

1 Class-Conditional Densities for Binary Data [25 Points]

Problem A [5 points]: Parameters of Full Model with Factorizing

Solution A.:

$$\begin{aligned} \text{I. A) } p(x|y) &= p(x_1, \dots, x_j, y) = \frac{p(x_1, \dots, x_j, y)}{p(y)} \\ &= p(x_j|x_1, \dots, x_{j-1}, y) p(x_1, \dots, x_{j-1}, y) \cdot \frac{1}{p(y)} \\ &= p(x_j|x_1, \dots, x_{j-1}, y) p(x_{j+1}|x_1, \dots, x_j, y) \dots p(x_n|x_1, y) p(x_1, y) \\ &= \theta_{x_jc} \theta_{x_{j+1}c} \dots \theta_{x_nc} \quad \text{for each } c, x_1, \dots, x_n \\ \text{There are } 2^D \text{ combos } x_1, \dots, x_n \\ \text{ " " } C \text{ " } y=c \\ &\therefore O(2^D \cdot C) \end{aligned}$$

Figure 1

Problem B [5 points]: Parameters of Full Model without Factorizing

Solution B.:

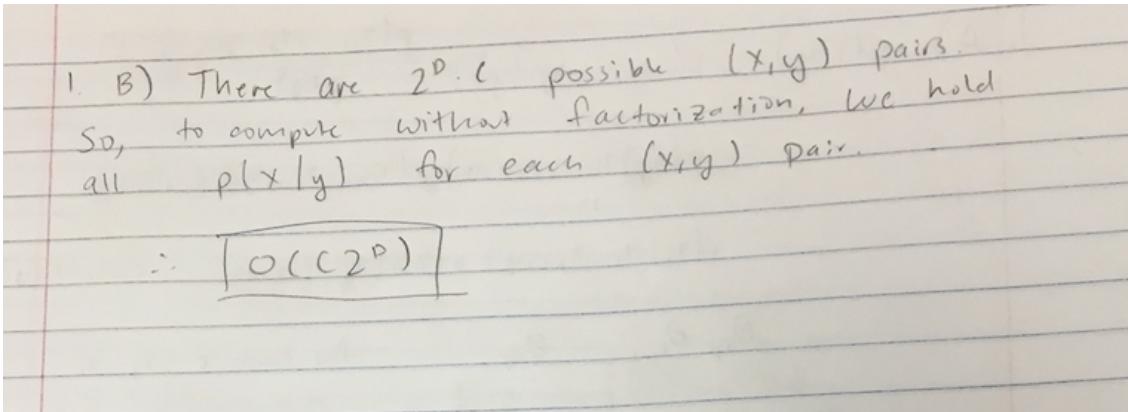


Figure 2

Problem C [2 points]: Naive Bayes vs. Full Model for Small N

Solution C.:

I. c) If N is very small, then too many parameters will lead to overfitting. So, Naive Bayes is better.

Figure 3

Problem D [2 points]: Naive Bayes vs. Full Model for Large N

Solution D.:

| 1D). If N is very large , then too few parameters
leads to underfitting. So, Full Bayes is better.

Figure 4

Problem E [11 points]: Computational Complexity of Making a Prediction Using Naive Bayes vs Full Model

Solution E.:

For Naive Bayes on a single test case:

$$p(y|x) = \frac{p(x|y) p(y)}{p(x)}$$

$p(y)$ is given - $O(1)$

$$p(x|y) = \prod_{i=1}^D p(x_i|y), \text{ so it takes } O(D) \text{ time}$$

to compute $p(x|y)$

$$p(x) = \sum_y p(x|y)$$

For $p(x|y=c)$, we need $O(D)$ time.
 There are C such cases.

$$\therefore O(CD + C) = \boxed{O(CD)}$$

For Full Bayes, we have

$$p(y|x) = \frac{p(x|y) p(y)}{p(x)}$$

From A), $p(x|y) = \theta_{y_1} \dots \theta_{y_D} = O(D)$ time for the product

$$p(x) = \sum_y p(x|y) = O(CD) \text{ time } (D \text{ for each } p(x|y), C \text{ for each } y)$$

$$\therefore \boxed{O(CD)}$$

Figure 5

2 Sequence Prediction [75 Points]

Problem A [10 points]: Max-Probability State Sequences for 6 Trained HMMs

Solution A.:

