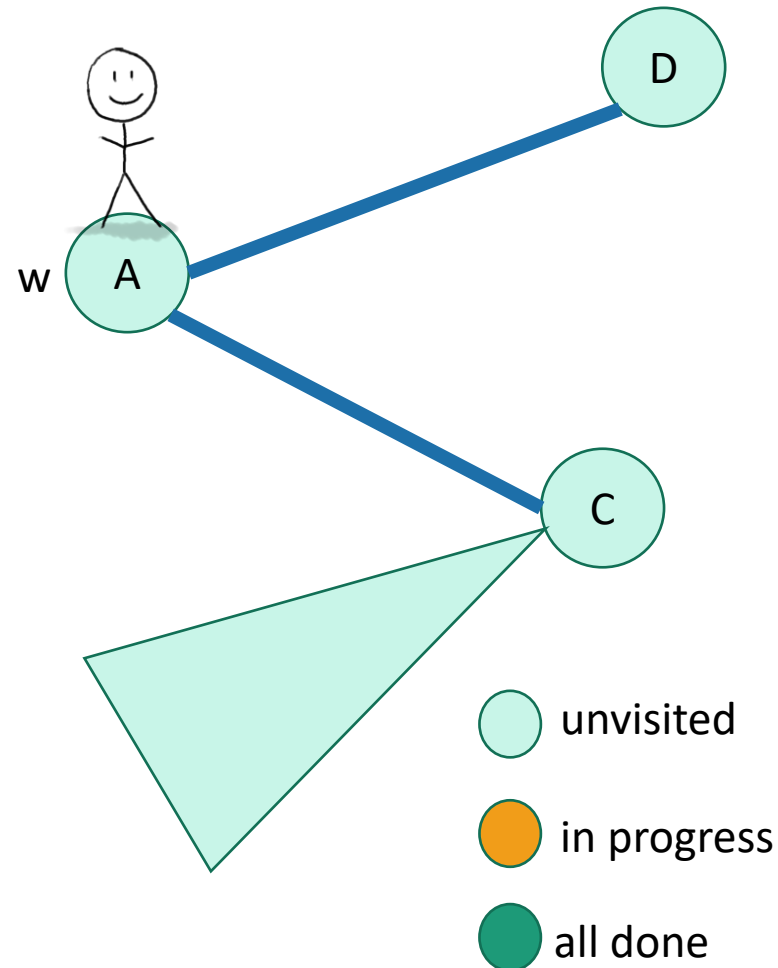
- Each vertex keeps track of whether it is:
 - Unvisited 
 - In progress 
 - All done 
- Each vertex will also keep track of:
 - The time we **first enter it**.
 - The time we finish with it and mark it **all done**.



You might have seen other ways to implement DFS than what we are about to go through. This way has more bookkeeping – the bookkeeping will be useful later!

Depth First Search

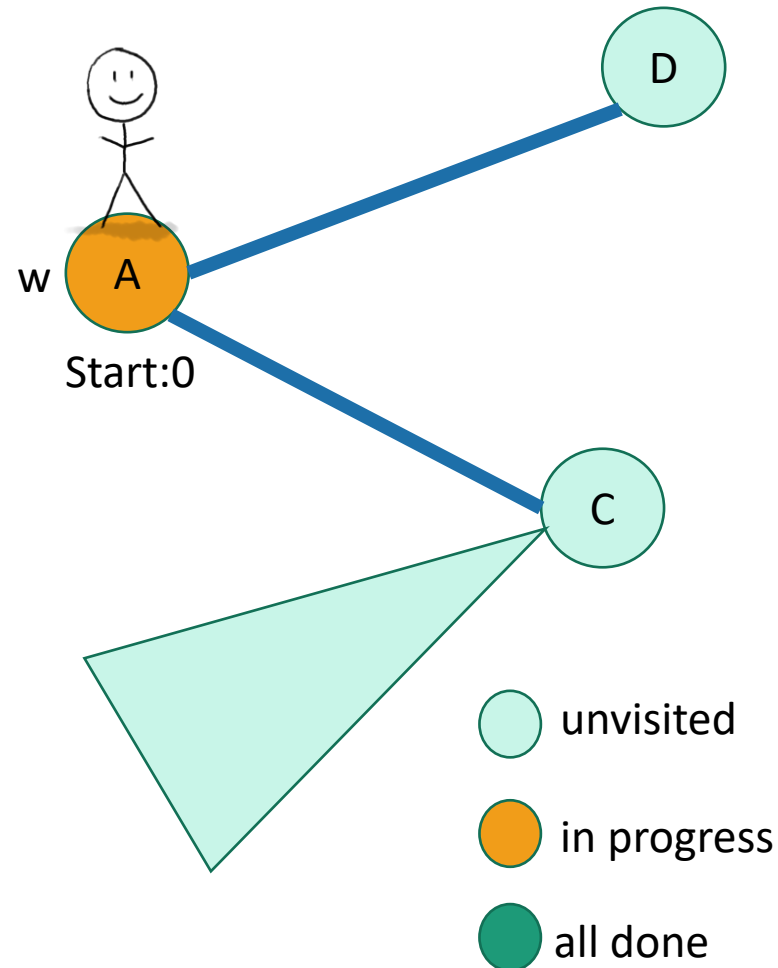
currentTime = 0



- **DFS**(w, currentTime):
 - w.startTime = currentTime
 - currentTime ++
 - Mark w as **in progress**.
 - **for** v in w.neighbors:
 - **if** v is **unvisited**:
 - currentTime = **DFS**(v, currentTime)
 - currentTime ++
 - w.finishTime = currentTime
 - Mark w as **all done**
 - **return** currentTime

Depth First Search

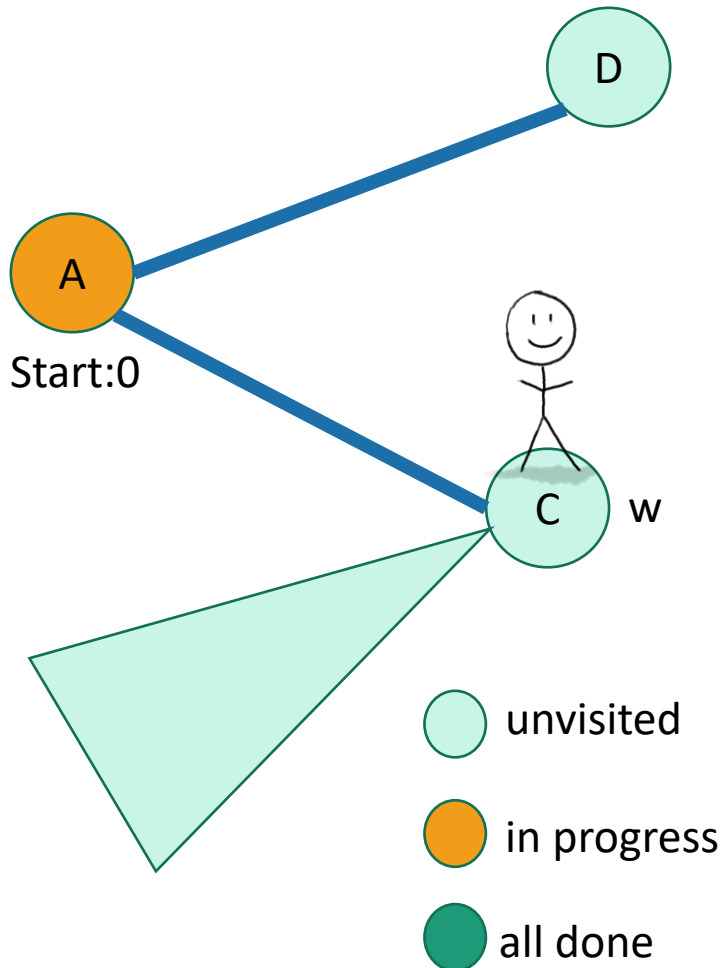
currentTime = 1



- **DFS**(w, currentTime):
 - w.startTime = currentTime
 - currentTime ++
 - Mark w as **in progress**.
 - **for** v in w.neighbors:
 - **if** v is **unvisited**:
 - currentTime = **DFS**(v, currentTime)
 - currentTime ++
 - w.finishTime = currentTime
 - Mark w as **all done**
 - **return** currentTime

Depth First Search

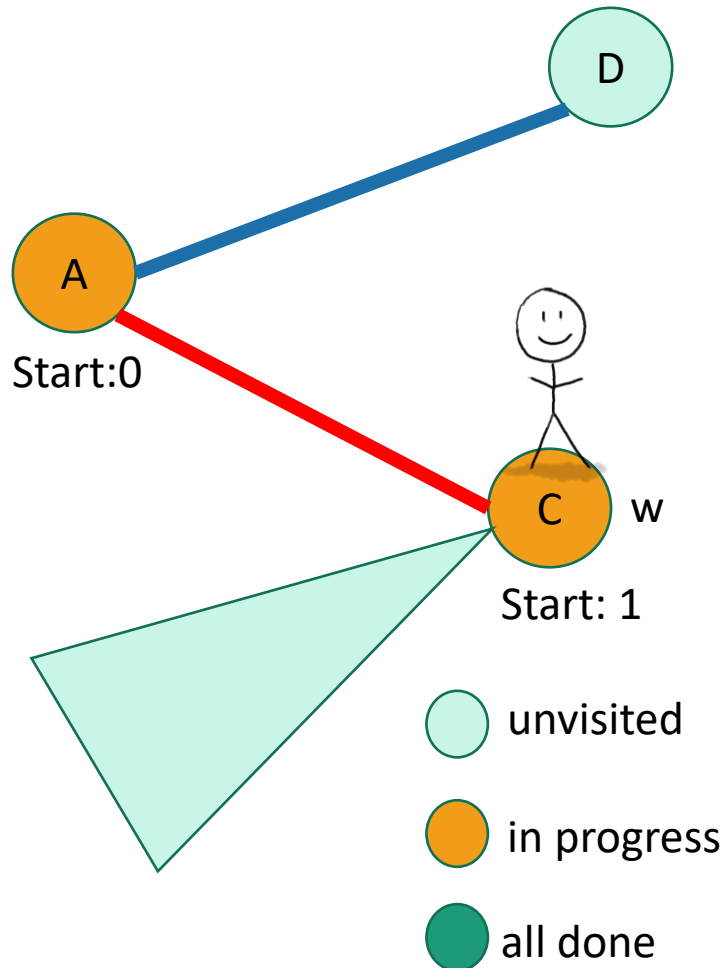
currentTime = 1



- **DFS(w, currentTime):**
 - w.startTime = currentTime
 - currentTime ++
 - Mark w as **in progress**.
 - **for** v in w.neighbors:
 - **if** v is **unvisited**:
 - currentTime = **DFS(v, currentTime)**
 - currentTime ++
 - w.finishTime = currentTime
 - Mark w as **all done**
 - **return** currentTime

