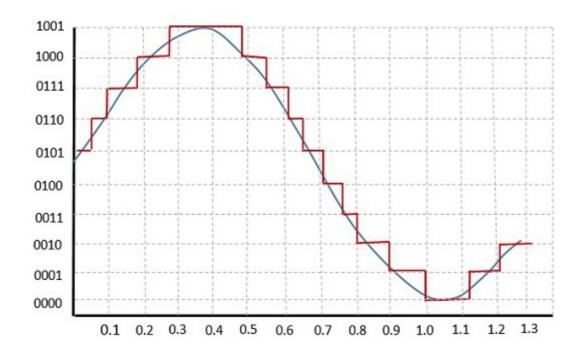
# Multimedia Systems Lecture – 18

Ву

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### Linear and Nonlinear/ Uniform and Nonuniform Quantization

• Samples are typically stored as uniformly quantized values. This is called *linear or uniform quantization*.



- There are two types of uniform quantization. They are *Mid-Rise* type and *Mid-Tread* type.
- The **Mid-Rise** type is so called because the origin lies in the middle of a raising part of the stair-case like graph. The quantization levels in this type are even in number.
- The **Mid-tread** type is so called because the origin lies in the middle of a tread of the stair-case like graph. The quantization levels in this type are odd in number.
- The difference between an input value and its quantized value is called a **Quantization Error**.

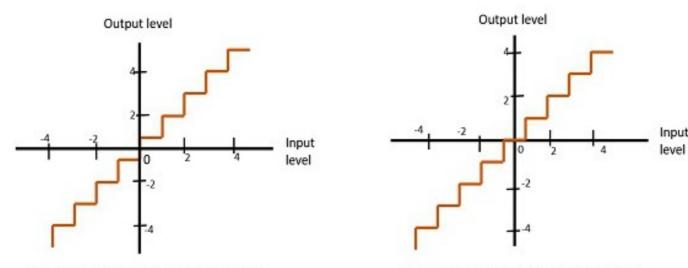


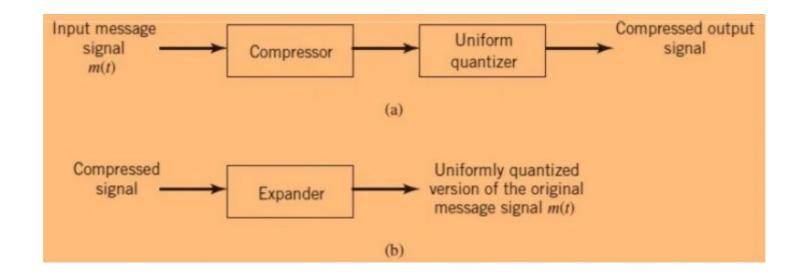
Fig 1: Mid-Rise type Uniform Quantization

Fig 2 : Mid-Tread type Uniform Quantization

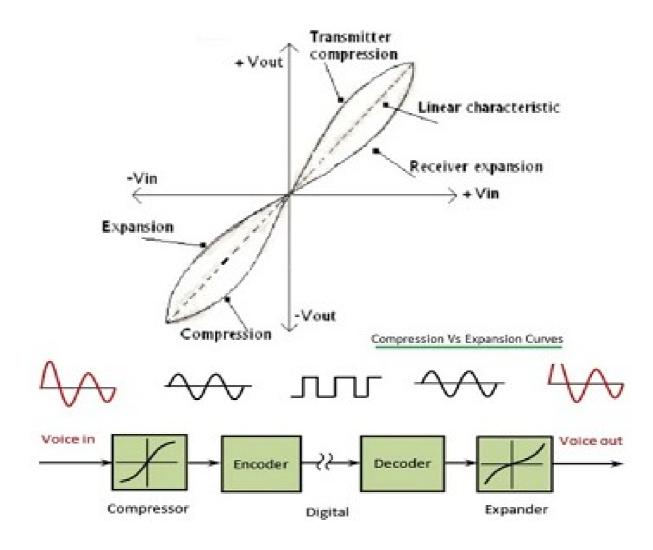
# Non-uniform Quantization

- If the quantization characteristic is nonlinear then the step size is not constant and quantization is known as non-uniform quantization.
- It is mostly used in case of speech or music as here the variation in amplitude is high which is expressed as crest factor and is given by crest factor = peak value of signal/rms value of signal
- Non-uniform quantization is achieved using companding.

- Companding:
- It is derived from two words, *Compressing* and *Expanding*.
- The desired form of non-uniform quantization can be achieved by using compressor followed by a uniform quantizer.



#### Companding Process



#### μ-law and A-law companding

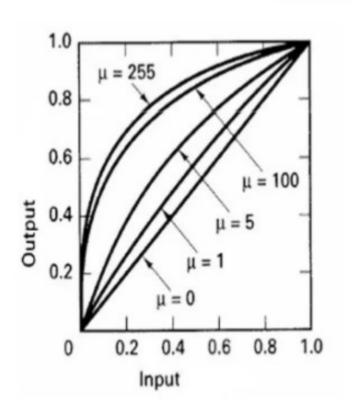
- μ-law is popular technique used in USA and Japan.
- Here the input and output relationship is given by

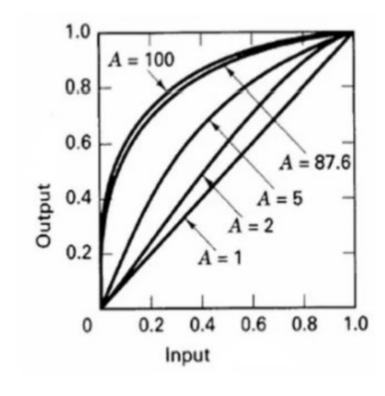
$$r = \frac{\operatorname{sign}(s)}{\ln(1+\mu)} \ln\left\{1 + \mu \left| \frac{s}{s_p} \right| \right\}, \qquad \left| \frac{s}{s_p} \right| \le 1$$

• A very similar rule, called A-law, is used in telephony in Europe.

$$r = \begin{cases} \frac{A}{1 + \ln A} \left( \frac{s}{s_p} \right), & \left| \frac{s}{s_p} \right| \le \frac{1}{A} \\ \frac{\text{sign}(s)}{1 + \ln A} \left[ 1 + \ln A \left| \frac{s}{s_p} \right| \right], & \frac{1}{A} \le \left| \frac{s}{s_p} \right| \le 1 \end{cases}$$
where  $\text{sign}(s) = \begin{cases} 1 & \text{if } s > 0, \\ -1 & \text{otherwise} \end{cases}$ 

#### μ-law and A-law Compression Characteristics





## Pulse Code Modulation (PCM)

- **Modulation** is the process of varying one or more parameters of a carrier signal in accordance with the instantaneous values of the message signal.
- There are many modulation techniques, which are classified according to the type of modulation employed. Of them all, the digital modulation technique used is **Pulse Code Modulation**.
- We know that the basic techniques for creating digital signals from analog ones consist of *sampling* and *quantization*.
- Pulse Code Modulation, is a formal term for the sampling and quantization we have already been using.
- *Pulse* comes from an engineer's point of view that the resulting digital signals can be thought of as infinitely narrow vertical "pulses."

#### Basic Elements of PCM