Figure 6

```

File #4:
Emission Sequence          Max Probability State Sequence
#####
23664                      01124
3630535602                  0111201112
350201162150142              011244012441112
00214005402015146362        11201112412444011112
2111266524665143562534450  2012012424124011112411124

File #5:
Emission Sequence          Max Probability State Sequence
#####
68535                      10111
4546566636                  1111111111
638436858181213              110111010000011
13240338308444514688        00010000000111111100
011166443444138253362262  2111111111111001111110101

```

Figure 7

Problem B [17 points]: Probability of Emission Sequence for 6 Trained HMMs

Solution B.:

Alphas on left, Betas on right

File #0:	
Emission Sequence	Probability of Emitting Sequence
25421	4.537e-05
01232367534	1.620e-11
5452674261527433	4.348e-15
7226213164512267255	4.739e-18
0247120602352051010255241	9.365e-24

File #1:	
Emission Sequence	Probability of Emitting Sequence
77550	1.181e-04
7224523677	2.033e-09
505767442426747	2.477e-13
72134131645536112267	8.871e-20
4733667771450051060253041	3.740e-24

File #2:	
Emission Sequence	Probability of Emitting Sequence
60622	2.088e-05
4687981156	5.181e-11
815833657775062	3.315e-15
21310222515963505015	5.126e-20
6503199452571274006320025	1.297e-25

File #3:	
Emission Sequence	Probability of Emitting Sequence
13661	1.732e-04
2102213421	8.285e-09
166066262165133	1.642e-12
53164662112162634156	1.063e-16
1523541005123230226306256	4.535e-22

Figure 5

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Figure 3

File #4:	
Emission Sequence	Probability of Emitting Sequence
23664	1.414e-04
3630535602	4.326e-09
350201162150142	9.793e-14
00214005402015146362	4.740e-18
2111266524665143562534450	5.618e-22

File #5:	
Emission Sequence	Probability of Emitting Sequence
68535	1.322e-05
4546566636	2.867e-09
638436858181213	4.323e-14
1324033830844514688	4.629e-18
0111664434441382533632626	1.440e-22

Figure 6

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23664	1.414e-04
3630535602	4.326e-09
350201162150142	9.793e-14
00214005402015146362	4.740e-18
2111266524665143562534450	5.618e-22

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1324033830844514688	4.629e-18
0111664434441382533632626	1.440e-22

Figure 4

Figure 8

Problem C [10 points]: Learned State Transition and Output Emission Matrices of Supervised Hidden Markov Model

Solution C.:

```
Transition Matrix:  
#####
# 2.83e-01 4.39e-01 1.14e-01 1.14e-01  
# 2.32e-01 4.15e-01 4.04e-02 4.04e-02  
# 1.84e-01 9.76e-02 3.69e-01 4.28e-01  
# 1.883e-01 9.903e-02 3.052e-01 4.075e-01  
#####  
  
Observation Matrix:  
#####
# 1.486e-01 2.288e-01 1.533e-01 1.179e-01 4.717e-02 5.189e-02 2.830e-02 1.297e-01 9.198e-02 2.358e-03  
# 1.062e-01 9.653e-03 1.931e-02 3.089e-02 1.699e-01 4.633e-02 1.409e-01 2.394e-01 1.371e-01 1.004e-01  
# 1.194e-01 4.299e-02 6.529e-02 9.076e-02 1.768e-01 2.022e-01 4.638e-02 5.096e-02 7.083e-02 1.274e-01  
# 1.694e-01 3.871e-02 1.468e-01 1.823e-01 4.839e-02 6.290e-02 9.032e-02 2.581e-02 2.161e-01 1.935e-02  
#####
```

Figure 9

Problem D [15 points]: Learned State Transition and Output Emission Matrices of Unsupervised Hidden Markov Model