Depth First Search

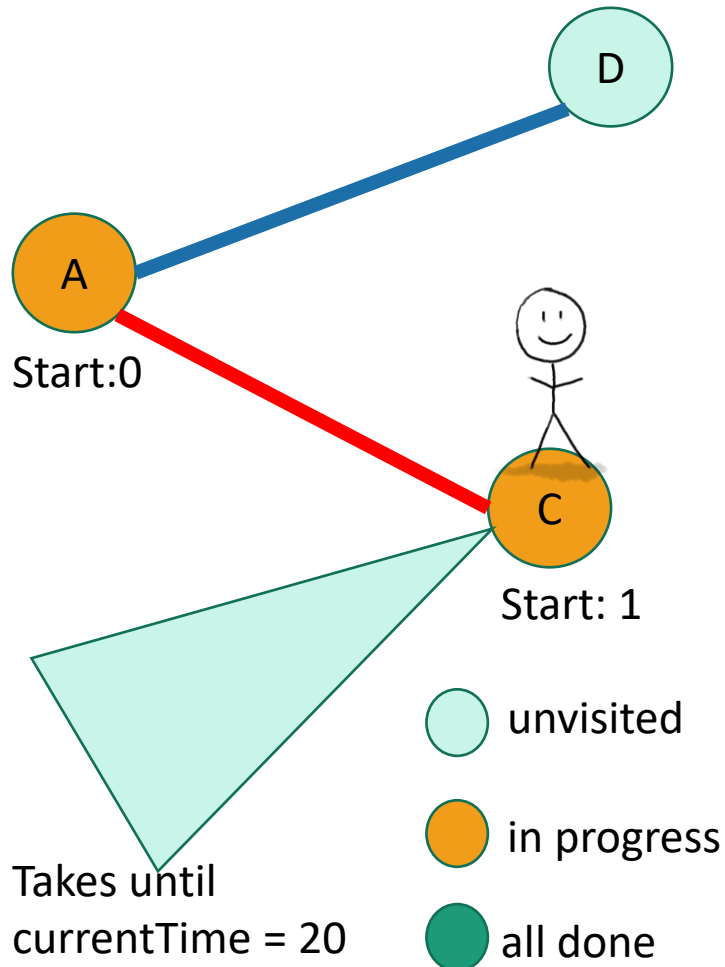
currentTime = 2



- **DFS**(w, currentTime):
 - w.startTime = currentTime
 - currentTime ++
 - Mark w as **in progress**.
 - **for** v in w.neighbors:
 - **if** v is **unvisited**:
 - currentTime = **DFS**(v, currentTime)
 - currentTime ++
 - w.finishTime = currentTime
 - Mark w as **all done**
 - **return** currentTime

Depth First Search

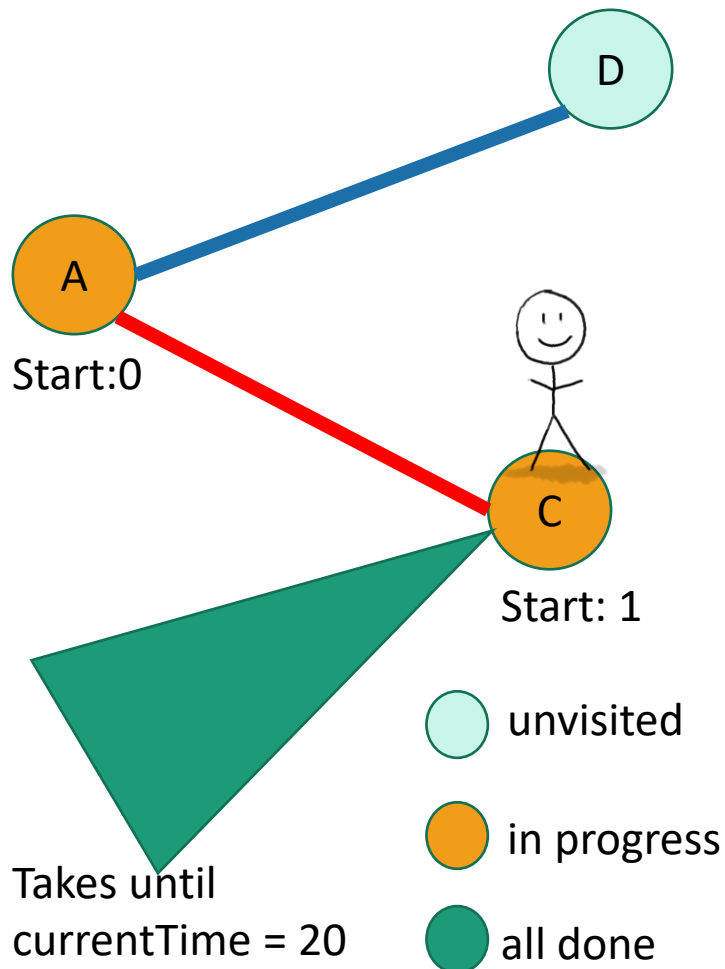
currentTime = 20



- **DFS**(w, currentTime):
 - w.startTime = currentTime
 - currentTime ++
 - Mark w as **in progress**.
 - **for** v in w.neighbors:
 - **if** v is **unvisited**:
 - currentTime = **DFS**(v, currentTime)
 - currentTime ++
 - w.finishTime = currentTime
 - Mark w as **all done**
 - **return** currentTime

Depth First Search

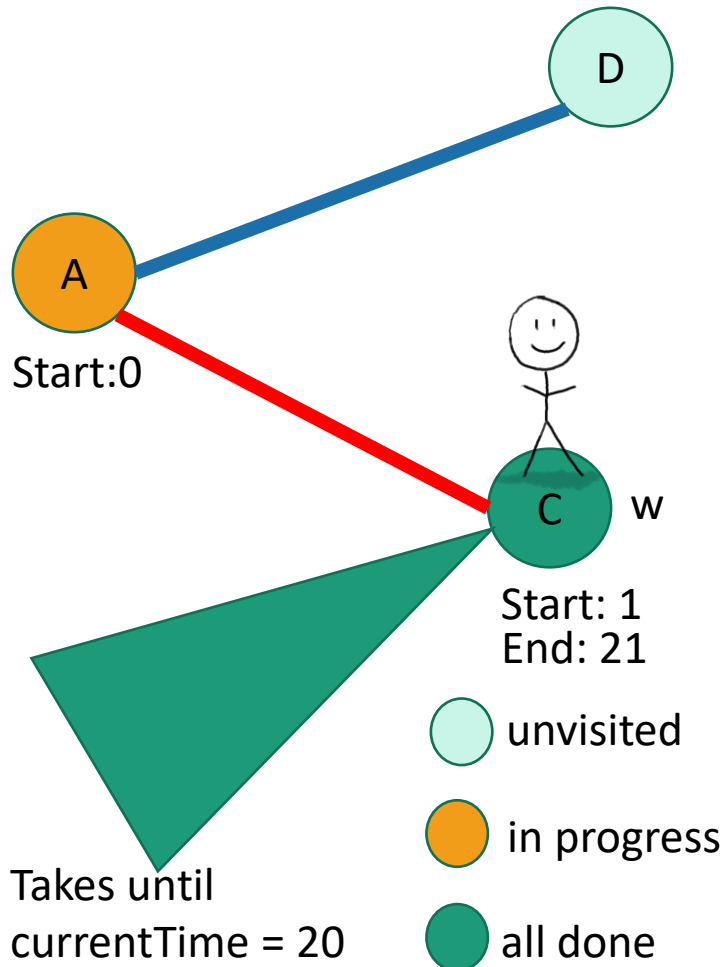
currentTime = 21



- **DFS**(w, currentTime):
 - w.startTime = currentTime
 - currentTime ++
 - Mark w as **in progress**.
 - **for** v in w.neighbors:
 - **if** v is **unvisited**:
 - currentTime = **DFS**(v, currentTime)
 - currentTime ++
 - w.finishTime = currentTime
 - Mark w as **all done**
 - **return** currentTime

Depth First Search

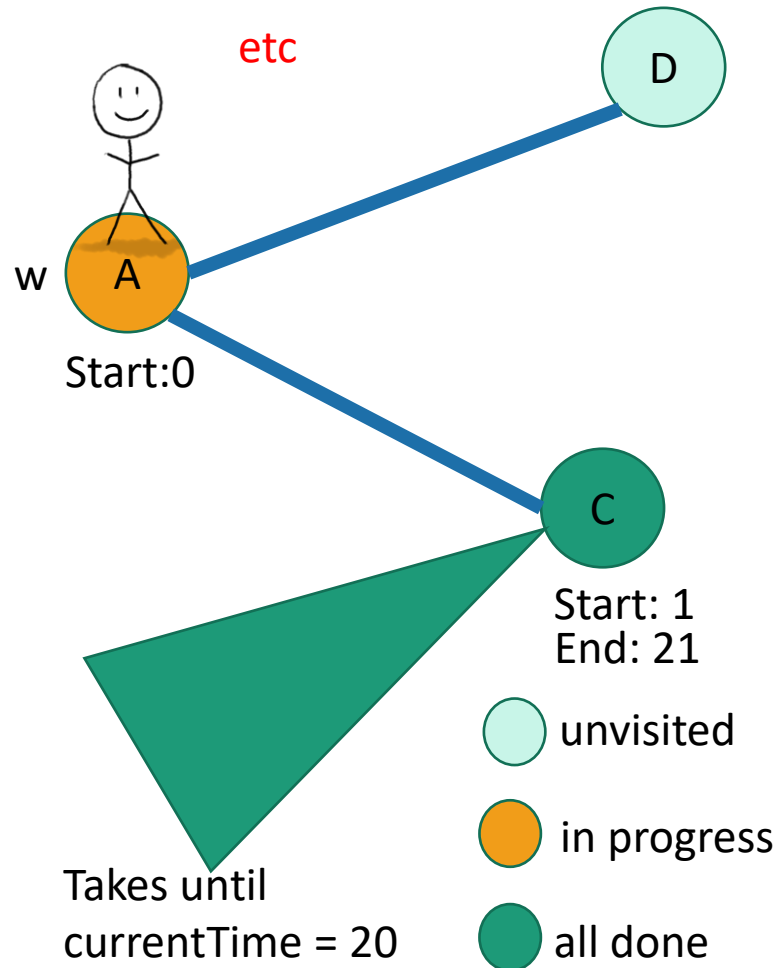
currentTime = 21



- **DFS(w, currentTime):**
 - w.startTime = currentTime
 - currentTime ++
 - Mark w as **in progress**.
 - **for** v in w.neighbors:
 - **if** v is **unvisited**:
 - currentTime
= **DFS(v, currentTime)**
 - currentTime ++
 - w.finishTime = currentTime
 - Mark w as **all done**
 - **return** currentTime

Depth First Search

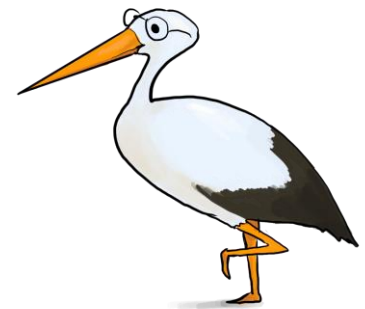
currentTime = 22



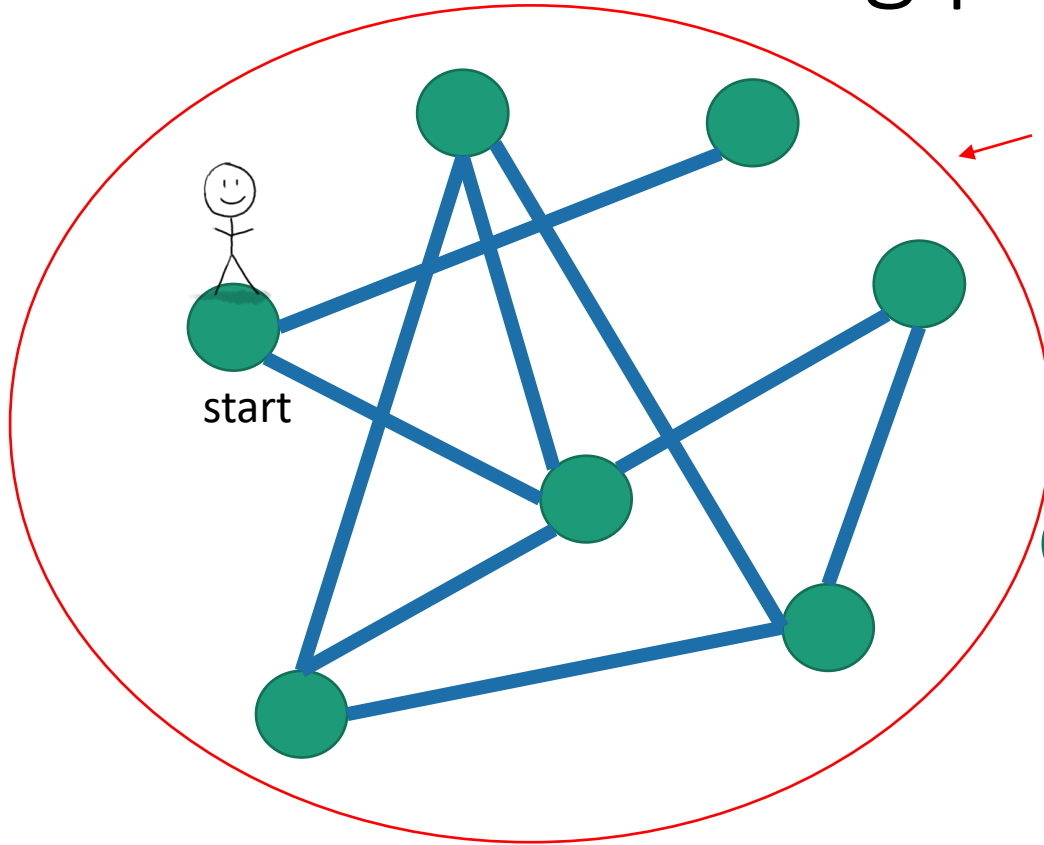
- **DFS(w, currentTime):**
 - w.startTime = currentTime
 - currentTime ++
 - Mark w as **in progress**.
 - **for** v in w.neighbors:
 - **if** v is **unvisited**:
 - currentTime
= **DFS(v, currentTime)**
 - currentTime ++
 - w.finishTime = currentTime
 - Mark w as **all done**
 - **return** currentTime

Fun exercise

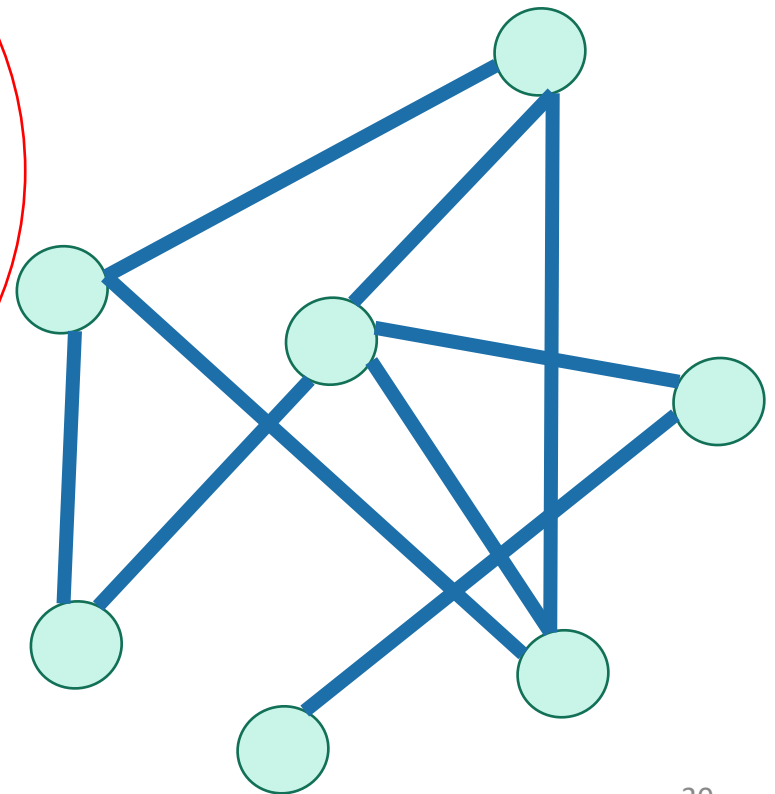
- Write pseudocode for an iterative version of DFS.



DFS finds all the nodes reachable from the starting point



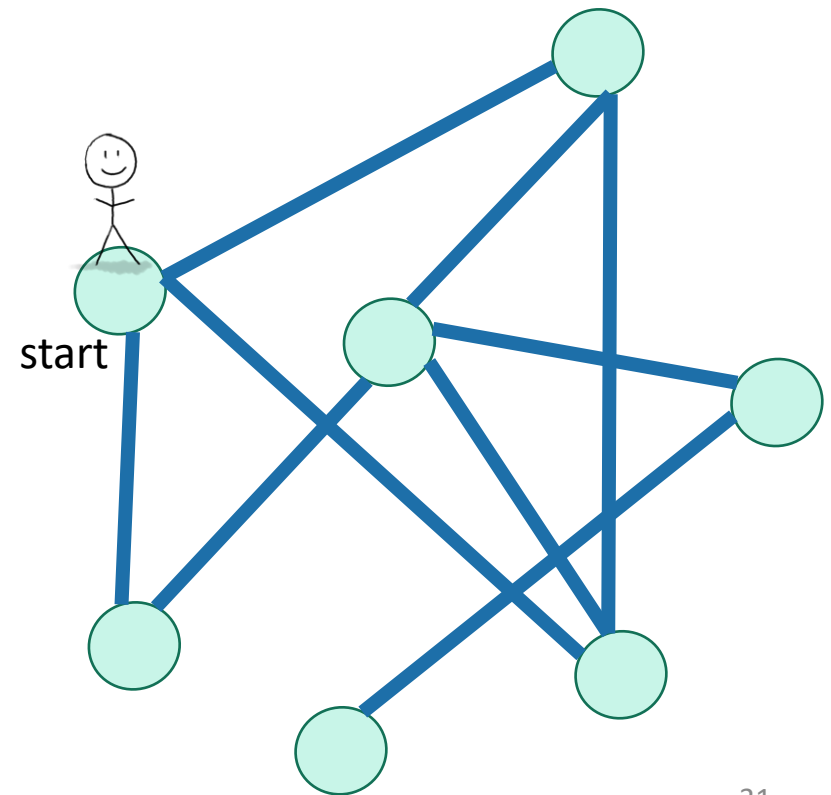
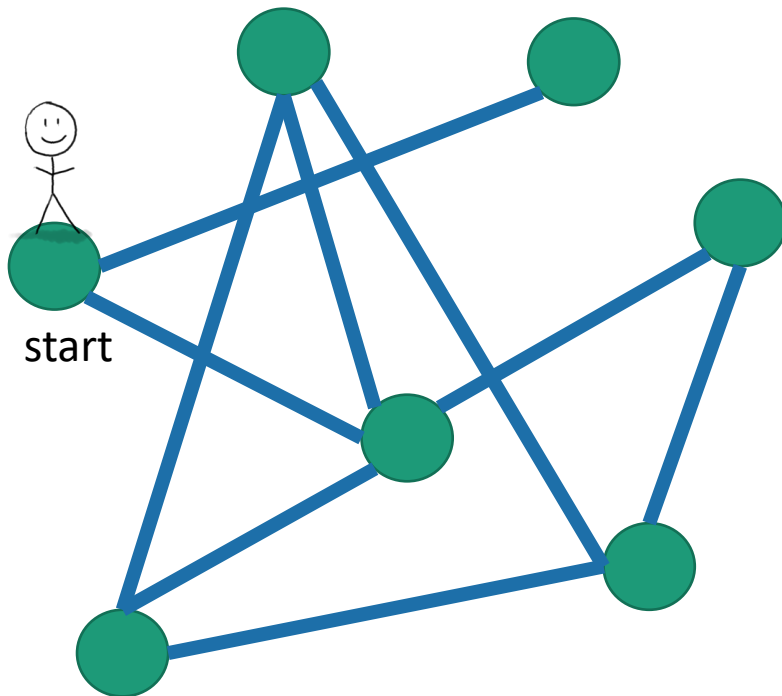
In an undirected graph, this is called a **connected component**.



One application of DFS: finding connected components.

To explore the whole graph

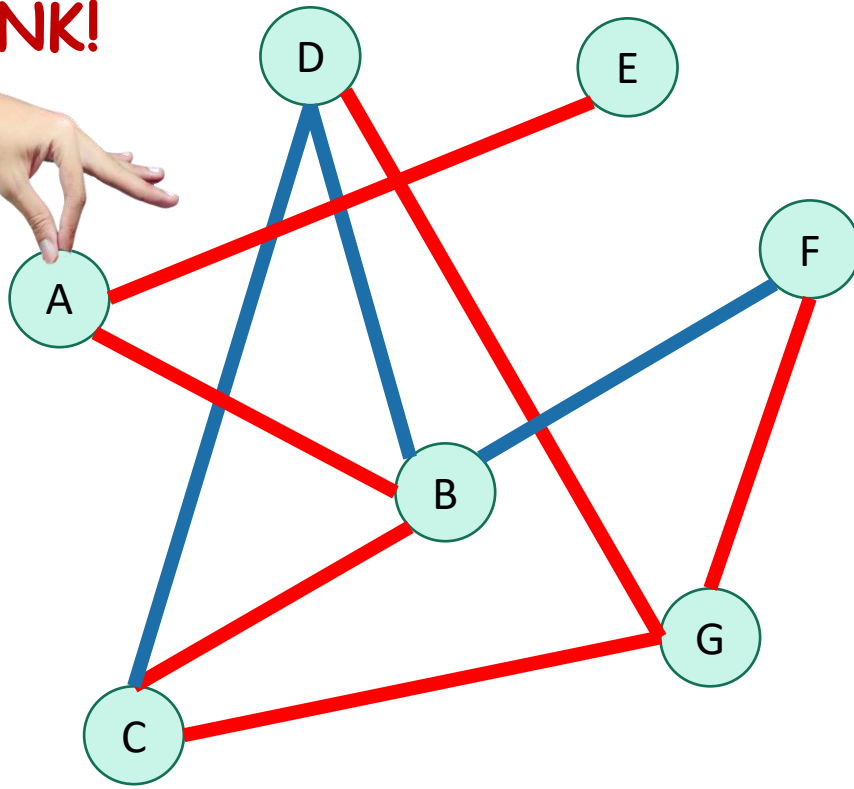
- Do it repeatedly!



Why is it called depth-first?