Solution D.:

```
Transition Matrix:  
#####  
5.413e-06 1.342e-01 8.658e-01 2.379e-08  
1.269e-01 3.610e-01 2.221e-02 4.899e-01  
3.634e-01 6.366e-01 4.555e-06 3.907e-09  
3.501e-02 1.027e-04 3.197e-01 6.452e-01  
  
Observation Matrix:  
#####  
1.362e-01 7.629e-04 1.634e-01 1.769e-01 6.810e-03 3.249e-01 8.314e-0  
3 3.654e-02 9.327e-02 5.301e-02  
2.355e-01 1.144e-01 1.697e-01 3.305e-07 1.571e-01 6.108e-15 1.349e-0  
1 3.375e-13 1.884e-01 2.590e-05  
1.178e-01 6.175e-02 2.302e-41 1.560e-01 1.620e-01 1.034e-01 1.120e-0  
1 1.037e-02 1.403e-01 1.363e-01  
7.573e-02 6.812e-02 7.632e-02 1.293e-01 8.978e-02 7.933e-02 3.900e-0  
2 2.643e-01 1.047e-01 7.342e-02
```

Figure 10: Note: this looks different because I ran it on my friend's computer because mine was performing very very slowly. I also seeded with 2019 (to check with Piazza). I know this seems fishy, but you can confirm the code in my submission, and I have unsupervised runs in the Jupyter notebook as well.

Problem E [5 points]: Compare 2C and 2D

Solution E.: *The variation in the unsupervised matrices is much more extreme; many values are either very close to 0 or decently close to 1 (in a geometric sense; many orders of magnitude larger than others). The variation in the supervised matrices is less extreme.*

Supervised offers a better approximation, as it involves training on observed state-emission pairings.

Unsupervised HMM's performance can be improved by training on additional data.

Problem F [5 points]: Generating Emission Sequences

Solution E:

```
File #0:  
Generated Emission  
#####  
0732531177124757152  
53745057075575217416  
13045515722754070475  
73045544665376701452  
01734233404272007760  
  
File #1:  
Generated Emission  
#####  
14157341770347455754  
17214115576711622477  
72545435202556554707  
76465221562053671444  
50274341070441007452  
  
File #2:  
Generated Emission  
#####  
32721226171066715694  
33691289911615255999  
6823056577751376347  
83562633163922007384  
65751670269167389530  
  
File #3:  
Generated Emission  
#####  
16224111411616240526  
20462010200553040525  
35146600612225165310  
35026644611056215656  
51235135163243411351
```

Figure 11

```
File #4:  
Generated Emission  
#####  
45324205325313104634  
61462063126464045101  
45633013054143131343  
20104103223235150650  
40106035636024626061  
  
File #5:  
Generated Emission  
#####  
30684656034184160614  
3265864246538682380  
66536028883018115844  
84438164146884124403  
36666044682816316065
```

Figure 12

Problem G [3 points]: Sparsity of Trained A and O Matrices

Solution G.: *A and O seem mostly sparse; that is, each row/column has 0 (or numbers very close to 0) for the majority of its entries.*

This means that, from any state, there are realistically very few other states that are transitioned to, and very few emissions that make sense in the context of this current state.

Problem H [5 points]: Hidden States vs. Sample Emission Sentences from HMM

Solution H.: *In the case where there is one hidden state, the sentence is pretty nonsensical; it's simply a sequence of terms picked from the frequency distribution of words in the document, as with only one state there's no distinguishing between the sampling distribution of words in different positions. As the number of hidden states increases, the sequences of words mirror more closely the kinds of sequences observed in the Constitution. For example, in the most sophisticated model (16 hidden states), we have the phrase "regulate the united at importation declaring," which is pretty sequentially realistic. In the less sophisticated models, the sentences are less and less sequentially logical.*

In general, increasing the number of hidden states will increase the training data likelihood, because it will lead to fitting the training data more closely (and thus mirroring its transitions more closely).

Problem I [5 points]: Analyzing Visualization of State

Solution I: *State 1 seems to have nouns - more specifically, nouns that represent significant entities in the operation of a government; nouns like "senate," "congress," "state," "office," etc. While other states, like state 9, are also composed primarily of nouns, they're more secondary in nature; state 9, for example, has nouns like "number," "resignation," "consequence," etc.*