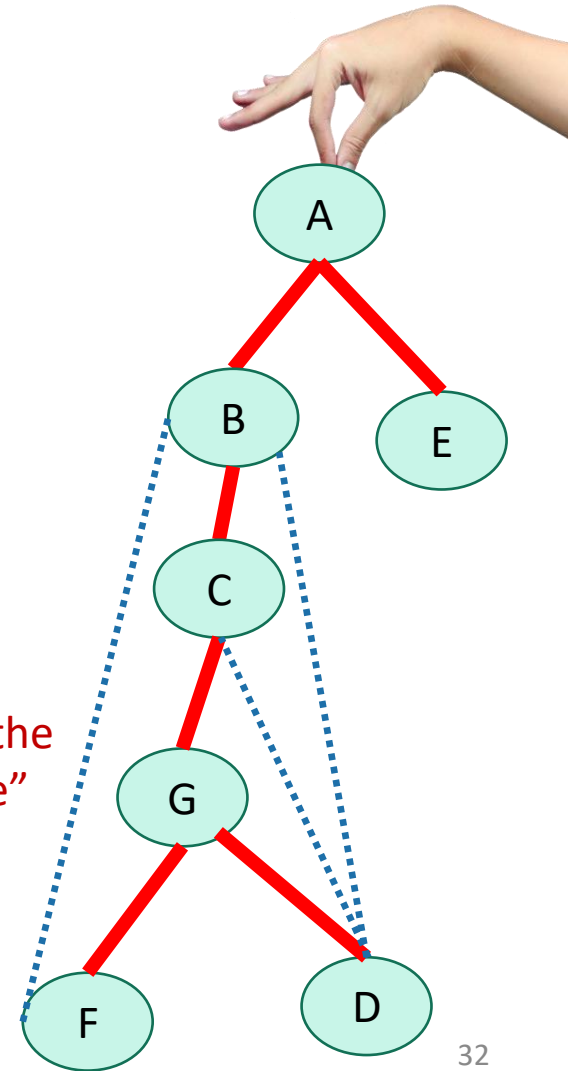
- We are implicitly building a tree:

YOINK!



- First, we go as deep as we can.

Call this the
"DFS tree"



Running time

To explore **just the connected component** we started in

- We look at each edge at most twice.
 - Once from each of its endpoints
- And basically we don't do anything else.
- So...



$O(m)$

Running time

To explore just the connected component we started in

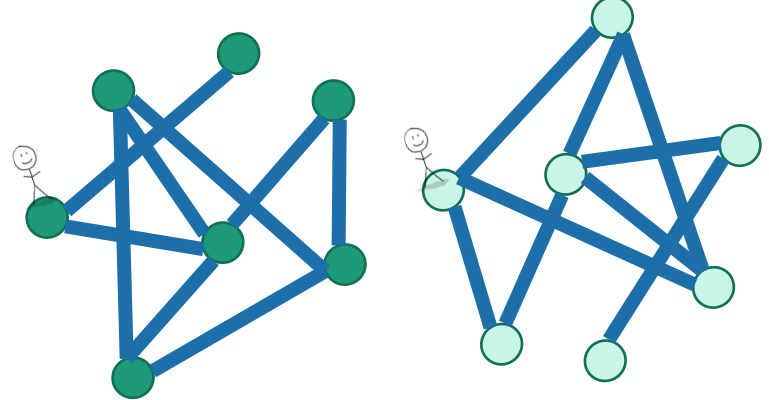
- Assume we are using the linked-list format for G .
- Say $C = (V', E')$ is a connected component.
- We visit each vertex in C exactly once.
 - Here, “visit” means “call DFS on”
- At each vertex w , we:
 - Do some book-keeping: $O(1)$
 - Loop over w 's neighbors and check if they are visited (and then potentially make a recursive call): $O(1)$ per neighbor or $O(\deg(w))$ total.
- Total time:
 - $\sum_{w \in V'} (O(\deg(w)) + O(1))$
 - $= O(|E'| + |V'|)$
 - $= O(|E'|)$



In a connected graph,
 $|V'| \leq |E'| + 1$.

Running time

To explore **the whole graph**

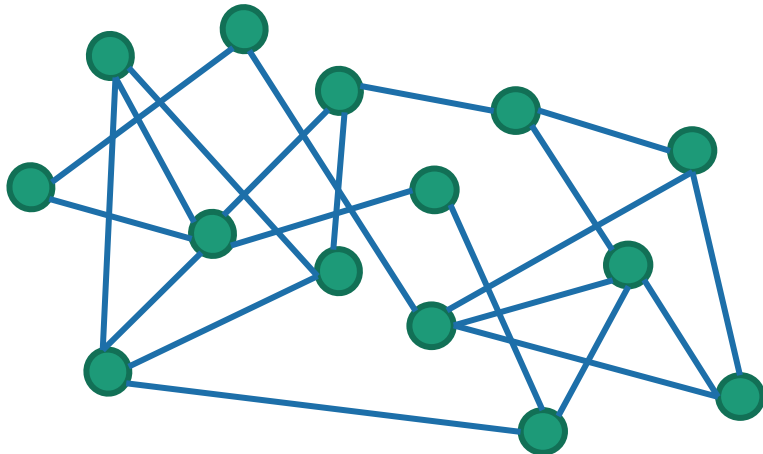


- Explore the connected components one-by-one.

- This takes time $O(n + m)$

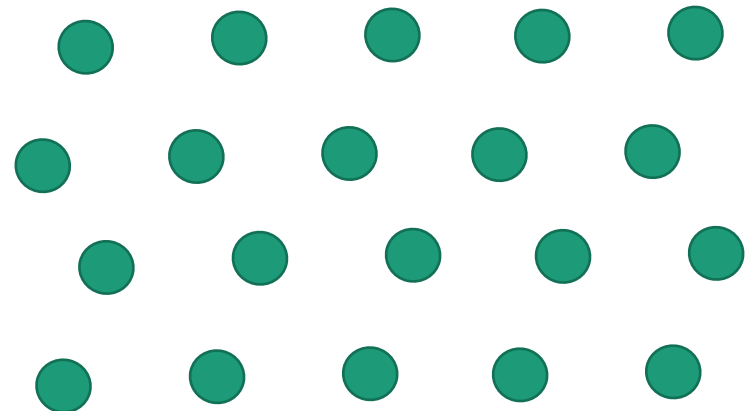
- Same computation as before:

$$\sum_{w \in V} (O(\deg(w)) + O(1)) = O(|E| + |V|) = O(n + m)$$



Here the running time is $O(m)$ like before

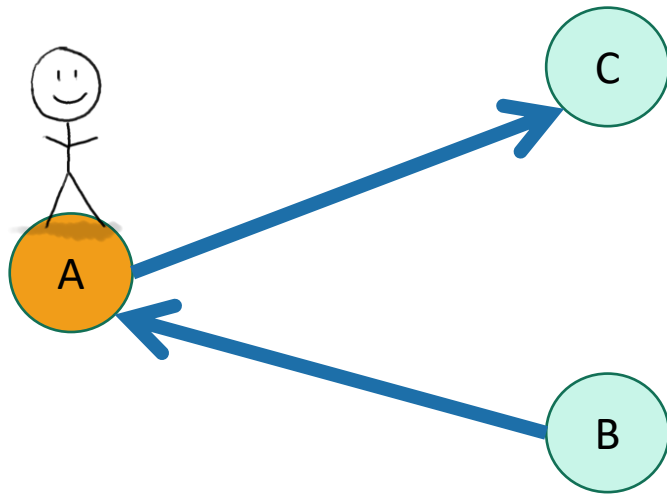
or



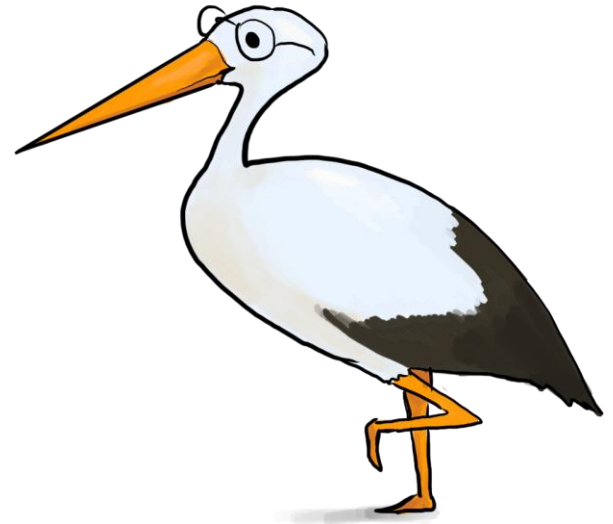
Here $m=0$ but it still takes time $O(n)$ to explore the graph.

You check:

DFS works fine on directed graphs too!

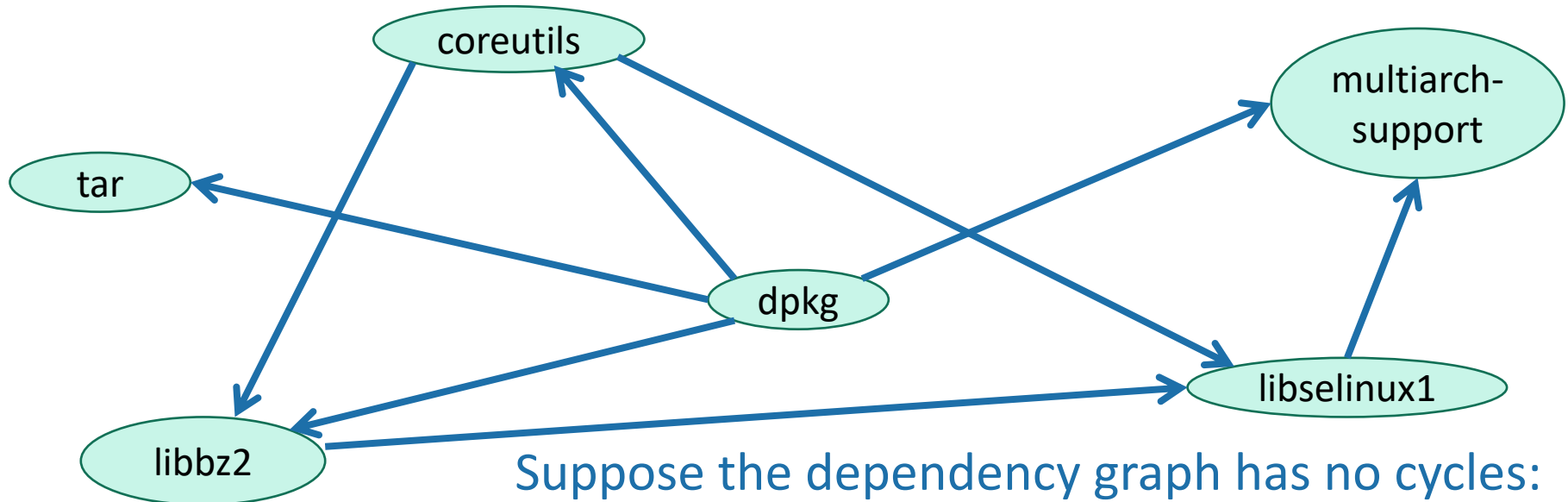


Only walk to C, not to B.



Application of DFS: topological sorting

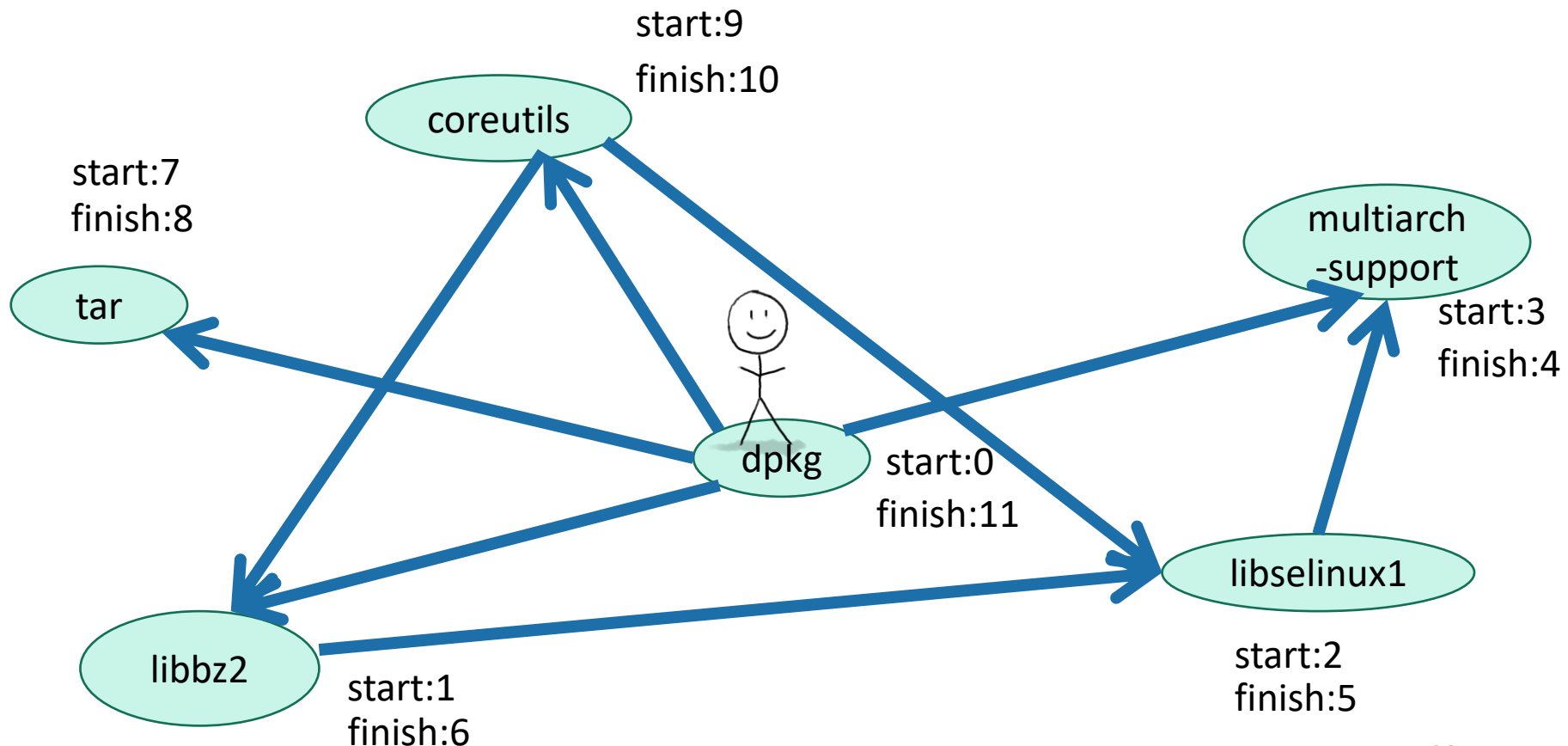
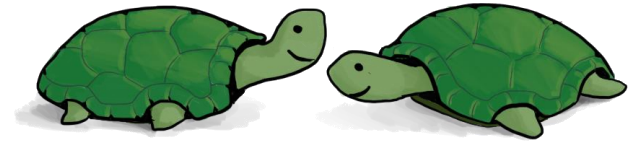
- Find an ordering of vertices so that all of the dependency requirements are met.
 - Aka, if v comes before w in the ordering, there is not an edge from w to v .



Suppose the dependency graph has no cycles:
it is a **Directed Acyclic Graph (DAG)**

Let's do DFS

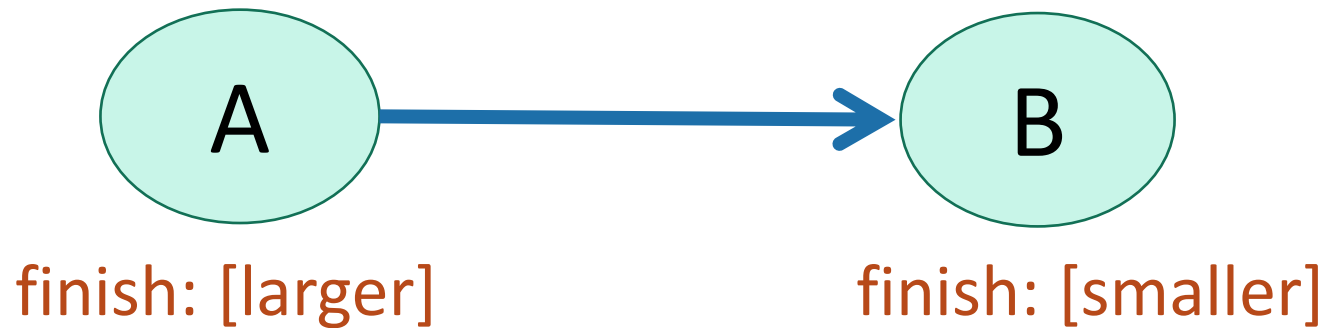
What do you notice about the finish times? Any ideas for how we should do topological sort?



Suppose the underlying
graph has no cycles

Finish times seem useful

Claim: In general, we'll always have:



To understand why, let's go back to that DFS tree.

A more general statement

(this holds even if there are cycles)

This is called the “parentheses theorem”

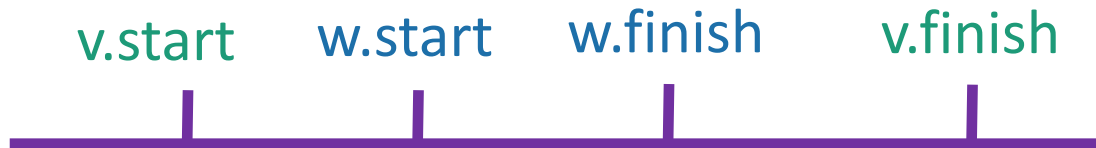
(check this statement carefully!)



- If v is a descendant of w in this tree:



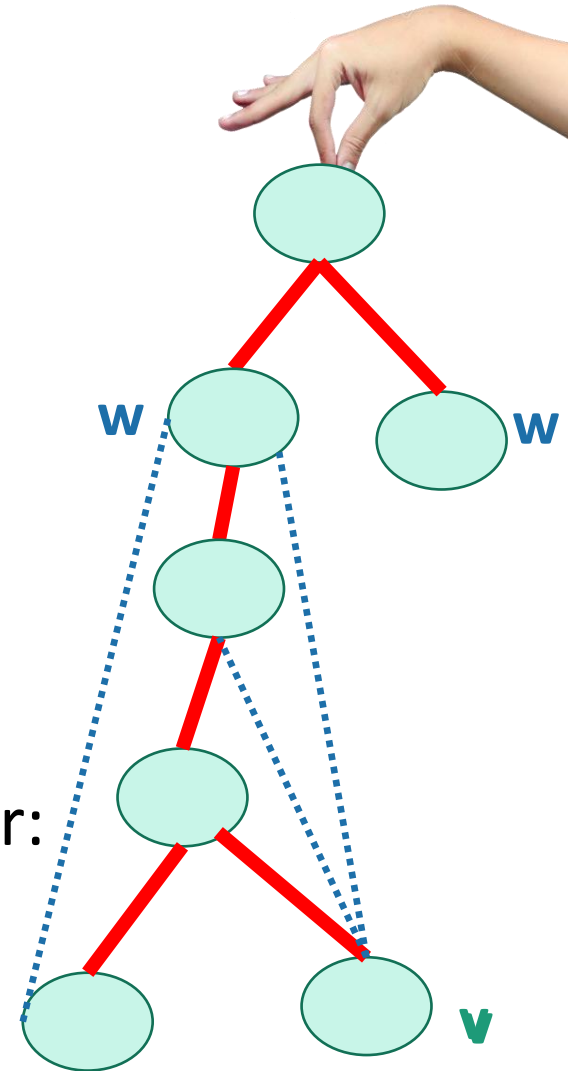
- If w is a descendant of v in this tree:



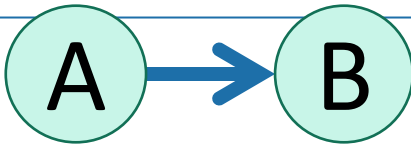
- If neither are descendants of each other:



(or the other way around)



So to prove this →

If  $A \rightarrow B$
Then $B.\text{finishTime} < A.\text{finishTime}$

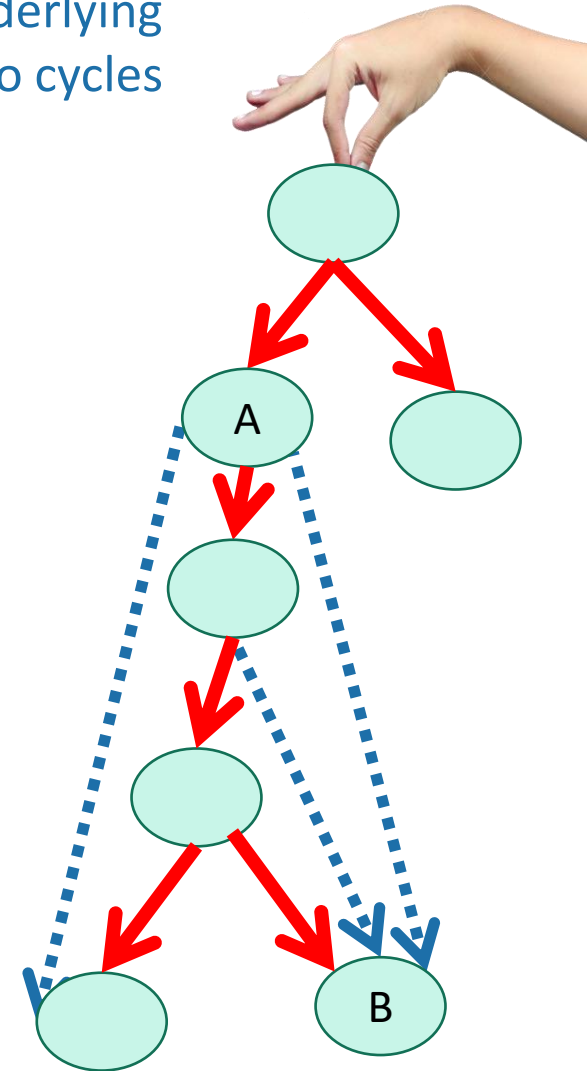
Suppose the underlying
graph has no cycles

- **Case 1:** B is a descendant of A in the DFS tree.

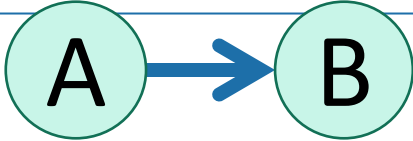
- Then



- aka, $B.\text{finishTime} < A.\text{finishTime}$.



So to prove this →

If 
Then $B.\text{finishTime} < A.\text{finishTime}$

Suppose the underlying
graph has no cycles

- **Case 2:** B is a **NOT** descendant of A in the DFS tree.

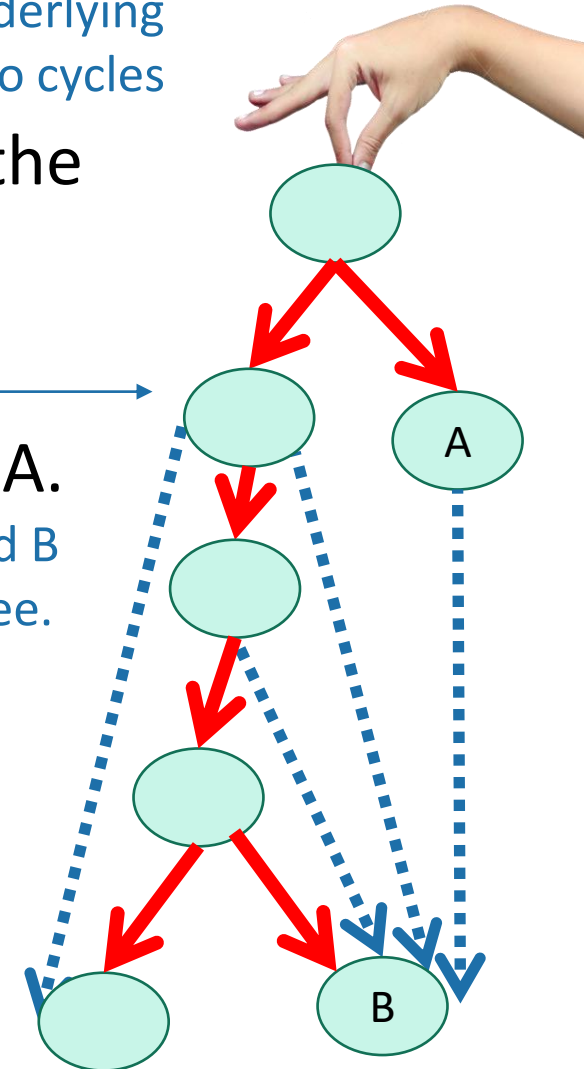
- Notice that A can't be a descendant of B or else there'd be a cycle; so it looks like this →

- Then we must have explored B before A.
 - Otherwise we would have gotten to B from A, and B would have been a descendant of A in the DFS tree.

- Then

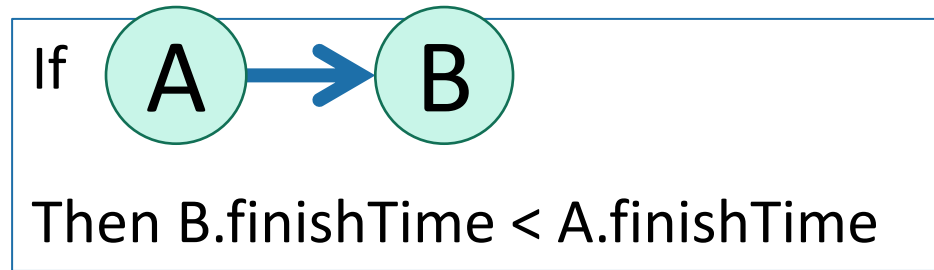


- aka, **$B.\text{finishTime} < A.\text{finishTime}$** .

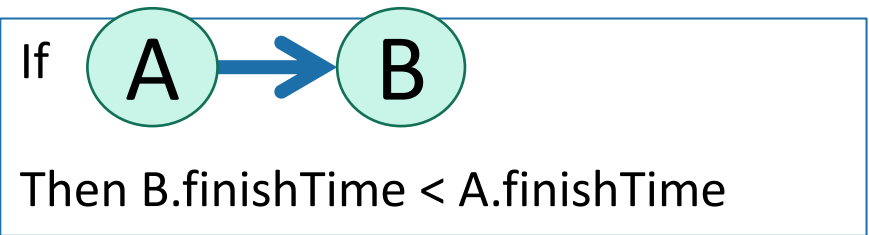


Theorem

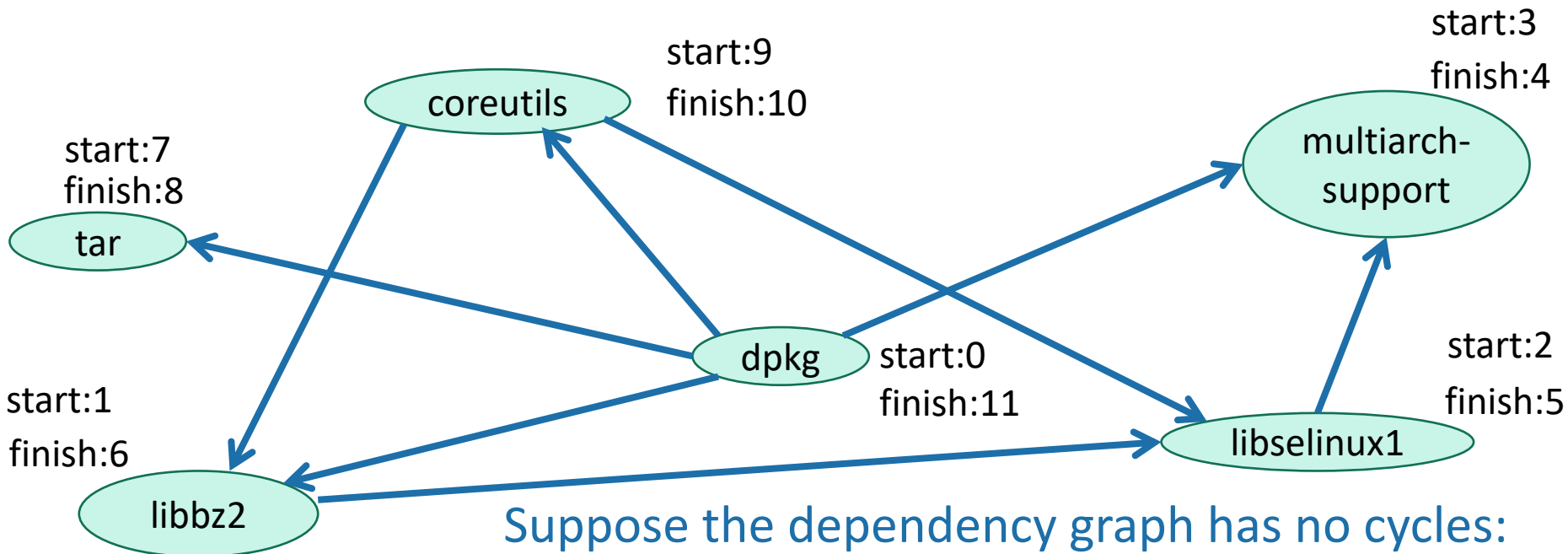
- If we run DFS on a directed acyclic graph,



Back to topological sorting



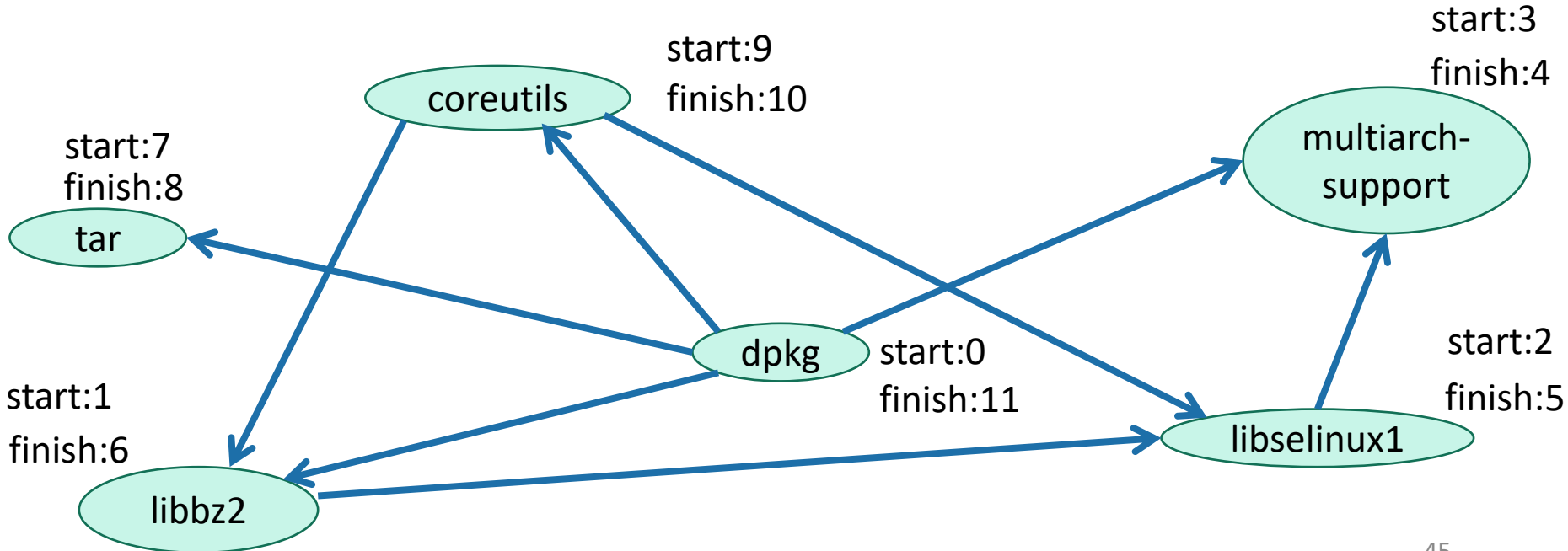
- In what order should I install packages?
- In reverse order of finishing time in DFS!



Suppose the dependency graph has no cycles:
it is a **Directed Acyclic Graph (DAG)**

Topological Sorting (on a DAG)

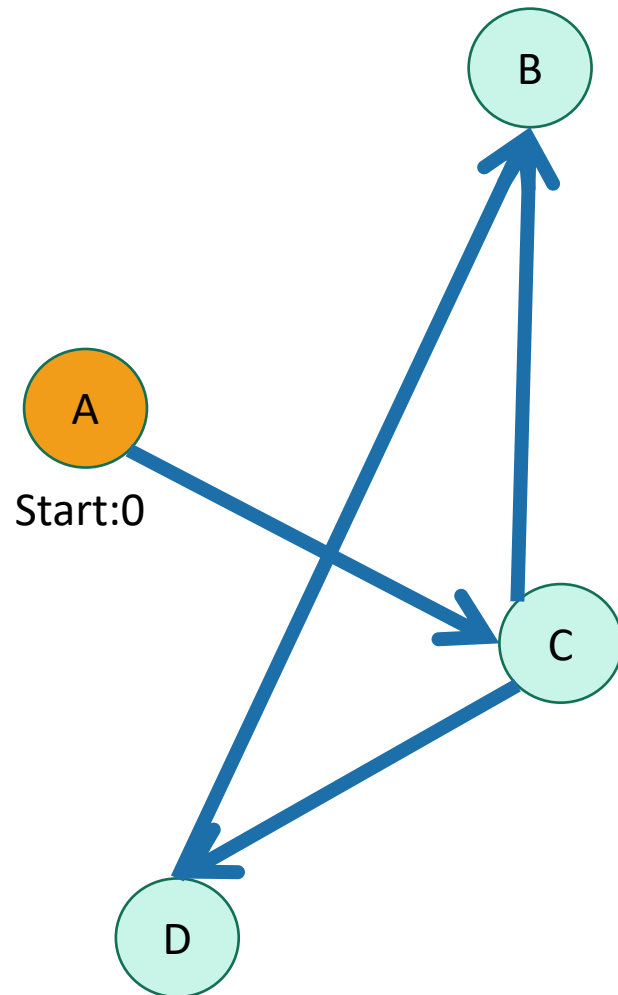
- Do DFS
 - When you mark a vertex as **all done**, put it at the **beginning** of the list.
- dpkg
 - coreutils
 - tar
 - libbz2
 - libselinux1
 - multiarch_support



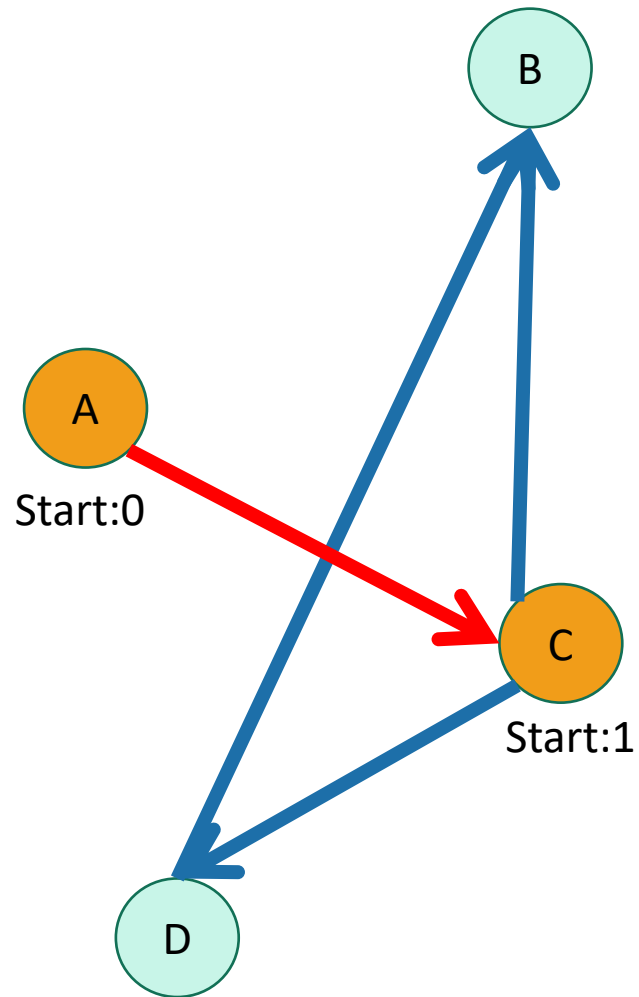
What did we just learn?

- DFS can help you solve the **topological sorting problem**
 - That's the fancy name for the problem of finding an ordering that respects all the dependencies
- Thinking about the DFS tree is helpful.

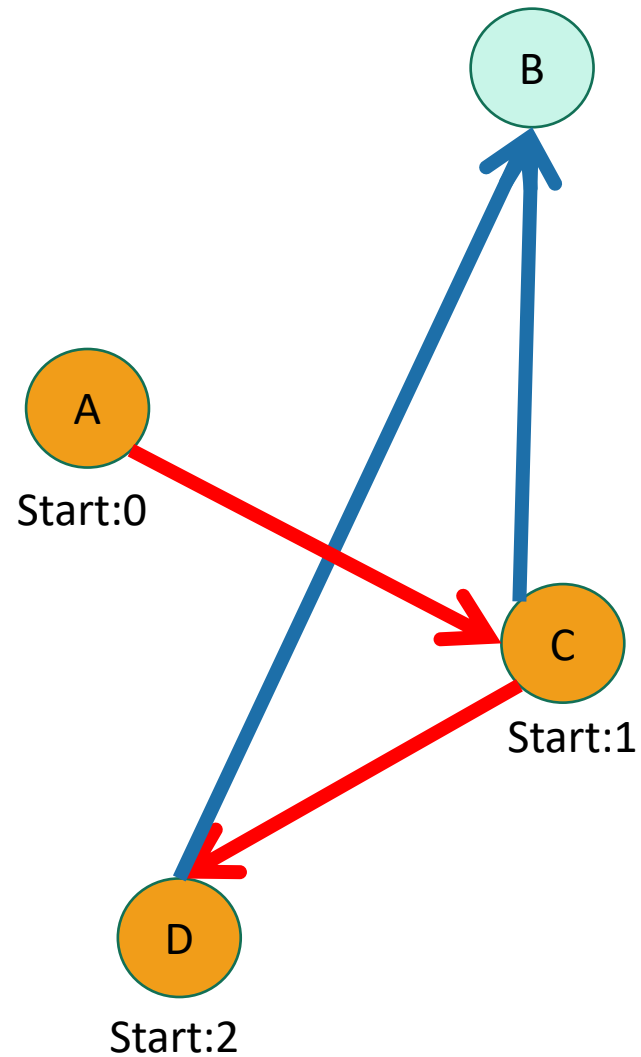
Example:



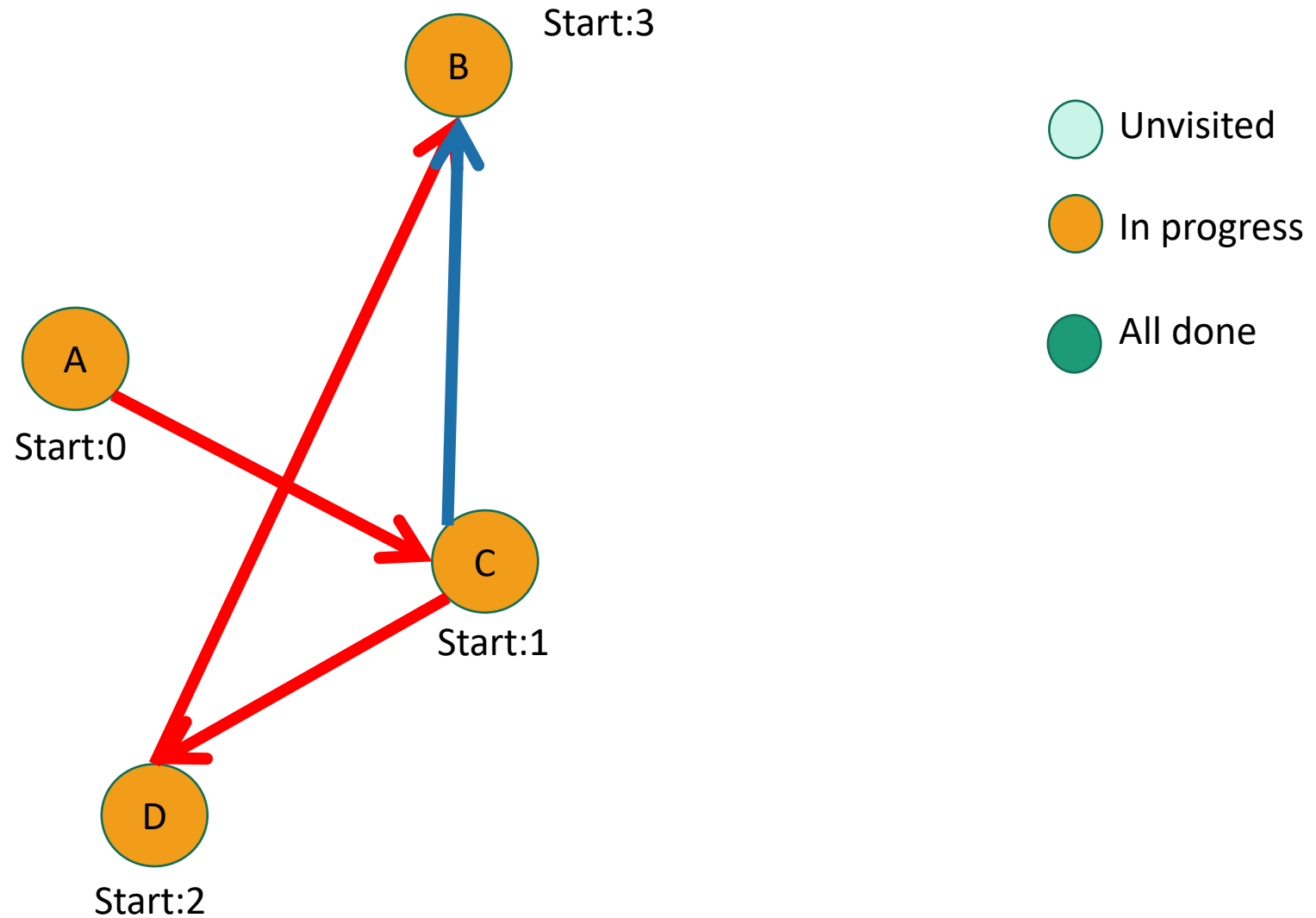
Example



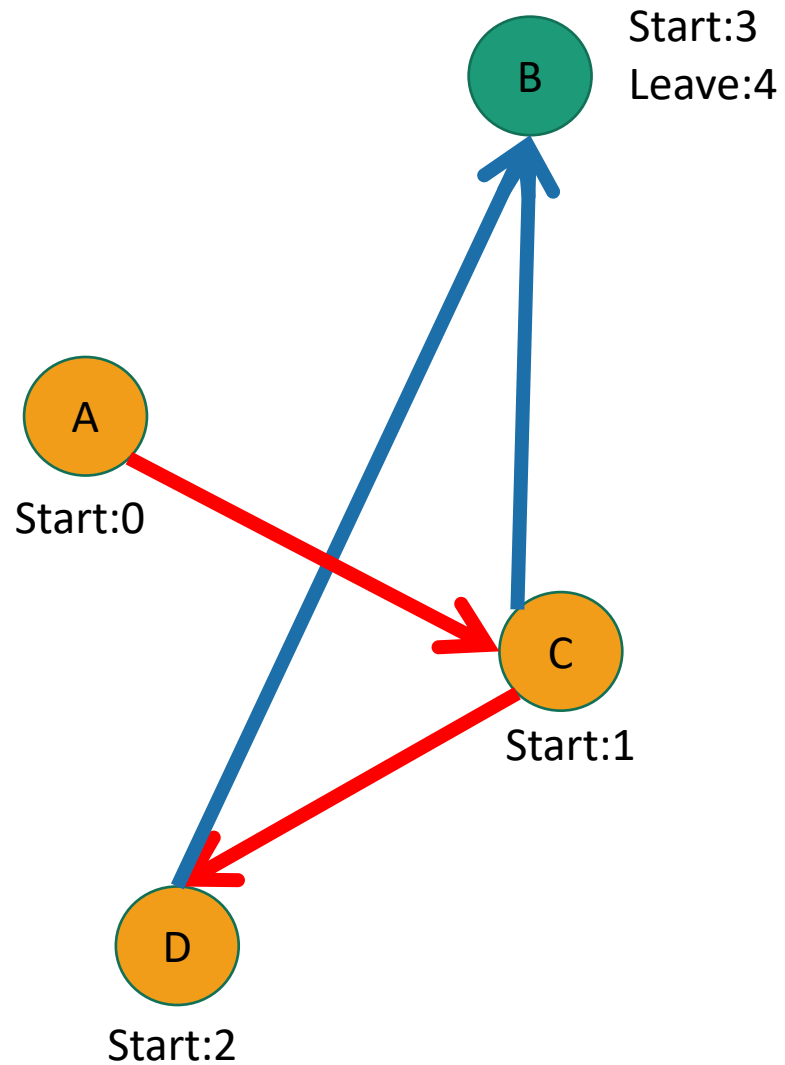
Example



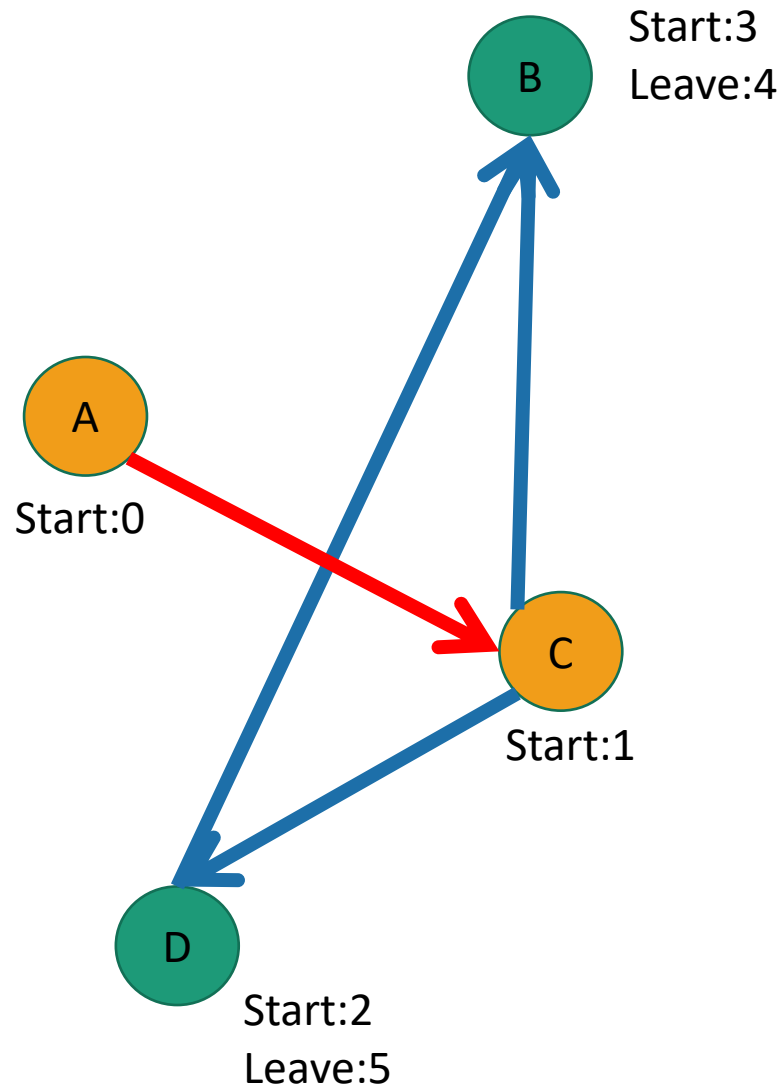
Example



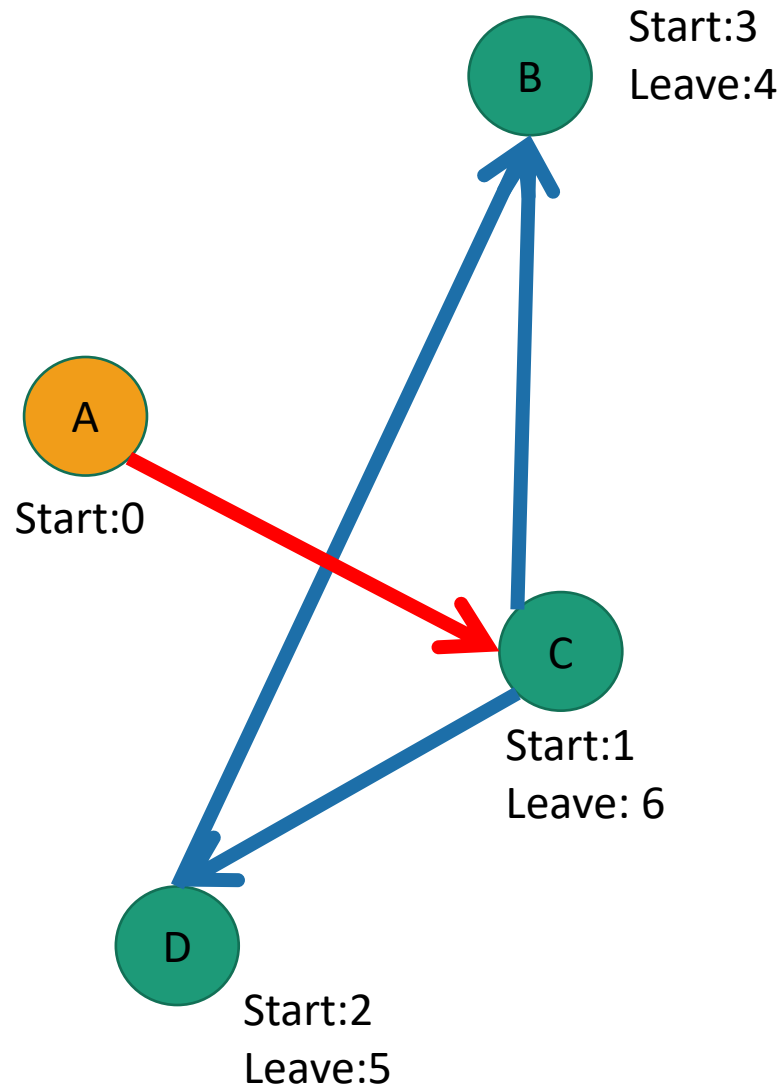
Example



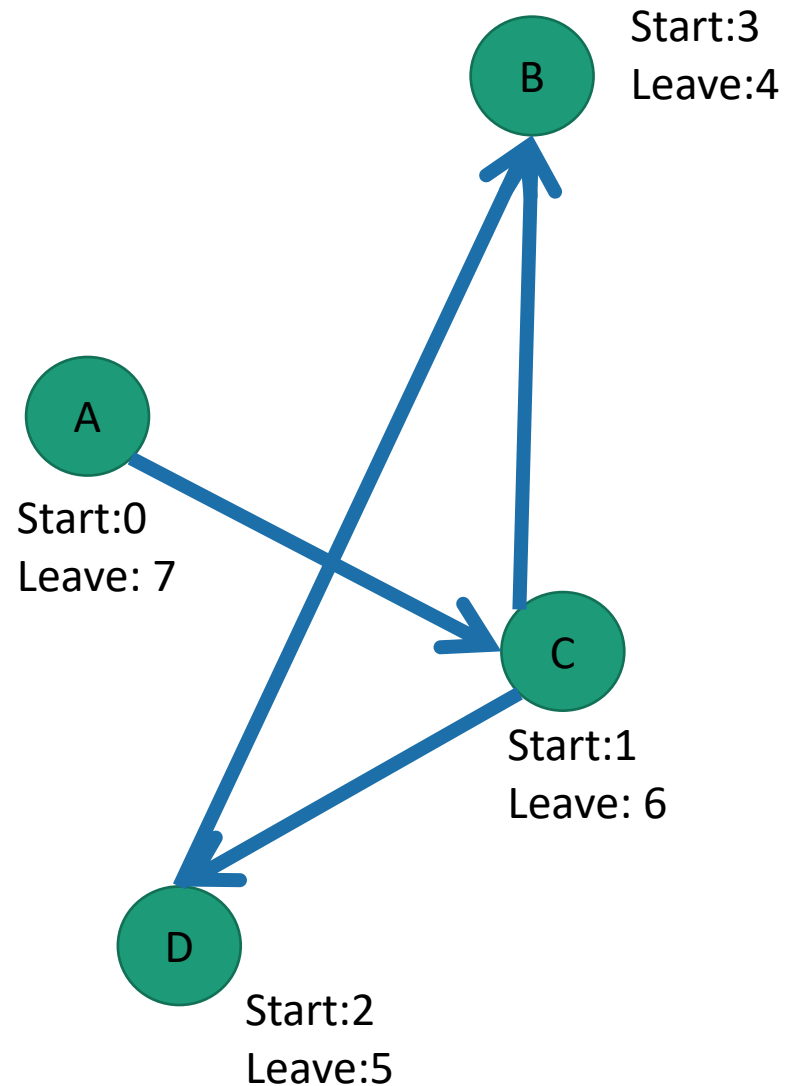
Example



Example



Example

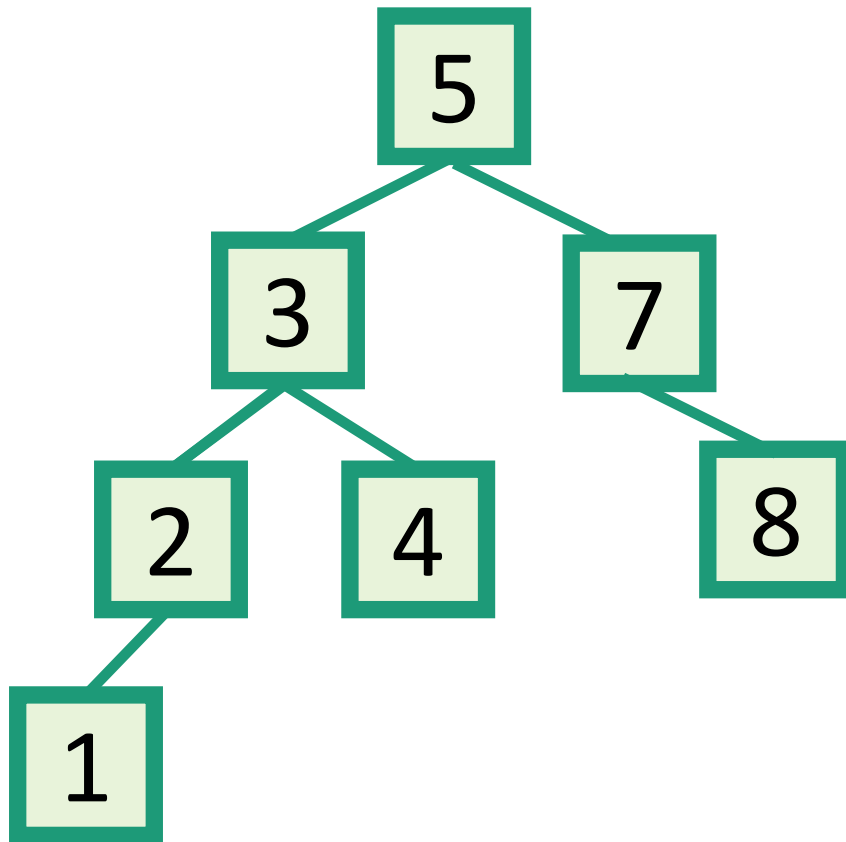


Do them in this order:



Another use of DFS that we've already seen

- In-order enumeration of binary search trees



Do DFS and print a node's label when you are done with the left child and before you begin the right child.

Acknowledgement

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